

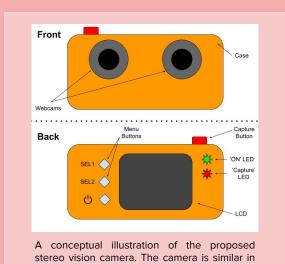
The Do-Pro: A Minimalistic Stereo Vision Camera



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Background:

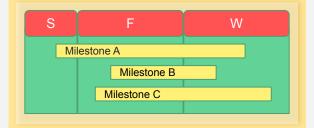
To perceive depth, two images of a scene must be observed at different points along a shared axis. Stereo vision cameras are specialized instruments designed to produce depth from at least two images. These cameras are specialized and expensive with state-of-the-art commercial cameras costing \$500 and requiring a mount. In this proposal, we aim to produce a more affordable stereo vision camera designed for versatile applications.



style to most handheld digital cameras

Milestones:

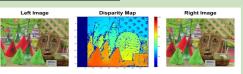
- Milestone A Develop simple stereo camera model and achieve functionality on breadboard
- Milestone B Calibrate stereo-vision cameras
- Milestone C Implement stereo vision processing, camera software mechanics, and PCB functionality



References:

- [1] A. Vij, "Stereo vision: How do 'terminators' see the world?," *Medium*, 23-Mar-2021. [Online].
- [2] B.K.P. Horn,, "Robot Vision", Cambridge, MA: MIT Press, 1986, ch. 13.
- [3] D. Scharstein, R. Szeliski and R. Zabih, "A taxonomy and evaluation of dense two-frame stereo correspondence algorithms," Proceedings IEEE Workshop on Stereo and Multi-Baseline Vision (SMBV 2001), 2001, pp. 131-140, doi: 10.1109/SMBV.2001.988771.

Software Deliverable:



Example of depth estimation on stereo vision image set.

Hardware Deliverable:



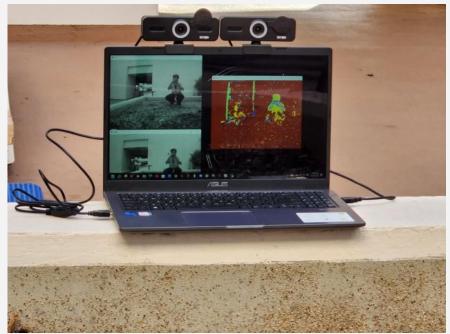
High level wiring schematic of the proposed stereo vision camera system

General Deliverables:

- Functional camera 3D-printed chassis and manufactured PCB
- Auto-calibration
- Image & video Processing
- UI + touch screen + instruction manual
- ***Object tracking***

Stereo-Vision Demonstration





https://youtu.be/KSEhb_ojmms

Estimated Expenses

Materials Expenses (Need to buy):

- \star Embedded Camera (x2) \$17.80
- ★ Touchscreen Display \$36.99
- **★** PCB Manufacturing \$25
- ★ Miscellaneous Components \$18.04
- ★ Vendors: Amazon, Digikey

Required Expenses: ~\$100

Requested Funding: \$175

