

POLAR COORDINATES

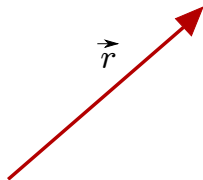
- 1 Polar Coordinates
- 2 Unit vectors \hat{r} and $\hat{\theta}$
- 3 Polar & Cartesian components of a vector
- 4 Velocity and Acceleration in Polar Coordinates
- 5 Examples

POLAR COORDINATES

- 1 Polar Coordinates
- 2 Unit vectors \hat{r} and $\hat{\theta}$
- 3 Polar & Cartesian components of a vector
- 4 Velocity and Acceleration in Polar Coordinates
- 5 Examples

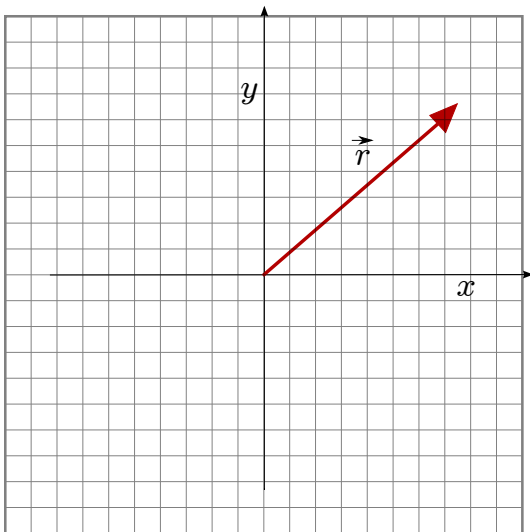
Polar Coordinates

Two Dimensional Plane



Polar Coordinates

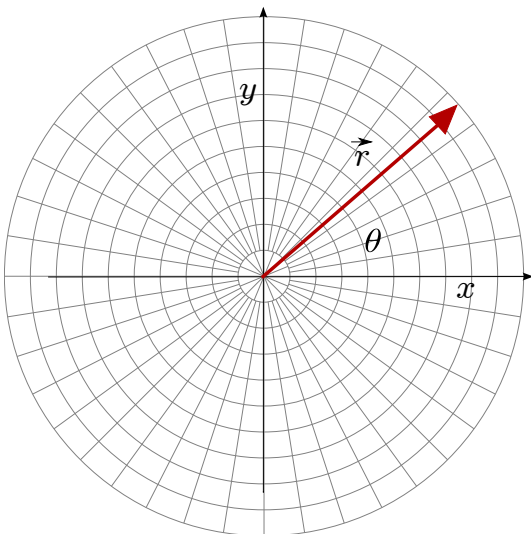
Two Dimensional Plane



- Cartesian Coordinates:
 (x, y)

Polar Coordinates

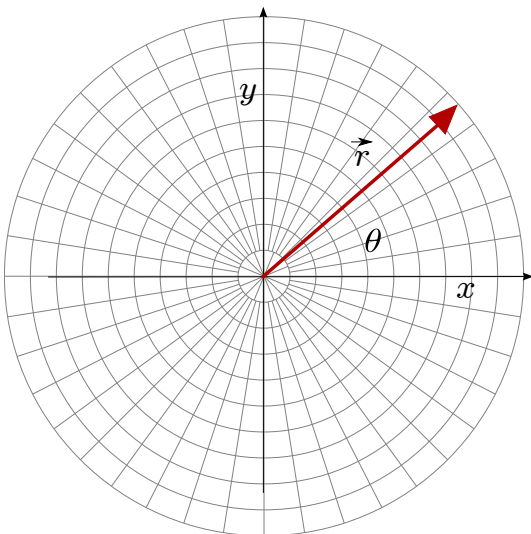
Two Dimensional Plane



- Cartesian Coordinates: (x, y)
- Polar Coords: (r, θ)

Polar Coordinates

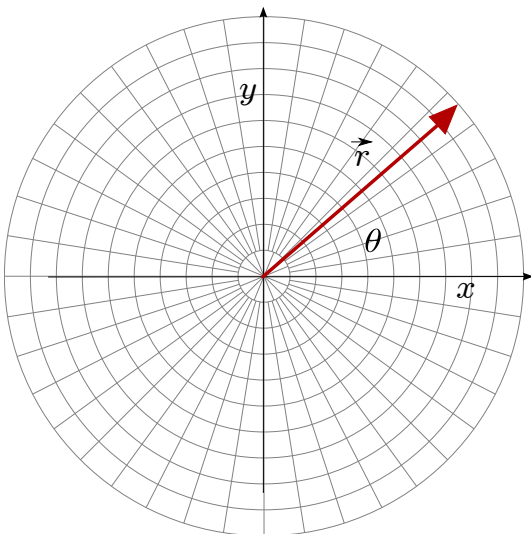
Two Dimensional Plane



- Cartesian Coordinates:
 (x, y)
- Polar Coords: (r, θ)
- $r \in [0, \infty)$,
 $\theta \in [0, 2\pi]$

Polar Coordinates

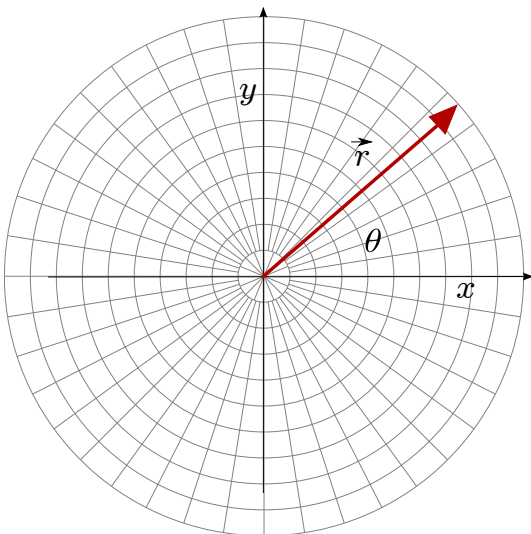
Two Dimensional Plane



- Cartesian Coordinates:
 (x, y)
- Polar Coords: (r, θ)
- $r \in [0, \infty)$,
 $\theta \in [0, 2\pi]$
- $r = \sqrt{x^2 + y^2}$,
 $\tan \theta = \frac{y}{x}$

Polar Coordinates

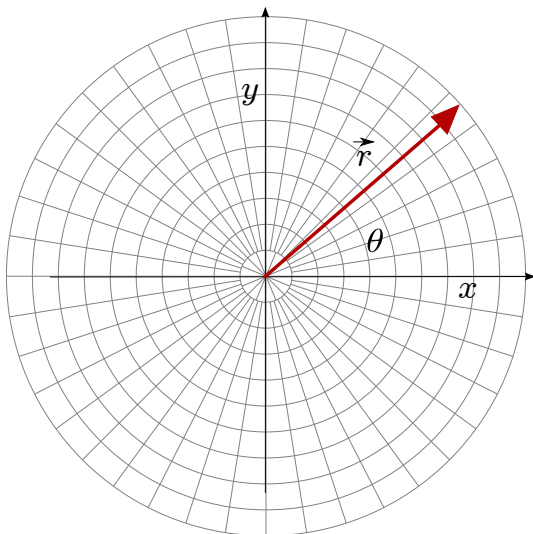
Two Dimensional Plane



- Cartesian Coordinates:
 (x, y)
- Polar Coords: (r, θ)
- $r \in [0, \infty)$,
 $\theta \in [0, 2\pi]$
- $r = \sqrt{x^2 + y^2}$,
 $\tan \theta = \frac{y}{x}$
- $x = r \cos \theta$,
 $y = r \sin \theta$

Polar Coordinates

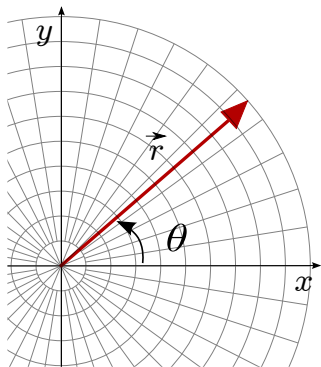
Two Dimensional Plane



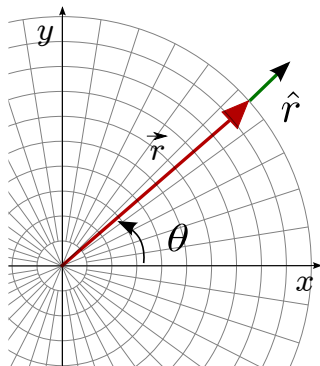
- Cartesian Coordinates:
 (x, y)
- Polar Coords: (r, θ)
- $r \in [0, \infty)$,
 $\theta \in [0, 2\pi]$
- $r = \sqrt{x^2 + y^2}$,
 $\tan \theta = \frac{y}{x}$
- $x = r \cos \theta$,
 $y = r \sin \theta$
- **Use of Polar Coords
nothing to do with
rotational motion**

Unit vectors \hat{r} and $\hat{\theta}$

Unit vectors \hat{r} and $\hat{\theta}$

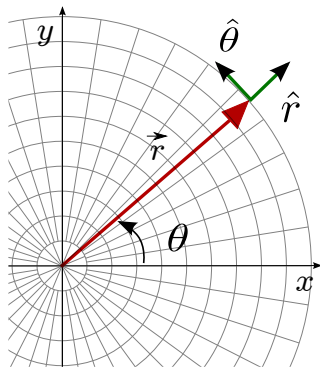


Unit vectors \hat{r} and $\hat{\theta}$



\hat{r} points along increasing r

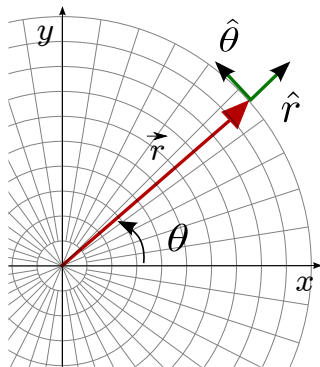
Unit vectors \hat{r} and $\hat{\theta}$



\hat{r} points along increasing r

$\hat{\theta}$ points along increasing θ

Unit vectors \hat{r} and $\hat{\theta}$



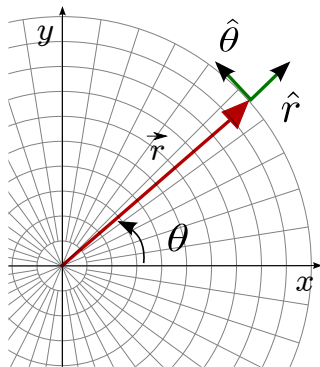
\hat{r} points along increasing r

$\hat{\theta}$ points along increasing θ

\hat{r} and $\hat{\theta}$ **not constant** unit vectors!

$$\hat{r}(\theta), \hat{\theta}(\theta)$$

Unit vectors \hat{r} and $\hat{\theta}$

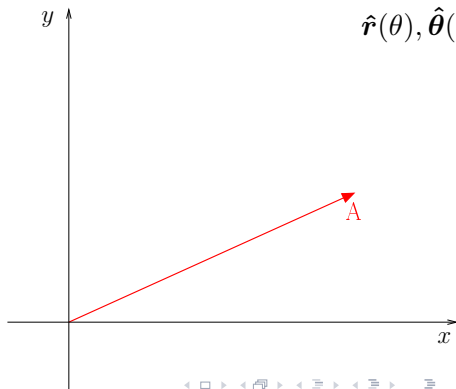


\hat{r} points along increasing r

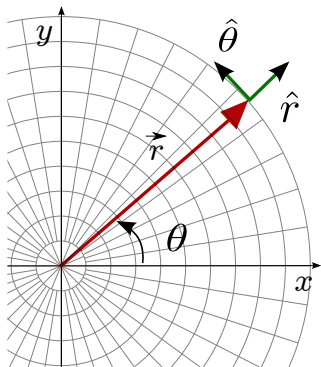
$\hat{\theta}$ points along increasing θ

\hat{r} and $\hat{\theta}$ **not constant** unit vectors!

$$\hat{r}(\theta), \hat{\theta}(\theta)$$



Unit vectors \hat{r} and $\hat{\theta}$

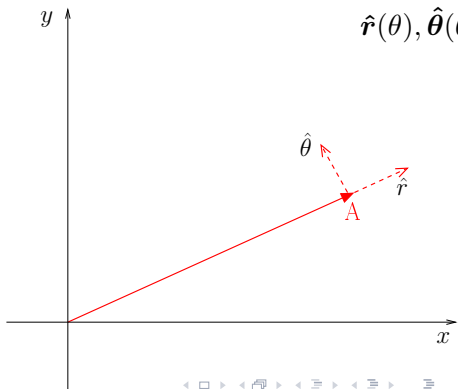


\hat{r} points along increasing r

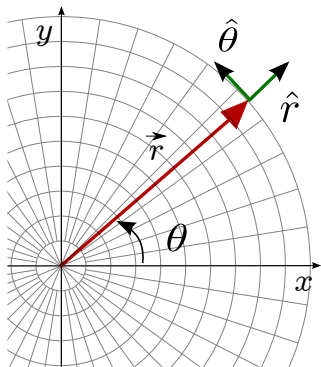
$\hat{\theta}$ points along increasing θ

\hat{r} and $\hat{\theta}$ **not constant** unit vectors!

$$\hat{r}(\theta), \hat{\theta}(\theta)$$



Unit vectors \hat{r} and $\hat{\theta}$

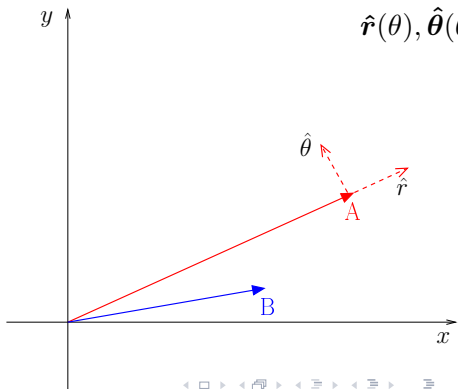


\hat{r} points along increasing r

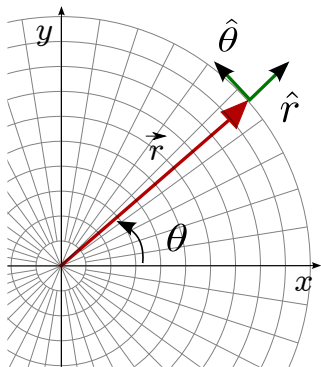
$\hat{\theta}$ points along increasing θ

\hat{r} and $\hat{\theta}$ **not constant** unit vectors!

$$\hat{r}(\theta), \hat{\theta}(\theta)$$



Unit vectors \hat{r} and $\hat{\theta}$

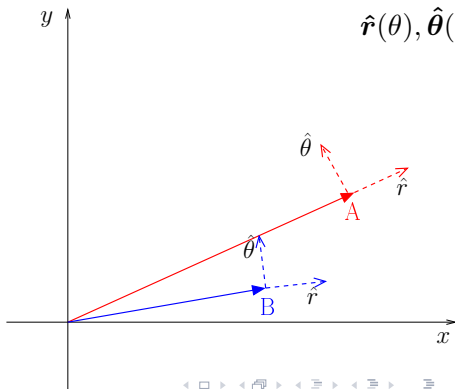


\hat{r} points along increasing r

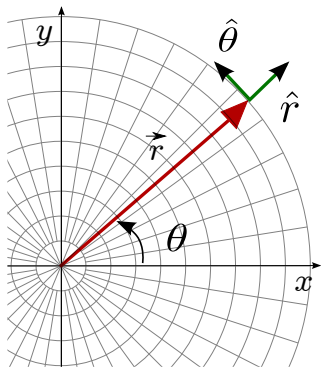
$\hat{\theta}$ points along increasing θ

\hat{r} and $\hat{\theta}$ **not constant** unit vectors!

$$\hat{r}(\theta), \hat{\theta}(\theta)$$



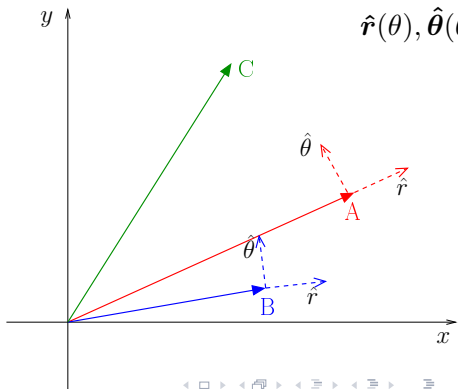
Unit vectors \hat{r} and $\hat{\theta}$



\hat{r} points along increasing r

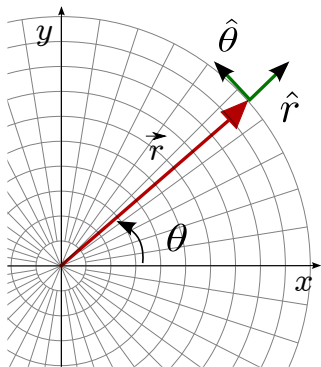
$\hat{\theta}$ points along increasing θ

\hat{r} and $\hat{\theta}$ **not constant** unit vectors!



$\hat{r}(\theta), \hat{\theta}(\theta)$

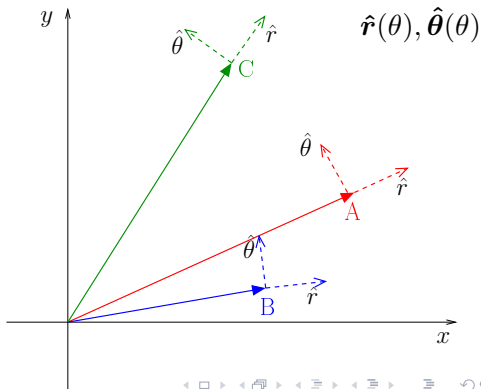
Unit vectors \hat{r} and $\hat{\theta}$



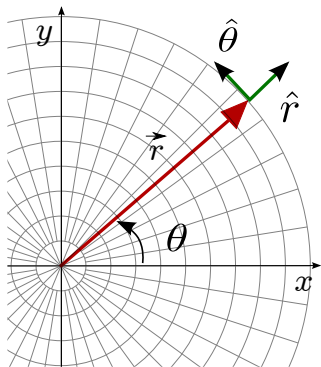
\hat{r} points along increasing r

$\hat{\theta}$ points along increasing θ

\hat{r} and $\hat{\theta}$ **not constant** unit vectors!



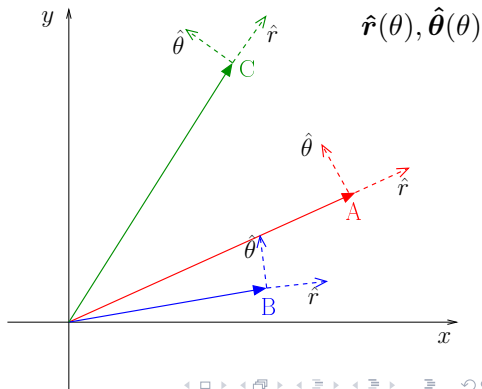
Unit vectors \hat{r} and $\hat{\theta}$



\hat{r} points along increasing r

$\hat{\theta}$ points along increasing θ

\hat{r} and $\hat{\theta}$ **not constant** unit vectors!

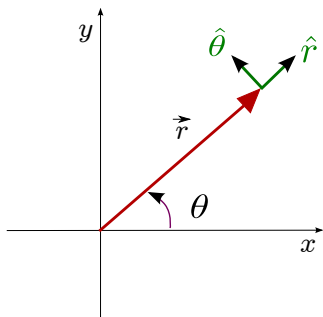


Ex: What are \hat{r} , $\hat{\theta}$ at the points

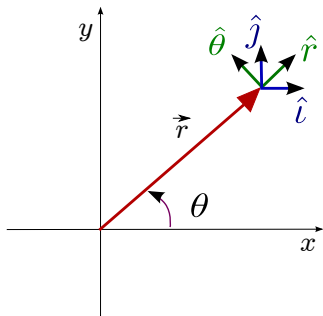
$$(x, y) = (1, 0); (-1, 0); \\ (0, 1); (0, -1)?$$

\hat{r} & $\hat{\theta}$ in terms of \hat{i} & \hat{j}

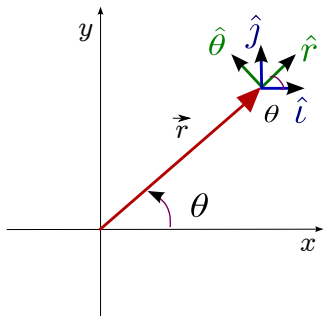
\hat{r} & $\hat{\theta}$ in terms of \hat{i} & \hat{j}



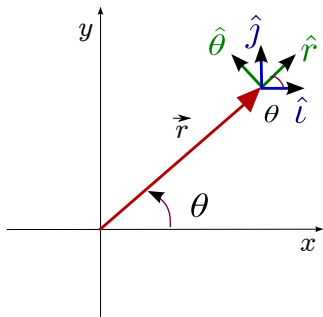
\hat{r} & $\hat{\theta}$ in terms of \hat{i} & \hat{j}



\hat{r} & $\hat{\theta}$ in terms of \hat{i} & \hat{j}



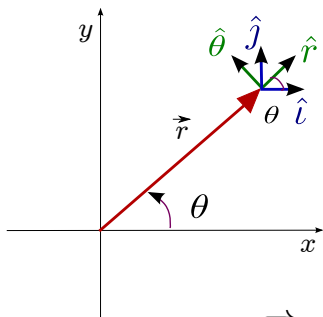
\hat{r} & $\hat{\theta}$ in terms of \hat{i} & \hat{j}



$$\hat{r} = \cos \theta \hat{i} + \sin \theta \hat{j}$$

$$\hat{\theta} = -\sin \theta \hat{i} + \cos \theta \hat{j}$$

\hat{r} & $\hat{\theta}$ in terms of \hat{i} & \hat{j}

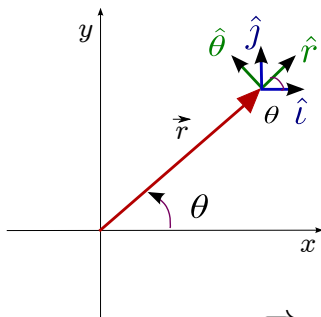


$$\hat{r} = \cos \theta \hat{i} + \sin \theta \hat{j}$$

$$\hat{\theta} = -\sin \theta \hat{i} + \cos \theta \hat{j}$$

$$\vec{A} = A_x \hat{i} + A_y \hat{j}$$

\hat{r} & $\hat{\theta}$ in terms of \hat{i} & \hat{j}

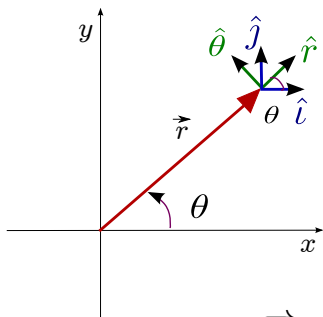


$$\hat{r} = \cos \theta \hat{i} + \sin \theta \hat{j}$$

$$\hat{\theta} = -\sin \theta \hat{i} + \cos \theta \hat{j}$$

$$\begin{aligned}\vec{A} &= A_x \hat{i} + A_y \hat{j} \\ &= A_r \hat{r} + A_\theta \hat{\theta}\end{aligned}$$

\hat{r} & $\hat{\theta}$ in terms of \hat{i} & \hat{j}



$$\hat{r} = \cos \theta \hat{i} + \sin \theta \hat{j}$$

$$\hat{\theta} = -\sin \theta \hat{i} + \cos \theta \hat{j}$$

$$\begin{aligned}\vec{A} &= A_x \hat{i} + A_y \hat{j} \\ &= A_r \hat{r} + A_\theta \hat{\theta}\end{aligned}$$

$$A_r = A_x \cos \theta + A_y \sin \theta$$

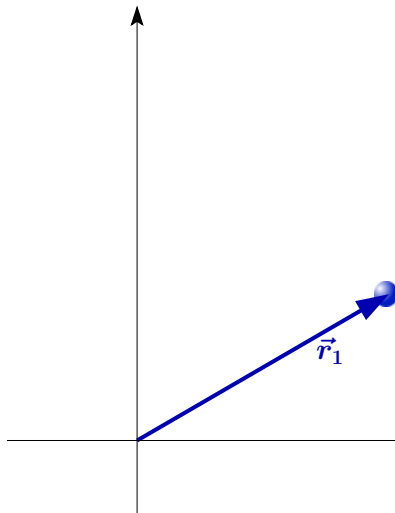
$$A_\theta = -A_x \sin \theta + A_y \cos \theta$$

Velocity & Acceleration in Polar Coordinates

Particle moving from

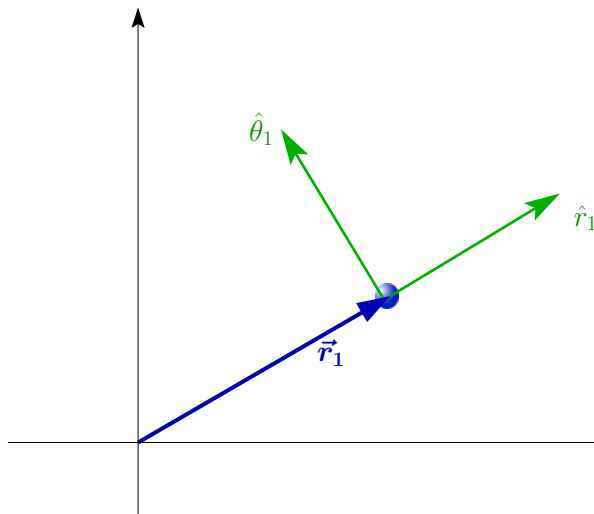
Velocity & Acceleration in Polar Coordinates

Particle moving from \vec{r}_1 at time t_1



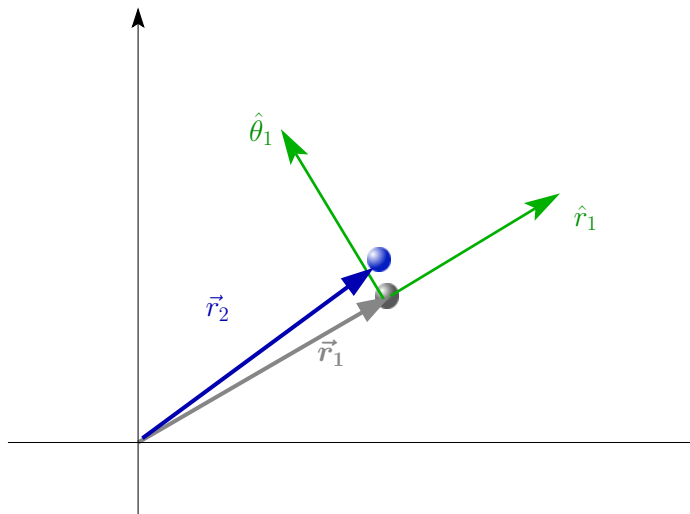
Velocity & Acceleration in Polar Coordinates

Particle moving from \vec{r}_1 at time t_1



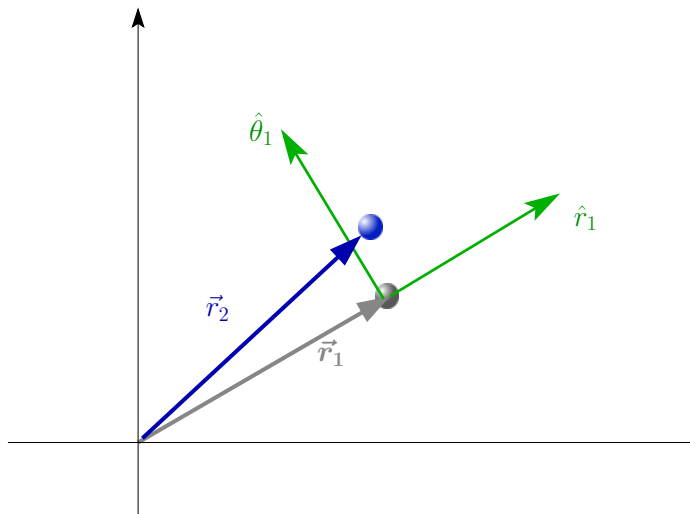
Velocity & Acceleration in Polar Coordinates

Particle moving from \vec{r}_1 at time t_1 to \vec{r}_2 at time t_2



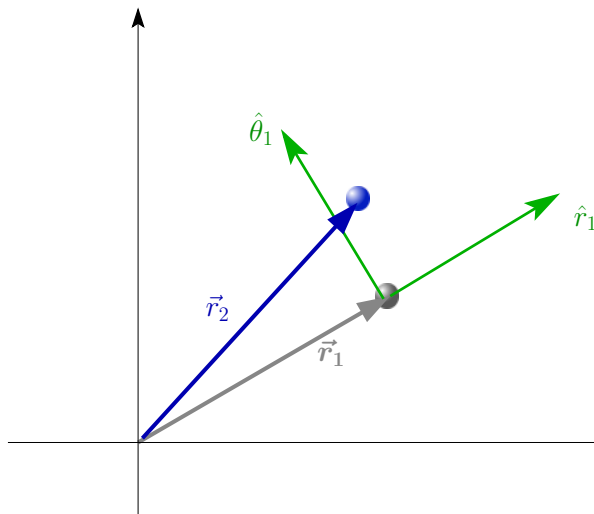
Velocity & Acceleration in Polar Coordinates

Particle moving from \vec{r}_1 at time t_1 to \vec{r}_2 at time t_2



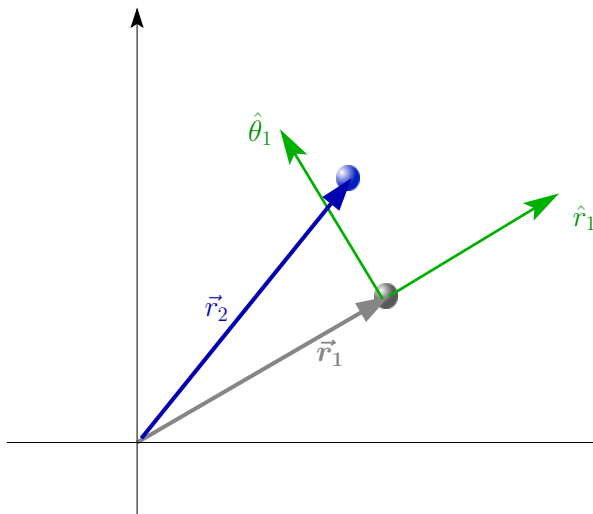
Velocity & Acceleration in Polar Coordinates

Particle moving from \vec{r}_1 at time t_1 to \vec{r}_2 at time t_2



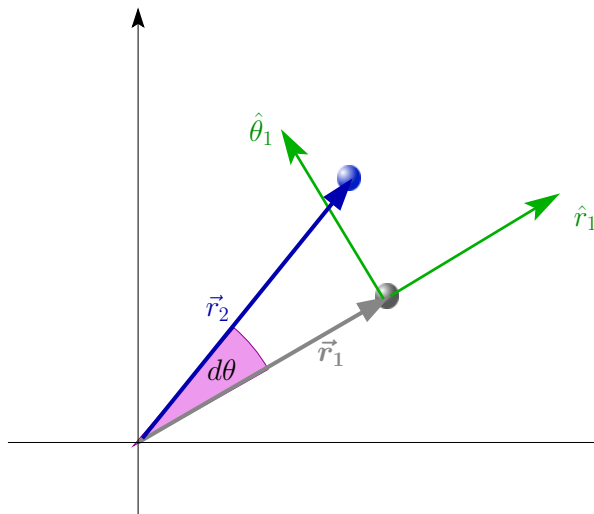
Velocity & Acceleration in Polar Coordinates

Particle moving from \vec{r}_1 at time t_1 to \vec{r}_2 at time t_2



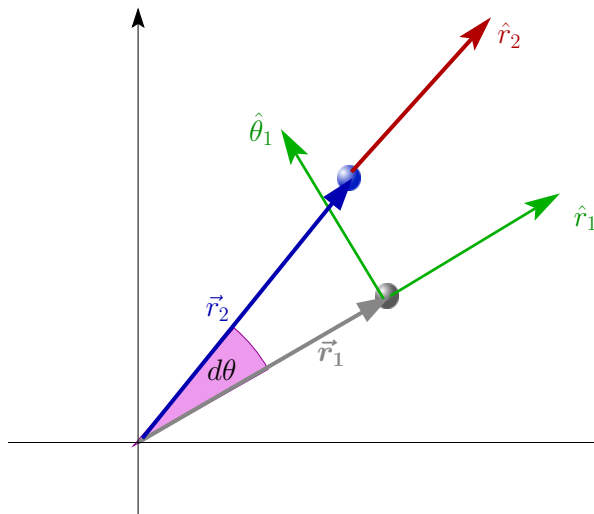
Velocity & Acceleration in Polar Coordinates

Particle moving from \vec{r}_1 at time t_1 to \vec{r}_2 at time t_2



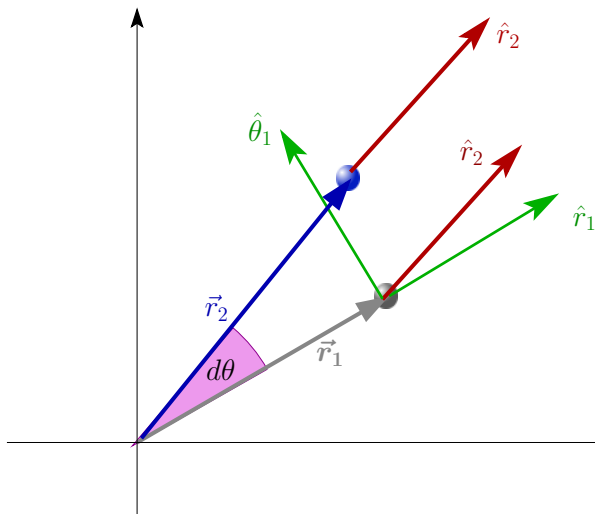
Velocity & Acceleration in Polar Coordinates

Particle moving from \vec{r}_1 at time t_1 to \vec{r}_2 at time t_2



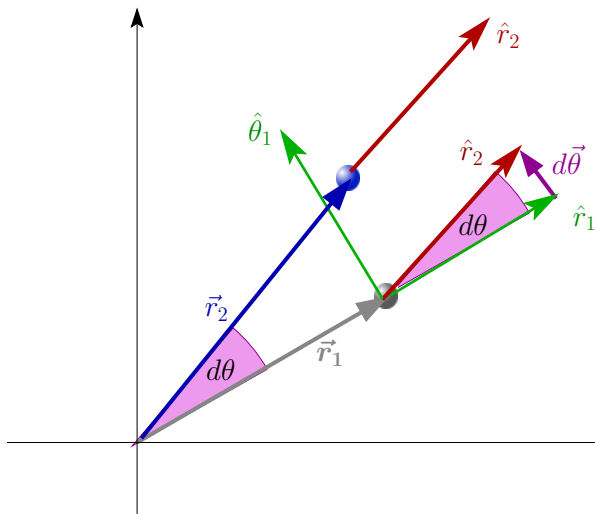
Velocity & Acceleration in Polar Coordinates

Particle moving from \vec{r}_1 at time t_1 to \vec{r}_2 at time t_2



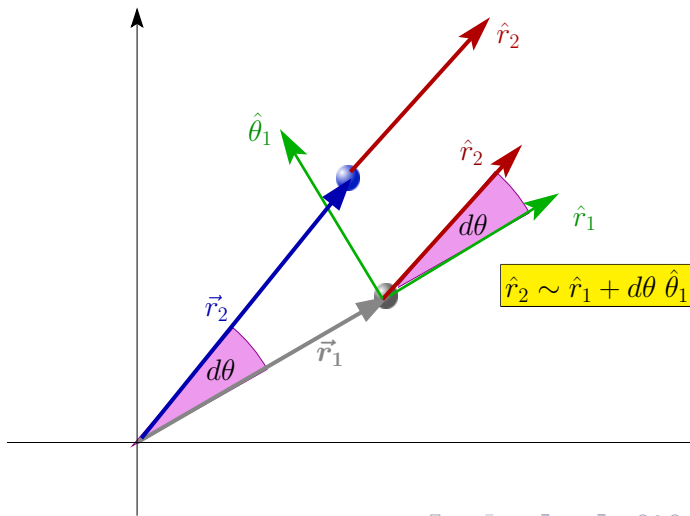
Velocity & Acceleration in Polar Coordinates

Particle moving from \vec{r}_1 at time t_1 to \vec{r}_2 at time t_2



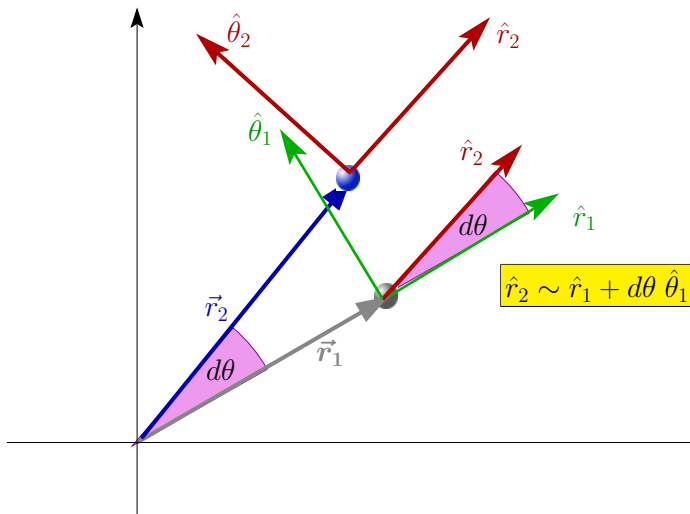
Velocity & Acceleration in Polar Coordinates

Particle moving from \vec{r}_1 at time t_1 to \vec{r}_2 at time t_2



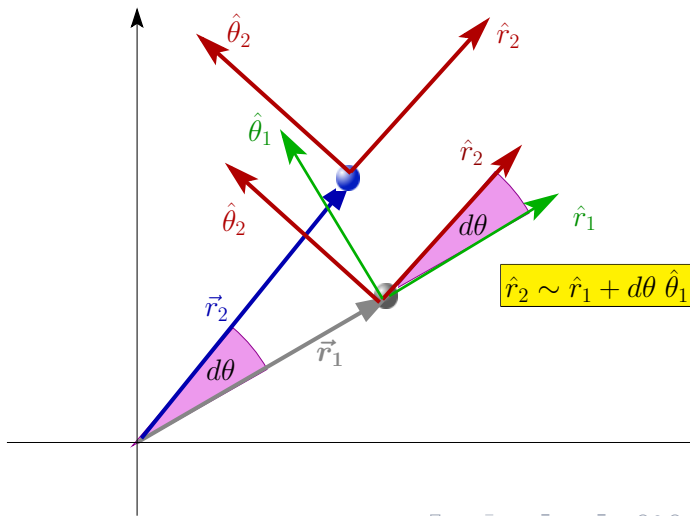
Velocity & Acceleration in Polar Coordinates

Particle moving from \vec{r}_1 at time t_1 to \vec{r}_2 at time t_2



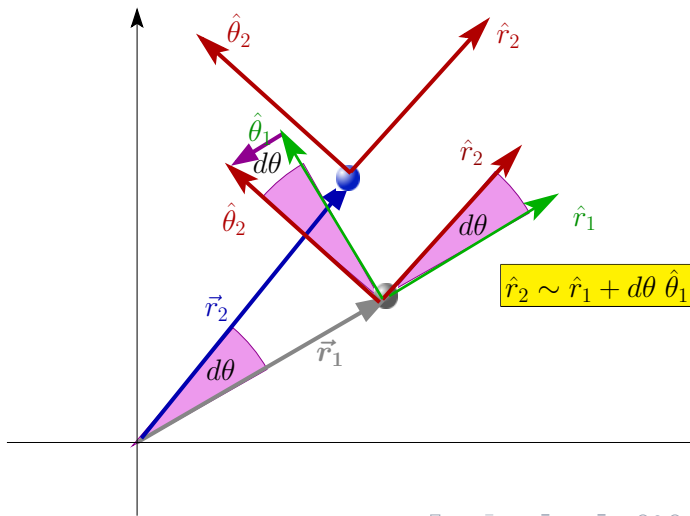
Velocity & Acceleration in Polar Coordinates

Particle moving from \vec{r}_1 at time t_1 to \vec{r}_2 at time t_2



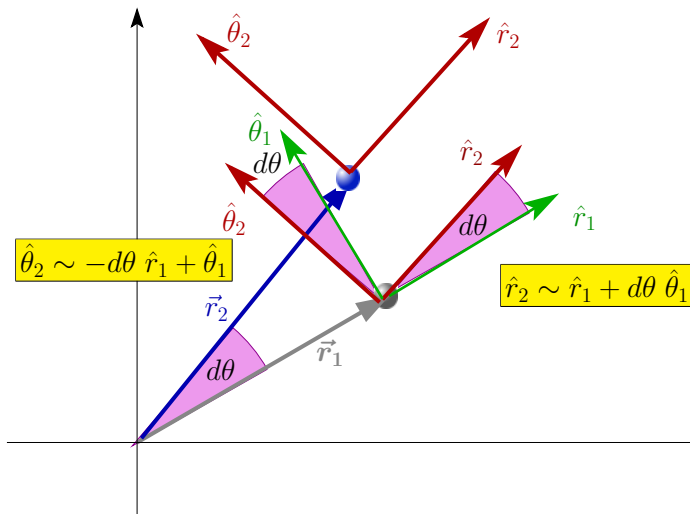
Velocity & Acceleration in Polar Coordinates

Particle moving from \vec{r}_1 at time t_1 to \vec{r}_2 at time t_2



Velocity & Acceleration in Polar Coordinates

Particle moving from \vec{r}_1 at time t_1 to \vec{r}_2 at time t_2

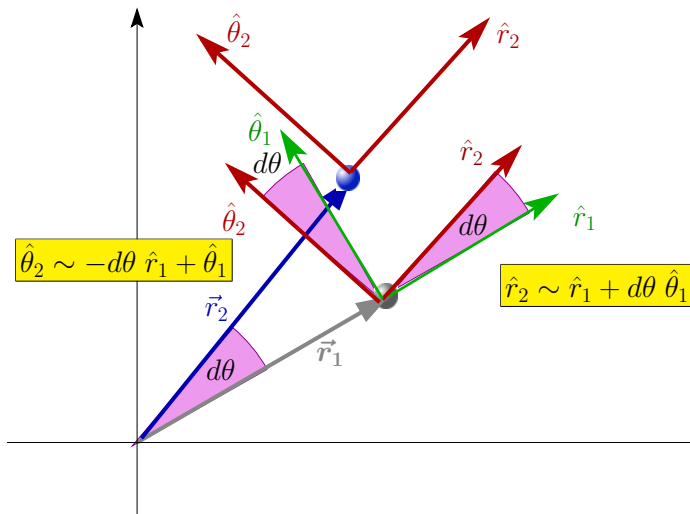


Velocity & Acceleration in Polar Coordinates

Particle moving from \vec{r}_1 at time t_1 to \vec{r}_2 at time t_2

$$d\hat{r} \sim d\theta \hat{\theta}$$

$$d\hat{\theta} \sim -d\theta \hat{r}$$

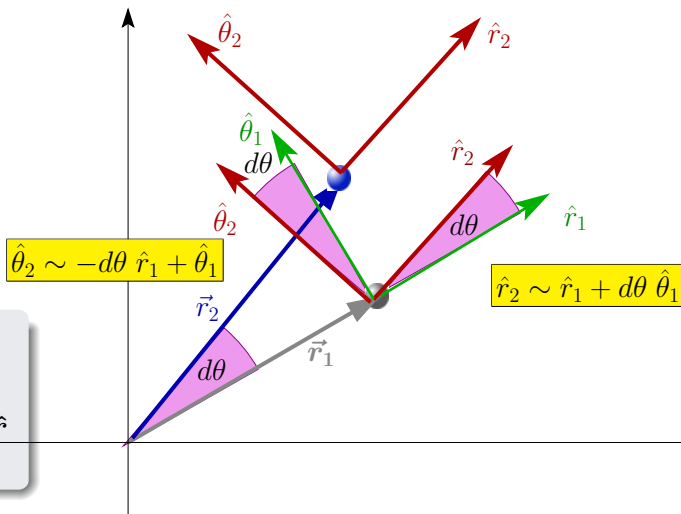


Velocity & Acceleration in Polar Coordinates

Particle moving from \vec{r}_1 at time t_1 to \vec{r}_2 at time t_2

$$d\hat{r} \sim d\theta \hat{\theta}$$

$$d\hat{\theta} \sim -d\theta \hat{r}$$



$$\frac{d\hat{r}}{dt} = \frac{d\theta}{dt} \hat{\theta} = \dot{\theta} \hat{\theta}$$
$$\frac{d\hat{\theta}}{dt} = -\frac{d\theta}{dt} \hat{r} = -\dot{\theta} \hat{r}$$

Velocity & Acceleration in Polar Coordinates

$$\vec{r}(t) = r(t)\hat{r}$$

Velocity & Acceleration in Polar Coordinates

$$\vec{r}(t) = r(t)\hat{r}$$

$$\vec{v}(t) = \frac{d\vec{r}}{dt} = \dot{r}\hat{r} + r\dot{\theta}\hat{\theta}$$

Velocity & Acceleration in Polar Coordinates

$$\vec{r}(t) = r(t)\hat{r}$$

$$\vec{v}(t) = \frac{d\vec{r}}{dt} = \dot{r}\hat{r} + r\dot{\theta}\hat{\theta}$$

$$\vec{a}(t) = \frac{d\vec{v}}{dt} = \left(\ddot{r} - r\dot{\theta}^2\right)\hat{r} + \left(r\ddot{\theta} + 2\dot{r}\dot{\theta}\right)\hat{\theta}$$

Velocity & Acceleration in Polar Coordinates

$$\vec{r}(t) = r(t)\hat{r}$$

$$\vec{v}(t) = \frac{d\vec{r}}{dt} = \dot{r}\hat{r} + r\dot{\theta}\hat{\theta}$$

$$\vec{a}(t) = \frac{d\vec{v}}{dt} = \left(\ddot{r} - r\dot{\theta}^2\right)\hat{r} + \left(r\ddot{\theta} + 2\dot{r}\dot{\theta}\right)\hat{\theta}$$

Note:

Velocity & Acceleration in Polar Coordinates

$$\vec{r}(t) = r(t)\hat{r}$$

$$\vec{v}(t) = \frac{d\vec{r}}{dt} = \dot{r}\hat{r} + r\dot{\theta}\hat{\theta}$$

$$\vec{a}(t) = \frac{d\vec{v}}{dt} = \left(\ddot{r} - r\dot{\theta}^2\right)\hat{r} + \left(r\ddot{\theta} + 2\dot{r}\dot{\theta}\right)\hat{\theta}$$

Note:

- $-r\dot{\theta}^2$ "looks" like Centrifugal force and $2\dot{r}\dot{\theta}$ like Coriolis force

Velocity & Acceleration in Polar Coordinates

$$\vec{r}(t) = r(t)\hat{r}$$

$$\vec{v}(t) = \frac{d\vec{r}}{dt} = \dot{r}\hat{r} + r\dot{\theta}\hat{\theta}$$

$$\vec{a}(t) = \frac{d\vec{v}}{dt} = \left(\ddot{r} - r\dot{\theta}^2\right)\hat{r} + \left(r\ddot{\theta} + 2\dot{r}\dot{\theta}\right)\hat{\theta}$$

Note:

- $-r\dot{\theta}^2$ "looks" like Centrifugal force and $2\dot{r}\dot{\theta}$ like Coriolis force
- But we are in an inertial frame with no fictitious forces

Velocity & Acceleration in Polar Coordinates

$$\vec{r}(t) = r(t)\hat{r}$$

$$\vec{v}(t) = \frac{d\vec{r}}{dt} = \dot{r}\hat{r} + r\dot{\theta}\hat{\theta}$$

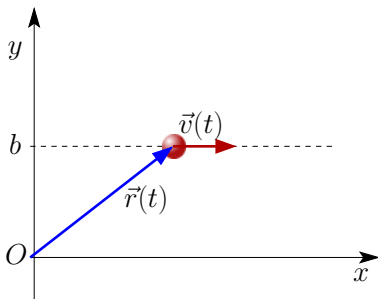
$$\vec{a}(t) = \frac{d\vec{v}}{dt} = \left(\ddot{r} - r\dot{\theta}^2\right)\hat{r} + \left(r\ddot{\theta} + 2\dot{r}\dot{\theta}\right)\hat{\theta}$$

Note:

- $-r\dot{\theta}^2$ "looks" like Centrifugal force and $2\dot{r}\dot{\theta}$ like Coriolis force
- But we are in a inertial frame with no fictitious forces
- Polar coords used for general motion in plane,
NOT for rotational motion alone

Eg. 1: Straight Line motion

Eg. 1: Straight Line motion

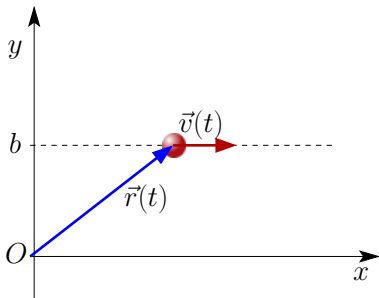


Eg. 1: Straight Line motion

Cartesian:

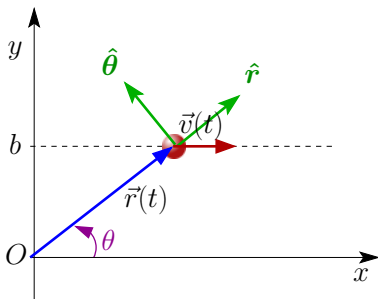
$$\vec{r}(t) = (vt)\hat{i} + b\hat{j}$$

$$\vec{v}(t) = v\hat{i}$$



Eg. 1: Straight Line motion

Cartesian:



$$\vec{r}(t) = (vt)\hat{i} + b\hat{j}$$

$$\vec{v}(t) = v\hat{i}$$

Eg. 1: Straight Line motion

Cartesian:

$$\vec{r}(t) = (vt)\hat{i} + b\hat{j}$$

$$\vec{v}(t) = v\hat{i}$$

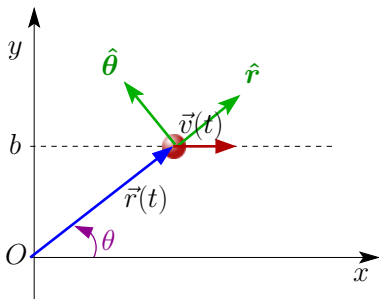
Polar:

$$\hat{r} = \frac{vt}{\sqrt{(vt)^2 + b^2}}\hat{i} + \frac{b}{\sqrt{(vt)^2 + b^2}}\hat{j}$$

$$\hat{\theta} = -\frac{b}{\sqrt{(vt)^2 + b^2}}\hat{i} + \frac{vt}{\sqrt{(vt)^2 + b^2}}\hat{j}$$

$$\vec{r}(t) = r\hat{r}$$

$$\vec{v}(t) = v \left(\frac{vt}{\sqrt{(vt)^2 + b^2}}\hat{r} - \frac{b}{\sqrt{(vt)^2 + b^2}}\hat{\theta} \right)$$



Eg. 1: Straight Line motion

Cartesian:

$$\vec{r}(t) = (vt)\hat{i} + b\hat{j}$$

$$\vec{v}(t) = v\hat{i}$$

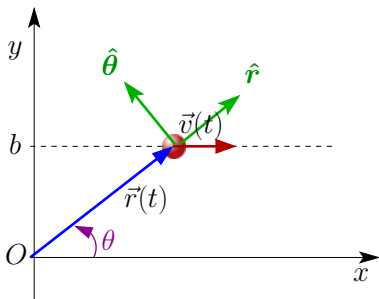
Polar:

$$\hat{r} = \frac{vt}{\sqrt{(vt)^2 + b^2}}\hat{i} + \frac{b}{\sqrt{(vt)^2 + b^2}}\hat{j}$$

$$\hat{\theta} = -\frac{b}{\sqrt{(vt)^2 + b^2}}\hat{i} + \frac{vt}{\sqrt{(vt)^2 + b^2}}\hat{j}$$

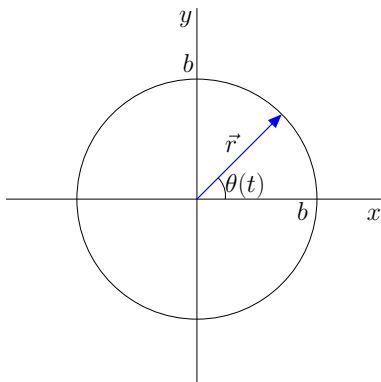
$$\vec{r}(t) = r\hat{r}$$

$$\vec{v}(t) = v \left(\frac{vt}{\sqrt{(vt)^2 + b^2}}\hat{r} - \frac{b}{\sqrt{(vt)^2 + b^2}}\hat{\theta} \right)$$



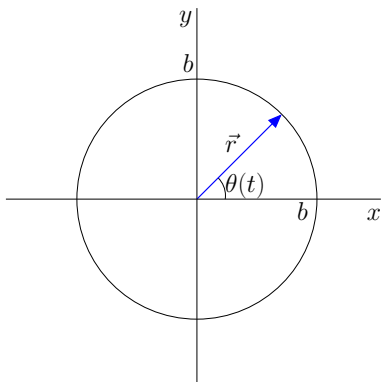
Question: What is \vec{a} ?

Circular Motion

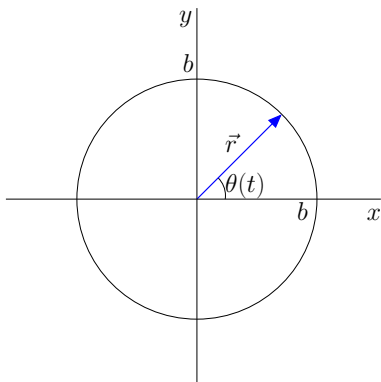


Circular Motion

Cartesian:



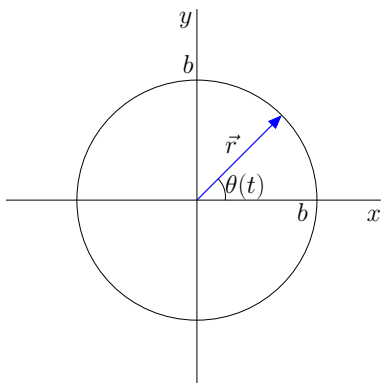
Circular Motion



Cartesian:

$$\vec{r}(t) = b \cos \theta(t) \hat{i} + b \sin \theta(t) \hat{j}$$

Circular Motion

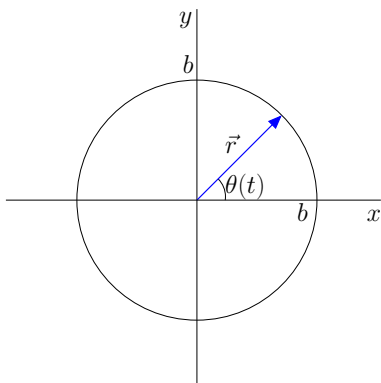


Cartesian:

$$\vec{r}(t) = b \cos \theta(t) \hat{i} + b \sin \theta(t) \hat{j}$$

$$\vec{v}(t) = -b \sin \theta(t) \hat{i} + b \cos \theta(t) \hat{j}$$

Circular Motion



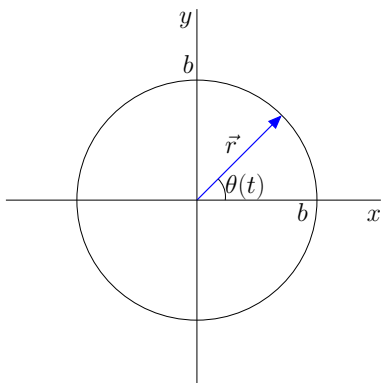
Cartesian:

$$\vec{r}(t) = b \cos \theta(t) \hat{i} + b \sin \theta(t) \hat{j}$$

$$\vec{v}(t) = -b \sin \theta(t) \hat{i} + b \cos \theta(t) \hat{j}$$

Polar:

Circular Motion



Cartesian:

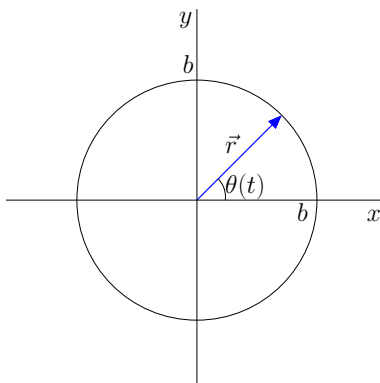
$$\vec{r}(t) = b \cos \theta(t) \hat{i} + b \sin \theta(t) \hat{j}$$

$$\vec{v}(t) = -b \sin \theta(t) \hat{i} + b \cos \theta(t) \hat{j}$$

Polar:

$$\vec{r}(t) = b \hat{r}$$

Circular Motion



Cartesian:

$$\vec{r}(t) = b \cos \theta(t) \hat{i} + b \sin \theta(t) \hat{j}$$

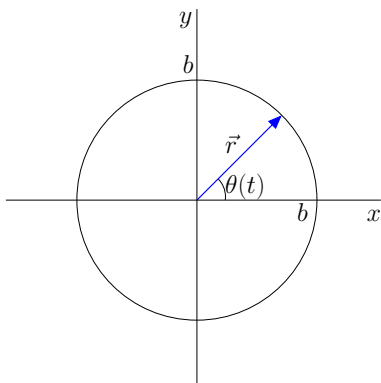
$$\vec{v}(t) = -b \sin \theta(t) \hat{i} + b \cos \theta(t) \hat{j}$$

Polar:

$$\vec{r}(t) = b \hat{r}$$

$$\vec{v}(t) = \dot{r} \hat{r} + r \dot{\theta} \hat{\theta}$$

Circular Motion



Cartesian:

$$\vec{r}(t) = b \cos \theta(t) \hat{i} + b \sin \theta(t) \hat{j}$$

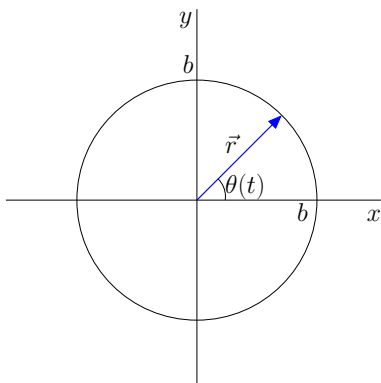
$$\vec{v}(t) = -b \sin \theta(t) \hat{i} + b \cos \theta(t) \hat{j}$$

Polar:

$$\vec{r}(t) = b \hat{r}$$

$$\begin{aligned} \vec{v}(t) &= \dot{r} \hat{r} + r \dot{\theta} \hat{\theta} \\ &= b \dot{\theta} \hat{\theta} \end{aligned}$$

Circular Motion



Cartesian:

$$\vec{r}(t) = b \cos \theta(t) \hat{i} + b \sin \theta(t) \hat{j}$$

$$\vec{v}(t) = -b \sin \theta(t) \hat{i} + b \cos \theta(t) \hat{j}$$

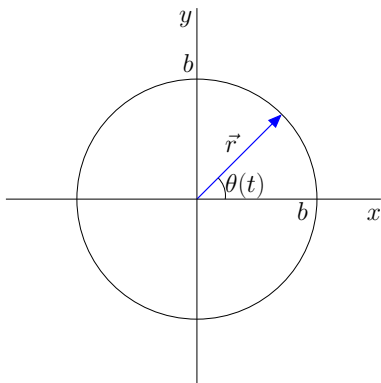
Polar:

$$\vec{r}(t) = b \hat{r}$$

$$\begin{aligned} \vec{v}(t) &= \dot{r} \hat{r} + r \dot{\theta} \hat{\theta} \\ &= b \dot{\theta} \hat{\theta} \end{aligned}$$

$$\begin{aligned} \vec{a} &= (\ddot{r} - r \dot{\theta}^2) \hat{r} + (r \ddot{\theta} + 2 \dot{r} \dot{\theta}) \hat{\theta} \\ &= -b \dot{\theta}^2 \hat{r} + b \ddot{\theta} \hat{\theta} \end{aligned}$$

Circular Motion



Cartesian:

$$\vec{r}(t) = b \cos \theta(t) \hat{i} + b \sin \theta(t) \hat{j}$$

$$\vec{v}(t) = -b \sin \theta(t) \hat{i} + b \cos \theta(t) \hat{j}$$

Polar:

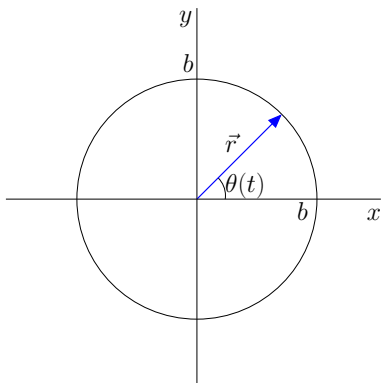
$$\vec{r}(t) = b \hat{r}$$

$$\begin{aligned} \vec{v}(t) &= \dot{r} \hat{r} + r \dot{\theta} \hat{\theta} \\ &= b \dot{\theta} \hat{\theta} \end{aligned}$$

$$\begin{aligned} \vec{a} &= (\ddot{r} - r \dot{\theta}^2) \hat{r} + (r \ddot{\theta} + 2 \dot{r} \dot{\theta}) \hat{\theta} \\ &= -b \dot{\theta}^2 \hat{r} + b \ddot{\theta} \hat{\theta} \end{aligned}$$

Centripetal +

Circular Motion



Cartesian:

$$\vec{r}(t) = b \cos \theta(t) \hat{i} + b \sin \theta(t) \hat{j}$$

$$\vec{v}(t) = -b \sin \theta(t) \hat{i} + b \cos \theta(t) \hat{j}$$

Polar:

$$\vec{r}(t) = b \hat{r}$$

$$\begin{aligned} \vec{v}(t) &= \dot{r} \hat{r} + r \dot{\theta} \hat{\theta} \\ &= b \dot{\theta} \hat{\theta} \end{aligned}$$

$$\begin{aligned} \vec{a} &= (\ddot{r} - r \dot{\theta}^2) \hat{r} + (r \ddot{\theta} + 2 \dot{r} \dot{\theta}) \hat{\theta} \\ &= -b \dot{\theta}^2 \hat{r} + b \ddot{\theta} \hat{\theta} \end{aligned}$$

Centripetal + Tangential acceleration

Spiral motion

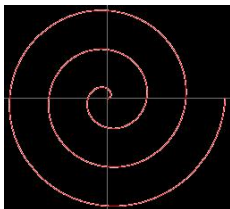
Archimedian spiral

$$r = a + b\theta$$

Spiral motion

Archimedian spiral

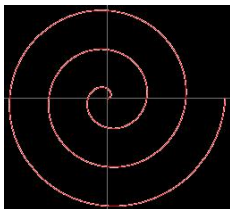
$$r = a + b\theta$$



Spiral motion

Archimedian spiral

$$r = a + b\theta$$



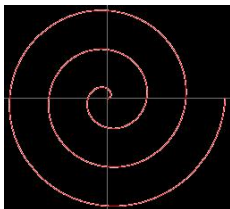
Logarithmic spiral

$$r = ab^{\theta}$$

Spiral motion

Archimedian spiral

$$r = a + b\theta$$



Logarithmic spiral

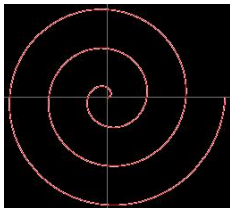
$$r = ab^{\theta}$$



Spiral motion

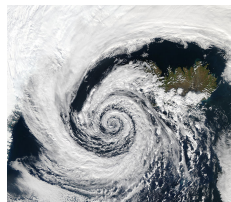
Archimedian spiral

$$r = a + b\theta$$



Logarithmic spiral

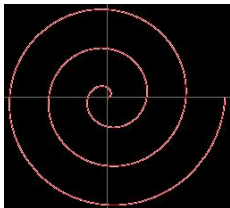
$$r = ab^{\theta}$$



Spiral motion

Archimedian spiral

$$r = a + b\theta$$



Logarithmic spiral

$$r = ab^{\theta}$$

