Yang Yang

 ♦ 1115 W 25th St, Los Angeles, CA 90007
 ⋈ yyang672@usc.edu
 +1 213 554 4842

Ø Personal Website in Linkedin
 ■ Google Scholar

Education

University of Southern California

Los Angeles, United States

PhD in Mechanical Engineering

Aug 2025 - Present

Advisor: Hangbo Zhao

Sichuan University

B. Eng in Mechanics with Honors

Chengdu, China
Sep 2021 – Jun 2025

o GPA: 3.83/4.0 (90.31/100)

 Courses: Theoretical Mechanics, Material Mechanics, Mathematical Methods in Engineering, Continuum Mechanics, Structural Mechanics, Fluid Mechanics, Computational Mechanics, Experimental Mechanics, Vibration Mechanics

Research Interests

My research interests are in Soft Robotics, Sensors, and Mechanics. They encompass tactile sensing, computational mechanics, and multi-model sensors. I am particularly interested in the design of new types of sensors and their application in soft robotics.

Experience

The Chinese University of Hong Kong Research Assistant, advised by Hongliang Ren	Hong Kong SAR, China Oct 2024 – May 2025
Tsinghua University Summer Research Intern, advised by Wenbo Ding	Shenzhen, China Jun 2024 – Aug 2024
Sichuan University Teaching Assistant, advised by Hong Zhang	Chengdu, China Feb 2024 – Jun 2024
Shanghai Jiao Tong University Summer Research Intern, advised by Daolin Ma	Shanghai, China Jun 2023 – Aug 2023

Honors and Awards

USC Viterbi School of Engineering Graduate School Fellowship	2025
Top 100 Undergraduate Students of Sichuan University	2025
Second Prize of Academic Scholarship at Sichuan University	2024
First Prize of Sichuan Province Mechanics Competition Individual Race	2023
First Prize of Sichuan Province Mechanics Competition Group Race (Leader)	2023
First Prize of Academic Scholarship at Sichuan University	2023
Outstanding Students of Sichuan University	2023

Publications

Conformable Vision-Based Tactile Sensor with Enhanced Soft Elastomer Design for Palpating Irregular Anatomical Surfaces

Yang Yang, Tao Zhang, Yupeng Wang, Wenchao Yue, Tangyou Liu, Hongliang Ren International Conference on Biomimetic Intelligence and Robotics (ICBIR) 2025, Accepted

Vitire: A Bimodel Visuotactile Tire with High-Resolution Sensing Capability

Shoujie Li[†], Jianle Xu[†], Tong Wu, **Yang Yang**, Yanbo Chen, Xueqian Wang, Wenbo Ding, Xiao-ping Zhang IEEE Transactions on Mechatronics, [Paper]

Three-dimension Tip Force Perception and Axial Contact Location Identification for Flexible Endoscopes using Tissue-compliant Soft Distal Attachment Cap Sensors

Tao Zhang[†], **Yang Yang**[†], Yang Yang, Huxin Gao, Jiewen Lai, Hongliang Ren International Conference on Robotics and Automation (ICRA 2025), [Paper]

Machine Learning-and Finite Element-Based Temperature-and Rate-Dependent Plasticity Model: Application to the Tensile Behavior

Bo Zhang, Yang Yang, Hao Wu, Yida Zhang, Quanyi Wang, Hong Zhang, Yongjie Liu, Qingyuan Wang Journal of Materials Engineering and Performance, [Paper]

A deep learning approach for low-cycle fatigue life prediction under thermal—mechanical loading based on a novel neural network model

Yang Yang, Bo Zhang, Hao Wu, Yida Zhang, Hong Zhang, Yongjie Liu, Qingyuan Wang Engineering Fracture Mechanics, [Paper]

Skills

Programming: C++, Python (Pytorch)

Platform/System: Finite Element Method, SoildWorks, MATLAB, Ubuntu, Linux, VS Code, Gazebo, ROS

Languages: Mandarin (Native), English (Fluent)