

view_frames Result
Recorded at time: 1615329444.305

odom

base_link

Broadcaster: /ekf_localization
Average rate: 50.180 Hz
Most recent transform: 1615329443.973 (0.332 sec old)
Buffer length: 4.982 sec

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1615329444.305 sec old)
Buffer length: 0.000 sec

chassis_link

unit_base_link

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1615329444.305 sec old)
Buffer length: 0.000 sec

front_fender_link

mid_mount

rear_mount

imu_link

navsat_link

rear_fender_link

front_left_wheel_link

front_right_wheel_link

rear_left_wheel_link

rear_right_wheel_link

realsense_link

flirL_link

flirR_link

os_sensor

os_imu

os_lidar

camera_realsense_lens

camera_realsense

camera_realsense_gazebo

