Computer Vision

Final Project Panorama Stitching

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Content

- SURF
 - Xxx
 - Yyy
 - ZZZ
- SIFT
 - XXX
 - Yyy
 - ZZZ
- Fast Panorama Stitching on Mobile
 - Xx
 - yy



SIFT Basic process

- 1. Scale Space and Image Pyramids
- 2. Localizing Extrema
- 3. Generating Orientations and Descriptors

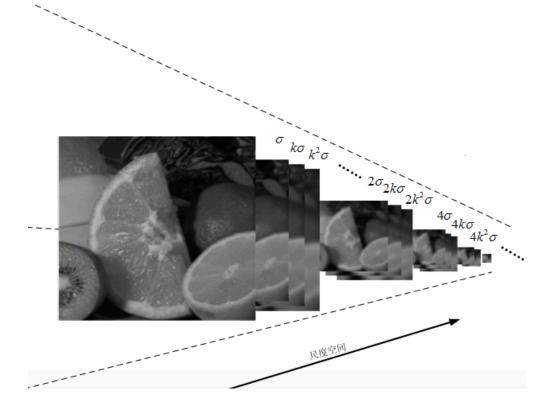


SIFT —— Scale Space & Image Pyramids

The Gaussian pyramid imitates different scales of the image --"the depth of the image"

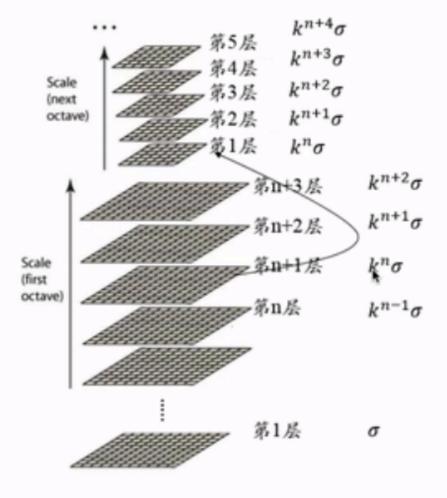
The problem solved by the scale space of the image is how to describe the image at all

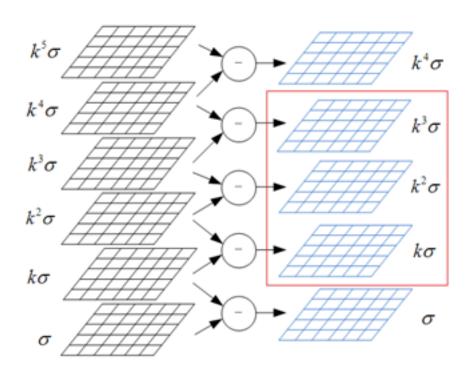
scales.





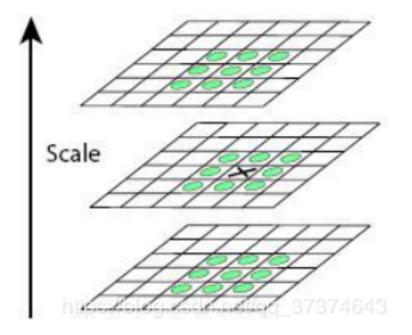
SIFT —— Scale Space & Image Pyramids



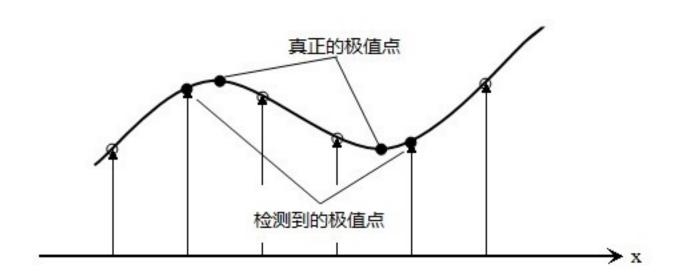




SIFT —— Localizing Extrema









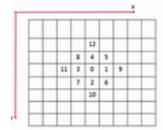
SIFT — Localizing Extrema

Sub-pixel interpolation

$$D(\Delta x, \Delta y, \Delta \sigma) = D(x, y, \sigma) + \begin{bmatrix} \frac{\partial D}{x} & \frac{\partial D}{y} & \frac{\partial D}{\sigma} \end{bmatrix} \begin{bmatrix} \Delta x \\ \Delta y \\ \Delta \sigma \end{bmatrix} + \frac{1}{2} \begin{bmatrix} \Delta x & \Delta y & \Delta \sigma \end{bmatrix} \begin{bmatrix} \frac{\partial^2 D}{\partial x^2} & \frac{\partial^2 D}{\partial x \partial y} & \frac{\partial^2 D}{\partial x \partial \sigma} \\ \frac{\partial^2 D}{\partial y \partial x} & \frac{\partial^2 D}{\partial y^2} & \frac{\partial^2 D}{\partial y \partial \sigma} \\ \frac{\partial^2 D}{\partial \sigma \partial y} & \frac{\partial^2 D}{\partial \sigma \partial y} & \frac{\partial^2 D}{\partial \sigma \partial z} \end{bmatrix} \begin{bmatrix} \Delta x \\ \Delta y \\ \Delta \sigma \end{bmatrix}$$

附: 有限差分求导法

$$\left(\frac{\partial f}{\partial x}\right) = \frac{f_1 - f_2}{2h}$$
 (1)

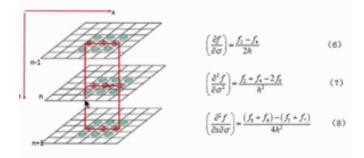


$$\left(\frac{\partial f}{\partial y}\right) = \frac{f_2 - f_4}{2h}$$
 (2)

$$\left(\frac{\partial^2 f}{\partial x^2}\right) = \frac{f_1 + f_2 - 2f_2}{h^2}$$
(5)

$$\left|\frac{\partial^{2} f}{\partial x^{2}}\right| = \frac{f_{1} + f_{4} - 2f_{6}}{b^{2}}$$
(4)

$$\left(\frac{\partial^2 f}{\partial x \partial y}\right) = \frac{(f_1 + f_2) - (f_2 + f_1)}{4h^2}$$
(5)



$$D(x) = D + \frac{\partial D^T}{\partial x} \Delta x + \frac{1}{2} \Delta x^T \frac{\partial^2 D^T}{\partial x^2} \Delta x$$

Derivation, substitution, iterative process to get new expression



SIFT — Localizing Extrema

A flat DoG response peak tends to have a larger main curvature across the edge and a smaller main curvature in the direction of the vertical edge.

$$H(x, y) = \begin{bmatrix} D_{xx}(x, y) & D_{xy}(x, y) \\ D_{xy}(x, y) & D_{yy}(x, y) \end{bmatrix}$$

$$Tr(H) = D_{xx} + D_{yy} = \alpha + \beta$$

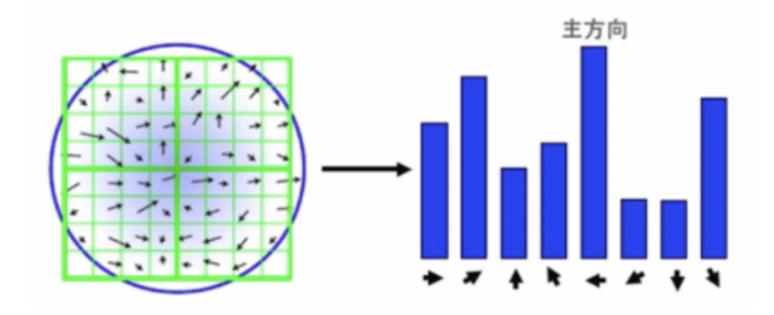
$$Det(H) = D_{xx}D_{yy} - (D_{xy})^2 = \alpha\beta$$

$$\frac{Tr(H)^2}{Det(H)} = \frac{(\alpha + \beta)^2}{\alpha\beta} = \frac{(\gamma + 1)^2}{\gamma}$$

$$\frac{Tr(H)^2}{Det(H)} < \frac{(\gamma+1)^2}{\gamma}$$



SIFT — Generating Orientations & Descriptors



 $m(x,y) = \sqrt{(L(x+1,y)-L(x-1,y))^2 + (L(x,y+1)-L(x,y-1))^2}$ $\theta(x,y) = \tan^{-1}((L(x,y+1)-L(x,y-1))/(L(x+1,y)-L(x-1,y)))$

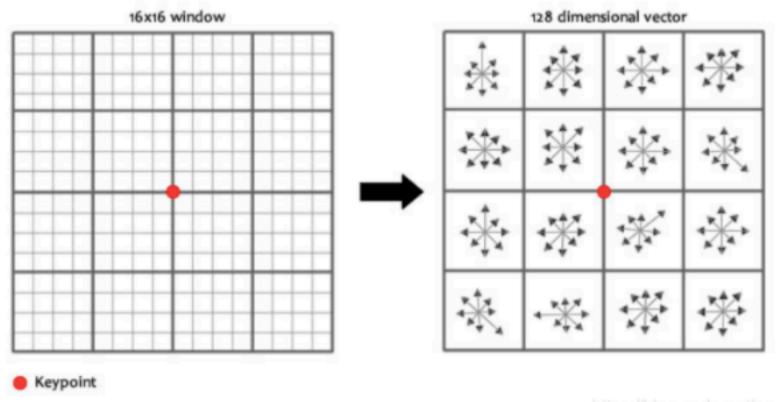
Robustness requirements:

- Secondary direction
- Smoothing



SIFT — Generating Orientations & Descriptors

对每个关键点使用4×4共16个种子点来描述,这样一个关键点就可以产生128维的SIFT特征向量。



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SIFT — Result

