Introduction to Information Theory

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Information Theory

- Originally developed by Shannon in 1948 as he was figuring out how to efficiently transmit communication signals over a possibly noisy communication channel.
- I am not so much interested in its original uses in communication theory, but in its development and application as a broadly applicable tool for describing probability distributions.
- Information theory lets us ask and answer questions such as:
 - 1. How random is a sequence of measurements?
 - 2. How much memory is needed to store the outcome of measurements?
 - 3. How much information does one measurement tell us about another?

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Some Info Theory References

- T.M. Cover and J.A. Thomas, Elements of Information Theory. John Wiley & Sons, Inc., 1991. By far the best information theory text around.
- C.E. Shannon and W. Weaver. The Mathematical Theory of Communication. University of Illinois Press. 1962. Shannon's original paper and some additional commentary. Very readable.
- J.P. Crutchfield and D.P. Feldman, "Regularities Unseen, Randomness Observed: Levels of Entropy Convergence." Chaos 15:25–53. 2003.
- 4. Tom Schneider. Information Theory Primer, http://www.lecb.ncifcrf.gov/~toms/paper/primer/. Brief narrative at an elementary level. Includes a review or logarithms.
- Entropy on the World Wide Web. http://www.math. psu.edu/gunesch/entropy.html. A huge list of links. Info theory applied to many different disciplines.
- D.P. Feldman. A Brief Tutorial on: Information Theory, Excess Entropy and Statistical Complexity: Discovering and Quantifying Statistical Structure. http://hornacek. coa.edu/dave/Tutorial/index.html.

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Notation for Probabilities

Information theory is concerned with probabilities. We first fix some notation.

- X is a random variable. The variable X may take values $x \in \mathcal{X}$, where \mathcal{X} is a finite set.
- likewise Y is a random variable, $Y = y \in \mathcal{Y}$.
- The probability that X takes on the particular value x is $\Pr(X=x)$, or just $\Pr(x)$.
- Probability of x and y occurring: $\Pr(X=x,Y=y)$, or $\Pr(x,y)$
- $\bullet \;$ Probability of x, given that y has occurred: $\Pr(X=x|Y=y) \; \text{or} \; \Pr(x|y)$

Example: A fair coin. The random variable X (the coin) takes on values in the set $\mathcal{X}=\{h,t\}$.

$$Pr(X = h) = 1/2$$
, or $Pr(h) = 1/2$.

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Different amounts of uncertainty?

- Anytime we describe a situation with probabilities, it's because we're uncertain of the outcome.
- However, some probability distributions indicate more uncertainty than others.
- ullet We seek a function H[X] that measures the amount of uncertainty associated with outcomes of the random variable X.
- What properties should such an uncertainty function have?
 - 1. Maximized when the distribution over \boldsymbol{X} is uniform.
 - 2. Continuous function of the probabilities of the different outcomes of ${\cal X}$
 - Independent of the way in which we might group probabilities.

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Entropy of a Single Variable

The requirements on the previous page $\emph{uniquely}$ determine H[X], up to a multiplicative constant.

The Shannon entropy of a random variable X is given by:

$$H[X] \equiv -\sum_{x \in \mathcal{X}} \Pr(x) \log_2(\Pr(x))$$
 . (1)

Using base-2 logs gives us units of bits.

Examples

- $\begin{array}{l} \bullet \ \ {\bf Fair\ Coin:}\ \Pr(h) = \frac{1}{2}, \Pr(t) = \frac{1}{2}. \\ H = -\frac{1}{2}\log_2\frac{1}{2} \frac{1}{2}\log_2\frac{1}{2} = 1 \ {\rm bit}. \end{array}$
- Biased Coin: $\Pr(h) = 0.6, \Pr(t) = 0.4.$ $H = -0.6 \log_2 0.6 0.4 \log_2 0.4 = 0.971$ bits.
- More Biased Coin: $\Pr(h) = 0.9, \Pr(t) = 0.1.$ $H = -0.9 \log_2 0.9 0.1 \log_2 0.1 = 0.469 \text{ bits.}$
- Totally Biased Coin: $\Pr(h) = 1.0, \Pr(t) = 0.0.$ $H = -1.0 \log_2 1.0 0.0 \log_2 0.0 = 0.0$ bits.

We now consider various interpretations for the entropy.

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Average Surprise

- $\bullet \log_2 x$ may be viewed as the *surprise* associated with the outcome x.
- ullet Thus, H[X] is the average, or expected value, of the surprise:

$$H[X] = \sum_{x} \left[-\log_2 x \right] \Pr(x) .$$

- The more surprised you are about a measurement, the more informative it is.
- The greater H[X], the more informative, on average, a measurement of X is.

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Difficulty of Guessing

For the next few slides, we'll focus on two examples.

- 1. A random variable X with four equally likely outcomes: $\Pr(a) = \Pr(b) = \Pr(c) = \Pr(d) = \frac{1}{4}.$
- 2. A random variable Y with four outcomes: $\Pr(\alpha) = \frac{1}{2}$, $\Pr(\beta) = \frac{1}{4}$, $\Pr(\gamma) = \frac{1}{8}$, $\Pr(\delta) = \frac{1}{8}$.

What is the optimal strategy for guessing (via yes-no questions) the outcome of a random variable?

- In general, try to divide the probability in half with each guess.
- Example: Guessing X:
 - 1. "is X equal to a or b?"
 - 2. If yes, "is X=a?" If no, "is X=c?"
- Using this strategy, it will always take 2 guesses.
- H[X] = 2. Coincidence???

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Guessing games, continued

What's the best strategy for guessing Y?

$$\Pr(\alpha) = \frac{1}{2}, \Pr(\beta) = \frac{1}{4}, \Pr(\gamma) = \frac{1}{8}, \Pr(\delta) = \frac{1}{8}.$$

- 1. Is it α ? If yes, then done, if no:
- 2. Is it β ? If yes, then done, if no:
- 3. Is it γ ? Either answer, done.

Ave # of guesses = $\frac{1}{2}(1) + \frac{1}{4}(2) + \frac{1}{4}(3) = 1.75$.

Not coincidentally, H[Y] = 1.75!!

General result: Average number of yes-no questions needed to guess the outcome of X is between H[X] and H[X]+1.

- This is consistent with the interpretation of H as uncertainty.
- If the probability is concentrated more on some outcomes than others, we can exploit this regularity to make more efficient guesses.

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Coding

- A code is a mapping from a set of symbols to another set of symbols.
- Here, we are interested in a code for the possible outcomes of a random variable that is as short as possible while still being decodable.
- Strategy: use short code words for the more common occurrences of X.
- This is identical to the strategy for guessing outcomes.

Example: Optimal binary code for Y:

Note: This code is unambiguously decodable:

$$0110010000000101 = \beta \alpha \gamma \delta \delta \gamma \gamma$$

This type of code is called an instantaneous code.

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Coding, continued

General Result: Average number of bits in optimal binary code for X is between H[X] and H[X] + 1.

This result is known as Shannon's noiseless source coding theorem or Shannon's first theorem.

 Thus, H[X] is the average memory, in bits, needed to store outcomes of the random variable X. Chaos & Dynamical Systems, Part II: SFI Summer School, Qingdao China July 2004

Summary of interpretations of entropy

- H[X] is the measure of uncertainty associated with the distribution of X.
- Requiring H to be a continuous function of the distribution, maximized by the uniform distribution, and independent of the manner in which subsets of events are grouped, uniquely determines H.
- H[X] is the expectation value of the surprise, $-\log_2\Pr(x)$.
- ullet $H[X] \leq$ Average number of yes-no questions needed to guess the outcome of $X \leq H[X] + 1$.
- $\bullet \ H[X] \ \leq \ \text{Average number of bits in optimal binary }$ code for $X \ \leq \ H[X] + 1.$
- $H[X] = \lim N \to \infty$ $\frac{1}{N} \times$ average length of optimal binary code of N copies of X.

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Joint and Conditional Entropies

Joint Entropy

- $H[X, Y] \equiv -\sum_{x \in \mathcal{X}} \sum_{y \in \mathcal{Y}} \Pr(x, y) \log_2(\Pr(x, y))$
- H[X,Y] is the uncertainty associated with the outcomes of X and Y.

Conditional Entropy

- $H[X|Y] \equiv -\sum_{x \in \mathcal{X}} \sum_{y \in \mathcal{Y}} \Pr(x, y) \log_2 \Pr(x|y)$.
- H[X|Y] is the average uncertainty of X given that Y is known.

Relationships

- $\bullet \ H[X,Y] = H[X] + H[Y|X]$
- H[Y|X] = H[X,Y] H[X]
- $\bullet \ H[Y|X] \neq H[X|Y]$

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Mutual Information

Definition

- $\bullet \ I[X;Y] = H[X] H[X|Y]$
- I[X; Y] is the average reduction in uncertainty of X given knowledge of Y.

Relationships

- $\bullet \ I[X;Y] = H[X] H[X|Y]$
- $\bullet \ I[X;Y] = H[Y] H[Y|X]$
- I[X;Y] = H[Y] + H[X] H[X,Y]
- $\bullet \ I[X;Y] = I[Y;X]$

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Example 1

Two independent, fair coins, C_1 and C_2 .

C_1	C_2	
	h	t
h	$\frac{1}{4}$	$\frac{1}{4}$
t	$\frac{1}{4}$	$\frac{1}{4}$

- $H[C_1] = 1$ and $H[C_2] = 1$.
- $H[C_1, C_2] = 2$.
- $H[C_1|C_2] = 1$. Even if you know what C_2 is, you're still uncertain about C_1 .
- $I[C_1; C_2] = 0$. Knowing C_1 does not reduce your uncertainty of C_2 at all.
- C_1 carries no information about C_2 .

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Example 2

Weather (rain or sun) yesterday W_0 and weather today W_1 .

	W_1	
W_0	r	s
r	<u>5</u> 8	1/8
s	$\frac{1}{8}$	$\frac{1}{8}$

- \bullet $H[W_0] = 0.811$ and $H[W_1] = 0.811$.
- $H[W_0, W_1] = 1.549.$
- Note that $H[W_0, W_1] \neq H[W_0] + H[W_1]$.
- $H[W_1|W_0] = 0.738$.

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- $I[W_0;W_1]=0.074$. Knowing the weather yesterday, W_0 , reduces your uncertainty about the weather today W_1 .
- W_0 carries 0.074 bits of information about W_1 .

Note: The above statistics are consistent with the perfectly periodic pattern: · · · rrrrrrssrrrrrrssrrrrrrss· · · · .

How could we detect if this was the actual pattern?

Application: Maximum Entropy

- A common technique in statistical inference is the maximum entropy method.
- Suppose we know a number of average properties of a random variable. We want to know what distribution the random variable comes from.
- This is an underspecified problem. What to do?
- Choose the distribution that maximizes the entropy while still yielding the correct average values.
- This is usually accomplished by using Lagrange multipliers to perform a constrained maximization.
- The justification for the maximum entropy method is that it assumes no information beyond what is already known in the form of the average values.
- Another application: In other settings in which one wants to design a maximally predictive model, one often adjusts parameters to maximize the mutual information between input variables and those variables that are to be predicted.

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