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25. svibnja 2011.



## Q LEARNING

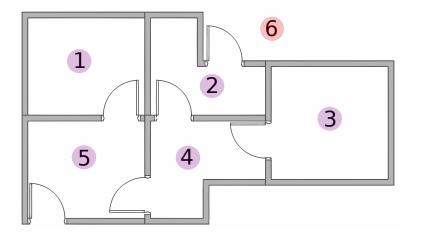
- Tehnika učenja s podrškom.
- Agent uči evaluacijsku funkciju

$$Q:S\times A\to\mathbb{R}$$

gdje je S skup stanja, a A skup akcija akcija.

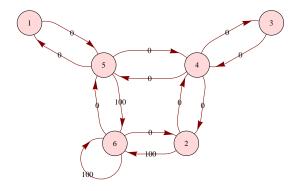
Agentu ne mora biti poznat model okoliša.

#### KRETANJE ROBOTA



SLIKA: Agent se nalazi u jednoj od soba, mora izaći van





SLIKA: Dijagram stanja prethodnog tlocrta



$$\begin{array}{c}
\longrightarrow \begin{bmatrix}
- & - & - & - & 0 & - \\
- & - & - & 0 & - & 100 \\
- & - & - & 0 & - & - & - \\
- & 0 & 0 & - & 0 & - & - \\
0 & - & - & 0 & - & 100 \\
- & 0 & - & - & 0 & 100
\end{bmatrix}
\qquad Q = \begin{bmatrix}
0 & 0 & 0 & 0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 & 0 & 0 & 0
\end{bmatrix}$$

Opis algoritma

$$Q_{2,6} = R_{2,6} + 0.8 \cdot \max\{Q_{6,2}, Q_{6,5}, Q_{6,6}\} = 100 + 0.8 \cdot 0 = 100$$



Opis algoritma

$$Q_{2,6} = R_{2,6} + 0.8 \cdot \max\{Q_{6,2}, Q_{6,5}, Q_{6,6}\} = 100 + 0.8 \cdot 0 = 100$$



Opis algoritma

$$Q_{4,2} = R_{4,2} + 0.8 \cdot \max\{Q_{2,4}, Q_{2,6}\} = 0 + 0.8 \cdot 100 = 80$$



$$Q_{2,6} = R_{2,6} + 0.8 \cdot \max\{Q_{6,2}, Q_{6,5}, Q_{6,6}\} = 100 + 0.8 \cdot 0 = 100$$



$$Q = \begin{bmatrix} 0 & 0 & 0 & 0 & 400 & 0 \\ 0 & 0 & 0 & 320 & 0 & 500 \\ 0 & 0 & 0 & 320 & 0 & 0 \\ 0 & 400 & 256 & 0 & 400 & 0 \\ 320 & 0 & 0 & 320 & 0 & 500 \\ 0 & 400 & 0 & 0 & 400 & 500 \end{bmatrix}$$

$$Q = \begin{bmatrix} 0 & 0 & 0 & 0 & 400 & 0 \\ 0 & 0 & 0 & 320 & 0 & 500 \\ 0 & 0 & 0 & 320 & 0 & 0 \\ 0 & 400 & 256 & 0 & 400 & 0 \\ 320 & 0 & 0 & 320 & 0 & 500 \\ 0 & 400 & 0 & 0 & 400 & 500 \end{bmatrix}$$

$$Q = \begin{bmatrix} 0 & 0 & 0 & 0 & 400 & 0 \\ 0 & 0 & 0 & 320 & 0 & 500 \\ 0 & 0 & 0 & 320 & 0 & 0 \\ 0 & 400 & 256 & 0 & 400 & 0 \\ 320 & 0 & 0 & 320 & 0 & 500 \\ 0 & 400 & 0 & 0 & 400 & 500 \end{bmatrix}$$

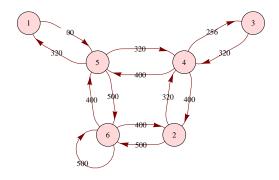
 $PUT: 3 \rightarrow 4$ 

$$Q = \begin{bmatrix} 0 & 0 & 0 & 0 & 400 & 0 \\ 0 & 0 & 0 & 320 & 0 & 500 \\ 0 & 0 & 0 & 320 & 0 & 0 \\ 0 & 400 & 256 & 0 & 400 & 0 \\ 320 & 0 & 0 & 320 & 0 & 500 \\ 0 & 400 & 0 & 0 & 400 & 500 \end{bmatrix}$$

$$Q = \begin{bmatrix} 0 & 0 & 0 & 0 & 400 & 0 \\ 0 & 0 & 0 & 320 & 0 & 500 \\ 0 & 0 & 0 & 320 & 0 & 0 \\ 0 & 400 & 256 & 0 & 400 & 0 \\ 320 & 0 & 0 & 320 & 0 & 500 \\ 0 & 400 & 0 & 0 & 400 & 500 \end{bmatrix}$$

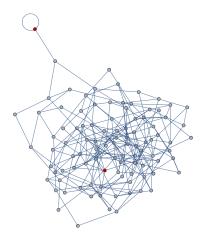
$$Q = \begin{bmatrix} 0 & 0 & 0 & 0 & 400 & 0 \\ 0 & 0 & 0 & 320 & 0 & 500 \\ 0 & 0 & 0 & 320 & 0 & 0 \\ 0 & 400 & 256 & 0 & 400 & 0 \\ 320 & 0 & 0 & 320 & 0 & 500 \\ 0 & 400 & 0 & 0 & 400 & 500 \end{bmatrix}$$

$$Q = \begin{bmatrix} 0 & 0 & 0 & 0 & 400 & 0 \\ 0 & 0 & 0 & 320 & 0 & 500 \\ 0 & 0 & 0 & 320 & 0 & 0 \\ 0 & 400 & 256 & 0 & 400 & 0 \\ 320 & 0 & 0 & 320 & 0 & 500 \\ 0 & 400 & 0 & 0 & 400 & 500 \end{bmatrix}$$



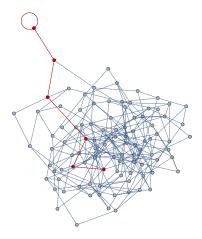
 $\operatorname{SLIKA}$ : Dijagram stanja iz perspektive funkcije Q





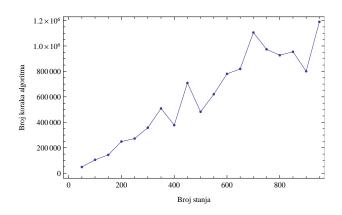
SLIKA: Dijagram sa 100 stanja



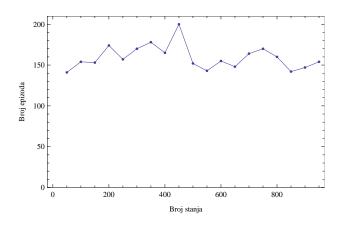


SLIKA: Dijagram sa 100 stanja



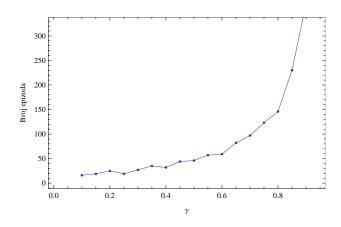


SLIKA: Broj koraka algoritma u odnosu na broj stanja



SLIKA: Broj epizoda u odnosu na broj stanja





 ${f SLIKA}$ : Broj epizoda u odnosu na vrijednost  $\gamma$