STA6106 Statistical Computing Project 3

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Problem 1

This problem is to get some codes to perform the support vector data description (SVDD)

a. Write an R function to perform the SVDD.

First, we want to compute the kernel matrix

$$\begin{bmatrix} k(x_1, x_1) & k(x_1, x_2) & \dots & k(x_1, x_n) \\ k(x_2, x_1) & k(x_2, x_2) & \dots & k(x_2, x_n) \\ \dots & \dots & \dots & \dots \\ k(x_n, x_1) & k(x_n, x_2) & \dots & k(x_n, x_n) \end{bmatrix}$$

To do this, we must define a kernel function. This function essentially calculates the distance between each pair of data vectors. The kernlab package includes a function rbfdot() that when called, creates another function that will compute these Gaussian distance.

```
my_kernel <- rbfdot(sigma=0.1)</pre>
```

We have now created a function my_kernel() that will calculate the linear distance between two data vectors for us. We check that this is equivalent to the gaussian function. RBF kernel distance equals to

$$\rho(\sigma(|x-x'|)^2)$$

```
my_matrix <- as.matrix(mydat)
my_kernel(my_matrix[1, ], my_matrix[2, ]) # Distance using my_kernel function</pre>
```

```
[,1]
[1,] 0.9714
```

```
[,1]
[1,] 0.9714
```

It is useful to note here that our new function my_kernel() is a special kind of function - that is, it belongs to the class rbfkernel.

```
class(my_kernel)
```

```
[1] "rbfkernel"
attr(,"package")
[1] "kernlab"
```

Regular R users are familiar with classes like matrix and function, but what is the rbfkernel class?

```
getClass('rbfkernel')
```

```
Class "rbfkernel" [package "kernlab"]
```

Slots:

Name: .Data kpar Class: function list

Extends:

Class "kernel", directly

Class "function", by class "kernel", distance 2

Class "OptionalFunction", by class "kernel", distance 3

Class "PossibleMethod", by class "kernel", distance 3

Class "kfunction", by class "kernel", distance 3

The getClass() command reveals that objects of the class rbfkernel should have two slots, one named .Data that contains a function and one named kpar that contains a list. It also reveals that rbfkernel is an extension of the class kernel, which is itself an extension of the class function. More on this later.

Now that we have defined an R function for applying our kernel function to a pair of data vectors, we can easily create a kernel matrix from our data matrix. There is a handy function in the kernlab package called kernelMatrix() that does exactly this. It requires as arguments kernel, the kernel function to be used, and x, the data matrix from which to compute the kernel matrix. We pass the function our kernel function my_kernel() and our data (mydat) as a matrix.

```
K <- kernelMatrix(kernel=my_kernel, x=as.matrix(mydat))</pre>
```

The function returns a $n \times n$ (66 × 66) matrix of class kernelMatrix.

```
dim(K)
```

[1] 66 66

class(K)

```
[1] "kernelMatrix"
attr(,"package")
[1] "kernlab"
```

The SVDD problem can be stated mathematically as

$$\max_{\alpha} \sum_{i} \alpha_{i} \ k(x_{i}, x_{i}) - \sum_{i,j} \alpha_{i} \alpha_{j} \ k(x_{i}, x_{j})$$

subject to $0 \le \alpha_i \le C$ and $\sum \alpha_i = 1$.

The quadratic solver in the kernlab package (a command called ipop()) solves quadratic programming problems in the form

$$min(c'x + \frac{1}{2}x'Hx)$$

subject to $b \le Ax \le b + r$ and $l \le x \le u$.

To re-state the SVDD problem in the form required by the quadratic solver we first note that the SVDD problem is a miximization, while the solver computes a minimization. Thus, we re-state the SVDD problem as

$$\min_{\alpha} - \sum_{i} \alpha_{i} \ k(x_{i}, x_{i}) + \sum_{i,j} \alpha_{i} \alpha_{j} \ k(x_{i}, x_{j})$$

, subject to the same constraints $0 \le \alpha_i \le C$ and $\sum \alpha_i = 1$.

Thus, if we set

$$x' = [\alpha_1, \alpha_2, ..., \alpha_n]$$

$$H = 2K = 2 \begin{bmatrix} k(x_1, x_1) & k(x_1, x_2) & \dots & k(x_1, x_n) \\ k(x_2, x_1) & k(x_2, x_2) & \dots & k(x_2, x_n) \\ \dots & \dots & \dots & \dots \\ k(x_n, x_1) & k(x_n, x_2) & \dots & k(x_n, x_n) \end{bmatrix}$$

$$c' = (-1) [k(x_1, x_1), k(x_2, x_2), ..., k(x_n, x_n)] = (-1) diag(K)$$

then

$$c'x + \frac{1}{2}x'Hx = (-1)\left[k(x_1, x_1), ..., k(x_n, x_n)\right] \left[\begin{array}{c} \alpha_1 \\ \alpha_2 \\ ... \\ \alpha_n \end{array}\right] + \frac{1}{2}(2)\left[\alpha_1, ..., \alpha_n\right] \left[\begin{array}{cccc} k(x_1, x_1) & k(x_1, x_2) & ... & k(x_1, x_n) \\ k(x_2, x_1) & k(x_2, x_2) & ... & k(x_2, x_n) \\ ... & ... & ... & ... & ... \\ k(x_n, x_1) & k(x_n, x_2) & ... & k(x_n, x_n) \end{array}\right] \left[\begin{array}{c} \alpha_1 \\ \alpha_2 \\ ... \\ \alpha_n \end{array}\right]$$

$$= (-1) \left(k(x_1, x_1) \alpha_1 + \ldots + k(x_n, x_n) \alpha_n \right) + left(\alpha_1 \alpha_1 k(x_1, x_1) + \alpha_1 \alpha_2 k(x_1, x_2) + \ldots + \alpha_n \alpha_n k(x_n, x_n) \alpha_n + left(\alpha_1 \alpha_1 k(x_1, x_1) + \alpha_1 \alpha_2 k(x_1, x_2) + \ldots + \alpha_n \alpha_n k(x_n, x_n) \alpha_n + left(\alpha_1 \alpha_1 k(x_1, x_1) + \alpha_1 \alpha_2 k(x_1, x_2) + \ldots + \alpha_n \alpha_n k(x_n, x_n) \alpha_n + left(\alpha_1 \alpha_1 k(x_1, x_1) + \alpha_1 \alpha_2 k(x_1, x_2) + \ldots + \alpha_n \alpha_n k(x_n, x_n) \alpha_n + left(\alpha_1 \alpha_1 k(x_1, x_1) + \alpha_1 \alpha_2 k(x_1, x_2) + \ldots + \alpha_n \alpha_n k(x_n, x_n) \alpha_n + left(\alpha_1 \alpha_1 k(x_1, x_1) + \alpha_1 \alpha_2 k(x_1, x_2) + \ldots + \alpha_n \alpha_n k(x_n, x_n) \alpha_n + left(\alpha_1 \alpha_1 k(x_1, x_1) + \alpha_1 \alpha_2 k(x_1, x_2) + \ldots + \alpha_n \alpha_n k(x_n, x_n) \alpha_n + left(\alpha_1 \alpha_1 k(x_1, x_1) + \alpha_1 \alpha_2 k(x_1, x_2) + \ldots + \alpha_n \alpha_n k(x_n, x_n) \alpha_n + left(\alpha_1 \alpha_1 k(x_1, x_1) + \alpha_1 \alpha_2 k(x_1, x_2) + \ldots + \alpha_n \alpha_n k(x_n, x_n) \alpha_n + left(\alpha_1 \alpha_1 k(x_1, x_1) + \alpha_1 \alpha_2 k(x_1, x_2) + \ldots + \alpha_n \alpha_n k(x_n, x_n) \alpha_n + left(\alpha_1 \alpha_1 k(x_1, x_1) + \alpha_1 \alpha_2 k(x_1, x_2) + \ldots + \alpha_n \alpha_n k(x_n, x_n) \alpha_n + left(\alpha_1 \alpha_1 k(x_1, x_1) + \alpha_1 \alpha_2 k(x_1, x_2) + \ldots + \alpha_n \alpha_n k(x_n, x_n) \alpha_n + left(\alpha_1 \alpha_1 k(x_1, x_1) + \alpha_n k(x_1, x_2) + \ldots + \alpha_n k(x_n, x_n) \alpha_n + left(\alpha_1 \alpha_1 k(x_1, x_1) + \alpha_n k(x_1, x_2) + \ldots + \alpha_n k(x_n, x_n) \alpha_n + left(\alpha_1 \alpha_1 k(x_1, x_1) + \alpha_n k(x_1, x_2) + \ldots + \alpha_n k(x_n, x_n) \alpha_n + left(\alpha_1 \alpha_1 k(x_1, x_1) + \alpha_n k(x_1, x_2) + \ldots + \alpha_n k(x_n, x_n) \alpha_n + left(\alpha_1 \alpha_1 k(x_1, x_2) + \ldots + \alpha_n k(x_n, x_n) \alpha_n + left(\alpha_1 \alpha_1 k(x_1, x_2) + \ldots + \alpha_n k(x_n, x_n) \alpha_n + left(\alpha_1 \alpha_1 k(x_1, x_2) + \ldots + \alpha_n k(x_n, x_n) \alpha_n + left(\alpha_1 \alpha_1 k(x_1, x_2) + \ldots + \alpha_n k(x_n, x_n) \alpha_n + left(\alpha_1 \alpha_1 k(x_1, x_2) + \ldots + \alpha_n k(x_n, x_n) \alpha_n + left(\alpha_1 \alpha_1 k(x_1, x_2) + \ldots + \alpha_n k(x_n, x_n) \alpha_n + left(\alpha_1 \alpha_1 k(x_1, x_2) + \ldots + \alpha_n k(x_n, x_n) \alpha_n + left(\alpha_1 \alpha_1 k(x_1, x_2) + \ldots + \alpha_n k(x_n, x_n) \alpha_n + left(\alpha_1 \alpha_1 k(x_1, x_2) + \ldots + \alpha_n k(x_n, x_n) \alpha_n + left(\alpha_1 k(x_1, x_2) + \ldots + \alpha_n k(x_n, x_n) \alpha_n + left(\alpha_1 k(x_1, x_2) + \ldots + \alpha_n k(x_n, x_n) \alpha_n + left(\alpha_1 k(x_1, x_2) + \ldots + \alpha_n k(x_n, x_n) \alpha_n + left(\alpha_1 k(x_1, x_2) + \ldots + \alpha_n k(x_n, x_n) \alpha_n + left(\alpha_1 k(x_1, x_2) + \ldots + \alpha_n k(x_n, x_n) \alpha_n + left(\alpha_1 k(x_1, x_2) + \ldots + \alpha_n k(x_n,$$

$$= -\sum_{i} \alpha_i \ k(x_i, x_i) + \sum_{i,j} \alpha_i \alpha_j \ k(x_i, x_j)$$

To re-state the constraints of the SVDD problem in the form required by the quadratic solver, we set

$$b = 1, A = [1, 1, ..., 1], x = \begin{bmatrix} \alpha_1 \\ \alpha_2 \\ ... \\ \alpha_n \end{bmatrix}, r = 0$$

$$l = \begin{bmatrix} 0 \\ 0 \\ \dots \\ 0 \end{bmatrix}, x = \begin{bmatrix} \alpha_1 \\ \alpha_2 \\ \dots \\ \alpha_n \end{bmatrix}, u = \begin{bmatrix} C \\ C \\ \dots \\ C \end{bmatrix}$$

then $b \leq Ax \leq b + r$ is equivalent to

$$1 \le [1, 1, \dots, 1] \begin{bmatrix} \alpha_1 \\ \alpha_2 \\ \dots \\ \alpha_n \end{bmatrix} \le 1 + 0$$

or

$$1 \le \sum \alpha_i \le 1$$

and $l \le x \le u$ is equivalent to $0 \le \alpha_i \le C$.

Using the re-formulation of the problem (and C=1), we pass the appropriate objects to the ipop() quadratic programming solver included in the kernlab package. this returns the vector of α 's that minimize the stated problem $min(c'x + \frac{1}{2}x'Hx)$.

```
C <- 1
my_c <- (-1)*diag(K)
my_H <- (2)*K
my_A <- rep(1, nrow(my_matrix))
my_b <- 1
my_l <- rep(0, nrow(my_matrix))
my_u <- rep(C, nrow(my_matrix))
my_r <- 0
my_solution <- ipop(c=my_c, H=my_H, A=my_A, b=my_b, l=my_l, u=my_u, r=my_r, maxiter=300, margin=1E-6)
my_alphas <- my_solution@primal # use @ symbol to access s4 slot</pre>
```

Note that the margin argument specifies how closely the solution obeys the constraints, so the α values found in the solution are not exact, but are accurate to at least six decimal places (since we set margin to 1E-6).

```
my_alphas <- round(my_alphas, abs(log10(1E-6)))</pre>
```

We check to make sure our α_i 's sum to one,

```
sum(my_alphas)
```

[1] 1

and that none of them are less than zero.

```
any(my_alphas < 0)</pre>
```

[1] FALSE

We believe we have found a solution to the SVDD problem, so we wrap the commands shown above into a function that takes as input a data matrix x, a kernel function k, and a tolerance tol (to be passed to ipop()'s margin argument). The function returns an object of class SVDD (an S4 class that we have defined, but its definition is not shown).

```
svdd <- function(x, k, cost, tol=1E-6){</pre>
  K <- kernelMatrix(kernel=k, x=x)</pre>
  n \leftarrow nrow(x)
  solution \leftarrow ipop(c=(-1)*diag(K)),
                     H=2*K,
                     A=rep(1, n),
                     b=1,
                     l=rep(0, n),
                     u=rep(cost, n),
                     r=0,
                     maxiter=300,
                    margin=tol)
  alphas <- solution@primal</pre>
  alphas <- round(alphas, abs(log10(tol))) # round based on tol
  svs <- x[alphas > 0, ] # these are the support vectors
  return(new('SVDD',
              data=x,
              cost=as.numeric(cost),
              alphas=alphas,
              support_vectors=svs,
              kernel=k,
              tolerance=tol,
              fun_call=match.call()
              ))
  }
```

We test the function on our test data set and inspect it using a summary method, which we defined with the class definition for the class SVDD. (SVDD class definition and summary method definition are not shown for the sake of brevity.)

```
# supplying no value to tol implies it should use the default value tol = 1E-6
euclidean_solution <- svdd(x=my_matrix, k=my_kernel, cost=5)
summary(euclidean_solution)</pre>
```

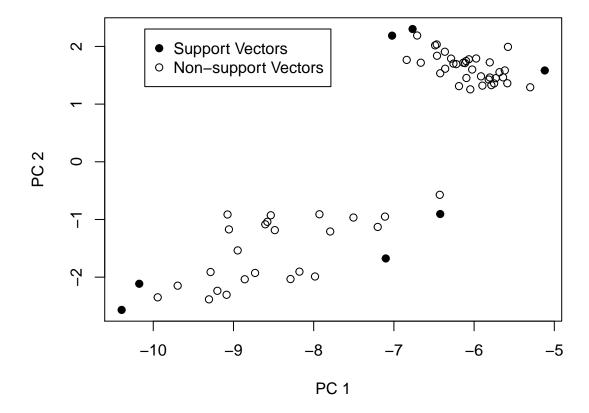
SVDD object using kernel function rbfkernel and cost = 5: 7 support vectors identified out of 66 observations.

```
V1 V2 V3 V4
[1,] 4.3 3.0 1.1 0.1
[2,] 5.8 4.0 1.2 0.2
[3,] 5.7 4.4 1.5 0.4
[4,] 5.0 2.0 3.5 1.0
[5,] 7.6 3.0 6.6 2.1
[6,] 4.9 2.5 4.5 1.7
[7,] 7.2 3.6 6.1 2.5
```

We examine our solution to see if it makes sense. The support vectors found should be the "edge cases" of the input data. Since the input data is defined in four dimensions, it is difficult to visualize all of its variability on a simple X-Y plot. To capture as much of the data's variability as possible in our plot, we plot the data along it's first two principal components and shade the support vectors. We abstract this plot away by defining a plot method for the SVDD class defined earlier. We invoke our plot method on our SVDD object euclidean_solution and the plot below is produced.

plot(euclidean_solution)

Cost = 5



b. Write an R function to perform the prediction of a new observation using SVDD.

The distance from a data vector to the center of the SVDD spheroid in the kernel space is given by

$$R_{x^*}^2 = k(x^*, x^*) - 2\sum_{i=1}^n \alpha_i k(x^*, x_j) + \sum_{i,j=1}^n \alpha_i \alpha_j k(x_i, x_j)$$

For the purpose of predicting outliers, we are interested in the radius of the SVDD spheroid in the kernel space, that is, the distance from the center of the spheroid to the very edge of the spheroid (in the kernel space). Any new observation farther away than this from the spheroid center would be identified as an outlier.

If we identify just the support vectors of a data set and find their distance from the spheroid center, we can determine the radius of the spheroid and use this to score new observations. We break the equation above into three terms to be calculated.

$$Term 1 = k(x^*, x^*)$$

Term 2 =
$$(-2)\sum_{i=1}^{n} \alpha_i k(x^*, x_j)$$

$$Term \ 3 = \sum_{i,j=1}^{n} \alpha_i \alpha_j k(x_i, x_j)$$

Term 1 is easily calculated using the kernel function passed to the svdd() function. Term 2 includes the α_i values, many of which are zero, so its computation can be simplified. Only the support vectors have a non-zero α_i , so we can reduce $(-2)\sum_{i=1}^n \alpha_i k(x^*, x_j)$ to $(-2)\sum_{i\in s} \alpha_i k(x^*, x_j)$, where s is the set of support vectors only. Term 3 can similarly be reduced. Also, note that while terms 1 and 2 differ for each data vector, term 3 is the same for every vector in a data set, so it only needs to be calculated once. For a data set with many support vectors, this may save considerable time.

There are two functions in the kernlab package that aid in the calculation of terms 1 and 2. The function kernelMult() calculates $\sum_{i=1}^{n} z_i k(x_i, x_j)$, so term 2 can be calculated by (-2)*kernelMult(kernel, support_vectors, alphas). The function kernelPol() computes $z_i z_j k(x_i, x_j)$, so term 3 can be calculated by sum(kernelPol(kernel, support_vectors, sv_alphas)).

Once R^2 is found for each support vector, the set of these may be averaged to find a suitable estimate for the radius of the SVDD spheroid. The calculated R^2 should be the same for all support vectors, but imprecision in the quadratic solver may cause this not to be the case.

Once the radius of the SVDD spheroid is obtained, a new observation may be scored. A new data vector z is accepted when its distance from the center of the spheroid is less than the radius of the spheroid, that is

$$k(z,z) - 2\sum_{i=1}^{n} \alpha_{i}k(z,x_{j}) + \sum_{i=1}^{n} \alpha_{i}\alpha_{j}k(x_{i},x_{j})$$

This is calculated in the same way as the distances of the support vectors from the center. Note that "term 3" appears here as well and may be reused again, saving even more computation.

We use these results to define a predict method for the class SVDD. The function takes the argument type, which if set to "boolean" will cause the method to return a vector of 0's and 1's, indicating a new data vector has been accepted or rejected, respectively. If the type argument is set to "radii", the method returns a list object containing the radius of the SVDD spheroid and the R^2 values for each new data vector.

```
setMethod(
    f='predict',
    signature='SVDD',
    definition=function(object, newdata, type=c('radii', 'boolean')){
        # isolate non-zero alpha values (corresponding to support vectors)
        sv_alphas <- object@alphas[object@alphas > 0]
        # calculate k(x_s, x_s) for each support vector
        term1 <- apply(object@support_vectors, 1, function(x) object@kernel(x, x))
        # kernelMult computes (-2) sum(alpha_i k(x_s, x_i)) for each support vector x_s
        term2 <- (-2)*kernelMult(kernel=object@kernel, x=object@support_vectors, z=sv_alphas)
        # kernelPol computes z_i z_j k(x_i, x_j)
        term3 <- sum(kernelPol(kernel=object@kernel, x=object@support_vectors, z=sv_alphas))
        radii <- term1+term2+term3 # term1 and term2 vectors, term3 scalar
        r2 <- mean(radii)</pre>
```

```
z1 <- apply(newdata, 1, function(x) object@kernel(x, x))
z2 <- (-2)*kernelMult(kernel=object@kernel, x=newdata, y=object@support_vectors, z=sv_alphas)
z_rad <- z1+z2+term3
if(type=='radii'){
   return(list(mod_r2=r2, newdata_r2=c(z_rad)))
   }else{
      return(as.numeric(z_rad>r2))
   }
})
```

We demonstrate the function below on the test data set.

```
predict(euclidean_solution, newdata=as.matrix(mydat2), type='boolean')
[71] 0 0 0 0 0 0
predict(euclidean_solution, newdata=as.matrix(mydat2), type='radii')
$mod_r2
[1] 0.5813
$newdata_r2
[1] 0.5385 0.4756 0.4751 0.5114 0.4946 0.5146 0.5007 0.4990 0.4991 0.4850
[11] 0.5368 0.5024 0.5101 0.5507 0.5132 0.5085 0.5070 0.5175 0.5106 0.5182
[21] 0.5272 0.5326 0.5074 0.4958 0.5048 0.5208 0.5216 0.5000 0.5077 0.5134
[31] 0.5107 0.5220 0.5503 0.4911 0.5126 0.5184 0.4980 0.5072 0.5331 0.5014
[41] 0.4945 0.4935 0.5057 0.5039 0.4945 0.5257 0.4988 0.6482 0.6358 0.5484
[51] 0.5244 0.5328 0.6014 0.5041 0.5164 0.5294 0.5010 0.4989 0.5109 0.5299
[61] 0.5425 0.6471 0.5164 0.5021 0.5382 0.5739 0.5518 0.5019 0.5006 0.5139
[71] 0.5271 0.5388 0.5215 0.5260 0.5450 0.5247
```

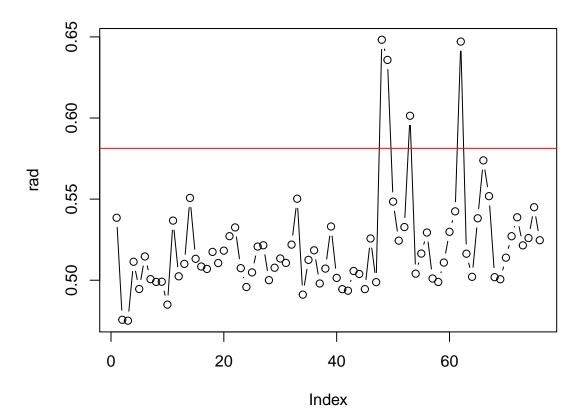
c. Write an R function for detecting potential outliers for a new set of observations, along with the upper threshold.

This task is trivial once the predict method above is defined. We call the predict method to return the R^2 for each

```
detect_outliers <- function(SVDD_obj, newdata, plot=T){
    x_mat <- as.matrix(newdata) # in case newdata is a data.frame
    pred <- predict(SVDD_obj, newdata=x_mat, type='radii')
    rad <- pred$newdata_r2
    r2 <- pred$mod_r2
    outlier_ind <- rad>r2
    num_outliers <- sum(outlier_ind)

if(plot=T){
    plot(rad, type='b')
    abline(h=r2, col='red')
}</pre>
```

```
msg <- paste(num_outliers, 'outliers out of', nrow(x_mat), 'observations detected. \n')
cat(msg)
return('outliers'=which(outlier_ind))
}
detect_outliers(SVDD_obj=euclidean_solution, newdata=mydat2)</pre>
```



4 outliers out of 76 observations detected.

[1] 48 49 53 62

Problem 2

The goal of problem 2 is to perform the support vector data description (SVDD) using the Mahalanobis kernel function. We will simplify the problem by using the identity function for g.

a. Write an R function to compute the Mahalanobis kernel distance $d_g(x)$

We will do you one better - we first define a class malhalanobis and then define a function to define a Mahalanobis kernel function given a covariance matrix. It's a function that defines a function that is of class malhalanobis (class definition not shown).

```
malhalanobis <- function(covmat){
  rval <- function(x, y = NULL) {
    if (!is(x, 'vector'))
      stop('x must be a vector')
    if (!is(y, 'vector') && !is.null(y))
      stop('y must be a vector')
    if (is(x, 'vector') && is.null(y)) {
      t(x)%*%solve(covmat)%*%x
      }
    if (is(x, 'vector') && is(y, 'vector')) {
      if (!length(x) == length(y))
         stop('number of dimension must be the same on both data points')
      t(x)%*%solve(covmat)%*%y
      }
    }
    return(new('malhalanobis', .Data=rval, kpar=list(covmat=covmat)))
}</pre>
```

We test the function by passing it the covariance matrix of our training data set and then an arbitrary point.

b. Write an R function to perform the Mahalanobis kernel SVDD.

The flexibility of our earlier code pays off here. The function svdd() defined earlier takes as an argument kernel, so we pass it our kernel function my_mal_kernel and our data set mydat and reuse the function.

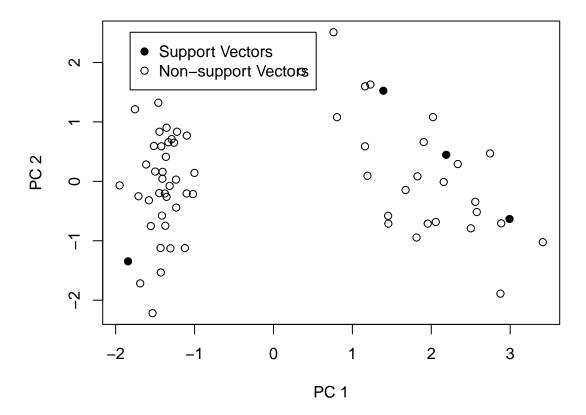
```
mal_solution <- svdd(as.matrix(mydat), k=my_mal_kernel, cost=1)
summary(mal_solution)</pre>
```

SVDD object using kernel function malhalanobis and cost = 1: 4 support vectors identified out of 66 observations.

```
V1 V2 V3 V4
[1,] 5.2 4.1 1.5 0.1
[2,] 6.0 2.2 4.0 1.0
[3,] 7.3 2.9 6.3 1.8
[4,] 5.8 2.8 5.1 2.4
```

plot(mal_solution)

Cost = 1

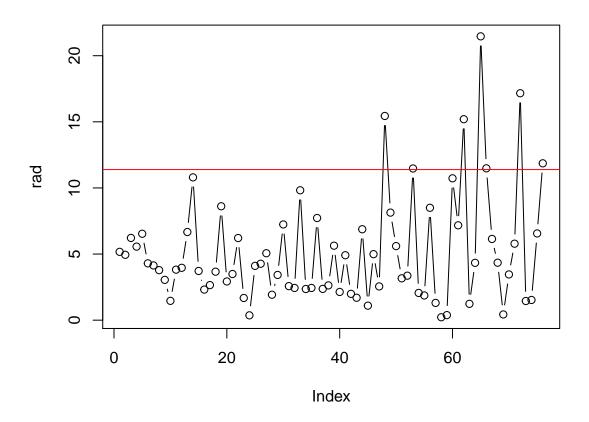


c. Write an ${\tt R}$ function to perform the prediction of a new observation using the Mahalanobis kernel SVDD.

Again, our flexible code earlier pays off. We can reuse our predict method for any SVDD object.

d. Write an R function for detecting potential outliers for a new set of observations, along with the upper threshold.

We reuse our function from earlier again.



7 outliers out of 76 observations detected.

[1] 48 53 62 65 66 72 76

Appendix with R code

```
class(K)
C <- 1
my_c <- (-1)*diag(K)
my_H <- (2)*K
my_A <- rep(1, nrow(my_matrix))</pre>
my_b < -1
my_l <- rep(0, nrow(my_matrix))</pre>
my_u <- rep(C, nrow(my_matrix))</pre>
my r <- 0
my_solution <- ipop(c=my_c, H=my_H, A=my_A, b=my_b, l=my_l, u=my_u, r=my_r, maxiter=300, margin=1E-6)
my_alphas <- my_solution@primal # use @ symbol to access s4 slot
my_alphas <- round(my_alphas, abs(log10(1E-6)))</pre>
sum(my_alphas)
any(my_alphas < 0)</pre>
svdd <- function(x, k, cost, tol=1E-6){</pre>
  K <- kernelMatrix(kernel=k, x=x)</pre>
  n \leftarrow nrow(x)
  solution <- ipop(c=(-1)*diag(K)),
                    H=2*K,
                    A=rep(1, n),
                    b=1.
                    l=rep(0, n),
                    u=rep(cost, n),
                    r=0,
                    maxiter=300,
                    margin=tol)
  alphas <- solution@primal
  alphas <- round(alphas, abs(log10(tol))) # round based on tol
  svs <- x[alphas > 0, ] # these are the support vectors
  return(new('SVDD',
              data=x,
              cost=as.numeric(cost),
              alphas=alphas,
              support_vectors=svs,
             kernel=k,
              tolerance=tol,
              fun call=match.call()
  }
# supplying no value to tol implies it should use the default value tol = 1E-6
euclidean_solution <- svdd(x=my_matrix, k=my_kernel, cost=5)</pre>
summary(euclidean_solution)
setMethod(
  f='plot',
  signature='SVDD',
  definition=function(x, y){
    if(class(x@kernel) == 'rbfkernel'){
      rotated_data <- prcomp(x@data, center=F, scale=F)$x</pre>
    }else{
     rotated_data <- prcomp(x@data, center=T, scale=T)$x</pre>
```

```
SV <- ifelse(x@alphas > 0, 19, 1)
    legend_x <- quantile(rotated_data[, 'PC1'], 0.02)</pre>
    legend_y <- quantile(rotated_data[, 'PC2'], 1)</pre>
    plot(rotated_data[, 'PC1'], rotated_data[, 'PC2'], type='p', pch=SV, xlab='PC 1', ylab='PC 2')
    legend(x=legend_x, y=legend_y, pch=c(19, 1), legend=c('Support Vectors', 'Non-support Vectors'))
    title(paste('Cost =', x@cost))
plot(euclidean solution)
setMethod(
  f='predict',
  signature='SVDD',
  definition=function(object, newdata, type=c('radii', 'boolean')){
    # isolate non-zero alpha values (corresponding to support vectors)
    sv_alphas <- object@alphas[object@alphas > 0]
    # calculate k(x_s, x_s) for each support vector
    term1 <- apply(object@support_vectors, 1, function(x) object@kernel(x, x))</pre>
    # kernelMult computes (-2) sum(alpha_i k(x_s, x_i)) for each support vector x_s
    term2 <- (-2)*kernelMult(kernel=object@kernel, x=object@support_vectors, z=sv_alphas)</pre>
    # kernelPol computes z_i z_j k(x_i, x_j)
    term3 <- sum(kernelPol(kernel=object@kernel, x=object@support_vectors, z=sv_alphas))</pre>
    radii <- term1+term2+term3 # term1 and term2 vectors, term3 scalar
    r2 <- mean(radii)
    z1 <- apply(newdata, 1, function(x) object@kernel(x, x))</pre>
    z2 <- (-2)*kernelMult(kernel=object@kernel, x=newdata, y=object@support_vectors, z=sv_alphas)</pre>
    z rad <- z1+z2+term3
    if(type=='radii'){
      return(list(mod_r2=r2, newdata_r2=c(z_rad)))
        return(as.numeric(z_rad>r2))
    })
predict(euclidean_solution, newdata=as.matrix(mydat2), type='boolean')
predict(euclidean_solution, newdata=as.matrix(mydat2), type='radii')
detect_outliers <- function(SVDD_obj, newdata, plot=T){</pre>
  x_mat <- as.matrix(newdata) # in case newdata is a data.frame</pre>
  pred <- predict(SVDD_obj, newdata=x_mat, type='radii')</pre>
  rad <- pred$newdata_r2
  r2 <- pred$mod_r2
  outlier_ind <- rad>r2
  num_outliers <- sum(outlier_ind)</pre>
  if(plot==T){
    plot(rad, type='b')
    abline(h=r2, col='red')
  }
  msg <- paste(num_outliers, 'outliers out of', nrow(x_mat), 'observations detected. \n')</pre>
  return('outliers'=which(outlier_ind))
}
```

```
detect_outliers(SVDD_obj=euclidean_solution, newdata=mydat2)
malhalanobis <- function(covmat){</pre>
  rval <- function(x, y = NULL) {</pre>
    if (!is(x, 'vector'))
      stop('x must be a vector')
    if (!is(y, 'vector') && !is.null(y))
      stop('y must be a vector')
    if (is(x, 'vector') && is.null(y)) {
      t(x)%*%solve(covmat)%*%x
    if (is(x, 'vector') && is(y, 'vector')) {
      if (!length(x) == length(y))
        stop('number of dimension must be the same on both data points')
      t(x)%*%solve(covmat)%*%y
      }
    }
  return(new('malhalanobis', .Data=rval, kpar=list(covmat=covmat)))
my_mal_kernel <- malhalanobis(covmat=cov(mydat))</pre>
class(my_mal_kernel)
my_mal_kernel(c(1, 1, 1, 1), c(1, 1, 1, 1)) # test case
mal_solution <- svdd(as.matrix(mydat), k=my_mal_kernel, cost=1)</pre>
summary(mal_solution)
plot(mal_solution)
predict(mal_solution, newdata=as.matrix(mydat2), type='boolean')
detect_outliers(SVDD_obj=mal_solution, newdata=mydat2)
```