## Tutorial 2

## Vectors and Polar coordinates

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**Problem 1.**  $\dot{r} = 4 \text{ m/s}, \, \dot{\theta} = 2 \text{ rad/s}.$ 

(1.1) (a) 
$$r(t=0) = 0m$$
 (b)  $\dot{r}(t=0) = 4m/s$  (c)  $\theta(t=0) = 0$  (d)  $\dot{\theta}(t=0) = 2rad/s$ 

- (1.2) At time  $t = t_1$  the particle is at r = 3 m. r(t) = 4t
  - (a)  $t_1 = 3/4 \ s$ .
  - (b)  $r(t_1) = 3m$ ,  $\theta(t_1) = 3/2$ rads
  - (c)  $x(t_1) = 3\cos\frac{3}{2} = 0.2122 \text{ m}, \quad y(t_1) = 3\sin\frac{3}{2} = 2.9925 \text{ m}.$
  - (d)  $v_x(t_1) = -5.7022 \text{ m/s}, \quad v_y(t_1) = 4.4142 \text{ m/s}.$
  - (e)  $v_r(t_1) = 4 \text{ m/s} \text{ and } v_{\theta}(t_1) = 6 \text{ m/s}.$
  - (f)  $a_r = \ddot{r} r\dot{\theta}^2 = -r\dot{\theta}^2 \implies a_r(t_1) = -12 \text{ m/s}^2.$  $a_\theta = r\ddot{\theta} + 2\dot{r} = 2\dot{r}\dot{\theta} \implies a_\theta(t_1) = 16 \text{ m/s}^2.$
  - (g) The Cartesian components of acceleration:  $a_x = a_r \cos \theta - a_\theta \sin \theta \implies a_x(t_1) = -16.8084 \text{ m/s}^2,$  $a_y = a_r \sin \theta + a_\theta \cos \theta \implies a_y(t_1) = -10.8388 \text{ m/s}^2.$
- (1.3) If the mass of the particle is 100 gm, determine (at time  $t_1$ )
  - (a) The Cartesian components of the Force and Torque:  $F_x = ma_x = -1.69 \text{ N}, F_y = ma_y = -1.08 \text{ N},$   $\vec{\tau} = (xF_y yF_x)\hat{k} = 4.83\hat{k} \text{ Nm}.$
  - (b) The polar components of the Force and the Torque:  $F_r = ma_r = -1.2 \text{ N}, F_\theta = ma_\theta = 1.6 \text{ N}, \tau_z = rF_\theta = 4.8 \text{ Nm}.$

**Problem 2.**  $\vec{v} = v_0 \hat{i}$ , y = a.  $\vec{r}(0) = a\hat{j}$ 

(2.1) 
$$r(t) = \sqrt{v_0^2 t^2 + a^2}$$
, and  $\theta(t) = \tan^{-1} \left(\frac{a}{v_0 t}\right)$ .

(2.2) Velocity vector:

$$v_x = v_0, v_y = 0;$$
  
 $v_r = \frac{v_0^2 t}{\sqrt{v_0^2 t^2 + a^2}}, \quad v_\theta = -\frac{v_0 a}{\sqrt{(v_0^2 t^2 + a^2)}}.$ 

(2.3) The acceleration vector:

$$a_x = 0 = a_y$$
  
$$a_r = a_\theta = 0.$$