```
64
          for pos i in range(len(state.lattice)):
 65
              for pos j in range(len(state.lattice)):
 66
                  interaction energy +=
                  -state.J*state.lattice[pos_i,pos_j]*(state.lattice[pos_i,(pos_j+1)%state.N]
                  + state.lattice[(pos i-1)%state.N,pos j] +
                  state.lattice[(pos i+1)%state.N,pos j] +
                  state.lattice[pos i, (pos j-1)%state.N])
 67
          interaction_energy *= 0.5 # avoid double counting
 68
 69
          magnetisation energy = -state.H*calculate magnetisation(state)
 70
 71
          return interaction energy+magnetisation energy
 72
 73
 74
      # In[]:
 75
 76
 77
      # Function to normalize data by number of lattice sites
 78
      def normalize data(data, N):
 79
          return data/(N**2)
 80
 81
 82
      # In[]:
 83
 84
 85
      # Metropolis algorithm
 86
      def Metropolis_algorithm(N_range, J, H, T_range, no_of_sweeps):
 87
          # arrays to store magnetisation and energy time series
 88
          M = np.zeros((len(N range),len(T range),no of sweeps))
 89
          E = np.zeros((len(N_range),len(T_range),no_of_sweeps))
 90
          M_normalized = np.zeros((len(N_range),len(T_range),no_of_sweeps))
 91
          E normalized = np.zeros((len(N range),len(T range),no of sweeps))
 92
          run time = np.zeros((len(N range),len(T range)))
 93
 94
          # Monte Carlo sweeps
 95
          for N index in range(len(N range)):
 96
              for T index in range(len(T range)):
 97
                  state = Ising(N range[N index], J, H)
 98
 99
                  t0 = time.time()
100
                  for sweep in range(no of sweeps): # run!
101
                      monte carlo sweep(state,T range[T index])
102
103
                      M[N index, T index, sweep] = calculate magnetisation (state)
104
                      E[N index,T index,sweep] = calculate energy(state)
105
                      M normalized[N index,T index,sweep] =
                      normalize data(M[N index,T index,sweep],state.N)
106
                      E_normalized[N_index,T_index,sweep] =
                      normalize_data(E[N_index,T_index,sweep],state.N)
107
108
                       if sweep%1000 == 0: # output checkpoints
                          print('N = \{0\}, T = \{1\}, sweep =
109
                           {2}'.format(N range[N index],T range[T index],sweep))
110
                  t1 = time.time()
111
                  run time[N index,T index] = t1-t0
112
113
          return M, E, M normalized, E normalized, run time
114
115
116
      # In[]:
117
118
119
      # Function to plot evolution of data over time
120
      def plot time series (data, N range, N index range, T range, T index range, start point,
      stop point, xname, yname):
121
          for N index in N index range:
122
              for T index in T index range:
```