

Privacy in Statistics and Machine Learning  
In-class Exercises for Lecture 15 (Multiplicative Weights)  
March 23, 2021

Spring 2021

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*Problems with marked with an asterisk (\*) are more challenging or open-ended.*

1. **(Online Learning Requires Randomization)** Show that every method that plays deterministic actions (where  $\mathbf{p}^t$  puts probability 1 on a single action) there is an adversary for which the regret is  $\Omega(T)$ .
2. **( $\sqrt{\ln(k)/T}$  lower bound)** Show that for any method (randomized or not), if the adversary picks cost vectors uniformly at random in  $\{0, 1\}^k$ , the expected regret will be  $\Theta(\sqrt{\ln(k)/T})$ . (*Hint: The expected cost paid by the algorithm is exactly  $T/2$ . Show that in hindsight, with probability at least  $1/2$ , one of the choices will have cost less than  $\frac{T}{2} - \Omega(\sqrt{T \ln(k)})$ .)*  
This means that the guarantee obtained by multiplicative weights is tight, in general.
3. **(MW with a perfect action)** Suppose we know ahead of time that there is a perfect choice  $a^*$  that always has cost 0. Show that we can set  $\eta$  so that the algorithm achieves total cost at most  $2 \ln(k)$ . (Be careful: our proof required  $\eta$  to be at most  $1/2$ .)
4. **(\*)** Show that if we know  $OPT$  ahead of time, we can set  $\eta$  to get an average cost of at most  $\frac{OPT}{T} + \frac{2}{T} \sqrt{\ln(k) \cdot \max(OPT, \ln(k))}$ .
5. Theorem 3.1 requires us to know the number of steps  $T$  ahead of time. Show that one can modify the algorithm to adapt automatically to the length of the process. Specifically, there is a standard trick known as “repeated doubling”: we start the algorithm assuming we will run for  $T_0 = 4 \ln(k)$  steps. If the number of steps exceeds  $T_0$ , we restart the algorithm assuming a length of  $T_1 = 2T_0$ . If the number of steps exceeds  $T_0 + T_1$ , we expand our time horizon to  $T_2 = 2T_1$ , and so on. Show that this variation achieves average regret  $O(\sqrt{\ln(k)/T})$  of  $T$  (without knowing  $T$ ).
6. How important is the fact that probabilities of higher-cost actions be selected with exponentially small probability? Consider an algorithm that, at each time  $t$ , selects action  $a$  with probability that scales polynomially in its cost so far  $c_a^{<t}$ . Specifically, suppose  $p_a^t = \frac{1}{1+c_a^{<t}}$ . Show a sequence of cost vectors on which the algorithm has expected average regret at least  $\Omega(k/T)$  (one can actually prove a stronger bound).