Deep Learning Tutorial Session

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Slides

Slides available from:

https://github.com/watson-ij/mltute

• In particular, the talk should be rendered as a webpage at:

```
https://github.com/watson-ij/mltute/blob/master/
20180907-mltute-iwatson.org
```

- Other Resources:
 - Keras documentation: http://keras.io/
 - Large repository of various tutorials, examples, and applications curated by the original author of Keras.
 - https://github.com/fchollet/keras-resources
 - Another tutorial presentation: https://uwaterloo.ca/data-science/sites/ca.data-science/files/uploads/files/keras_tutorial.pdf

Goals

- If you're already a deep learning master, take a long lunch break, get some coffee, see the new building at the front gate
- Get up and running quickly with Deep Learning
 - In particular, the goal is to build neural networks you can take home today!
- Therefore, use Keras to get up and running quickly
- Outline of the session:
 - Basic Usage of Keras (Iris)
 - Convolutional Neural Net in Keras (MNIST)
 - GANs (using MNIST)
- For this lecture, I recommend using google colaboratory
 - Machine learning education and research tool setup by google, all the packages are installed, just need a google account to sign in

https://colab.research.google.com

• Lets setup a new workspace

Google Colab

- https://colab.research.google.com/notebook
- Offers free jupyter-notebook-as-a-service in the cloud
 - Even offers free access to cloud-based GPUs
- Has all the packages we'll need for today pre-installed
- Demo
 - Basic jupyter usage

```
!ls
import os
?os
pi = 3.14159
pi*2
def area(radius):
    return pi*radius**2
area(1)
import numpy as np
import matplotlib.pyplot as plt
x = np.linspace(-3.14, 3.14, 100)
y = np.sin(x)
plt.plot(x, y)
plt.show()
```





- Deep learning framework built by Google engineer François Chollet
- High-level interface built allowing eg Theano or Tensorflow as a backend
 - Has been accepted into mainline Tensorflow, so always accessible there
- Library written in python, user-friendly interface
- Easy to get started building networks
- Highly modular and easily expandable
 - Can drop down into the underlying library when complex/bespoke operations are needed
- Quickly build and train serious models

Dependences

If you want to follow along with a local setup:
With python and pip installed, you can pull the dependencies by pip
installing (you might need to add '-user' to the end of the command lines):

```
pip install matplotlib
pip install keras
pip install tensorflow # Pulls in the CPU version of tensorflow
pip install seaborn # For downloading viewing the iris dataset
pip install scikit-learn
pip install h5py
```

For a GPU tensorflow, usually best to build yourself (out of scope)

Continuing

• Follow along either on the web-based service, or your own machine

```
import h5py
import matplotlib
# matplotlib.use("AGG") # To batch graphics
import matplotlib.pyplot as plt
import os
import keras
from keras.models import Sequential
from keras.lavers import (Dense, Activation,
 Flatten, Conv2D.
 Dropout, Reshape,
      UpSampling2D, BatchNormalization,
 MaxPooling2D)
from keras.optimizers import SGD
import seaborn as sns
import sklearn.cross validation as scv
import sklearn
import numpy as np
```

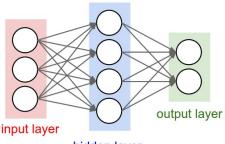
```
# Can also use Keras from tensorflow
keras = tf.keras
Sequential = keras.Sequential
Activation = keras.layers.Activation
Dense = keras.layers.Dense
LeakyReLU = keras.layers.LeakyReLU
BatchNormalization = keras.layers.BatchNormalization
Reshape = keras.layers.Reshape
UpSampling2D = keras.layers.UpSampling2D
Dropout = keras.layers.Dropout
Conv2D = keras.layers.Dropout
Conv2D = keras.layers.Bayers.Dropout
MaxPooling2D = keras.layers.Bayers.MaxPooling2D
Flatten = keras.layers.Flatten
SCD = keras.optimizers.SCD
mnist = keras.datests.mnist.
```

import tensorflow as tf

Overarching Idea of (Supervised) Maching Learning

- Framework for Machine Learning: given a set of data, and set of expected outputs, build a system which learns how to connect data to output
- Neural Network is one type, connect stacks of tensor operators with fixed linear and non-linear transformations
- Optimize transformation parameters so as to approximate expected outputs

Neural Networks



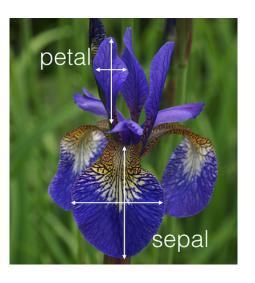
hidden layer

- Example shown: input vector \vec{x} , goes through $\vec{y}_{hidden} = W\vec{x} + \vec{b}$, then $\vec{y}_{output} = \sigma(\vec{y}_{hidden})$ (σ is some non-linear turn-on curve)
- I.e. hidden layer combines \vec{x} by some weights, then if the weighted sum passes a threshold \vec{b} , we turn on the output (with the $\sigma(x)=1/(1+e^{-x})$ to gate the ops)
- Need to train the weight matrix W and the bias vector b and optimize
 a "loss" function that represents a distance from the target output

Backpropagation

- The algorithm to train neural networks is called backpropagation
- We start with the parameters set to arbitrary values, usually picked from e.g. unit gaussian
- We run a forward pass through the network and calculate the loss
- Using the chain rule, calculate derivates backward from the loss to the higher layers
- Propagate changes based on the gradient $\Delta w_i = -\eta \frac{\partial f}{\partial w_i}$

The iris dataset and a basic network with Keras



- The iris dataset is a classic classification task, first studied by Fisher in 1936.
- The goal is, given features measured from a particular iris, classify it into one of three species
 - Iris setosa, virginica, versicolor.
- The variables are: Sepal width and length, petal width and length (all in cm).

Iris dataset

We begin by loading the iris dataset, helpfully available from the seaborn pacakge, which also lets us create plots showing the correlations between the variables.

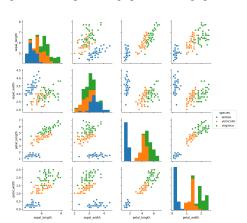
```
iris = sns.load_dataset("iris")
iris.head()
```

	sepal_length	sepal_width	petal_length	petal_width	species
0	5.1	3.5	1.4	0.2	setosa
1	4.9	3.0	1.4	0.2	setosa
2	4.7	3.2	1.3	0.2	setosa
3	4.6	3.1	1.5	0.2	setosa
4	5.0	3.6	1.4	0.2	setosa

Iris Variables

Lets view the basic variables we have. Setosa (blue) looks easily separable by the petal length and width, but versicolor and virginica are a little tricky.

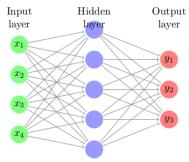
```
plot = sns.pairplot(iris, hue="species")
plot.savefig('iris.png'); 'iris.png'
```



Keras Networks

In order to classify the irises, we'll build a simple network in Keras.

- The basic network type in Keras is the Sequential model.
- The Sequential model builds a neural network by stacking layers
 - Keras also has a Graph model that allows arbitrary connections
- It builds up like lego, adding one layer on top of another and connecting between the layers
 - Keras comes with a menagerie of pre-built layers for you to use.
- Interface to/from the model with numpy arrays



Model

- Our model will be a simple NN with a single hidden layer
- We start by building a Sequential model and add a Dense (fully-connected) layer, with sigmoid activation
- Dense: standard layer, all inputs connect to all outputs: $\hat{y} = W\hat{x} + \hat{b}$
 - keras.layers.Dense(output_dim)
 - Can also set the initalization, add an activation layer inline, add regularizers inline, etc.
- Activation: essentially acts as a switch for a given node, turns output on/off based on threshold
 - keras.layers.Activation(type)
 - Where *type* might be:
 - *sigmoid*: $f(x) = \frac{1}{1 + e^{-x}}$
 - tanh: $f(x) = tanh x = \frac{e^x e^{-x}}{e^x + e^{-x}}$
 - relu: $f(x) = \max(0, x)$, 'rectified linear unit'
 - softplus: $f(x) = \ln(1 + e^x)$, smooth approx. to relu
 - softmax: $f_k(x) = \frac{e^{-x_k}}{\sum_i e^{-x_i}}$ for the k'th output, as last layer of categorical distribution, represents a probability distribution over the outputs

Build a model: Python code

```
# Build a model
model = Sequential()
model.add(Dense(128, input_shape=(4,)))
model.add(Activation('sigmoid'))
# model.add(Dense(128))
# model.add(Activation('sigmoid'))
model.add(Dense(3))
model.add(Activation('softmax'))
model.compile(optimizer='adam', loss='categorical_crossentropy',
      metrics=['accuracy'])
model.summary()
Laver (type)
                     Output Shape
dense_1 (Dense) (None, 128)
activation 1 (Activation) (None, 128)
dense 2 (Dense) (None, 3)
activation_2 (Activation) (None, 3)
```

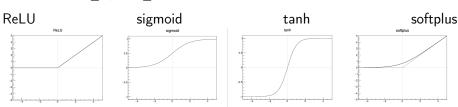
More on model building

- When =add=ing layers, keras takes care of input/output size details
 - Except for the input layer, which must be specified
- The final layer we make size 3 after a softmax activiation
 - This will output the network probability for each of the potential iris classes as a numpy array (nsamples, (psetosa, pvirginica, pversicolor))
- We compile the model with an optimizer and loss function
 - The loss function will be minimized during the training phase
- We can give auxilliary metrics which will be calculated with the loss
- Keras automatically takes care of calculating derivatives through the network for the backprop phase
- We could be more explicit in creating the functions if we want more control over hyperparameters:

More on model building

Here we used the adam optimizer which automatically updates the step sizes used for parameter optimization, with a categorical cross-entropy loss, which measures $-\sum_i t_i \log p_i$ where t_i is 1 for the true label and p_i is the probability of the *i*th label assigned by the model. As the model assigns higher probability to the correct label, the cross-entropy goes to 0.

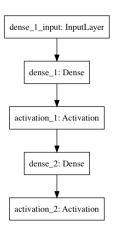
- Other options to consider:
 - Activation: sigmoid, softmax, linear, tanh, relu, ...
 - Optimizer: SGD, RMSprop, Adagrad, Adadelta, Adam, . . .
 - Loss: categorical_crossentropy, binary_crossentropy, mean squared error, . . .



Model picutre

If pydot is installed we can also output a picture of the network

```
keras.utils.plot_model(model, to_file='iris_model.png')
'iris_model.png'
```



Training Code

```
# Split the variables to train, and the target
variables = iris.values[:, :4]
species = iris.values[:, 4]
# One hot encode the species target
smap = {'setosa' : 0, 'versicolor' : 1, 'virginica' : 2}
species_enc = np.eye(3)[list(smap[s] for s in species)]
# To show we are simply passing numpy arrays of the data
print variables[0], species[0], species_enc[0]
train_X, test_X, train_y, test_y = \
  scv.train_test_split(variables, species_enc, train_size=0.8, random_state
model.fit(train_X, train_y, epochs=15, batch_size=1, verbose=1)
[5.1 3.5 1.4 0.2] setosa [ 1. 0. 0.]
Epoch 1/15
120/120 [============] - Os - loss: 0.2873 - acc: 0.9500
Epoch 15/15
```

Training

- Now we fit to the training data.
- We can set the number of epochs, batch_size, and verbose'ity
 - Epochs: number of training passes through the complete dataset
 - Batch size: number of datapoints to consider together when updating the network
- We pass through the input data as a numpy array (nsamples, 4)
- We pass the output as (nsamples, 3) where for each sample one of the positions is 1, corresponding to the correct class.
- We use the np.eye identity matrix creator to help us transform the raw species information (which labels classes setosa, virginica, versicolor) to the expected format
 - Setosa = (1, 0, 0)
 - Versicolor = (0, 1, 0)
 - Virginica = (0, 0, 1)
- We fit the model to a labelled dataset simply by calling fit with the dataset train_X and the true labels train_y

Evaluation

- After running the model, we can evaluate how well it works on the labelled test data we kept aside for overfitting evaluation purposes.
 - Overfitting is when the model fits to the training set in a way that doesn't generalize to unseen samples
 - One usually also has a separate validation set, use the test set on a single model, choose a model you like, then check the hyperparameters didn't cause bias by checking the validation

```
# The evaluation passes out the overall loss,
# as well as any other metrics you included
# when compiling the model
loss, accuracy = model.evaluate(test_X, test_y, verbose=0)
print("Loss={:.2f}\nAccuracy = {:.2f}".format(loss, accuracy))
Loss=0.11
```

Prediction

- And we can ask the model to predict some unlabelled data
 - For illustration, we just use our test data, and compare the true label against the 'prediction'
 - In the output, I stack the true answers (first rows), and the prediction, which can basically be interpreted as the model's probability for each category (second rows)

```
pred_y = model.predict(test_X)
print np.stack([test_y, pred_y], axis=1)[:10]
    0.00000000e+00
                    0.00000000e+00
                                    1.0000000e+001
    2.63856982e-05
                    8.96630138e-02
                                    9.10310626e-01]]
    0.00000000e+00 1.0000000e+00
                                    0.00000000e+001
    1.57812089e-02
                                    2.06995625e-0211
                    9.63519156e-01
    1.00000000e+00
                    0.00000000e+00
                                    0.0000000e+001
    9.96497989e-01
                    3.50204227e-03
                                    1.25929889e-0911
    0.00000000e+00
                    0.00000000e+00
                                    1.0000000e+001
    4.74178378e-05
                    1.32592529e-01
                                    8.67359996e-01]]
```

MNIST digit recognition and Convolutional Networks

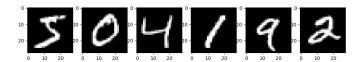
- Another, more recent, classic classification task.
- Given a 28x28 image of a handwritten digit, can you train a classifier to recognize the numbers from 0 to 9?
- Keras has the ability to download the dataset and parse it into numpy arrays. We use to_categorical to one hot encode the true labels (which number did they write?) as for the irises

Examples

- We can use matplotlib.pyplot to show a few example digits
- In jupyter, matplotlib results will show automatically, so you don't need to print it out (or resize it for that matter)

```
print x_train.shape, y_train_enc.shape
plt.clf()
for i in range(6):
    plt.subplot(1,6,i+1)
    plt.imshow(x_train[i], cmap='gray')

F = plt.gcf(); F.set_size_inches((14,2))
plt.savefig('mnist-examples.png'); 'mnist-examples.png'
```



Simple Network

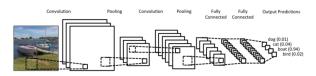
- We can start by simply trying a basic neural network as before.
- 'Flatten' takes the 2D input and concatenates the rows together to a 1D form suitable for passing to a 'Dense' layer.

Simple Network

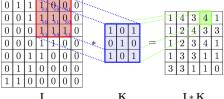
And fit and evaluate as we did before

```
model.fit(x_train, y_train_enc, epochs=3, verbose=1)
loss, accuracy = model.evaluate(x_test, y_test_enc, verbose=0)
print("Loss={:.2f}\nAccuracy = {:.2f}\".format(loss, accuracy))
Epoch 1/3
60000/60000 [=============] - 4s - loss: 0.5373 - acc: 0.8
Epoch 2/3
60000/60000 [============= ] - 4s - loss: 0.3729 - acc: 0.8
Epoch 3/3
60000/60000 [============= ] - 4s - loss: 0.3207 - acc: 0.9
Loss=0.30
Accuracy = 0.91
```

A Convolutional Network



- One of the great advances in image classification in recent times
- We have some filter kernel K of size $n \times m$ which we apply to every $n \times m$ cell on the original image to create a new filtered image.
- It has been seen that applying these in multiple layers of a network can build up multiple levels of abstraction to classify higher-level features.
 - And, importantly, is trainable many, many layers deep



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Reshaping data for Keras

- Convolution of this type in Keras is provided by the Conv2D layer
- Conv2D requires passing an array of width x height x channels
 - Where channels might represent colors of an image
- We have black and white images so we'll just reshape it into the required form with a single channel.
- We plot the image just check show the shaping is correct

```
x_train_dense = x_train.reshape((len(x_train), 28,28,1))
x_test_dense = x_test.reshape((len(x_test), 28,28,1))

plt.clf()
plt.imshow(x_train_dense[0,:,:,0], cmap="gray")
F = plt.gcf(): F.set_size_inches((2,2)); plt.savefig("testimg.png"); "testi
```

ML Tute



Building a Convolutional Neural Network in Keras

- Now, lets build a convolutional neural network!
- Generally, Conv2D will be stacked on top of each other with MaxPooling2D layers and learn edge detection at lower layers and higher level feature extraction in subsequent layers.
- But just to show how to use them in keras, we'll just create one convolution layer with 32 filters, then Flatten it into a 1D array and pass it into a Dense hidden layer before the output.
- We can set the kernel_size (m x n size of the filter), and the number of filters used

Building a Convolutional Neural Network in Keras

 We can set the kernel_size (m x n size of the filter), and the number of filters used

```
model = Sequential()
model.add(Conv2D(32, kernel_size=(3,3),input_shape=(28,28,1)))
model.add(Activation('relu'))
model.add(Flatten())
model.add(Dense(128))
model.add(Activation('sigmoid'))
model.add(Dense(10))
model.add(Activation('softmax'))
model.compile(optimizer='adam',
      loss='categorical_crossentropy',
```

metrics=['accuracy'])

Training

And train the model. This is already starting to get to the point where a GPU would be extremely helpful!

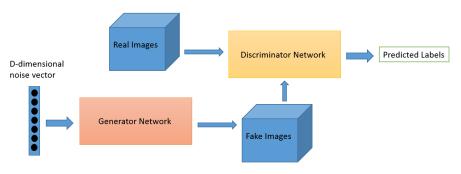
model.fit(x_train_dense, y_train_enc, epochs=4, verbose=1)

```
Epoch 1/4
60000/60000 [============= ] - 65s - loss: 0.4544 - acc: 0.
Epoch 2/4
60000/60000 [============= ] - 70s - loss: 0.1745 - acc: 0.
Epoch 3/4
60000/60000 [============] - 68s - loss: 0.1369 - acc: 0.
Epoch 4/4
<keras.callbacks.History object at 0x11d742390>
loss, accuracy = model.evaluate(x_test_dense, y_test_enc, verbose=0)
print("Loss={:.3f}\nAccuracy = {:.3f}".format(loss, accuracy))
```

Loss=0.117 Accuracy = 0.964

A Convolution GAN

- The idea is to train two adverserial networks,
 - One is trying to create images equivalent to the MNIST dataset
 - Given an input of noise, the latent space
 - The other trying to label the images as either from the dataset or fake
 - Fake = generated by the opposing dataset



- References:
 - For more on GANs and their uses: https://arxiv.org/pdf/1701.00160.pdf

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- Code based on: https://github.com/jacobgil/keras-dcgan
- Some tricks for training GANs https://github.com/soumith/ganhacks
 I.J. Watson (USeoul)
 ML Tute
 ML Workshop 7.9.2018

Idea: Image generator network

- We start with the image generation network
- Essentially a image classifier in reverse.
- The top layer is for high-level feature inputs which we'll randomly set during the training.
- We then pass through Dense layers and then reshape into a 7 x 7 x channels image-style layer.
- We Upsampling2D and pass through convolutional filters until the last layer which outputs a 28x28x1 image as expected of an MNIST greyscale image.
 - Essentially we're adding features as we go up, instead of extracting features as we go down
- BatchNormalization is a technique to improve the network stability by providing the next layer inputs with zero mean and unit variance

```
# Complete code for the generator model
nfeatures = 100
generate = Sequential()
generate.add(Dense(1024, input_dim=nfeatures))
generate.add(Activation('tanh'))
generate.add(Dense(128*7*7))
generate.add(BatchNormalization())
generate.add(Activation('tanh'))
generate.add(Reshape((7, 7, 128)))
generate.add(UpSampling2D(size=(2,2)))
generate.add(Conv2D(64, (5,5), padding='same'))
generate.add(Activation('tanh'))
generate.add(UpSampling2D(size=(2,2)))
generate.add(Conv2D(1, (5, 5), padding='same'))
generate.add(Activation('sigmoid'))
generate.compile(loss="binary_crossentropy", optimizer="SGD")
```

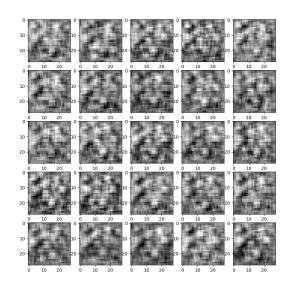
Generator Test

Now, just to check everythings put together properly, randomly pass some data through the network and check we get image outputs as expected.

```
nim = 25
pred = generate.predict(np.random.uniform(0, 1, (nim,nfeatures)))
plt.clf()
for i in range(nim):
    plt.subplot(np.sqrt(nim),np.sqrt(nim),i+1)
    plt.imshow(pred[i,:,:,0], cmap='gray')

pred[0].shape, np.average(pred[0])
F = plt.gcf(); F.set_size_inches((10,10)); plt.savefig("genimg_no.pp
```

Example images, pre-training



Discriminator

- Next, we create the discriminating network, with an image input
- As for classification, we have a convolutional layer attached to Dense layers.
- For the output, we now have a single sigmoid with interpretation:
 - 0: The network thinks its definitely a generated image
 - 1: The network thinks its definitely a real MNIST dataset image

```
# Complete code for the discriminator network
discr = Sequential()
discr.add(Conv2D(64, (5,5), input_shape=(28,28,1), padding='same'))
discr.add(Activation('tanh'))
discr.add(MaxPooling2D((2,2)))
discr.add(Conv2D(128, (5,5)))
discr.add(Activation('tanh'))
discr.add(MaxPooling2D((2,2)))
discr.add(Dropout(0.5))
discr.add(Flatten())
discr.add(Dense(1024))
discr.add(Activation('tanh'))
discr.add(Dense(1))
discr.add(Activation('sigmoid'))
discr.compile(loss='binary_crossentropy',
      optimizer=SGD(lr=0.0005, momentum=0.9, nesterov=True))
```

Test the discriminator

- Test the network with a few MNIST images and some random images.
- Since the network isn't trained we don't yet expect any differences in the output.

```
x_prepred = np.concatenate(
    [x_train[:5,:,:].reshape(5,28,28,1) / 256.,
    np.random.uniform(0, 1, (5, 28, 28, 1))], axis=0)
discr.predict(x_prepred)
```

GAN

- Now we set up a network which will be used to train the generation network.
- Keras allows us to simply add the models we just created together into a Sequential like they were ordinary layers.
- So, we feed the generator output into the discriminator input and set up an optimizer which will try to drive the generator to produce MNIST-like images (i.e. to fool the discriminator).
- Keras allows us to turn layer training on and off through the "trainable" variable attached to a layer, so when we train the generator we can easily turn training for the discriminator off.

Setup GAN

```
gen_discr = Sequential()
gen_discr.add(generate)
discr.trainable = False
gen_discr.add(discr)
gen_discr.compile(loss='binary_crossentropy',
    optimizer=SGD(lr=0.0005, momentum=0.9, nesterov=True),
    metrics=['accuracy'])
discr.trainable = True
```

Training the GAN

- Finally, we have the actual training
- Here, we setup the batches ourselves and alternate between training the discriminator and generator
 - model.train_on_batch
 - This was previously put together by Keras itself
- We start by taking a batch of MNIST images (labeled 1), and generator images (labeled 0) and run a training batch on the discriminator network
- Then, we turn off training off the discriminator and run training on the generator+discriminator network with random high-level feature inputs to the generator
- We try to drive all the outputs to 1, i.e. train the generator to more MNIST-like images (as according to the discriminator network)
- Last remark: we are saving the networks after each epoch with model.save
 - Load with keras.models.load_model

Training the GAN

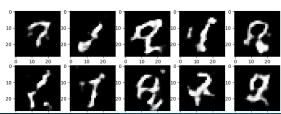
```
batch size = 100
n = pochs = 10
print every nth epoch = 50
x_tu_all = x_train.reshape(len(x_train), 28, 28, 1) / 256.
zeros = np.arrav([0]*batch size)
ones = np.array([1]*batch_size)
oneszeros = np.array([1]*batch_size + [0]*batch_size)
losses d = []
losses_g = []
for epoch in range(n epochs):
   print ("Epoch", epoch)
   discr.save("/discr-"+str(epoch))
    generate.save("/generate-"+str(epoch))
   for i in range(0, len(x train), batch size):
x_gen = generate.predict(np.random.uniform(0, 1, (batch_size, nfeatures)))
x_tru = x_tru_all[i:i+batch_size]
# Train the discriminator by taking example MNIST and generator-produced images
discr.trainable=True
loss_d = discr.train_on_batch(np.concatenate([x_tru, x_gen], axis=0), oneszeros)
# Now, turn discriminator training off, so we can train the generator
discr_trainable=False
loss_g = gen_discr.train_on_batch(np.random.uniform(0, 1, (batch_size, nfeatures)), ones)
if i % (print every nth epoch*batch size) == 0:
   print (i / batch_size, "discr", loss_d, "--", "gen", loss_g[0], "( acc.", loss_g[1], ")")
losses_g.append(loss_g)
losses_d.append(loss_d)
```

Checking results

Lets see how we did, lets just generate a bunch of images

```
nim = 25
pred = generate.predict(np.random.uniform(0, 1, (nim,nfeatures)))
plt.clf()
for i in range(nim):
    plt.subplot(np.sqrt(nim),np.sqrt(nim),i+1)
    plt.imshow(pred[i,:,:,0], cmap='gray')

pred[0].shape, np.average(pred[0])
F = plt.gcf(); F.set_size_inches((10,10)); plt.savefig("genimg_after.png"); "genimg")
```



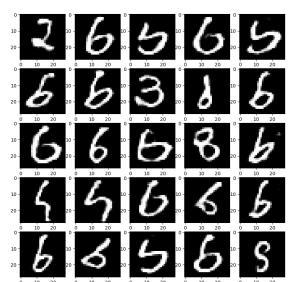
I.J. Watson (USeoul)

Good images

- Whats the "best" being produced by the GAN?
- Only accept above 0.9 from discriminator

```
nim = 25
target = .9
plt.clf()
for i in range(nim):
    best = 0; pred=None
    while best < target:
pred = generate.predict(np.random.uniform(0, 1, (1,nfeatures)))
best = discr.predict(pred)[0][0]
    plt.subplot(np.sqrt(nim).np.sqrt(nim).i+1)
    plt.imshow(pred[0,:,:,0], cmap='gray')

pred[0].shape, np.average(pred[0])
F = plt.gcf(); F.set_size_inches((10,10)); plt.savefig("genimg40_best.9.png"); "genimg40_best.9.png"</pre>
```



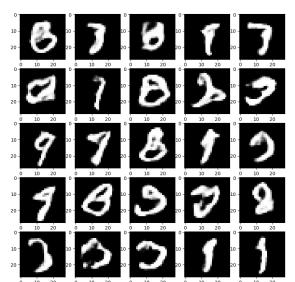
Bad images

- Whats the "worst" being produced by the GAN?
- Only accept below 0.1 from discriminator

```
nim = 25
target = .1

plt.clf()
for i in range(nim):
    best = 1; pred=None
    while best > target:
pred = generate.predict(np.random.uniform(0, 1, (1,nfeatures)))
best = discr.predict(pred)[0][0]
    plt.subplot(np.sqrt(nim),np.sqrt(nim),i+1)
    plt.imshow(pred[0,:,:,0], cmap='gray')

pred[0].shape, np.average(pred[0])
F = plt.gcf(); F.set_size_inches((10,10)); plt.savefig("genimg40_worst.1.png"); "genimg40_worst.1.png"
```



Extensions

- Try different networks, what works well, what fails badly?
- Add another set of inputs hot-one encoding the number you want to generate,
 - The discriminator will need to say which number it believes its seeing as well as how likely it is to be real
 - The generator will need to train with the number output as a loss also

Train requiring GAN to also output the correct number

```
nfeatures = 100
generate = Sequential()
generate.add(Dense(1024, input_dim=(nfeatures + 10)))
generate.add(Activation('tanh'))
generate.add(BatchNormalization())
generate.add(BatchNormalization())
generate.add(Activation('tanh'))
generate.add(UpSampling2D(size=(2,2)))
generate.add(Conv2D(64, (5,5), padding='same')))
generate.add(Conv2D(64, (5,5), padding='same')))
generate.add(Conv2D(1, (5, 5), padding='same')))
```

Create the Discriminator

Create the combined network

```
gen_discr = Sequential()
gen_discr .add(generate)
discr.trainable = False
gen_discr.compile(loss='categorical_crossentropy', optimizer=SGD(lr=0.0005, momentum=0.9, nesterov=True),
    # optimizer='adam',
    metrics=['accuracy'])
discr.trainable = True

batch_size = 100
n_epochs = 50
print_every_nth_epoch = 50
x_tru_all = x_train.reshape(len(x_train), 28, 28, 1) / 256.

zeros = np.array([0]*batch_size)
oneszeros = np.array([1]*batch_size)
oneszeros = np.array([1]*batch_size)
oneszeros = np.array([1]*batch_size)
```

Pre-train the discriminator on the (untrained) generator output and real MNIST

```
# pre train the gan to be able to distinguish numbers
pre_losses_d = []
for epoch in range(5):
    print ("Epoch", epoch)
    for i in range(0, len(x_train), batch_size):
one_hot_gen = np.eye(10)[np.random.random_integers(0, 9, size=(batch_size,))]
x_inp = np.concatenate([np.random.uniform(0, 1, (batch_size, nfeatures)), one_hot_gen], axis=1)
x_gen = generate.predict(x_inp)
x_tru = x_tru_all[i:i+batch_size]
v tru = v train enc[i:i+batch size]
discr trainable = True
for_d_tru = np.concatenate([np.zeros((batch_size,1)), y_tru], axis=1)
for d gen = np.concatenate([np.ones((batch size.1)), np.zeros((batch size.10))], axis=1)
loss d = discr.train on batch(np.concatenate([x tru, x gen], axis=0),
      np.concatenate([for_d_tru, for_d_gen], axis=0))
if i % (print every nth epoch*batch size) == 0:
    print (i / batch_size, "discr", loss_d)
pre_losses_d.append(loss_d)
loss, accuracy = discr.evaluate(x test dense,
np.concatenate([np.zeros((len(y_test_enc),1)), y_test_enc], axis=1), verbose=0)
print("Loss={:.3f}\nAccuracy = {:.3f}".format(loss, accuracy))
```

Train the generator and discriminator together

```
losses d = []
losses_g = []
for epoch in range(n epochs):
    print ("Epoch", epoch)
    discr.save("discr-num-"+str(epoch))
    generate.save("generate-num-"+str(epoch))
    for i in range(0, len(x train), batch size):
one_hot_gen = np.eye(10)[np.random.random_integers(0, 9, size=(batch_size,))]
x_inp = np.concatenate([np.random.uniform(0, 1, (batch_size, nfeatures)), one_hot_gen], axis=1)
x_gen = generate.predict(x_inp)
x_tru = x_tru_all[i:i+batch_size]
y_tru = y_train_enc[i:i+batch_size]
discr trainable = True
for_d_tru = np.concatenate([np.zeros((batch_size,1)), y_tru], axis=1)
for_d_gen = np.concatenate([np.ones((batch_size,1)), np.zeros((batch_size,10))], axis=1)
loss d = discr.train on batch(np.concatenate([x tru, x gen], axis=0),
      np.concatenate([for d tru, for d gen], axis=0))
discr.trainable=False
for_g = np.concatenate([np.zeros((batch_size,1)), one_hot_gen], axis=1)
new inp g = np.concatenate([np.random.uniform(0, 1, (batch size, nfeatures)), one hot gen], axis=1)
loss_g = gen_discr.train_on_batch(new_inp_g, for_g)
if i % (print_every_nth_epoch*batch_size) == 0:
    print (i / batch_size, "discr", loss_d, "--", "gen", loss_g[0], "( acc.", loss_g[1], ")")
losses g.append(loss g)
losses_d.append(loss_d)
print ("done")
```

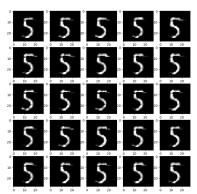
Check the output of the labelled GAN

```
# generate = tf.keras.models.load_model('generate-num-41')
nim = 25
numb = 1
pred = generate.predict(np.concatenate([np.random.uniform(0, 1, (nim,nfeatures)), np.eye(10)[[numb,]*nim]], ax
plt.clf()
for i in range(nim):
    plt.subplot(np.sqrt(nim),np.sqrt(nim),i+1)
    plt.imshow(pred[i,:,:,0], cmap='gray')

pred[0].shape, np.average(pred[0])
F = plt.gcf(); F.set_size_inches((10,10)); plt.savefig("gen-num-img_after-%d.png" % numb); "gen-num-img_after-%d.png" % numb); "gen-num-img_after-%d
```

Some examples from labelled GAN





Backup