

sol<sup>n</sup>. 3(A) In polar co-ordinates centered at O,  
The position vector of the car at any time  $0 \leq t < t_0$

$$\vec{r}(t) = v_0 t \hat{\lambda} \quad \text{such that } \hat{\lambda} \text{ makes an angle} \\ \text{--- (1)} \quad \omega_0 t \text{ with the } x\text{-axis}$$

$$\Rightarrow \dot{\vec{r}}(t) = v_0 \hat{\lambda} + v_0 t \omega_0 \hat{\theta} \quad \text{--- (2)}$$

$$\Rightarrow \ddot{\vec{r}}(t) = 2v_0 \omega_0 \hat{\theta} - v_0 t \omega_0^2 \hat{\lambda} \quad \text{--- (3)}$$

If  $\mu g > 2v_0 \omega_0$  then the frictional forces acting on the wheels of the car can support the acceleration in eq<sup>n</sup> (3) for  $0 < t < t_0$ .

$$\vec{F} = M(2v_0 \omega_0 \hat{\theta} - v_0 t \omega_0^2 \hat{\lambda})$$

$\Rightarrow$  The force exerted by the wheels of the car on the platform

$$\vec{F}' = -\vec{F} = M(v_0 \omega_0^2 t \hat{\lambda} - 2v_0 \omega_0 \hat{\theta}) \quad \text{--- (4)}$$

clearly at  $t = t_0$   $|\vec{F}| = \mu M g$

$$\Rightarrow 4v_0^2 \omega_0^2 + v_0^2 t_0^2 \omega_0^4 = \mu^2 g^2$$

$$\Rightarrow t_0^2 = (\mu^2 g^2 - 4v_0^2 \omega_0^2) / v_0^2 \omega_0^4 \quad \text{--- (5)}$$

$$\Rightarrow R = v_0 t_0 = (\mu^2 g^2 - 4v_0^2 \omega_0^2)^{1/2} / \omega_0^2 \quad \text{--- (6)}$$

(B) From eq<sup>n</sup> (3) and eq<sup>n</sup> (5), radial acceleration at  $t = t_0$

$$a_r(t_0) = v_0 t_0 \omega_0^2 = (\mu^2 g^2 - 4v_0^2 \omega_0^2)^{1/2} \quad \text{--- (7)}$$

$$a_\theta(t_0) = 2v_0 \omega_0 \quad \text{--- (8)}$$

(c) In an infinitesimal time interval  $dt$  after time  $t$  such that  $0 < t < t_0$  &  $0 < t+dt < t_0$ , the work done by the car

$$\begin{aligned} dw &= \vec{F}'(t) \cdot \dot{\vec{x}}(t) dt \\ &= M(v_0 \omega_0^2 t \hat{x} - 2v_0 \omega_0 \hat{\theta}) \cdot (v_0 \hat{x} + v_0 \omega_0 t \hat{\theta}) dt \\ &= M(v_0^2 \omega_0^2 t dt - 2v_0^2 \omega_0^2 t dt) = -Mv_0^2 \omega_0^2 t dt \quad \text{--- (5)} \end{aligned}$$

$\therefore$  Total work done by the car in the time interval  $0 < t < t_0$

$$\begin{aligned} w &= \int dw = -Mv_0^2 \omega_0^2 \int_0^{t_0} t dt = -Mv_0^2 \omega_0^2 \frac{t_0^2}{2} = -\frac{M}{2} \left( \frac{\mu^2 g^2}{\omega_0^2} - 4v_0^2 \right) \\ &= \frac{M}{2} \left( 4v_0^2 - \frac{\mu^2 g^2}{\omega_0^2} \right) \quad \text{--- (6)} \end{aligned}$$

Consistency with work energy theorem,

Newton's 3rd law implies

$$\begin{aligned} \text{Work done by the car} &= -(\text{Work done on the car by friction}) \\ &= -(\text{change in kinetic energy of the car}) \end{aligned}$$

$E_k^n$  ② implies

$$\text{Initial kinetic energy of car} = \frac{1}{2} M v_0^2$$

$$\text{Kinetic energy at } t_0 = \frac{1}{2} M v_0^2 + \frac{1}{2} M v_0^2 t_0^2 \omega_0^2$$

$$\begin{aligned} \Rightarrow \text{Work done by the car} &= -\frac{1}{2} M v_0^2 t_0^2 \omega_0^2 \\ &= -\frac{M}{2} \left( 4v_0^2 - \frac{\mu^2 g^2}{\omega_0^2} \right) \end{aligned}$$