

Computer Vision

Final Project Panorama Stitching

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Current Approaches

- > transition smoothing: reduce color differences between source images to make seams invisible and remove stitching artifacts
 - ➤ **Alpha blending**: fast transition smoothing approach, but it cannot avoid ghosting problems caused by object motion and small spatial alignment errors
 - ➤ Gradient Domain Image Blending approaches: can reduce color differences and smooth color transitions using gradient domain operations, producing high-quality composite images
- > optimal seam finding: search for seams in overlapping areas along paths where differences between source images are minimal
- > combination: optimal seams first, if seams and stitching artifacts are visible, transition smoothing to reduce color differences to hide the artifacts then
 - graph cut -> find optimal seams
 - > poisson blending -> smoothing color transitions



Current Approaches Problem

- > computational and memory costs are high
- > pixels are easy saturated in color correction
- don't work well for source images in very different colors and luminance
- > linear blending, moving objects on the overlapping areas will cause ghosting artifacts

Solution

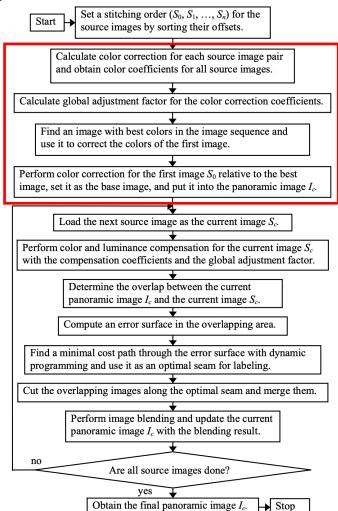
- ✓ don't need to keep all source images in memory due to the sequential stitching.
- ✓ dynamic programming for optimal seam finding allowing image labeling much faster than using graph cut
- ✓ combination of color correction and image blending
- ✓ high-quality panoramic images from long image sequences with very different colors and luminance
- ✓ work well on both indoor and outdoor scenes



Summary

Fast Panorama Stitching for High-Quality Panoramic Images on Mobile Phones

Yingen Xiong and Kari Pulli, Member, IEEE



Color Correction

- > color correction for all source images to reduce color differences
- > smoothen remaining color transitions between adjacent images

> Image Labeling

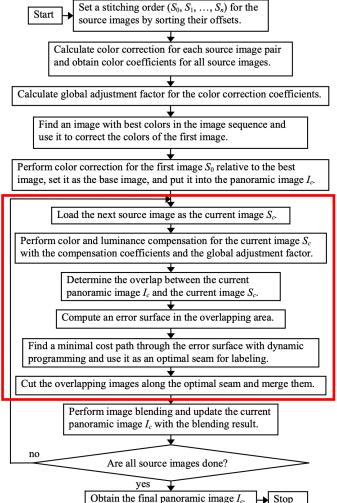
- error surface is constructed with squared differences between overlapping images
- low-cost path is found through the error surface by dynamic programming and used as an optimal seam to create labeling

Image Blending Operations

- ➢ linear blending → source images are similar in color and luminance
- poisson blending -> colors remain too different



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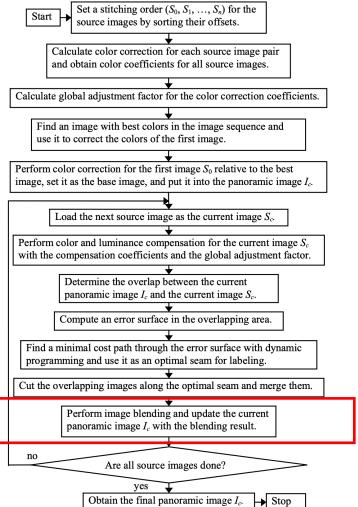
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Basic idea: compute light averages in the overlap area by linearizing the gamma-corrected RGB

Suppose S_{i-1} and S_i are adjacent images, S_{i-1}^o and S_i^o are where image overlap

$$\alpha_{c,i} = \frac{\sum_{p} (P_{c,i-1}(p))^{\gamma}}{\sum_{p} (P_{c,i}(p))^{\gamma}} \quad c \in \{R, G, B\} (i = 1, 2, 3, \dots, n)$$

 $P_{c,i-1}(p)$: the color value of pixel p in image S_{i-1}^o $P_{c,i}(p)$: the color value of pixel p in image S_i^o γ : gamma coefficient(set to 2.2 in paper)



Basic idea: compute light averages in the overlap area by linearizing the gamma-corrected RGB

 g_c : global adjustment in the whole image sequence for each color channel c

Solve the least-squares equation

$$\min_{g_c} \sum_{i=0}^{n} \left(g_c \alpha_{c,i} - 1 \right)^2 \quad c \in \{R, G, B\}$$

$$g_c = \frac{\sum_{i=0}^{n} \alpha_{c,i}}{\sum_{i=0}^{n} \alpha_{c,i}^2} c \in \{R, G, B\} (i = 0, 1, ..., n)$$



Basic idea: compute light averages in the overlap area by linearizing the gamma-corrected RGB

$$\alpha_{c,i} = \frac{\sum_{p} \left(P_{c,i-1}(p) \right)^{\gamma}}{\sum_{p} \left(P_{c,i}(p) \right)^{\gamma}} \quad c \in \{R, G, B\} (i = 1, 2, 3, \dots, n)$$

$$g_{c} = \frac{\sum_{i=0}^{n} \alpha_{c,i}}{\sum_{i=0}^{n} \alpha_{c,i}^{2}} c \in \{R, G, B\} (i = 0, 1, \dots, n)$$

$$P_{c,i}(p) \leftarrow \left(g_{c} \alpha_{c,i} \right)^{1/\gamma} P_{c,i}(p), c \in \{R, G, B\} (i = 0, 1, \dots, n)$$



```
def getBestImgIndex(imgs):
    best_index = 0
    best_value = 255
    for index, img in enumerate(imgs):
        current_mean = np.array([np.mean(img[:,:,0]))
for three channels
        diff = np.max(current_mean) - np.min(curre)
        if diff < best_value:  # choose the best_index = index
        best_value = diff
    return best_index
best_img_index = getBestImgIndex(imgs)</pre>
```

```
def colorCorrection(images_temp, shift, bestIndex, gamma=2.2):
    alpha = np.ones((3, len(images_temp)))
    for rightBorder in range(bestIndex+1, len(images_temp)):
        for i in range(bestIndex+1, rightBorder+1):
           I = images_temp[i]
           J = images temp[i-1]
           overlap = I.shape[1] - shift[i-1]
           for channel in range(3):
                alpha[channel, i] = np.sum(np.power(J[:,-overlap-1:,channel], gamma))/np.sum(np.power(I[:,
0:overlap+1, channel], gamma)) # derivative
        G = np.sum(alpha, 1)/np.sum(np.square(alpha), 1)
        for i in range(bestIndex+1, rightBorder+1):
           for channel in range(3):
                images_temp[i][:,:,channel] = np.power(G[channel] * alpha[channel, i], 1.0/gamma) * images_temp
    for leftBorder in range(bestIndex-1, -1, -1):
        for i in range(bestIndex-1, leftBorder-1, -1):
           I = images_temp[i]
           J = images_temp[i+1]
           overlap = I.shape[1] - shift[i-1]
           for channel in range(3):
                alpha[channel, i] = np.sum(np.power(J[:,0:overlap+1,channel], gamma))/np.sum(np.power(I[:,
-overlap-1:,channel],gamma))
        G = np.sum(alpha, 1)/np.sum(np.square(alpha), 1)
        for i in range(bestIndex-1, leftBorder-1, -1):
           for channel in range(3):
                images_temp[i][:,:,channel] = np.power(G[channel] * alpha[channel, i], 1.0/gamma) * images_temp
[i][:,:,channel]
    return images_temp
```



Optimal Seam Finding and Image Labeling





Input images



e: error surface $e = (I_c^o - S_c^o)^2$



E: cumulative minimum squared difference

$$E(h, w) = e(h, w) + min(E(h - 1, w - 1), E(h - 1, w), E(h - 1, w + 1))$$



All possible paths

Optimal path m_c : tracking back the paths with a minimal cost from bottom to top



Panorama image

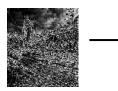


Optimal Seam Finding and Image Labeling





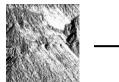
Input images



```
def calcErrorSurface(panorama, curr_img, overlap, channel):
    left = panorama[:, -overlap-1:, channel]
    right = curr_img[:, 0:overlap+1, channel]
    return np.square(left - right)
```









```
def calcSeamPath(E, e):
    h = e.shape[0]
    path = np.zeros((h, 1))
    idx = np.argmin(E[h-1, :])
    path[h-1] = idx
    for h in range(e.shape[0]-2,-1,-1):  # tracking back the paths w:
        w = int(path[h+1][0])
        if w > 0 and E[h, w-1] == E[h+1, w]-e[h+1, w]:
            path[h] = w-1
        elif w < e.shape[1] - 1 and E[h, w+1] == E[h+1, w]-e[h+1, w]:
            path[h] = w+1
        else:
            path[h] = w

path[path==0] = 1
    return path</pre>
```

Panorama image

```
def calcSeam(e):
    E = np.zeros(e.shape)  # cumulative minimum squared difference
    E[0,:] = e[0,:]
    # dynamic programming
    for h in range(1, e.shape[0]):
        for w in range(0, e.shape[1]):
            if w == 0:
                 cost = min(E[h-1, w], E[h-1, w+1])
            elif w == e.shape[1]-1:
                 cost = min(E[h-1, w-1], E[h-1, w])
        else:
                 cost = min(E[h-1, w-1], E[h-1, w], E[h-1, w+1])
            E[h,w] = e[h,w] + cost
    return E
```



Image Blending

Simple linear blending: images are similar in color and luminance after color correction

 δ pixels width on both sides of the seam

$$P_{I_c, \text{ rew}}(p) = \frac{d_1^n P_{I_c}(p) + d_2^n P_{S_c}(p)}{d_1^n + d_2^n}$$

 d_1 , d_2 : distances from pixel p to boundaries

 $P_{I_{c,new}}(p)$: new color of pixel p

n: order



Image Blending

Poisson blending: perform image blending in the gradient domain

 (G_x, G_y) : gradients of source images using the labeling obtained using optimal seams

$$\operatorname{div}(G) = \frac{\partial G_x}{\partial x} + \frac{\partial G_y}{\partial y}$$

$$\nabla^2 I(x, y) = \frac{\partial^2 I(x, y)}{\partial x^2} + \frac{\partial^2 I(x, y)}{\partial y^2}$$

$$I(x+1,y) + I(x-1,y) + I(x,y+1) + I(x,y-1) - 4f(x,y) = G_x(x,y) - G_x(x-1,y) + G_y(x,y) - G_y(x,y-1)$$

solve linear practical differential equation by fixing the colors at the seam and solving new colors I(x, y) over the gradient field









Results





