

Simulated underwater glider sampling for Antarctic krill

Doug Kinzey, NOAA Southwest Fisheries Science Center

11/6/2021

Introduction

Two functions, `gldrs()` and `gldry()`, simulate the ability of the spatial patterns of autonomous underwater gliders to sample the acoustic energy returns attributed to Antarctic krill. A database of krill acoustic densities collected during US AMLR ship surveys from two strata in CCAMLR Subarea 48.1 from 1992 to 2011 is sampled using the sawtooth vertical pattern of underwater gliders equipped with echosounders that ensonify the water column vertically 100 m below the gliders in this up and down pattern (each descent and return is called a ‘yo’) to a maximum depth of between 150 or 1000 m per dive in this example. Any maximum yo depth can be simulated, but the acoustic data available from US AMLR ship surveys ends at 500 m. Here the gliders ensonify the first 250 m of the water column regardless of maximum yo depth.

Input parameters

```
NASC.yrs = c(2001:2009,2011)
AMLR.area = 'SA'
n.rep = 100
n.gldr = c(1)
save.tables = 1
max.NASC.m = 250
depths = c(150,200,300,400,500,700,1000)
azfp.off = c(150,150,150,150,150,150,150)
qntl.vals = c(0.97,0.98,0.99,0.999,1)
smpl.st = 0
```

There are ten input parameters to run a base simulation.

‘NASC.yrs’ are the years to be sampled, with a maximum range of ‘c(2001:2009,2011)’ (the sampling strata in the database were unsampled by the ships in 2010).

‘AMLR.area’ can be one of two values ‘SA’ (the southern area, Bransfield Strait) or ‘WA’ (the western area, Cape Shirreff).

‘n.rep’ is the number of replicated sets of glider samples to collect, ‘9’ in the example. Run-time increases with increasing replicates.

‘n.gldr’ is the number of gliders sampling the stratum during each replicate. It can be a scalar or a vector of values representing sequentially increasing numbers of gliders. When ‘n.gldr()’ is a vector it will overwrite the results with each new grouping of gliders so the simulation results in this case need to be saved as tables (`save.tables = 1`) and then accessed for analysis using `read.table()`. Run-time increases with increasing

gliders/replicate. Run times for 500 replicates of 5 glider/replicate can take over a week and can run out of memory on a 24 thread 32 GB RAM PC.

‘max.NASC.m’ is the maximum depth ensonified by the gliders. In the example, the echosounder is turned off at 150 m regardless of the maximum yo depth so this is always 250m.

‘depths’ are the maximum yo depths to be simulated.

‘azfp.off’ is a vector of the same length as ‘depths’. This allows the option to ensonify deeper during deeper dives up to the maximum depth of krill densities recorded in the database of 500 m.

‘qntl.vals’ allow the proportions of krill in these highly skewed distributions to be assessed.

‘smp1.st’ allows either random (= 0) starting positions in the database for each replicate sample, or using the same starting positions (= 1) for each replicate as a previous simulation. If this option is desired, save.tables = 1 for the previous simulation, and then the ‘gldr_strt_...’ files from the first run need to be called from the second run. This option can be useful in evaluating the effects of changes in the coding on identical glider sampling patterns.

Load the databases

There are two databases: (1) ‘NASC_leg1.RData’ (dimensions 100 x 199772), the krill acoustic values binned into 100 m horizontal by 5 m vertical cells (transposed in the simulation functions for easier visualization), and (2) ‘leg1.csv’ (dimensions 199772 x 5), the unique identifiers, strata and year for each column of ‘NASC_leg1.RData’.

```
load('NASC_leg1.RData')
leg1 <- read.csv('leg1.csv')
```

Source the R code

There are two R scripts, ‘gldry.r’, and ‘gldrs.r’ containing two functions, ‘gldry()’, which calculates the path a glider would follow from a given starting position and maximum yo depth and ‘gldrs()’, which reads the input parameters and calculates four arguments that are passed to ‘gldry()’. ‘gldry()’ calculates the glider sampling pattern and returns this pattern and three other arguments to ‘gldrsl()’ which then uses the glider sampling pattern on the acoustic database.

```
source('gldry.r')
source('gldrs.r')
```

Run the simulation

The values above are the default arguments for gldrs() but they can be changed in the function calls below.

```
Sys.time() # keep track of runtime
```

```
## [1] "2021-11-18 15:18:18 PST"
```

```
gldrs(NASC.yrs=NASC.yrs,AMLR.area=AMLR.area,n.rep=n.rep,n.gldr=n.gldr,
      save.tables=save.tables,max.NASC.m=max.NASC.m,depths=depths,
      azfp.off=azfp.off,qntl.vals=qntl.vals,smp1.st=smp1.st)
Sys.time()
```

```
## [1] "2021-11-18 16:33:16 PST"
```

Next steps

After ‘Gldr_simulation.rmd’ has been rendered, the working directory will contain output files from the simulation. These can be plotted using ‘Figures2_7.rmd’, and ‘Figures8-9.rmd’.