

Desert ant adaptive navigation Milestones:

1. Implement the matlab-project of gordon team and understand the code
2. Fix the pathintegration of grodon's team
3. Extend classes (as prototypes) .
 - sucessfunction
 - adaptfunction
 - memory array
4. Implement the above classes
5. Calibrate the simulation
6. Simulation an compare with data

If time try conditions with “exotic” parameters

Contact R. Wehner for additional data