



SYNC or Swim

A Particle Model of the Interaction within Fish Schools

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The coordination of events to operate a system in unison.
Some natural physical examples:

- Circadian Rhythms
- Round of Applause (WHAT?!?! - Let's try it!)

Example - Human Grouping



One object influencing another by providing feedback.
Real life examples

- Animal Swarming



One object influencing another by providing feedback.
Real life examples

- Human Imitation (Memes/Trends)





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- For mathematical purposes, consider a swarm as an emergent behavior with no central coordination that arises due to several simple instinctual rule that animals of a given species follow.
- Other terms we will be using interchangeably with “collective behavior”: swarm, school(specific to fish), aggregate



- Learning C/CUDA
- Applying mathematical models to real life phenomenon
- How will environmental factors affect the animal aggregate
- How animal aggregates will affect the environment

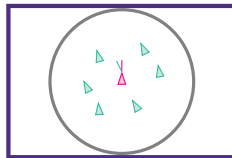


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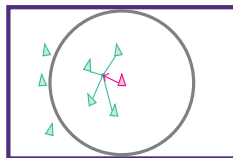
- **Alignment**





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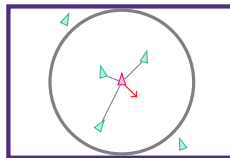
- **Alignment**
- **Cohesion**





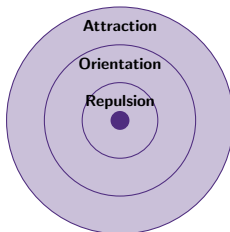
Our model represents each fish adhering to the following three rules:

- **Alignment**
- **Cohesion**
- **Separation**





- Lagrangian Algorithm
- Metric distance model



Attractive and Repulsive Forces Between Fish



- Attraction between a fish i and neighbor j :

$$A = C_a \frac{p_j - p_i}{d^2}$$

Attractive and Repulsive Forces Between Fish



$$A = C_a \frac{p_j - p_i}{d^2}$$

- Repulsion between fish i and neighbor j :

$$R = -C_r \frac{p_j - p_i}{d^4}$$



$$A = C_a \frac{p_j - p_i}{d^2}$$

$$R = -C_r \frac{p_j - p_i}{d^4}$$

- Overall Attraction:

$$F_A = C_a \frac{p_j - p_i}{d^2} - C_r \frac{p_j - p_i}{d^4}$$

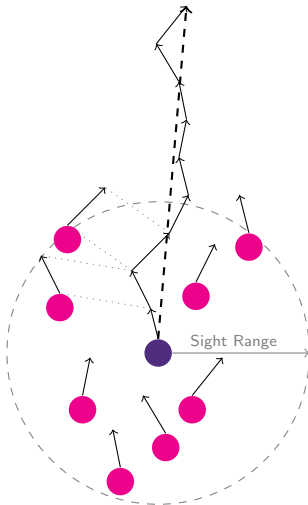
The Attraction and Repulsion Coefficients



Directional Alignment of Fish i



$$F_{D_i} = \sum_{j=1}^N \frac{v_j}{\|p_i - p_j\|}$$



Total Force on Fish i From All Neighbors



$$F_{i_N} = \sum_{j=1}^N \left(W_a \left(C_a \frac{p_j - p_i}{d^2} - C_r \frac{p_j - p_i}{d^4} \right) + W_d \left(\frac{v_j}{\|p_i - p_j\|} \right) \right) \quad (1)$$

Total Force on Fish i From All Neighbors



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And, acceleration of each fish is the same as our force (taking each mass to be 1).

Calculating Forces, Velocities, and Positions



At every timestep, the following calculations occur for each particle (let's call it particle i):

Calculating Forces, Velocities, and Positions



At every timestep, the following calculations occur for each particle (let's call it particle i):

- 1 Calculate $||p_i - p_j||$

Calculating Forces, Velocities, and Positions



At every timestep, the following calculations occur for each particle (let's call it particle i):

- 2 If the $\|p_i - p_j\| < \text{SIGHT}$, use (1) to determine the force between particle j and particle i , and sum forces over all particles within SIGHT of particle i (F_{iN})

Calculating Forces, Velocities, and Positions



At every timestep, the following calculations occur for each particle (let's call it particle i):

- 3 Use F_{iN} calculated above to update particle i 's velocity as follows:

$$v_i = v_i + a_i \cdot dt$$

Calculating Forces, Velocities, and Positions



At every timestep, the following calculations occur for each particle (let's call it particle i):

- 4 And update particle i 's position using:

$$p_i = p_i + v_i \cdot dt$$







Where Do We Go From Here?



- Add initial conditions for species-specific parameters
 - Density of swarms, how they behave towards targets and obstacles, etc.
- Move calculations from CPU to GPU to speed up calculation time



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QUESTIONS?