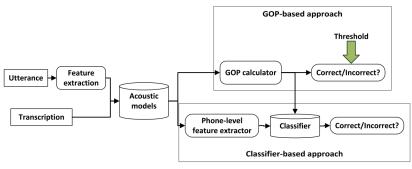
# 发音良好度 (GOP) 基于 Kaldi 的实现

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## A Typical Mispronunciation Detection System



(Hu et al., 2015)

## GMM-based Goodness Of Pronunciation (GOP)

In the conventional GMM-HMM based system, GOP was first proposed in (Witt et al., 2000).

Defined as the duration normalised log of the posterior:

$$GOP(p) = \frac{1}{t_e - t_s + 1} \log p(p|\mathbf{o})$$
 (1)

- the input observations
- p the canonical phone
- $t_s$ ,  $t_e$  the start and end frame indexes

## **GOP-GMM Calculation**

$$\log p(p|\mathbf{o}) = \frac{p(\mathbf{o}|p)p(p)}{\sum_{q \in Q} p(\mathbf{o}|q)p(q)} \approx \frac{p(\mathbf{o}|p)}{\sum_{q \in Q} p(\mathbf{o}|q)}$$
(2)

Q the whole phone set

#### How To Calculate

Numerator Forced alignment

Denominator Viterbi decoding with an unconstrained phone loop, assuming  $\sum_{q_t \in Q} p(\mathbf{o}|q_t) \approx \max_{q_t \in Q} p(\mathbf{o}|q_t)$ 

An implemented example (deprecated): https://github.com/jimbozhang/kaldi-gop



## **DNN-based GOP**

In the NN-HMM based system, GOP was defined as the log phone posterior ratio between the canonical phone and the one with the highest score (Hu et al., 2015).

$$LPP(p) = \log p(p|\mathbf{o}; t_s, t_e)$$
(3)

$$GOP(p) = \log \frac{LPP(p)}{\max_{q \in Q} LPP(q)}$$
 (4)

## **GOP-NN Calculation**

$$LPP(p) \approx \frac{1}{t_e - t_s + 1} \sum_{t=t_s}^{t_e} \log p(p|o_t)$$
 (5)

$$p(p|o_t) = \sum_{s \in p} p(s|o_t)$$
 (6)

s the senone label

 $\{s|s\in p\}$  the states belonging to those triphones whose current phone is p

### Phone-level Feature

Extract a feature vector for each phone segment  $o_i$  for supervised training. The phone-level feature is defined as:

$$[LPP(p_1), \cdots, LPP(p_M), LPR(p_1|p_i), \cdots, LPR(p_j|p_i), \cdots]^T$$
 (7)

where the Log Posterior Ratio (LPR) between phone  $p_j$  and  $p_i$  is defined as:

$$LPR(p_j|p_i) = \log p(p_j|\mathbf{o}; t_s, t_e) - \log p(p_i|\mathbf{o}; t_s, t_e)$$
(8)

An implemented example (临时地址):

https://github.com/jimbozhang/kaldi/tree/gop/egs/gop

### Reference



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