A Brief, Introductory Overview of Dynamical Systems and Chaos

- A Dynamical System is any system that changes over time
 - A Differential Equation
 - A system of differential equations
 - Iterated functions
 - Cellular Automata
- The goal of this brief introduction is to define a handful of terms and introduce the phenomena associated with chaos.
- I will focus on iterated functions.
- Let's start with an example.

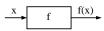
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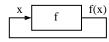
Example: Iterating the squaring rule, $f(\boldsymbol{x}) = \boldsymbol{x}^2$

ullet Consider the function $f(x)=x^2$. What happens if we start with a number and repeatedly apply this function to it?

- E.g., $3^2 = 9$, $9^2 = 81$, $81^2 = 6561$, etc.
- The iteration process can also be written $x_{n+1} = x_n^2$.
- In this is example, the initial value 3 is the **seed**. The seed is often denoted x_0 .
- The sequence $3, 9, 81, 6561, \cdots$ is the **orbit** or the **itinerary** of 3.
- Picture the function as a "box" that takes x as an input and outputs f(x):



• Iterating the function is then achieved by feeding the output back to the function, making a feedback loop:



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The squaring rule, continued

In dynamics, we are usually interested in the long-term behavior of the orbit, not in the particulars of the orbit.

- The seed 3 tends toward infinity—it gets bigger and bigger.
- Any $x_0 > 1$ will tend toward infinity.
- If $x_0 = 1$ or $x_0 = 0$, then the point never changes. These are fixed points.
- If $0 \le x_0 < 1$, then x_0 approaches 0.
- We can summarize this with the following diagram:

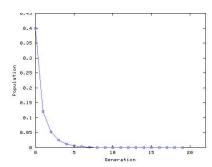
0 1

- 0 and 1 are both fixed points
- 0 is a **stable** or **attracting** fixed point
- 1 is an unstable or repelling fixed point

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Logistic Equation

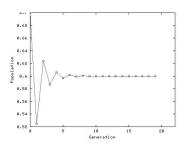
- Logistic equation: f(x) = rx(1-x).
- A simple model of resource-limited population growth.
- The population x is expressed as a fraction of the carrying capacity. $0 \le x \le 1$.
- $\bullet \ r$ is a parameter—the growth rate—that we will vary.
- Let's first see what happens if r = 0.5.

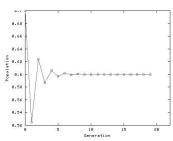


- This graph is known as a **time series plot**.
- 0 is an attracting fixed point.

Logistic Equation, r=2.5

 \bullet Logistic equation, r=2.5.





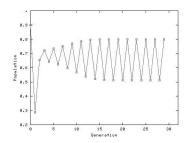
- All initial conditions are pulled toward 0.6.
- 0.6 is an attracting fixed point.

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Logistic Equation, r = 3.2

• Logistic equation, r = 3.2.



- Initial conditions are pulled toward a **cycle** of period 2.
- \bullet The orbit oscillates between 0.513045 and 0.799455.
- This cycle is an attractor. Many different initial conditions get pulled to it.

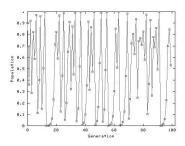
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Logistic Equation, r = 4.0

• Logistic equation, r = 4.0.

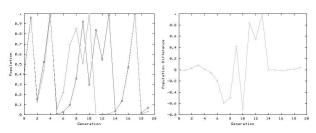


- What's going on here?!
- The orbit is not periodic. In fact, it never repeats.
- This is a rigorous result; it doesn't rely on computers.
- What happens if we try different initial conditions?

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Different Initial conditions

• Logistic equation, r=4.0. Two different initial conditions, $x_0=0.4$ and $x_0=0.41$.



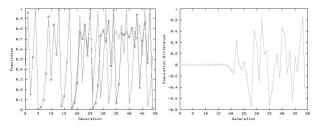
- The right graph plots the difference between the two orbits on the left with slightly different initial conditions.
- Note that the difference between the two orbits grows.
- Can think of one initial condition as the true one, and the other as the measured one.
- The plot on the right then shows what happens to our prediction error over time.
- What happens if the two initial conditions are closer together?

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Sensitive Dependence on Initial Conditions

• Logistic equation, r=4.0. Two different initial conditions, $x_0=0.4$ and $x_0=0.4000001$.



- The two initial conditions differ by one part in one million
- The orbits differ significantly after around 20 iterations, whereas before they differed after around 4 iterations.
- \bullet Increasing the accuracy of the initial condition by a factor of 10^5 allow us to predict the outcome 5 times further.
- Thus, for all practical purposes, this system is unpredictable, even though it is deterministic.
- This phenomena is known as Sensitive Dependence on Initial Conditions, or, more colloquially, The Butterfly Effect.

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Definition of Sensitive Dependence on Initial Conditions

 A dynamical system has sensitive dependence on initial conditions (SDIC) if arbitrarily small differences in initial conditions eventually lead to arbitrarily large differences in the orbits.

More formally

- Let X be a metric space, and let f be a function that maps X to itself: $f:X\mapsto X.$
- The function f has SDIC if there exists a $\delta>0$ such that $\forall x_1\in X$ and $\forall \epsilon>0$, there is an $x_2\in X$ and a natural number $n\in N$ such that $d[x_1,x_2]<\epsilon$ and $d[f^n(x_1),f_n(x_2)]>\delta.$
- In other words, two initial conditions that start ϵ apart will, after n iterations, be separated by a distance δ .

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Definition of Chaos

There is not a 100% standard definition of chaos. But here is one of the most commonly used ones:

An iterated function is chaotic if:

- 1. The function is deterministic.
- 2. The system's orbits are bounded.
- The system's orbits are aperiodic; i.e., they never repeat.
- 4. The system has sensitive dependence on initial conditions.

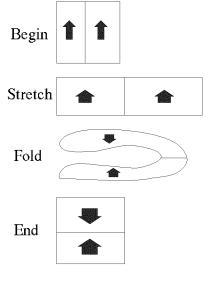
Other properties of a chaotic dynamical system $(f:X\mapsto X)$ that are sometimes taken as defining features:

- 1. Dense periodic points: The periodic points of f are dense in X.
- 2. **Topological transitivity:** For all open sets $U,V\in X$, there exists an $x\in U$ such that, for some $n<\infty$, $f_n(x)\in V$. I.e., in any set there exists a point that will get arbitrarily close to any other set of points.

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Geometry of Chaos

Geometrically, all chaotic systems involve stretching and folding:

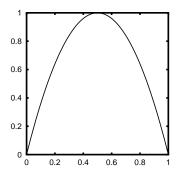


- Stretching pulls nearby points apart, leading to sensitive dependence on initial conditions.
- Folding keeps the orbits bounded.

Geometry of Chaos, continued

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The logistic equation may be viewed as stretching and folding the unit interval onto itself:



- Note that the amount of stretching is captured by the slope of the function.
- We shall see that the "average slope" is related to the degree of SDIC, which is in turn related to the unpredictability.
- Thus, SDIC is a geometric property of the system.
- We will make this idea precise in the next set of lectures.

Chaos and Dynamical Systems: Selected References

There are many excellent references and textbooks on dynamical systems. Some of my favorites:

- Peitgen, et al. Chaos and Fractals: New Frontiers of Science.
 Springer-Verlag. 1992. Huge (almost 1000 pages), and very clear. Excellent balance of rigor and intuition.
- Cvitanović, Universality in Chaos, second edition, World Scientific. 1989. Comprehensive collection of reprints. Very handy. Nice introduction by Cvitanović.
- Gleick, Chaos: Making a New Science. Penguin Books. 1988.
 Popular science book. But very good. Extremely well written and accurate.
- Devaney. An Introduction to Chaotic Dynamical Systems, second edition. Perseus Publishing. 1989. Advanced undergrad math textbook. Very clear.

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