



Northeastern  
University

# **EECE 7205 Fundamentals of Computer Engineering Project 2**

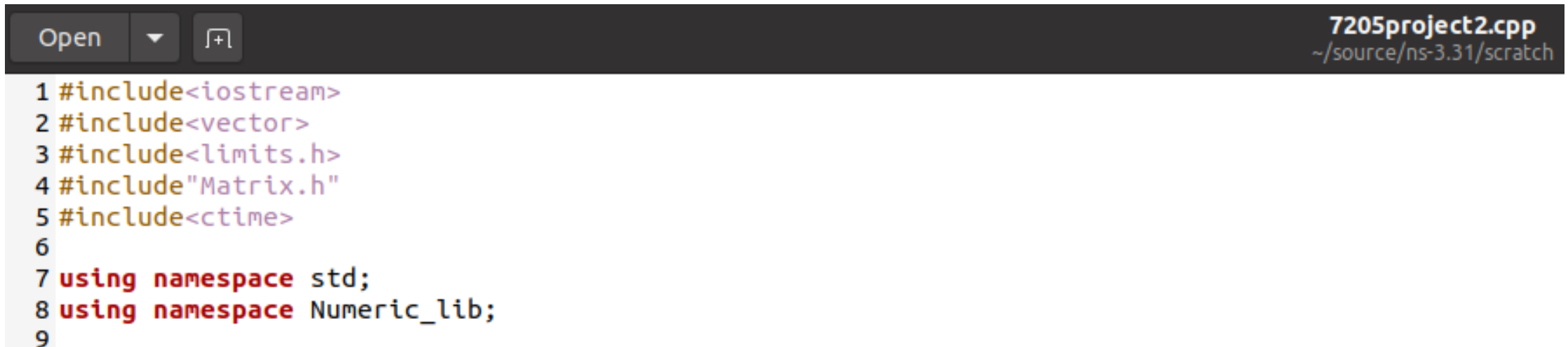
**Liangshe Li**

- **Part1 Program Setup**
- **Part2 Input and Output**
- **Part3 Conclusion**

# Part1 Program Setup

This part, I will explain the lines in my code.

First is the head files and namespace I set:

A screenshot of a code editor interface. The top bar is dark grey and contains three buttons: 'Open', a dropdown arrow, and a file icon. On the right side of the top bar, the text '7205project2.cpp' is displayed in a light color, with the file path '~/source/ns-3.31/scratch' below it. The main area of the editor shows C++ code with line numbers 1 through 9 on the left. The code includes several header files and uses namespaces. The code is color-coded: keywords like 'using' and 'namespace' are in red, and other tokens are in blue or purple.

```
1 #include<iostream>
2 #include<vector>
3 #include<limits.h>
4 #include"Matrix.h"
5 #include<ctime>
6
7 using namespace std;
8 using namespace Numeric_lib;
9
```

Here I establish a new data structure called “task”.

```
10 struct task {  
11     int num; // the number of the task  
12     bool ct; // judge whether the task is a cloud task  
13     double pri; //  
14     int FTL; // the finish time of the task in a core  
15     int FTWS; // the finish time of the task in sending  
16     int FTC; // the finish time of the task in cloud  
17     int FTWR; // the finish time of the task in receiving  
18     int RTL; // the earliest time that the task can start in local core  
19     int RTWS; // the earliest time that the task can start in sending  
20     int RTC; // the earliest time that the task can start in cloud  
21     int RTWR; //the earliest time that the task can start in receiving  
22     int ST; // the task's actual start time  
23     int chan; // illustrate which channel the task operate (local core = 0,1,2, cloud=3)  
24     bool exit; //whether it is an exit task  
25     bool entry; // whether it is an entry task  
26     int ready1;  
27     int ready2;  
28 };
```

Here I explain the function of each parameter in the new data structure:

- **num:** the serial number of the task
- **ct:** judge whether the task is a cloud task
- **pri:** the priority level of the task
- **FTL:** if local schedule, the finish time of the task in local core
- **FTWS:** if cloud schedule, the finish sending time of the task in wireless channel
- **FTC:** if cloud schedule, the finish compute time of the task in cloud
- **FTWR:** if cloud schedule, the finish receiving time of the task in wireless channel
- **RTL:** if local schedule, the ready time of the task in local core
- **RTWS:** if cloud schedule, the ready sending time of the task in wireless channel
- **RTC:** if cloud schedule, the ready compute time of the task in cloud
- **RTWR:** if cloud schedule, the ready receiving time of the task in wireless channel
- **ST:** the actual start time of the task
- **chan:** the location of the task(if 0,1,2, is in local core 1,2,3; if 3, is in cloud)
- **exit:** judge whether the task is an exit task
- **entry:** judge whether the task is an entry task
- **ready1:** in kernel algorithm, the number of immediate predecessors of task which have not been scheduled
- **ready2:** in kernel algorithm, the number of tasks in the same channel before the task which have not been scheduled

Here is the Phase One in Step One: Primary assignment.

```
// Phase one in step one: primary assignment
void primary(vector<task>&ini, Matrix<int, 2>&ta, int t)
{
    int min;
    unsigned int i;
    unsigned int j;
    for (i = 0; i < ta.dim1(); i++)
    {
        ini[i].num = i + 1;
        min = ta(i, 0);
        for (j = 0; j < ta.dim2(); j++)
            if (ta(i, j) < min)
                min = ta(i, j);

        if (min > t)
            ini[i].ct = 1;
        else
            ini[i].ct = 0;
    }
}
```

Here is the Phase Two in Step One: Task prioritizing. (I also determine the value of exit and entry)

```
49 -
50 // Phase two in step one: task prioritizing
51 void prioritize(vector<task>&ini, Matrix<int, 2>&ta, Matrix<int, 2>&G,int t)
52 {
53     unsigned int i;
54     unsigned int j,m;
55     int k ;
56     double w;
57     double max;
58     m = ini.size() - 1;
59     for (i = 0; i < ini.size(); i++)
60     {
61         k = 0;
62         for (j = 0; j < G.dim2(); j++)
63             if (G(m - i, j) == 1)
64                 k = k + 1;
65         if (k == 0)
66             ini[m - i].exit = 1;
67         k = 0;
68         for (j = 0; j < G.dim2(); j++)
69             if (G(j, m - i) == 1)
70                 k = k + 1;
71         if(k==0)
72             ini[m - i].entry = 1;
73         max = 0;
74         w = 0;
75         if (!(ini[m - i].ct))
76         {
77             for (j = 0; j < ta.dim2(); j++)
78                 w = w + ta(m - i, j);
79             w = w / 3;
80         }
81         else
82             w = t;
83         for (j = 0; j < G.dim2(); j++)
84             if ((G(m - i, j) == 1) && (max < ini[j].pri))
85                 max = ini[j].pri;
86         ini[m - i].pri = w + max;
87     }
88 }
89
```

Here is the main function of Phase Three in Step One: Execution unit selection.

I use “mint” to compute the minimum finish time in local core and use “anot” to compute the minimum finish time in cloud. Then compare this two values to determine whether the task in cloud or local core.

```

3
4 void initials(vector<task>&S, vector<task>&ini, Matrix<int, 2>&ta, Matrix<int, 2>&G, int ts, int tc, int tr)
5 {
6     unsigned int i;
7     int t;
8     int maxp; // find the max priority in each iteration of ini
9     int mint; // find the minimum finish time of local
10    int anot; // perpare for another time (cloud)
11    t = ts + tc + tr;
12    for (i = 0; i < G.dim1(); i++)
13    {
14        maxp = find_biggest_pri(ini);
15        if (!ini[maxp].ct)
16        {
17            mint = locals(ini[maxp], S, G, ta);
18            anot = clouds(ini[maxp], S, G, ts, tc, tr);
19            if (anot < mint)
20            {
21                ini[maxp].RTL = 0;
22                ini[maxp].FTL = 0;
23                ini[maxp].chan = 3;
24                ini[maxp].FTWR = anot;
25                ini[maxp].ST = anot - t;
26            }
27            else
28            {
29                ini[maxp].FTC = 0;
30                ini[maxp].FTWS = 0;
31                ini[maxp].RTWS = 0;

```

```

7205project2.cp
~/source/ns-3.31/src

1        ini[maxp].RTL = 0;
2        ini[maxp].FTL = 0;
3        ini[maxp].chan = 3;
4        ini[maxp].FTWR = anot;
5        ini[maxp].ST = anot - t;
6    }
7    else
8    {
9        ini[maxp].FTC = 0;
10       ini[maxp].FTWS = 0;
11       ini[maxp].RTWS = 0;
12       ini[maxp].RTC = 0;
13       ini[maxp].RTWR = 0;
14       ini[maxp].FTWR = 0;
15       ini[maxp].FTL = mint;
16       ini[maxp].ST = mint - ta(ini[maxp].num - 1, ini[maxp].chan);
17   }
18   }
19   else
20   {
21       ini[maxp].FTL = 0;
22       ini[maxp].RTL = 0;
23       ini[maxp].chan = 3;
24       ini[maxp].FTWR = clouds(ini[maxp], S, G, ts, tc, tr);
25       ini[maxp].ST = ini[maxp].FTWR - t;
26   }
27   S.push_back(ini[maxp]);
28   ini.erase(ini.begin() + maxp);
29   }
30 }
31 // return a task's finish time

```



Here is the function which returns the maximum finish time of task in local core.

```
5
6 // if local schedule, return the smallest finish time
7 int locals(task &vi, vector<task>&S, Matrix<int, 2>&G, Matrix<int, 2>&ta)
8 {
9     vi.Rtl = d_rtl(vi, S, G);
10    unsigned int i;
11    unsigned int j;
12    int mint=INT_MAX;
13    int ft;
14    int max = 0; // find a local core's biggest finish time
15    if (S.size()==0)
16    {
17        for (i = 0; i < ta.dim2(); i++)
18        {
19            ft = ta(vi.num - 1, i);
20            if (mint > ft)
21            {
22                mint = ft;
23                vi.chan = i;
24            }
25        }
26        return mint;
27    }
28    for (i = 0; i < ta.dim2(); i++)
29    {
30        ft = vi.Rtl + ta(vi.num - 1, i);
31        max = 0;
32        for (j = 0; j < S.size(); j++)
33            if ((S[j].chan == i) && (max < S[j].FTL))
34                max = S[j].FTL;
35        if(max>vi.Rtl)
36            ft=max+ ta(vi.num - 1, i);
37        if (mint > ft)
38        {
39            mint = ft;
40            vi.chan = i;
41        }
42    }
43    return mint;
44 }
```

The first function returns the serial number of the task whose priority is biggest.  
The third function returns RTL of the task if local schedule.

```
--
90 int find_biggest_pri(vector<task>&ini)
91 {
92     unsigned int i;
93     int max=0;
94     for (i = 0; i < ini.size(); i++)
95         if (ini[i].pri > ini[max].pri)
96             max = i;
97     return max;
98 }
99
00 // find the max in two numbers
01 int max2(int &m, int &n)
02 {
03     if (m >= n)
04         return m;
05     else
06         return n;
07 }
08
09 // if local schedule, return RTL
10 int d_rtl(task &vi, vector<task>&S, Matrix<int, 2>&G)
11 {
12     unsigned int i;
13     unsigned int j;
14     int max=0;
15     if (S.size()!=0)
16     {
17         for (i = 0; i < G.dim2(); i++)
18             if (G(i, vi.num - 1) == 1)
19                 for (j = 0; j < S.size(); j++)
20                     if ((S[j].num == i + 1)&&(max < max2(S[j].FTL, S[j].FTWR)))
21                         max = max2(S[j].FTL, S[j].FTWR);
22     }
23     return max;
24 }
25
```

Here is the function which returns the finish receiving time of task in wireless channel if cloud schedule. Also compute FTWS and FTC.

```

199         mint = ft;
200         vi.chan = i;
201     }
202 }
203 return mint;
204 }
205
206 // if cloud schedule, return the finish time
207 int clouds(task &vi, vector<task>&S, Matrix<int, 2>&G, int ts, int tc, int tr)
208 {
209     vi.RTWS = d_rtws(vi, S, G);
210     unsigned int i;
211     int maxs = 0;
212     int t;
213     int maxc = 0;
214     int maxr = 0;
215     int ft;
216     t = ts + tc + tr;
217     if (S.size()==0)
218     {
219         vi.FTWS = ts;
220         vi.RTC = ts;
221         vi.FTC = ts + tc;
222         vi.RTWR = ts+tc;
223         return t;
224     }
225     for(i=0;i<S.size();i++)
226         if (S[i].chan == 3)
227             if (maxs < S[i].FTWS)
228                 maxs = S[i].FTWS;
229     if (maxs > vi.RTWS)
230         vi.FTWS = maxs + ts;

```

```

222         vi.RTWR = ts+tc;
223         return t;
224     }
225     for(i=0;i<S.size();i++)
226         if (S[i].chan == 3)
227             if (maxs < S[i].FTWS)
228                 maxs = S[i].FTWS;
229     if (maxs > vi.RTWS)
230         vi.FTWS = maxs + ts;
231     else
232         vi.FTWS = vi.RTWS + ts;
233     vi.RTC = d_rtc(vi, S, G);
234     for (i = 0; i < S.size(); i++)
235         if (S[i].chan == 3)
236             if (maxc < S[i].FTC)
237                 maxc = S[i].FTC;
238     if (maxc > vi.RTC)
239         vi.FTC = maxc + tc;
240     else
241         vi.FTC = vi.RTC + tc;
242     vi.RTWR = d_rtwr(vi);
243     for (i = 0; i < S.size(); i++)
244         if (S[i].chan == 3)
245             if (maxr < S[i].FTWR)
246                 maxr = S[i].FTWR;
247     if (maxr > vi.RTWR)
248         ft = maxr + tr;
249     else
250         ft = vi.RTWR + tr;
251     return ft;
252 }
253
254 void initials(vector<task>&S, vector<task>&ini, Matrix<int, 2>&ta, Matrix<int, 2>&tb)

```

Here I compute RTWS, RTC, RTWR of the task if cloud schedule.

```
124 }
125
126 // if cloud schedule, return RTWS
127 int d_rtws(task &vi, vector<task>&S, Matrix<int, 2>&G)
128 {
129     unsigned int i;
130     unsigned int j;
131     int max=0;
132     if (S.size()!=0)
133     {
134         for (i = 0; i < G.dim2(); i++)
135             if (G(i, vi.num - 1) == 1)
136                 for (j = 0; j < S.size(); j++)
137                     if ((S[j].num == i + 1)&&(max < max2(S[j].FTL, S[j].FTWS)))
138                         max = max2(S[j].FTL, S[j].FTWS);
139     }
140     return max;
141 }
142
143 // if cloud schedule, return RTC
144 int d_rtc(task &vi, vector<task>&S, Matrix<int, 2>&G)
145 {
146     unsigned int i;
147     unsigned int j;
148     int max=vi.FTWS;
149     if (S.size()!=0)
150     {
151         for (i = 0; i < G.dim2(); i++)
152             if (G(i, vi.num - 1) == 1)
153                 for (j = 0; j < S.size(); j++)
154                     if ((S[j].num == i + 1)&&(max < max2(vi.FTWS, S[j].FTC)))
155                         max = max2(vi.FTWS, S[j].FTC);
156     }
157     return max;
158 }
159
160 // if cloud schedule, return RTWR
161 int d_rtwr(task &vi)
162 {
163     return vi.FTC;
164 }
165
```

The first function returns the actual finish time of the task.

The second function prints the schedule of all tasks (involving the channel of task, the start and finish time of task)

```
100 }
101
102 // return a task's finish time
103 int find_ft(task&vi)
104 {
105     int max;
106     max = max2(vi.FTL, vi.FTWR);
107     return max;
108 }
109
110 // print the sequence S
111 void prints(vector<task>&S)
112 {
113     unsigned int i;
114     int k,m;
115     for (i = 0; i < S.size(); i++)
116     {
117         k = 1 + S[i].chan;
118         m = find_ft(S[i]);
119         cout << "Task" << S[i].num << ": ";
120         switch (S[i].chan)
121         {
122             case 0:
123                 cout << "local core" << k << ", ";
124                 break;
125             case 1:
126                 cout << "local core" << k << ", ";
127                 break;
128             case 2:
129                 cout << "local core" << k << ", ";
130                 break;
131             case 3:
132                 cout << "cloud" << ", ";
133                 break;
134             default:
135                 break;
136         }
137         cout << "start time is: " << S[i].ST << ", finish time is: " << m << endl;
138     }
139 }
140
141 // return the completion time of sequence S
```

The first function returns the total completion time of the schedule.  
The second function returns the total energy consumed in the schedule.

```
39 }
40
41 // return the completion time of sequence S
42 int find_tcom(vector<task>&S)
43 {
44     unsigned int i;
45     int max=0;
46     for (i = 0; i < S.size(); i++)
47         if ((S[i].exit) && (max < find_ft(S[i])))
48             max = find_ft(S[i]);
49     return max;
50 }
51
52 // return the total energy of the sequence S
53 double find_en(vector<task>&S, int p1, int p2, int p3, double ps)
54 {
55     unsigned int i;
56     double ene=0;
57     for (i = 0; i < S.size(); i++)
58     {
59         switch (S[i].chan)
60         {
61             case 0:
62                 ene = ene + p1 * (find_ft(S[i]) - S[i].ST);
63                 break;
64             case 1:
65                 ene = ene + p2 * (find_ft(S[i]) - S[i].ST);
66                 break;
67             case 2:
68                 ene = ene + p3 * (find_ft(S[i]) - S[i].ST);
69                 break;
70             case 3:
71                 ene = ene + ps * (S[i].FTWS - S[i].ST);
72                 break;
73             default:
74                 break;
75         }
76     }
77     return ene;
78 }
79
```

Here is Step Two: Task Migration.

The outer loop repeats to run the “mcc” function until the energy consumed is minimized.

```
516     }  
517 }  
518  
519 void outerloop(vector<task>&S, Matrix<int, 2>&G, Matrix<int, 2>&ta, int ts, int tc, int tr, int p1, int p2, int p3, double ps, int tmax)  
520 {  
521     double en;  
522     double en1=0;  
523     en = find_en(S, p1, p2, p3, ps);  
524     while (en1<en)  
525     {  
526         en= find_en(S, p1, p2, p3, ps);  
527         mcc(S, G, ta, ts, tc, tr, p1, p2, p3, ps, tmax);  
528         en1= find_en(S, p1, p2, p3, ps);  
529     }  
530 }  
531  
532 int main()  
533 }
```

Here is the “mcc” function which involves kernel algorithm.

```
7205project2.cpp
~/source/ns-3.31/scratch

474 void mcc(vector<task>&S, Matrix<int, 2>&G, Matrix<int, 2>&ta, int ts, int tc, int tr, int p1, int p2, int p3, double ps, int tmax)
475 {
476     unsigned int i, j;
477     int tcom;
478     int tcom2;
479     int a;
480     double en;
481     double en1;
482     double en2;
483     double ratio1=0;
484     double ratio2;
485     vector<task>SN;
486     tcom = find_tcom(S);
487     en = find_en(S, p1, p2, p3, ps);
488     for (i = 0; i < S.size(); i++)
489     {
490         a = S[i].chan;
491         if (S[i].chan != 3)
492         {
493             for (j = 0; j < 4; j++)
494             {
495                 if (j != a)
496                 {
497                     SN.erase(SN.begin(), SN.end());
498                     en1 = find_en(S, p1, p2, p3, ps);
499                     kernel(S, SN, j, S[i], G, ta, ts, tc, tr);
500                     tcom2 = find_tcom(SN);
501                     en2 = find_en(SN, p1, p2, p3, ps);
502                     if ((en2 < en1) && (tcom >= tcom2))
503                         S = SN;
504                     else if ((en2 < en1) && (tcom2 <= tmax))
505                     {
506                         ratio2 = (en - en2) / (tcom2 - tcom);
507                         if (ratio2 > ratio1)
508                         {
509                             ratio1 = ratio2;
510                             S = SN;
511                         }
512                     }
513                 }
514             }
515         }
516     }
517 }
```



Here is the function which is the implementation of kernel algorithm.

```
433
434 void kernel(vector<task>&S, vector<task>&SN, int ktar, task vtar, Matrix<int, 2>&G, Matrix<int, 2>&ta, int ts, int tc, int tr)
435 {
436     unsigned int i;
437     int m;
438     int t;
439     t = ts + tc + tr;
440     vector<task>re;
441     re = S;
442     for (i = 0; i < re.size(); i++)
443         if (vtar.num == re[i].num)
444             {
445                 re[i].chan = ktar;
446                 if (ktar == 3)
447                     {
448                         re[i].FTl = 0;
449                         re[i].RTl = 0;
450                     }
451             }
452     while (re.size() != 0)
453     {
454         get_ready1(re, G);
455         get_ready2(re);
456         m = 0;
457         while ((re[m].ready1 != 0) && (re[m].ready2 != 0))
458             m = m + 1;
459         if (re[m].chan == 3)
460             {
461                 re[m].FTWR = clouds(re[m], SN, G, ts, tc, tr);
462                 re[m].ST = re[m].FTWR - t;
463             }
464         else
465             {
466                 re[m].FTl = localse(re[m], SN, G, ta);
467                 re[m].ST = re[m].FTl - ta(re[m].num - 1, re[m].chan);
468             }
469         SN.push_back(re[m]);
470         re.erase(re.begin() + m);
471     }
472 }
473
```

The first function is to compute the value of ready1.  
The second function is to compute the value of ready2.

```
380 //compute all the ready1 in a sequence
381 void get_ready1(vector<task>&S, Matrix<int, 2>&G)
382 {
383     unsigned int i, j, k;
384     int m;
385     for (i = 0; i < S.size(); i++)
386     {
387         m = 0;
388         for (j = 0; j < G.dim2(); j++)
389             if (G(j, S[i].num-1) == 1)
390                 for (k = 0; k < S.size(); k++)
391                     if (S[k].num == j + 1)
392                         m = m + 1;
393         S[i].ready1 = m;
394     }
395 }
396
397 //compute all the ready2 in a sequence
398 void get_ready2(vector<task>&S)
399 {
400     unsigned int i, j;
401     int m;
402     for (i = 0; i < S.size(); i++)
403     {
404         m = 0;
405         for (j = 0; j < S.size(); j++)
406             if ((S[i].chan == S[j].chan) && (S[j].ST < S[i].ST))
407                 m = m + 1;
408         S[i].ready2 = m;
409     }
410 }
411
```

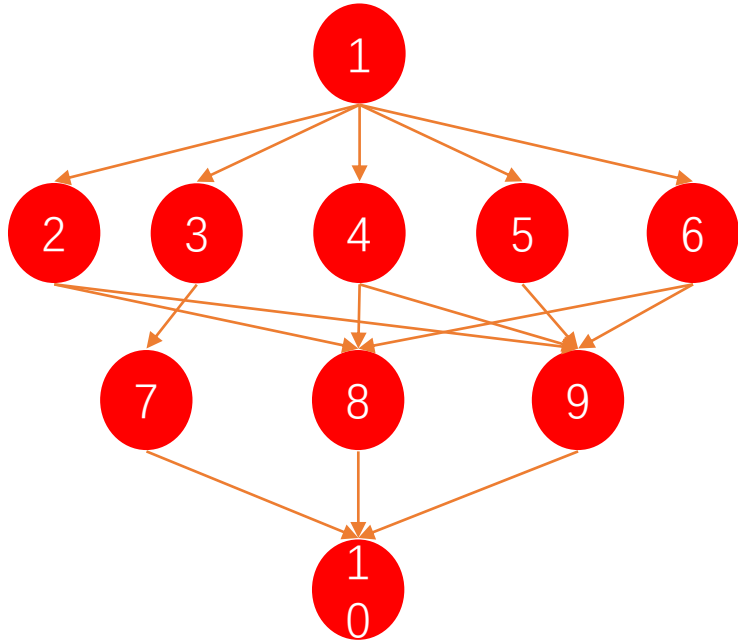
Here is where I compute the running time of the program (in the main function). I use “rt” to compute running time.

```
ta1(9, 2) = 2;
primary(ini1, ta1, t1);
prioritize(ini1, ta1, G1,t1);
start = clock();
initials(S1, ini1, ta1, G1, ts1, tc1, tr1);
end = clock();
cout << "Initial schedule:" << endl;
prints(S1);
rt = (double)(end - start) / (double)(CLOCKS_PER_SEC)*(double)(1000.000000);
cout << " Now the total energy is: " << find_en(S1, p11, p12, p13, ps1)<<endl;
cout << " Now the completion time is: " << find_tcom(S1) << endl;
cout << "The running time of initial schedule of Graph 1 is "<<rt<<" ms"<< endl;
start = clock();
outerloop(S1, G1, ta1, ts1, tc1, tr1, p11, p12, p13, ps1, tmax1);
end = clock();
cout << "After Task Migration:" << endl;
prints(S1);
rt = (double)(end - start) / (double)(CLOCKS_PER_SEC)*(double)(1000.000000);
cout << " Now the total energy is: " << find_en(S1, p11, p12, p13, ps1) << endl;
cout << " Now the completion time is: " << find_tcom(S1) << endl;
cout << "The running time of task migration of Graph 1 is "<<rt<<" ms"<< endl;
cout << endl;
int N2 = 8; // the number of tasks
```

# Part2 Input and Output

- This part I will use two examples to verify the correctness of my codes.
- The first example is the same with paper [1].
- The second example is a good example to show how the cloud can save energy for the whole schedule.

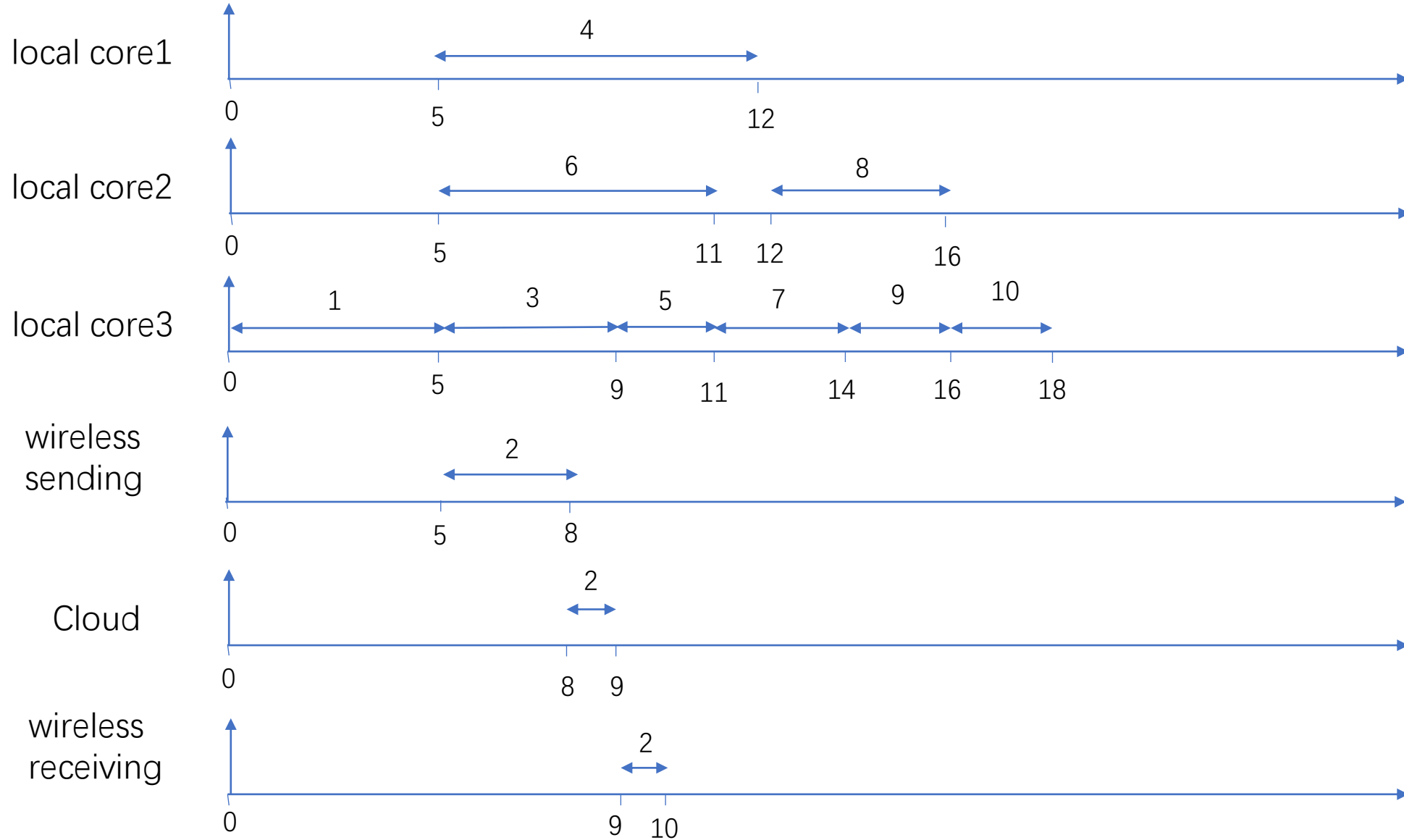
# Input of the first example



$$T_{max} = 27 \quad \begin{cases} T^S = 3; \\ T^C = 1; \\ T^R = 1; \end{cases} \quad \begin{cases} P_1 = 1; \\ P_2 = 2; \\ P_3 = 4; \\ P_s = 0.5; \end{cases}$$

Time in each core	local core1	local core2	local core3
Task 1	9	7	5
Task 2	8	6	5
Task 3	6	5	4
Task 4	7	5	3
Task 5	5	4	2
Task 6	7	6	4
Task 7	8	5	3
Task 8	6	4	2
Task 9	5	3	2
Task 10	7	4	2

# Output of the first example after initial schedule



# After initial schedule

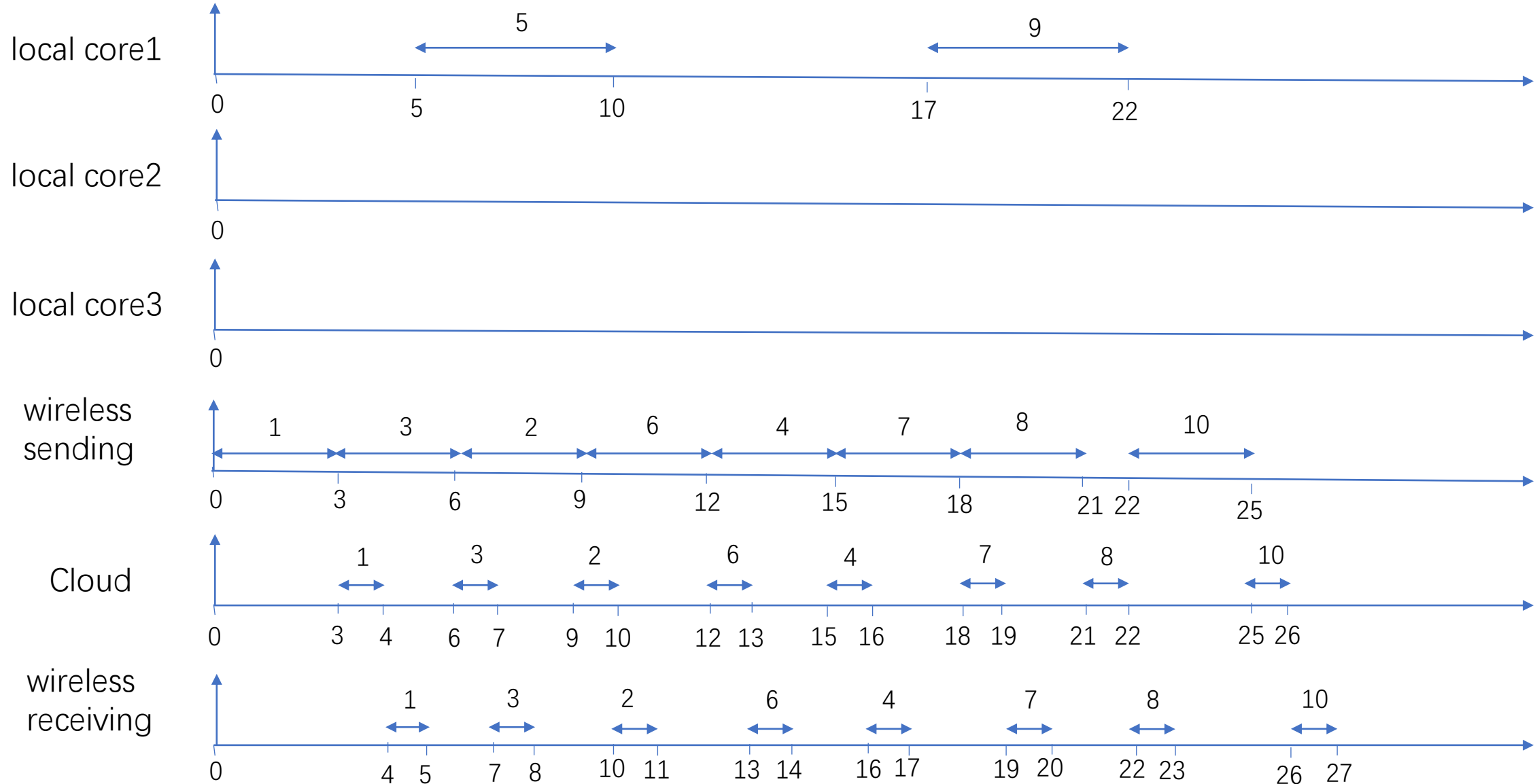
The completion time of the schedule is 18.

The total energy consumed is 100.5.

The running time of the initial schedule program is 0.019 ms.

```
eece@ubuntu:~$ cd source/ns-3.31/scratch
eece@ubuntu:~/source/ns-3.31/scratch$ ls
7205project2.cpp      Matrix.h      mythird2.cc
a.out                 mylora.cc     scratch-simulator.cc
manet-routing-compare.cc mythird1.cc   subdir
eece@ubuntu:~/source/ns-3.31/scratch$ g++ 7205project2.cpp
eece@ubuntu:~/source/ns-3.31/scratch$ ./a.out
Initial schedule:
Task1: local core3, start time is: 0,finish time is: 5
Task3: local core3, start time is: 5,finish time is: 9
Task2: cloud, start time is: 5,finish time is: 10
Task6: local core2, start time is: 5,finish time is: 11
Task4: local core1, start time is: 5,finish time is: 12
Task5: local core3, start time is: 9,finish time is: 11
Task7: local core3, start time is: 11,finish time is: 14
Task8: local core2, start time is: 12,finish time is: 16
Task9: local core3, start time is: 14,finish time is: 16
Task10: local core3, start time is: 16,finish time is: 18
Now the total energy is: 100.5
Now the completion time is: 18
The running time of initial schedule of Graph 1 is 0.019 ms
After Task Migration:
```

# Output of the first example after task migration





# After task migration

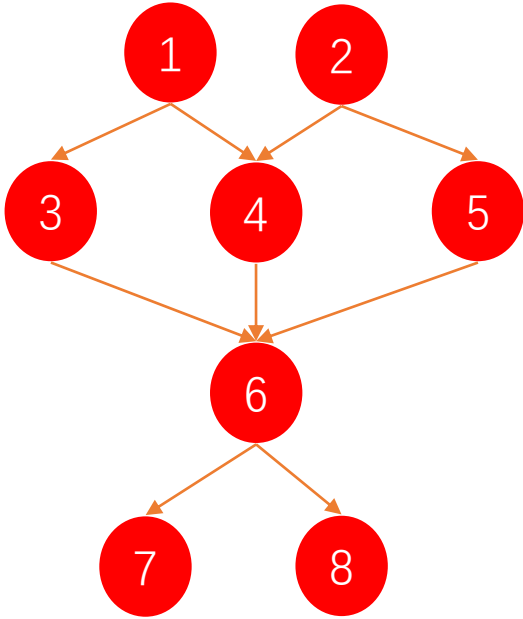
The completion time of the schedule is 27.

The total energy consumed is 22.

The running time of the initial schedule program is 1.208 ms.

```
The running time of initial schedule of Graph 1 is 0.019 ms
After Task Migration:
Task1: cloud, start time is: 0,finish time is: 5
Task3: cloud, start time is: 3,finish time is: 8
Task2: cloud, start time is: 6,finish time is: 11
Task6: cloud, start time is: 9,finish time is: 14
Task4: cloud, start time is: 12,finish time is: 17
Task5: local core1, start time is: 5,finish time is: 10
Task7: cloud, start time is: 15,finish time is: 20
Task8: cloud, start time is: 18,finish time is: 23
Task9: local core1, start time is: 17,finish time is: 22
Task10: cloud, start time is: 22,finish time is: 27
Now the total energy is: 22
Now the completion time is: 27
The running time of task migration of Graph 1 is 1.208 ms
```

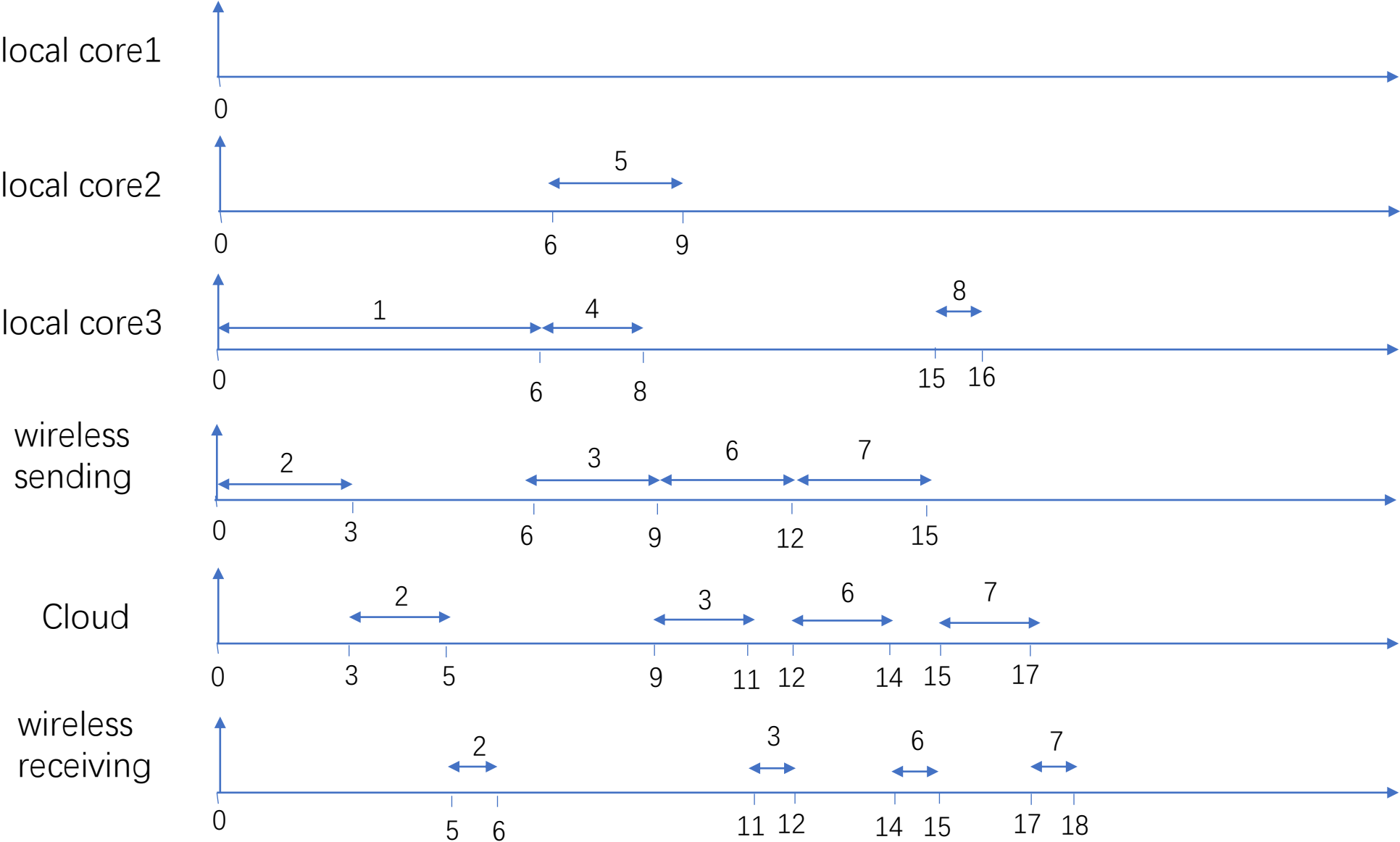
# Input of the second example



Time in each core	local core1	local core2	local core3
Task 1	9	8	6
Task 2	8	7	6
Task 3	10	9	7
Task 4	6	4	2
Task 5	5	3	1
Task 6	7	5	4
Task 7	15	11	10
Task 8	6	4	1

$$T_{max} = 27 \quad \begin{cases} T^S = 3; \\ T^C = 2; \\ T^R = 1; \end{cases} \quad \begin{cases} P_1 = 2; \\ P_2 = 3; \\ P_3 = 5; \\ P_s = 1.5; \end{cases}$$

# Output of the second example after initial schedule



# After initial schedule

The completion time of the schedule is 18.

The total energy consumed is 72.

The running time of the initial schedule program is 0.011 ms.

```
The running time of task migration of Graph 1 is 1.208 ms
```

```
Initial schedule:
```

```
Task1: local core3, start time is: 0,finish time is: 6
```

```
Task2: cloud, start time is: 0,finish time is: 6
```

```
Task3: cloud, start time is: 6,finish time is: 12
```

```
Task4: local core3, start time is: 6,finish time is: 8
```

```
Task5: local core2, start time is: 6,finish time is: 9
```

```
Task6: cloud, start time is: 9,finish time is: 15
```

```
Task7: cloud, start time is: 12,finish time is: 18
```

```
Task8: local core3, start time is: 15,finish time is: 16
```

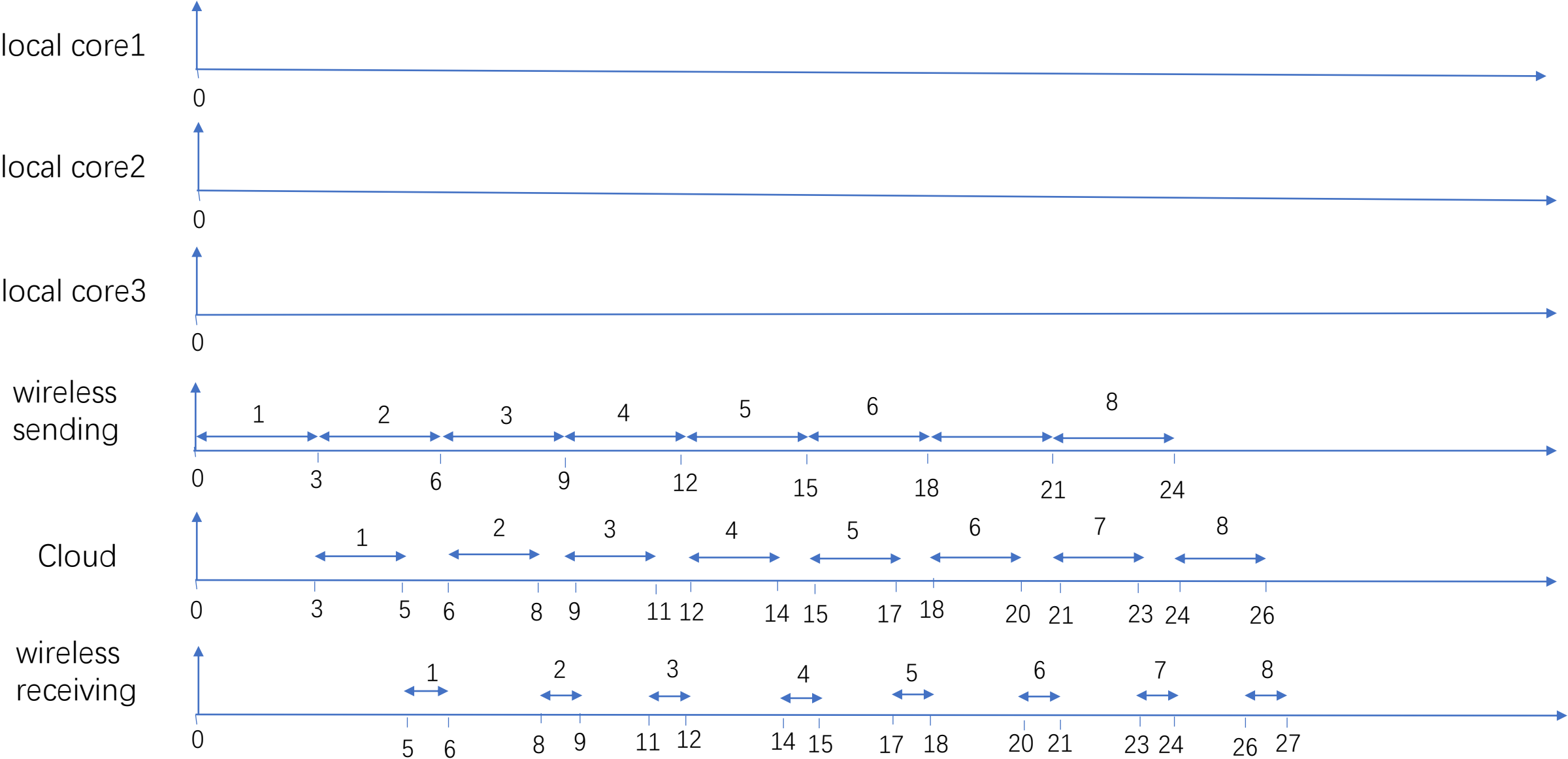
```
Now the total energy is: 72
```

```
Now the completion time is: 18
```

```
The running time of initial schedule of Graph 2 is 0.011 ms
```

```
After all of Task Migration:
```

# Output of the second example after task migration



# After task migration

The completion time of the schedule is 27.

The total energy consumed is 36.

The running time of the initial schedule program is 0.425 ms.

```
Now the completion time is: 18
The running time of initial schedule of Graph 2 is 0.011 ms
After all of Task Migration:
Task1: cloud, start time is: 0,finish time is: 6
Task2: cloud, start time is: 3,finish time is: 9
Task3: cloud, start time is: 6,finish time is: 12
Task4: cloud, start time is: 9,finish time is: 15
Task5: cloud, start time is: 12,finish time is: 18
Task6: cloud, start time is: 15,finish time is: 21
Task7: cloud, start time is: 18,finish time is: 24
Task8: cloud, start time is: 21,finish time is: 27
Now the total energy is: 36
Now the completion time is: 27
The running time of initial schedule of Graph 2 is 0.425 ms
```

# Part3 Conclusion

- Achieve the goal which is to minimize the consumption of the mobile device.
- Apply one example in paper [1].
- The result of another example is absolutely correct.
- The result of the first example is little different from paper [1]

# References

[1] X. Lin, Y. Wang, Q. Xie and M. Pedram, "Energy and Performance-Aware Task Scheduling in a Mobile Cloud Computing Environment," *2014 IEEE 7th International Conference on Cloud Computing*, Anchorage, AK, 2014, pp. 192-199, doi: 10.1109/CLOUD.2014.35.