

# GAL20V8

High Performance E<sup>2</sup>CMOS PLD Generic Array Logic™

### **Features**

- HIGH PERFORMANCE E<sup>2</sup>CMOS<sup>®</sup> TECHNOLOGY
- 5 ns Maximum Propagation Delay
- Fmax = 166 MHz
- 4 ns Maximum from Clock Input to Data Output
- UltraMOS<sup>®</sup> Advanced CMOS Technology
- 50% to 75% REDUCTION IN POWER FROM BIPOLAR
  - 75mA Typ Icc on Low Power Device
- 45mA Typ Icc on Quarter Power Device
- ACTIVE PULL-UPS ON ALL PINS
- E<sup>2</sup> CELL TECHNOLOGY
  - Reconfigurable Logic
- Reprogrammable Cells
- 100% Tested/100% Yields
- High Speed Electrical Erasure (<100ms)
- 20 Year Data Retention
- EIGHT OUTPUT LOGIC MACROCELLS
  - Maximum Flexibility for Complex Logic Designs
  - Programmable Output Polarity
  - Also Emulates 24-pin PAL® Devices with Full Function/ Fuse Map/Parametric Compatibility
- PRELOAD AND POWER-ON RESET OF ALL REGISTERS
  - 100% Functional Testability
- APPLICATIONS INCLUDE:
  - DMA Control
  - State Machine Control
  - High Speed Graphics Processing
  - Standard Logic Speed Upgrade
- ELECTRONIC SIGNATURE FOR IDENTIFICATION
- LEAD-FREE PACKAGE OPTIONS

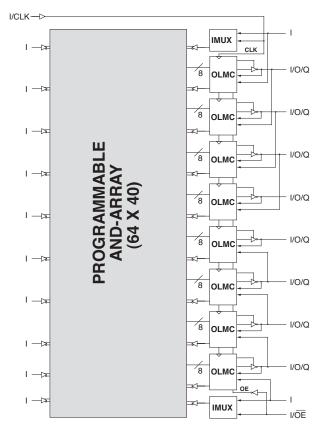
### Description

The GAL20V8C, at 5ns maximum propagation delay time, combines a high performance CMOS process with Electrically Erasable (E²) floating gate technology to provide the highest speed performance available in the PLD market. High speed erase times (<100ms) allow the devices to be reprogrammed quickly and efficiently.

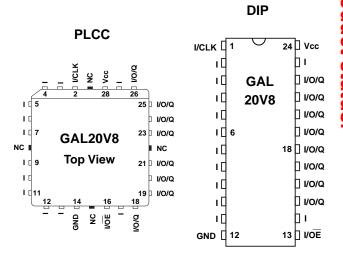
The generic architecture provides maximum design flexibility by allowing the Output Logic Macrocell (OLMC) to be configured by the user. An important subset of the many architecture configurations possible with the GAL20V8 are the PAL architectures listed in the table of the macrocell description section. GAL20V8 devices are capable of emulating any of these PAL architectures with full function/fuse map/parametric compatibility.

Unique test circuitry and reprogrammable cells allow complete AC, DC, and functional testing during manufacture. As a result, Lattice Semiconductor delivers 100% field programmability and functionality of all GAL products. In addition, 100 erase/write cycles and data retention in excess of 20 years are specified.

### Functional Block Diagram



### **Pin Configuration**



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Select devices have been discontinued.

See Ordering Information section for product sta



## **GAL20V8 Ordering Information**

# Conventional Packaging Commercial Grade Specifications

Tpd (ns)	Tsu (ns)	Tco (ns)	Icc (mA)	Ordering #	Package
5	3	4	115	GAL20V8C-5LJ <sup>1</sup>	28-Lead PLCC
7.5	7	5	115	GAL20V8C-7LJ	28-Lead PLCC
			115	GAL20V8B-7LP <sup>1</sup>	24-Pin Plastic DIP
10	10	7	115	GAL20V8C-10LJ	28-Lead PLCC
			115	GAL20V8B-10LP	24-Pin Plastic DIP
15	12	10	55	GAL20V8B-15QP	24-Pin Plastic DIP
			55	GAL20V8B-15QJ	28-Lead PLCC
			90	GAL20V8B-15LP	24-Pin Plastic DIP
			90	GAL20V8B-15LJ	28-Lead PLCC
25	15	12	55	GAL20V8B-25QP	24-Pin Plastic DIP
			55	GAL20V8B-25QJ	28-Lead PLCC
			90	GAL20V8B-25LP	24-Pin Plastic DIP
			90	GAL20V8B-25LJ	28-Lead PLCC

### **Industrial Grade Specifications**

Tpd (ns)	Tsu (ns)	Tco (ns)	Icc (mA)	Ordering #	Package
10	10	7	130	GAL20V8C-10LJI	28-Lead PLCC
			130	GAL20V8B-10LPI <sup>1</sup>	24-Pin Plastic DIP
			130	GAL20V8B-10LJI	28-Lead PLCC
15	12	10	130	GAL20V8B-15LPI	24-Pin Plastic DIP
			130	GAL20V8B-15LJI	28-Lead PLCC
20	13	11	65	GAL20V8B-20QPI	24-Pin Plastic DIP
			65	GAL20V8B-20QJI	28-Lead PLCC
25	15	12	65	GAL20V8B-25QPI	24-Pin Plastic DIP
			65	GAL20V8B-25QJI	28-Lead PLCC
			130	GAL20V8B-25LPI	24-Pin Plastic DIP
			130	GAL20V8B-25LJI	28-Lead PLCC

<sup>1.</sup> Discontinued per PCN #06-07. Contact Rochester Electronics for available inventory.



### Lead-Free Packaging Commercial Grade Specifications

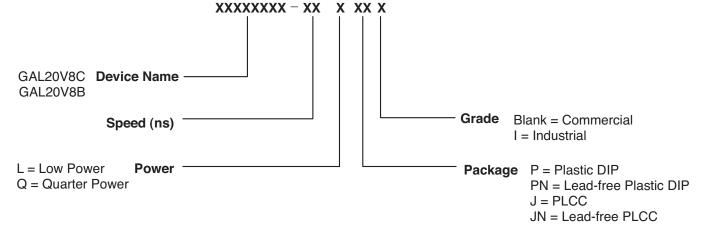
Tpd (ns)	Tsu (ns)	Tco (ns)	Icc (mA)	Ordering #	Package
5	3	4	115	GAL20V8C-5LJN <sup>1</sup>	Lead-Free 28-Lead PLCC
7.5	7	5	115	GAL20V8C-7LJN	Lead-Free 28-Lead PLCC
			115	GAL20V8B-7LPN <sup>1</sup>	Lead-Free 24-Pin Plastic DIP
10	10	7	115	GAL20V8C-10LJN	Lead-Free 28-Lead PLCC
			115	GAL20V8B-10LPN	Lead-Free 24-Pin Plastic DIP
15	12	10	55	GAL20V8B-15QJN	Lead-Free 28-Lead PLCC
			55	GAL20V8B-15QPN	Lead-Free 24-Pin Plastic DIP
			90	GAL20V8B-15LJN	Lead-Free 28-Lead PLCC
			90	GAL20V8B-15LPN	Lead-Free 24-Pin Plastic DIP
25	15	12	55	GAL20V8B-25QJN	Lead-Free 28-Lead PLCC
			55	GAL20V8B-25QPN	Lead-Free 24-Pin Plastic DIP
			90	GAL20V8B-25LJN	Lead-Free 28-Lead PLCC
			90	GAL20V8B-25LPN	Lead-Free 24-Pin Plastic DIP

### **Industrial Grade Specifications**

Tpd (ns)	Tsu (ns)	Tco (ns)	Icc (mA)	Ordering #	Package
10	10	7	130	GAL20V8C-10LJNI	Lead-Free 28-Pin Plastic DIP
			130	GAL20V8B-10LPNI <sup>1</sup>	Lead-Free 24-Pin Plastic DIP
15	12	10	130	GAL20V8B-15LJNI	Lead-Free 28-Lead PLCC
			130	GAL20V8B-15LPNI	Lead-Free 24-Pin Plastic DIP
20	13	11	65	GAL20V8B-20QJNI	Lead-Free 28-Lead PLCC
			65	GAL20V8B-20QPNI	Lead-Free 24-Pin Plastic DIP
25	15	12	65	GAL20V8B-25QJNI	Lead-Free 28-Lead PLCC
			65	GAL20V8B-25QPNI	Lead-Free 24-Pin Plastic DIP
			130	GAL20V8B-25LJNI	Lead-Free 28-Lead PLCC
			130	GAL20V8B-25LPNI	Lead-Free 24-Pin Plastic DIP

<sup>1.</sup> Discontinued per PCN #06-07. Contact Rochester Electronics for available inventory.

### **Part Number Description**





### **Output Logic Macrocell (OLMC)**

The following discussion pertains to configuring the output logic macrocell. It should be noted that actual implementation is accomplished by development software/hardware and is completely transparent to the user.

There are three global OLMC configuration modes possible: simple, complex, and registered. Details of each of these modes is illustrated in the following pages. Two global bits, SYN and ACO, control the mode configuration for all macrocells. The XOR bit of each macrocell controls the polarity of the output in any of the three modes, while the AC1 bit of each of the macrocells controls the input/output configuration. These two global and 16 individual architecture bits define all possible configurations in a GAL20V8. The information given on these architecture bits is only to give a better understanding of the device. Compiler software will transparently set these architecture bits from the pin definitions, so the user should not need to directly manipulate these architecture bits.

The following is a list of the PAL architectures that the GAL20V8 can emulate. It also shows the OLMC mode under which the devices emulate the PAL architecture.

PAL Architectures Emulated by GAL20V8	GAL20V8 Global OLMC Mode
20R8 20R6	Registered Registered
20R4 20RP8 20RP6	Registered Registered Registered
20RP4 20L8	Registered  Complex
20H8 20P8	Complex Complex
14L8 16L6	Simple Simple
18L4 20L2	Simple Simple
14H8 16H6 18H4	Simple Simple Simple
20H2 14P8 16P6	Simple Simple Simple
18P4 20P2	Simple Simple Simple

### **Compiler Support for OLMC**

Software compilers support the three different global OLMC modes as different device types. These device types are listed in the table below. Most compilers have the ability to automatically select the device type, generally based on the register usage and output enable (OE) usage. Register usage on the device forces the software to choose the registered mode. All combinatorial outputs with OE controlled by the product term will force the software to choose the complex mode. The software will choose the simple mode only when all outputs are dedicated combinatorial without OE control. The different device types listed in the table can be used to override the automatic device selection by the software. For further details, refer to the compiler software manuals.

When using compiler software to configure the device, the user must pay special attention to the following restrictions in each mode. In **registered mode** pin 1 and pin 13 (DIP pinout) are permanently

configured as clock and output enable, respectively. These pins cannot be configured as dedicated inputs in the registered mode.

In **complex mode** pin 1 and pin 13 become dedicated inputs and use the feedback paths of pin 22 and pin 15 respectively. Because of this feedback path usage, pin 22 and pin 15 do not have the feedback option in this mode.

In **simple mode** all feedback paths of the output pins are routed via the adjacent pins. In doing so, the two inner most pins (pins 18 and 19) will not have the feedback option as these pins are always configured as dedicated combinatorial output.

	Registered	Complex	Simple	Auto Mode Select
ABEL	P20V8R	P20V8C	P20V8AS	P20V8
CUPL	G20V8MS	G20V8MA	G20V8MA G20V8AS G20V8	
LOG/iC	GAL20V8_R	GAL20V8_C7	GAL20V8_C8	GAL20V8
OrCAD-PLD	"Registered" <sup>1</sup>	"Complex"1	"Simple"1	GAL20V8A
PLDesigner	P20V8R <sup>2</sup>	P20V8C <sup>2</sup>	P20V8C <sup>2</sup>	P20V8A
TANGO-PLD	G20V8R	G20V8C	G20V8AS <sup>3</sup>	G20V8

- 1) Used with Configuration keyword.
- 2) Prior to Version 2.0 support.
- 3) Supported on Version 1.20 or later.



### **Registered Mode**

In the Registered mode, macrocells are configured as dedicated registered outputs or as I/O functions.

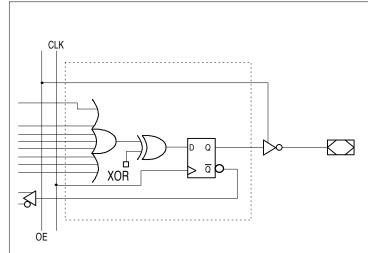
Architecture configurations available in this mode are similar to the common 20R8 and 20RP4 devices with various permutations of polarity, I/O and register placement.

All registered macrocells share common clock and output enable control pins. Any macrocell can be configured as registered or I/O. Up to eight registers or up to eight I/Os are possible in this mode.

Dedicated input or output functions can be implemented as subsets of the I/O function.

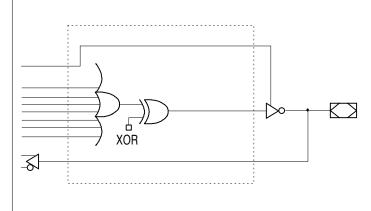
Registered outputs have eight product terms per output. I/Os have seven product terms per output.

The JEDEC fuse numbers, including the User Electronic Signature (UES) fuses and the Product Term Disable (PTD) fuses, are shown on the logic diagram on the following page.



### **Registered Configuration for Registered Mode**

- SYN=0.
- AC0=1.
- XOR=0 defines Active Low Output.
- XOR=1 defines Active High Output.
- AC1=0 defines this output configuration.
- Pin 1 controls common CLK for the registered outputs.
- Pin 13 controls common  $\overline{OE}$  for the registered outputs.
- Pin 1 & Pin 13 are permanently configured as CLK & OE for registered output configuration.



### **Combinatorial Configuration for Registered Mode**

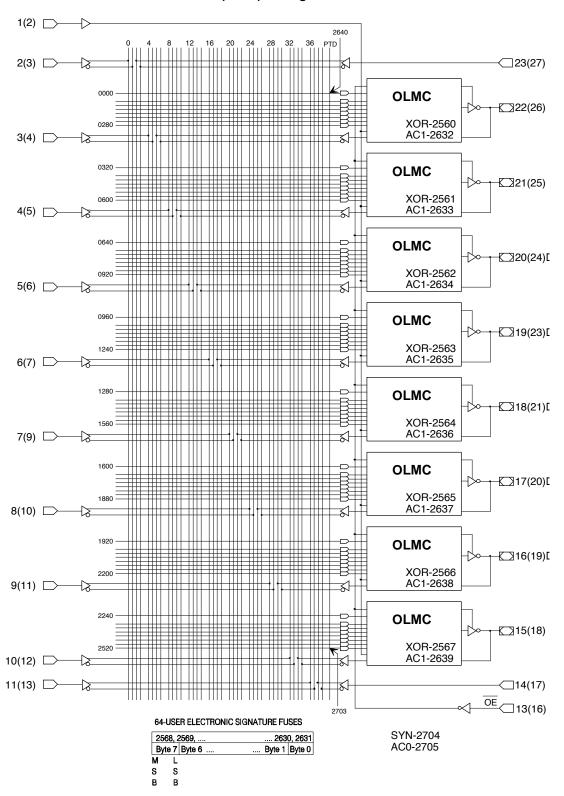
- SYN=0.
- AC0=1.
- XOR=0 defines Active Low Output.
- XOR=1 defines Active High Output.
- AC1=1 defines this output configuration.
- Pin 1 & Pin 13 are permanently configured as CLK & OE for registered output configuration..

Note: The development software configures all of the architecture control bits and checks for proper pin usage automatically.



### Registered Mode Logic Diagram

### **DIP (PLCC) Package Pinouts**





### **Complex Mode**

In the Complex mode, macrocells are configured as output only or I/O functions.

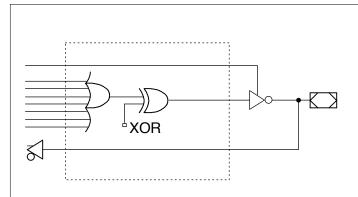
Architecture configurations available in this mode are similar to the common 20L8 and 20P8 devices with programmable polarity in each macrocell.

Up to six I/Os are possible in this mode. Dedicated inputs or outputs can be implemented as subsets of the I/O function. The two outer most macrocells (pins 15 & 22) do not have input capability. De-

signs requiring eight I/Os can be implemented in the Registered mode.

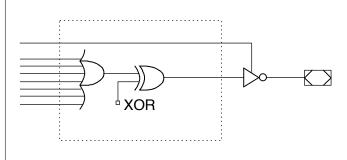
All macrocells have seven product terms per output. One product term is used for programmable output enable control. Pins 1 and 13 are always available as data inputs into the AND array.

The JEDEC fuse numbers including the UES fuses and PTD fuses are shown on the logic diagram on the following page.



### **Combinatorial I/O Configuration for Complex Mode**

- SYN=1.
- AC0=1.
- XOR=0 defines Active Low Output.
- XOR=1 defines Active High Output.
- AC1=1.
- Pin 16 through Pin 21 are configured to this function.



### **Combinatorial Output Configuration for Complex Mode**

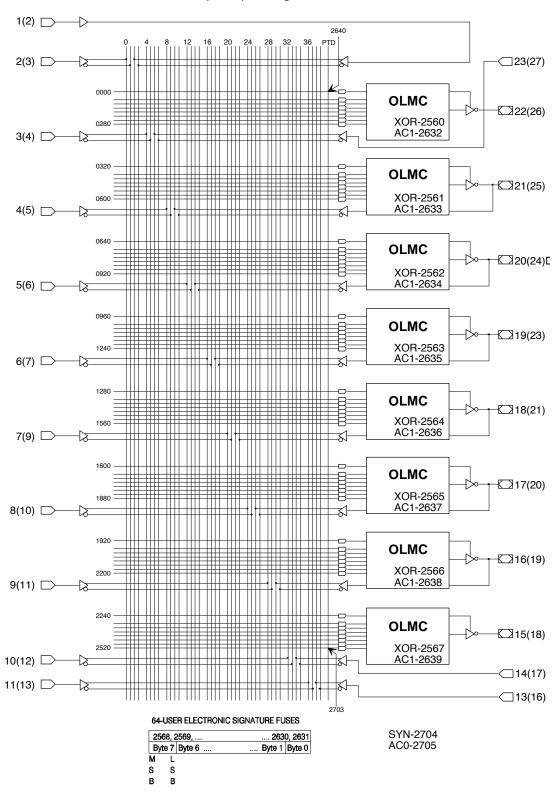
- SYN=1.
- AC0=1.
- XOR=0 defines Active Low Output.
- XOR=1 defines Active High Output.
- AC1=1.
- Pin 15 and Pin 22 are configured to this function.

Note: The development software configures all of the architecture control bits and checks for proper pin usage automatically.



### **Complex Mode Logic Diagram**

### **DIP (PLCC) Package Pinouts**





### **Simple Mode**

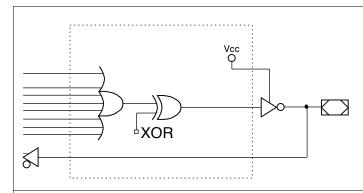
In the Simple mode, pins are configured as dedicated inputs or as dedicated, always active, combinatorial outputs.

Architecture configurations available in this mode are similar to the common 14L8 and 16P6 devices with many permutations of generic output polarity or input choices.

All outputs in the simple mode have a maximum of eight product terms that can control the logic. In addition, each output has programmable polarity.

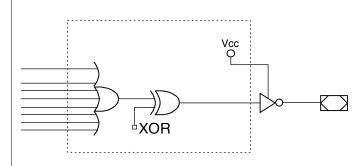
Pins 1 and 13 are always available as data inputs into the AND array. The "center" two macrocells (pins 18 and 19) cannot be used in the input configuration.

The JEDEC fuse numbers including the UES fuses and PTD fuses are shown on the logic diagram on the following page.



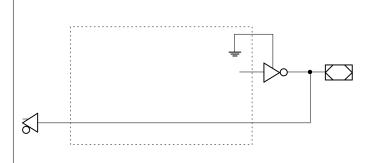
# **Combinatorial Output with Feedback Configuration** for Simple Mode

- SYN=1.
- AC0=0.
- XOR=0 defines Active Low Output.
- XOR=1 defines Active High Output.
- AC1=0 defines this configuration.
- All OLMC except pins 18 & 19 can be configured to this function.



### **Combinatorial Output Configuration for Simple Mode**

- SYN=1.
- AC0=0.
- XOR=0 defines Active Low Output.
- XOR=1 defines Active High Output.
- AC1=0 defines this configuration.
- Pins 18 & 19 are permanently configured to this function.



### **Dedicated Input Configuration for Simple Mode**

- SYN=1.
- AC0=0.
- XOR=0 defines Active Low Output.
- XOR=1 defines Active High Output.
- AC1=1 defines this configuration.
- All OLMC except pins 18 & 19 can be configured to this function.

Note: The development software configures all of the architecture control bits and checks for proper pin usage automatically.



### Simple Mode Logic Diagram

### **DIP (PLCC) Package Pinouts** 1(2) 2640 **23(27)** 2(3) 0000 **OLMC** XOR-2560 +22(26)AC1-2632 0280 3(4) **OLMC** XOR-2561中 21(25) AC1-2633 4(5) **OLMC** XOR-2562 20(24) AC1-2634 0920 5(6) **OLMC** XOR-2563 19(23) AC1-2635 1240 6(7) 1280 **OLMC** XOR-2564 ₩ 18(21)[ AC1-2636 1560 7(9) 1600 **OLMC** XOR-2565 AC1-2637 -**₹** 17(20)[ 8(10) **OLMC** XOR-2566 16(19) AC1-2638 9(11) OLMC XOR-2567 15(18) AC1-2639 10(12) **14(17)** 11(13) 13(16) 64-USER ELECTRONIC SIGNATURE FUSES SYN-2704 2568, 2569, .... ... 2630, 2631 AC0-2705 Byte 7 Byte 6 ... ... Byte 1 Byte 0

S S B



### **Absolute Maximum Ratings**(1)

Supply voltage V <sub>cc</sub>	–0.5 to +7V
Input voltage applied	–2.5 to V <sub>CC</sub> +1.0V
Off-state output voltage applied	–2.5 to V <sub>cc</sub> +1.0V
Storage Temperature	–65 to 150°C
Ambient Temperature with	
Power Applied	55 to 125°C

1.Stresses above those listed under the "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress only ratings and functional operation of the device at these or at any other conditions above those indicated in the operational sections of this specification is not implied (while programming, follow the programming specifications).

### **Recommended Operating Conditions**

### **Commercial Devices:**

Ambient Temperature ( $T_A$ ) ...... 0 to 75°C Supply voltage ( $V_{CC}$ ) with Respect to Ground ...... +4.75 to +5.25V

### Industrial Devices:

### **DC Electrical Characteristics**

### Over Recommended Operating Conditions (Unless Otherwise Specified)

SYMBOL	PARAMETER	CONDITION	MIN.	TYP.3	MAX.	UNITS
VIL	Input Low Voltage		Vss - 0.5	_	0.8	V
<b>V</b> IH	Input High Voltage		2.0	_	Vcc+1	V
IIL1	Input or I/O Low Leakage Current	$0V \le VIN \le VIL (MAX.)$	_	_	-100	μΑ
Iн	Input or I/O High Leakage Current	3.5 <b>V</b> ≤ <b>V</b> IN ≤ <b>V</b> CC	_	_	10	μΑ
<b>V</b> OL	Output Low Voltage	Iol = MAX. Vin = VIL or VIH	_	1	0.5	V
<b>V</b> OH	Output High Voltage	IOH = MAX. Vin = VIL or VIH	2.4		_	V
<b>I</b> OL	Low Level Output Current		_	_	16	mA
Іон	High Level Output Current		_	_	-3.2	mA
los <sup>2</sup>	Output Short Circuit Current	<b>V</b> cc = 5V <b>V</b> out = 0.5V T <sub>A</sub> = 25°C	-30	_	-150	mA

### **COMMERCIAL**

Icc	Operating Power	<b>V</b> IL = 0.5V <b>V</b> IH = 3.0V	L -5/-7/-10	_	75	115	mA
	Supply Current	f <sub>toggle</sub> = 15MHz Outputs Open					

### **INDUSTRIAL**

Ico	Operating Power	<b>V</b> <sub>IL</sub> = 0.5V <b>V</b> <sub>IH</sub> = 3.0V	L-10	_	75	130	mA
	Supply Current	f <sub>toggle</sub> = 15MHz Outputs Open					

<sup>1)</sup> The leakage current is due to the internal pull-up resistor on all pins. See Input Buffer section for more information.

<sup>2)</sup> One output at a time for a maximum duration of one second. Vout = 0.5V was selected to avoid test problems caused by tester ground degradation. Characterized but not 100% tested.

<sup>3)</sup> Typical values are at Vcc = 5V and  $T_A = 25$  °C



### **AC Switching Characteristics**

### **Over Recommended Operating Conditions**

				CC	M	CC	OM	CON	I/IND		
DADAMETED	TEST	DESCRIPTION			5	-	7	-1	0	LINUTC	]
PARAMETER	COND <sup>1</sup> .	DECOKII HOIV		MIN.	MAX.	MIN.	MAX.	MIN.	MAX.	UNITS	
<b>t</b> pd	Α	Input or I/O to	8 outputs switching	1	5	3	7.5	3	10	ns	
		Comb. Output	1 output switching	_	_	_	7	_	_	ns	1
<b>t</b> co	Α	Clock to Output De	lay	1	4	2	5	2	7	ns	Ī
tcf <sup>2</sup>	_	Clock to Feedback	Delay	_	3	_	3	_	6	ns	1
<b>t</b> su	_	Setup Time, Input of	or Feedback before Clock↑	3	_	5	_	7.5	_	ns	1
<b>t</b> h	_	Hold Time, Input or	Feedback after Clock↑	0	_	0	_	0	_	ns	1
	Α	Maximum Clock Fr External Feedback		142.8	_	100	_	66.7	_	MHz	
<b>f</b> max <sup>3</sup>	А	Maximum Clock Fr Internal Feedback,		166	_	125	_	71.4	_	MHz	
	А	Maximum Clock Fr No Feedback	equency with	166	_	125	_	83.3	_	MHz	
<b>t</b> wh	_	Clock Pulse Duration	on, High	3	_	4	_	6	_	ns	1
<b>t</b> wl	_	Clock Pulse Duration	on, Low	3	_	4	_	6	_	ns	1
<b>t</b> en	В	Input or I/O to Outp	out Enabled	1	6	3	9	3	10	ns	1
	В	OE to Output Enab	led	1	6	2	6	2	10	ns	]
<b>t</b> dis	С	Input or I/O to Outp	out Disabled	1	5	2	9	2	10	ns	
	С	OE to Output Disab	pled	1	5	1.5	6	1.5	10	ns	]
	1										

- 1) Refer to Switching Test Conditions section.
- 2) Calculated from fmax with internal feedback. Refer to fmax Descriptions section.
- 3) Refer to **fmax Descriptions** section. Characterized initially and after any design or process changes that may affect these parameters.

### Capacitance ( $T_A = 25^{\circ}C$ , f = 1.0 MHz)

SYMBOL	PARAMETER	MAXIMUM*	UNITS	TEST CONDITIONS
Cı	Input Capacitance	8	pF	$V_{CC} = 5.0V, V_1 = 2.0V$
C <sub>I/O</sub>	I/O Capacitance	8	pF	$V_{CC} = 5.0V, V_{VO} = 2.0V$

<sup>\*</sup>Characterized but not 100% tested



### **Absolute Maximum Ratings**(1)

Supply voltage V <sub>cc</sub>	–0.5 to +7V
Input voltage applied	–2.5 to V <sub>CC</sub> +1.0V
Off-state output voltage applied	–2.5 to V <sub>cc</sub> +1.0V
Storage Temperature	–65 to 150°C
Ambient Temperature with	
Power Applied	–55 to 125°C

1.Stresses above those listed under the "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress only ratings and functional operation of the device at these or at any other conditions above those indicated in the operational sections of this specification is not implied (while programming, follow the programming specifications).

### **Recommended Operating Conditions**

### **Commercial Devices:**

Ambient Temperature ( $T_A$ ) ...... 0 to 75°C Supply voltage ( $V_{CC}$ ) with Respect to Ground ...... +4.75 to +5.25V

### Industrial Devices:

### **DC** Electrical Characteristics

### Over Recommended Operating Conditions (Unless Otherwise Specified)

SYMBOL	PARAMETER	CONDITION	MIN.	TYP.3	MAX.	UNITS
<b>V</b> IL	Input Low Voltage		Vss – 0.5	_	0.8	V
<b>V</b> IH	Input High Voltage		2.0	_	Vcc+1	V
IIL¹	Input or I/O Low Leakage Current	$0V \le V_{IN} \le V_{IL} (MAX.)$	_	_	-100	μΑ
Iн	Input or I/O High Leakage Current	3.5 <b>V</b> ≤ <b>V</b> IN ≤ <b>V</b> CC	_	_	10	μΑ
<b>V</b> OL	Output Low Voltage	Iol = MAX. Vin = VIL or VIH	_	_	0.5	V
<b>V</b> OH	Output High Voltage	IOH = MAX. Vin = VIL or VIH	2.4	_	1	V
<b>I</b> OL	Low Level Output Current		_	_	24	mA
<b>І</b> ОН	High Level Output Current		_	_	-3.2	mA
los <sup>2</sup>	Output Short Circuit Current	<b>V</b> cc = 5V <b>V</b> out = 0.5V T <sub>A</sub> = 25°C	-30	_	-150	mA

### **COMMERCIAL**

Icc	Operating Power	<b>V</b> <sub>IL</sub> = 0.5V <b>V</b> <sub>IH</sub> = 3.0V	L -7/-10	_	75	115	mA
	Supply Current	f <sub>toggle</sub> = 15MHz Outputs Open	L -15/-25	_	75	90	mA
			<b>Q</b> -15/-25	_	45	55	mA

### **INDUSTRIAL**

Icc	Operating Power	<b>V</b> IL = 0.5V <b>V</b> IH = 3.0V	<b>L</b> -10/-15/-25	_	75	130	mA
	Supply Current	f <sub>toggle</sub> = 15MHz Outputs Open	<b>Q</b> -20/-25	-	45	65	mA

<sup>1)</sup> The leakage current is due to the internal pull-up resistor on all pins. See Input Buffer section for more information.

<sup>2)</sup> One output at a time for a maximum duration of one second. Vout = 0.5V was selected to avoid test problems caused by tester ground degradation. Characterized but not 100% tested.

<sup>3)</sup> Typical values are at Vcc = 5V and  $T_A = 25$  °C



### **AC Switching Characteristics**

### **Over Recommended Operating Conditions**

				CC	OM	СОМ	/ IND	СОМ	/ IND	IN	ID	СОМ	/ IND	
DADAM	TEST	DESCRIPTION		-	7	-1	0	-1	5	-2	0	-2	:5	UNITS
PARAM.	COND <sup>1</sup> .	DECORN HOR		MIN.	MAX.	MIN.	MAX.	MIN.	MAX.	MIN.	MAX.	MIN.	MAX.	UNITS
<b>t</b> pd	Α	Input or I/O to	8 outputs switching	3	7.5	3	10	3	15	3	20	3	25	ns
		Comb. Output	1 output switching	_	7	_	_	_	_	_	_	_	_	ns
tco	Α	Clock to Output [	Delay	2	5	2	7	2	10	2	11	2	12	ns
<b>t</b> cf <sup>2</sup>	_	Clock to Feedbac	ck Delay	_	3	_	6	_	8	_	9	_	10	ns
<b>t</b> su	_	Setup Time, Inpu	t or Fdbk before Clk↑	7	_	10	_	12	_	13	_	15	_	ns
<b>t</b> h	_	Hold Time, Input or Fdbk after Clk↑		0	_	0	_	0	_	0	_	0	_	ns
	Α	Maximum Clock Frequency with External Feedback, 1/(tsu + tco)		83.3	_	58.8	_	45.5	_	41.6	_	37	_	MHz
<b>f</b> max <sup>3</sup>	А	Maximum Clock Frequency with Internal Feedback, 1/(tsu + tcf)		100	_	62.5	_	50	_	45.4	_	40	_	MHz
	Α	Maximum Clock Frequency with No Feedback		100	_	62.5	_	62.5	_	50	_	41.7	_	MHz
<b>t</b> wh	_	Clock Pulse Dura	ation, High	5	_	8	_	8	_	10	_	12	_	ns
<b>t</b> wl	_	Clock Pulse Dura	ation, Low	5	_	8	_	8	_	10	_	12	_	ns
<b>t</b> en	В	Input or I/O to Output Enabled		3	9	3	10	_	15	_	18	_	25	ns
	В	OE to Output Enabled		2	6	2	10	_	15	_	18	-	20	ns
<b>t</b> dis	С	Input or I/O to Output Disabled		2	9	2	10	_	15	_	18	_	25	ns
	С	OE to Output Dis	abled	1.5	6	1.5	10	_	15	_	18	<b>—</b>	20	ns

<sup>1)</sup> Refer to Switching Test Conditions section.

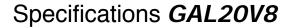
## Capacitance (TA = 25°C, f = 1.0 MHz)

SYMBOL	PARAMETER	MAXIMUM*	UNITS	TEST CONDITIONS
C,	Input Capacitance	8	pF	$V_{CC} = 5.0V, V_{I} = 2.0V$
C <sub>I/O</sub>	I/O Capacitance	8	pF	$V_{CC} = 5.0V, V_{VO} = 2.0V$

<sup>\*</sup>Characterized but not 100% tested.

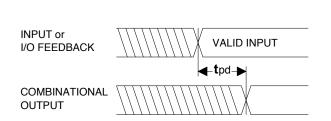
<sup>2)</sup> Calculated from fmax with internal feedback. Refer to fmax Descriptions section.

<sup>3)</sup> Refer to fmax Descriptions section.

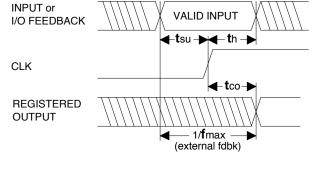




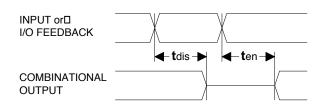
### **Switching Waveforms**



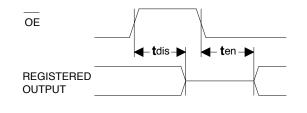
**Combinatorial Output** 



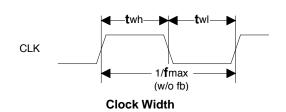
**Registered Output** 

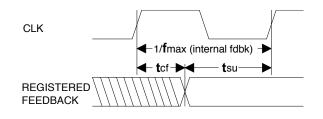


Input or I/O to Output Enable/Disable



**OE to Output Enable/Disable** 

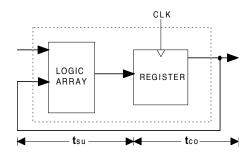




fmax with Feedback

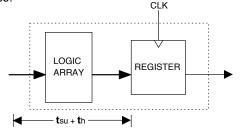


### **fmax Descriptions**



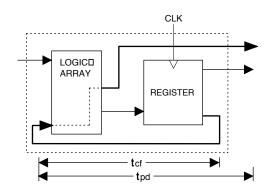
fmax with External Feedback 1/(tsu+tco)

**Note:** fmax with external feedback is calculated from measured tsu and tco.



fmax with No Feedback

**Note:** fmax with no feedback may be less than 1/(twh + twl). This is to allow for a clock duty cycle of other than 50%.



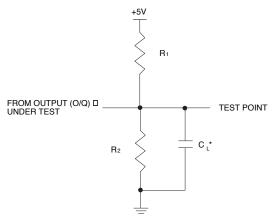
fmax with Internal Feedback 1/(tsu+tcf)

**Note:** tcf is a calculated value, derived by subtracting tsu from the period of fmax w/internal feedback (tcf = 1/fmax - tsu). The value of tcf is used primarily when calculating the delay from clocking a register to a combinatorial output (through registered feedback), as shown above. For example, the timing from clock to a combinatorial output is equal to tcf + tpd.

### **Switching Test Conditions**

Input Pulse Levels	GND to 3.0V	
Input Rise and	nput Rise and GAL20V8B	
Fall Times	1.5ns 10% – 90%	
Input Timing Reference	1.5V	
Output Timing Refere	1.5V	
Output Load	See Figure	

3-state levels are measured 0.5V from steady-state active level.



\*C, INCLUDES TEST FIXTURE AND PROBE CAPACITANCE

### **GAL20V8B Output Load Conditions (see figure)**

Test Condition		R <sub>2</sub>	CL
	200Ω	390Ω	50pF
Active High	∞	390Ω	50pF
Active Low	200Ω	390Ω	50pF
Active High	∞	390Ω	5pF
Active Low	200Ω	390Ω	5pF
	Active High Active Low Active High	$ \begin{array}{c c} & 200\Omega \\ \hline \text{Active High} & \infty \\ \hline \text{Active Low} & 200\Omega \\ \hline \text{Active High} & \infty \\ \hline \end{array} $	$\begin{array}{ccc} & 200\Omega & 390\Omega \\ \text{Active High} & \infty & 390\Omega \\ \text{Active Low} & 200\Omega & 390\Omega \\ \text{Active High} & \infty & 390\Omega \\ \end{array}$

### **GAL20V8C Output Load Conditions (see figure)**

Tes	Test Condition		R <sub>2</sub>	C∟
Α		$200\Omega$	$200\Omega$	50pF
В	Active High	∞	$200\Omega$	50pF
	Active Low	200Ω	$200\Omega$	50pF
С	Active High	∞	200Ω	5pF
	Active Low	200Ω	200Ω	5pF



### **Electronic Signature**

An electronic signature is provided in every GAL20V8 device. It contains 64 bits of reprogrammable memory that can contain user defined data. Some uses include user ID codes, revision numbers, or inventory control. The signature data is always available to the user independent of the state of the security cell.

NOTE: The electronic signature is included in checksum calculations. Changing the electronic signature will alter the checksum.

### **Security Cell**

A security cell is provided in the GAL20V8 devices to prevent unauthorized copying of the array patterns. Once programmed, this cell prevents further read access to the functional bits in the device. This cell can only be erased by re-programming the device, so the original configuration can never be examined once this cell is programmed. The Electronic Signature is always available to the user, regardless of the state of this control cell.

### **Latch-Up Protection**

GAL20V8 devices are designed with an on-board charge pump to negatively bias the substrate. The negative bias minimizes the potential of latch-up caused by negative input undershoots. Additionally, outputs are designed with n-channel pull-ups instead of the traditional p-channel pull-ups in order to eliminate latch-up due to output overshoots.

### **Device Programming**

GAL devices are programmed using a Lattice Semiconductorapproved Logic Programmer, available from a number of manufacturers. Complete programming of the device takes only a few seconds. Erasing of the device is transparent to the user, and is done automatically as part of the programming cycle.

### **Output Register Preload**

When testing state machine designs, all possible states and state transitions must be verified in the design, not just those required in the normal machine operations. This is because, in system operation, certain events occur that may throw the logic into an illegal state (power-up, line voltage glitches, brown-outs, etc.). To test a design for proper treatment of these conditions, a way must be provided to break the feedback paths, and force any desired (i.e., illegal) state into the registers. Then the machine can be sequenced and the outputs tested for correct next state conditions.

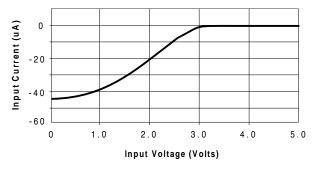
GAL20V8 devices include circuitry that allows each registered output to be synchronously set either high or low. Thus, any present state condition can be forced for test sequencing. If necessary, approved GAL programmers capable of executing text vectors perform output register preload automatically.

### **Input Buffers**

GAL20V8 devices are designed with TTL level compatible input buffers. These buffers have a characteristically high impedance, and present a much lighter load to the driving logic than bipolar TTL devices.

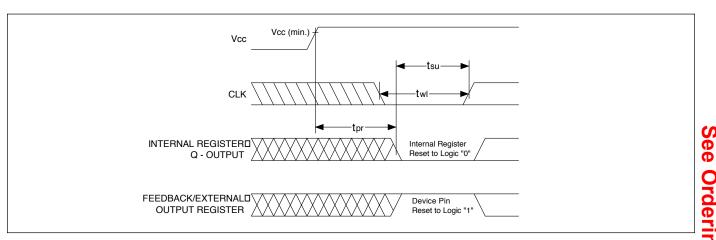
The GAL20V8 input and I/O pins have built-in active pull-ups. As a result, unused inputs and I/O's will float to a TTL "high" (logical "1"). Lattice Semiconductor recommends that all unused inputs and tri-stated I/O pins be connected to another active input,  $V_{\rm CC}$ , or Ground. Doing this will tend to improve noise immunity and reduce  $I_{\rm CC}$  for the device.

### **Typical Input Pull-up Characteristic**





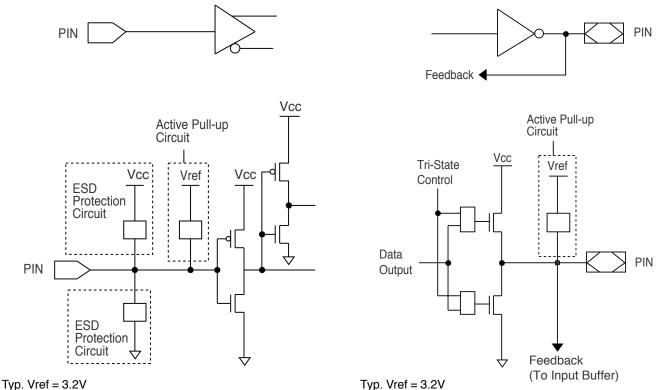
### **Power-Up Reset**



Circuitry within the GAL20V8 provides a reset signal to all registers during power-up. All internal registers will have their Q outputs set low after a specified time (tpr,  $1\mu s$  MAX). As a result, the state on the registered output pins (if they are enabled) will always be high on power-up, regardless of the programmed polarity of the output pins. This feature can greatly simplify state machine design by providing a known state on power-up. Because of the asynchronous nature of system power-up, some conditions must be met to provide

a valid power-up reset of the device. First, the Vcc rise must be monotonic. Second, the clock input must be at static TTL level as shown in the diagram during power up. The registers will reset within a maximum of tpr time. As in normal system operation, avoid clocking the device until all input and feedback path setup times have been met. The clock must also meet the minimum pulse width requirements.





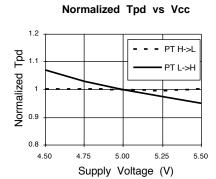
Typical Input Typical Output

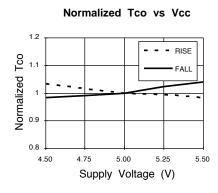


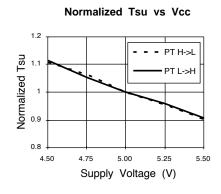
# See Ordering Information section for product status. Select devices have been discontinued

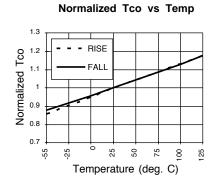


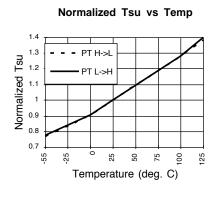
### **GAL20V8C: Typical AC and DC Characteristic Diagrams**

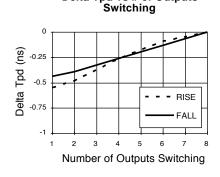




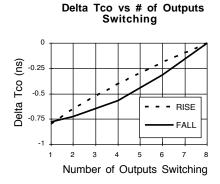


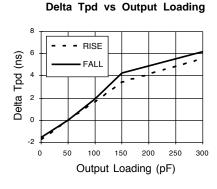


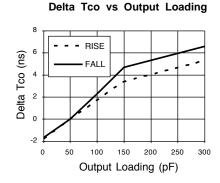




Delta Tpd vs # of Outputs

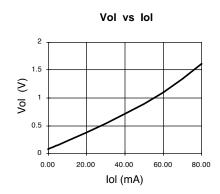


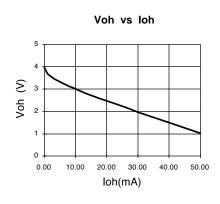


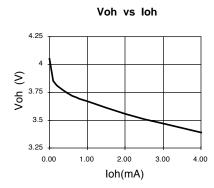


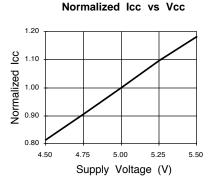


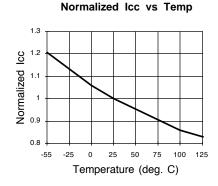
### **GAL20V8C: Typical AC and DC Characteristic Diagrams**

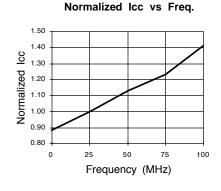


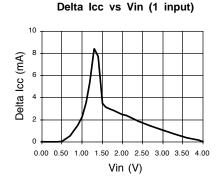


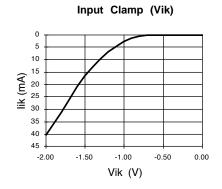












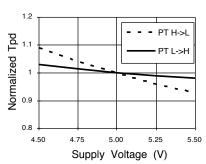


# See Ordering Information section for product status. Select devices have been discontinued

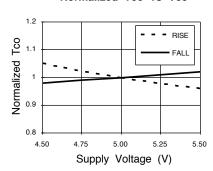


### GAL20V8B-7/-10: Typical AC and DC Characteristic Diagrams

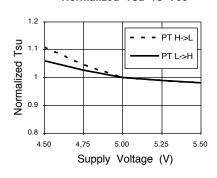
Normalized Tpd vs Vcc



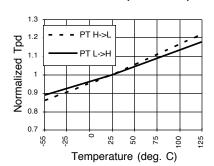
Normalized Tco vs Vcc



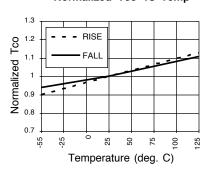
Normalized Tsu vs Vcc



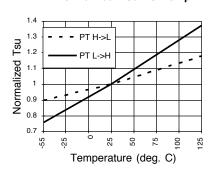
Normalized Tpd vs Temp



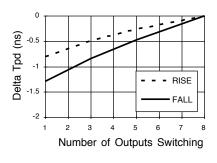
Normalized Tco vs Temp



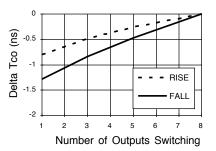
Normalized Tsu vs Temp



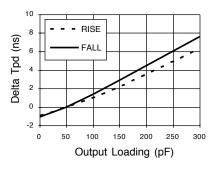
Delta Tpd vs # of Outputs Switching



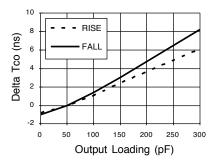
Delta Tco vs # of Outputs Switching



Delta Tpd vs Output Loading



Delta Tco vs Output Loading

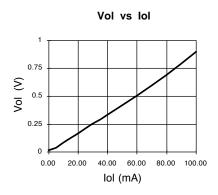


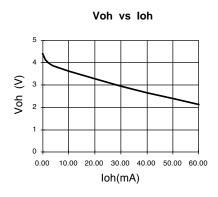


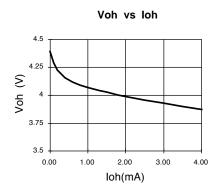
# See Ordering Information section for product status. Select devices have been discontinued.

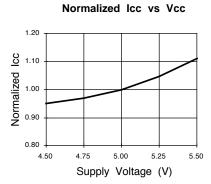


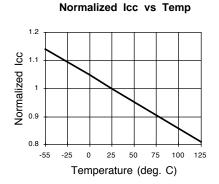
### GAL20V8B-7/-10: Typical AC and DC Characteristic Diagrams

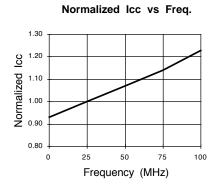


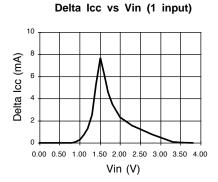


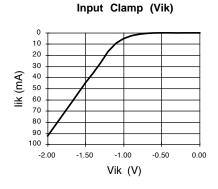










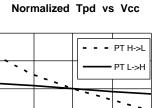




# See Ordering Information section for product status. Select devices have been discontinued

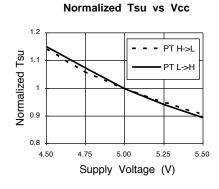


### GAL20V8B-15/-25: Typical AC and DC Characteristic Diagrams

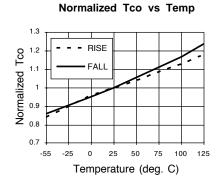


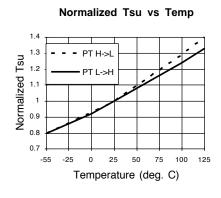
1.2 Normalized Tpd 8.0 4.50 5.25 5.50 Supply Voltage (V)

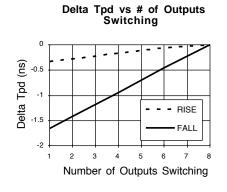
Normalized Tco vs Vcc 1.2 Normalized Tco 1.1 0.9 0.8 5.50 4.50 5.00 Supply Voltage (V)

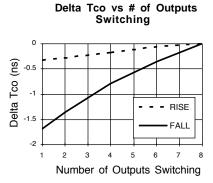


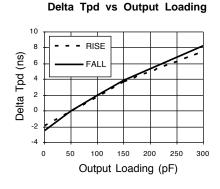
Normalized Tpd vs Temp PT H->L Normalized Tpd 0.9 -55 25 100 Temperature (deg. C)

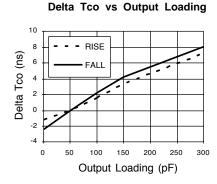










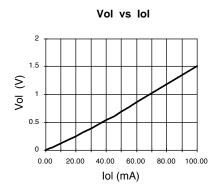


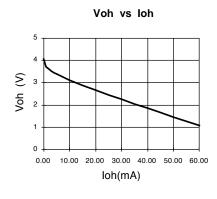


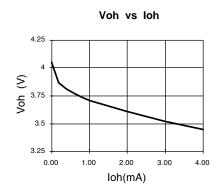
# See Ordering Information section for product status. Select devices have been discontinued.

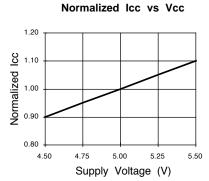


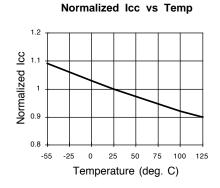
### GAL20V8B-15/-25: Typical AC and DC Characteristic Diagrams

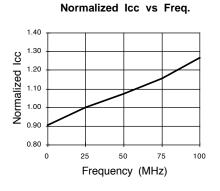


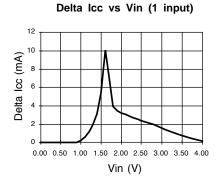


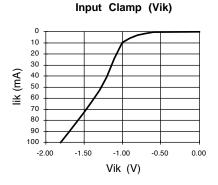














Revision History					
Date	Version	Change Summary			
-	20v8_06	Previous Lattice release.			
August 2006	20v8_07	Updated for lead-free package options.			