### Polar Coordinates

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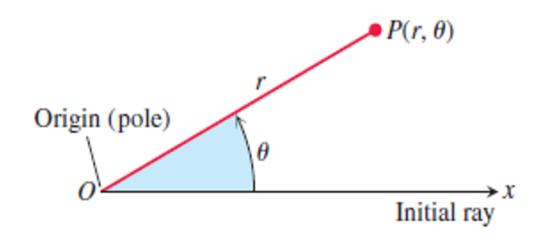
- We know how to specify the location of a point in the plane by means of coordinates relative to two perpendicular coordinates axes.
   Such a system is called as Cartesian (or rectangular) coordinate systems.
- Some time a moving point has special affinity for some fixed point, such as a planet moving in an orbit under the central attraction of Sun.
- In such cases the path of particle is best described by its angular direction and its distance from the fixed point.

This representation of a point is called Polar coordinates.

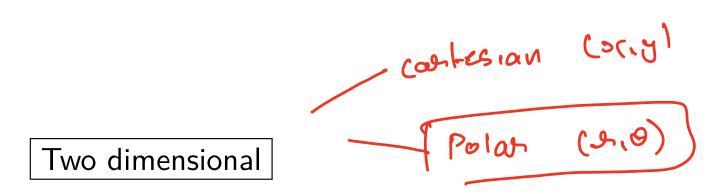
#### Mathematical definition

### Polar coordinates for a point P.

- Fix an origin O, called the pole, and an initial ray from O (initial ray is called polar axis).
- ② Let r be the 'directed' distance from O to P and  $\theta$  be the 'directed' angle (counterclockwise, usually measured in radians) from the polar axis to the ray OP.
- ③ P is represented by the ordered pair  $(r, \theta)$ . Here  $r, \theta$  are called polar coordinates of the point P.



# Types of coordinate systems

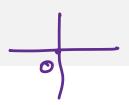


Three dimensional

Spherical Polar (3, 0, 0)

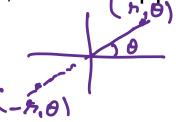
cylindrical Polar (2,0,2)

### Remarks

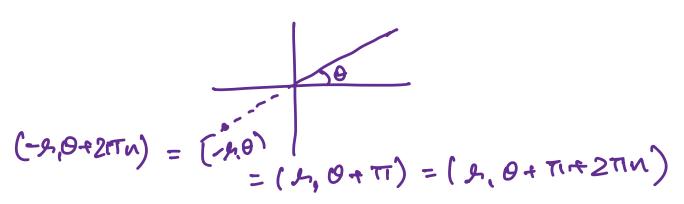


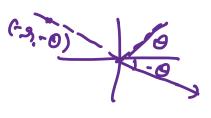
If P = O, then r = 0 and  $(0, \theta)$  represents the origin (pole) for any value of  $\theta$ .

The point  $(r, \theta)$  and  $(-r, \theta)$  lie on the same line through the origin O and the same distance |r| from O, but on opposite sides of O.



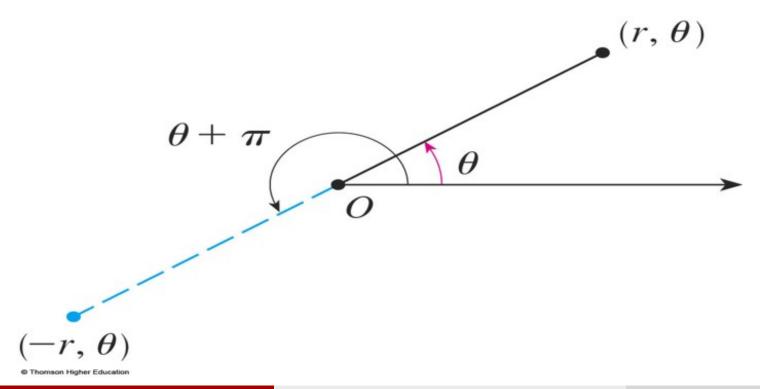
**3** Note that  $(-r, \theta)$  represents the same point as  $(r, \theta + \pi)$ .





4. If r > 0, then the point  $(r, \theta)$  lies in the same quadrant as  $\theta$ .

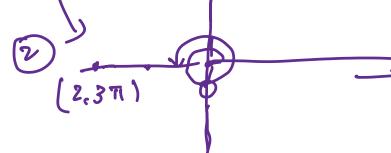
5. If r < 0, then the point  $(r, \theta)$  lies in the quadrant on the opposite side of the pole.



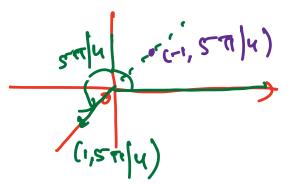
# **Examples**

Plot the points whose polar coordinates are given as follows:

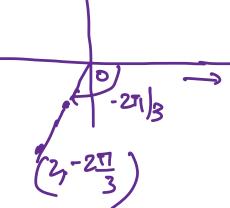
- $\bullet \quad \left(1, \frac{5\pi}{4}\right)$
- **2**  $(2,3\pi)$





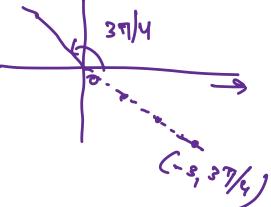




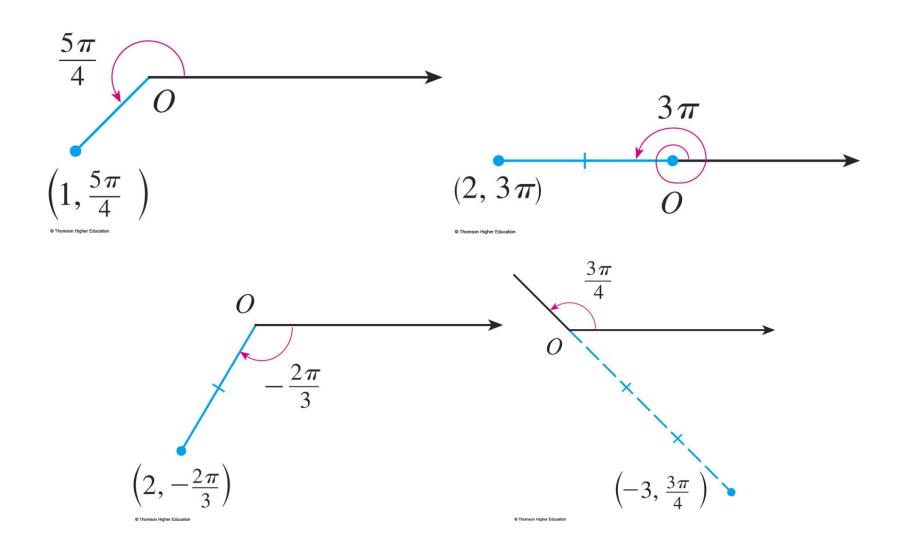


(-1,571/4)





# Solutions



### Cartesian Vs Polar coordinates

In the Cartesian coordinate system, every point has a <u>unique</u> representation.

Whereas, in the polar coordinate system, each point has many representations. For instance, the point  $(2, \frac{\pi}{6})$ .

$$\frac{1}{(2,\pi/6)} = (2, \frac{\pi}{6} + 2\pi\pi)$$

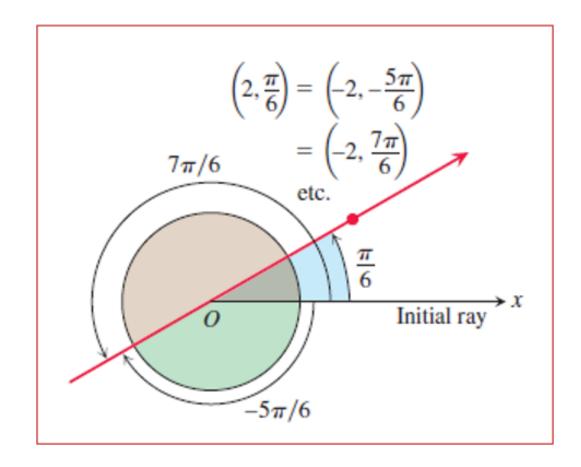
$$= (-2, \pi + \frac{\pi}{6}) = (-2, \frac{\pi}{6} + 2\pi\pi)$$

$$= (-2, -5\frac{\pi}{6}) = (-2, \frac{\pi}{6} - \pi)$$

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## Different Polar representations of a point

Since a complete counterclockwise rotation is given by an angle  $2\pi$ , the point represented by polar coordinates  $(r, \theta)$  is also represented by

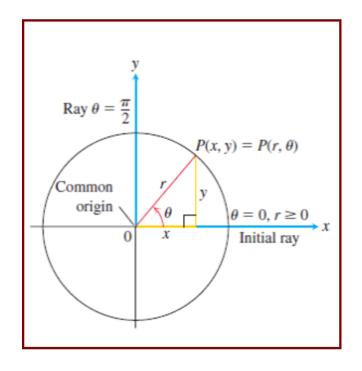
$$(r, \theta + 2n\pi)$$
 and  $(-r, \theta + (2n+1)\pi)$ 

where *n* is any integer.

Therefore every point has <u>infinite</u> polar representations.

#### Relation between Cartesian and Polar coordinates

#### From Polar to Cartesian



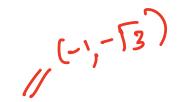
- The pole corresponds to the origin.
- The polar axis coincides with the positive x-axis.
- If the point P has Cartesian coordinates (x, y) and polar coordinates  $(r, \theta)$ , then from the figure, we have

$$\cos\theta = \frac{x}{r}$$
,  $\sin\theta = \frac{y}{r}$   $\Rightarrow x = r\cos\theta$ , and  $y = r\sin\theta$ .

**Note.** Although the above equations, deduced from the figure, illustrates the case where r>0 and  $0<\theta<\frac{\pi}{2}$ , but these equations are valid for all values of r and  $\theta$ .

**Example.** Convert the point  $(2, \frac{\pi}{3})$  from Polar to Cartesian coordinates.

$$J=2, O=T_{3}$$
 $S=J(0)$ 
 $S=J(0)$ 



= (1, 53)

**Exercise.** Find the Cartesian coordinates of  $(-2, \frac{\pi}{3})$  and  $(1, \frac{\pi}{4})$ .

#### From Cartesian to Polar

$$r^2 = x^2 + y^2, \quad \tan\theta = \frac{y}{x}$$

**Example.** Represent the point with Cartesian coordinates (-1, -1) in terms of polar coordinates.

# While finding the $\theta$

- The above equations do not uniquely determine  $\theta$  for a positive r, when x and y are given.
- This is because, as  $\theta$  increases through the interval  $0 \le \theta \le 2\pi$ , each value of  $\tan \theta$  occurs twice.
- So, in converting from Cartesian to polar coordinates, it is not good enough just to find r and  $\theta$  that satisfy the equations  $r^2 = x^2 + y^2$ ,  $\tan \theta = \frac{y}{x}$ .
- Rather we must choose  $\theta$  so that the point  $r, \theta$  lies in the correct quadrant.

### General formula

If the Cartesian coordinates (x, y) are given we can use the following formula to find the polar coordinates  $(r, \theta)$ :

$$r = +\sqrt{x^2 + y^2}$$

$$\theta = \begin{cases} \tan^{-1}(\frac{y}{x}) & \text{if } x > 0; \\ \tan^{-1}(\frac{y}{x}) + \pi \text{ or } \tan^{-1}(\frac{y}{x}) - \pi & \text{if } x < 0; \\ \frac{\pi}{2} & \text{if } x = 0, y > 0; \\ -\frac{\pi}{2} & \text{if } x = 0, y < 0. \end{cases}$$

Note that for the origin,  $\theta$  can take any value.

#### Exercise

Convert the Cartesian coordinates  $(\sqrt{3},1),(1,-\sqrt{3})$  and  $(-\sqrt{3},-1)$  into polar coordinates.

$$(53.1) - x=13 \qquad A = x = 2$$

$$7=1 \qquad tan0 = \frac{1}{53} \implies 0 = \frac{11}{6}, 771/6$$

$$\therefore \text{ polar coordinates will be } (2,776)$$

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