Extra Credit Works

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Chapter 1.1 #17 Drag Race

Solution Let us consider Alice and Kevin begin from a standing start in the race and they move foward with a constant acceleration. Let us denote A for Alice and K for Kevin then we can say that

a(t) = k, where k is a constant.

Then the *velocity* is

$$v(t) = \int a(t)dt + C$$
$$= \int kdt + C$$
$$= kt + C$$

The initial velocity is zero, Thus, we get

$$v(0) = 0$$
$$k(0) + C = 0$$
$$C = 0$$

Therefore the velocity is

$$v(t) = kt$$

Let us denote that

$$s(t) = \int v(t)dt + C_1$$
$$= \int ktdt + C_1$$
$$= \frac{kt^2}{2} + C_1$$

The constant value will be zero since our standing point is at the beginning of the race. Therefore,

$$s(t) = \frac{1}{2}kt^2$$

Now, the acceleration is the second derivative of the position function, or is the first derivative of the velocity function. Therefore,

$$a = \frac{\mathrm{d}v}{\mathrm{d}t} = k$$

Let D represent the total distance of the racec and T be the time then we get

$$D = s(t) = \frac{1}{2}aT^2$$

Solving this equation for T to get

$$T = \sqrt{\frac{2D}{a}}$$

For Kevin, when she has $\frac{1}{4}$ left to go she has already traveled $\frac{3}{4}$ of the entire distance D, so we can express this as follows:

$$t_{\frac{3}{4}} = \sqrt{\frac{2\left(\frac{3}{4}\right)D}{a}}$$
$$= \sqrt{\frac{3}{4}}\sqrt{\frac{2D}{a}}$$
$$= \frac{\sqrt{3}}{2}T$$

Thus, the total time for Kevin to complete the race is,

$$T = t_{\frac{1}{4}} + t_{\frac{3}{4}}$$

$$T = 3 + \frac{\sqrt{3}}{2}T$$

$$T\left(1 - \frac{\sqrt{3}}{2}\right) = 3$$

$$T\left(\frac{2 - \sqrt{3}}{2}\right) = 3$$

$$T = \frac{6}{2 - \sqrt{3}}$$

$$T = 6\left(2 + \sqrt{3}\right)$$

Thus,

$$T = 6\left(2 + \sqrt{3}\right) \approx 22.3923$$
 seconds for Kevin to finish the race.

Now, we need to find the time how long it takes for Alice to finish the race in a similar manner. When Alice has $\frac{1}{3}$ to go her has already covered $\frac{2}{3}$ of the total distance of the race.

$$t_{\frac{2}{3}} = \sqrt{\frac{2\left(\frac{2}{3}\right)D}{a}}$$
$$= \sqrt{\frac{2}{3}}\sqrt{\frac{2D}{a}}$$
$$= \sqrt{\frac{2}{3}}T$$

Therefore, the total time for Alice to complete the race is

$$T = t_{\frac{1}{3}} + t_{\frac{2}{3}}$$

$$T = 4 + \sqrt{\frac{2}{3}}T$$

$$T\left(1 - \sqrt{\frac{2}{3}}\right) = 4$$

$$T\left(\frac{\sqrt{3} - \sqrt{2}}{\sqrt{3}}\right) = 4$$

$$T = \frac{4\sqrt{4}}{\sqrt{3} - \sqrt{2}}$$

$$T = 4\sqrt{3}\left(\sqrt{3} + \sqrt{2}\right)$$

$$T = 4\left(3 + \sqrt{6}\right) \approx 21.798$$

Thus, Alice wins by

$$T = 6\left(2 + \sqrt{3}\right) - 4\left(3 + \sqrt{6}\right)$$
$$= 6\sqrt{3} - 4\sqrt{6}$$
$$\approx 0.594$$

Thus, Alice wins by $(6\sqrt{3} - 4\sqrt{6})$ seconds.

Chapter 1 B: Picard's Method

(a) Use Picard's method with $\psi_0(x) = 1$ to obtain the next four successive approximations of the solution to

$$y'(x) = y(x), \quad y(0) = 1$$

Show that these approximations are just the partial sums of the Maclaurin series for the actual solution e^x .

Solution Given that

$$y'(x) = y(x), \quad y(0) = 1$$
 (1)

Also given that

$$f(x,y) = y(x) \tag{2}$$

According to picards theorem, we have

$$\phi_{n+1}(x) = y_0 + \int_{x_0}^x f(t, \phi_0(t)) dt$$

$$= 1 + \int_0^x 1 dt$$

$$= 1 + x$$
(3)

$$\phi_2(x) = y_0 + \int_0^x f(t, \phi_1(t))dt$$

$$= 1 + \int_0^x f(t, (1+t))dt$$

$$= 1 + x + \frac{x^2}{2}$$
(4)

$$\phi_3(x) = y_0 + \int_0^x f(t, \phi_2(t)) dt$$

$$= 1 + \int_0^x f\left(t, \left(1 + t + \frac{t^2}{2}\right)\right) dt$$

$$= 1 + x + \frac{x^2}{2} + \frac{x^3}{6}$$
(5)

$$\phi_4(x) = y_0 + \int_0^x f(t, \phi_3(t)) dt$$

$$= 1 + \int_0^x f\left(t, \left(1 + t + \frac{t^2}{2}\right)\right) dt$$

$$= 1 + x + \frac{x^2}{2} + \frac{x^3}{6} + \frac{x^4}{24}$$
(6)

By observing the pattern as n goes, it is enough to say that

$$\phi_n(x) = 1 + x + x^2 + \frac{x^2}{2} + \frac{x^3}{6} + \dots + \frac{x^n}{n!}$$

This is the partial sum of the Maclaurian series of e^x .

(b) Use Picard's method with $\psi + 0(x) = 0$ to obtain the next three successive approximations of the solution to the nonlinear problem

$$y'(x) = 3x - [y(x)^2], \quad y(0) = 0$$

Graph these approximations for $0 \le x \le 1$.

Solution

$$y(x_1) = y(x_0) + \int_{x_0}^x f(x, y) dx$$

= $f(x, y) = 2x - y^2$
 $y(0) = 0$ (1)

We assume that $x_0 = 0, x_1 = 0.25$ then

$$\phi_{1}(x) = y(0) + \int_{0}^{x} \phi_{0}(x)dx = 0 + \int_{0}^{x} 2x - 0dx = x^{2}$$

$$\phi_{2}(x) = y(0) + \int_{0}^{x} \phi_{1}(x)dx = 0 + \int_{0}^{x} (2x - x^{2})dx = x^{2} - ex^{2} + ex^{2} - ex^{2} + ex^{2} +$$

If x = 0.25, $\phi_1(x) = 0.0625$, $\phi_2(x) = 0.05729$, $\phi_3(x) = 0.05761$, $\phi_4(x) = 0.0576009$. Thus, the better approximation at x = 0.25 is 0.0576.

If
$$x = 0.5$$
, $\phi_1(x) = 0.25$, $\phi_2(x) = 0.2083$, $\phi_3(x) = 0.203125$, $\phi_4(x) = 0.21302$.

If
$$x = 0.75$$
, $\phi_1(x) = 0.5625$, $\phi_2(x) = 0.421875$, $\phi_3(x) = 0.44824$, $\phi_4(x) = 0.605419$.

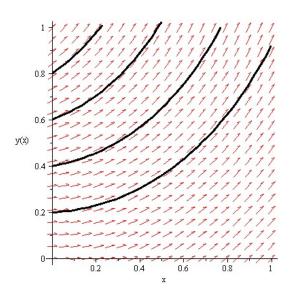


Figure 1:

(c) In Problem 29 in Exercises 1.2, we showed that the initial value problem

$$y'(x) = 3[y(x)]^{2/3}, y(2) = 0$$

does not have a unique solution. Show that Picard's method beginning with $\psi_0(x) = 0$ converges to the solution y(x) = 0, whereas Picard's method beginning with $\psi_0(x) = x - 2$ converges to the second solution $y(x) = (x - 2)^3$.

Solution The given IVP can be written as

$$y'(t) = f(x, y(x)) \text{ where } f(x, y(x)) = 3(y(x))^{2/3}$$
 (1)

The first iteration is given by

$$y_1(x) = y(2) + \int_2^x f(u, y(2)) du$$

= 0 + \int_2^t f(u, 0) du \qquad (2)
= 0 + \int_0^x 0 du = 0

If we repeat the procedure, then we get

$$y_2(x) = 0 (3)$$

Thus, we get the trivial solution y(x) = 0 for the IVP.

Suppose that

$$\phi_0(x) = x - 2 \tag{4}$$

Then the first iteration is given by

$$\phi_1(x) = \phi_0(x) + \int_2^x f(u, \phi_0(x)) du$$

$$= x - 2 + \int_2^x f(u, x - 2) du$$

$$= x - 2 + \int_2^x 3(x - 2)^{2/3} du = x - 23 \frac{(x - 2)^{5/3}}{5/3} \Big|_2^x$$

$$= x - 2 + \frac{9}{5}(x - 2)^{5/3} = (x - 2) \left(1 + \frac{9}{5}(x - 2)^{2/3}\right)$$
(5)

The second iteration is given by

$$\phi_{2}(x) = \phi_{0}(x) + \int_{2}^{x} (fu, \phi_{1}(x)) du$$

$$= x - 2 + \int_{2}^{x} f(u, x - 2) du$$

$$= x - 2 + \int_{2}^{x} x - 2 + \frac{9}{5} (x - 2)^{5/3} du = x - 2 + \left(\frac{(x - 2)^{2}}{2} + \frac{9}{5} \frac{(x - 2)^{8/3}}{8/3} \right)_{2}^{x}$$

$$= x - 2 = \frac{(x - 2)^{2}}{2} + \frac{27}{40} (x - 2)^{8/3}$$
(6)

The Phase Line

(a) The slopes in the direction field are all identical along horizontal lines.

Solution

(b) New solutions can be generated from old ones by time shifting [i.e., replacing y(t) with $y(t-t_0)$.]

Solution

(c) Sketch the phase line for y' = (y-1)(y-2)(y-3) and state the nature of its equilibria.

Solution

(d) Use the phase line for $y' = -(y-1)^{5/3}(y-2)^2(y-3)$ to predict the asymtotic behavior as $t \to \infty$ of the solution satisfying y(0) = 2.1.

Solution

(e) Sketch the phase line for $y' = y\sin y$ and state the nature of its equilibria.

Solution

(f) Sketch the phase lines for $y' = y \sin y + 0.1$ and $y' = y \sin y - 0.1$. Discuss the effect of the small perturbation ± 0.1 on the equilibria.

Solution

Chapter 4 A: Nonlinear Equations Solvable by First-Order Techniques

(a) Solution

The given equation can ben rewritten as

$$2x\frac{\mathrm{d}w}{\mathrm{d}x} - w + \frac{1}{w} = 0$$
$$2x\frac{\mathrm{d}w}{\mathrm{d}x} = w - \frac{1}{w}$$
$$\frac{1}{w - 1/w}dw = \frac{1}{2x}dx$$

Therefore we get

$$\frac{1}{2} \int \left(\frac{1}{w^2 - 1} 2w \right) dw = \frac{1}{2} \int \frac{1}{b} 2dx$$

That is

$$\ln w^{2} - 1 = \ln |x| + C$$

$$w^{2} - 1 = x + C$$

$$w = \frac{\mathrm{d}y}{\mathrm{d}x} = \sqrt{x+1}$$

Thus, we obtain

$$y = \int (x+1)^{\frac{1}{2}} dx = \frac{1}{2\sqrt{x+1}} + C$$

(b) Solution

$$(2y)(w)\frac{\mathrm{d}w}{\mathrm{d}y} = 1 + w^2$$
$$2y\frac{\mathrm{d}w}{\mathrm{d}y} = \frac{1}{w} + w = \frac{w^2 + 1}{w}$$

This becomes

$$\frac{1}{2} \int 1(w^2 + 1) (2w) dw = \frac{1}{2} \int \frac{1}{y} dy$$

Then we obtain

$$w = \sqrt{y - 1} + C$$

$$\int \frac{1}{\sqrt{y-1}} dy = \int dx \sqrt{y-1} = 2x + C_1$$

Thus we obtain

$$y_1 = 1 + 4x^2 + C$$

Then we need to have another equation.

$$2yw\frac{\mathrm{d}w}{\mathrm{d}y} = -yw2\frac{\mathrm{d}w}{\mathrm{d}y} = -\frac{yw}{yw} = -1$$

$$\int dw = -\frac{1}{2} \int dy$$
$$-2 \int \frac{1}{y} dy = \int dx$$

This becomes

$$-2\ln|y| = x + C$$

$$\ln|y| = -\frac{1}{2}x + C$$

Thus, we get

$$y_2 = Ce^{-\frac{x}{2}}$$

(c) Suspended Cable.

Solution The given differential equation is

$$y'' = \frac{1}{a}\sqrt{1 + \left(\frac{\mathrm{d}y}{\mathrm{d}x}\right)^2}; \quad y(0) = a, \quad y'(0) = 0, \quad \text{where } a(\neq 0) \text{ is a constant.}$$
 (1)

Let v = y' then we can say that $\frac{\mathrm{d}v}{\mathrm{d}x} = y''$

Now, we solve

$$\frac{\mathrm{d}v}{\mathrm{d}x} = \frac{1}{a}\sqrt{1+v^2}$$

$$\int \frac{dv}{\sqrt{1+v^2}} = a \int dx$$
(2)

This becomes

$$\ln\sqrt{1+v^2} + v = ax \tag{3}$$

Thus, this is enough reason to say that

$$x'(0) = 0$$

This means C = 0.

Therefore

$$\ln \sqrt{1+v^2} + v = ax$$

$$\sqrt{1+v^2} + v = e^{ax}$$

$$\left(-\sqrt{1+v^2}\right) = (v - e^{ax})^2$$

$$v = \frac{e^{2ax} - 1}{2e^{ax}} = \frac{1}{2} \left[e^{ax} - e^{-ax}\right]$$
(4)

$$\frac{dy}{dx} = \frac{1}{2} \left(e^{ax} - e^{-ax} \right)
\int dy = \frac{1}{2} \int \left(e^{ax} - e^{-ax} \right) dx
y = \frac{1}{2} \frac{\left(e^{ax} + e^{-ax} \right)}{a} + C_2$$
(5)

At y(0) = a,

$$a = \frac{1}{2}\frac{2}{a} + C_2$$

Therefore,

$$C_2 = \frac{\left(a^2 - 1\right)}{a}$$

Then finally we get

$$y = \frac{1}{2} \left(\frac{a^{ax} + e^{-ax}}{a} \right) + \frac{a^2 - 1}{a} \tag{6}$$

Chapter 4C: Simple Pendulum

(a) **Solution** By assuming the problem consisting of mass m suspended by a rod of length l and writing the derived nonlinear initial value problem,

$$\frac{\mathrm{d}^2 \theta}{\mathrm{d}t^2} + \frac{g}{l}\sin\theta = 0, \quad \theta(0) = \alpha(0), \theta'(0) = 0$$

Let us determine the equation of motion for the pendulum and its period.

$$\left(\frac{\mathrm{d}\theta}{\mathrm{d}t}\right) \left(\frac{\mathrm{d}^2\theta}{\mathrm{d}t^2}\right) + \frac{g}{l}\sin\theta \left(\frac{\mathrm{d}\theta}{\mathrm{d}t}\right) = 0$$

$$\frac{\mathrm{d}}{\mathrm{d}t} \left(\frac{1}{2} \left(\frac{\mathrm{d}\theta}{\mathrm{d}t}\right)^2 - \frac{g}{l}\cos\theta\right) = 0$$

$$\frac{1}{2} \left(\frac{\mathrm{d}\theta}{\mathrm{d}t}\right)^2 - \frac{g}{l}\cos t het a = c$$

$$\left(\frac{\theta}{t}\right)^2 - \frac{2g}{l}\cos\theta = C$$
(1)

By applying the initial conditions,

$$\left(\theta'(0)\right)^2 - \frac{2g}{l}\cos theta(0) = C\tag{2}$$

Then we get

$$0 - \frac{2g}{l}\cos\alpha = C$$

$$C = -\frac{2g}{l}\cos\alpha$$
(3)

By substituting C value into $\left(\frac{d\theta}{dt}\right)^2 - \frac{2g}{l}\cos\theta = C$, then we get

$$\left(\frac{\mathrm{d}\theta}{\mathrm{d}t}\right)^{2} - \frac{2g}{l}\cos\theta = -\frac{2g}{l}\cos\alpha$$

$$\left(\frac{\mathrm{d}\theta}{\mathrm{d}t}\right)^{2} = \frac{2g}{l}\left(\cos\theta - \cos\alpha\right)$$

$$\frac{\mathrm{d}\theta}{\mathrm{d}t} = -\sqrt{\frac{2g}{l}\left(\cos\theta - \cos\alpha\right)}$$

$$dt = -\sqrt{\frac{1}{2g}\frac{d\theta}{\sqrt{(\cos\theta - \cos\alpha)}}}$$
(4)

(b) **Solution** By using the formula, $\cos x = 1 - 2\sin^2 x$, we can say that

$$dt = -\sqrt{\frac{1}{2g}} \frac{d\theta}{\sqrt{((1 - 2\sin^2\theta) - (1 - 2\sin^2\alpha))}}$$

$$dt = -\frac{1}{2} \sqrt{\frac{l}{g}} \frac{d\theta}{\sqrt{\sin^2\frac{\alpha}{2} - \sin^2\frac{\theta}{2}}}$$
(5)

(c) **Solution** Now, let us determine the elapsed time T, for the pendulum to fall from the angle $\theta = \alpha$ to the angle $\theta = \beta$ corresponding to $\phi = \frac{\pi}{2}$ to $\phi = \Phi$

$$T = \int_0^t dt = -\frac{1}{2} \sqrt{\frac{l}{g}} \frac{d\theta}{\sqrt{\sin^2 \frac{\alpha}{2} - \sin^2 \frac{\theta}{2}}}$$

$$= -\frac{1}{2} \sqrt{\frac{l}{g}} \int_{\frac{\pi}{2}}^{\phi} \frac{d\theta}{\sqrt{\sin^2 \frac{\alpha}{2} - \sin^2 \frac{\theta}{2}}}$$

$$= -\sqrt{\frac{l}{g}} \int_{\frac{\pi}{2}}^{\phi} \frac{d\phi}{\sqrt{1 - k^2 \sin^2 \phi}}, \quad \text{where } k = \sin \frac{\alpha}{2}$$

$$(6)$$

Thus, we get

$$-T = \sqrt{\frac{1}{g}} \int_{\frac{\pi}{2}}^{\phi} \frac{d\phi}{1 - k^2 \sin^2 \phi}$$
 (7)

(d) **Solution** Let us determine the period P of the pendulum. The period is defined to be the time required for it swing from one extreme to other extreme and back. Therefore, from α to $-\alpha$ and from $-\alpha$ to α . Therefore, the total period is four equal parts. Thus, the period is given by

$$P = (4)\sqrt{\frac{l}{g}} \int_0^{\frac{\pi}{2}} \frac{d\phi}{\sqrt{1 - k^2 \sin^2 \phi}}$$
 (8)

Now, the integral

$$\int_0^{\frac{\pi}{2}} \frac{d\phi}{\sqrt{1 - k^2 \sin^2(\phi)}}$$

is called an elliptic integral of the first kind and denoted by

$$F\left(k, \frac{\pi}{2}\right) = \int_0^{\frac{\pi}{2}} \frac{d\phi}{\sqrt{1 - k^2 \sin^2 \phi}}$$

(e) Solution

$$\frac{P}{4} + (-T) = \sqrt{\frac{l}{g}} \int_{0}^{\frac{\pi}{2}} \frac{d\phi}{\sqrt{1 - k^{2} \sin^{2}(\phi)}} + \sqrt{\frac{l}{g}} \int_{\frac{\pi}{2}}^{\phi} \frac{d\phi}{\sqrt{1 - k^{2} \sin^{2}(\phi)}}$$

$$-T + \frac{P}{4} = \sqrt{\frac{l}{g}} \int_{0}^{\phi} \frac{d\phi}{\sqrt{1 - k^{2} \sin^{2}\phi}}$$

$$-T + \frac{P}{4} = \sqrt{\frac{l}{g}} F(k, \Phi)$$
(9)

This is obtained by substituting

$$F(k,\Phi) = \int_0^{\phi} \frac{d\phi}{\sqrt{1 - k^2 \sin^2 \phi}}$$

Linearization of Nonlinear Problems

(a) Solution

$$\theta'(t) = -\sin \theta(t)$$

$$\theta''(0) = -\sin(\theta(0))$$

$$\theta'''(t) = -\cos \theta(t)\theta'(t)$$

$$\theta^{(4)} = \sin(\theta(t))(\theta'(t))^{2} - \cos(\theta(t))\theta''(t)$$
(1)

$$\theta^{(4)}(0) = \sin \theta(0)(\theta'(0))^2 + \cos(\theta(0))\sin(\theta(0))$$

$$\theta^{(5)}(t) = \cos(\theta(t))(\theta'(t))^3 + 2\sin(\theta(t))\theta'(t)\theta''(t) + \frac{\mathrm{d}(\sin 2\theta(t))}{\mathrm{d}t} \left(\frac{1}{2}\right)$$

$$\theta^{(5)}(t) = \cos(\theta(t))(\theta'(t))^3 + 2\sin\theta(t)\theta'(t)\theta'(t) + \cos 2\theta(t)\theta'(t)$$

$$\theta^{(5)}(0) = \cos(\theta(0))(\theta'(0))^3 + 2\sin\theta(0)\theta'(0)\theta'(0) + \cos 2\theta(0)\theta'(0)$$

(b) Solution

$$derivs\theta t + \theta = 0$$

Now solving for θ , then we get

$$\theta = C_1 e^t + C_2 e^{-t}$$
$$\theta(0) = C_1 + C_2 = \frac{\pi}{2}$$

Since

$$\theta'(t) = C_1 e^t - C_2 e^{-t}$$

The constant values are

$$C_1 - C_2 = 0$$

$$C_1 = C_2 = \frac{\pi}{24}$$

Thus,

$$\theta(t) = \frac{\pi}{24} \left[e^t + e^{-t} \right]$$

- (c) Solution
- (d) Solution
- (e) Solution

Chapter 4E: Convolution Method

(a) **Solution** The convolution of two functions g and f is the function $g \times f$ define by

$$(g \times f)(t) = \int_0^t g(t - u)f(u)du$$

And by Leibnitz's rule

$$\frac{\mathrm{d}}{\mathrm{d}t} \int_{a}^{t} h(t, u) du = \int_{a}^{t} \frac{\partial h}{\partial t}(t, u) du + h(t, t)$$

$$(y \times f)'(t) = \frac{\mathrm{d}}{\mathrm{d}t} \left[(y \times f)(t) \right]$$

$$= \frac{\mathrm{d}}{\mathrm{d}t} \int_0^t y(t-u)f(u)du$$

$$= \int_0^t \frac{\partial}{\partial t} (y(t-u)f(u))du + y(t-t)f(t)$$

$$= \int_0^t y'f(u)du + y(0)f(t)$$

$$= (y' \times f)(t) + y(0)f(t)$$
(1)

Therefore we obtain

$$(y \times f)'(t) = (y' \times f)(t) + y(0)f(t)$$

Then, we can use this equation to get

$$(y \times f)'' = \frac{d}{dt} ((y \times f)') (t)$$

$$= \frac{d}{dt} [(y' \times f) (t) + y(0)f(t)]$$

$$= \frac{d}{d} ((y' \times f) (t)) + \frac{d}{dt} (y(0)f(t))$$

$$= [(y'' \times f) (t) + y'(0)f(t)] + y(0)f'(t)$$

$$= [(y'' \times f) (t) + y'(0)f(t)] + y(0)f'(t)$$
(2)

Therefore, we get

$$(y \times f)'' = [(y'' \times f)(t) + y'(0)f(t)] + y(0)f'(t)$$

(b) Solution Given the differential equation

$$ay'' + by' + cy = 0$$

Let $y_k(t)$ is the solution to the given differential equation. To show that $y_k \times f$ is the particular solution to ay'' + by' + cy = f(t) satisfying y(0) = y'(0) = 0.

$$(y_{k} \times f)'' = (y_{k}'' \times f)(t) + y_{k}(0)f(t) + y_{k}(0)y'(t)$$

$$= (y'' \times f)(t) + \frac{f(t)}{a}$$

$$(y_{k} \times f)'(t) = (y_{k} \times f)'(t) + y_{k}(0)f(t)$$

$$= (y_{k}' \times f)(t)$$
(3)

Therefore

$$a(y_k'' \times f)(t) + b(y_k \times f)'(t) + c(y_k \times f) = a\left[(y_k'' \times f)(t) + \frac{f(t)}{a}\right] + b(y_k')(t) + c(y_k \times f)$$
$$= f(t) + a(y_k'' \times f)(t) + b(y_k' \times f)(t) + c(y_k \times f)$$

Then

$$L\left(a(y_k'' \times f)(t) + b(y_k' \times f)(t) + c(y_k \times f)\right) = aL\left((y_k'' \times f)\right)$$

$$= L(f)L\left(a_k'' + by_k' + cy_k\right)$$

$$= L(f) \times 0$$

$$= 0$$

By applying Inver Laplace Transform, we get

$$a(y_k'' \times f)(t) + b(y_k \times f)'(t) + c(y_k \prime f) = 0$$

Thus, $y_k \times f$ is the solution of the given differential equation. Moreover,

$$y_k \times f \Big|_{t=0} = \int_0^0 f(v) y_k(0-v) dv = 0$$

Hence showed.

(c) **Solution** Since $y_k(t)$ is a solution of the corresponding homogeneous equation and $(y_k \times f)$ is a particular solution, it is obvious to say that $(y_k \times f) + y_k(t)$ is a solution of $ay_k'' + by_k' cy_k = f(t)$. Also,

$$((y \times f) + y_k)(0) = (y \times f)(0) + y_k(0)$$

= 0 + y₀
= y₀

$$((y \times f) + y_k)^k (0) = (y \times f)'(0) + y'_k(0)$$

= y_1

By using **Uniqueness Theorem** of the solutions of ODE, $y_k(0)$ is the unique solution of the homogeneous equation with the initial conditions $y_k(0) = y_k$, $y'_k(0) = y_1$.

For the same equation $y_k(t)$ is the solution of the homogeneous equation with the initial condition $y_k(0) = 0$, $y_k'(0) = \frac{1}{a}$.

Thus, $(y \times f) + y_k$ must be the unique solution of $ay_k'' + by_k' + cy_k = f(t)$ with $y(0) = y_0$ and $y'(0) = y_1$.

- (d) Solution
 - (a) Finding the general solution of the homogeneous equation.

$$y'' + y = 0$$
$$y = c_1 \sin t + c_2 \cos t$$

From part (b), $y_k = c_1 \sin t + c_2 \cos t$ satisfying $y_k(0) = 0, y_k'(0) = \frac{1}{a} = 1$.

That is

$$y_k(0) = 0 = 0 + c_2$$

 $y'_k(0) = 1 = c_1 - 0$

Therefore $y_k = \sin t$ Now, by using part (c), we find y_k as y(0) = 0, y'(0) = -1.

$$y_k(0) = 0 = 0 + c_2$$
$$y'_k(0) = -1 = c_1 - 0$$

Therefore $y_k = -\sin t$. From part (c), the solution of the given equation is

$$(y_k \times f)(t) + y_k(t) = (\sin x \tan)(t) - \sin t$$

$$= \int_0^t \sin t - uu du - \sin t$$

$$= \int_0^t \sin t \cos u - \sin u \cos t \tan u du - \sin t$$

$$= \sin t \int_0^t \sin u du - \cos t \int_0^t \sec u - \cos u du - \sin t$$

$$= \sin t \left[-\cos u \right]_0^t - \cos t \left[\ln \sec u + \tan u - \sin u_0^t \right] - \sin t$$

$$= -\cos t \ln \left[\sec t + \tan t \right]$$

(b) The general solution to the homogeneous equation is

$$2y'' + y' - y = 0$$
$$y = c_1 e^{-t} + c_2 e^{\frac{t}{2}}$$

Then, $y_k = 0c_1e^{-t} + c_2e^{\frac{t}{2}}$ satisfying $y_k(0) = 0, y_k'(0) = \frac{1}{a} = \frac{1}{2}$.

$$y_k(0) = 0 = c_1 + c_2$$

 $y'_k(0) = \frac{1}{2} = c_1 + \frac{1}{2}c_2$

So $c_1 = -\frac{1}{3}$, $c_2 = \frac{1}{3}$

$$y_k = \frac{1}{3}e^{\frac{t}{2}} - \frac{1}{3}e^{-t}$$

By using the part (c), $y_k = c_1 e^{-t} + c_2 e^{\frac{t}{w}}$ satisfying y(0) = 1, y' = -1.

$$y_k(0) = 1 = c_1 + c_2$$

 $y'_1(0) = -1 = c_1 + \frac{1}{2}c_2$

$$y_k = \frac{4}{3}e^{\frac{t}{2}} - \frac{1}{3}e^{-t}$$

Therefore from the part (c) given equation is,

$$(y_k \times f)(t) = \int_0^t \left(\frac{1}{3}e^{\frac{(t-u)}{2}} - \frac{1}{3}e^{-t}\sin(u)\right) du + \frac{4}{3}e^{\frac{t}{2}} - \frac{1}{3}e^{-t}$$
$$= -\frac{6}{39}e^{-t}\sin t + \frac{3}{13}e^{-t}\cos t - \frac{2}{3}e^{-t} + \frac{56}{39}e^{\frac{t}{2}}$$

(c) Now, the general solution to homogeneous equation is 2y'' - 2y' + y = 0 is

$$y = c_1 e^t + c_2 t e^t$$

Therefore, from the part (b), $y_k = c_1 e^t + c_2 t e^t$ satisfying $y_k(0) = 0, y_0' = \frac{1}{a} = 1$.

$$y_k(0) = 0 = c_1$$

$$y_k'(0) = 1 = c_1 + c_2$$

Thus,

$$c_1 = 0, c_2 = 1$$

Therefore $y_k = te^t$. Now by using the part (c), $c_1e^t + c_2te^t$ satisfying y(0) = 2, y'(0) = 0 (given).

$$y_k(0) = 2 = c_1$$

$$y_k'(0) = c_1 + c_2$$

So we get $c_1 = 2, c_2 = -2$.

Thus, from the part (c), the solution for the given equation is

$$(y_k \times f)(t) + y_k(t) = \int_0^t (t - u)e^{t - u} \sqrt{ue^u} du + 2e^t - 2e^t$$
$$= \frac{4}{15}t^{\frac{5}{2}}e^t - 2te^t + 2e^t$$