

```
import matplotlib.pyplot as plt
import math
```

```
W = 0
THETA = 1
TIME = 2
N = 2000
```

```
def main(problem=0, F=0):
    if(problem == 3.3):
        for i in range(0, N):
            w_i = data[i][W] - (g/l)*data[i][THETA]*dt
             $\theta_i$  = data[i][THETA] + w_i * dt
            t_i = data[i][TIME] + dt
            data[i + 1] = [w_i,  $\theta_i$ , t_i]
    else:
        for i in range(0, N):
            w_i = data[i][W] + (-(g/l) * math.sin(data[i][THETA]) -
                                q*data[i][W] + F * math.sin( $\Omega$  * data[i][TIME])) * dt
             $\theta_i$  = data[i][THETA] + w_i * dt
            if( $\theta_i$  < -math.pi):
                 $\theta_i$  =  $\theta_i$  + 2*math.pi
            elif( $\theta_i$  > math.pi):
                 $\theta_i$  =  $\theta_i$  - 2*math.pi

            t_i = data[i][TIME] + dt
            data[i + 1] = [w_i,  $\theta_i$ , t_i]
```

```
def plot(x, y, title, labelx, labely, style='-', legendLabel=FileNotFoundError):
    if(labelx is not None):
        plt.xlabel(labelx)
    if(labely is not None):
        plt.ylabel(labely)
    if(title is not None):
        plt.title(title)
    line = plt.plot(x, y, style, label=legendLabel, color='k')
    if(legendLabel is not None):
        plt.legend()
    return line
```

```
if __name__ == '__main__':
     $\omega$  = 0
     $\theta$  = 0.2
    t = 0
    g = 9.8
    l = 1
    dt = 0.04
```

```
# Amplitude
F = [0, 0.5, 1.2]
# Angular Frequency
 $\Omega$  = (2/3)
# strength of damping
```

```

q = 0.5
# the mass
m = 1

data = dict()
data[0] = [ $\omega$ ,  $\theta$ , t]
main(problem=3.3)

radians = []
time = []
for key in data.keys():
    radians.append(data[key][THETA])
    time.append(data[key][TIME])
plot(time, radians, "Simple Pendulum - Euler-Cromer method", "times (s)",
      " $\theta$  (Radians)", legendLabel="Length = "+str(l)+" m time step = "+str(dt)+"s")
plt.xlim([0, 10])
plt.ylim([-0.3, 0.3])
plt.show()

# Change the initial value of the length
l = 9.8

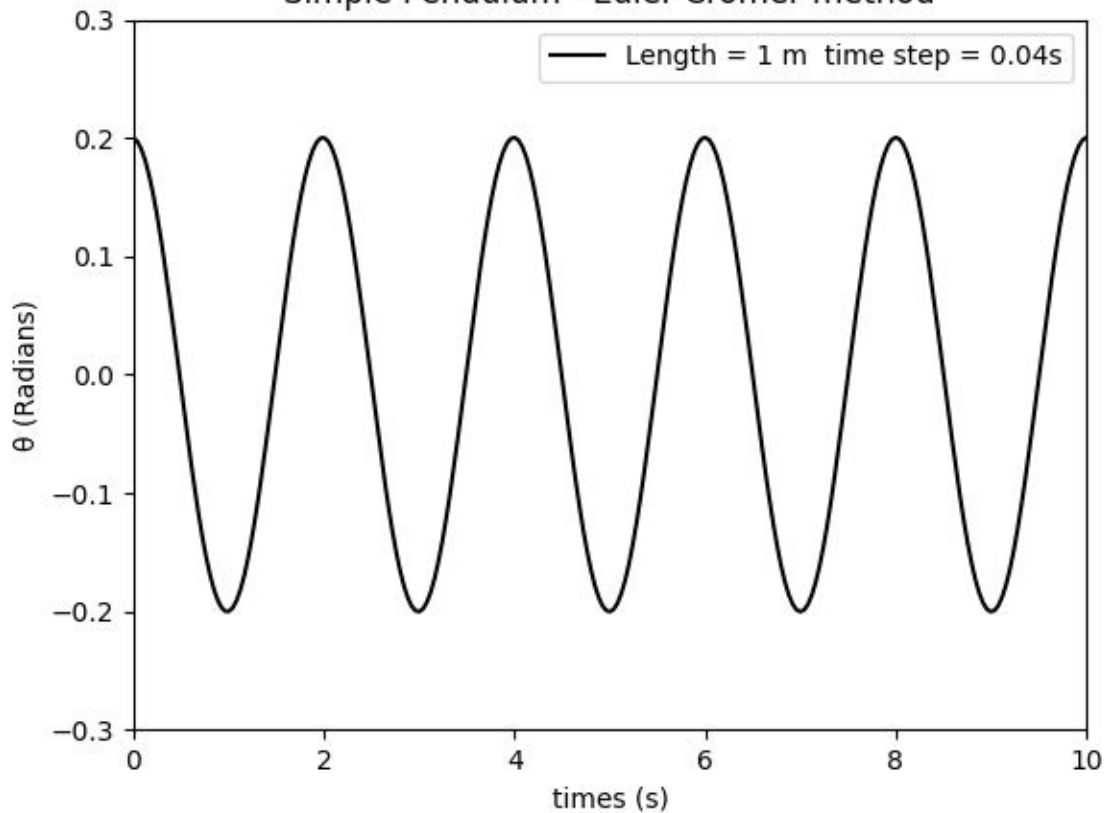
fig = plt.figure()
gs = fig.add_gridspec(3, hspace=0)
axs = gs.subplots(sharex=True, sharey=False)

i = 0
for damping in F:
    data.clear()
    data[0] = [ $\omega$ ,  $\theta$ , t]
    main(problem=3.6, F=damping)

    w_list = []
    time = []
    for key in data.keys():
        w_list.append(data[key][W])
        time.append(data[key][TIME])
    axs[i].plot(time, w_list, '-i', color='k')
    i = i + 1
axs[0].text(40, 0.03, 'FD = 0', style='italic', color="black")
axs[1].text(44.4, -0.6, 'FD = 0.5', style='italic', color="black")
axs[2].text(44, -1.3, 'FD = 1.2', style='italic', color="black")
axs[1].set_ylabel('ω (radians/s)')
plt.xlabel('time (s)')
plt.xlim([0, 60])
axs[0].set_title('ω versus time')
plt.show()

```

# Simple Pendulum - Euler-Cromer method



$\omega$  versus time

