

# Segmentation\_Assignment\_Implementation\_canet(2)

April 22, 2021

## 1 Segmentation of Indian Traffic

```
[1]: from google.colab import drive
drive.mount('/content/drive')
```

Mounted at /content/drive

```
[ ]: # # !mkdir data/output
# # !unzip data.zip
# # !rm -rf data
```

```
[2]: # !pip install tensorflow==2.3.0
# !pip uninstall keras
# !pip install -U segmentation-models
```

Collecting tensorflow==2.3.0

Downloading [https://files.pythonhosted.org/packages/16/89/f2d29c2eafc2eeafb17d5634340e06366af904d332341200a49d954bce85/tensorflow-2.3.0-cp37-cp37m-manylinux2010\\_x86\\_64.whl](https://files.pythonhosted.org/packages/16/89/f2d29c2eafc2eeafb17d5634340e06366af904d332341200a49d954bce85/tensorflow-2.3.0-cp37-cp37m-manylinux2010_x86_64.whl) (320.4MB)

| 320.4MB 56kB/s

Requirement already satisfied: opt-einsum>=2.3.2 in

/usr/local/lib/python3.7/dist-packages (from tensorflow==2.3.0) (3.3.0)

Requirement already satisfied: protobuf>=3.9.2 in /usr/local/lib/python3.7/dist-packages (from tensorflow==2.3.0) (3.12.4)

Requirement already satisfied: wrapt>=1.11.1 in /usr/local/lib/python3.7/dist-packages (from tensorflow==2.3.0) (1.12.1)

Requirement already satisfied: absl-py>=0.7.0 in /usr/local/lib/python3.7/dist-packages (from tensorflow==2.3.0) (0.12.0)

Requirement already satisfied: astunparse==1.6.3 in /usr/local/lib/python3.7/dist-packages (from tensorflow==2.3.0) (1.6.3)

Requirement already satisfied: h5py<2.11.0,>=2.10.0 in /usr/local/lib/python3.7/dist-packages (from tensorflow==2.3.0) (2.10.0)

Requirement already satisfied: scipy==1.4.1 in /usr/local/lib/python3.7/dist-packages (from tensorflow==2.3.0) (1.4.1)

Requirement already satisfied: wheel>=0.26 in /usr/local/lib/python3.7/dist-packages (from tensorflow==2.3.0) (0.36.2)

Requirement already satisfied: tensorboard<3,>=2.3.0 in

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/usr/local/lib/python3.7/dist-packages (from tensorflow==2.3.0) (2.4.1)
Requirement already satisfied: six>=1.12.0 in /usr/local/lib/python3.7/dist-
packages (from tensorflow==2.3.0) (1.15.0)
Requirement already satisfied: termcolor>=1.1.0 in
/usr/local/lib/python3.7/dist-packages (from tensorflow==2.3.0) (1.1.0)
Collecting tensorflow-estimator<2.4.0,>=2.3.0
  Downloading https://files.pythonhosted.org/packages/e9/ed/5853ec0ae380cb
a4588eab1524e18ece1583b65f7ae0e97321f5ff9dfd60/tensorflow_estimator-2.3.0-py2.py
3-none-any.whl (459kB)
    |                                     | 460kB 53.2MB/s
Requirement already satisfied: gast==0.3.3 in
/usr/local/lib/python3.7/dist-packages (from tensorflow==2.3.0) (0.3.3)
Requirement already satisfied: keras-preprocessing<1.2,>=1.1.1 in
/usr/local/lib/python3.7/dist-packages (from tensorflow==2.3.0) (1.1.2)
Collecting numpy<1.19.0,>=1.16.0
  Downloading https://files.pythonhosted.org/packages/d6/c6/58e517e8b1fb19
2725cfa23c01c2e60e4e6699314ee9684a1c5f5c9b27e1/numpy-1.18.5-cp37-cp37m-manylinux
1_x86_64.whl (20.1MB)
    |                                     | 20.1MB 166kB/s
Requirement already satisfied: grpcio>=1.8.6 in
/usr/local/lib/python3.7/dist-packages (from tensorflow==2.3.0) (1.32.0)
Requirement already satisfied: google-pasta>=0.1.8 in
/usr/local/lib/python3.7/dist-packages (from tensorflow==2.3.0) (0.2.0)
Requirement already satisfied: setuptools in /usr/local/lib/python3.7/dist-
packages (from protobuf>=3.9.2->tensorflow==2.3.0) (54.2.0)
Requirement already satisfied: google-auth<2,>=1.6.3 in
/usr/local/lib/python3.7/dist-packages (from
tensorflow<3,>=2.3.0->tensorflow==2.3.0) (1.28.1)
Requirement already satisfied: markdown>=2.6.8 in /usr/local/lib/python3.7/dist-
packages (from tensorflow<3,>=2.3.0->tensorflow==2.3.0) (3.3.4)
Requirement already satisfied: google-auth-oauthlib<0.5,>=0.4.1 in
/usr/local/lib/python3.7/dist-packages (from
tensorflow<3,>=2.3.0->tensorflow==2.3.0) (0.4.4)
Requirement already satisfied: werkzeug>=0.11.15 in
/usr/local/lib/python3.7/dist-packages (from
tensorflow<3,>=2.3.0->tensorflow==2.3.0) (1.0.1)
Requirement already satisfied: tensorboard-plugin-wit>=1.6.0 in
/usr/local/lib/python3.7/dist-packages (from
tensorflow<3,>=2.3.0->tensorflow==2.3.0) (1.8.0)
Requirement already satisfied: requests<3,>=2.21.0 in
/usr/local/lib/python3.7/dist-packages (from
tensorflow<3,>=2.3.0->tensorflow==2.3.0) (2.23.0)
Requirement already satisfied: cachetools<5.0,>=2.0.0 in
/usr/local/lib/python3.7/dist-packages (from google-
auth<2,>=1.6.3->tensorflow<3,>=2.3.0->tensorflow==2.3.0) (4.2.1)
Requirement already satisfied: rsa<5,>=3.1.4; python_version >= "3.6" in
/usr/local/lib/python3.7/dist-packages (from google-
auth<2,>=1.6.3->tensorflow<3,>=2.3.0->tensorflow==2.3.0) (4.7.2)

```

Requirement already satisfied: pyasn1-modules>=0.2.1 in /usr/local/lib/python3.7/dist-packages (from google-auth<2,>=1.6.3->tensorboard<3,>=2.3.0->tensorflow==2.3.0) (0.2.8)

Requirement already satisfied: importlib-metadata; python\_version < "3.8" in /usr/local/lib/python3.7/dist-packages (from markdown>=2.6.8->tensorboard<3,>=2.3.0->tensorflow==2.3.0) (3.10.1)

Requirement already satisfied: requests-oauthlib>=0.7.0 in /usr/local/lib/python3.7/dist-packages (from google-auth-oauthlib<0.5,>=0.4.1->tensorboard<3,>=2.3.0->tensorflow==2.3.0) (1.3.0)

Requirement already satisfied: chardet<4,>=3.0.2 in /usr/local/lib/python3.7/dist-packages (from requests<3,>=2.21.0->tensorboard<3,>=2.3.0->tensorflow==2.3.0) (3.0.4)

Requirement already satisfied: idna<3,>=2.5 in /usr/local/lib/python3.7/dist-packages (from requests<3,>=2.21.0->tensorboard<3,>=2.3.0->tensorflow==2.3.0) (2.10)

Requirement already satisfied: certifi>=2017.4.17 in /usr/local/lib/python3.7/dist-packages (from requests<3,>=2.21.0->tensorboard<3,>=2.3.0->tensorflow==2.3.0) (2020.12.5)

Requirement already satisfied: urllib3!=1.25.0,!1.25.1,<1.26,>=1.21.1 in /usr/local/lib/python3.7/dist-packages (from requests<3,>=2.21.0->tensorboard<3,>=2.3.0->tensorflow==2.3.0) (1.24.3)

Requirement already satisfied: pyasn1>=0.1.3 in /usr/local/lib/python3.7/dist-packages (from rsa<5,>=3.1.4; python\_version >= "3.6"->google-auth<2,>=1.6.3->tensorboard<3,>=2.3.0->tensorflow==2.3.0) (0.4.8)

Requirement already satisfied: typing-extensions>=3.6.4; python\_version < "3.8" in /usr/local/lib/python3.7/dist-packages (from importlib-metadata; python\_version < "3.8"->markdown>=2.6.8->tensorboard<3,>=2.3.0->tensorflow==2.3.0) (3.7.4.3)

Requirement already satisfied: zipp>=0.5 in /usr/local/lib/python3.7/dist-packages (from importlib-metadata; python\_version < "3.8"->markdown>=2.6.8->tensorboard<3,>=2.3.0->tensorflow==2.3.0) (3.4.1)

Requirement already satisfied: oauthlib>=3.0.0 in /usr/local/lib/python3.7/dist-packages (from requests-oauthlib>=0.7.0->google-auth-oauthlib<0.5,>=0.4.1->tensorboard<3,>=2.3.0->tensorflow==2.3.0) (3.1.0)

ERROR: datascience 0.10.6 has requirement folium==0.2.1, but you'll have folium 0.8.3 which is incompatible.

ERROR: alumentations 0.1.12 has requirement imgaug<0.2.7,>=0.2.5, but you'll have imgaug 0.2.9 which is incompatible.

Installing collected packages: tensorflow-estimator, numpy, tensorflow

Found existing installation: tensorflow-estimator 2.4.0

Uninstalling tensorflow-estimator-2.4.0:

Successfully uninstalled tensorflow-estimator-2.4.0

Found existing installation: numpy 1.19.5

Uninstalling numpy-1.19.5:

Successfully uninstalled numpy-1.19.5

Found existing installation: tensorflow 2.4.1

```

Uninstalling tensorflow-2.4.1:
  Successfully uninstalled tensorflow-2.4.1
Successfully installed numpy-1.18.5 tensorflow-2.3.0 tensorflow-estimator-2.3.0

Uninstalling Keras-2.4.3:
  Would remove:
    /usr/local/lib/python3.7/dist-packages/Keras-2.4.3.dist-info/*
    /usr/local/lib/python3.7/dist-packages/docs/*
    /usr/local/lib/python3.7/dist-packages/keras/*
  Would not remove (might be manually added):
    /usr/local/lib/python3.7/dist-packages/docs/md_autogen.py
    /usr/local/lib/python3.7/dist-packages/docs/update_docs.py
Proceed (y/n)? y
  Successfully uninstalled Keras-2.4.3
Collecting segmentation-models
  Downloading https://files.pythonhosted.org/packages/da/b9/4a183518c21689a56b834eaaa45cad242d9ec09a4360b5b10139f23c63f4/segmentation_models-1.0.1-py3-none-any.whl
Collecting image-classifiers==1.0.0
  Downloading https://files.pythonhosted.org/packages/81/98/6f84720e299a4942ab80df5f76ab97b7828b24d1de5e9b2cbb6073228b7/image_classifiers-1.0.0-py3-none-any.whl
Collecting efficientnet==1.0.0
  Downloading https://files.pythonhosted.org/packages/97/82/f3ae07316f0461417dc54affab6e86ab188a5a22f33176d35271628b96e0/efficientnet-1.0.0-py3-none-any.whl
Collecting keras-applications<=1.0.8,>=1.0.7
  Downloading https://files.pythonhosted.org/packages/71/e3/19762fd6c62877ae9102edf6342d71b28fbfd9dea3d2f96a882ce099b03f/Keras_Applications-1.0.8-py3-none-any.whl (50kB)
    |                               | 51kB 7.5MB/s
Requirement already satisfied, skipping upgrade: scikit-image in
/usr/local/lib/python3.7/dist-packages (from efficientnet==1.0.0->segmentation-models) (0.16.2)
Requirement already satisfied, skipping upgrade: numpy>=1.9.1 in
/usr/local/lib/python3.7/dist-packages (from keras-applications<=1.0.8,>=1.0.7->segmentation-models) (1.18.5)
Requirement already satisfied, skipping upgrade: h5py in
/usr/local/lib/python3.7/dist-packages (from keras-applications<=1.0.8,>=1.0.7->segmentation-models) (2.10.0)
Requirement already satisfied, skipping upgrade: scipy>=0.19.0 in
/usr/local/lib/python3.7/dist-packages (from scikit-image->efficientnet==1.0.0->segmentation-models) (1.4.1)
Requirement already satisfied, skipping upgrade: networkx>=2.0 in
/usr/local/lib/python3.7/dist-packages (from scikit-image->efficientnet==1.0.0->segmentation-models) (2.5.1)
Requirement already satisfied, skipping upgrade: matplotlib!=3.0.0,>=2.0.0 in
/usr/local/lib/python3.7/dist-packages (from scikit-image->efficientnet==1.0.0->segmentation-models) (3.2.2)

```

Requirement already satisfied, skipping upgrade: imageio>=2.3.0 in /usr/local/lib/python3.7/dist-packages (from scikit-image->efficientnet==1.0.0->segmentation-models) (2.4.1)

Requirement already satisfied, skipping upgrade: PyWavelets>=0.4.0 in /usr/local/lib/python3.7/dist-packages (from scikit-image->efficientnet==1.0.0->segmentation-models) (1.1.1)

Requirement already satisfied, skipping upgrade: pillow>=4.3.0 in /usr/local/lib/python3.7/dist-packages (from scikit-image->efficientnet==1.0.0->segmentation-models) (7.1.2)

Requirement already satisfied, skipping upgrade: six in /usr/local/lib/python3.7/dist-packages (from h5py->keras-applications<=1.0.8,>=1.0.7->segmentation-models) (1.15.0)

Requirement already satisfied, skipping upgrade: decorator<5,>=4.3 in /usr/local/lib/python3.7/dist-packages (from networkx>=2.0->scikit-image->efficientnet==1.0.0->segmentation-models) (4.4.2)

Requirement already satisfied, skipping upgrade: kiwisolver>=1.0.1 in /usr/local/lib/python3.7/dist-packages (from matplotlib!=3.0.0,>=2.0.0->scikit-image->efficientnet==1.0.0->segmentation-models) (1.3.1)

Requirement already satisfied, skipping upgrade: cyclor>=0.10 in /usr/local/lib/python3.7/dist-packages (from matplotlib!=3.0.0,>=2.0.0->scikit-image->efficientnet==1.0.0->segmentation-models) (0.10.0)

Requirement already satisfied, skipping upgrade: python-dateutil>=2.1 in /usr/local/lib/python3.7/dist-packages (from matplotlib!=3.0.0,>=2.0.0->scikit-image->efficientnet==1.0.0->segmentation-models) (2.8.1)

Requirement already satisfied, skipping upgrade: pyparsing!=2.0.4,!=2.1.2,!=2.1.6,>=2.0.1 in /usr/local/lib/python3.7/dist-packages (from matplotlib!=3.0.0,>=2.0.0->scikit-image->efficientnet==1.0.0->segmentation-models) (2.4.7)

Installing collected packages: keras-applications, image-classifiers, efficientnet, segmentation-models

Successfully installed efficientnet-1.0.0 image-classifiers-1.0.0 keras-applications-1.0.8 segmentation-models-1.0.1

```
[3]: import tensorflow as tf
```

```
[4]: tf.__version__
```

```
[4]: '2.3.0'
```

```
[5]:
```

```
!curl --header 'Host: doc-08-6c-docs.googleusercontent.com' --user-agent_
↳ 'Mozilla/5.0 (X11; Ubuntu; Linux x86_64; rv:87.0) Gecko/20100101 Firefox/87.
↳ 0' --header 'Accept: text/html,application/xhtml+xml,application/xml;q=0.
↳ 9,image/webp,*/*;q=0.8' --header 'Accept-Language: en-US,en;q=0.5' --header_
↳ 'DNT: 1' --cookie_
↳ 'AUTH_strj46uec8h0uimj0a76oqt8s090ljp_nonce=ee6a5dkvkinho' --header_
↳ 'Upgrade-Insecure-Requests: 1' 'https://doc-08-6c-docs.googleusercontent.com/
↳ docs/securesc/i310t34egoh5k9i7d2vg3j7qd6ho7o0u/
↳ n85bo3bhkbhv9q37c6c8kps6kjd0cqeU/1618983675000/00325028343414406087/
↳ 00325028343414406087/1PQZUT1kwuiD7_9k2zEnZX-fpETP1mADz?
↳ e=download&authuser=1&nonce=ee6a5dkvkinho&user=00325028343414406087&hash=0rjrvvnp67uc4sa1a4
↳ --output 'data.zip'
```

% Total	% Received	% Xferd	Average Speed	Time	Time	Time	Current
			Dload Upload	Total	Spent	Left	Speed
100 2231M	0 2231M	0 0	81.5M 0	--:--:--	0:00:27	--:--:--	31.2M

[6]: !unzip data.zip

Streaming output truncated to the last 5000 lines.

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inflating: data/images/377/frame28480_leftImg8bit.jpg
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inflating: data/mask/416/0002861\_gtFine\_polygons.json  
inflating: data/mask/416/0003423\_gtFine\_polygons.json



inflating: data/mask/416/0003613\_gtFine\_polygons.json  
inflating: data/mask/416/0003921\_gtFine\_polygons.json  
inflating: data/mask/416/0004068\_gtFine\_polygons.json  
inflating: data/mask/416/0004280\_gtFine\_polygons.json  
inflating: data/mask/416/0004571\_gtFine\_polygons.json  
inflating: data/mask/416/0005055\_gtFine\_polygons.json  
inflating: data/mask/416/0005174\_gtFine\_polygons.json  
inflating: data/mask/416/0005244\_gtFine\_polygons.json  
inflating: data/mask/416/0005840\_gtFine\_polygons.json  
inflating: data/mask/416/0006082\_gtFine\_polygons.json  
inflating: data/mask/416/0006371\_gtFine\_polygons.json  
inflating: data/mask/416/0006575\_gtFine\_polygons.json  
creating: data/mask/417/  
inflating: data/mask/417/0000000\_gtFine\_polygons.json  
inflating: data/mask/417/0000584\_gtFine\_polygons.json  
inflating: data/mask/417/0000695\_gtFine\_polygons.json  
inflating: data/mask/417/0000781\_gtFine\_polygons.json  
inflating: data/mask/417/0000848\_gtFine\_polygons.json  
inflating: data/mask/417/0000940\_gtFine\_polygons.json  
inflating: data/mask/417/0001083\_gtFine\_polygons.json  
inflating: data/mask/417/0001183\_gtFine\_polygons.json  
inflating: data/mask/417/0001487\_gtFine\_polygons.json  
inflating: data/mask/417/0001756\_gtFine\_polygons.json  
inflating: data/mask/417/0001986\_gtFine\_polygons.json  
inflating: data/mask/417/0002149\_gtFine\_polygons.json  
inflating: data/mask/417/0002365\_gtFine\_polygons.json  
inflating: data/mask/417/0002457\_gtFine\_polygons.json  
inflating: data/mask/417/0002558\_gtFine\_polygons.json  
inflating: data/mask/417/0002652\_gtFine\_polygons.json  
inflating: data/mask/417/0003404\_gtFine\_polygons.json  
inflating: data/mask/417/0003987\_gtFine\_polygons.json  
inflating: data/mask/417/0004119\_gtFine\_polygons.json  
inflating: data/mask/417/0004398\_gtFine\_polygons.json  
inflating: data/mask/417/0004560\_gtFine\_polygons.json  
inflating: data/mask/417/0004921\_gtFine\_polygons.json  
inflating: data/mask/417/0005099\_gtFine\_polygons.json  
inflating: data/mask/417/0005231\_gtFine\_polygons.json  
inflating: data/mask/417/0005466\_gtFine\_polygons.json  
inflating: data/mask/417/0005971\_gtFine\_polygons.json  
inflating: data/mask/417/0006252\_gtFine\_polygons.json  
inflating: data/mask/417/0006366\_gtFine\_polygons.json  
inflating: data/mask/417/0006547\_gtFine\_polygons.json  
inflating: data/mask/417/0006899\_gtFine\_polygons.json  
inflating: data/mask/417/0007249\_gtFine\_polygons.json  
inflating: data/mask/417/0007492\_gtFine\_polygons.json  
inflating: data/mask/417/0007940\_gtFine\_polygons.json  
inflating: data/mask/417/0008080\_gtFine\_polygons.json  
inflating: data/mask/417/0008799\_gtFine\_polygons.json

inflating: data/mask/417/0010926\_gtFine\_polygons.json  
inflating: data/mask/417/0011515\_gtFine\_polygons.json  
inflating: data/mask/417/0012819\_gtFine\_polygons.json  
inflating: data/mask/417/0013412\_gtFine\_polygons.json  
inflating: data/mask/417/0013929\_gtFine\_polygons.json  
inflating: data/mask/417/0014129\_gtFine\_polygons.json  
inflating: data/mask/417/0015139\_gtFine\_polygons.json  
inflating: data/mask/417/0015248\_gtFine\_polygons.json  
inflating: data/mask/417/0015371\_gtFine\_polygons.json  
inflating: data/mask/417/0015565\_gtFine\_polygons.json  
inflating: data/mask/417/0015878\_gtFine\_polygons.json  
inflating: data/mask/417/0016322\_gtFine\_polygons.json  
inflating: data/mask/417/0016558\_gtFine\_polygons.json  
inflating: data/mask/417/0016881\_gtFine\_polygons.json  
inflating: data/mask/417/0017008\_gtFine\_polygons.json  
inflating: data/mask/417/0017425\_gtFine\_polygons.json  
inflating: data/mask/417/0017623\_gtFine\_polygons.json  
inflating: data/mask/417/0018056\_gtFine\_polygons.json  
inflating: data/mask/417/0018442\_gtFine\_polygons.json  
inflating: data/mask/417/0018578\_gtFine\_polygons.json  
inflating: data/mask/417/0018972\_gtFine\_polygons.json  
inflating: data/mask/417/0019370\_gtFine\_polygons.json  
inflating: data/mask/417/0019674\_gtFine\_polygons.json  
inflating: data/mask/417/0019901\_gtFine\_polygons.json  
inflating: data/mask/417/0020010\_gtFine\_polygons.json  
inflating: data/mask/417/0020316\_gtFine\_polygons.json  
inflating: data/mask/417/0020462\_gtFine\_polygons.json  
inflating: data/mask/417/0020558\_gtFine\_polygons.json  
inflating: data/mask/417/0020614\_gtFine\_polygons.json  
inflating: data/mask/417/0020794\_gtFine\_polygons.json  
inflating: data/mask/417/0021541\_gtFine\_polygons.json  
creating: data/mask/419/  
inflating: data/mask/419/frame0002\_gtFine\_polygons.json  
inflating: data/mask/419/frame0092\_gtFine\_polygons.json  
inflating: data/mask/419/frame0179\_gtFine\_polygons.json  
inflating: data/mask/419/frame0392\_gtFine\_polygons.json  
inflating: data/mask/419/frame0512\_gtFine\_polygons.json  
inflating: data/mask/419/frame0842\_gtFine\_polygons.json  
inflating: data/mask/419/frame1232\_gtFine\_polygons.json  
inflating: data/mask/419/frame1349\_gtFine\_polygons.json  
inflating: data/mask/419/frame1679\_gtFine\_polygons.json  
inflating: data/mask/419/frame1769\_gtFine\_polygons.json  
inflating: data/mask/419/frame1979\_gtFine\_polygons.json  
inflating: data/mask/419/frame2279\_gtFine\_polygons.json  
inflating: data/mask/419/frame2459\_gtFine\_polygons.json  
inflating: data/mask/419/frame2789\_gtFine\_polygons.json  
inflating: data/mask/419/frame2909\_gtFine\_polygons.json  
inflating: data/mask/419/frame3119\_gtFine\_polygons.json

inflating: data/mask/419/frame3239\_gtFine\_polygons.json  
inflating: data/mask/419/frame3389\_gtFine\_polygons.json  
inflating: data/mask/419/frame3719\_gtFine\_polygons.json  
creating: data/mask/421/  
inflating: data/mask/421/00000001\_gtFine\_polygons.json  
inflating: data/mask/421/0000064\_gtFine\_polygons.json  
inflating: data/mask/421/0000325\_gtFine\_polygons.json  
inflating: data/mask/421/0000351\_gtFine\_polygons.json  
inflating: data/mask/421/0000450\_gtFine\_polygons.json  
inflating: data/mask/421/0000477\_gtFine\_polygons.json  
inflating: data/mask/421/0000571\_gtFine\_polygons.json  
inflating: data/mask/421/0000711\_gtFine\_polygons.json  
inflating: data/mask/421/0000766\_gtFine\_polygons.json  
inflating: data/mask/421/0000800\_gtFine\_polygons.json  
inflating: data/mask/421/0000863\_gtFine\_polygons.json  
inflating: data/mask/421/0000969\_gtFine\_polygons.json  
inflating: data/mask/421/0001218\_gtFine\_polygons.json  
inflating: data/mask/421/0001340\_gtFine\_polygons.json  
inflating: data/mask/421/0001535\_gtFine\_polygons.json  
inflating: data/mask/421/0001664\_gtFine\_polygons.json  
inflating: data/mask/421/0001753\_gtFine\_polygons.json  
inflating: data/mask/421/0001864\_gtFine\_polygons.json  
inflating: data/mask/421/0002057\_gtFine\_polygons.json  
inflating: data/mask/421/0002174\_gtFine\_polygons.json  
inflating: data/mask/421/0002308\_gtFine\_polygons.json  
inflating: data/mask/421/0002384\_gtFine\_polygons.json  
inflating: data/mask/421/0002459\_gtFine\_polygons.json  
inflating: data/mask/421/0002544\_gtFine\_polygons.json  
inflating: data/mask/421/0002701\_gtFine\_polygons.json  
inflating: data/mask/421/0002781\_gtFine\_polygons.json  
inflating: data/mask/421/0002860\_gtFine\_polygons.json  
inflating: data/mask/421/0002989\_gtFine\_polygons.json  
inflating: data/mask/421/0003108\_gtFine\_polygons.json  
inflating: data/mask/421/0003184\_gtFine\_polygons.json  
inflating: data/mask/421/0003290\_gtFine\_polygons.json  
inflating: data/mask/421/0003368\_gtFine\_polygons.json  
inflating: data/mask/421/0003459\_gtFine\_polygons.json  
inflating: data/mask/421/0003527\_gtFine\_polygons.json  
inflating: data/mask/421/0003605\_gtFine\_polygons.json  
inflating: data/mask/421/0003667\_gtFine\_polygons.json  
inflating: data/mask/421/0003806\_gtFine\_polygons.json  
inflating: data/mask/421/0004379\_gtFine\_polygons.json  
inflating: data/mask/421/0004455\_gtFine\_polygons.json  
inflating: data/mask/421/0004611\_gtFine\_polygons.json  
inflating: data/mask/421/0004728\_gtFine\_polygons.json  
inflating: data/mask/421/0004767\_gtFine\_polygons.json  
inflating: data/mask/421/0004915\_gtFine\_polygons.json  
inflating: data/mask/421/0005106\_gtFine\_polygons.json

inflating: data/mask/421/0005325\_gtFine\_polygons.json  
inflating: data/mask/421/0005563\_gtFine\_polygons.json  
inflating: data/mask/421/0005642\_gtFine\_polygons.json  
inflating: data/mask/421/0005694\_gtFine\_polygons.json  
inflating: data/mask/421/0005775\_gtFine\_polygons.json  
inflating: data/mask/421/0006130\_gtFine\_polygons.json  
inflating: data/mask/421/0006617\_gtFine\_polygons.json  
inflating: data/mask/421/0006851\_gtFine\_polygons.json  
inflating: data/mask/421/0007163\_gtFine\_polygons.json  
inflating: data/mask/421/0007235\_gtFine\_polygons.json  
inflating: data/mask/421/0007546\_gtFine\_polygons.json  
inflating: data/mask/421/0008620\_gtFine\_polygons.json  
inflating: data/mask/421/0010022\_gtFine\_polygons.json  
inflating: data/mask/421/0010131\_gtFine\_polygons.json  
inflating: data/mask/421/0010446\_gtFine\_polygons.json  
inflating: data/mask/421/0010702\_gtFine\_polygons.json  
inflating: data/mask/421/0010798\_gtFine\_polygons.json  
inflating: data/mask/421/0010849\_gtFine\_polygons.json  
inflating: data/mask/421/0011194\_gtFine\_polygons.json  
inflating: data/mask/421/0011554\_gtFine\_polygons.json  
inflating: data/mask/421/0011728\_gtFine\_polygons.json  
inflating: data/mask/421/0012269\_gtFine\_polygons.json  
inflating: data/mask/421/0012782\_gtFine\_polygons.json  
inflating: data/mask/421/0012940\_gtFine\_polygons.json  
inflating: data/mask/421/0013292\_gtFine\_polygons.json  
inflating: data/mask/421/0013355\_gtFine\_polygons.json  
inflating: data/mask/421/0013385\_gtFine\_polygons.json  
inflating: data/mask/421/0013631\_gtFine\_polygons.json  
inflating: data/mask/421/0013677\_gtFine\_polygons.json  
inflating: data/mask/421/0013764\_gtFine\_polygons.json  
inflating: data/mask/421/0013804\_gtFine\_polygons.json  
inflating: data/mask/421/0013856\_gtFine\_polygons.json  
inflating: data/mask/421/0013928\_gtFine\_polygons.json  
inflating: data/mask/421/0013989\_gtFine\_polygons.json  
inflating: data/mask/421/0014059\_gtFine\_polygons.json  
inflating: data/mask/421/0014234\_gtFine\_polygons.json  
inflating: data/mask/421/0014430\_gtFine\_polygons.json  
inflating: data/mask/421/0014733\_gtFine\_polygons.json  
inflating: data/mask/421/0014834\_gtFine\_polygons.json  
inflating: data/mask/421/0014891\_gtFine\_polygons.json  
inflating: data/mask/421/0014989\_gtFine\_polygons.json  
inflating: data/mask/421/0015017\_gtFine\_polygons.json  
inflating: data/mask/421/0015110\_gtFine\_polygons.json  
inflating: data/mask/421/0015153\_gtFine\_polygons.json  
inflating: data/mask/421/0015337\_gtFine\_polygons.json  
inflating: data/mask/421/0015393\_gtFine\_polygons.json  
inflating: data/mask/421/0015471\_gtFine\_polygons.json  
inflating: data/mask/421/0015552\_gtFine\_polygons.json

inflating: data/mask/421/0015640\_gtFine\_polygons.json  
creating: data/mask/422/  
inflating: data/mask/422/0000083\_gtFine\_polygons.json  
inflating: data/mask/422/0000264\_gtFine\_polygons.json  
inflating: data/mask/422/0000946\_gtFine\_polygons.json  
inflating: data/mask/422/0001101\_gtFine\_polygons.json  
inflating: data/mask/422/0001202\_gtFine\_polygons.json  
inflating: data/mask/422/0001439\_gtFine\_polygons.json  
inflating: data/mask/422/0001625\_gtFine\_polygons.json  
inflating: data/mask/422/0001711\_gtFine\_polygons.json  
inflating: data/mask/422/0001842\_gtFine\_polygons.json  
inflating: data/mask/422/0002550\_gtFine\_polygons.json  
inflating: data/mask/422/0002723\_gtFine\_polygons.json  
inflating: data/mask/422/0002821\_gtFine\_polygons.json  
inflating: data/mask/422/0003026\_gtFine\_polygons.json  
inflating: data/mask/422/0003275\_gtFine\_polygons.json  
inflating: data/mask/422/0003353\_gtFine\_polygons.json  
inflating: data/mask/422/0003620\_gtFine\_polygons.json  
inflating: data/mask/422/0003814\_gtFine\_polygons.json  
inflating: data/mask/422/0004826\_gtFine\_polygons.json  
inflating: data/mask/422/0005835\_gtFine\_polygons.json  
inflating: data/mask/422/0006760\_gtFine\_polygons.json  
inflating: data/mask/422/0007176\_gtFine\_polygons.json  
inflating: data/mask/422/0007298\_gtFine\_polygons.json  
inflating: data/mask/422/0007361\_gtFine\_polygons.json  
inflating: data/mask/422/0007442\_gtFine\_polygons.json  
inflating: data/mask/422/0007743\_gtFine\_polygons.json  
inflating: data/mask/422/0007889\_gtFine\_polygons.json  
inflating: data/mask/422/0008035\_gtFine\_polygons.json  
creating: data/mask/423/  
inflating: data/mask/423/frame0007\_gtFine\_polygons.json  
inflating: data/mask/423/frame0999\_gtFine\_polygons.json  
inflating: data/mask/423/frame12699\_gtFine\_polygons.json  
inflating: data/mask/423/frame5607\_gtFine\_polygons.json  
inflating: data/mask/423/frame7487\_gtFine\_polygons.json  
inflating: data/mask/423/frame7987\_gtFine\_polygons.json  
inflating: data/mask/423/frame8397\_gtFine\_polygons.json  
inflating: data/mask/423/frame8847\_gtFine\_polygons.json  
inflating: data/mask/423/frame9927\_gtFine\_polygons.json  
creating: data/mask/424/  
inflating: data/mask/424/frame0349\_gtFine\_polygons.json  
inflating: data/mask/424/frame0499\_gtFine\_polygons.json  
inflating: data/mask/424/frame0799\_gtFine\_polygons.json  
inflating: data/mask/424/frame0924\_gtFine\_polygons.json  
inflating: data/mask/424/frame1149\_gtFine\_polygons.json  
creating: data/mask/426/  
inflating: data/mask/426/00000000\_gtFine\_polygons.json  
inflating: data/mask/426/0000343\_gtFine\_polygons.json

```
inflating: data/mask/426/0000454_gtFine_polygons.json
inflating: data/mask/426/0000639_gtFine_polygons.json
  creating: data/mask/428/
inflating: data/mask/428/frame0359_gtFine_polygons.json
inflating: data/mask/428/frame0839_gtFine_polygons.json
inflating: data/mask/428/frame0959_gtFine_polygons.json
inflating: data/mask/428/frame1079_gtFine_polygons.json
inflating: data/mask/428/frame1199_gtFine_polygons.json
inflating: data/mask/428/frame1319_gtFine_polygons.json
inflating: data/mask/428/frame1439_gtFine_polygons.json
inflating: data/mask/428/frame1559_gtFine_polygons.json
inflating: data/mask/428/frame1679_gtFine_polygons.json
inflating: data/mask/428/frame1799_gtFine_polygons.json
inflating: data/mask/428/frame2039_gtFine_polygons.json
inflating: data/mask/428/frame3119_gtFine_polygons.json
inflating: data/mask/428/frame3359_gtFine_polygons.json
inflating: data/mask/428/frame3479_gtFine_polygons.json
inflating: data/mask/428/frame3599_gtFine_polygons.json
inflating: data/mask/428/frame3719_gtFine_polygons.json
inflating: data/mask/428/frame3839_gtFine_polygons.json
inflating: data/mask/428/frame3959_gtFine_polygons.json
  creating: data/mask/429/
inflating: data/mask/429/frame10303_gtFine_polygons.json
inflating: data/mask/429/frame13262_gtFine_polygons.json
inflating: data/mask/429/frame13699_gtFine_polygons.json
inflating: data/mask/429/frame15812_gtFine_polygons.json
inflating: data/mask/429/frame18062_gtFine_polygons.json
inflating: data/mask/429/frame18403_gtFine_polygons.json
```

```
[7]: root_dir = "data/"
data_image_path = "data/images/"
data_mask_path = "data/mask/"
```

```
[8]: import math
from PIL import Image, ImageDraw
from PIL import ImagePath
import pandas as pd
import os
from os import walk
from os import path
from tqdm import tqdm
import json
import cv2
import numpy as np
import matplotlib.pyplot as plt
import urllib
import tensorflow as tf
```

```
[9]: import segmentation_models as sm
from segmentation_models import Unet
from segmentation_models.metrics import iou_score

import imgaug.augmenters as iaa
import numpy as np
from tensorflow import keras

from sklearn.model_selection import train_test_split
import matplotlib.pyplot as plt
```

Segmentation Models: using `tf.keras` framework.

```
[10]: !mkdir data/output
```

Preprocessing

## 2 1. Get all the file name and corresponding json files

```
[11]: def return_file_names_df(root_dir):
    # write the code that will create a dataframe with two columns ['images',
    ↪ 'json']
    # the column 'image' will have path to images
    # the column 'json' will have path to json files
    image_list = []
    json_list = []

    root_folders = os.listdir(root_dir)
    image_folders = os.listdir(root_dir + '/images')

    print()

    for folder in image_folders:

        frame_names = os.listdir(root_dir + 'images' + "/" + folder)

        for frame in frame_names:

            image_file = os.path.join(root_dir + 'images' + "/" + folder + "/",
            ↪ frame)
            image_list.append(image_file)

            frame_json = frame.split("_")[0] + "_gtFine_polygons.json"
```

```

        json_file = os.path.join(root_dir + 'mask' + "/" + folder + "/",
        ↪frame_json)

        json_list.append(json_file)

data = {"image":image_list, "json":json_list}
data_df = pd.DataFrame(data)

return data_df

```

```

[12]: data_df = return_file_names_df(root_dir)
data_df.head()

```

```

[12]:                                     image
json
0  data/images/347/frame13126_leftImg8bit.jpg
data/mask/347/frame13126_gtFine_polygons.json
1  data/images/347/frame8141_leftImg8bit.jpg
data/mask/347/frame8141_gtFine_polygons.json
2  data/images/347/frame8981_leftImg8bit.jpg
data/mask/347/frame8981_gtFine_polygons.json
3  data/images/347/frame1239_leftImg8bit.jpg
data/mask/347/frame1239_gtFine_polygons.json
4  data/images/347/frame3671_leftImg8bit.jpg
data/mask/347/frame3671_gtFine_polygons.json

```

If you observe the dataframe, we can consider each row as single data point, where first feature is image and the second feature is corresponding json file

```

[13]: def grader_1(data_df):
        for i in data_df.values:
            if not (path.isfile(i[0]) and path.isfile(i[1]) and i[0][12:i[0].
            ↪find('_')]==i[1][10:i[1].find('_')]):
                return False
        return True

```

```

[14]: grader_1(data_df)

```



```
[14]: True
```

```
[15]: data_df.shape
```

```
[15]: (4008, 2)
```

## 3 2. Structure of sample Json file

- Each File will have 3 attributes
  - imgHeight: which tells the height of the image
  - imgWidth: which tells the width of the image
  - objects: it is a list of objects, each object will have multiple attributes,
    - \* label: the type of the object
    - \* polygon: a list of two element lists, representing the coordinates of the polygon

**Compute the unique labels** Let's see how many unique objects are there in the json file. to see how to get the object from the json file please check this [blog](#)

```
[16]: def return_unique_labels(data_df):  
    # for each file in the column json  
    # read and store all the objects present in that file  
    # compute the unique objects and retrun them  
    # if open any json file using any editor you will get better sense of it  
    unique_labels = []  
  
    for item in data_df['json']:  
        f = open(item,)  
        data = json.load(f)  
        for o in data['objects']:  
            unique_labels.append(o['label'])  
  
    unique_labels = set(unique_labels)  
    print(len(unique_labels))  
    return unique_labels
```

```
[17]: unique_labels = return_unique_labels(data_df)
```

```
40
```

```
[18]: label_clr = {'road':10, 'parking':20, 'drivable fallback':20,'sidewalk':  
    ↪30,'non-drivable fallback':40,'rail track':40,\n                'person':50, 'animal':50, 'rider':60, 'motorcycle':70,␣  
    ↪'bicycle':70, 'autorickshaw':80,\n                'car':80, 'truck':90, 'bus':90, 'vehicle fallback':90,␣  
    ↪'trailer':90, 'caravan':90,\n
```

```

        'curb':100, 'wall':100, 'fence':110,'guard rail':110,\
↪'billboard':120,'traffic sign':120,\
        'traffic light':120, 'pole':130, 'polegroup':130,\
↪'obs-str-bar-fallback':130,'building':140,\
        'bridge':140,'tunnel':140, 'vegetation':150, 'sky':160,\
↪'fallback background':160,'unlabeled':0,\
        'out of roi':0, 'ego vehicle':170, 'ground':
↪180,'rectification border':190,\
        'train':200}

```

```

[19]: def grader_2(unique_labels):
        if (not (set(label_clr.keys())-set(unique_labels))) and len(unique_labels)\
↪== 40:
            print("True")
        else:
            print("Flase")

grader_2(unique_labels)

```

True

```

[20]: unique_labels

```

```

[20]: {'animal',
        'autorickshaw',
        'bicycle',
        'billboard',
        'bridge',
        'building',
        'bus',
        'car',
        'caravan',
        'curb',
        'drivable fallback',
        'ego vehicle',
        'fallback background',
        'fence',
        'ground',
        'guard rail',
        'motorcycle',
        'non-drivable fallback',
        'obs-str-bar-fallback',
        'out of roi',
        'parking',
        'person',
        'pole',
        'polegroup',

```

```

'rail track',
'rectification border',
'rider',
'road',
'sidewalk',
'sky',
'traffic light',
'traffic sign',
'trailer',
'train',
'truck',
'tunnel',
'unlabeled',
'vegetation',
'vehicle fallback',
'wall'}

```

## 4 3. Extracting the polygons from the json files

```

[21]: def get_poly(file):
    # this function will take a file name as argument

    # it will process all the objects in that file and returns

    # label: a list of labels for all the objects label[i] will have the
    ↳corresponding vertices in vertexlist[i]
    # len(label) == number of objects in the image

    # vertexlist: it should be list of list of vertices in tuple formate
    # ex: [[(x11,y11), (x12,y12), (x13,y13) .. (x1n,y1n)]
    #      [(x21,y21), (x22,y12), (x23,y23) .. (x2n,y2n)]
    #      .....
    #      [(xm1,ym1), (xm2,ym2), (xm3,ym3) .. (xmn,ymn)]]
    # len(vertexlist) == number of objects in the image

    # * note that label[i] and vertexlist[i] are corresponds to the same
    ↳object, one represents the type of the object
    # the other represents the location

    # width of the image
    # height of the image

    label = []
    vertexlist = []

    f = open(file,)

```

```

data = json.load(f)

# label
for o in data['objects']:

    vertexlist_temp = []
    for vertex in o['polygon']:

        if len(vertex) != 2:
            print(file)
            print(o['label'])
        if len(vertex) == 2:
            vertexlist_temp.append((vertex[0], vertex[1]))

    if len(vertexlist_temp) != 0:
        label.append(o['label'])
        vertexlist.append(vertexlist_temp)

# width
w = data['imgWidth']

# height
h = data['imgHeight']

return w, h, label, vertexlist

```

```
[22]: # data/mask/354/frame0011_gtFine_polygons.json
```

```

[23]: def grader_3(file):
        w, h, labels, vertexlist = get_poly(file)
        print(len((set(labels)))==18 and len(vertexlist)==227 and w==1920 and
↪h==1080 \
            and isinstance(vertexlist,list) and isinstance(vertexlist[0],list)
↪and isinstance(vertexlist[0][0],tuple) )

grader_3('data/mask/201/frame0029_gtFine_polygons.json')

```

True

## 5 4. Creating Image segmentations by drawing set of polygons

### 5.0.1 Example

```
[24]: import math
from PIL import Image, ImageDraw
from PIL import ImagePath
side=8
x1 = [ ((math.cos(th) + 1) *9, (math.sin(th) + 1) * 6) for th in [i * (2 * math.
    ↳pi) / side for i in range(side)] ]
x2 = [ ((math.cos(th) + 2) *9, (math.sin(th) + 3) *6) for th in [i * (2 * math.
    ↳pi) / side for i in range(side)] ]

print(len(x1))

img = Image.new("RGB", (28,28))
img1 = ImageDraw.Draw(img)
# please play with the fill value
# writing the first polygon
img1.polygon(x1, fill =20)
# writing the second polygon
img1.polygon(x2, fill =30)

img=np.array(img)
# note that the filling of the values happens at the channel 1, so we are
    ↳considering only the first channel here
plt.imshow(img[:, :,0])
print(img.shape)
print(img[:, :,0]//10)
im = Image.fromarray(img[:, :,0])
im.save("test_image.png")
```

8

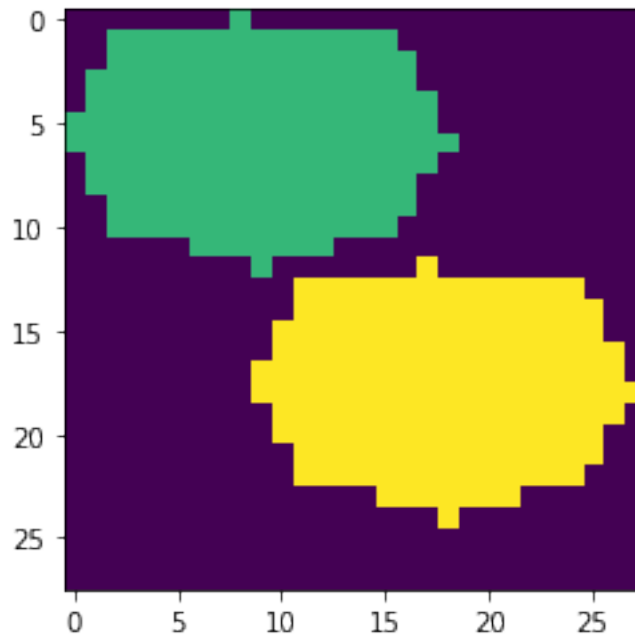
(28, 28, 3)

```
[[0 0 0 0 0 0 0 0 2 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0]
 [0 0 2 2 2 2 2 2 2 2 2 2 2 2 2 0 0 0 0 0 0 0 0 0 0 0]
 [0 0 2 2 2 2 2 2 2 2 2 2 2 2 2 2 0 0 0 0 0 0 0 0 0 0]
 [0 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 0 0 0 0 0 0 0 0 0 0]
 [0 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 0 0 0 0 0 0 0 0 0 0]
 [2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 0 0 0 0 0 0 0 0 0]
 [2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 0 0 0 0 0 0 0 0 0]
 [0 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 0 0 0 0 0 0 0 0 0]
 [0 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 0 0 0 0 0 0 0 0 0]
 [0 0 2 2 2 2 2 2 2 2 2 2 2 2 2 2 0 0 0 0 0 0 0 0 0 0]
 [0 0 2 2 2 2 2 2 2 2 2 2 2 2 2 2 0 0 0 0 0 0 0 0 0 0]
 [0 0 0 0 0 0 2 2 2 2 2 2 2 0 0 0 0 0 0 0 0 0 0 0 0 0]
 [0 0 0 0 0 0 0 0 2 0 0 0 0 0 0 0 3 0 0 0 0 0 0 0 0 0]
 [0 0 0 0 0 0 0 0 0 0 3 3 3 3 3 3 3 3 3 3 3 3 3 0 0 0]]
```

```

[0 0 0 0 0 0 0 0 0 0 0 3 3 3 3 3 3 3 3 3 3 3 3 3 3 0 0]
[0 0 0 0 0 0 0 0 0 0 0 3 3 3 3 3 3 3 3 3 3 3 3 3 3 0 0]
[0 0 0 0 0 0 0 0 0 0 0 3 3 3 3 3 3 3 3 3 3 3 3 3 3 3 0]
[0 0 0 0 0 0 0 0 0 0 0 3 3 3 3 3 3 3 3 3 3 3 3 3 3 3 0]
[0 0 0 0 0 0 0 0 0 0 0 3 3 3 3 3 3 3 3 3 3 3 3 3 3 3 3]
[0 0 0 0 0 0 0 0 0 0 0 3 3 3 3 3 3 3 3 3 3 3 3 3 3 3 0]
[0 0 0 0 0 0 0 0 0 0 0 3 3 3 3 3 3 3 3 3 3 3 3 3 3 0 0]
[0 0 0 0 0 0 0 0 0 0 0 3 3 3 3 3 3 3 3 3 3 3 3 3 3 0 0]
[0 0 0 0 0 0 0 0 0 0 0 3 3 3 3 3 3 3 3 3 3 3 3 3 3 0 0]
[0 0 0 0 0 0 0 0 0 0 0 3 3 3 3 3 3 3 3 3 3 3 3 3 0 0 0]
[0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 3 3 3 3 3 0 0 0 0 0 0 0]
[0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 3 0 0 0 0 0 0 0 0 0]
[0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0]
[0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0]
[0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0]

```



```

[25]: def compute_masks(data_df):
        # after you have computed the vertexlist plot that polygone in image like
        ↳ this

        # img = Image.new("RGB", (w, h))
        # img1 = ImageDraw.Draw(img)
        # img1.polygon(vertexlist[i], fill = label_clr[label[i]])

        # after drawing all the polygons that we collected from json file,
        # you need to store that image in the folder like this "data/output/scene/
        ↳ framenummer_gtFine_polygons.png"

```

```

# after saving the image into disk, store the path in a list
# after storing all the paths, add a column to the data_df['mask'] ex:
→data_df['mask']= mask_paths

mask = []

for file in data_df['json']:

    w, h, labels, vertexlist = get_poly(file)

    img = Image.new("RGB", (w, h))
    img1 = ImageDraw.Draw(img)

    for i in range(len(labels)):
        if len(vertexlist[i]) != 0:
            try:
                img1.polygon(vertexlist[i], fill = label_clr[labels[i]])

            except:
                print(file)

    img=np.array(img)
    # note that the filling of the values happens at the channel 1, so we are
→considering only the first channel here

    im = Image.fromarray(img[:, :, 0])

    # frame folder name 201
    frame_folder_name = file.split("/")[2]
    # .json to .png
    frame_image_name = file.split("/")[3]
    frame_polyimage_name = frame_image_name.split(".")[0] + ".png"
    file = root_dir + "output/" + frame_folder_name + "/" +
→frame_polyimage_name

    if not os.path.isdir(root_dir + "output/" + frame_folder_name + "/"):
        os.mkdir(root_dir + "output/" + frame_folder_name + "/")

    im.save(file)
    mask.append(file)

```

```
data_df.insert(1, "mask", mask, True)

return data_df
```

```
[26]: data_df = compute_masks(data_df)
data_df.head()
```

```
data/mask/354/frame0011_gtFine_polygons.json
```

```
[26]:
```

	image	...
	json	
0	data/images/347/frame13126_leftImg8bit.jpg	...
	data/mask/347/frame13126_gtFine_polygons.json	
1	data/images/347/frame8141_leftImg8bit.jpg	...
	data/mask/347/frame8141_gtFine_polygons.json	
2	data/images/347/frame8981_leftImg8bit.jpg	...
	data/mask/347/frame8981_gtFine_polygons.json	
3	data/images/347/frame1239_leftImg8bit.jpg	...
	data/mask/347/frame1239_gtFine_polygons.json	
4	data/images/347/frame3671_leftImg8bit.jpg	...
	data/mask/347/frame3671_gtFine_polygons.json	

```
[5 rows x 3 columns]
```

```
[27]: import urllib.request

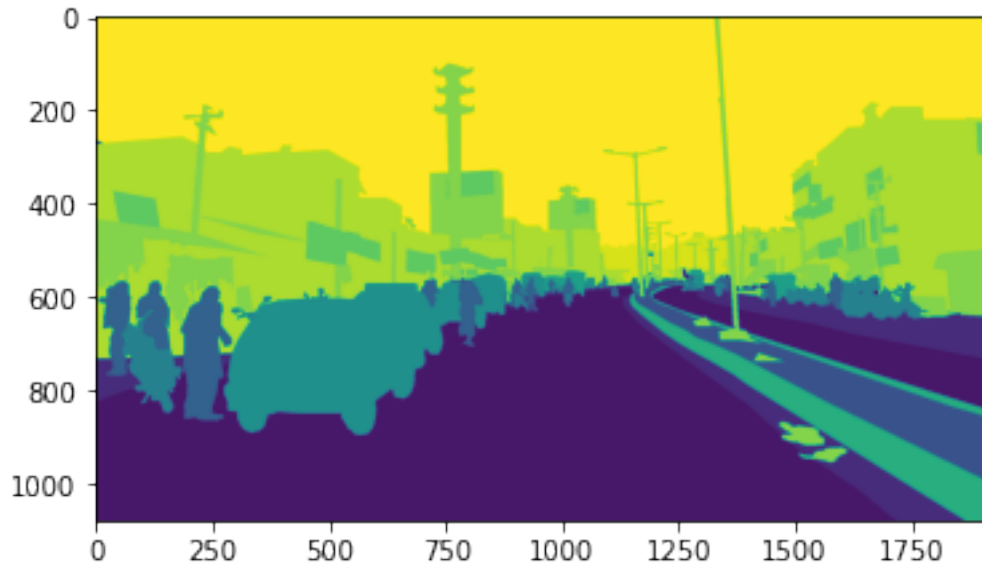
def grader_3():
    url = "https://i.imgur.com/4XSU1Hk.png"
    url_response = urllib.request.urlopen(url)
    img_array = np.array(bytearray(url_response.read()), dtype=np.uint8)
    img = cv2.imdecode(img_array, -1)
    my_img = cv2.imread('data/output/201/frame0029_gtFine_polygons.png', cv2.
↳IMREAD_UNCHANGED)
    plt.imshow(my_img)
    print((my_img==img).all())
    print(np.unique(img))
    print(np.unique(my_img))
    data_df.to_csv('preprocessed_data.csv', index=False)

grader_3()
```

```
False
```

```
[ 0  10  20  40  50  60  70  80  90 100 120 130 140 150 160]
[ 0  10  20  40  50  60  70  80  90 100 120 130 140 150 160]
```





```
[28]: data_df = pd.read_csv('preprocessed_data.csv')
```

```
[29]: data_df.head(1)
```

```
[29]:
```

	image	...
	json	
0	data/images/347/frame13126_leftImg8bit.jpg	...
	data/mask/347/frame13126_gtFine_polygons.json	

[1 rows x 3 columns]

## 6 Process and Prepare Image Data

```
[30]: X_train, X_test = train_test_split(data_df, test_size=0.20)
```

```
[31]: X_train.head(1)
```

```
[31]:
```

	image	...
	json	
3843	data/images/237/frame15317_leftImg8bit.jpg	...
	data/mask/237/frame15317_gtFine_polygons.json	

[1 rows x 3 columns]

```
[32]: image_list = []
```

```

for image in X_train['image']:
    image = cv2.imread(image, cv2.IMREAD_UNCHANGED)
    image = cv2.cvtColor(image, cv2.COLOR_BGR2RGB)
    image = cv2.resize(image, (256, 256), cv2.INTER_NEAREST)

    image_list.append(image)

image_list = np.array(image_list)

image_list.shape

```

[32]: (3206, 256, 256, 3)

```

[33]: data_mean = np.mean(image_list, axis=(0,1,2))
      data_std = np.std(image_list, axis=(0,1,2))

      print("mean across all train images' channels")
      print(data_mean)
      print("\n")
      print("standard deviation across all channels")
      print(data_std)

```

```

mean across all train images' channels
[93.3447582  97.62711925 96.4458347 ]

```

```

standard deviation across all channels
[65.32714513 69.63017598 77.50792521]

```

```

[34]: # mean across all train images' channels
      # [93.59830872 97.96180858 96.83046767]

      # standard deviation across all channels
      # [64.78668326 69.12853367 77.16108069]

```

```

[35]: np.array(X_train['image']).shape, np.array(X_test['mask']).shape

```

[35]: ((3206,), (802,))

```

[36]: aug2 = iaa.Fliplr(0.5)
      aug1 = iaa.Flipud(0.5)
      aug3 = iaa.Crop(percent=(0, 0.1))
      aug4 = iaa.Emboss(alpha=(1), strength=1)
      aug5 = iaa.DirectedEdgeDetect(alpha=(0.8), direction=(1.0))
      aug6 = iaa.Sharpen(alpha=(1.0), lightness=(1.5))
      aug7 = iaa.Sometimes(

```

```

    0.5,
    iaa.GaussianBlur(sigma=(0, 0.5))
)

```

```

[37]: def preprocess_image(image):

    image = np.float32(image)

    image -= data_mean
    image /= data_std

    return image


def visualize(images):
    n = len(images)
    plt.figure(figsize=(16, 5))
    for i, (name, image) in enumerate(images.items()):
        plt.subplot(1, n, i + 1)
        plt.xticks([])
        plt.yticks([])
        plt.title(' '.join(name.split('_')).title())
        if i==1:
            plt.imshow(image, cmap='gray', vmax=1, vmin=0)
        else:
            plt.imshow(image)
    plt.show()


class Dataset:
    # we will be modifying this CLASSES according to your data/problems

    # the parameters needs to changed based on your requirements
    # here we are collecting the file_names because in our dataset, both our
    → images and maks will have same file name
    # ex: fil_name.jpg    file_name.mask.jpg
    def __init__(self, data, CLASSES):

        self.ids = data['image']
        # the paths of images
        self.images_fps = np.array(data['image'])
        # the paths of segmentation images
        self.masks_fps = np.array(data['mask'])
        # giving labels for each class
        self.class_values = CLASSES

```

```

def __getitem__(self, i):

    # read data
    image = cv2.imread(self.images_fps[i], cv2.IMREAD_UNCHANGED)
    image = cv2.cvtColor(image, cv2.COLOR_BGR2RGB)
    image = cv2.resize(image, (512, 512), cv2.INTER_NEAREST)

    mask = cv2.imread(self.masks_fps[i], cv2.IMREAD_UNCHANGED)
    mask = cv2.resize(mask, (512, 512), cv2.INTER_NEAREST)

    image_masks = [(mask == v) for v in self.class_values]

    image_mask = np.stack(image_masks, axis=-1).astype('float32')

    a = np.random.uniform()
    if a<0.2:
        image = aug1.augment_image(image)
        image_mask = aug1.augment_image(image_mask)
    elif a<0.3:
        image = aug3.augment_image(image)
        image_mask = aug3.augment_image(image_mask)
    elif a<0.4:
        image = aug4.augment_image(image)
        image_mask = aug4.augment_image(image_mask)
    elif a<0.5:
        image = aug5.augment_image(image)
        image_mask = aug5.augment_image(image_mask)
    # elif a<0.6:
    #     image = aug6.augment_image(image)
    #     image_mask = aug6.augment_image(image_mask)
    # else:
    #     image = aug7.augment_image(image)
    #     image_mask = aug7.augment_image(image_mask)

    image = preprocess_image(image)

    return image, image_mask

def __len__(self):
    return len(self.ids)

```

```

class Dataloder(tf.keras.utils.Sequence):
    def __init__(self, dataset, batch_size, shuffle=False):
        self.dataset = dataset
        self.batch_size = batch_size
        self.shuffle = shuffle
        self.indexes = np.arange(len(dataset))

    def __getitem__(self, i):

        # collect batch data
        start = i * self.batch_size
        stop = (i + 1) * self.batch_size
        data = []
        for j in range(start, stop):
            data.append(self.dataset[j])

        batch = [np.stack(samples, axis=0) for samples in zip(*data)]

        return tuple(batch)

    def __len__(self):
        return len(self.indexes) // self.batch_size

    def on_epoch_end(self):
        if self.shuffle:
            self.indexes = np.random.permutation(self.indexes)

```

```

[38]: label_clr = {'road':10, 'parking':20, 'drivable fallback':20,'sidewalk':
↳30,'non-drivable fallback':40,'rail track':40,\
                'person':50, 'animal':50, 'rider':60, 'motorcycle':70,␣
↳'bicycle':70, 'autorickshaw':80,\
                'car':80, 'truck':90, 'bus':90, 'vehicle fallback':90,␣
↳'trailer':90, 'caravan':90,\
                'curb':100, 'wall':100, 'fence':110,'guard rail':110,␣
↳'billboard':120,'traffic sign':120,\
                'traffic light':120, 'pole':130, 'polegroup':130,␣
↳'obs-str-bar-fallback':130,'building':140,\
                'bridge':140,'tunnel':140, 'vegetation':150, 'sky':160,␣
↳'fallback background':160,'unlabeled':0,\
                'out of roi':0, 'ego vehicle':170, 'ground':
↳180,'rectification border':190,\
                'train':200}

```

```

[39]: CLASSES = list(np.unique(list(label_clr.values())))

```

```
[40]: len(CLASSES)
```

```
[40]: 21
```

```
[41]: train_dataset = Dataset(X_train, CLASSES)
      test_dataset  = Dataset(X_test, CLASSES)
```

```
[42]: train_dataloader = Dataloader(train_dataset, batch_size=9, shuffle=True)
      test_dataloader = Dataloader(test_dataset, batch_size=3, shuffle=True)
```

```
[43]: train_dataloader[0][0].shape, test_dataloader[0][1].shape
```

```
[43]: ((9, 512, 512, 3), (3, 512, 512, 21))
```

```
[43]:
```

## 7 Training CANet

```
[44]: # !pip install tensorflow==2.3.0
```

```
[45]: import tensorflow as tf
      # tf.compat.v1.enable_eager_execution()
      from tensorflow import keras
      from tensorflow.keras.layers import *
      from tensorflow.keras.preprocessing import image
      from tensorflow.keras.models import Model, load_model
      from tensorflow.keras.layers import UpSampling2D
      from tensorflow.keras.layers import MaxPooling2D, GlobalAveragePooling2D
      from tensorflow.keras.layers import concatenate
      from tensorflow.keras.layers import Multiply
      from tensorflow.keras.callbacks import EarlyStopping, ModelCheckpoint
      from tensorflow.keras import backend as K
      from tensorflow.keras.layers import Dropout, Input, Add, Dense, Activation,
      ↪ZeroPadding2D, BatchNormalization, Flatten, Conv2D, AveragePooling2D,
      ↪MaxPooling2D, GlobalMaxPooling2D, GlobalAveragePooling2D
      from tensorflow.keras.models import Model, load_model
      from tensorflow.keras.layers import add, multiply
      from tensorflow.keras.utils import plot_model
      from tensorflow.keras.initializers import glorot_uniform, he_normal
      from tensorflow.keras.regularizers import l1, l2, L1, L2
      K.set_image_data_format('channels_last')
      K.set_learning_phase(1)
      import numpy as np
```

WARNING:tensorflow:From <ipython-input-45-2d47755f9a12>:20: set\_learning\_phase (from tensorflow.python.keras.backend) is deprecated and will be removed after

2020-10-11.

Instructions for updating:

Simply pass a True/False value to the `training` argument of the `\_\_call\_\_` method of your layer or model.

```
[46]: print(tf.__version__)
```

2.3.0

## 8 Conv and Identity Block

- as a part of this assignment we will be implementing the architecture based on this paper <https://arxiv.org/pdf/2002.12041.pdf>
- We will be using the custom layers concept that we used in seq-seq assignment
- You can divide the whole architecture can be divided into two parts
  1. Encoder
  2. Decoder
- Encoder:
  - The first step of the encoder is to create the channel maps  $[C_1, C_2, C_3, C_4]$
  - $C_1$  width and heights are 4x times less than the original image
  - $C_2$  width and heights are 8x times less than the original image
  - $C_3$  width and heights are 8x times less than the original image
  - $C_4$  width and heights are 8x times less than the original image
  - you can reduce the dimensions by using stride parameter.
  - $[C_1, C_2, C_3, C_4]$  are formed by applying a “conv block” followed by  $k$  number of “identity block”. i.e the  $C_k$  feature map will single “conv block” followed by  $k$  number of “identity blocks”.
  - The conv block and identity block of  $C_1$ : the number filters in the convolutional layers will be  $[4, 4, 8]$  and the number of filters in the parallel conv layer will also be 8.
  - The conv block and identity block of  $C_2$ : the number filters in the convolutional layers will be  $[8, 8, 16]$  and the number of filters in the parallel conv layer will also be 16.
  - The conv block and identity block of  $C_3$ : the number filters in the convolutional layers will be  $[16, 16, 32]$  and the number of filters in the parallel conv layer will also be 32.
  - The conv block and identity block of  $C_4$ : the number filters in the convolutional layers will be  $[32, 32, 64]$  and the number of filters in the parallel conv layer will also be 64.
  - Here  $\oplus$  represents the elementwise sum

NOTE: these filters are of your choice, you can explore more options also

- Example: if your image is of size  $(512, 512, 3)$ 
  - \* the output after  $C_1$  will be  $128 * 128 * 8$
  - \* the output after  $C_2$  will be  $64 * 64 * 16$
  - \* the output after  $C_3$  will be  $64 * 64 * 32$
  - \* the output after  $C_4$  will be  $64 * 64 * 64$

```

[47]: class convolutional_block(tf.keras.layers.Layer):

    def __init__(self, filters, stride, layer_name):
        super().__init__()

        self.F1, self.F2, self.F3 = filters
        self.stride = stride
        self.layer_name = layer_name

        self.conv1 = Conv2D(filters=self.F1,
                              kernel_size=(1,1),
                              name= self.layer_name+"_conv1",
                              strides = (1, 1),
↪kernel_initializer='he_normal', activation='relu')

        self.bn1 = BatchNormalization(axis = 3)

        self.activation1 = Activation('relu')

        self.conv2 = Conv2D(filters=self.F2,
                              kernel_size=(3, 3),
                              name= self.layer_name+"_conv2",
↪padding='same',
                              strides = (self.stride, self.
↪stride),kernel_initializer='he_normal', activation='relu'
                              )

        self.bn2 = BatchNormalization(axis = 3)
        self.activation2 = Activation('relu')

        self.conv3 = Conv2D(filters=self.F3,
                              kernel_size=(1, 1),
                              name= self.layer_name+"_conv3",
↪padding='same',
                              strides = (1,
↪1),kernel_initializer='he_normal', activation='relu'
                              )

        self.bn3 = BatchNormalization(axis = 3)

        self.conv4 = Conv2D(filters=self.F3,
                              kernel_size=(3, 3),
                              name= self.layer_name+"_conv4",
↪padding='same',
                              strides = (self.stride, self.
↪stride),kernel_initializer='he_normal', activation='relu'
                              )

```



```

self.bn4 = BatchNormalization(axis = 3)
self.activation4 = Activation('relu')

self.dropout = Dropout(rate=0.5)
self.bn = BatchNormalization()

def call(self, X):
    # write the architecture that was mentioned above

    X_parallel = X

    X = self.conv1(X)
    X = self.bn1(X)
    X = self.activation1(X)

    # X = self.dropout(X)

    X = self.conv2(X)
    X = self.bn2(X)
    X = self.activation2(X)

    # X = self.dropout(X)

    X = self.conv3(X)
    X = self.bn3(X)

    X_parallel = self.conv4(X_parallel)
    X_parallel = self.bn4(X_parallel)
    X_parallel = self.activation4(X_parallel)

    X = tf.math.add(X, X_parallel)

    X = Activation('relu')(X)

    # X = self.bn(X)

    return X

```

```
[48]: class identity_block(tf.keras.layers.Layer):

    def __init__(self, filters, layer_name, kernel_size):
        super().__init__()
        self.F1, self.F2, self.F3 = filters
        self.strides = 1
        self.layer_name = layer_name
        self.kernel_size = kernel_size

        self.conv1 = Conv2D(filters=self.F1,
                              kernel_size=(1, 1),
                              strides=(1, 1), padding='same',
                              name=self.layer_name + '_conv_1',
↪kernel_initializer='he_normal', activation='relu')

        self.bn1 = BatchNormalization()

        self.activation1 = Activation('relu')

        self.conv2 = Conv2D(filters=self.F2,
                              kernel_size=(3, 3),
                              strides=(1, 1), padding='same',
                              name=self.layer_name + '_conv_2',
↪kernel_initializer='he_normal', activation='relu'
                              )

        self.bn2 = BatchNormalization()

        self.activation2 = Activation('relu')

        self.conv3 = Conv2D(filters=self.F3,
                              kernel_size=(1, 1),
                              strides=(1, 1), padding='same',
                              name=self.layer_name + '_conv_3',
↪kernel_initializer='he_normal', activation='relu'
                              )

        self.bn3 = BatchNormalization()

        self.dropout = Dropout(rate=0.5)

        self.bn = BatchNormalization()

    def call(self, X):
```

```

# write the architecutre that was mentioned above
X_parallel = X

X = self.conv1(X)
X = self.bn1(X)
X = self.activation1(X)

# X = self.dropout(X)

X = self.conv2(X)
X = self.bn2(X)
X = self.activation2(X)

# X = self.dropout(X)

X = self.conv3(X)
X_bn = self.bn3(X)

X = tf.math.add(X_bn, X_parallel)

X = Activation('relu')(X)

return X

```

## 9 Global Flow and Context Flow

- The output of the  $C_4$  will be passed to Chained Context Aggregation Module (CAM)
- The CAM module will have two operations names Context flow and Global flow
- The Global flow:
  - as shown in the above figure first we will apply global avg pooling which results in  $(\#, 1, 1, \text{number\_of\_filters})$  then applying BN, RELU,  $1 \times 1$  Conv layer sequentially which results a matrix  $(\#, 1, 1, \text{number\_of\_filters})$ . Finally apply upsampling / conv2d transpose to make the output same as the input dimensions  $(\#, \text{input\_height}, \text{input\_width}, \text{number\_of\_filters})$
  - If you use upsampling then use bilinear pooling as interpolation technique
- The Context flow:
  - as shown in the above figure (c) the context flow will get inputs from two modules **a** . **C4 b. From the above flow**
  - We will be concatenating the both inputs on the last axis.
  - After the concatenation we will be applying Average pooling which reduces the size of feature map by  $N \times$  times
  - In the paper it was mentioned that to apply a group convolutions, but for the assignment we will be applying the simple conv layers with kernel size  $(3 \times 3)$
  - We are skipping the channel shuffling

- similarly we will be applying a simple conv layers with kernel size  $(3 * 3)$  consider this output is  $X$
- later we will get the  $Y = (X \otimes \sigma((1 \times 1) \text{conv}(\text{relu}((1 \times 1) \text{conv}(X)))))) \oplus X$ , here  $\oplus$  is elementwise addition and  $\otimes$  is elementwise multiplication
- Finally apply upsampling / conv2d transpose to make the output same as the input dimensions (#, input\_height, input\_width, number\_of\_filters)
- If you use upsampling then use bilinear pooling as interpolation technique

NOTE: here N times reduction and N time increments makes the input and out shape same, you can explore with the N values, you can choose  $N = 2$  or  $4$

- Example with  $N=2$ :
  - Assume the C4 is of shape (64,64,64) then the shape of GF will be (64,64,32)
  - Assume the C4 is of shape (64,64,64) and the shape of GF is (64,64,32) then the shape of CF1 will be (64,64,32)
  - Assume the C4 is of shape (64,64,64) and the shape of CF1 is (64,64,32) then the shape of CF2 will be (64,64,32)
  - Assume the C4 is of shape (64,64,64) and the shape of CF2 is (64,64,32) then the shape of CF3 will be (64,64,32)

```
[49]: class global_flow(tf.keras.layers.Layer):
    def __init__(self):
        super().__init__()

        self.avgpool = GlobalAveragePooling2D()

        self.bn = BatchNormalization(axis=3)

        self.activation = Activation('relu')

        self.conv = Conv2D(filters=64,activation='relu', kernel_size=(1,1),
        ↪name = 'gf_conv1', kernel_initializer='he_normal',)

        self.conv_transpose = Conv2DTranspose(64 , (64, 64), use_bias = False,
        ↪kernel_initializer='he_normal', activation='relu')

    def call(self, X):
        # implement the global flow operation

        X = self.avgpool(X)
        X = tf.expand_dims(X, axis=1)
        X = tf.expand_dims(X, axis=2)

        X = self.bn(X)
```

```

X = self.activation(X)

X = self.conv(X)

X = self.conv_transpose(X)

return X

```

```

[50]: class context_flow(tf.keras.layers.Layer):
    def __init__(self):
        super().__init__()

        self.avg_pool      = AveragePooling2D((2, 2), (2, 2), name = 'CF1_pool'␣
→)
        self.conv_1        = Conv2D(64, (3, 3), padding = 'same', name =␣
→'CF1_conv1', kernel_initializer='he_normal', activation='relu')
        self.conv_2        = Conv2D(64, (3, 3), padding = 'same', name =␣
→'CF1_conv2', kernel_initializer='he_normal', activation='relu')
        self.conv_3        = Conv2D(64, (1, 1), padding = 'same', name =␣
→'CF1_conv3', kernel_initializer='he_normal', activation='relu')
        self.activation_relu = Activation('relu')
        self.conv_4        = Conv2D(64, (1, 1), padding = 'same', name =␣
→'CF1_conv4', kernel_initializer='he_normal', activation='relu')
        self.activation_sigmoid = Activation('sigmoid')
        self.upsample      = Conv2DTranspose(64, (33, 33), use_bias = False,␣
→kernel_initializer='he_normal', activation='relu')

    def call(self, X):
        # here X will a list of two elements
        INP, FLOW = X[0], X[1]

        X = tf.keras.layers.concatenate([INP, FLOW], axis=-1)
        # implement the context flow as mentioned in the above cell

        X_avg_pool = self.avg_pool(X) # avg pool

        X_conv_3_3 = self.conv_1(X_avg_pool) # conv 3*3

```

```

X_conv_1_1_1 = self.conv_3(X_conv_3_3) # conv 1*1

X_relu      = self.activation_relu(X_conv_1_1_1) # relu

X_conv_1_1_2 = self.conv_4(X_relu) # conv 1*1

X_sigmoid = self.activation_sigmoid(X_conv_1_1_2) # sigmoid

X_mul = tf.math.multiply(X_conv_3_3 , X_sigmoid)

X_add = tf.math.add(X_conv_3_3, X_mul)

X = self.upsample(X_add)

return X

```

## 10 FSM

- As shown in the above architecture we will be having 4 context flows
- if you have implemented correctly all the shapes of Global Flow, and 3 context flows will have the same dimension
- the output of these 4 modules will be added to get the same output matrix
- The output of after the sum, will be sent to the Feature selection module *FSM*
- Example:
  - if the shapes of GF, CF1, CF2, CF3 are (64,64,32), (64,64,32), (64,64,32), (64,64,32), (64,64,32) respectively then after the sum we will be getting (64,64,32), which will be passed to the next module.

Feature selection module:

- As part of the FSM we will be applying a conv layer (3,3) with the padding="same" so that the output and input will have same shapes
- Let call the output as X
- Pass the X to global pooling which results the matrix (#, 1, 1, number\_of\_channels)
- Apply 1 \* 1 conv layer, after the pooling
- the output of the 1 \* 1 conv layer will be passed to the Batch normalization layer, followed by Sigmoid activation function.
- we will be having the output matrix of shape (#, 1, 1, number\_of\_channels) lets call it 'Y'
- we can interpret this as attention mechanism, i.e for each channel we will having a weight

- the dimension of X (#, w, h, k) and output above steps Y is (#, 1, 1, k) i.e we need to multiply each channel of X will be multiplied with corresponding channel of Y
- After creating the weighted channel map we will be doing upsampling such that it will double the height and width.
- apply upsampling with bilinear pooling as interpolation technique
- Example:
  - Assume the matrix shape of the input is (64,64,32) then after upsampling it will be (128,128,32)

```
[51]: class fsm(tf.keras.layers.Layer):
    def __init__(self):
        super().__init__()

        self.conv_3_3 = Conv2D(32, (3, 3), activation='relu', padding_
        ⇨ 'same', name = 'FS_conv1', kernel_initializer='he_normal',)
        self.avg_pool = tf.keras.layers.GlobalAveragePooling2D( name_
        ⇨ 'FS_pool') # GlobalMaxPooling2D # GlobalAveragePooling2D
        self.conv_1_1 = Conv2D(32, (1,1), activation='relu', name =_
        ⇨ 'FS_conv2', kernel_initializer='he_normal',)
        self.bn = BatchNormalization()
        self.sigmoid = Activation('sigmoid')
        self.upsample = UpSampling2D((2,2), interpolation='bilinear')

    def call(self, X):
        # implement the FSM modules based on image in the above cells

        X_conv_3_3 = self.conv_3_3(X)

        X_global_avg_pool = self.avg_pool(X_conv_3_3)

        X_global_avg_pool = tf.expand_dims(X_global_avg_pool, axis=1)
        X_global_avg_pool = tf.expand_dims(X_global_avg_pool, axis=2)

        X_conv_1_1 = self.conv_1_1(X_global_avg_pool)

        X_bn = self.bn(X_conv_1_1)

        X_sigmoid = self.sigmoid(X_bn)

        x = tf.math.multiply(X_conv_3_3, X_sigmoid)
```

```
x = self.upsample(x)

return x
```

## 11 AGCN

- Adapted Global Convolutional Network (AGCN):
  - AGCN will get the input from the output of the “conv block” of  $C_1$
  - In all the above layers we will be using the padding=“same” and stride=(1,1)
  - so that we can have the input and output matrices of same size
- Example:
  - Assume the matrix shape of the input is (128,128,32) then the output it will be (128,128,32)

```
[52]: class agcn(tf.keras.layers.Layer):
    def __init__(self):
        super().__init__()
        name = "global_conv_net"

        self.conv_1 = Conv2D(32, (7, 1), strides=(1, 1), activation='relu',
        ↪padding = 'same', name = 'AG_conv1', kernel_initializer='he_normal',)
        self.conv_2 = Conv2D(32, (1, 7), strides=(1, 1), activation='relu',
        ↪padding = 'same', name = 'AG_conv2', kernel_initializer='he_normal',)

        self.conv_3 = Conv2D(32, (1, 7), strides=(1, 1),
        ↪activation='relu',padding = 'same', name = 'AG_conv3',
        ↪kernel_initializer='he_normal',)
        self.conv_4 = Conv2D(32, (7, 1), strides=(1, 1),
        ↪activation='relu',padding = 'same', name = 'AG_conv4',
        ↪kernel_initializer='he_normal',)

        self.conv_5 = Conv2D(32, (3, 3), strides=(1, 1),
        ↪activation='relu',padding = 'same', name = 'AG_conv5',
        ↪kernel_initializer='he_normal',)

    def call(self, X):
        # please implement the above mentioned architecture
        X_7_1_1 = self.conv_1(X)
        X_1_7_1 = self.conv_2(X_7_1_1)

        X_1_7_2 = self.conv_3(X)
        X_7_1_2 = self.conv_4(X_1_7_2)
```



```

X_res_input = tf.math.add(X_1_7_1, X_7_1_2)

X_res = self.conv_5(X_res_input)

X = tf.math.add(X_res_input, X_res)

return X

```

- `<img src='https://i.imgur.com/prH3Mno.png' width="600">`
- as shown in the architecture, after we get the AGCN it will get concatenated with the FSM output
- If we observe the shapes both AGCN and FSM will have same height and weight
- we will be concatenating both these outputs over the last axis
- The concatenated output will be passed to a conv layers with filters = number of classes in our data set and the activation function = 'relu'
- we will be using padding="same" which results in the same size feature map
- If you observe the shape of matrix, it will be 4x times less than the original image
- to make it equal to the original output shape, we will do 4x times upsampling of rows and columns
- apply upsampling with bilinear pooling as interpolation technique
- Finally we will be applying sigmoid activation.
- Example:
  - Assume the matrix shape of AGCN is (128,128,32) and FSM is (128,128,32) the concatenation will make it (128, 128, 64)
  - Applying conv layer will make it (128,128,21)
  - Finally applying upsampling will make it (512, 512, 21)
  - Applying sigmoid will result in the same matrix (512, 512, 21)

## 12 CANET Model

```

[53]: tf.keras.backend.clear_session()

X_input = Input(shape=(512,512,3))

X = Conv2D(64, (3, 3), name='conv1', padding="same",
↪kernel_initializer='he_normal', activation='relu')(X_input)
X = BatchNormalization()(X)
X = Activation('relu')(X)
X = MaxPooling2D((2, 2), strides=(2, 2))(X)

```

```

# C_1 BLOCK
X_ag = convolutional_block(filters=[4, 4, 8], stride=2, layer_name="C_1") (X)
X = identity_block(filters=[4, 4, 8], layer_name="C_1_identity_1",
    ↪kernel_size=3) (X_ag)

# C_2 BLOCK
X = convolutional_block(filters = [8, 8, 16], stride = 2, layer_name="C_2") (X)
X = identity_block(filters=[8, 8, 16], layer_name="C_2_identity_1",
    ↪kernel_size=3) (X)
X = identity_block(filters=[8, 8, 16], layer_name="C_2_identity_2",
    ↪kernel_size=3) (X)

# C_3 BLOCK
X = convolutional_block(filters = [16, 16, 32], stride = 1, layer_name="C_3")
    ↪(X)
X = identity_block(filters=[16, 16, 32], layer_name="C_3_identity_1",
    ↪kernel_size=3) (X)
X = identity_block(filters=[16, 16, 32], layer_name="C_3_identity_2",
    ↪kernel_size=3) (X)
X = identity_block(filters=[16, 16, 32], layer_name="C_3_identity_3",
    ↪kernel_size=3) (X)

# C_4 BLOCK
X = convolutional_block(filters = [32, 32, 64], stride = 1, layer_name="C_4") (X)
X = identity_block(filters=[32, 32, 64], layer_name="C_4_identity_1",
    ↪kernel_size=3) (X)
X = identity_block(filters=[32, 32, 64], layer_name="C_4_identity_2",
    ↪kernel_size=3) (X)
X = identity_block(filters=[32, 32, 64], layer_name="C_4_identity_3",
    ↪kernel_size=3) (X)
X = identity_block(filters=[32, 32, 64], layer_name="C_4_identity_4",
    ↪kernel_size=3) (X)

print("C4 {}".format(X.shape))

# Global Flow 1
X_GF = global_flow() (X)

print("GF {}".format(X_GF.shape))

# [Global_flow_output_1 + stage_5_output] ---> Context Flow 1
X_CF_1 = context_flow()(X, X_GF)

```

```

print("CF1 {}".format(X_CF_1.shape))

# [conv_inden + context_flow_1] --> context flow 2
# X_concat_2 = concatenate([X,X_CF_1]) # c12
X_CF_2 = context_flow()([X,X_CF_1])
print("CF2 {}".format(X_CF_2.shape))

# [conv_inden + context_flow_2] --> context flow 3
# X_concat_3 = concatenate([X,X_CF_2]) # c3
X_CF_3 = context_flow()([X,X_CF_2])
print("CF3 {}".format(X_CF_3.shape))

# [all_context_flow + global_flow] --> Feature selection module (FSM)

X_add_1 = Add()([X_GF, X_CF_1, X_CF_2, X_CF_3])
print("X_add {}".format(X_add_1.shape))

X_fsm = fsm()(X_add_1)
print("X_fsm {}".format(X_fsm.shape))

# [first_conv_output] --> AGCN
X_AG = agcn()(X_ag)
print("X_AG {}".format(X_AG.shape))

CF = concatenate([X_fsm, X_AG])

output = tf.keras.layers.Conv2DTranspose(filters=21, kernel_size=(4,4),
↳strides=4, activation='softmax')(CF)

print(output.shape)

# upsaple_last = UpSampling2D((4,4), interpolation = 'bilinear')(CF)

# output = Conv2D(21, (1, 1), padding = 'same', name = 'FinalBlock1',)(output)
↳# , activation = 'softmax'

# output = Activation('softmax')(output)

```

```

C4 (None, 64, 64, 64)
GF (None, 64, 64, 64)
CF1 (None, 64, 64, 64)
CF2 (None, 64, 64, 64)
CF3 (None, 64, 64, 64)
X_add (None, 64, 64, 64)
X_fsm (None, 128, 128, 32)
X_AG (None, 128, 128, 32)

```

(None, 512, 512, 21)

```
[54]: model = Model(inputs = X_input, outputs = output, name = "myModel")
      model.summary()
```

Model: "myModel"

```
-----
Layer (type)                 Output Shape          Param #   Connected to
=====
input_1 (InputLayer)         [(None, 512, 512, 3) 0
-----
conv1 (Conv2D)               (None, 512, 512, 64) 1792      input_1[0][0]
-----
batch_normalization (BatchNorm (None, 512, 512, 64) 256      conv1[0][0]
-----
activation (Activation)      (None, 512, 512, 64) 0
batch_normalization[0][0]
-----
max_pooling2d (MaxPooling2D) (None, 256, 256, 64) 0
activation[0][0]
-----
convolutional_block (convolutio (None, 128, 128, 8)  5160
max_pooling2d[0][0]
-----
identity_block (identity_block) (None, 128, 128, 8)  288
convolutional_block[0][0]
-----
convolutional_block_1 (convolut (None, 64, 64, 16)   2160
identity_block[0][0]
-----
identity_block_1 (identity_bloc (None, 64, 64, 16)   992
convolutional_block_1[0][0]
-----
identity_block_2 (identity_bloc (None, 64, 64, 16)   992
identity_block_1[0][0]
-----
-----
```

```

convolutional_block_2 (convolut (None, 64, 64, 32) 8160
identity_block_2[0][0]
-----
identity_block_3 (identity_bloc (None, 64, 64, 32) 3648
convolutional_block_2[0][0]
-----
identity_block_4 (identity_bloc (None, 64, 64, 32) 3648
identity_block_3[0][0]
-----
identity_block_5 (identity_bloc (None, 64, 64, 32) 3648
identity_block_4[0][0]
-----
convolutional_block_3 (convolut (None, 64, 64, 64) 31680
identity_block_5[0][0]
-----
identity_block_6 (identity_bloc (None, 64, 64, 64) 13952
convolutional_block_3[0][0]
-----
identity_block_7 (identity_bloc (None, 64, 64, 64) 13952
identity_block_6[0][0]
-----
identity_block_8 (identity_bloc (None, 64, 64, 64) 13952
identity_block_7[0][0]
-----
identity_block_9 (identity_bloc (None, 64, 64, 64) 13952
identity_block_8[0][0]
-----
global_flow (global_flow) (None, 64, 64, 64) 16781632
identity_block_9[0][0]
-----
context_flow (context_flow) (None, 64, 64, 64) 4542656
identity_block_9[0][0]
global_flow[0][0]
-----
context_flow_1 (context_flow) (None, 64, 64, 64) 4542656
identity_block_9[0][0]
context_flow[0][0]

```

```

-----
context_flow_2 (context_flow)      (None, 64, 64, 64)    4542656
identity_block_9[0][0]
context_flow_1[0][0]
-----

add (Add)                          (None, 64, 64, 64)    0
global_flow[0][0]
context_flow[0][0]
context_flow_1[0][0]
context_flow_2[0][0]
-----

fsm (fsm)                          (None, 128, 128, 32) 19648      add[0][0]
-----

agcn (agcn)                        (None, 128, 128, 32) 27296
convolutional_block[0][0]
-----

concatenate (Concatenate)          (None, 128, 128, 64) 0          fsm[0][0]
                                           agcn[0][0]
-----

conv2d_transpose_4 (Conv2DTrans (None, 512, 512, 21) 21525
concatenate[0][0]
=====
=====
Total params: 30,596,301
Trainable params: 30,593,693
Non-trainable params: 2,608
-----
-----

```

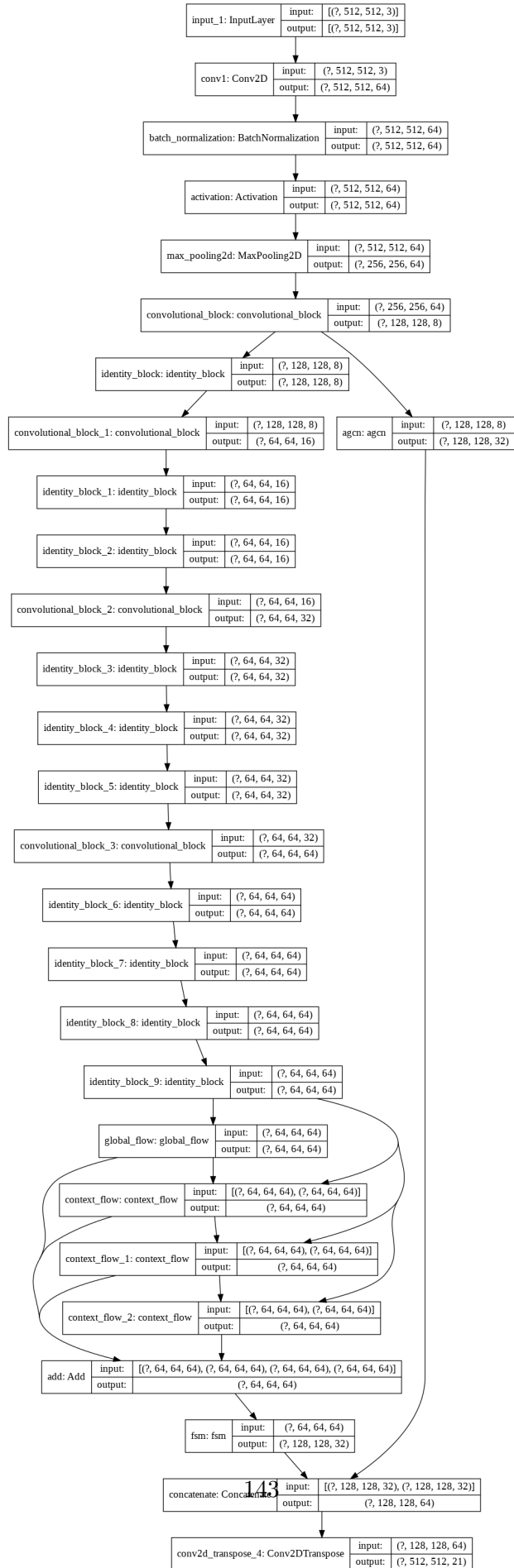
- If you observe the arcitecture we are creating a feature map with 2x time less width and height
- we have written the first stage of the code above.
- Write the next layers by using the custom layers we have written

```

[55]: tf.keras.utils.plot_model(
      model, to_file='CANET_2nd_Implementation.png', show_shapes=True,
      ↪ show_layer_names=True,
      rankdir='TB')

```

[55]:



## 13 Train CANET

```
[56]: import tensorboard
```

```
[57]: import tensorflow as tf
```

```
[58]: canet_model_path = "/content/drive/MyDrive/Colab Notebooks/image segmentation/"
```

```
[59]: global initial_learning_rate
initial_learning_rate = 0.01
global total_epochs
total_epochs = 40

# optim = tf.keras.optimizers.SGD(learning_rate=initial_learning_rate,
↳momentum=0.9)
optim = tf.keras.optimizers.Adam(learning_rate=initial_learning_rate)

focal_loss = sm.losses.cce_dice_loss

model.compile(optim, focal_loss, metrics=[iou_score])

def decay_fn(epoch, lr):

    if epoch > 30:
        return 0.000001
    elif epoch > 20:
        return 0.00001
    elif epoch > 10:
        return 0.0001
    else:
        return 0.001

class CustomCallback(tf.keras.callbacks.Callback):

    def on_train_begin(self, logs={}):
        self.history={'loss': [], 'iou_score': [], 'val_loss': [], 'val_iou_score': []}
        self.init_lr = initial_learning_rate

    def on_epoch_end(self, epoch, logs={}):
```



```

    # print("\n epoch : {} -- learning rate : {}".format(epoch, self.model.
    ↪optimizer.learning_rate))

    self.history['val_loss'].append(logs.get('val_loss'))
    self.history['val_iou_score'].append(logs.get('val_iou_score'))
    self.history['loss'].append(logs.get('loss'))
    self.history['iou_score'].append(logs.get('iou_score'))

    if epoch >= 13:
        loss_1 = self.history['val_loss'][epoch]
        loss_2 = self.history['val_loss'][epoch-1]

        if loss_1 > loss_2:
            self.init_lr = self.init_lr * 0.01
            K.set_value(self.model.optimizer.learning_rate, self.init_lr)

    elif epoch > 2:
        loss_1 = self.history['val_loss'][epoch]
        loss_2 = self.history['val_loss'][epoch-1]

        if loss_1 > loss_2:
            self.init_lr = self.init_lr * 0.55
            K.set_value(self.model.optimizer.learning_rate, self.init_lr)

tensorboard_callback = tf.keras.callbacks.TensorBoard(log_dir='logs/fit',
    ↪histogram_freq=0, profile_batch = 100000000)

lr_scheduler = tf.keras.callbacks.LearningRateScheduler(decay_fn)

early_stop = tf.keras.callbacks.EarlyStopping(monitor = "val_loss", patience =
    ↪5, mode='min')

reduce_lr = tf.keras.callbacks.ReduceLROnPlateau(monitor = 'val_loss', factor =
    ↪0.1, patience = 5, min_lr = 0.000001, mode='min')

customCallback = CustomCallback()

filepath = "/content/drive/MyDrive/Colab Notebooks/Image Segmentation/CANET.h5"

model_checkpoint = tf.keras.callbacks.ModelCheckpoint(filepath, monitor =
    ↪"val_loss", save_best_only=True, verbose = 0, mode='min')

# callbacks

```

```

callBacks = [tensorboard_callback, early_stop, customCallback,]

history = model.fit(train_dataloader,
                    steps_per_epoch=len(train_dataloader),
                    epochs=total_epochs,
                    validation_data=test_dataloader,
                    callbacks=callBacks, )

## hello world, hello world
## hello world,

```

WARNING:tensorflow:Model failed to serialize as JSON. Ignoring... Layer convolutional\_block has arguments in `\_\_init\_\_` and therefore must override `get\_config`.

Epoch 1/40

356/356 [=====] - ETA: 0s - loss: 0.9493 - iou\_score: 0.0897  
 WARNING:tensorflow:Callbacks method `on\_test\_batch\_end` is slow compared to the batch time (batch time: 0.0276s vs `on\_test\_batch\_end` time: 0.0575s). Check your callbacks.

356/356 [=====] - 452s 1s/step - loss: 0.9493 - iou\_score: 0.0897 - val\_loss: 0.9540 - val\_iou\_score: 0.0840

Epoch 2/40

356/356 [=====] - 443s 1s/step - loss: 0.8901 - iou\_score: 0.1224 - val\_loss: 0.8974 - val\_iou\_score: 0.1205

Epoch 3/40

356/356 [=====] - 447s 1s/step - loss: 0.8777 - iou\_score: 0.1291 - val\_loss: 0.9049 - val\_iou\_score: 0.1185

Epoch 4/40

356/356 [=====] - 445s 1s/step - loss: 0.8648 - iou\_score: 0.1385 - val\_loss: 0.9999 - val\_iou\_score: 0.1061

Epoch 5/40

356/356 [=====] - 444s 1s/step - loss: 0.8462 - iou\_score: 0.1497 - val\_loss: 0.8738 - val\_iou\_score: 0.1347

Epoch 6/40

356/356 [=====] - 442s 1s/step - loss: 0.8412 - iou\_score: 0.1543 - val\_loss: 0.8931 - val\_iou\_score: 0.1285

Epoch 7/40

356/356 [=====] - 449s 1s/step - loss: 0.8393 - iou\_score: 0.1547 - val\_loss: 0.8508 - val\_iou\_score: 0.1497

Epoch 8/40

356/356 [=====] - 446s 1s/step - loss: 0.7750 - iou\_score: 0.2199 - val\_loss: 0.6755 - val\_iou\_score: 0.3292

Epoch 9/40

356/356 [=====] - 447s 1s/step - loss: 0.6341 - iou\_score: 0.3542 - val\_loss: 0.6612 - val\_iou\_score: 0.3456

Epoch 10/40

356/356 [=====] - 450s 1s/step - loss: 0.6380 -

```

iou_score: 0.3512 - val_loss: 0.6752 - val_iou_score: 0.3315
Epoch 11/40
356/356 [=====] - 444s 1s/step - loss: 0.6233 -
iou_score: 0.3611 - val_loss: 0.6485 - val_iou_score: 0.3492
Epoch 12/40
356/356 [=====] - 447s 1s/step - loss: 0.6188 -
iou_score: 0.3639 - val_loss: 0.6415 - val_iou_score: 0.3547
Epoch 13/40
356/356 [=====] - 454s 1s/step - loss: 0.6159 -
iou_score: 0.3663 - val_loss: 0.6472 - val_iou_score: 0.3528
Epoch 14/40
356/356 [=====] - 450s 1s/step - loss: 0.6069 -
iou_score: 0.3721 - val_loss: 0.6342 - val_iou_score: 0.3612
Epoch 15/40
356/356 [=====] - 447s 1s/step - loss: 0.6111 -
iou_score: 0.3696 - val_loss: 0.6350 - val_iou_score: 0.3589
Epoch 16/40
356/356 [=====] - 440s 1s/step - loss: 0.6099 -
iou_score: 0.3718 - val_loss: 0.6315 - val_iou_score: 0.3640
Epoch 17/40
356/356 [=====] - 444s 1s/step - loss: 0.6070 -
iou_score: 0.3731 - val_loss: 0.6316 - val_iou_score: 0.3616
Epoch 18/40
356/356 [=====] - 450s 1s/step - loss: 0.6003 -
iou_score: 0.3766 - val_loss: 0.6346 - val_iou_score: 0.3596
Epoch 19/40
356/356 [=====] - 449s 1s/step - loss: 0.5995 -
iou_score: 0.3769 - val_loss: 0.6335 - val_iou_score: 0.3612
Epoch 20/40
356/356 [=====] - 449s 1s/step - loss: 0.6015 -
iou_score: 0.3763 - val_loss: 0.6404 - val_iou_score: 0.3607
Epoch 21/40
356/356 [=====] - 447s 1s/step - loss: 0.6035 -
iou_score: 0.3747 - val_loss: 0.6333 - val_iou_score: 0.3606

```

```

[60]: # model.load_weights("/content/drive/MyDrive/Colab Notebooks/image segmentation/
↪best_model_2.h5")
canet_model_path = "/content/drive/MyDrive/Colab Notebooks/Image Segmentation/
↪CANET.h5"

```

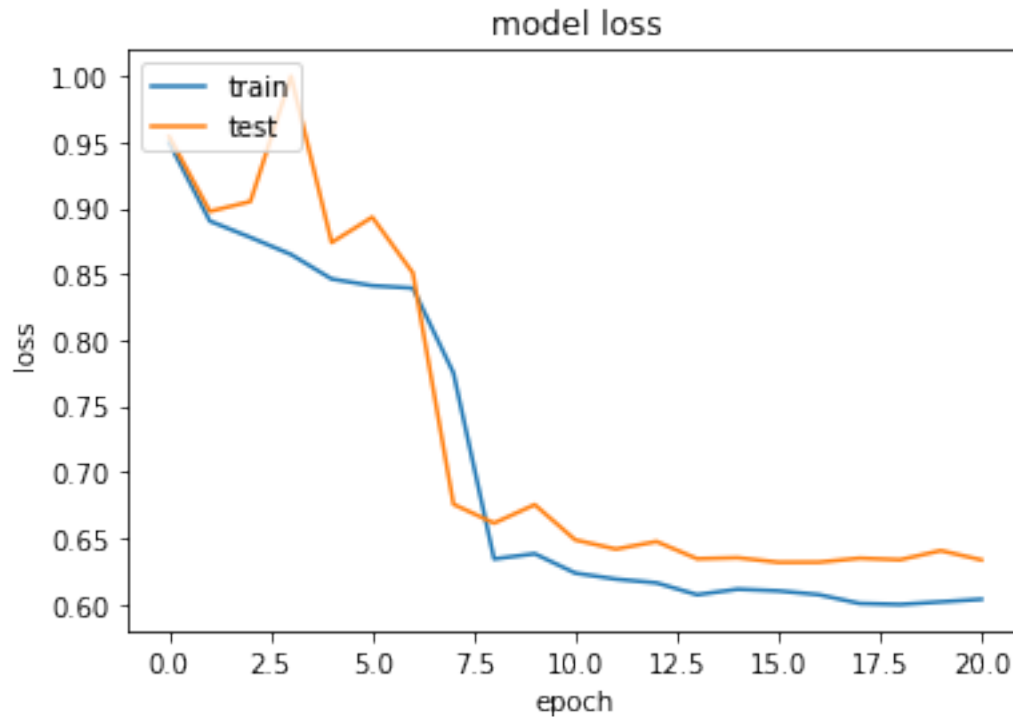
```

[61]: model.save_weights(canet_model_path)
model.load_weights(canet_model_path)

```

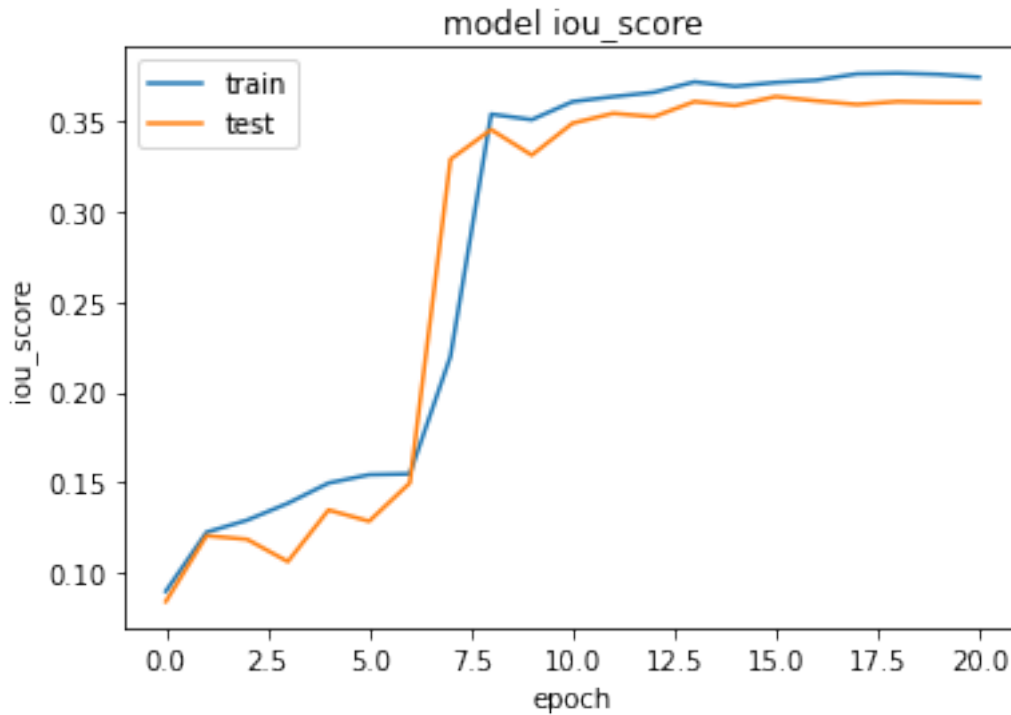
## 14 CANET Loss

```
[62]: plt.plot(history.history['loss'])
plt.plot(history.history['val_loss'])
plt.title('model loss')
plt.ylabel('loss')
plt.xlabel('epoch')
plt.legend(['train', 'test'], loc='upper left')
plt.show()
```



## 15 CANET IOU SCORE

```
[63]: plt.plot(history.history['iou_score'])
plt.plot(history.history['val_iou_score'])
plt.title('model iou_score')
plt.ylabel('iou_score')
plt.xlabel('epoch')
plt.legend(['train', 'test'], loc='upper left')
plt.show()
```



```
[64]: %load_ext tensorboard
      %tensorboard --logdir logs/fit
```

<IPython.core.display.Javascript object>

```
[65]: # model.load_weights(canet_model_path)
```

```
[78]: def show_predicted_image(true_image, true_mask):
      #original image
      # image = cv2.imread(true_image, cv2.IMREAD_UNCHANGED)
      # image = cv2.resize(image, (256, 256), cv2.INTER_NEAREST)
      # image = cv2.normalize(image, None, alpha=0, beta=1, norm_type=cv2.
      ↪NORM_MINMAX, dtype=cv2.CV_32F)

      image = cv2.imread(true_image, cv2.IMREAD_UNCHANGED)
      image = cv2.cvtColor(image, cv2.COLOR_BGR2RGB)
      image = cv2.resize(image, (512, 512), cv2.INTER_NEAREST)
      image = preprocess_image(image)

      #predicted segmentation map
      predicted = model.predict(image[np.newaxis,:,:,:])
      predicted = tf.argmax(predicted, axis=-1)
```

```

print("shape {}".format(predicted.shape))
#print("shape 1 {}".format(predicted[0,:,:,:0].shape))

#original segmentation map
image_mask = cv2.imread(true_mask, cv2.IMREAD_UNCHANGED)
image_mask = cv2.resize(image_mask, (256,256), cv2.INTER_NEAREST)

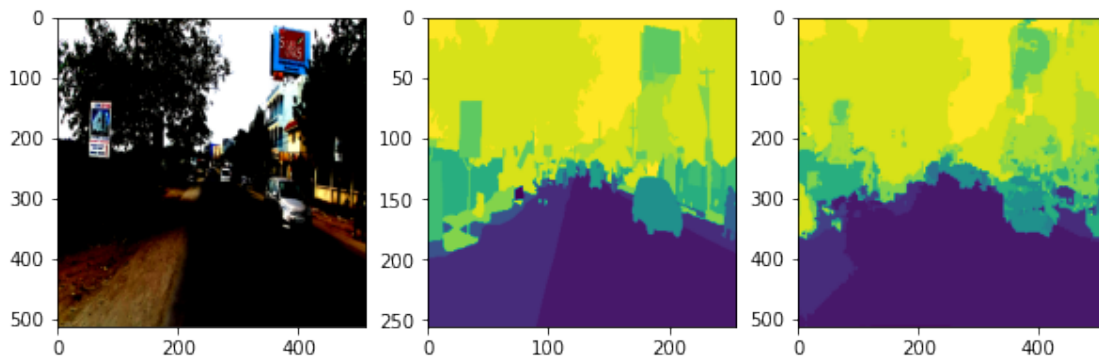
plt.figure(figsize=(10,6))
plt.subplot(131)
plt.imshow(image)
plt.subplot(132)
plt.imshow(image_mask) # , cmap='gray', vmax=1, vmin=0
plt.subplot(133)
# plt.imshow(predicted[0,:,:,:0], cmap='gray', vmax=0.001, vmin=0.0001)
plt.imshow(predicted[0])
plt.show()

```

```
[79]: show_predicted_image(np.array(X_test['image'])[0], np.array(X_test['mask'])[0])
```

Clipping input data to the valid range for imshow with RGB data ([0..1] for floats or [0..255] for integers).

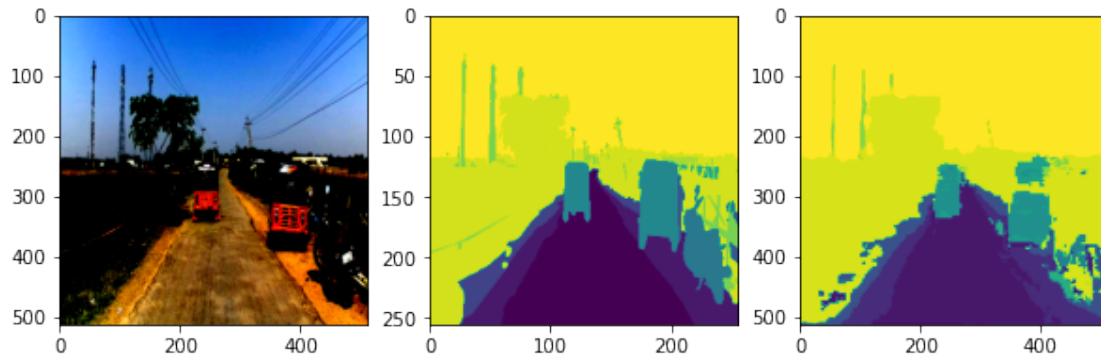
shape (1, 512, 512)



```
[80]: show_predicted_image(np.array(X_test['image'])[1], np.array(X_test['mask'])[1])
```

Clipping input data to the valid range for imshow with RGB data ([0..1] for floats or [0..255] for integers).

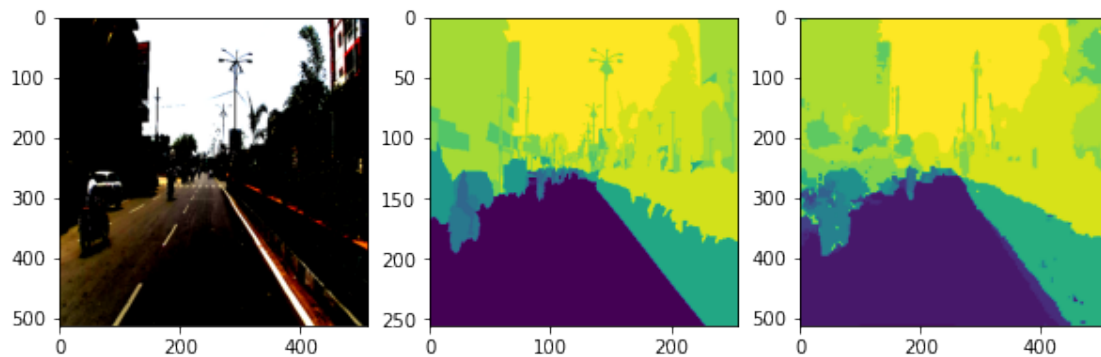
shape (1, 512, 512)



```
[81]: show_predicted_image(np.array(X_test['image'])[2], np.array(X_test['mask'])[2])
```

Clipping input data to the valid range for imshow with RGB data ([0..1] for floats or [0..255] for integers).

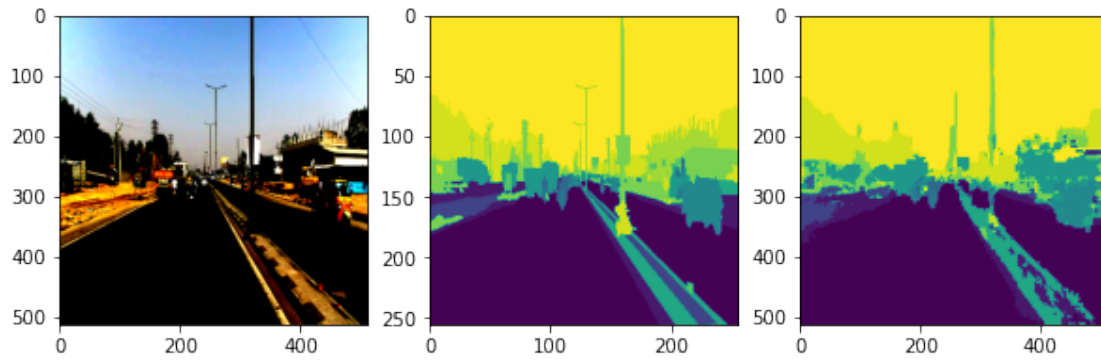
shape (1, 512, 512)



```
[82]: show_predicted_image(np.array(X_test['image'])[3], np.array(X_test['mask'])[3])
```

Clipping input data to the valid range for imshow with RGB data ([0..1] for floats or [0..255] for integers).

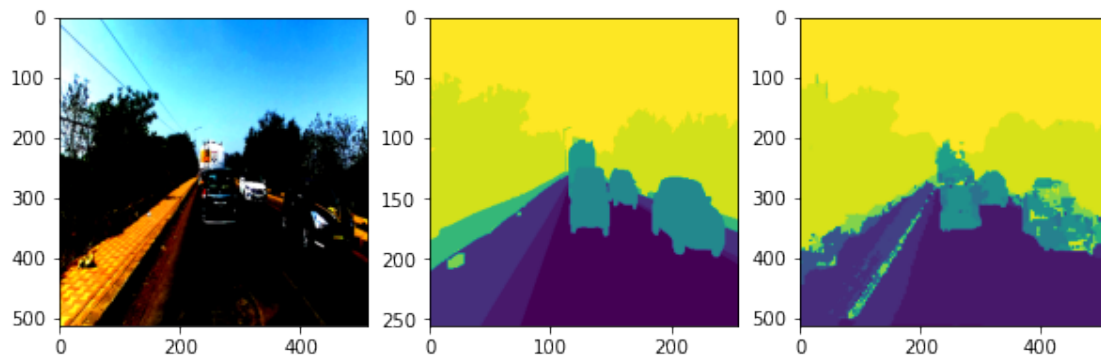
shape (1, 512, 512)



```
[83]: show_predicted_image(np.array(X_test['image'])[4], np.array(X_test['mask'])[4])
```

Clipping input data to the valid range for imshow with RGB data ([0..1] for floats or [0..255] for integers).

shape (1, 512, 512)

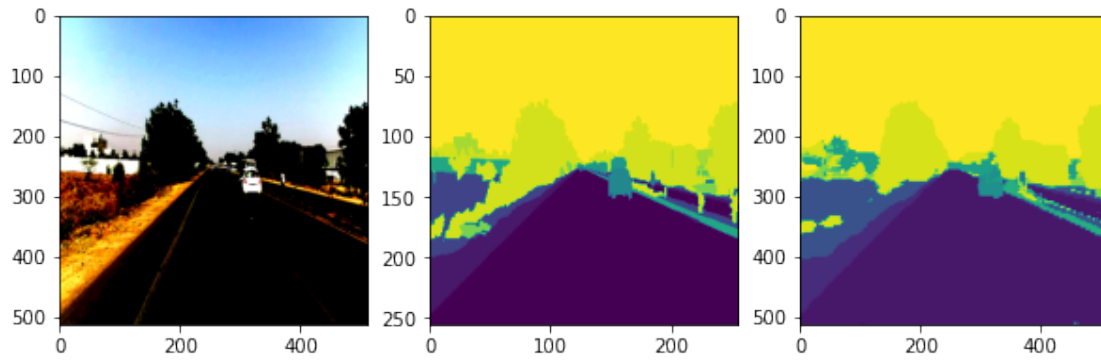


```
[84]: show_predicted_image(np.array(X_test['image'])[5], np.array(X_test['mask'])[5])
```

Clipping input data to the valid range for imshow with RGB data ([0..1] for floats or [0..255] for integers).

shape (1, 512, 512)

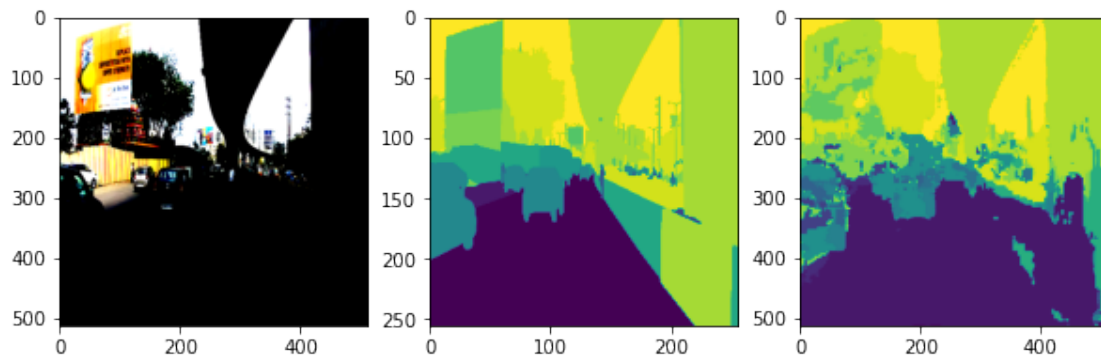




```
[85]: show_predicted_image(np.array(X_test['image'])[6], np.array(X_test['mask'])[6])
```

Clipping input data to the valid range for imshow with RGB data ([0..1] for floats or [0..255] for integers).

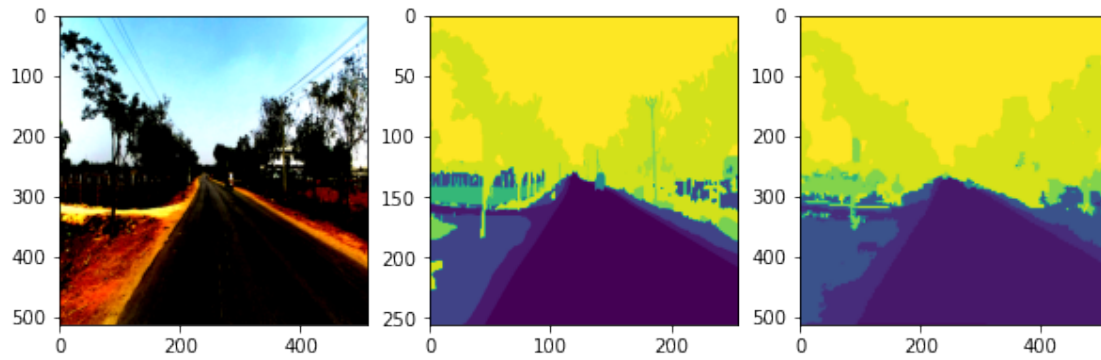
```
shape (1, 512, 512)
```



```
[86]: show_predicted_image(np.array(X_test['image'])[7], np.array(X_test['mask'])[7])
```

Clipping input data to the valid range for imshow with RGB data ([0..1] for floats or [0..255] for integers).

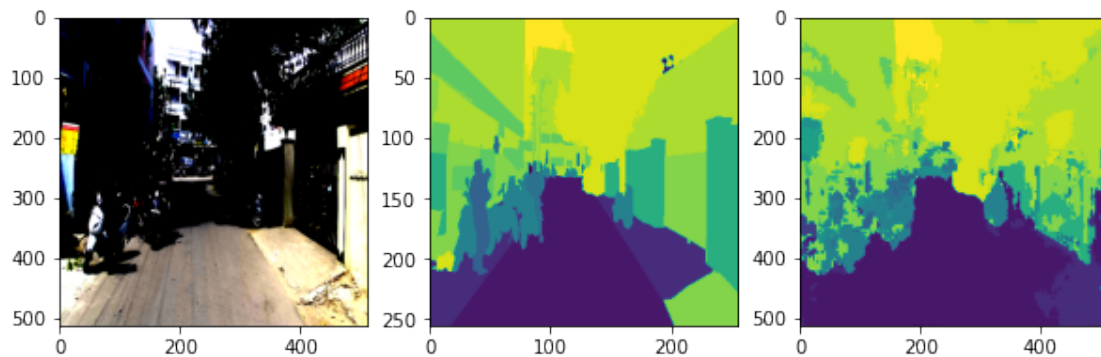
```
shape (1, 512, 512)
```



```
[87]: show_predicted_image(np.array(X_test['image'])[8], np.array(X_test['mask'])[8])
```

Clipping input data to the valid range for imshow with RGB data ([0..1] for floats or [0..255] for integers).

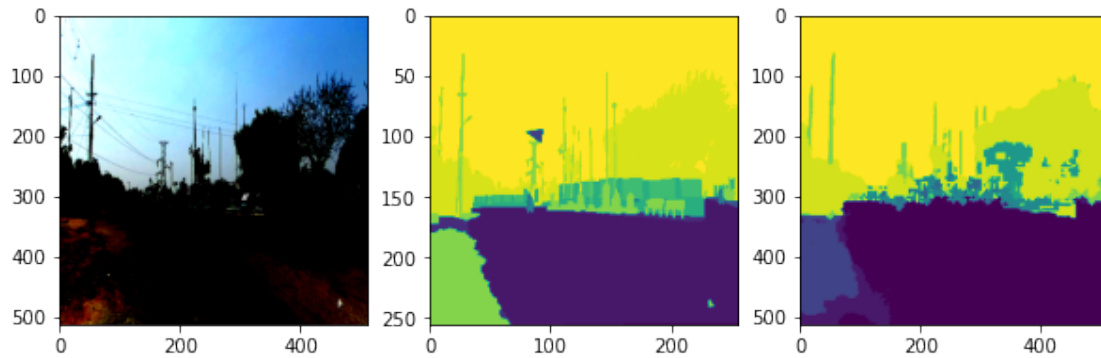
```
shape (1, 512, 512)
```



```
[88]: show_predicted_image(np.array(X_test['image'])[9], np.array(X_test['mask'])[9])
```

Clipping input data to the valid range for imshow with RGB data ([0..1] for floats or [0..255] for integers).

```
shape (1, 512, 512)
```



## 16 Dice Loss

```
[89]: """
1. formula
-----
2 * (common objects between pred_mask and actual mask) / (all the objects in_
    ↳actual mask + all the objects in predicted mask)

2. Range
-----
[0, 1]

3. Interpretation and How is it helpful in segmentation.
-----

1. Dice loss is very useful when a image is very unbalanced(majority of pixels_
    ↳belongs to a object class),
    because it does not calculate loss by comparing pixels of predicted mask and_
    ↳targeted mark,
    unlike pixel wise cross entropy.

"""
```

```
[89]: '\n1. formula\n-----\n2 * (common objects between pred_mask and actual mask)
/ (all the objects in actual mask + all the objects in predicted mask)\n\n2.
Range\n-----\n[0, 1]\n\n3. Interpretation and How is it helpful in
segmentation.\n-----\n\n1. Dice loss is very
useful when a image is very unbalanced(majority of pixels belongs to a object
class),\n    because it does not calculate loss by comparing pixels of predicted
mask and targeted mark,\n    unlike pixel wise cross entropy.\n\n'
```

### 16.0.1 Usefull tips:

- use “interpolation=cv2.INTER\_NEAREST” when you are resizing the image, so that it won’t mess with the number of classes
- keep the images in the square shape like  $256 * 256$  or  $512 * 512$
- Carefull when you are converting the (W, H) output image into (W, H, Classes)
- Even for the canet, use the segmentation model’s losses and the metrics
- The goal of this assignment is make you familier in with computer vision problems, image preprocessing, building complex architectures and implementing research papers, so that in future you will be very confident in industry
- you can use the tensorboard logss to see how is yours model’s training happening
- use callbacks that you have implemented in previous assignments

### 16.0.2 Things to keep in mind

- You need to train above built model and plot the train and test losses.
- Make sure there is no overfitting, you are free play with the identity blocks in C1, C2, C3, C4
- before we apply the final sigmoid activation, you can add more conv layers or BN or dropouts etc
- you are free to use any other optimizer or learning rate or weights init or regularizations

[89] :