

CONTROLLER PIN MAPPING

VNH 5019 #1

IN A	D43
IN B	D47
PWM	D13
CS	A8

VNH 5019 #2

IN A	D39
IN B	D41
PWM	D12
CS	A9

VNH 5019 #3

IN A	D35
IN B	D37
PWM	D10
CS	A10

VNH 5019 #4

IN A	D31
IN B	D33
PWM	D9
CS	A11

Analog

A0	A7
A1	A6
A2	A5
A3	A4
5V	GND

Test Switch

D22

PWM

D2	D8
D3	D7
D4	D6
D5	-
5V	GND

Digital

D34	D20
D32	D21
D30	D24
D28	D26
5V	GND

ICSP

Reset	D52	D50
GND	D51	5V

Serial Comm.

5V	5V
GND	GND
D16	D14
D17	D15
-	-

Receiver

D36
D38
D40
D42
D48
D49
5V
GND

LED

D29	D27	D25	D23
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X-Bee

5V
GND
D18
D19
-

Servo

D44	D46	D45	D11
5V,3A	5V,3A	5V,3A	5V,3A
GND	GND	GND	GND

Serial Comm.

Rx 0	USB
Tx 0	USB
Rx 1	D19
Tx 1	D18
Rx 2	D17
Tx 2	D16
Rx 3	D15
Tx 3	D14

SPI Comm.

MISO	D50
MOSI	D51
SCK	D52
SS	D53*

TWI Comm.

SDA	D20
SCL	D21

Interrupt

INT 0	D2
INT 1	D3
INT 2	D21
INT 3	D20
INT 4	D19
INT 5	D18

Specification

Microcontroller	Arduino Mega2560 R
Processor	ATmega 2560
Motor Driver	Pololu VNH5019 Singl
Clock Speed	16 MHz
Flash Memory	256 KB
RAM/ ROM	8 KB/ 4 KB
PWM	8-Bit
Power Input	7-12VDC Rocommende
DC Jack	2.1mm Center-Positiv

ARDUINO MEGA 2560 R3 PIN MAPPING

Pin Name	Device
Digital Pin 0 (RX0)	USB
Digital Pin 1 (TX0)	USB
Digital Pin 2 (PWM, INT0)	PWM 1
Digital Pin 3 (PWM, INT1)	PWM 3
Digital Pin 4 (PWM)	PWM 5
Digital Pin 5 (PWM)	PWM 7
Digital Pin 6 (PWM)	PWM 6
Digital Pin 7 (PWM)	PWM 4
Digital Pin 8 (PWM)	PWM 2
Digital Pin 9 (PWM)	VNH5019 #4 PWM
Digital Pin 10 (PWM)	VNH5019 #3 PWM
Digital Pin 11 (PWM)	Servo #4 PWM
Digital Pin 12 (PWM)	VNH5019 #2 PWM
Digital Pin 13 (PWM, LED)	VNH5019 #1 PWM
Digital Pin 14 (TX3)	Serial 6
Digital Pin 15 (RX3)	Serial 8
Digital Pin 16 (TX2)	Serial 5
Digital Pin 17 (RX2)	Serial 7
Digital Pin 18 (TX1, INT5)	X Bee 3
Digital Pin 19 (RX1, INT4)	X Bee 4
Digital Pin 20 (SDA, INT3)	Digital 2
Digital Pin 21 (SCL, INT2)	Digital 4
Digital Pin 22	Test Switch
Digital Pin 23	LED 4
Digital Pin 24	Digital 6
Digital Pin 25	LED 3
Digital Pin 26	Digital 8
Digital Pin 27	LED 2
Digital Pin 28	Digital 7
Digital Pin 29	LED 1
Digital Pin 30	Digital 5
Digital Pin 31	VNH5019 #4 INA
Digital Pin 32	Digital 3
Digital Pin 33	VNH5019 #4 INB
Digital Pin 34	Digital 1
Digital Pin 35	VNH5019 #3 INA

Pin Name	Device
Digital Pin 36	Receiver 1
Digital Pin 37	VNH5019 #3 INB
Digital Pin 38	Receiver 2
Digital Pin 39	VNH5019 #2 INA
Digital Pin 40	Receiver 3
Digital Pin 41	VNH5019 #2 INB
Digital Pin 42	Receiver 4
Digital Pin 43	VNH5019 #1 INA
Digital Pin 44 (PWM)	Servo #1 PWM
Digital Pin 45 (PWM)	Servo #3 PWM
Digital Pin 46 (PWM)	Servo #2 PWM
Digital Pin 47	VNH5019 #1 INB
Digital Pin 48	Receiver 5
Digital Pin 49	Receiver 6
Digital Pin 50 (MISO)	ICSP
Digital Pin 51 (MOSI)	ICSP
Digital Pin 52 (SCK)	ICSP
Digital Pin 53 (SS)	- *

Pin Name	Device
Analog Pin 0	Analog 1
Analog Pin 1	Analog 3
Analog Pin 2	Analog 5
Analog Pin 3	Analog 7
Analog Pin 4	Analog 8
Analog Pin 5	Analog 6
Analog Pin 6	Analog 4
Analog Pin 7	Analog 2
Analog Pin 8	VNH5019 #1 CS
Analog Pin 9	VNH5019 #2 CS
Analog Pin 10	VNH5019 #3 CS
Analog Pin 11	VNH5019 #4 CS
Analog Pin 12	- *
Analog Pin 13	- *
Analog Pin 14	- *
Analog Pin 15	- *

* Pin is not provided on the expanded port.

POLOLU VNH5019 SINGLE OPERATION

IN A	IN B	PWM	OUT A	OUT B	Operating Mode
1	1	1	H	H	Brake to Vcc
1	0	1	H	L	Clockwise
0	1	1	L	H	Counterclockwise
0	0	1	L	L	Brake to Ground

DEFAULT CONTROLLER OPERATION

Device	Motor Driver	Receiver Channel	Operation
Motor 1	1	1	Drive Motor 1
Motor 2	2	2	Drive Motor 2
Motor 3 (Left Wheel)	3	3 and 4	Control Robot Direction
Motor 4 (Right Wheel)	4	3 and 4	Control Robot Direction
-	-	5	Unassigned
-	-	6	Unassigned

