

# CS 457, Fall 2019

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Drexel University, Department of Computer Science

Lecture 12



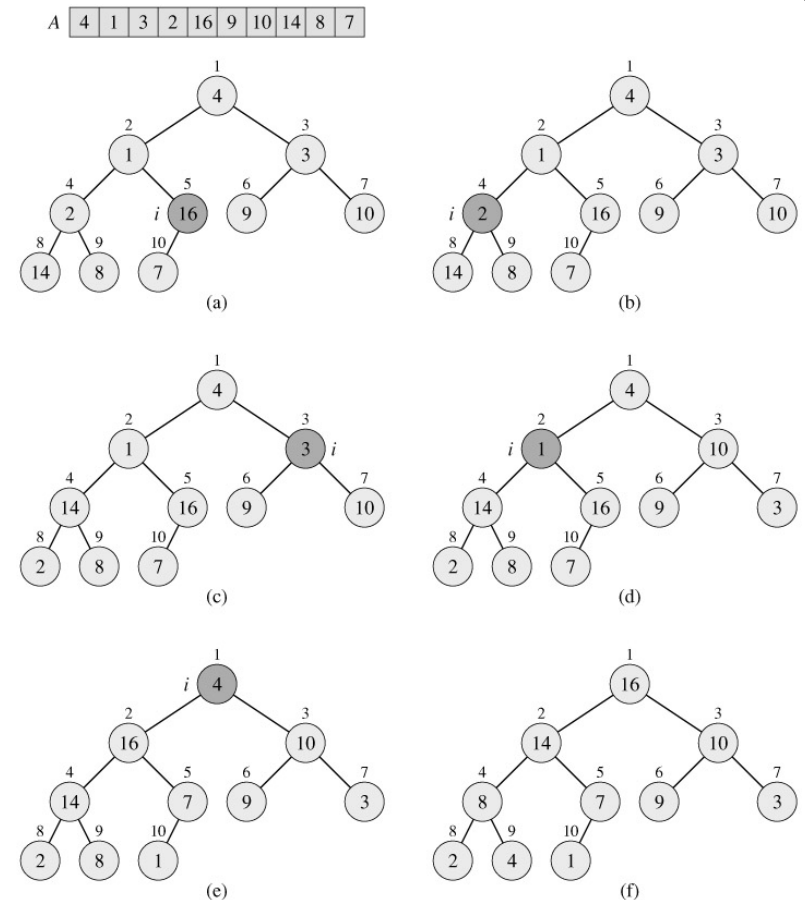
# Build-Max-Heap

## Build-Max-Heap (A)

1.  $A.\text{heap-size} = A.\text{length}$
2. **for**  $i = \lfloor A.\text{length}/2 \rfloor$  **down to** 1
3.      $\text{Max-Heapify}(A, i)$

What is the running time of Build-Max-Heap?

$$T(n) = \sum_{h=0}^{\lfloor \log n \rfloor} \left\lfloor \frac{n}{2^{h+1}} \right\rfloor O(h) = O\left(n \sum_{h=0}^{\lfloor \log n \rfloor} \frac{h}{2^h}\right) = O(n)$$

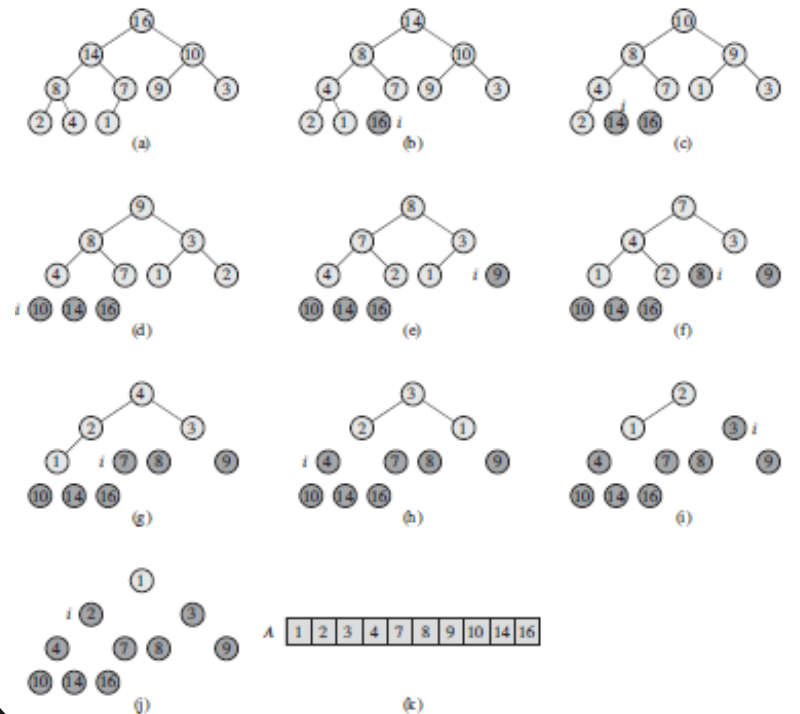




# Heapsort

## Heapsort(A)

1. Build-Max-Heap(A)
2. **for**  $i = A.length$  **down to** 2
3.     exchange  $A[1]$  with  $A[i]$
4.      $A.heap\text{-}size = A.heap\text{-}size - 1$
5.     Max-Heapify(A,1)





# Binary Trees and Induction

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- Binary trees play a major role in computer science
  - E.g., heaps, binary search trees, red-black trees
  - It is important to have good intuition regarding their properties
- What is a **complete** (rooted) binary tree?
  - A binary tree in which all leaves have the same depth.
  - How many **leaves** does a complete binary tree of height  $h$  have?  $2^h$
  - How many **nodes** does a complete binary tree of height  $h$  have?  $2^{h+1} - 1$
  - Can you prove this using **induction**?
- What is a **full** (rooted) binary tree?
  - A binary tree in which every node is either a leaf or has degree exactly 2.
  - How many **leaves** does a full binary tree with  $n$  nodes have?
  - Show that there are at most  $\lceil n/2^{h+1} \rceil$  nodes of height  $h$  in any  $n$ -node full binary tree



# Today's Lecture

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- Binary trees (remember to read through Appendix B!)
  - Structural induction
  - Search trees
- Dynamic programming



# Structural Induction Problem

**Question:** A rooted binary tree is a rooted tree in which each node has at most two children. A node of a tree is full if it contains a non-empty left child and a non-empty right child. Prove, using induction, that for any rooted binary tree, the number of full nodes is one less than the number of leaves.

**Solution:** For the base case, we consider the set of trees with 1 node. Clearly, there exists only one such tree that comprises of a single node and no edges. For this tree, the number of leaves is 1 and the number of full nodes is 0, so the number of full nodes is indeed exactly one less than the number of leaves in this case.

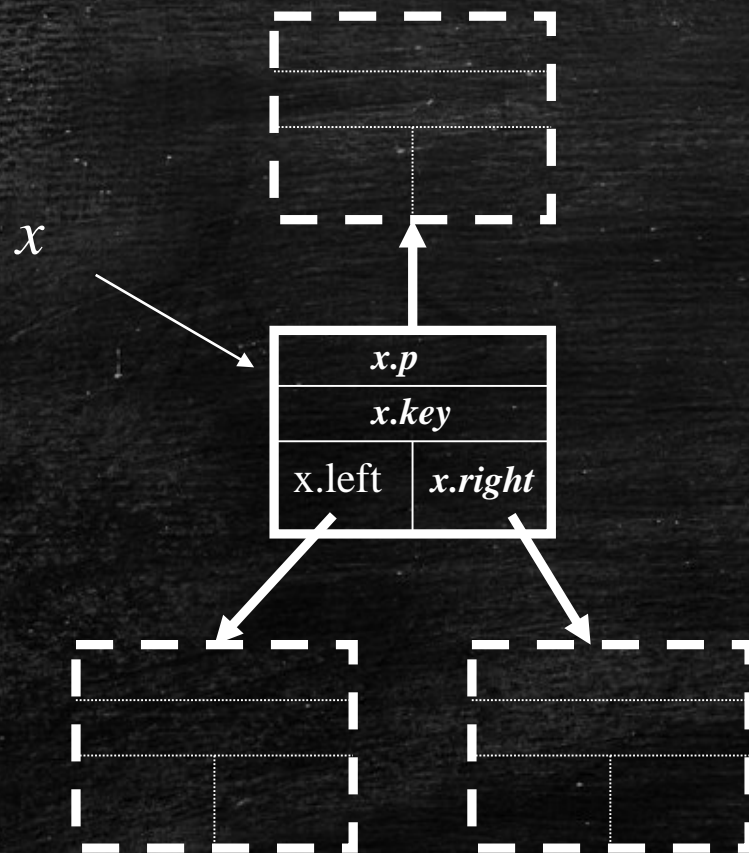
For the inductive step, we assume that for every rooted binary tree of size  $n \geq 1$  the number of nodes with two children is exactly one less than the number of leaves, and our goal is to show that the same is true for *every* rooted binary tree of size  $n + 1$ . To prove this step, consider *any* possible rooted binary tree  $T$  of size  $n + 1$ , and remove one of its leaves, which reduces it to a tree  $T'$  of  $n$  nodes. If  $\ell$  is the number of leaves of  $T'$ , then we know, by our inductive hypothesis, that the number full nodes of  $T'$  is exactly  $\ell - 1$ . The leaf that we removed must have either been an only child of its parent, or one of two children. We consider both possibilities below.

- If the leaf that we removed was the only child of its parent, then its removal did not affect the number of full nodes and it did not affect the number of leaves either, since it removed a leaf and transformed its parent into one. Therefore, the number of leaves in  $T$  must have been  $\ell$  as well, and the number of full nodes of  $T$  must have been  $\ell - 1$ , which is consistent with the statement that we are trying to prove.
- If, on the other hand, the leaf that we removed was the second child of its parent, then its removal decreased the number of leaves by one, but it also decreased the number of full nodes by one as well. Therefore, the number of leaves in the initial tree was  $\ell + 1$  and the number of full nodes was  $\ell$ , which is once again consistent with the statement that we are trying to prove.



# Binary Search Trees

- Each node  $x$  in a binary search tree (BST) contains:



- $x.key$  - The value stored at  $x$
- $x.left$  - Pointer to left child of  $x$
- $x.right$  - Pointer to right child of  $x$
- $x.p$  - Pointer to parent of  $x$



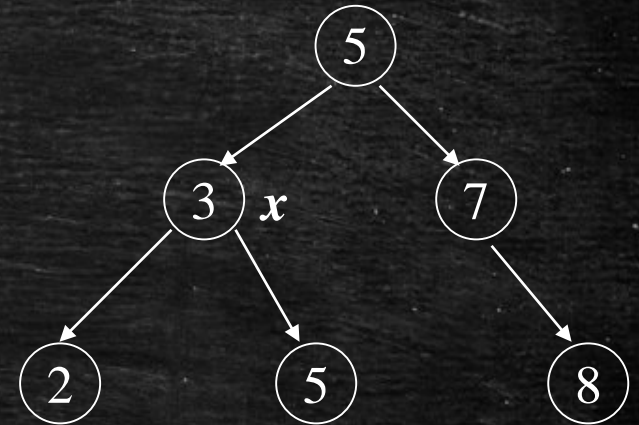
# Binary Search Tree Property

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- Keys in BST satisfy the following properties:

Let  $x$  be a node in a BST:

- If  $y$  is in the left subtree of  $x$  then:  
 $y.key \leq x.key$
- If  $y$  is in the right subtree of  $x$  then:  
 $y.key > x.key$

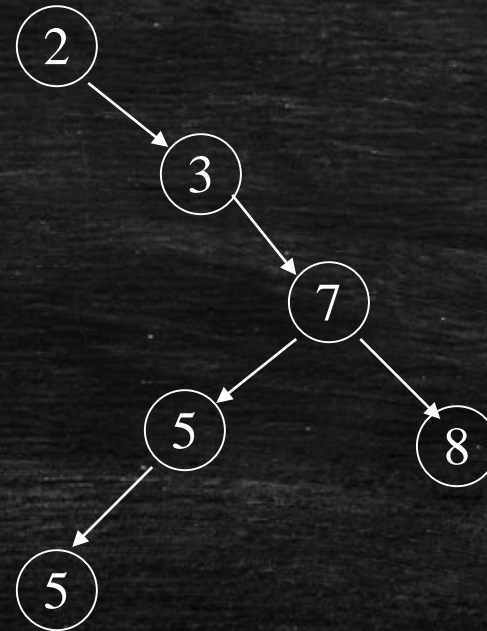
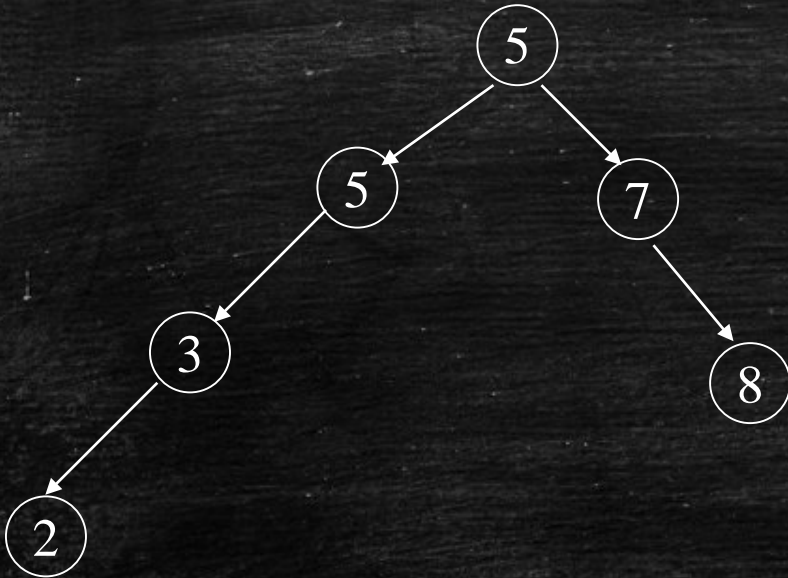




# Binary Search Tree Examples

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- Two valid BST's for the keys: 2,3,5,5,7,8





# Searching in BST

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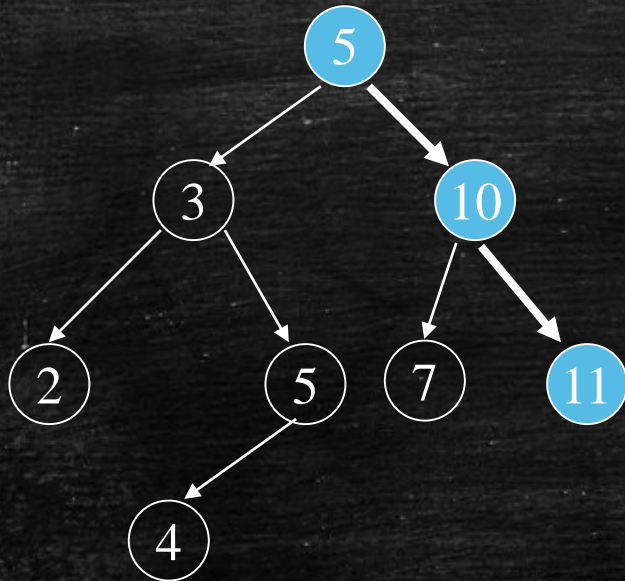
- To find element with key  $k$  in tree  $T$ :
  - Compare  $k$  with the root
  - If  $k < \text{key}[\text{root}[T]]$  search for  $k$  in left subtree
  - Otherwise, search for  $k$  in right subtree

```
Search( $T, k$ )  
   $x = \text{root}[T]$   
  if  $x == \text{NIL}$   
    return("not found")  
  if  $k == \text{key}[x]$   
    return("found the key")  
  if  $k < \text{key}[x]$   
    Search( $\text{left}[x], k$ )  
  else  
    Search( $\text{right}[x], k$ )
```

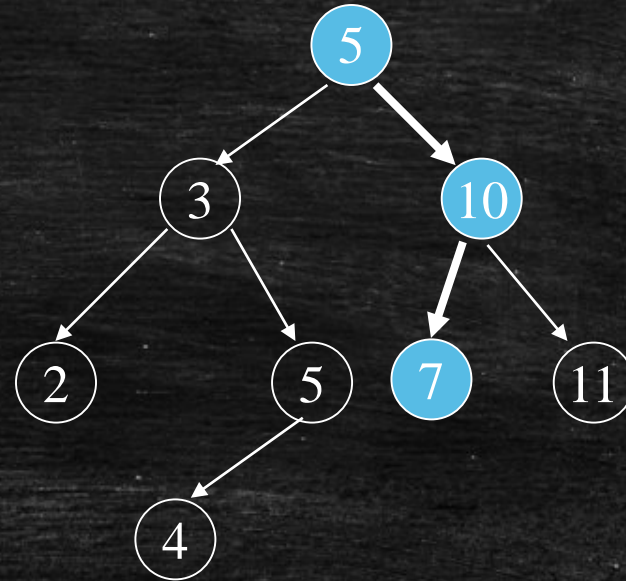


## Examples:

- $\text{Search}(T, 11)$



- $\text{Search}(T, 6)$

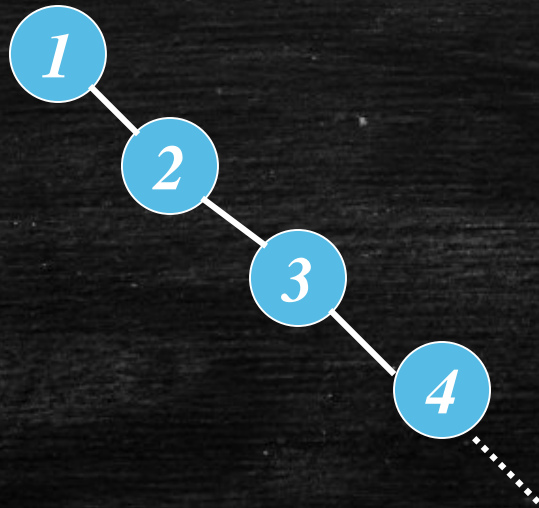




# Analysis of Search

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- Running time of search for a tree of height  $h$  is  $O(h)$
- After insertion of  $n$  keys, worst case running time of search is  $O(n)$
- One could bound **expected height** of binary search trees





# Red-black Trees

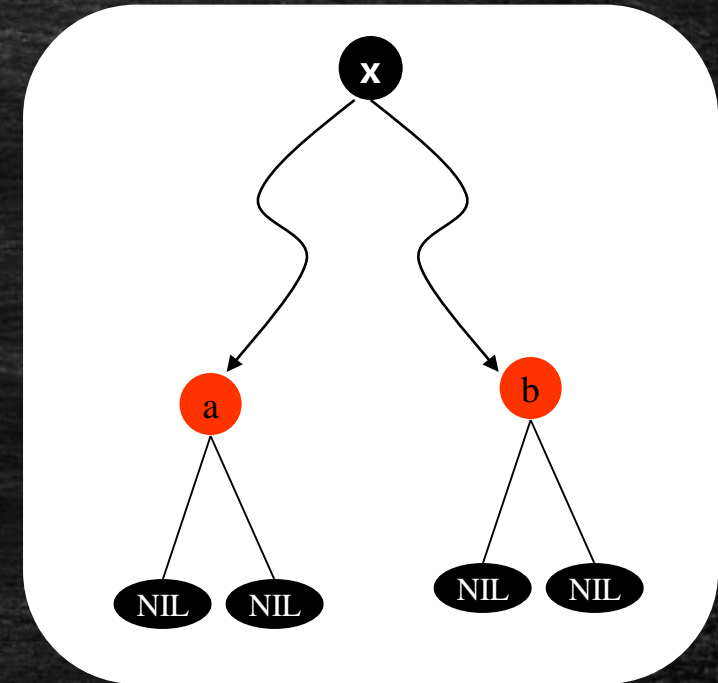
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- They are **balanced search trees** (their height is  $O(\log n)$ )
- Most of the search and update operations on these trees take  **$O(\log n)$  time**
- The structure is **well balanced**, i.e., each subtree is a balanced search tree.



# Red-black Trees

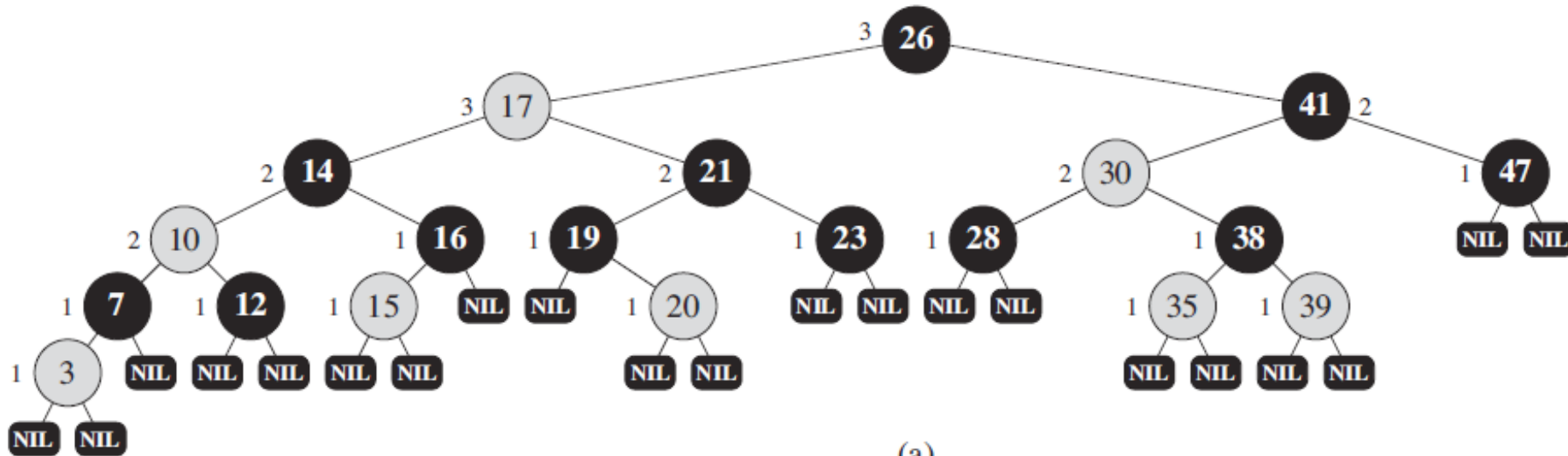
1. Every node is either red or black
2. The root is black
3. Every leaf (NIL) is black
4. If a node is red, both its children are black
5. All paths from a node  $x$  to a leaf have same number of black nodes (Black-Height( $x$ ))





# Example

- A red-black tree with  $n$  keys has height at most  $2 \log(n + 1)$
- Proof (Intuition): Merge the red nodes into their parents





# Divide and Conquer

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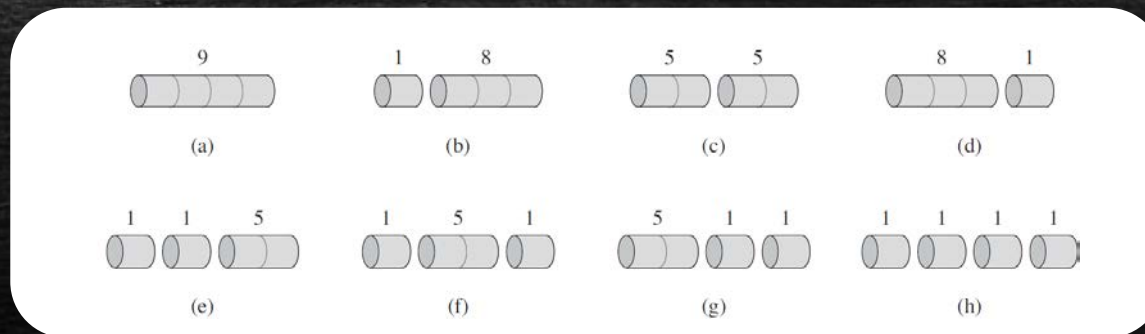
- **Divide and conquer** algorithm design approach
  - Divide the problem into smaller instances of same problem
  - Conquer the subproblems by solving them recursively until small enough
  - Combine solutions of the subproblems into solution for original problem
- We can analyze the running time using **recurrence equations**
  - E.g., for merge-sort:  $T(n) = 2T(n/2) + n$  and  $T(n) = 1$  for  $n \leq 2$
  - We can solve such equations using master theorem, recursion-tree, or substitution method
- What about the recurrence equation for **Fibonacci numbers**?
  - $F_0 = 0, F_1 = 1$ , and  $F_i = F_{i-1} + F_{i-2}$  for  $i \geq 2$
  - $T(n) = T(n-1) + T(n-2) + 1$
  - This leads to  $T(n) = \Theta(2^n)$ . Can we do better than that?



# Dynamic Programming

- **Rod Cutting** Problem

- Given a rod of length  $n$  inches and a table of prices  $p_i$  for each  $i = 1, \dots, n$  (price of a rod of  $i$  inches), determine the maximum revenue  $r_n$  obtainable by cutting up the rod and selling it in pieces.
- E.g., say that the rod length is  $n=4$  inches and the prices are  $p_1=1$ ,  $p_2=5$ ,  $p_3=8$ , and  $p_4=9$



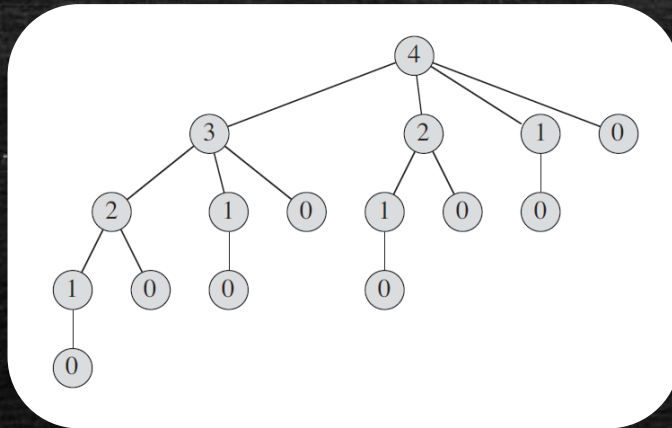
- What would be a natural **greedy algorithm** for this problem?
  - Cutting a piece of size  $i$  with the largest  $p_i/i$  ratio and continue in the remaining rod of length  $n-i$
  - Show that this algorithm does not always return the optimal solution
- $r_n = \max(p_n, r_1 + r_{n-1}, \dots, r_{n-1} + r_1)$
- $r_n = \max_{1 \leq i \leq n} (p_i, r_{n-i})$



# Dynamic Programming

- **Rod Cutting Problem**

- What does the recursion tree look like for divide & conquer using equation  $r_n = \max_{1 \leq i \leq n} (p_i, r_{n-i})$ ?



CUT-ROD( $p, n$ )

```
1  if  $n == 0$ 
2      return 0
3   $q = -\infty$ 
4  for  $i = 1$  to  $n$ 
5       $q = \max(q, p[i] + \text{CUT-ROD}(p, n - i))$ 
6  return  $q$ 
```

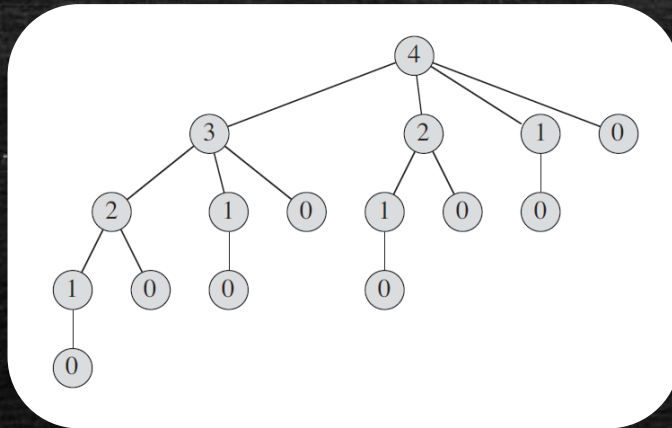
- No need to compute  $r_i$  again and again!



# Dynamic Programming

- **Rod Cutting Problem**

- What does the recursion tree look like for **divide & conquer** using equation  $r_n = \max_{1 \leq i \leq n} (p_i, r_{n-i})$ ?



MEMOIZED-CUT-ROD-AUX( $p, n, r$ )

```
1 if  $r[n] \geq 0$ 
2   return  $r[n]$ 
3 if  $n == 0$ 
4    $q = 0$ 
5 else  $q = -\infty$ 
6   for  $i = 1$  to  $n$ 
7      $q = \max(q, p[i] + \text{MEMOIZED-CUT-ROD-AUX}(p, n - i, r))$ 
8    $r[n] = q$ 
9   return  $q$ 
```

Initially all the values in  $r$  are negative

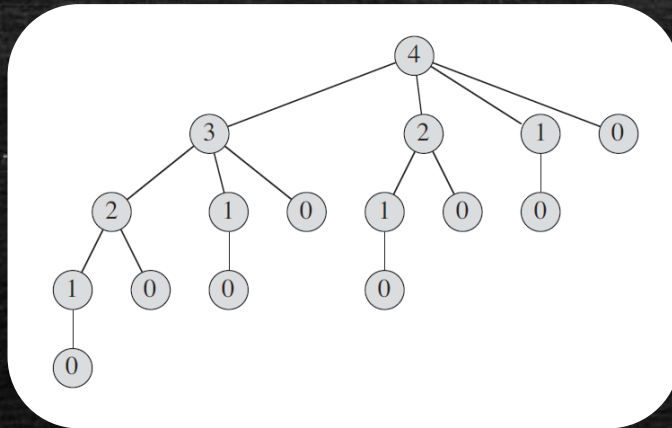
- No need to compute  $r_i$  again and again!
- Approach 1: **top-down** with **memoization** (save as you go)



# Dynamic Programming

- **Rod Cutting Problem**

- What does the recursion tree look like for **divide & conquer** using equation  $r_n = \max_{1 \leq i \leq n} (p_i, r_{n-i})$ ?



## BOTTOM-UP-CUT-ROD( $p, n$ )

```
1  let  $r[0..n]$  be a new array
2   $r[0] = 0$ 
3  for  $j = 1$  to  $n$ 
4       $q = -\infty$ 
5      for  $i = 1$  to  $j$ 
6           $q = \max(q, p[i] + r[j - i])$ 
7       $r[j] = q$ 
8  return  $r[n]$ 
```

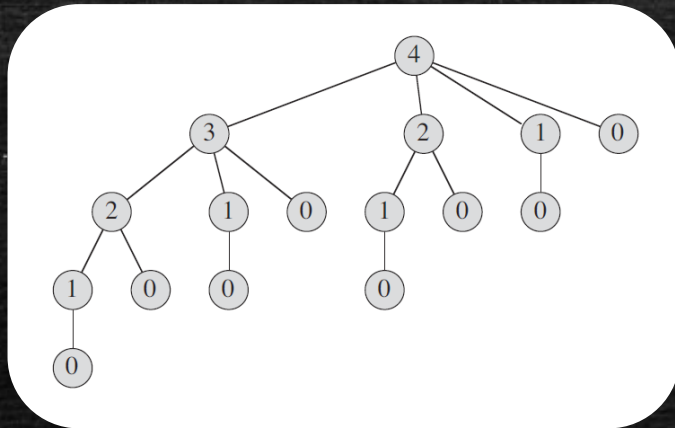
- No need to compute  $r_i$  again and again!
- Approach 1: **top-down** with **memoization** (save as you go)
- Approach 2: **bottom-up** (save from small to big subproblems)



# Dynamic Programming

- **Rod Cutting Problem**

- What does the recursion tree look like for **divide & conquer** using equation  $r_n = \max_{1 \leq i \leq n} (p_i, r_{n-i})$ ?



- No need to compute  $r_i$  again and again!
- Approach 1: **top-down** with **memoization** (save as you go)
- Approach 2: **bottom-up** (save from small to big subproblems)
- We can represent the dependence using the **subproblem graph**:
- To **reconstruct a solution**, we can keep track of the optimal choice in each case

