



# SYNC or Swim

## A Particle Model of the Interaction within Fish Schools

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The coordination of events to operate a system in unison.  
Some examples:

- Circadian Rhythms

The coordination of events to operate a system in unison.  
Some examples:

- Animal Swarming



The coordination of events to operate a system in unison.  
Some examples:

- Human Imitation (Memes/Trends)





The coordination of events to operate a system in unison.  
Some examples:

- Round of Applause

# Example - Human Grouping



Rules to Follow:

- **Walk** slowly toward center of the group.
- **Slow down** if you're within two feet of another person.
- **Stop** if you are within one foot of another person.

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- The coordinated behavior of animals of the same species and the emergent properties that arise.
- For mathematical purposes, consider a swarm as an emergent behavior with no central coordination.



- Learning C/CUDA
- Applying mathematical models to real life phenomenon
- How will environmental factors affect the animal aggregate
- How animal aggregates will affect the environment

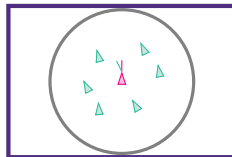


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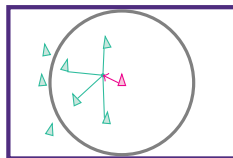
- **Alignment**





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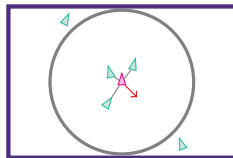
- **Alignment**
- **Cohesion**





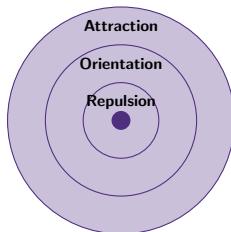
Our model represents each fish adhering to the following three rules:

- **Alignment**
- **Cohesion**
- **Separation**





- Lagrangian Algorithm
- Metric distance model



# Attractive and Repulsive Forces Between Fish



- Attraction between a fish  $i$  and neighbor  $j$  :

$$A = C_a \frac{p_j - p_i}{d^2}$$





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- Repulsion between fish  $i$  and neighbor  $j$ :

$$R = -C_r \frac{p_j - p_i}{d^4}$$



$$A = C_a \frac{p_j - p_i}{d^2}$$

$$R = -C_r \frac{p_j - p_i}{d^4}$$

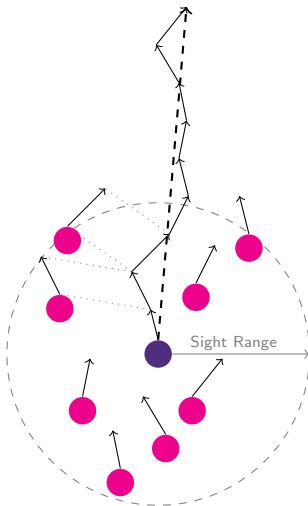
- Overall Attraction:

$$F_A = C_a \frac{p_j - p_i}{d^2} - C_r \frac{p_j - p_i}{d^4}$$

# Directional Alignment of Fish $i$



$$F_{D_i} = \sum_{j=1}^N \frac{v_j}{\|p_i - p_j\|}$$



# Total Force on Fish $i$ From All Neighbors



$$F_{i_N} = \sum_{j=1}^N \left( W_a \left( C_a \frac{p_j - p_i}{d^2} - C_r \frac{p_j - p_i}{d^4} \right) + W_d \left( \frac{v_j}{\|p_i - p_j\|} \right) \right) \quad (1)$$

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$$F_{iN} = \sum_{j=1}^N \left( W_a \left( C_a \frac{p_j - p_i}{d^2} - C_r \frac{p_j - p_i}{d^4} \right) + W_d \left( \frac{v_j}{\|p_i - p_j\|} \right) \right) \quad (1)$$

And, acceleration of each fish is the same as our force (taking each mass to be 1).

# Calculating Forces, Velocities, and Positions



At every timestep, the following calculations occur for each particle (let's call it particle  $i$ ):

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# Calculating Forces, Velocities, and Positions



At every timestep, the following calculations occur for each particle (let's call it particle  $i$ ):

- 1 Calculate  $\|p_i - p_j\|$ .

# Calculating Forces, Velocities, and Positions



At every timestep, the following calculations occur for each particle (let's call it particle  $i$ ):

- 2 If the  $\|p_i - p_j\| < \text{SIGHT}$ , use (1) to determine the force between particle  $j$  and particle  $i$ , and sum forces over all particles within SIGHT of particle  $i$  ( $F_{iN}$ ).



# Calculating Forces, Velocities, and Positions



At every timestep, the following calculations occur for each particle (let's call it particle  $i$ ):

- 3 Use  $F_{iN}$  calculated above to update particle  $i$ 's velocity as follows:

$$v_i = v_i + F_{iN} \cdot dt$$

# Calculating Forces, Velocities, and Positions



At every timestep, the following calculations occur for each particle (let's call it particle  $i$ ):

.

- 4 And update particle  $i$ 's position using:

$$p_i = p_i + v_i \cdot dt$$







# Where Do We Go From Here?



- Add initial conditions for species-specific parameters
  - Density of swarms, how they behave towards targets and obstacles, etc.
- Move calculations from CPU to GPU to speed up calculation time



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## QUESTIONS?

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`github.com/dpebert7/sync`