



EECE5155: Wireless Sensor Networks and the Internet of Things

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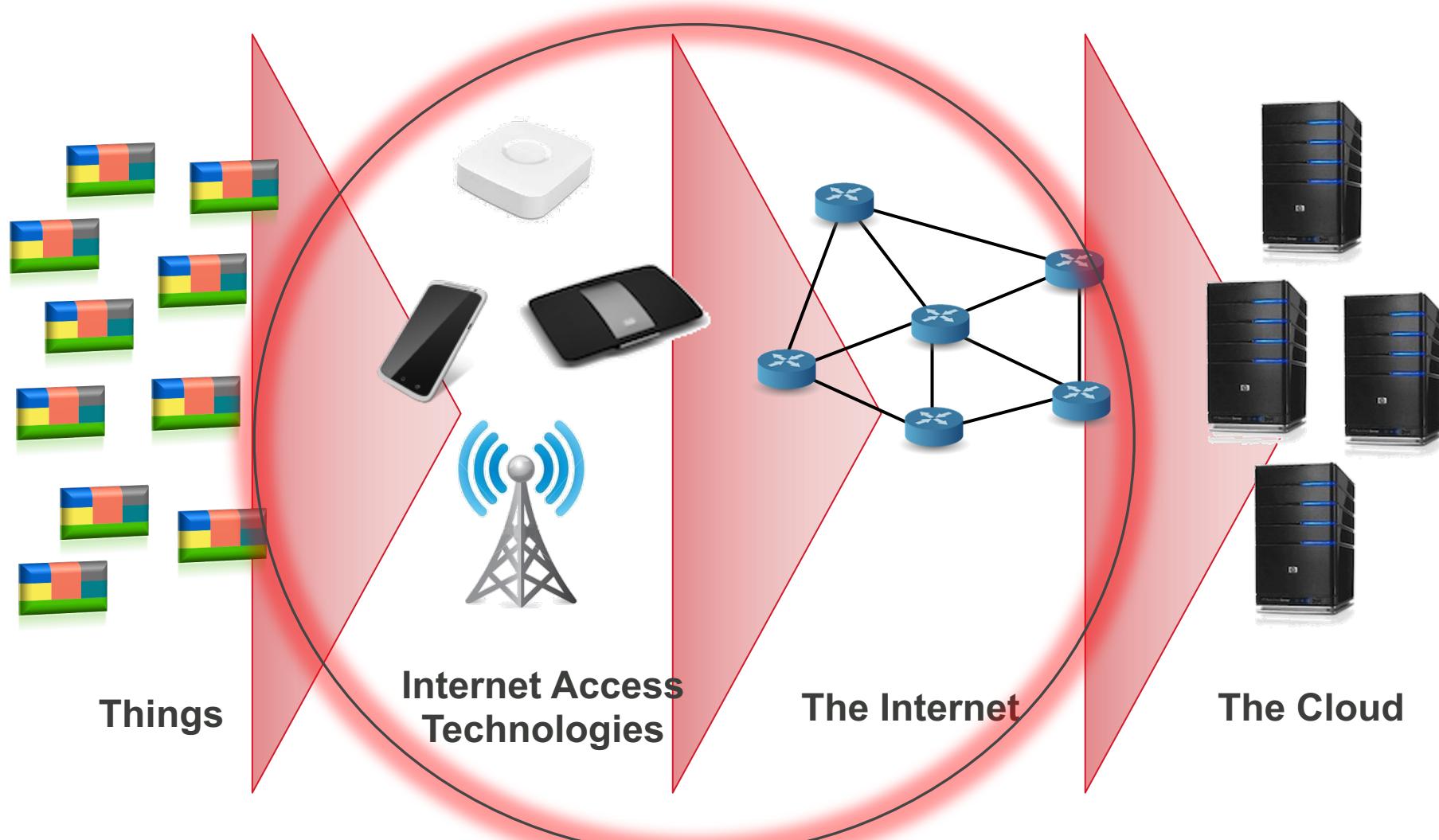
Module T4: Data Communication

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Part 2: Protocols and Standards

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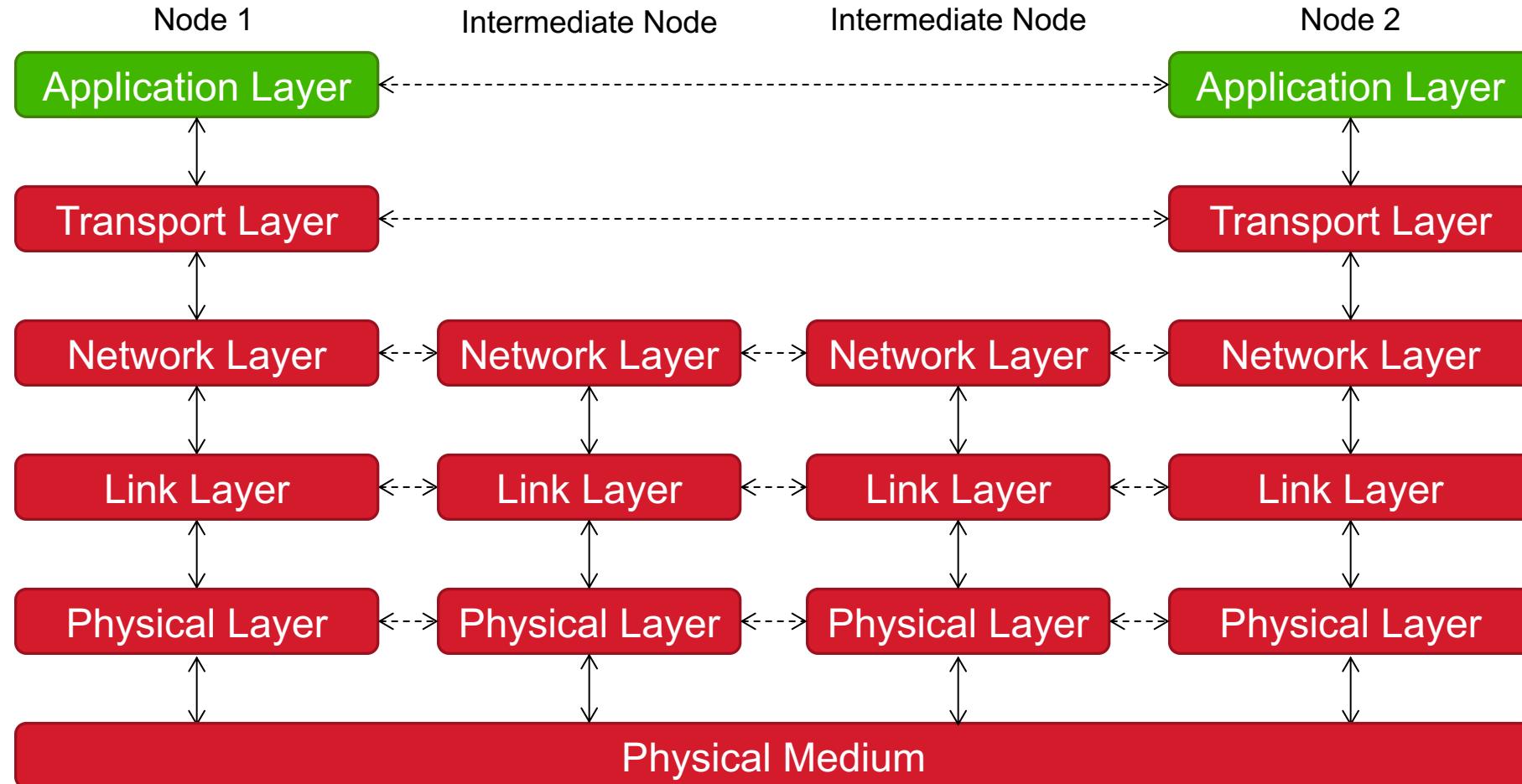
Outline

- The Protocol Stack
- The Physical Layer
- The Link Layer
- The Network Layer
- The Transport Layer
- IoT Standards

The Protocol Stack

- To reduce their design complexity, most networks are organized as a **stack of layers**, each one built upon the one below it:
 - Each layer offers certain services to the higher layers...
 - ... which are accessed by means of interfaces ...
 - ... **without actually showing the details** of their implementation
- **Different types of networks** might have different:
 - Number of layers
 - Name of each layer
 - Contents of each layer
 - Function of each layer
- Layer n of a node interacts with layer n of another node by following a layer n protocol

The Protocol Stack



The Physical Layer

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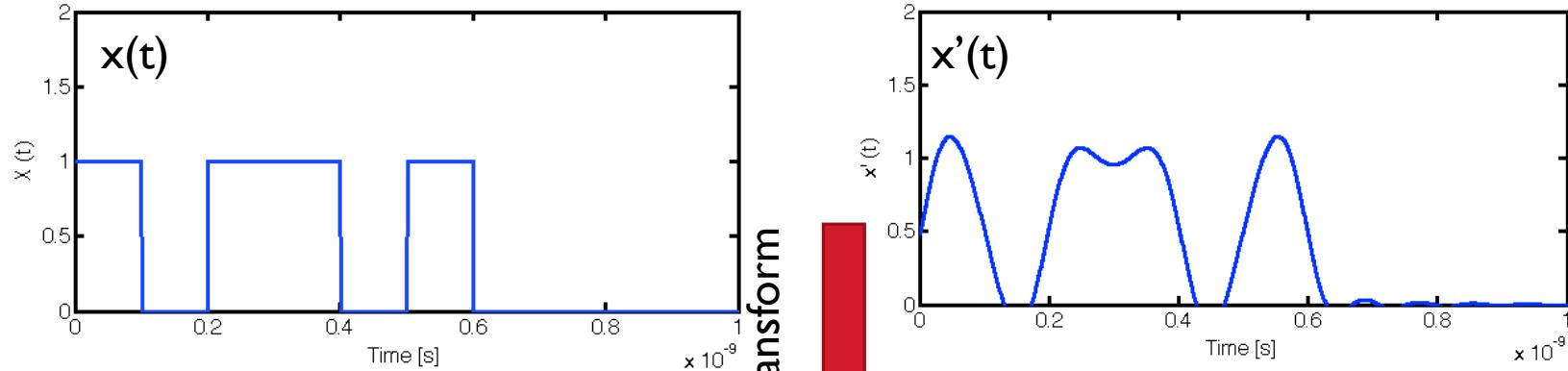
- Defines the way in which bits (0s and 1s) are transmitted as **signals** over a **communication channel**:
 - **Signal:** “A function that conveys information about the behavior or attributes of some phenomenon”
 - **E.g., electric, magnetic, electromagnetic, acoustic, molecular, etc.**
 - **Channel:** “The medium that carries the signal to be transmitted”
 - **E.g., twisted pair, coaxial cable, optical fiber, air, water, etc.**

Some Basic Concepts

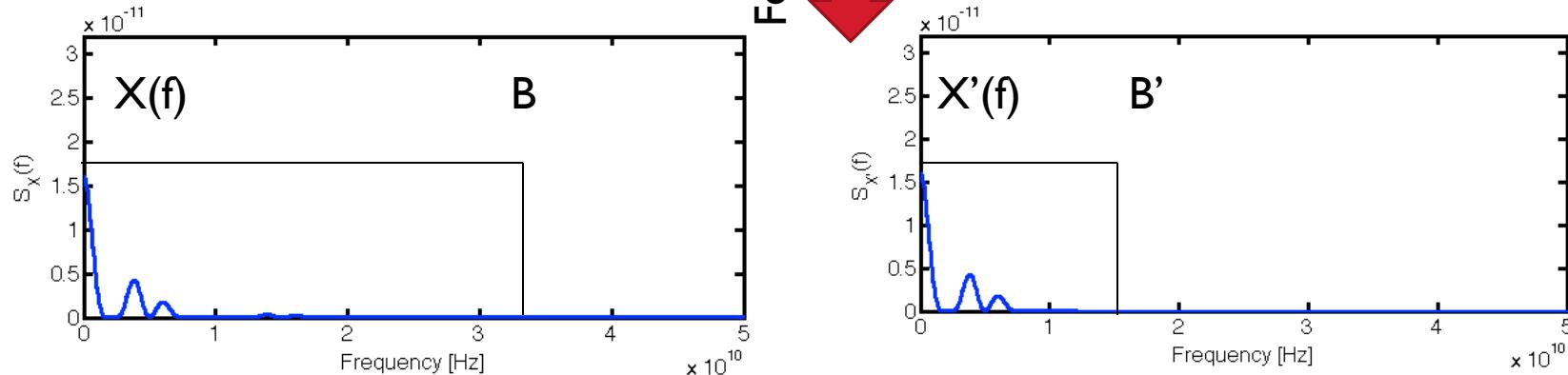
- **Baseband Signal:** a signal whose range of frequencies expands from 0 Hz (or very close) up to a certain cut-off frequency
 - Used for example in some of the wired networking standards (e.g., Ethernet 10BASE5, 10BASET, etc.)
- **Passband Signal:** a signal whose range of frequencies is away from 0 Hz
 - Used for example in Radio Frequency (RF) communications, Digital Subscriber Line (DSL) systems, etc.
- **Bandwidth:**
 - **For baseband signals:** the highest frequency of the signal
 - **For passband signals:** the difference between the upper and the lower frequency of the signal

Representation of Baseband Signals

- Time domain:

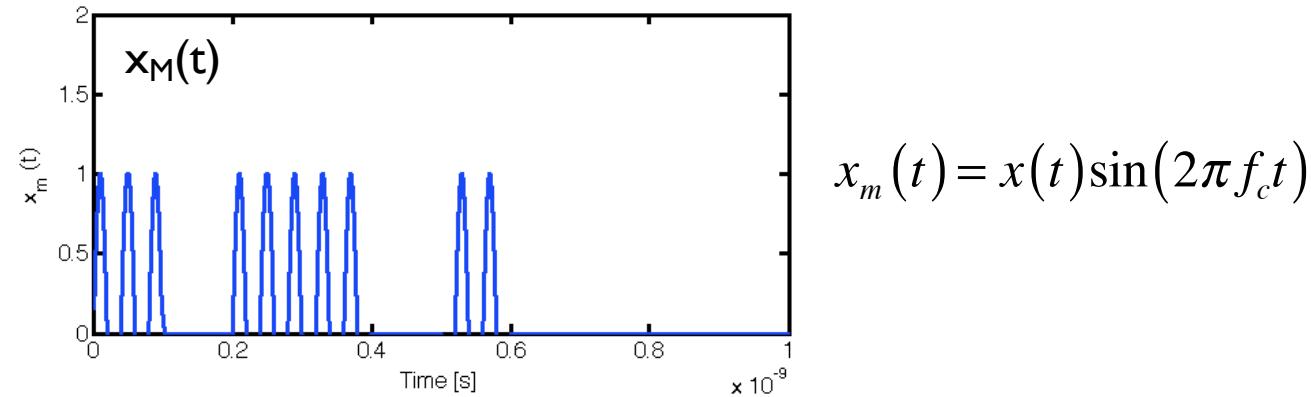


- Frequency domain:

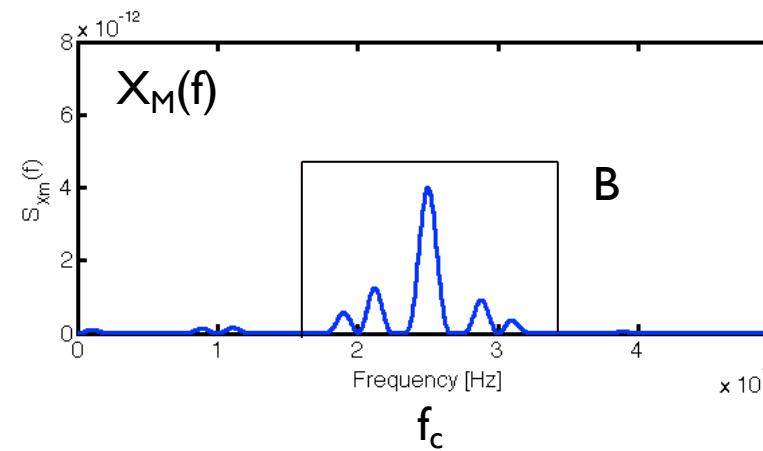


Representation of Passband Signals

- Time domain:



- Frequency domain:



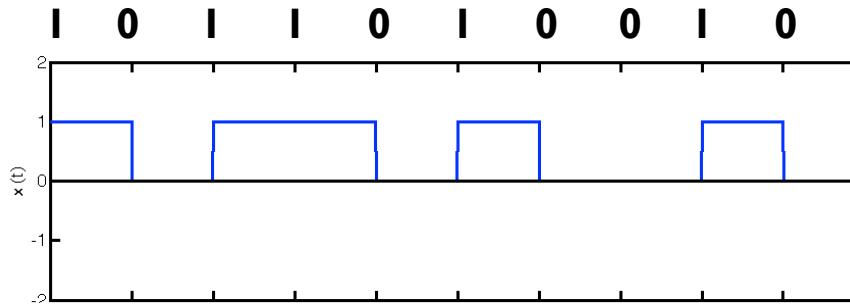
Digital Modulation (at the Transmitter)

- Mechanism by which a binary sequence is converted in a signal suited for transmission in the physical medium
 - **Baseband:** commonly used in wired communication
 - **Passband:** commonly used in wireless and optical communication

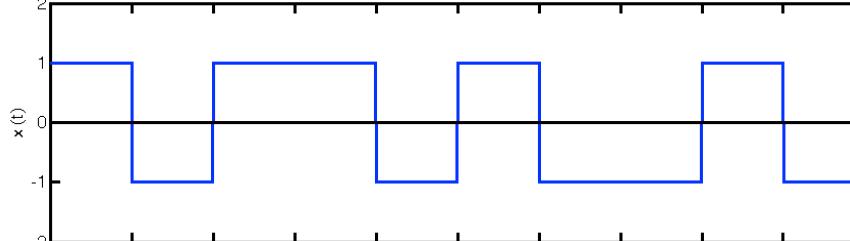
- **Unipolar Non-Return-to-Zero:**
 - A binary 1 is transmitted as a positive voltage
 - A binary 0 is transmitted as a null voltage
- **Bipolar Non-Return-to-Zero:**
 - A binary 1 is transmitted as a positive voltage
 - A binary 0 is transmitted as a negative voltage
- **Non-Return-to-Zero Inverted:**
 - A binary 1 is transmitted as a transition in the signal level
 - A binary 0 is transmitted as a no transition

Examples

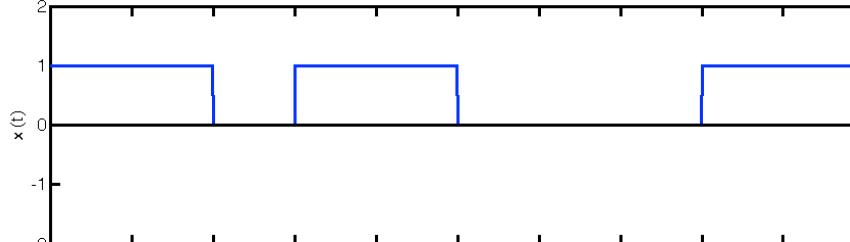
**Unipolar
NRZ**



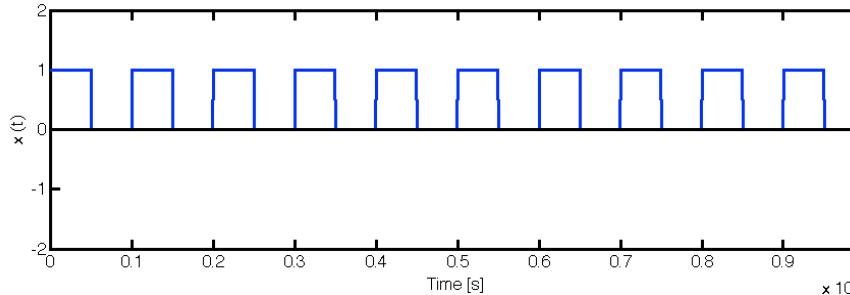
Bipolar NRZ



**NRZ
Inverted**



Clock

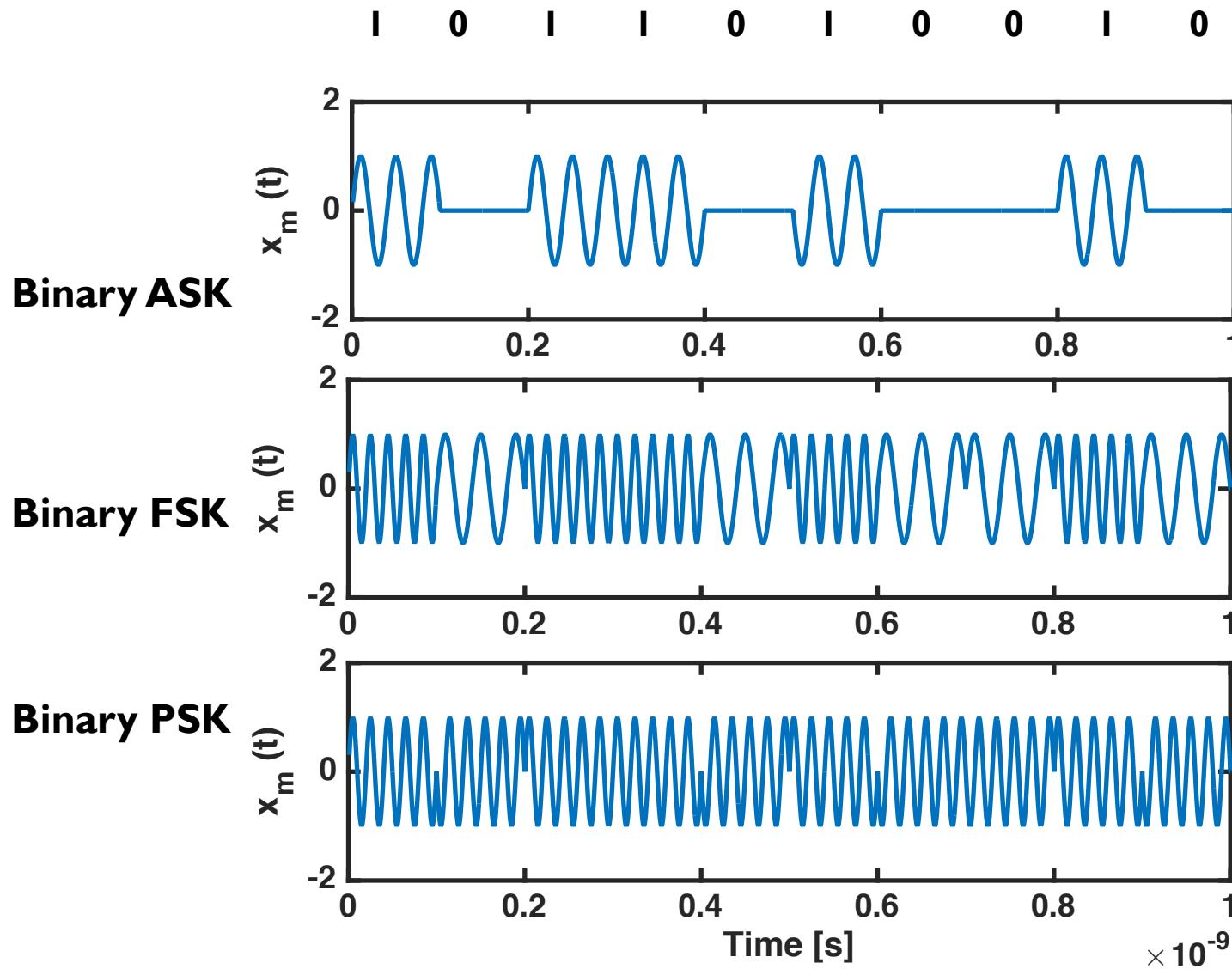


(e.g., USB)

Passband Modulations

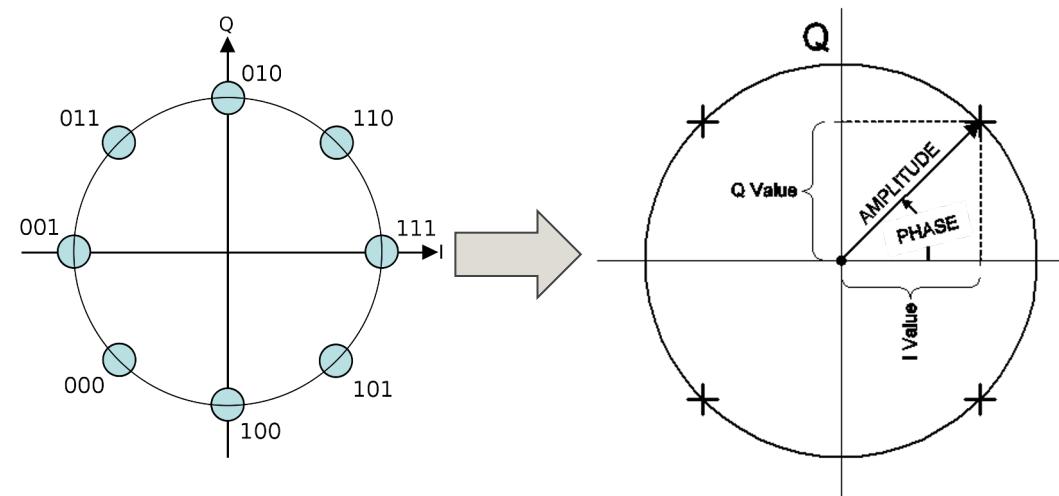
- **Single Carrier Modulations:** the properties of a single tone or carrier frequency are changed according to the data to be transmitted:
 - **Amplitude Shift Keying (ASK):**
 - Two amplitude levels are used to transmit a binary 1 and a binary 0
 - More amplitude levels can be used to transmit more symbols, e.g., 00, 01, 10, 11
 - **Frequency Shift Keying (FSK):**
 - Two different frequency tones are used to transmit a binary 1 and a binary 0
 - More frequency tones can be used to transmit more symbols
 - **Phase Shift Keying (PSK):**
 - The phase of the carrier signal is shifted by a certain phase at each symbol transition:
 - **Binary Phase Shift Keying (BPSK):** phase is shifted by 0 or 180 degrees
 - More phases can be used to transmit more symbols, e.g., QPSK
 - **Quadrature Amplitude Modulation:** combination of amplitude and phase modulations
 - E.g., 16QAM (4 bits per symbol), 64QAM (6 bits per symbol)

Examples

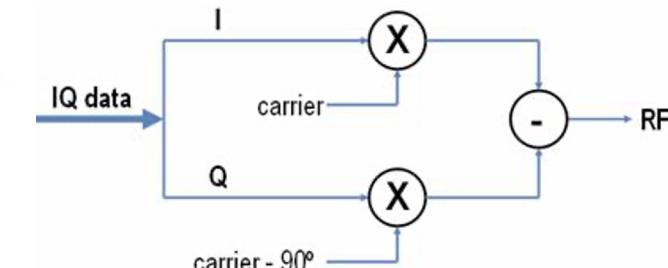


Important: In-phase and Quadrature Data

- Precisely varying the phase of a high-frequency carrier sine wave in a hardware circuit according to an input message signal is difficult
 - Circuit would be expensive and difficult to design/build!
- Instead, the concept of in-phase and quadrature components is introduced to manipulate the signal in baseband before being up-converted (at the transmitter) or after being down-converted (at the receiver)

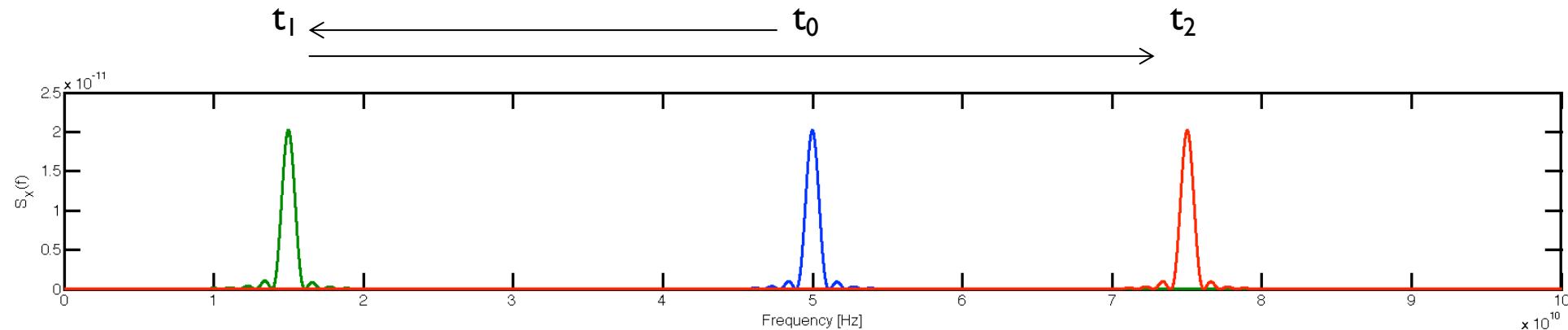


$\cos(\alpha + \beta) = \cos(\alpha)\cos(\beta) - \sin(\alpha)\sin(\beta)$
 $A\cos(2\pi f_c t + \varphi) = A\cos(2\pi f_c t)\cos(\varphi) - A\sin(2\pi f_c t)\sin(\varphi)$
 $I = A \cos(\varphi)$
 $Q = A \sin(\varphi)$
 $A \cos(2\pi f_c t + \varphi) = I \cos(2\pi f_c t) - Q \sin(2\pi f_c t)$



Frequency Hopping

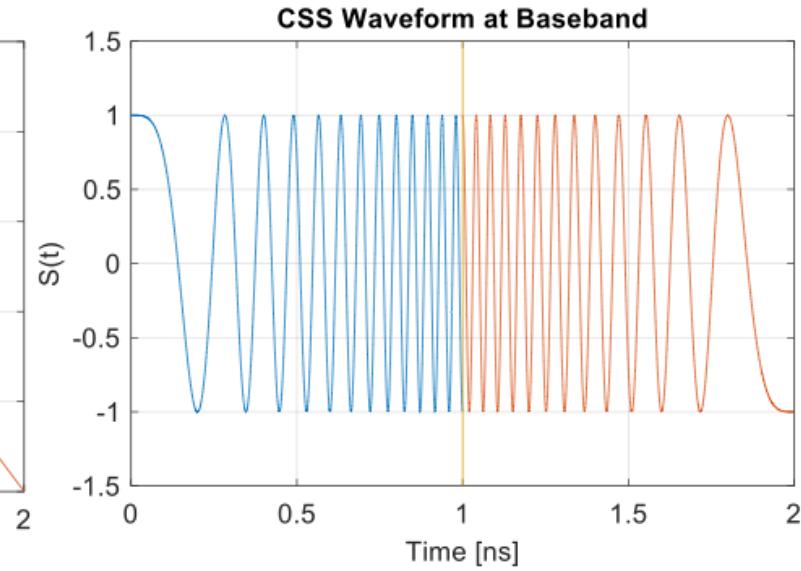
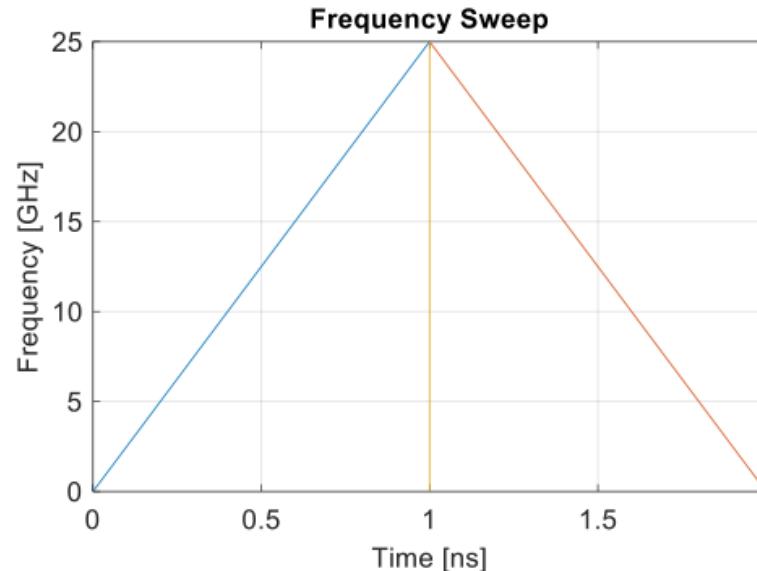
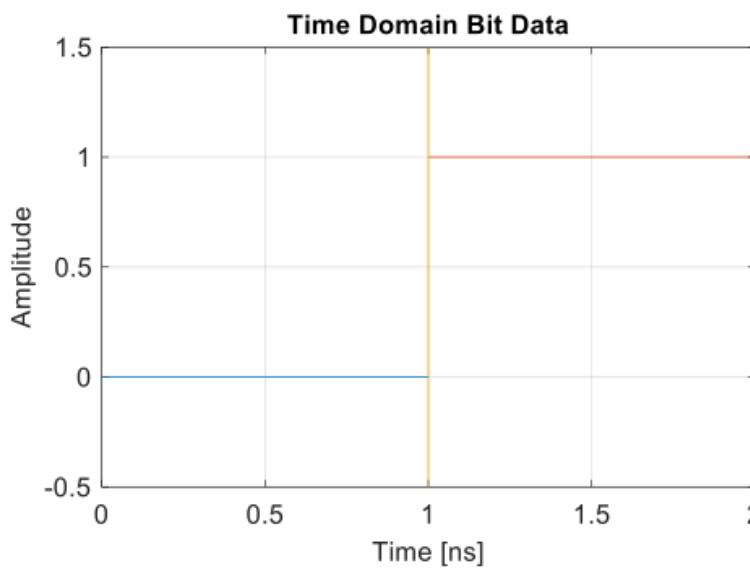
- The transmitter hops among frequencies many times per second
 - Enhanced security, low interference, high spectral reuse
 - E.g., military communications, Bluetooth



This is at the basis of Bluetooth!

Chirp Spread Spectrum

- Information is encoded in the changes in carrier frequency across a large bandwidth
- Signal occupies a wideband spectrum at all times

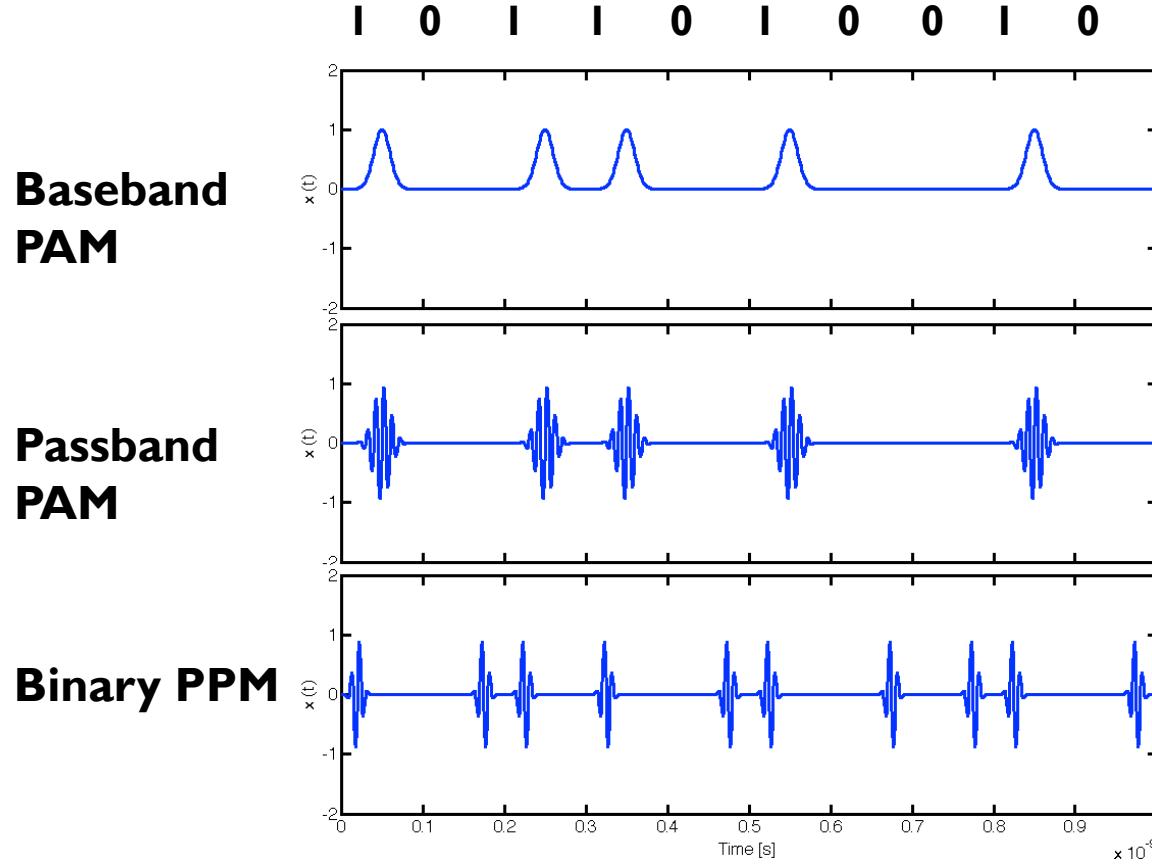


We will talk more about this modulation when covering LoRaWAN, one of the major IoT standards!

Pulse-based Modulations

- Make use of pulse-shape signals
 - **Pulse Amplitude Modulation (PAM):** two different pulse amplitudes are used to transmit either 0 or 1
 - Unipolar (On/Off), Bipolar, and multi-level variations exist
 - **Pulse Position Modulation (PPM):** the relative temporal position of a pulse within a slot is used to transmit either 0 or 1
 - Multi-level PPM modulations are also common

Examples



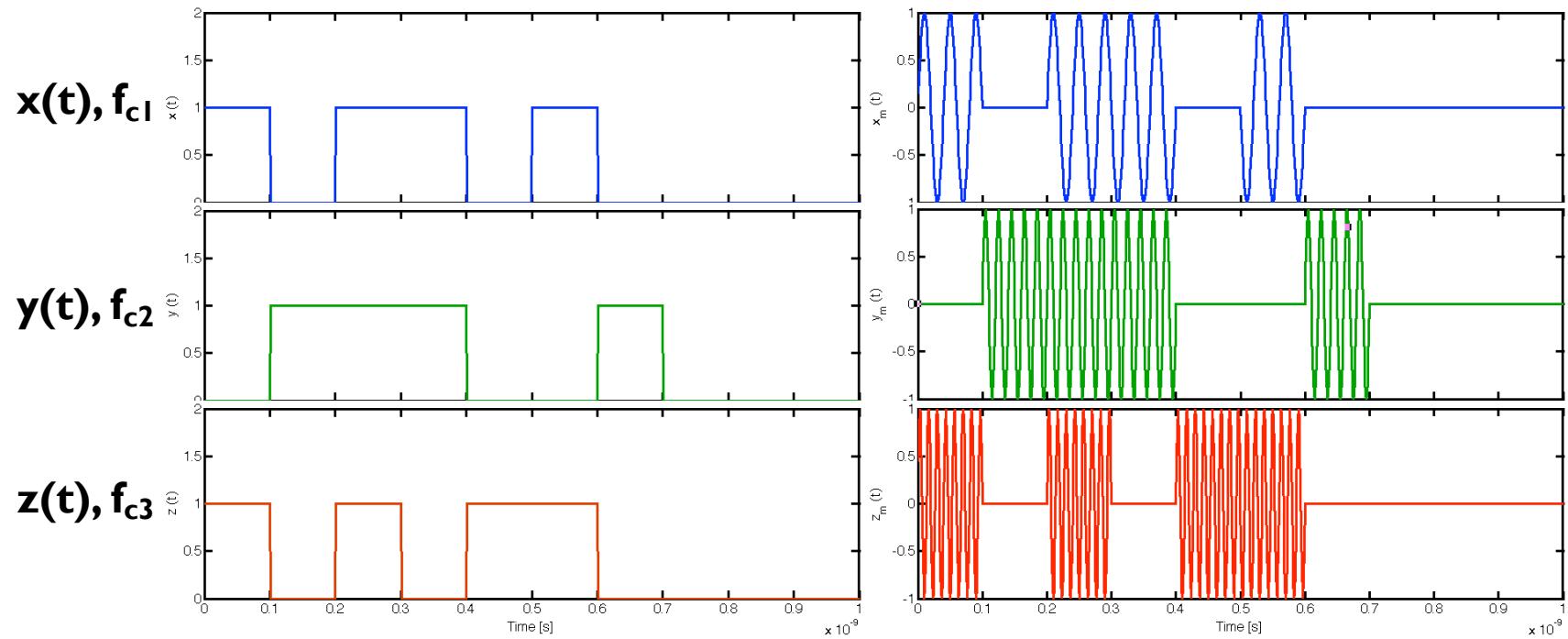
Multiplexing

- To combine **multiple signals over the same physical medium**
 - Either to enable one user to transmit more information at the same time
 - Or to enable multiple users to share the physical medium without interfering → We will see more about this at the link layer
- Common techniques:
 - **Frequency Division Multiplexing (FDM)**
 - **Time Division Multiplexing (TDM)**
 - **Code Division Multiplexing (CDM)**

Frequency Division Multiplexing

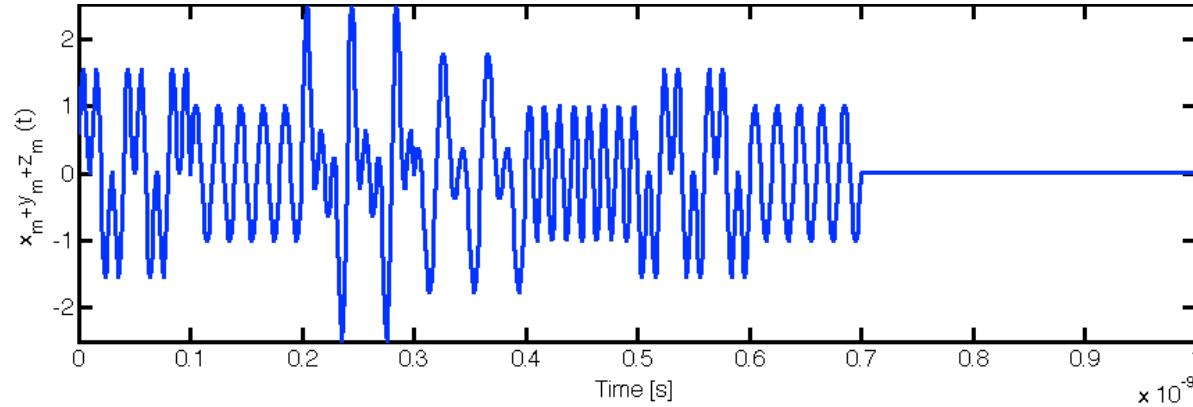
- To utilize different bandpass signals at different frequencies over the same medium simultaneously
- In classical FDM,
 - The separation between frequencies needs to be larger than twice the baseband signal bandwidth

Example

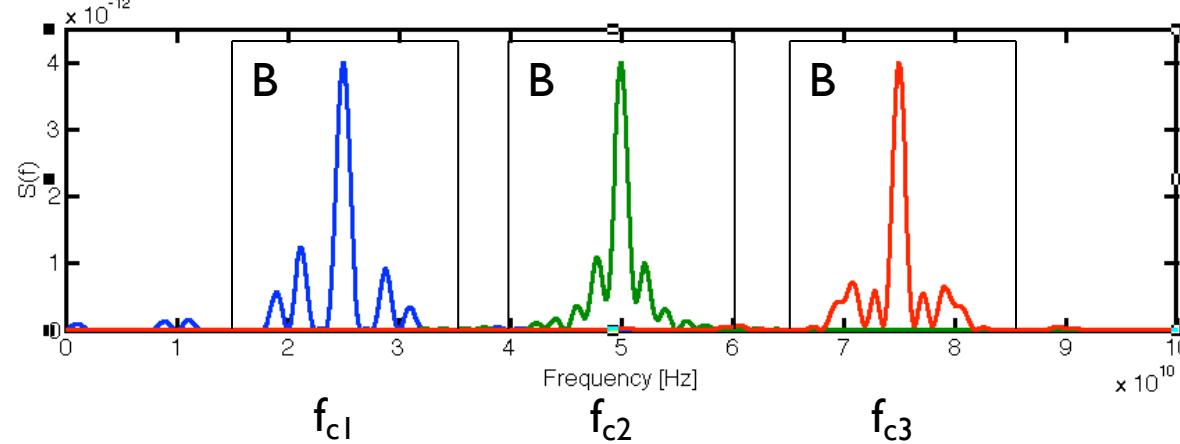


Example

$x(t) + y(t) + z(t)$

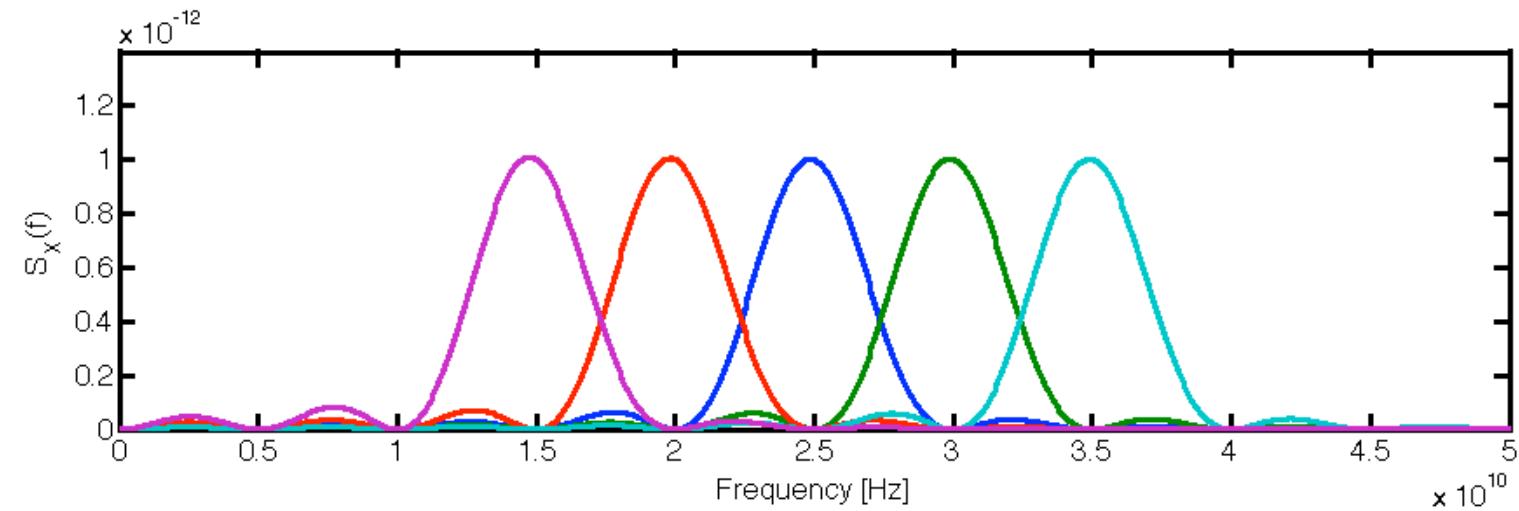


$S_x(f) + S_y(f) + S_z(f)$



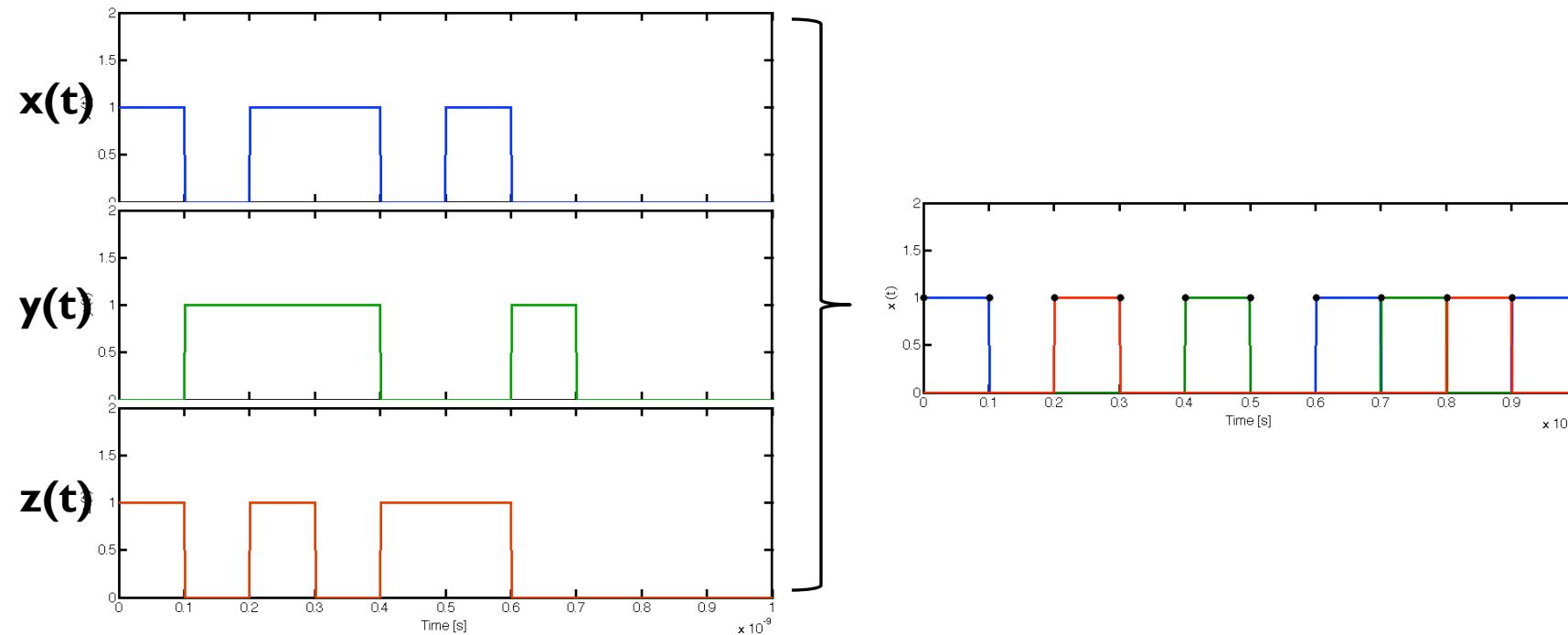
Orthogonal Frequency Division Multiplexing

- Multiple sub-bands can be used without any actual band guard, by properly designing their position and shape:
 - Each “sub-band” is very narrow → Very low data-rate per carrier
 - But many parallel “sub-bands” can be used simultaneously → **High aggregated data-rate**



Time Division Multiplexing

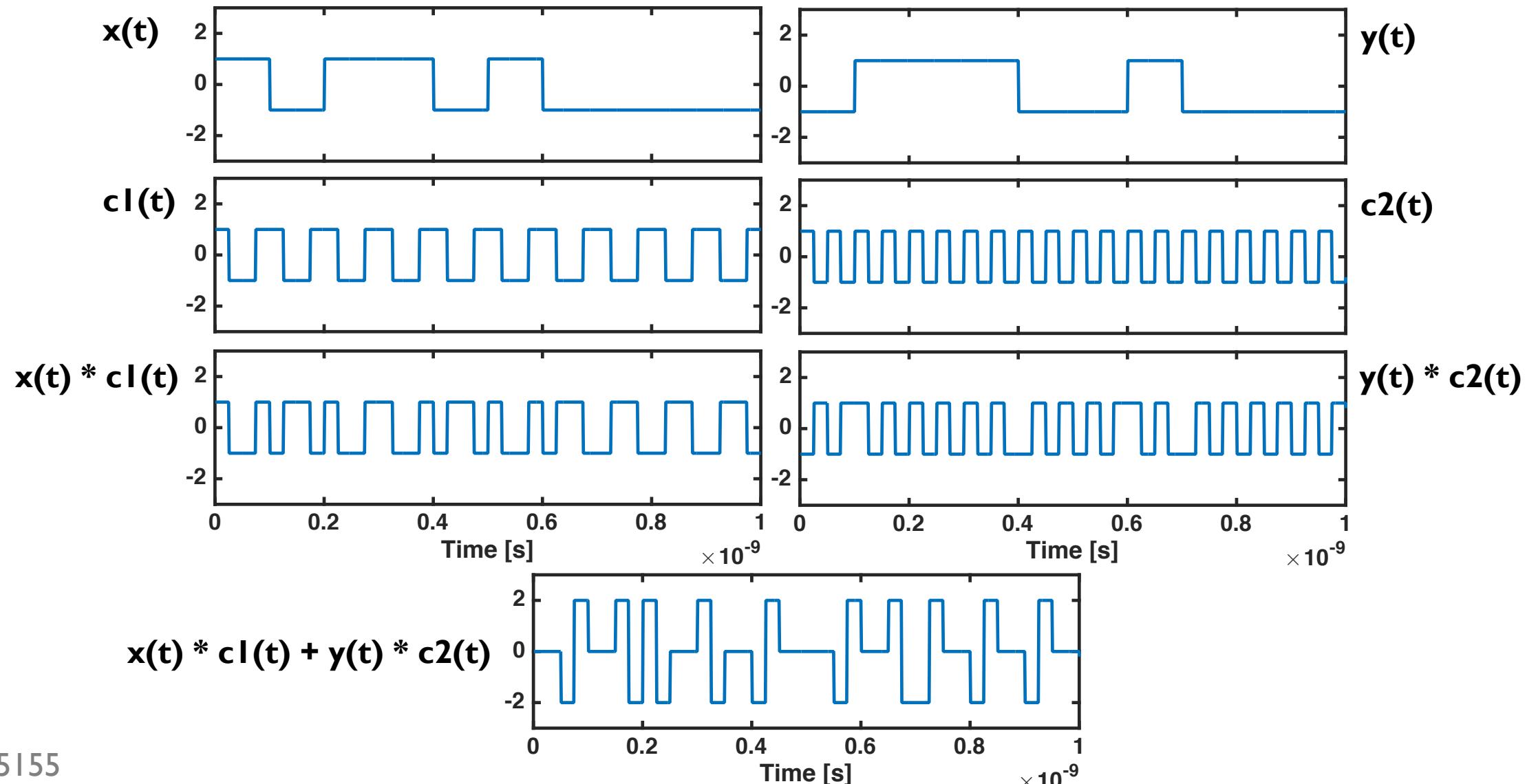
- Different signals take different times or slots to utilize the physical medium
 - Tight synchronization is needed!



Code Division Multiplexing

- To spread a narrow band signal over a wider frequency band:
 - Multiple signals can occupy the same frequency band without altering each other...
 - ... as long as they use different orthogonal codes
 - Code: a binary signal whose bits, usually called chips, are much shorter than the data bits
- To encode the data,
 - the transmitted signal is multiplied by a specific code
- To decode the data,
 - the received signal is multiplied by the same code

Example



Demodulation (at the receiver)

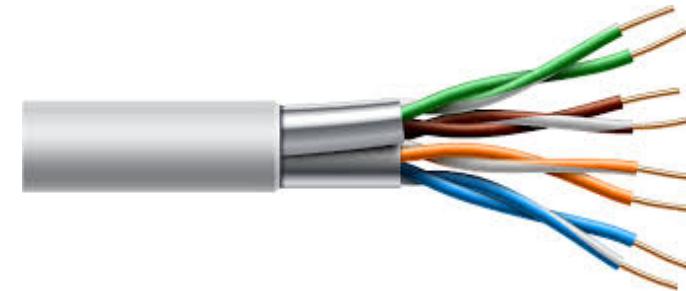
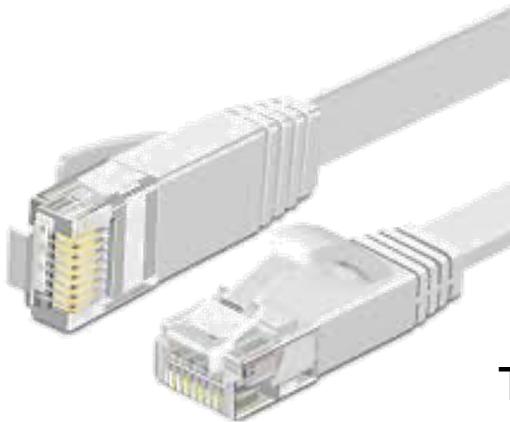
- The receiver looks at the received waveform and matches it with the data bit that caused the transmitter to generate this waveform
 - Necessary: one-to-one mapping between data and waveform
 - Because of channel imperfections, this is at best possible for digital signals, but not for analog signals
- Problems caused by
 - **Carrier synchronization:** frequency can vary between sender and receiver (drift, temperature changes, aging, ...)
 - **Symbol synchronization:** When does symbol representing a certain bit start/end?
 - **Frame synchronization:** When does a packet start/end?
- **Biggest problem:** Received signal is not the transmitted signal!
 - Why? Because of the **channel!**

Channel Response

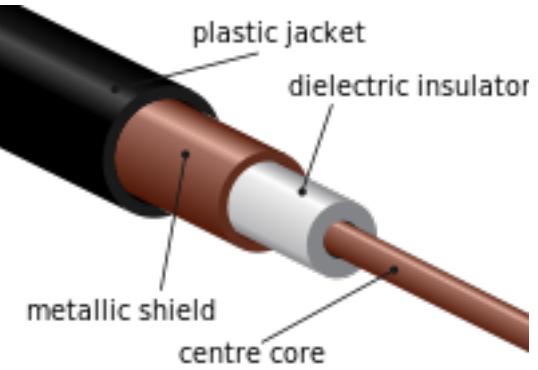
- **Channel Response:**
 - When a signal propagates through a channel, it usually suffers from **attenuation** (i.e., its power decreases) and it experiences a certain **delay**
 - In addition, the channel might affect the different frequency components of a signal in a different way, which results in **distortion**
 - Moreover, there might be:
 - **Noise:** any undesired random fluctuation of the signal
 - E.g., thermal noise, shot noise, etc.
 - **Interference:** generated by other users or phenomena, not necessarily random
 - E.g., multi-user interference, microwave ovens, etc.

All these depend on the type of channel!

Wired Channels



Twisted pairs

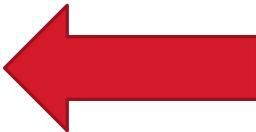


Coaxial cables

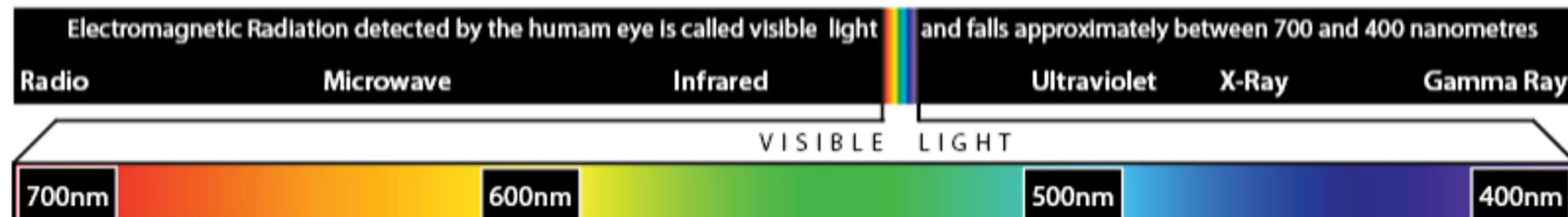
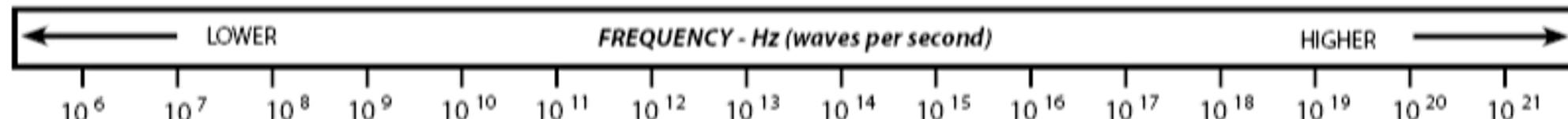
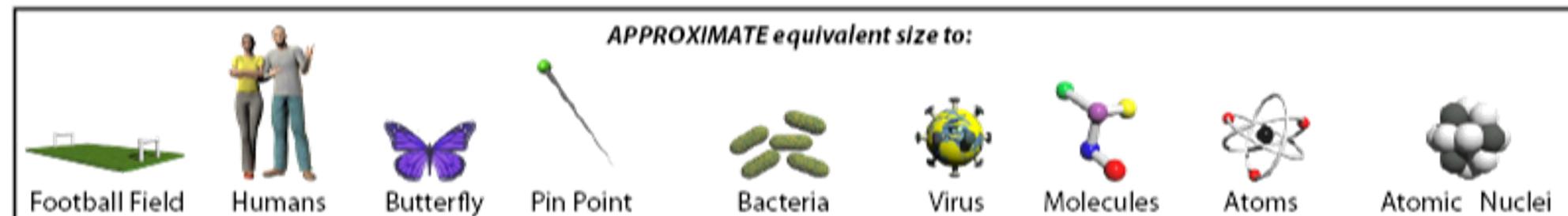
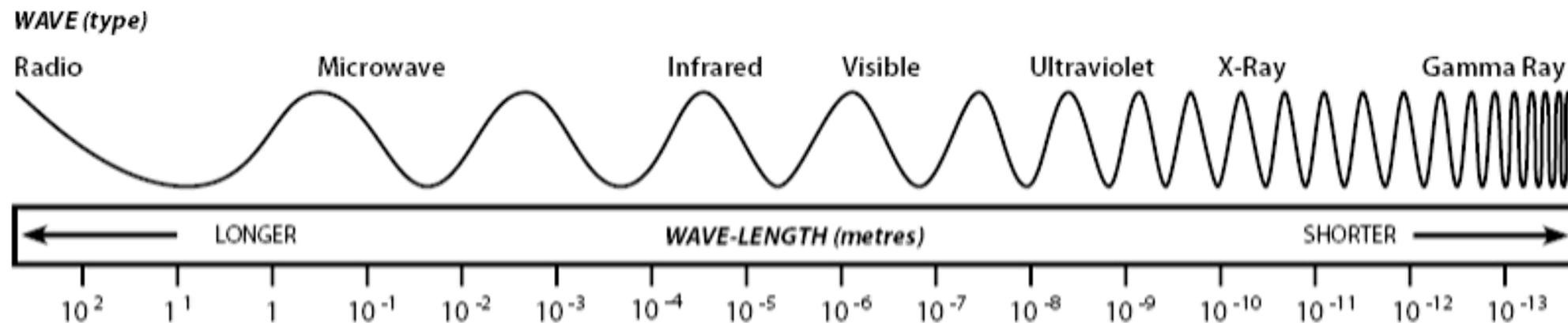


Optical fibers

- **Electromagnetic Communication**
- **Acoustic Communication**
- **Molecular Communication**
- ...

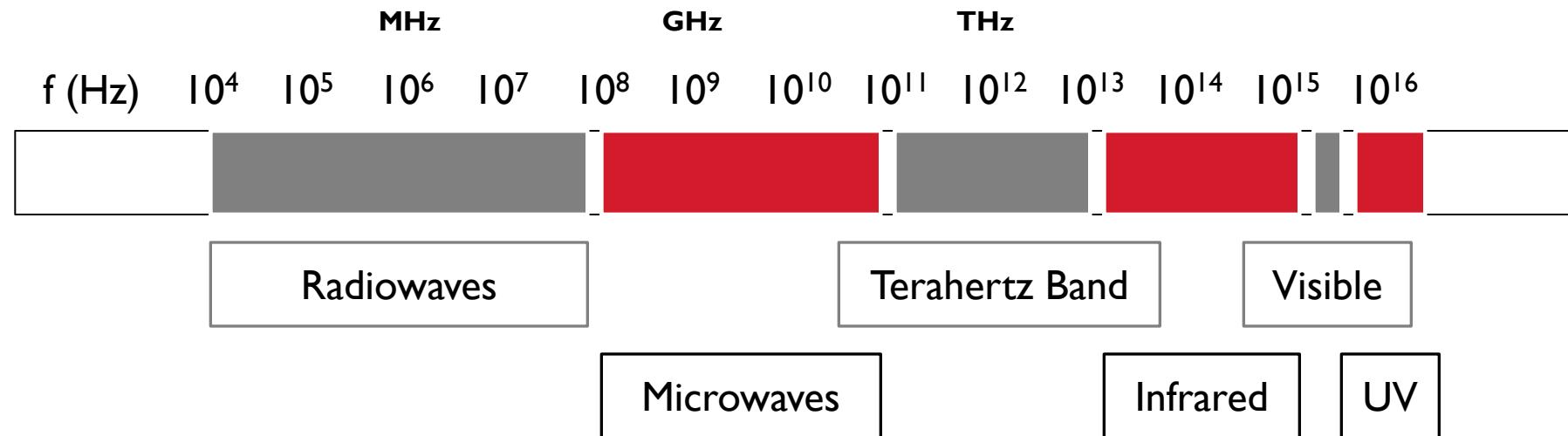


The Electromagnetic Spectrum



Electromagnetic Communication

- Based on the transmission of electromagnetic (EM) waves, which propagate in the free space at close to the speed of light in the vacuum ($c \approx 3 \cdot 10^8$ m/s)



Radiowaves

- **From 3 kHz to 300 MHz**
- **Properties:**
 - Easy to generate
 - Omnidirectional propagation
 - Transmission distance up to hundreds of km
 - Can penetrate buildings
- **Applications:**
 - AM radio broadcasting
 - $f_c = [153-279 \text{ kHz}, 531-1611 \text{ kHz}, 2.3-26.1 \text{ MHz}]$, $B=10 \text{ kHz}$, Spacing=20 kHz
 - FM radio broadcasting
 - $f_c = [87.5-108 \text{ MHz}]$, $B=20 \text{ kHz}$, Spacing=200 kHz
 - TV broadcasting
 - $f_c = [54-806 \text{ MHz}]$, $B=[5-8 \text{ MHz}]$
 - Marine communication, air traffic control
 - ...

Microwaves

- **From 300 MHz to 30 GHz**
- **Properties:**
 - Easy to generate
 - Omnidirectional or directional propagation
 - Transmission distances decreases fast with distance (from hundreds of m up to few km)
 - Cannot easily penetrate buildings
- **Applications:**
 - Cellular telephony (1G, 2G, 3G, 4G and 5G New Radio Frequency-Range I)
 - $f_c = [806-960 \text{ MHz}, 1710-2025 \text{ MHz}, 2110-2200 \text{ MHz}, 2600-2690, \dots]$, B=depends on standard=[200kHz, 20 MHz]
 - Cordless phones
 - $f_c = [1.9, 2.4, 5.8 \text{ GHz}]$, B=3.6 kHz
 - WiFi, Bluetooth, ZigBee
 - $f_c = [2.4, 5 \text{ GHz}]$, B=depends on the standard

Millimeter Waves

- **From 30 GHz to 300 GHz**
- **Properties:**
 - Harder to generate
 - Mostly directional propagation
 - Transmission distances decreases very fast with distance (from hundreds of m up to few km)
 - Cannot penetrate buildings
- **Applications:**
 - 5G New Radio Frequency Range 2
 - $f_c=[24-250 \text{ GHz}]$, $B=\text{up to } 800 \text{ MHz}$
 - WiFi (IEEE 802.11ad and ay)
 - $f_c=60 \text{ GHz}$, up to $B=14 \text{ GHz}$ (57-71 GHz)
 - ...

- **From 300 GHz to 10 THz (not yet regulated!)**
- **Properties:**
 - Not so easy to generate (becoming easier...)
 - Mainly directional propagation
 - Transmission distance below ten meters, unless ultra-directional systems are used
 - Cannot penetrate buildings, objects, etc.
- **Applications:**
 - Very high bandwidth applications (multi Gbps and Tbps links):
 - Next generation WLAN/WPAN
 - Next generation small cell systems
 - Electromagnetic Nanonetworks
 - ...

Optical Wireless Communications

- **From 10 THz to 790 THz (infrared, visible, ultra-violet)**
- **Properties:**
 - Different technologies with different complexity and performance exists:
 - E.g., LEDs for low-cost OWC systems over short distances or more expensive lasers for LAN interconnection across buildings
 - Directional propagation only
 - Transmission distance changes drastically with application and technology (from few m up to km)
 - Cannot penetrate buildings, objects, etc.
- **Applications:**
 - Remote control for TV, DVD, etc.
 - LiFi: Indoor LAN with LEDs
 - Temporary network installation (e.g., fairs, conferences)
 - ...

Wireless Propagation

- A wirelessly propagating signal might experience
 - **Delay:** The signals propagate at the speed of light, not instantaneously
 - **Attenuation:** The energy of the transmitted signal is distributed over larger areas as it propagates
 - **Distortion:** The waveform (shape) of the received signal is different from the transmitted one

Attenuation: Path Loss

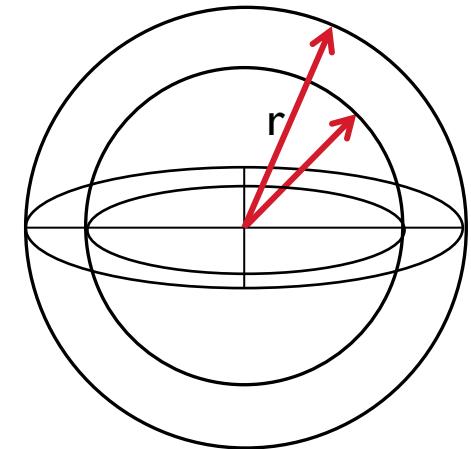
- Measures how much power is lost as the signal propagates over longer distances
- The simplest model for the free space path-loss: the **Friis transmission equation**

$$P_{rx}(d) = P_{tx} G_{tx} \frac{1}{4\pi d^2} \frac{\lambda^2}{4\pi} G_{rx}$$

$$P_{rx}(d) = P_{tx} G_{tx} G_{rx} \left(\frac{\lambda}{4\pi d} \right)^2$$

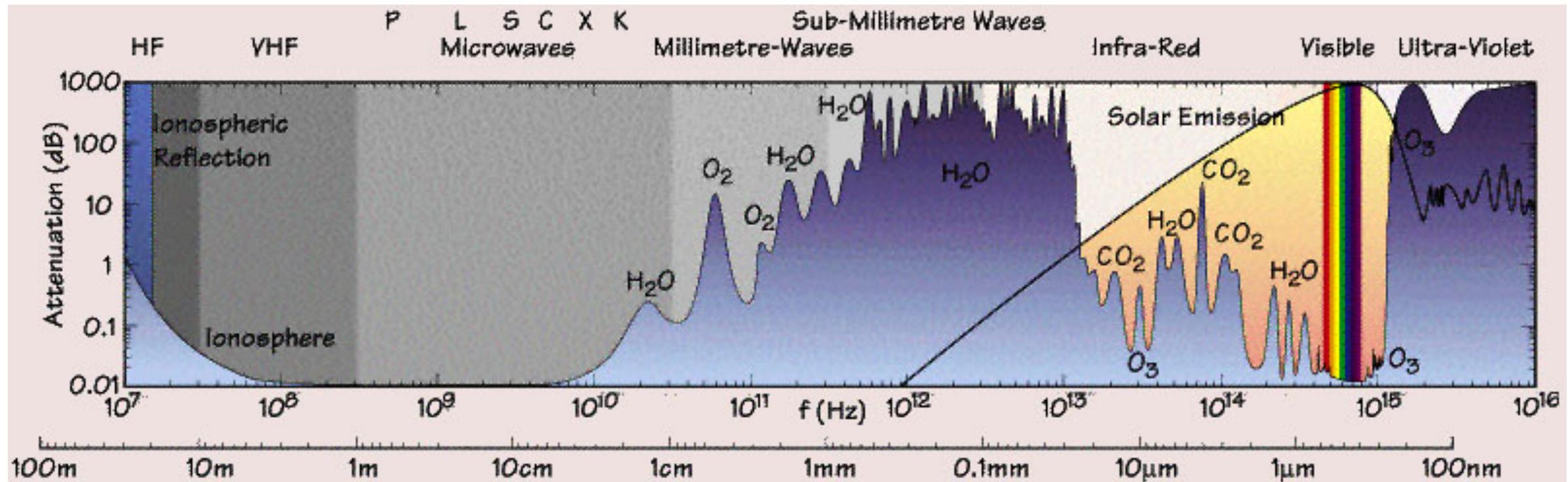
$$P_{rx}(d) = P_{rx}(d_0) \left(\frac{d_0}{d} \right)^2$$

- P_{rx} = Power at the receiver
- P_{tx} = Power at the transmitter
- d = distance
- G_{tx} = Antenna gain at the transmitter
- G_{rx} = Antenna gain at the receiver
- $\lambda = c/f$ = Signal wavelength
- c = signal propagation speed
- f = signal frequency
- d_0 = reference distance



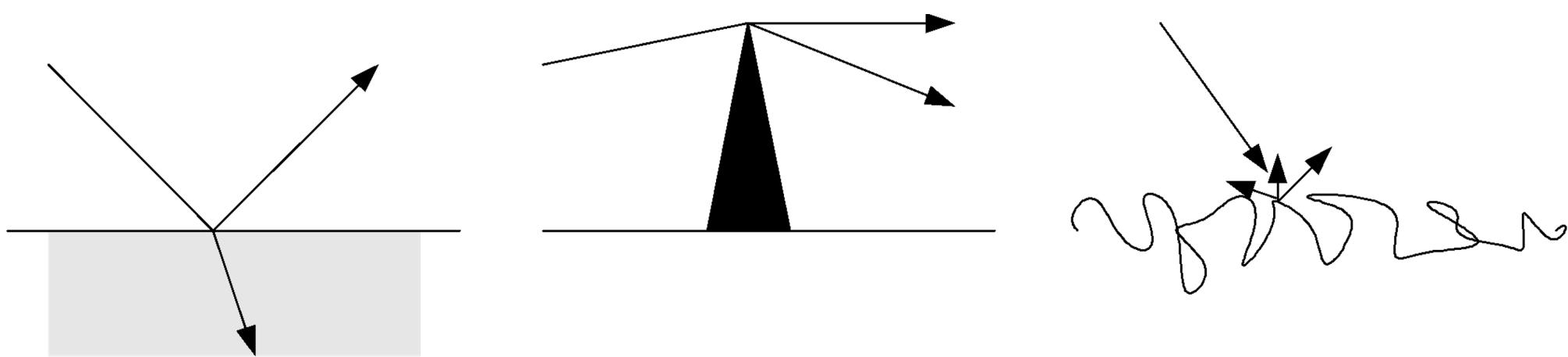
Attenuation: Frequency Selectivity

- Attenuation might be different at different frequencies, because of different phenomena
 - For example, absorption by different molecules lead to frequency-selective behavior



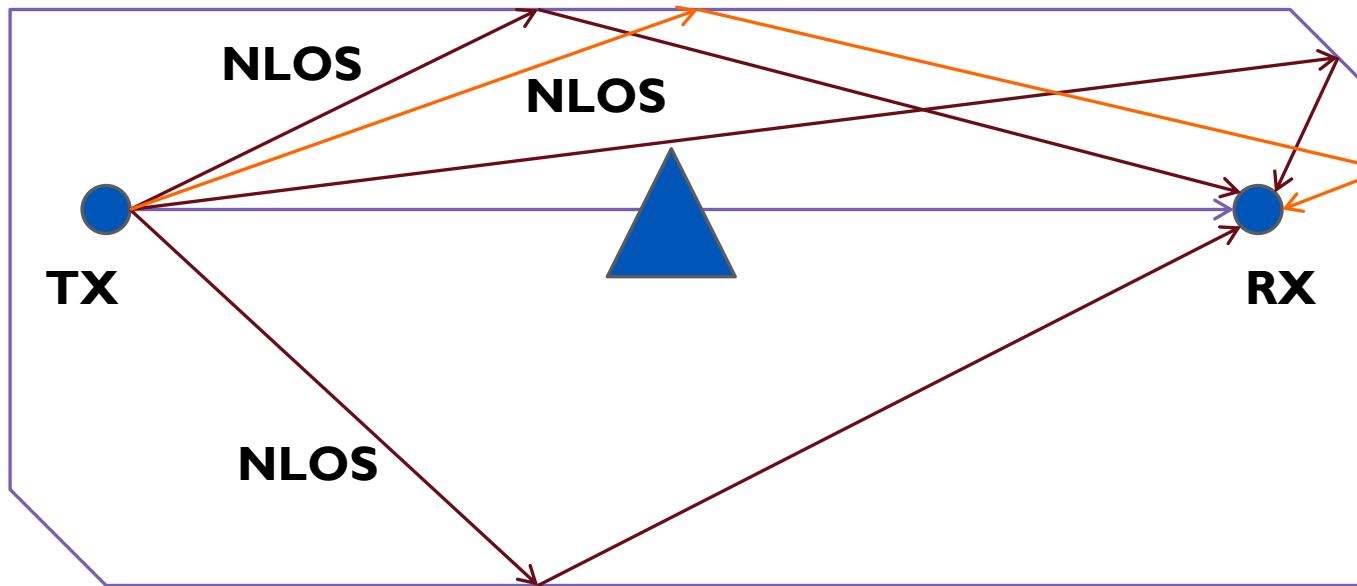
Distortion Effects

- Sources of distortion
 - **Reflection/refraction:** bounce of a surface; enter material
 - **Diffraction:** start “new wave” from a sharp edge
 - **Scattering:** multiple reflections at rough surfaces (e.g., tree leaves)
 - **Doppler fading:** shift in frequencies (loss of center)

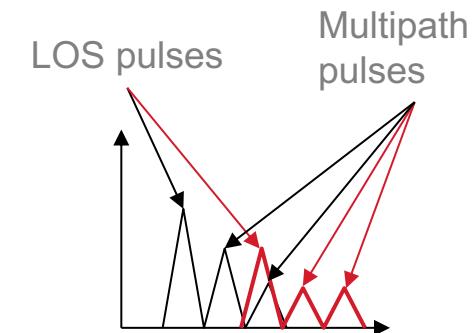


Distortion Effects: Non-line of Sight Paths

- Because of reflection, scattering, ..., radio communication is not limited to the direct line of sight communication
 - Effects depend strongly on frequency, thus different behavior at higher frequencies

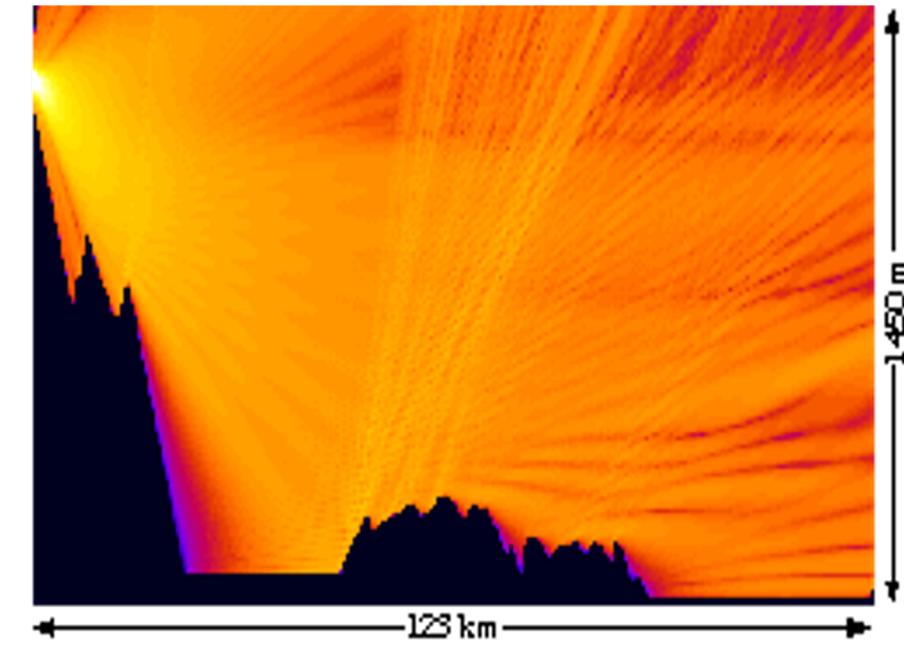
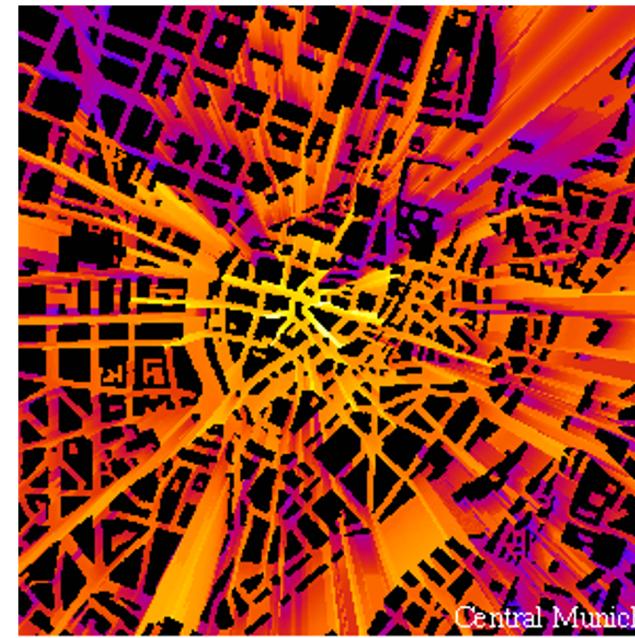
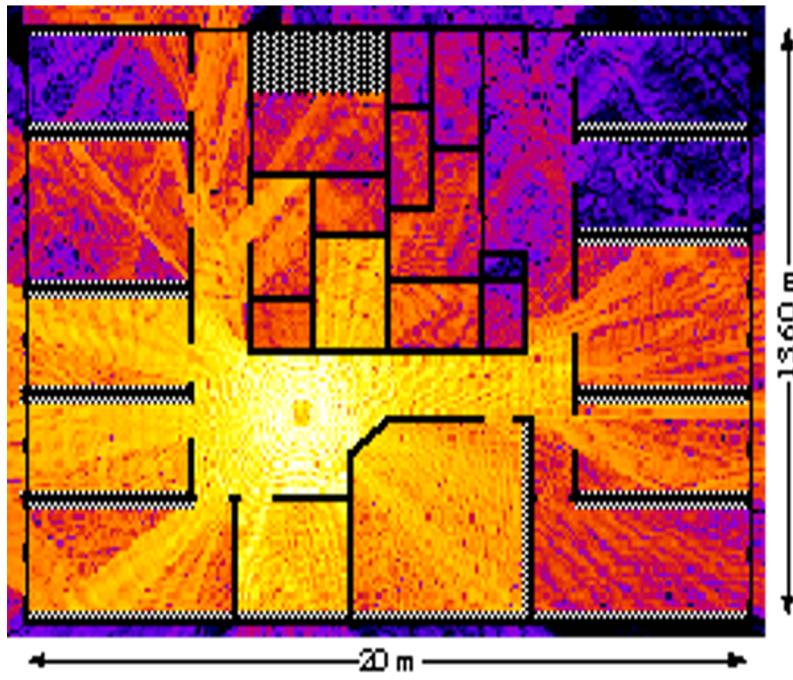


- Different paths have different lengths = propagation time
 - Results in **delay spread** of the wireless channel
 - Closely related to **frequency-selective fading** properties of the channel
 - With movement: **fast fading**



Wireless Signal Strength in Multi-path Environments

- Brighter color = stronger signal
- Obviously, simple (quadratic) free space attenuation formula is not sufficient to capture these effects



Path-loss in Multi-path Scenarios

- To take into account the stronger attenuation resulting from the presence of obstacles and multi-path propagation, a modified path-loss equation is used

$$P_{rx}(d) = P_{rx}(d_0) \left(\frac{d_0}{d} \right)^\gamma$$

- where γ is the path-loss exponent and, generally, $2 < \gamma < 5$
- This can also be rewritten in logarithmic form (in dBW):

$$P_{rx}(d)[dB] = P_{rx}(d_0)[dB] + 10\gamma \log_{10} \left(\frac{d_0}{d} \right)$$

- To take into account the random locations of the obstacles and their role, a Gaussian random variable with 0 mean and σ^2 variance can be added to the pathloss in dB

$$P_{rx}(d)[dB] = P_{rx}(d_0)[dB] + 10\gamma \log_{10} \left(\frac{d_0}{d} \right) + X_\sigma[dB]$$

- This is equivalent to multiplying with a lognormal distributed r.v. in metric units
 - This is why we refer to this as lognormal fading

Noise and Interference

- The received signal is further affected by
 - **Noise**
 - Temperature-dependent effects in the receiver electronics
 - Common model: **Additive White Gaussian Noise (AWGN)**
 - Noise is modeled as an additional random signal that appears at the receiver, independent of what is being received, and follows a Gaussian distribution with zero mean and the same power at all frequencies (that is what white means)
 - **Interference**
 - Co-channel interference: another sender uses the same spectrum
 - Adjacent-channel interference: another sender uses some other part of the radio spectrum, but receiver filters are not good enough to fully suppress it
- Conclusion: The received signal is distorted by the channel and corrupted by noise and interference
 - What is the result on the received bits?

Symbols and Bit Errors

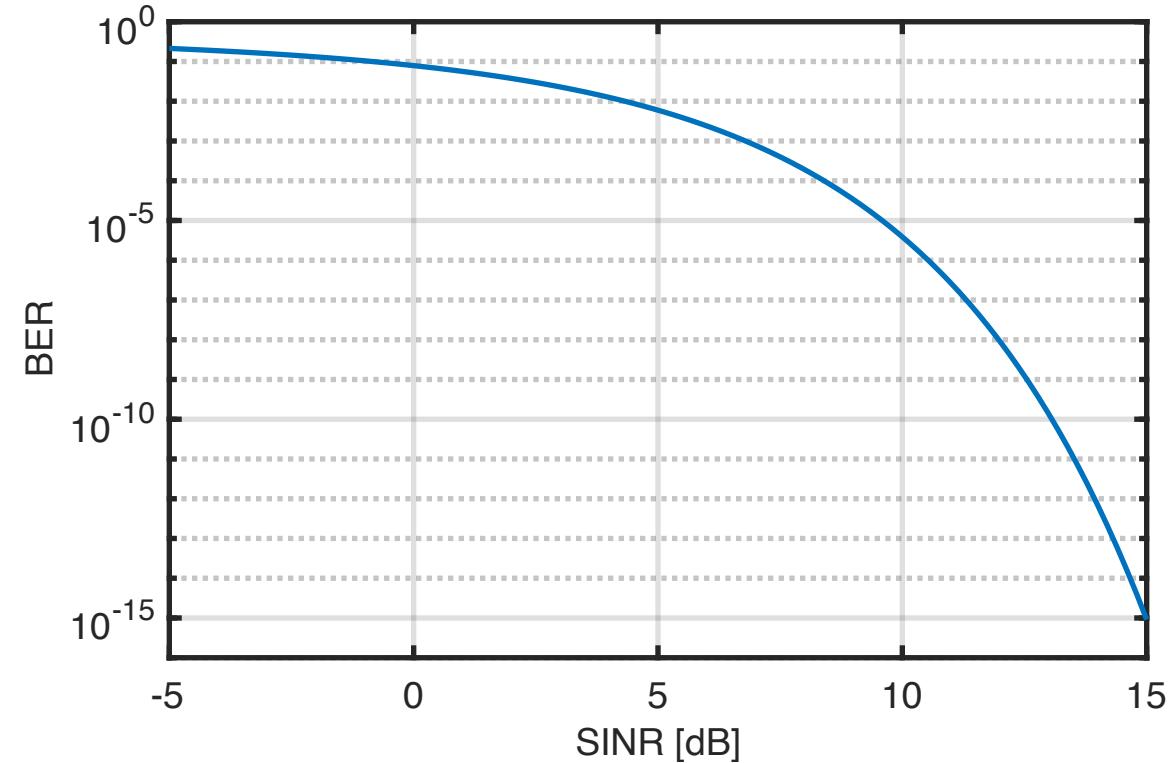
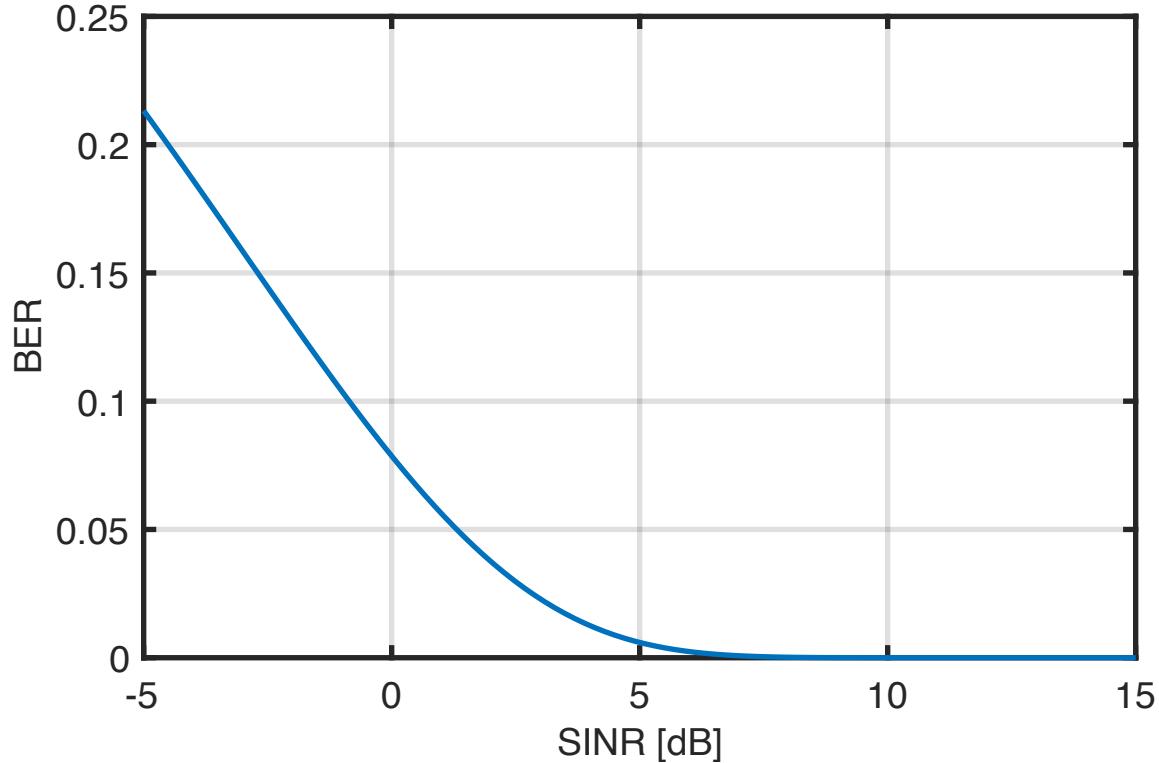
- Extracting symbols out of a distorted/corrupted waveform causes errors
- The number of errors depends on strength of the received signal compared to the corruption
 - This is measured by the **Signal to Interference plus Noise Ratio (SINR)**

$$SINR = 10 \log_{10} \left(\frac{P_{rx}}{N_0 + \sum_{i=1}^k I_i} \right)$$

- The SINR allows to compute **Bit Error Rate (BER)** for a given modulation
 - Also depends on data rate (# bits/symbol) of modulation
 - E.g., for a Binary Phase Shift Keying modulation:

$$BER(SINR) = \frac{1}{2} \operatorname{erfc} \left(\sqrt{\frac{E_b}{N_0}} \right) \text{ with } \frac{E_b}{N_0} = SINR \text{ (only for BPSK)}$$

BER vs SINR

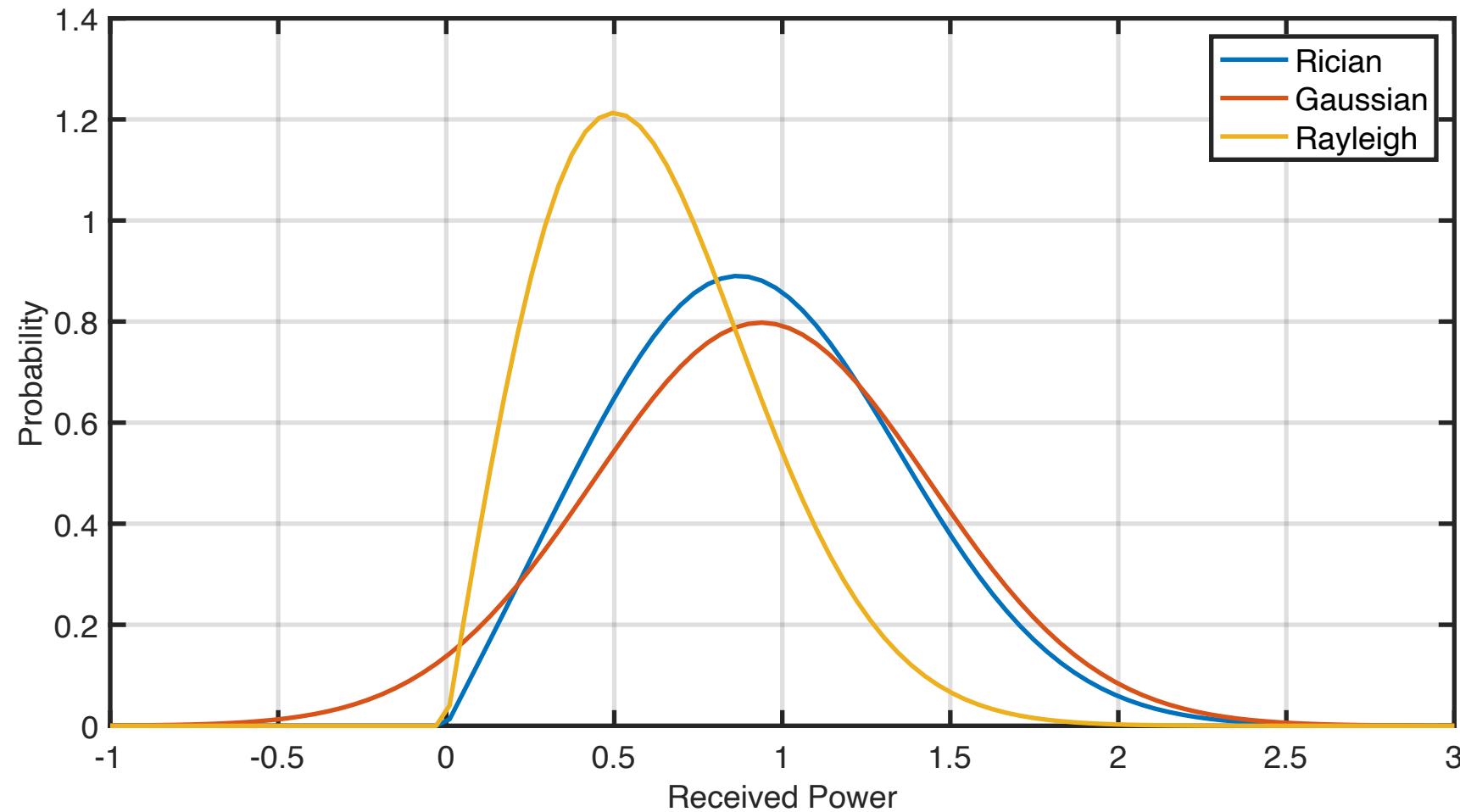


Notes: when plotting the BER, please use a logarithmic axis!
For a communication system to work properly, you should aim for $\text{BER} = 10^{-4}$ or lower!

(Analog) Channel Models

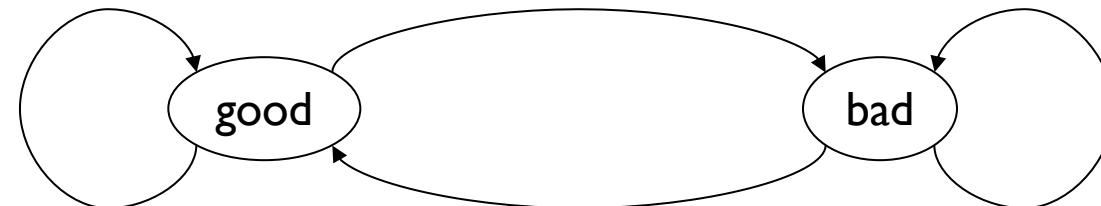
- When designing a networking application, being able to estimate the SINR (and, correspondingly, the BER) is extremely important
 - It determines for example how far apart the devices should be, how much power should they transmit, etc.
- To predict the SINR, we utilize channel models, which stochastically capture the behavior of the wireless channel
- Common channel models consider:
 - Transmission power P_{tx} is constant
 - Noise is additive, Gaussian and white (AWGN, Slide 49)
 - If free-space (no obstacles), there is one direct path for the signal → Friis equation (Slide 43)
 - If there is one dominant line-of-sight plus many indirect paths:
 - Signal has a Rice distribution (**Rice fading**)
 - If there is no line-of-sight path, but only many indirect paths:
 - Amplitude of resulting signal has a Rayleigh distribution (**Rayleigh fading**)
 - This is the model used for the majority of mobile scenarios at frequencies < 6 GHz

Channel Models



(Digital) Channel Models

- Instead of calculating signals, these are aimed at directly modeling the resulting bit error behavior
- Many models:
 - Binary symmetric channel (BSC)
 - Each bit is erroneous with constant probability, independent of the other bits
 - Markov models – states with different BERs
 - Example: Gilbert-Elliott model with “bad” and “good” channel states and high/low bit error rates



- Fractal channel models describe number of (in-)correct bits in a row by a heavy-tailed distribution

Wireless Channel Quality – Summary

- Wireless channels are substantially worse than wired channels
 - In throughput, bit error characteristics, energy consumption, ...
- Wireless channels are extremely diverse
 - There is no such thing as THE typical wireless channel
- Various schemes for quality improvement exist
 - Some of them geared towards high-performance wireless communication – not necessarily suitable for IoT
 - Some of them general-purpose
 - Energy issues need to be taken into account!

Choice of Modulation

- With all this knowledge in mind, going back to “signals”, how do we pick a modulation?
 - Consider: required data rate, available symbol rate, implementation complexity, required BER, channel characteristics, ...
 - Tradeoffs: the faster one sends, the longer one can sleep
 - However, power consumption can depend on modulation scheme
 - Tradeoffs: symbol rate (high?) versus data rate (low)
 - Use m-ary transmission to get a transmission over
- Adapt modulation choice to operation conditions
 - Akin to dynamic voltage scaling, introduce Dynamic Modulation Scaling

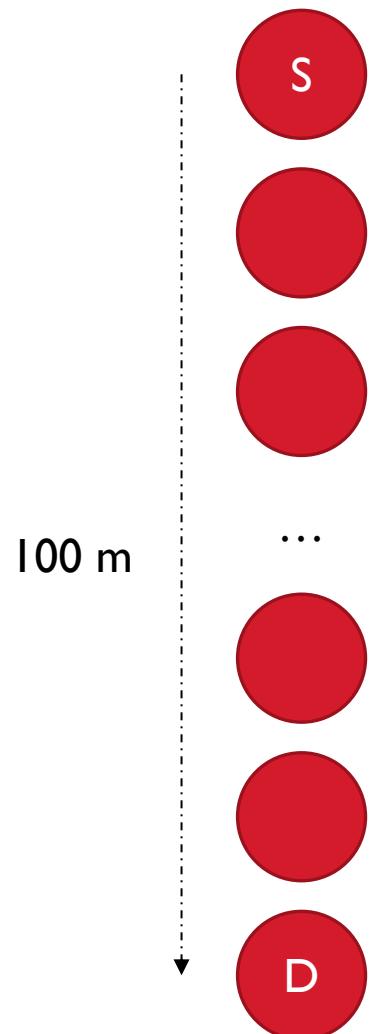
Summary of the Physical Layer

- Wireless radio communication introduces many uncertainties and vagaries into a communication system
- Handling the unavoidable errors will be a major challenge for the communication protocols
- Dealing with limited bandwidth in an energy-efficient manner is the main challenge
- Ideally, we design the hardware (transceiver and antennas) and the software (at least the physical layer) together:
 - That is why we need ECE!!!!

Class Exercise

- Consider the scenario on the right, with a source and a destination node 100 m apart. The transceiver in each node has the following specifications:

- Transmitter:
 - Frequency of operation: 2.4 GHz
 - Transmission power, P_{tx} : 10 mW
 - Antenna gain: 0 dBi
- Receiver:
 - Antenna gain: 0 dBi
 - Noise power model, P_N : $k \cdot B \cdot T$, where
 - k =Boltzmann constant = $1.380649 \times 10^{-23} \text{ J/K}$
 - B =system bandwidth [Hz]
 - T =system temperature [Kelvin degrees]



Class Exercise

- I) Under the assumption of free-space propagation, compute and plot the received power in dBm as a function of distance.

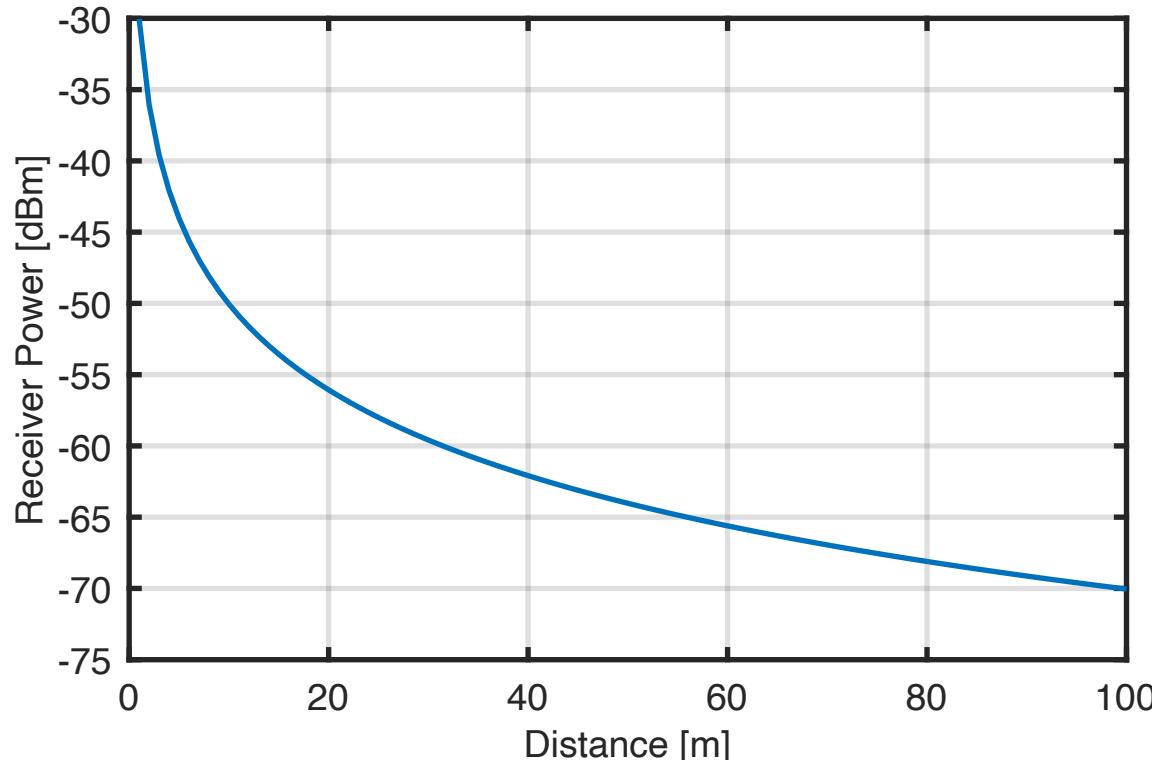
Class Exercise

$$P_{rx}(d) = P_{tx} G_{tx} G_{rx} \left(\frac{\lambda}{4\pi d} \right)^2$$

$$P_{rx}(d)[dBm] = P_{tx}[dBm] + G_{tx}[dBi] + G_{rx}[dBi] + 20 \log_{10} \frac{\lambda}{4\pi d}$$

$$\lambda = \frac{c}{f}$$

$$P_{rx}(d)[dBm] = 10 \log_{10}(10 \text{ mW}) + 0 \text{ dBi} + 0 \text{ dBi} + 20 \log_{10} \frac{c}{4\pi f d}$$



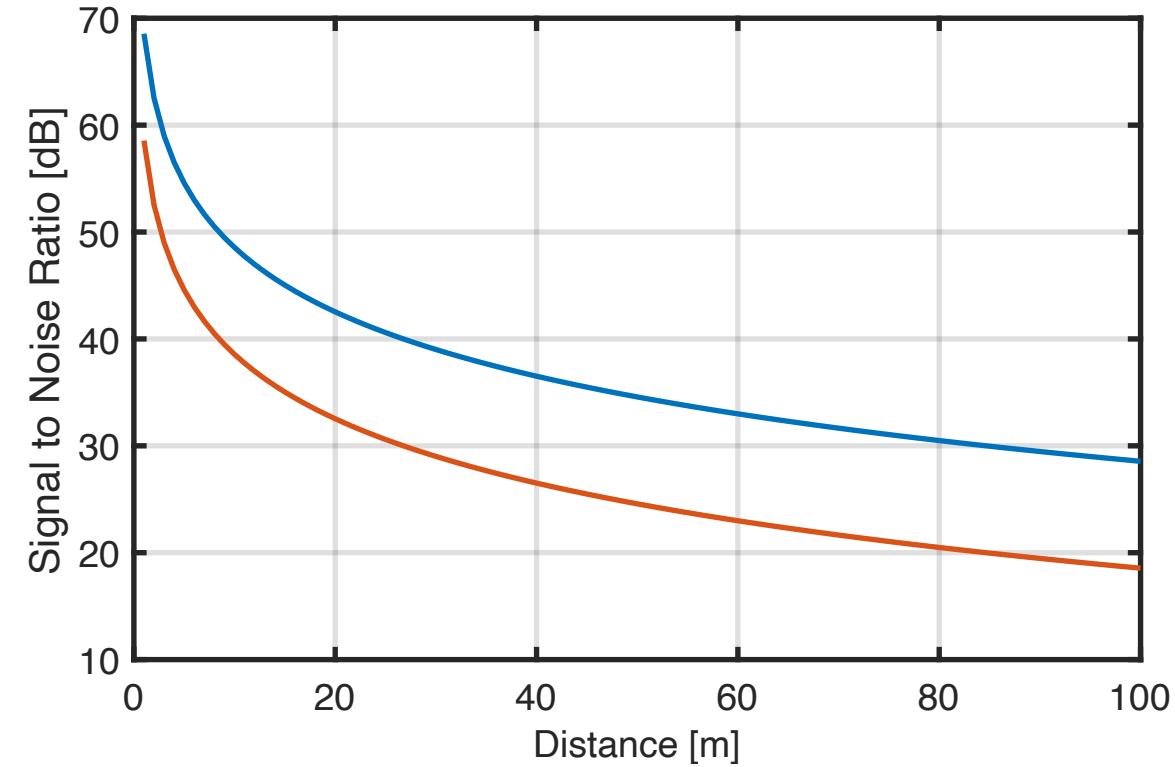
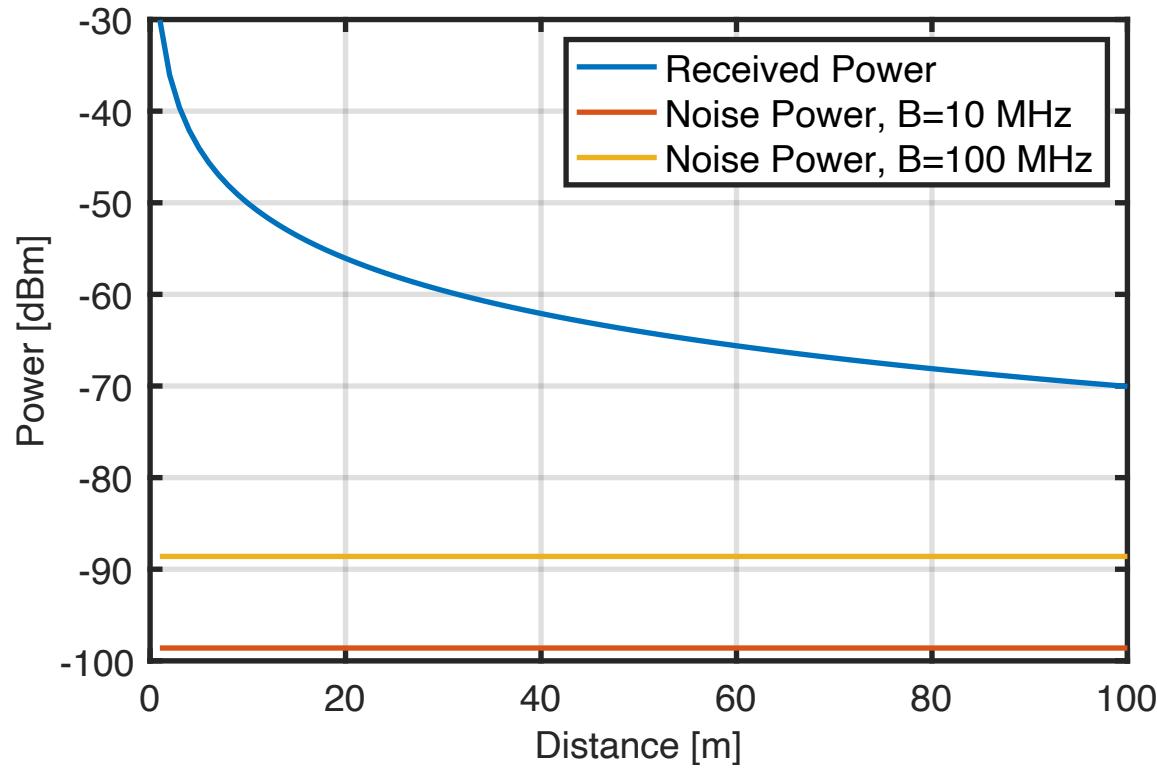
How meaningful is this?

Class Exercise

- 2) On the same figure, plot the noise in dBm at the receiver for the following two scenarios:
 - $T=1000 \text{ K}$, $B=10 \text{ MHz}$
 - $T=1000 \text{ K}$, $B=100 \text{ MHz}$

Class Exercise

$$P_N[\text{dBm}] = 10 \log_{10} kBT + 30 \quad (\text{to convert from dBW to dBm})$$



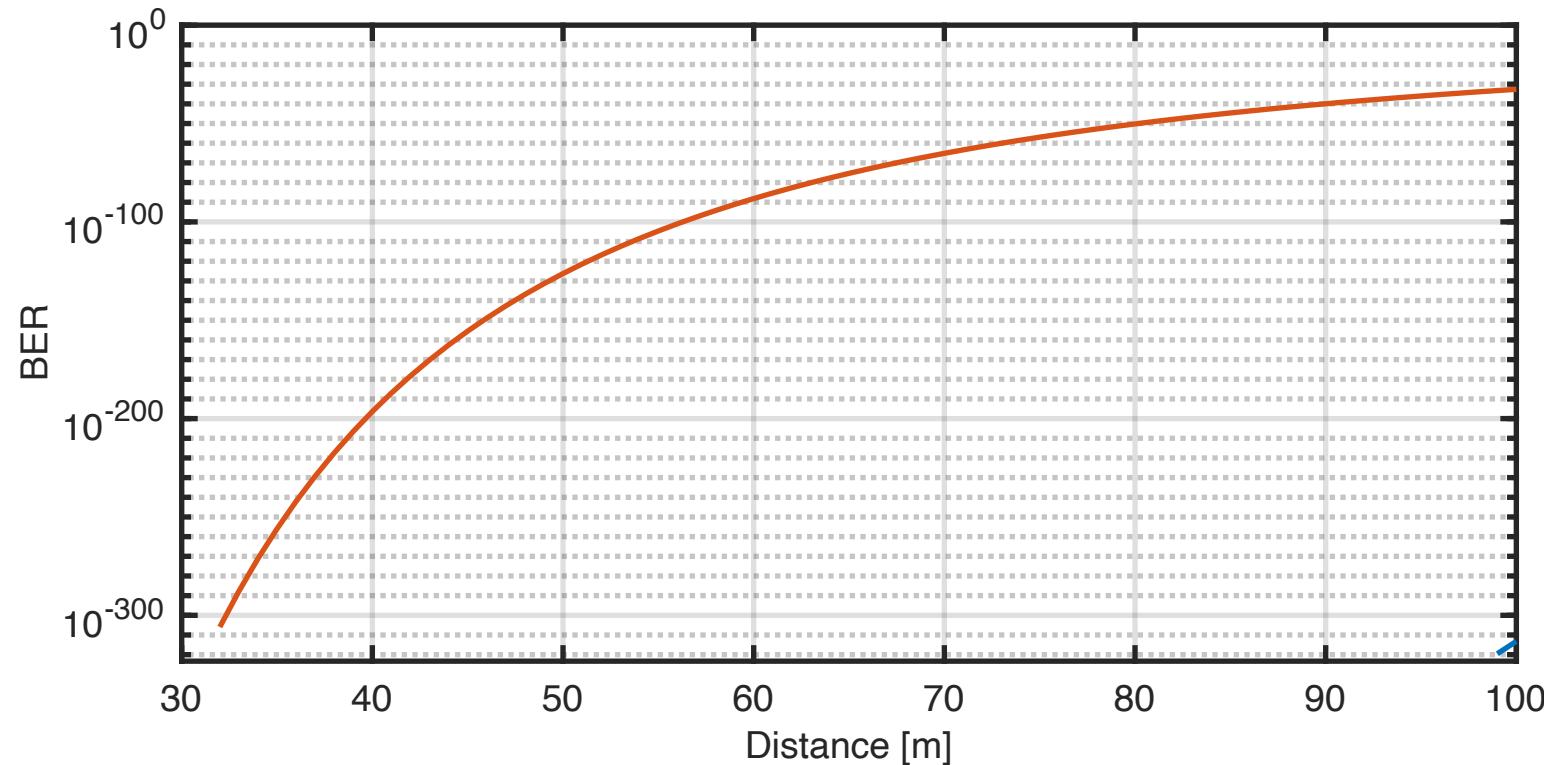
The power is much larger than the noise, good!

Class Exercise

- 3) Under the assumption that a BPSK modulation is being used, what is the bit error rate (BER) as a function of distance?

Class Exercise

$$BER(SINR) = \frac{1}{2} \operatorname{erfc}\left(\sqrt{\frac{E_b}{N_0}}\right) \text{ with } \frac{E_b}{N_0} = SINR \text{ (only for BPSK), in linear scale}$$

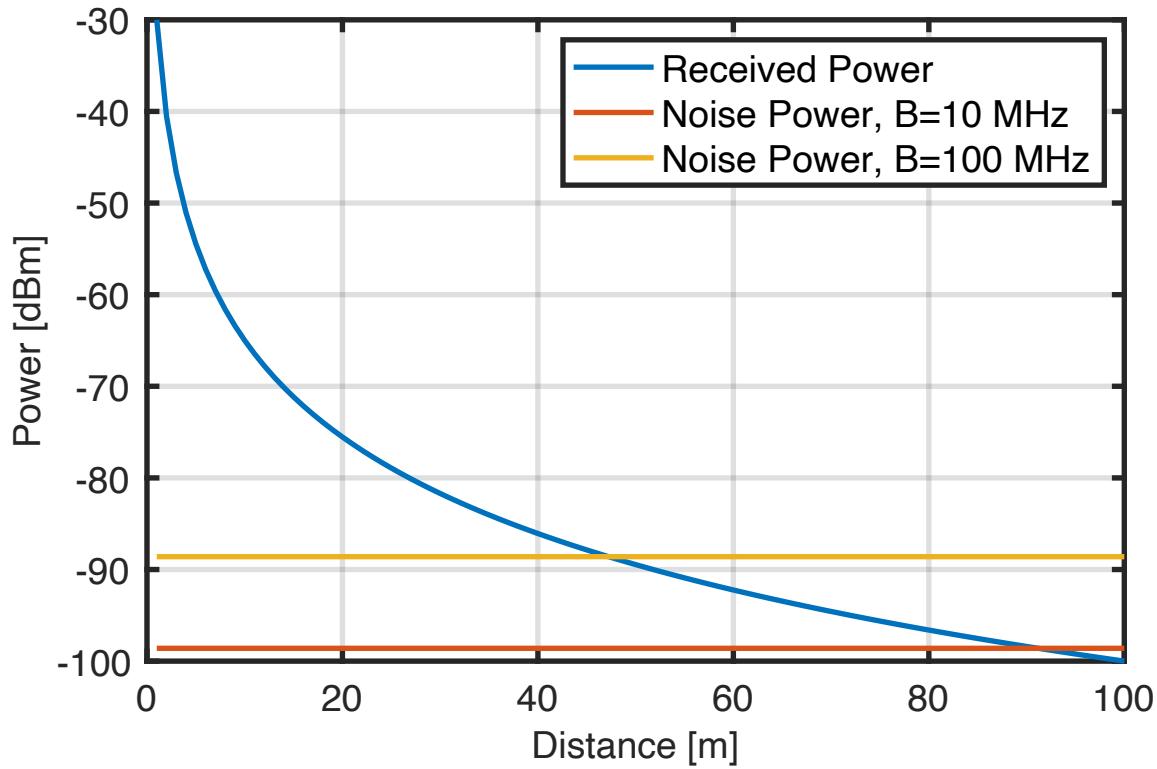


Class Exercise

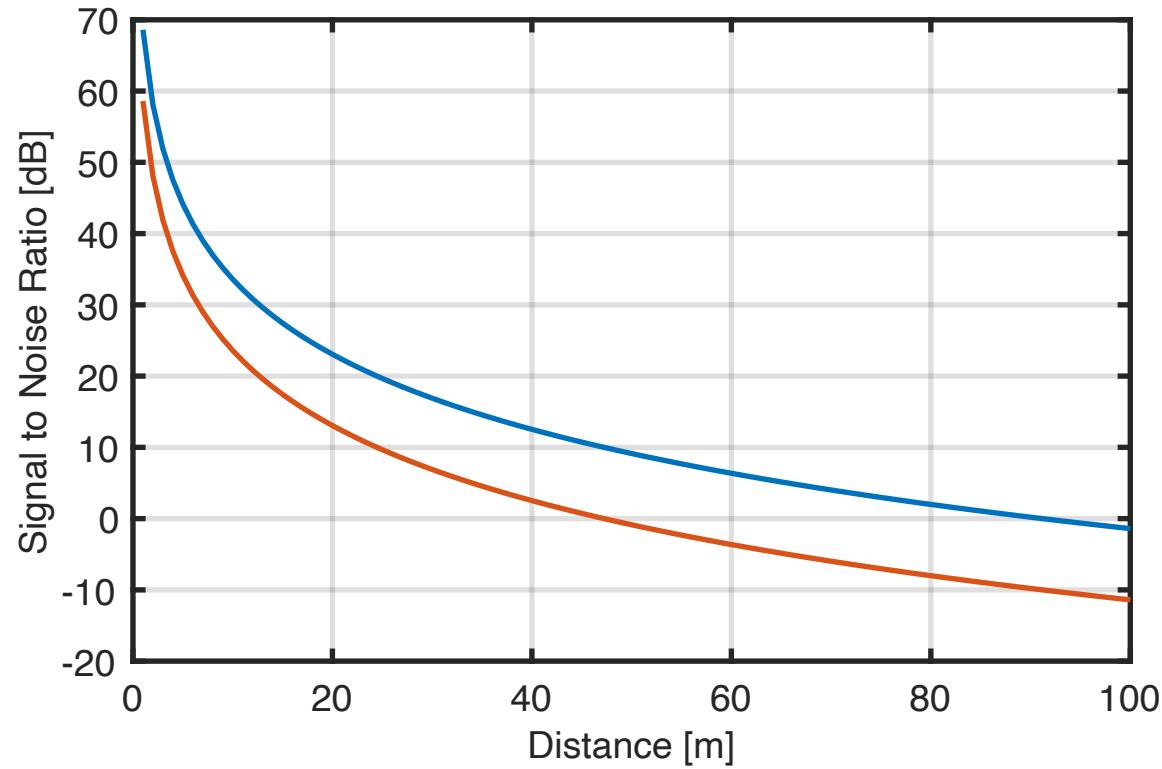
- 4) Let's consider that the system is no longer in free-space, but inside of a building, with multi-path propagation. Consider a reference distance $d_0=1$ m, and a propagation exponent of $\gamma=3.5$.
 - Plot the received power, the SNR and the BER as functions of distance

Class Exercise

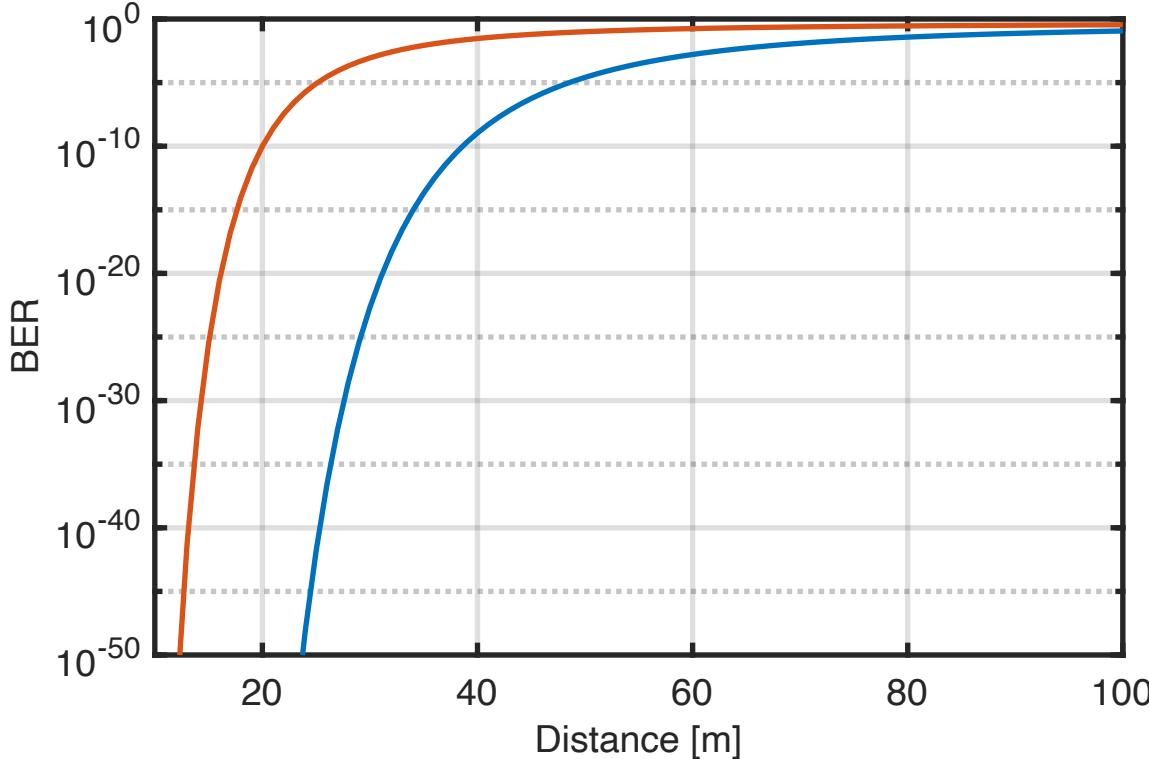
$$P_{rx}(d)[dB] = P_{rx}(d_0)[dB] + 10\gamma \log_{10} \left(\frac{d_0}{d} \right)$$



We consider free-space until 1 meter, then not free space
 $P_{rx}(d_0)[dBm] = -30 \text{ dBm}$



Class Exercise



- Now this is more of a problem.
- Things just get worse:
 - Random fading
 - Multi-user interference
- *More in your homework*