



Final Project

CSE 327

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Introduction



+

SNN



Introduction



Introduction



→ **"Tokyo"**



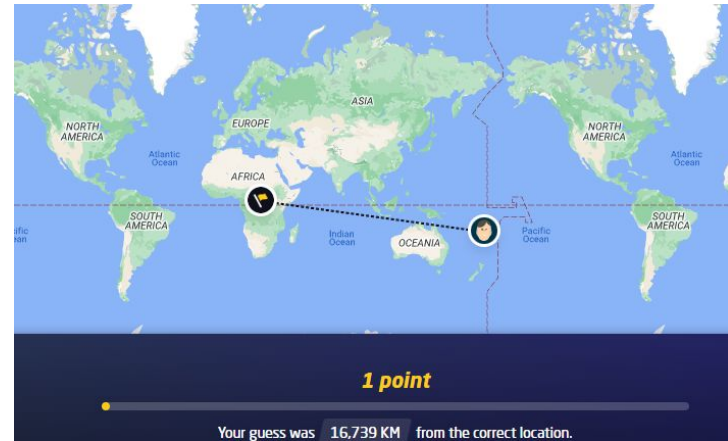
Motivation



**"Guess where you are based
on your surroundings"**



Motivation



Dataset

Five locations

- Seoul, Tokyo, NYC, London, Paris
- Big, populous cities.
- Well-documented coverage.



Dataset

Size/Quantity

- 50,000 images
- 32 x 32
- 3 color channels (RGB)

Preprocessing

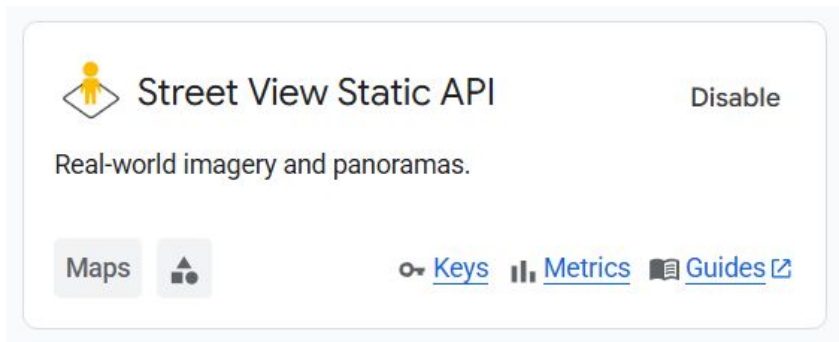
- 128 x 128 → 32 x 32
- Removes huge watermarks



Dataset

Preparation

- Google Maps API
- Google streetview scraper



Dataset

```
response = requests.get(signed_url)

if response.status_code == 200:
    filename = os.path.join(OUTPUT_FOLDER, f"streetview_{index}.jpg")

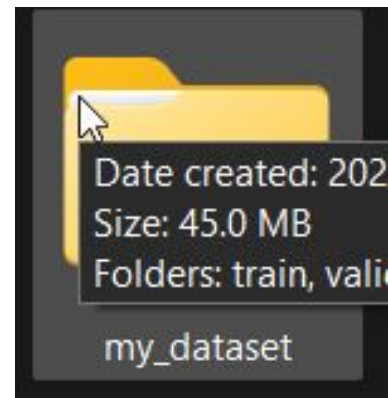
    # Save original image
    with open(filename, "wb") as file:
        file.write(response.content)

    # Open and resize the image to 32x32
    try:
        with Image.open(filename) as img:
            resized_img = img.resize((FINAL_SIZE, FINAL_SIZE), Image.Resampling.LANCZOS)
            resized_img.save(filename)
```

1-2 hours, 2 Google accounts

Dataset

- ❑ **my_dataset**
 - ❑ **train**
 - ❑ class0
 - ❑ images 0-7999
 - ❑ class1
 - ❑ images 0-7999
 - ❑ ...
 - ❑ **validation**
 - ❑ class0
 - ❑ images 8000-9999
 - ❑ class1
 - ❑ images 8000-9999
 - ❑ ...



Model Architecture

Spikformer (2023)

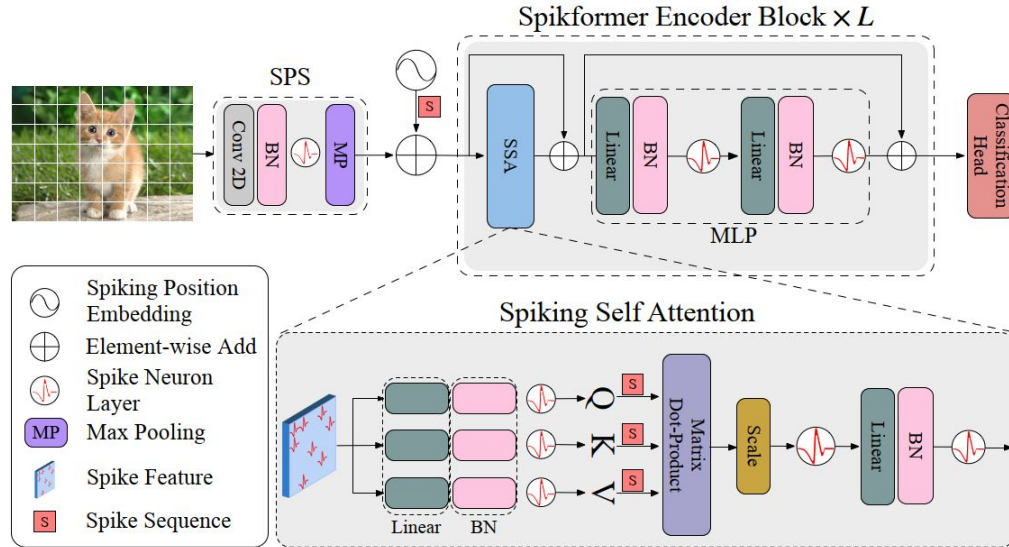
→ Spiking neural network + Transformer

Foundation for various SNN transformer models in the future.

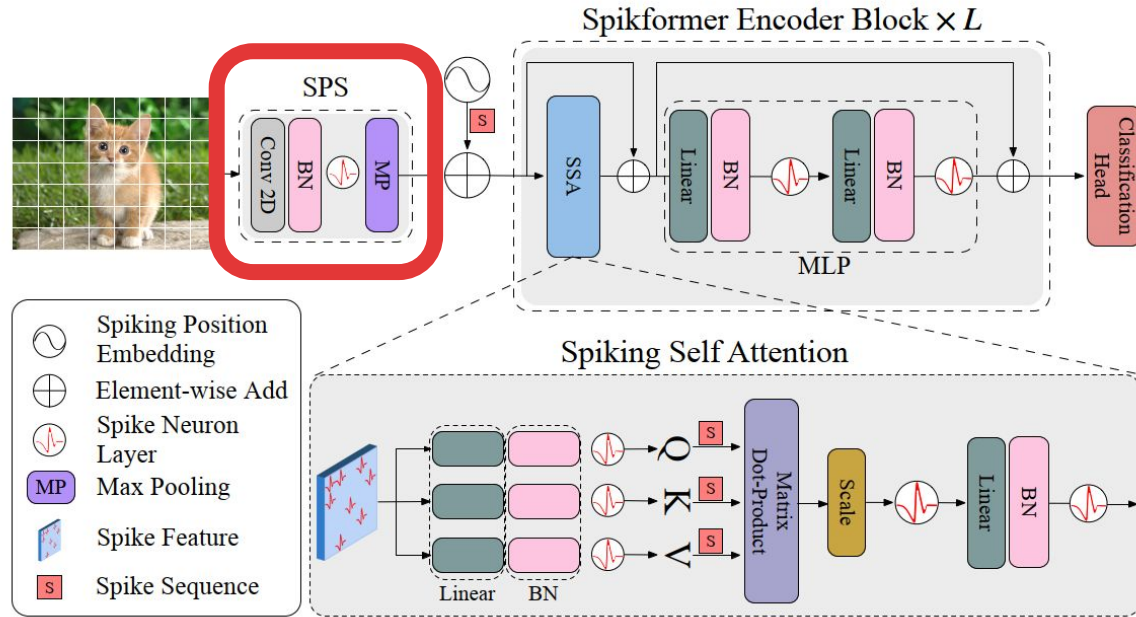


Model Architecture

Spikformer: When Spiking Neural Network Meets Transformer

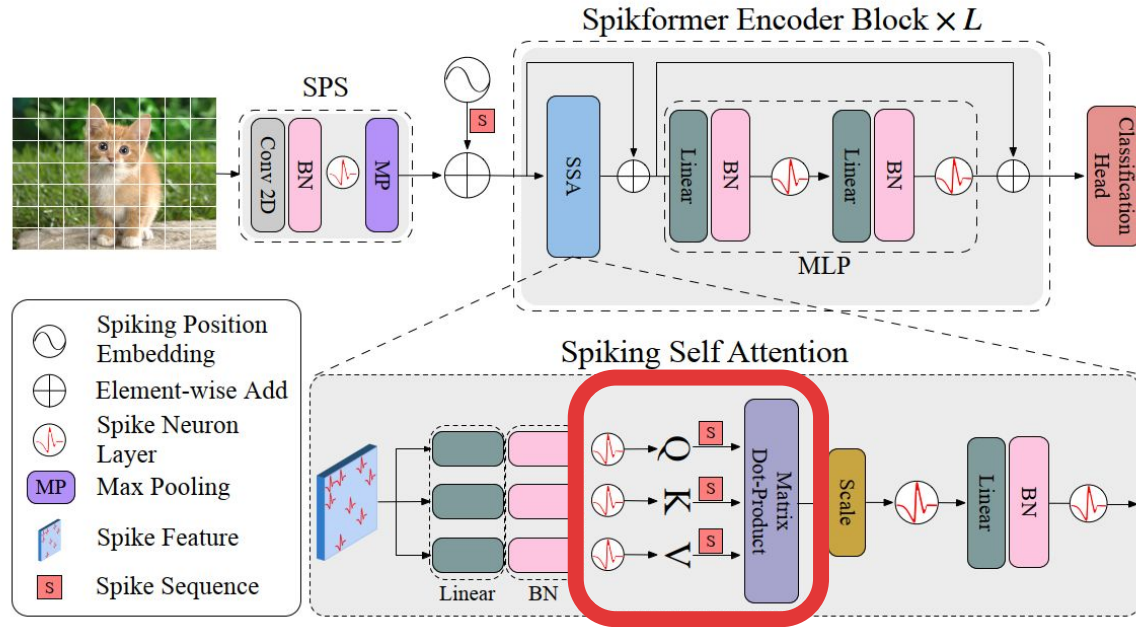


Model Architecture



SPS: Splits input into N flattened spike patches

Model Architecture

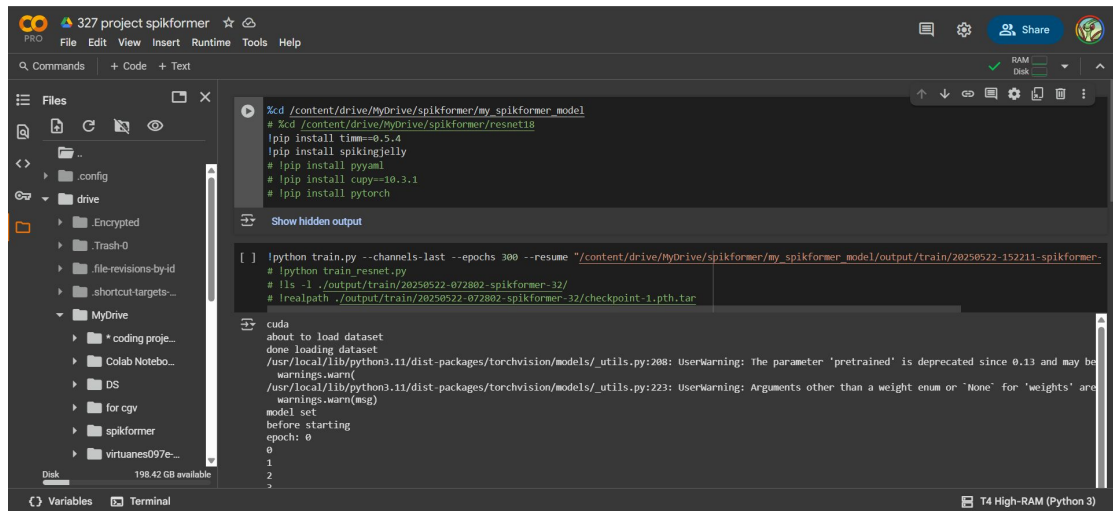


SSA: Perform dot product on sparse spike matrices (no floating points)

Training Environment

Google Colab + Google Drive

T4 GPU - around 4 hours of free use



The screenshot displays the Google Colab environment. On the left, a file explorer shows the 'MyDrive' folder containing a 'spikformer' directory. The main area shows a code cell with the following commands:

```
%cd /content/drive/MyDrive/spikformer/my_spikformer_model
# %cd /content/drive/MyDrive/spikformer/resnet18
!pip install timm==0.5.4
!pip install spikingjelly
# !pip install pyyaml
# !pip install cupy==10.3.1
# !pip install torch
```

Below the code cell, the output shows the execution of a training script:

```
[ ] !python train.py --channels-last --epochs 300 --resume "/content/drive/MyDrive/spikformer/my_spikformer_model/output/train/20250522-152211-spikformer-..."
!python train_resnet.py
!ls -l ./output/train/20250522-072802-spikformer-32/
!realpath ./output/train/20250522-072802-spikformer-32/checkpoint-1.pth.tar
```

The bottom status bar indicates 'T4 High-RAM (Python 3)' and '198.42 GB available'.

Training Environment

Hyperparameters

- epochs: 300
- time_step: 4
- patch_size: 4
- batch_size: 64
- lr: $5e-4$
- opt: adamw



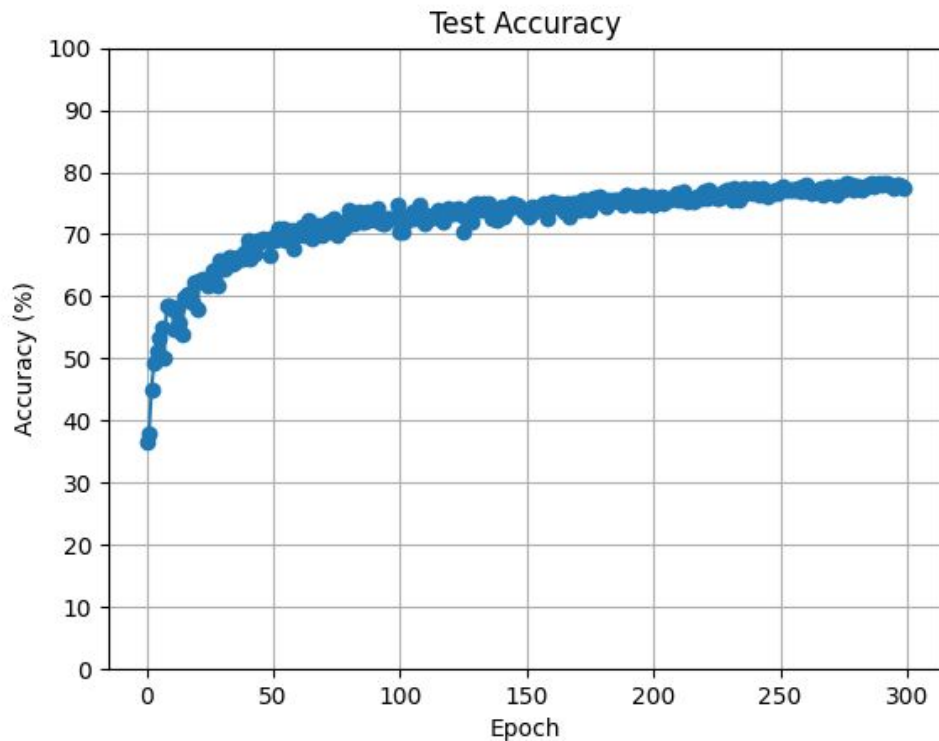
Training Procedure

Run train.py on Colab

Resume training with checkpoints

 checkpoint-296.pth.tar checkpoint-305.pth.tar checkpoint-307.pth.tar last.pth.tar model_best.pth.tar

Results



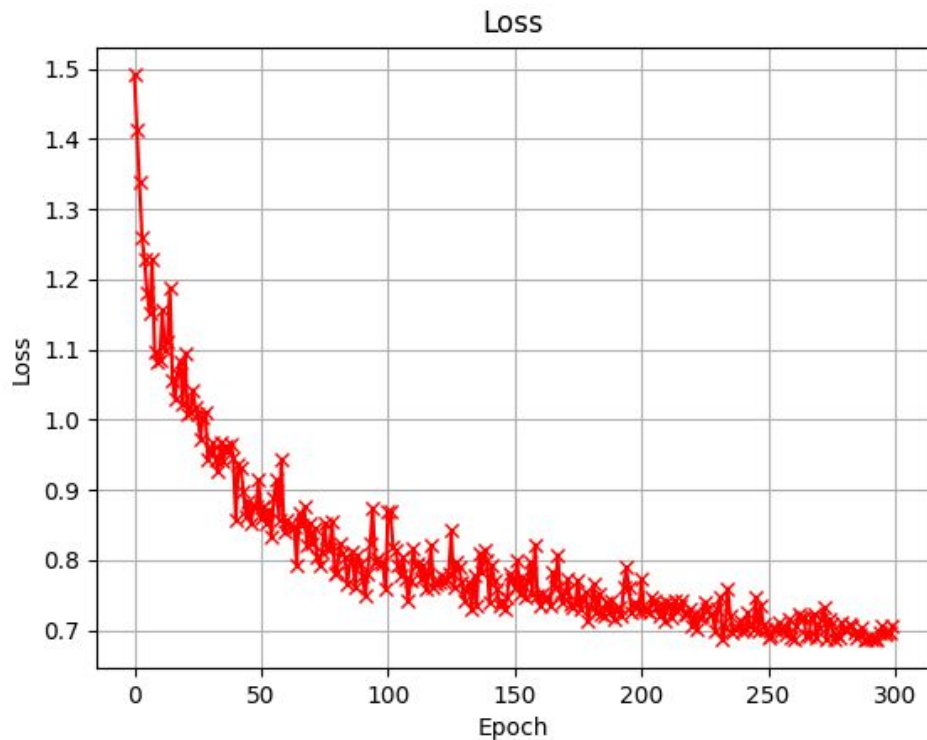
Highest accuracy:

- 78.24%

Total time:

- 15h 39m

Results



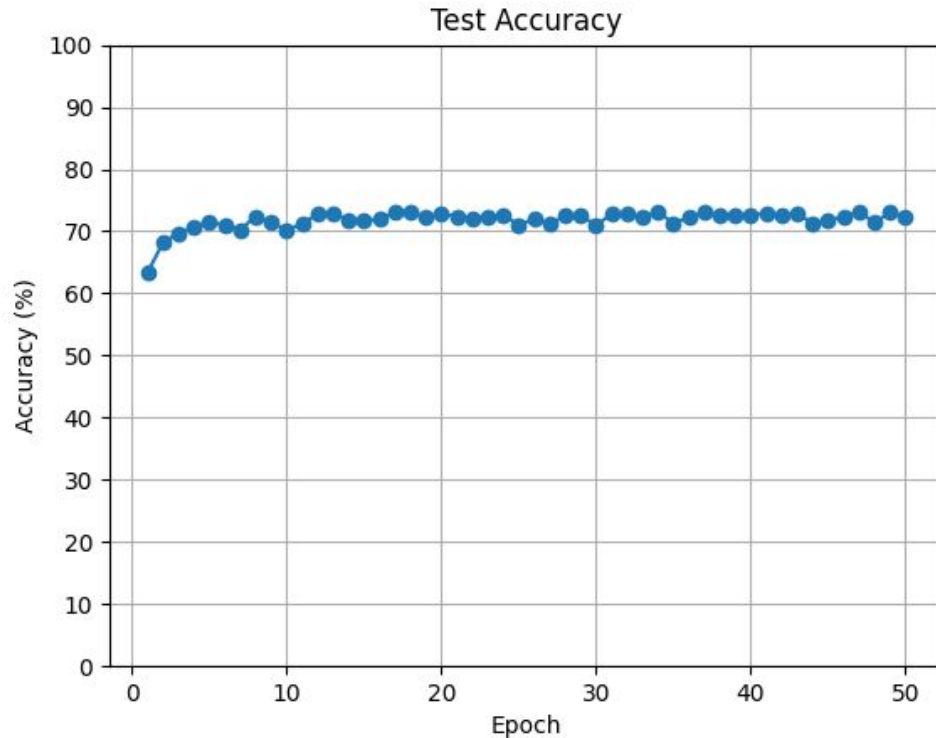
Highest accuracy:

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Model Comparison - ResNet18

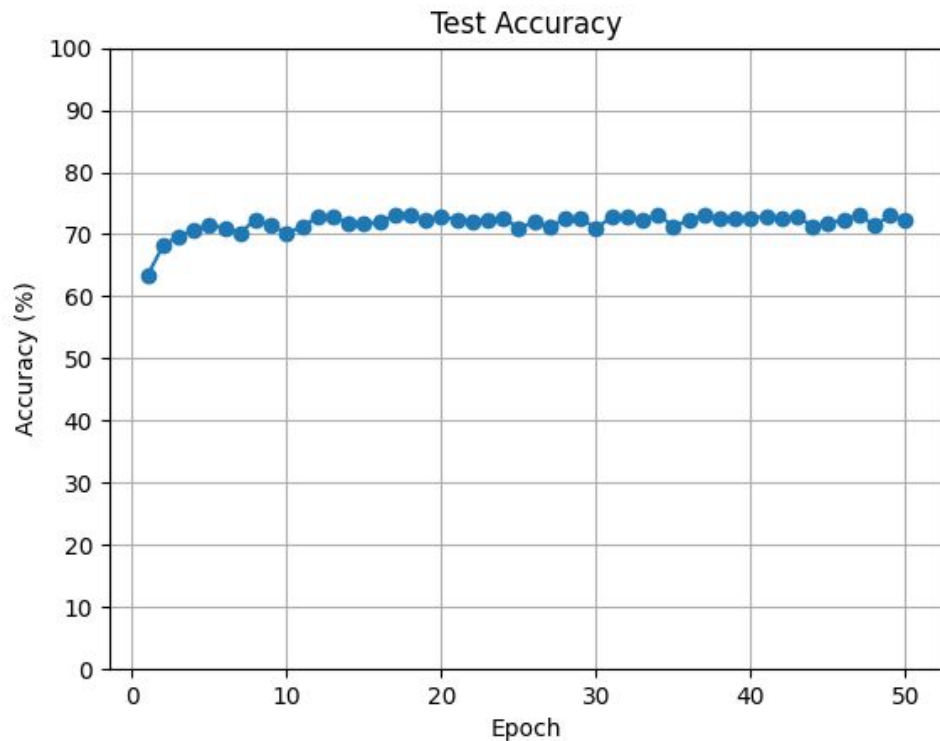


Highest accuracy:

- 73.16%
- ~4% lower

Performance
stabilized very
quickly

Model Comparison - ResNet18



Time per epoch

- **ResNet18:**
364.18s
- **Spikformer:**
187.92s

Me vs Spikformer



Me vs Spikformer



My guess:

London

Spikformer:

London

Me vs Spikformer



My guess:

London

Spikformer:

London

Answer:

London

Me vs Spikformer



Me vs Spikformer



My guess:
Spikformer:

Seoul
Tokyo

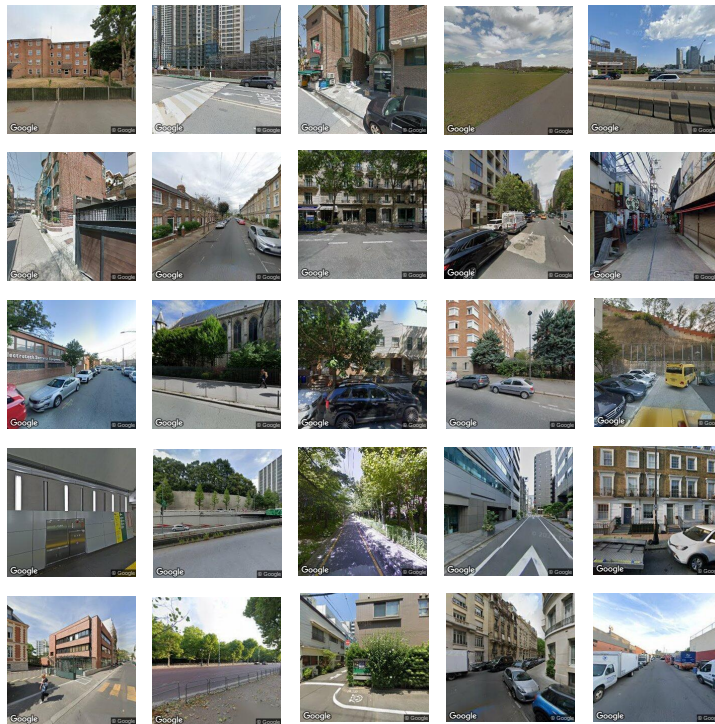
Me vs Spikformer



My guess: Seoul
Spikformer: Tokyo

Answer: Seoul

Me vs Spikformer



Me: 14/25

Spikformer: 19/25

Challenges

- Training environment had more issues than expected
- Could not monitor energy output

Conclusion

- Results exceeded my expectations
- Gained insights into various aspects of training a vision model
- Felt motivated & enjoyed the process



References

Deng, B., et al. (2022). Spikformer: When Spiking Neural Network Meets Vision Transformer. arXiv: 2209.15425. <https://arxiv.org/abs/2209.15425>

Yao, M., Hu, J., Zhou, Z., Yuan, L., Tian, Y., Xu, B., & Li, G. (2023). Spike-driven Transformer. arXiv:2307.01694. <https://arxiv.org/abs/2307.01694>

Haas, L., Skreta, M., Alberti, S., & Finn, C. (2024). PIGEON: Predicting Image Geolocations. arXiv:2307.05845. <https://arxiv.org/abs/2307.05845>

GeoGuessr. (n.d.). GeoGuessr - Let's explore the world!. Retrieved from <https://www.geoguessr.com>

Thank You!

Any questions?