

# DP-fy your DATA: How to (and why) Synthesize Differentially Private Synthetic Data



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## Researchers and Engineers at Google Research

# Plan for Today

0  
1 Data in machine learning

0  
5 DP synthetic images

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0  
2 Differential privacy

0  
6 DP synthetic tabular  
data

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0  
3 DP synthetic text

0  
7 Important privacy  
considerations

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0  
4 Break (10m)

# Data In Machine Learning



# The Role of Data 2009

**“For many tasks, words and word combinations provide all the representational machinery we need to learn from text.”**



## EXPERT OPINION

Contact Editor: **Brian Brannon**, bbrannon@computer.org

## The Unreasonable Effectiveness of Data

Alon Halevy, Peter Norvig, and Fernando Pereira, Google

Eugene Wigner’s article “The Unreasonable Effectiveness of Mathematics in the Natural Sciences”<sup>1</sup> examines why so much of physics can be neatly explained with simple mathematical formulas

such as  $f = ma$  or  $e = mc^2$ . Meanwhile, sciences that involve human beings rather than elementary particles have proven more resistant to elegant mathematics. Economists suffer from physics envy over their inability to neatly model human behavior.

behavior. So, this corpus could serve as the basis of a complete model for certain tasks—if only we knew how to extract the model from the data.

### Learning from Text at Web Scale

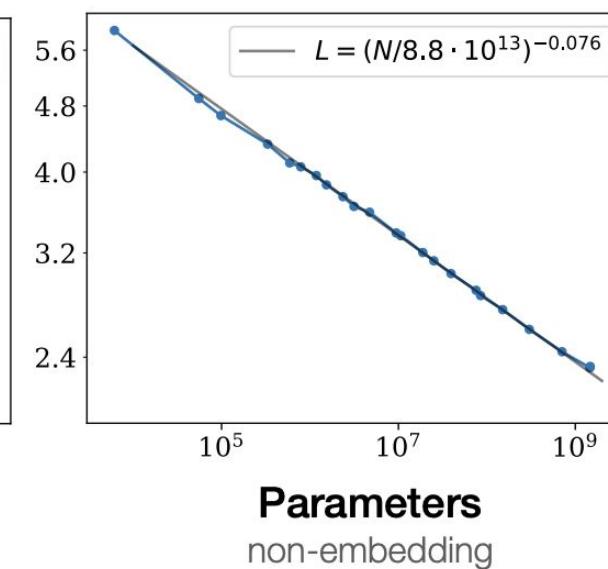
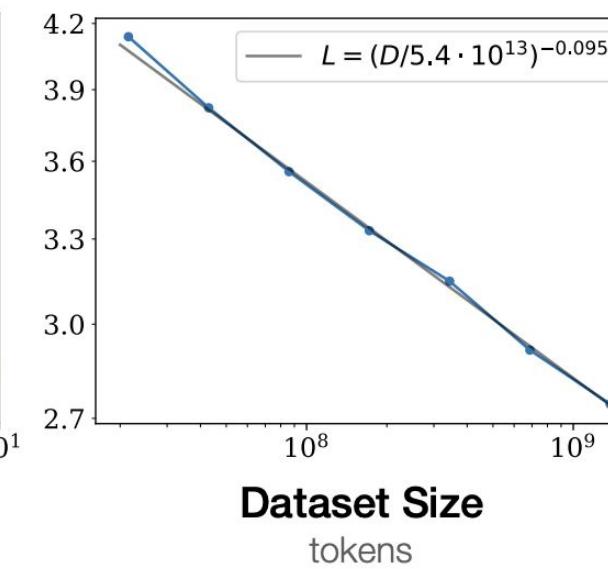
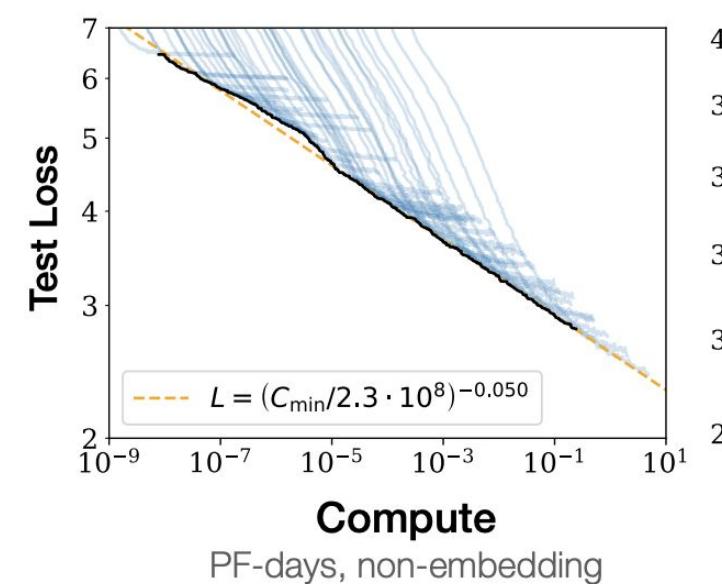
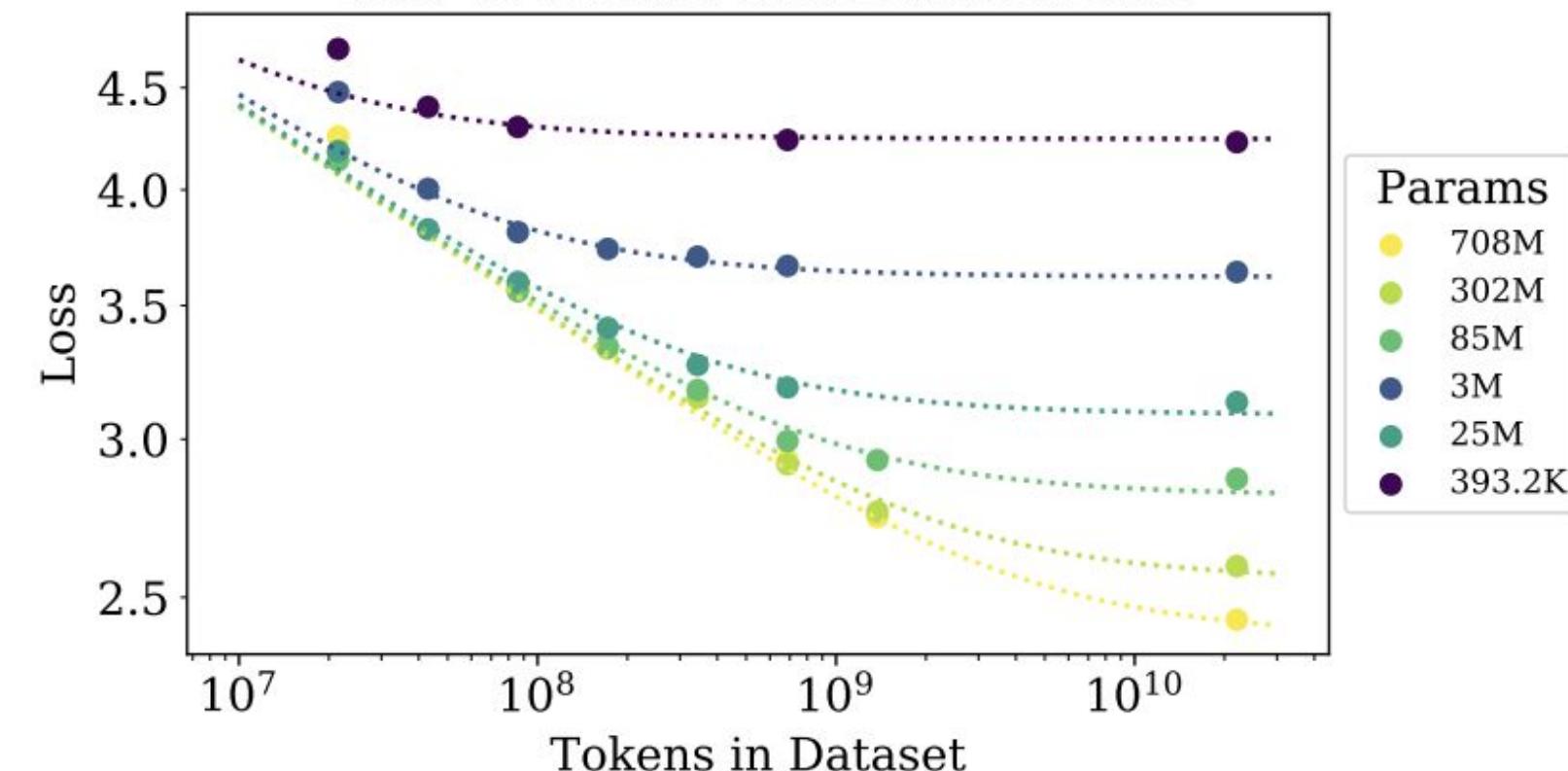
The biggest successes in natural-language-related machine learning have been statistical speech recognition and statistical machine translation. The reason for these successes is not that these tasks are easier than other tasks; they are in fact much harder than tasks such as document classification that ex-

# The Role of Data: 2020+

## Scaling Laws:

Capture the precise trade-off between model quality, training dataset size, and computation necessary

Loss vs Model and Dataset Size



LONG LIVE THE REVOLUTION.  
OUR NEXT MEETING WILL BE  
AT THE DOCKS AT MIDNIGHT  
ON JUNE 28 TAB

AHA, FOUND THEM!



WHEN YOU TRAIN PREDICTIVE MODELS  
ON INPUT FROM YOUR USERS, IT CAN  
LEAK INFORMATION IN UNEXPECTED WAYS.

# But need good data hygiene

Data comes with restrictions on use:

- Some data may be personal: names, phone numbers, locations, ...
- Some data may be regulated: GDPR, AIA, ...

For LLMs especially:

- Larger data sets are more likely to include private information by chance
- Models are large, opaque, and difficult to understand directly
- GenAI outputs are rich enough (text, images) to potentially include detailed private information

# The Promise of Synthetic Data

What if...

- Can generate new data
- That is similar in distribution to given data
- But is entirely synthetic and new...

Can we train models on synthetic data instead?

# Why Synthetic Data?

Change the beginning of the usual pipeline



By changing the data, keep the rest of the pipeline the same:

- Same architecture
- Same optimizers
- Same deployment checks
- Same ...

# Types of Synthetic Data

Pure Synthetic Data

DP Synthetic Data

# Pure Synthetic Data: Homework for LLMs

“Synthetic data generation using large language models (LLMs) offers a powerful solution to a commonly faced problem: the availability of high-quality, diverse, and privacy-compliant data.”

Synthetic data is used to:

- Create more examples of the same concept (e.g. generate more 5th grade algebra problems)
- Rewrite or rephrase training examples to get more diversity (e.g. provide summaries of topics)

Mostly commonly generated by prompting existing LLMs:

Suppose you are a movie reviewer. Please generate a movie review to show your <feeling> about the movie <movie> with detailed explanation...



There are movies and then there are films. The plot...

# Pure Synthetic Data: Perpetual Motion Machine?

The screenshot shows a web page from the journal 'nature'. At the top, the word 'nature' is written in a large, bold, black sans-serif font. Below it is a horizontal navigation bar with three items: 'Explore content ▾', 'About the journal ▾', and 'Publish with us ▾'. A thick black horizontal line separates this from the main content area. In the content area, there is a breadcrumb navigation showing 'nature > articles > article'. Below that, the text 'Article | Open access | Published: 24 July 2024' is displayed. The main title of the article is 'AI models collapse when trained on recursively generated data', which is rendered in a large, bold, dark gray font.

In addition to other challenges – e.g. factuality / hallucination, diversity of examples, representativeness, etc.

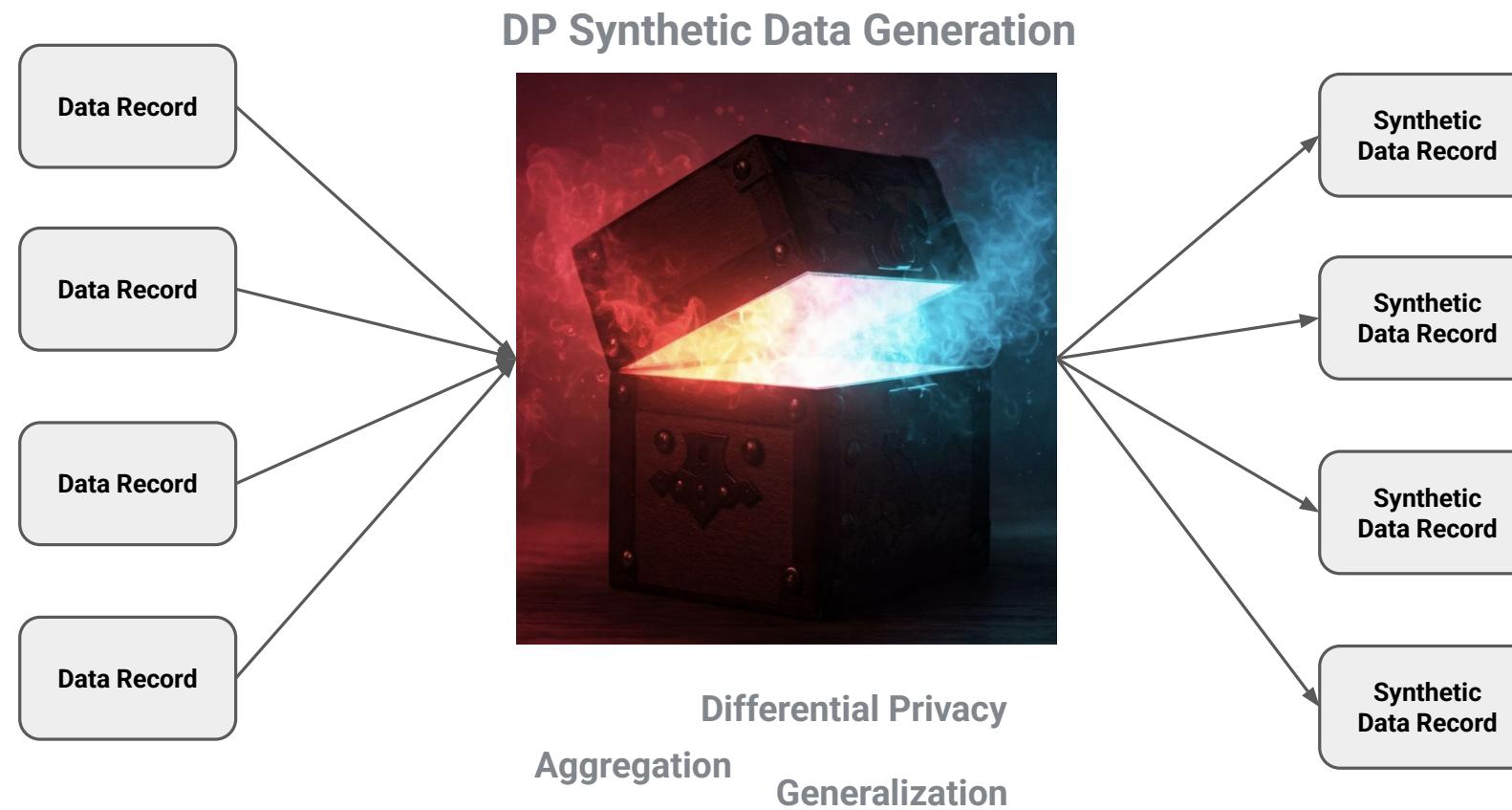
# Types of Synthetic Data

Pure Synthetic Data

DP Synthetic Data

# DP Synthetic Data

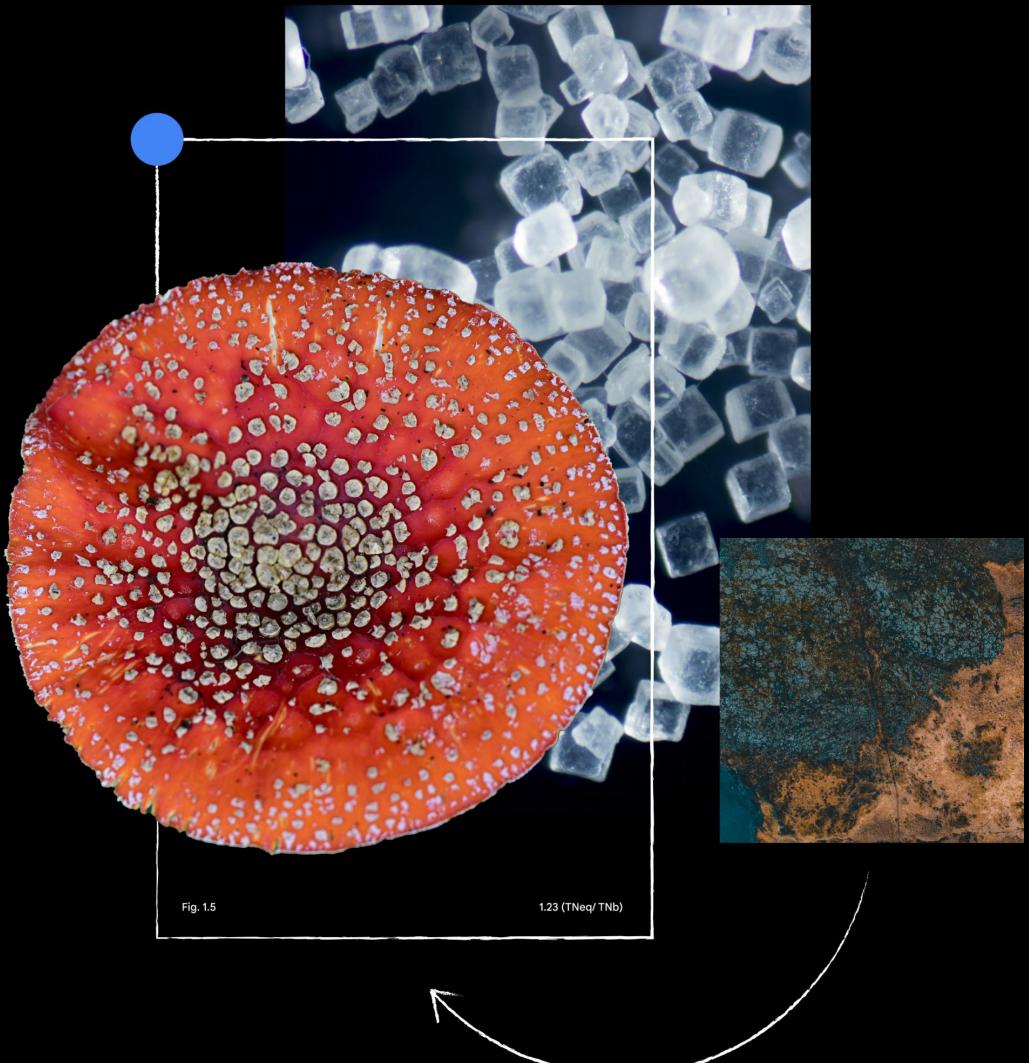
Many-Many Relationship between user data and synthetic data with strong privacy protections.



# Today

- What is privacy?
- How to generate useful DP Synthetic Data - text, images, tables, ...
- How to evaluate its utility?
- What else you need to do in practice?

# Differential Privacy



# What is privacy?



Privacy (UK: /'prɪvəsɪ/, US: /'praɪ-/) is the ability of an individual or group to **seclude** themselves or **information about themselves**, and thereby express themselves selectively.

(From Wikipedia)

# Privacy Principles in Machine Learning

- Transparency and User control
  - o Users can be aware of what data is used, what purpose it is used or and how it is processed, and have full control on whether to enable the collection and use of their data
- Data minimization
  - o Data is only collected focusing on specific computation needs, with access limited at all data processing stages
- Data anonymization
  - o The final released output of the computation (e.g. ML model) does not reveal anything unique about an individual.
- Auditability and verifiability
  - o Users, and potentially third parties can audit and verify privacy claims by examining released models, open-sourced code, and privatized system logs, etc.

# How to anonymize?

Idea 1:

- Remove user ids!

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TECHNOLOGY

## *The "Re-identification" of Governor William Weld's Medical Information: A Critical Re-examination of Health Data Identification Risks and Privacy Protections, Then and Now*

Author: Daniel C. Barth-Jones, M.P.H., Ph.D., Assistant Professor of Clinical Epidemiology, Department of Epidemiology, Mailman School of Public Health, Columbia University.

### ***Abstract:***

The 1997 re-identification of Massachusetts Governor William Weld's medical data within an insurance data set which had been stripped of direct identifiers has had a profound impact on the development of de-identification provisions within the 2003 Health Insurance Portability and Accountability Act (HIPAA)

## ***A Face Is Exposed for AOL Searcher No. 4417749***

By MICHAEL BARBARO and TOM ZELLER

Robust De-anonymization of Large Datasets  
(How to Break Anonymity of the Netflix Prize Dataset)

- 5 digit zipcode + DOB + gender uniquely identifies 87% of US population.

# How to anonymize?

Idea 2:

- Only allow access to aggregates

# How to anonymize?

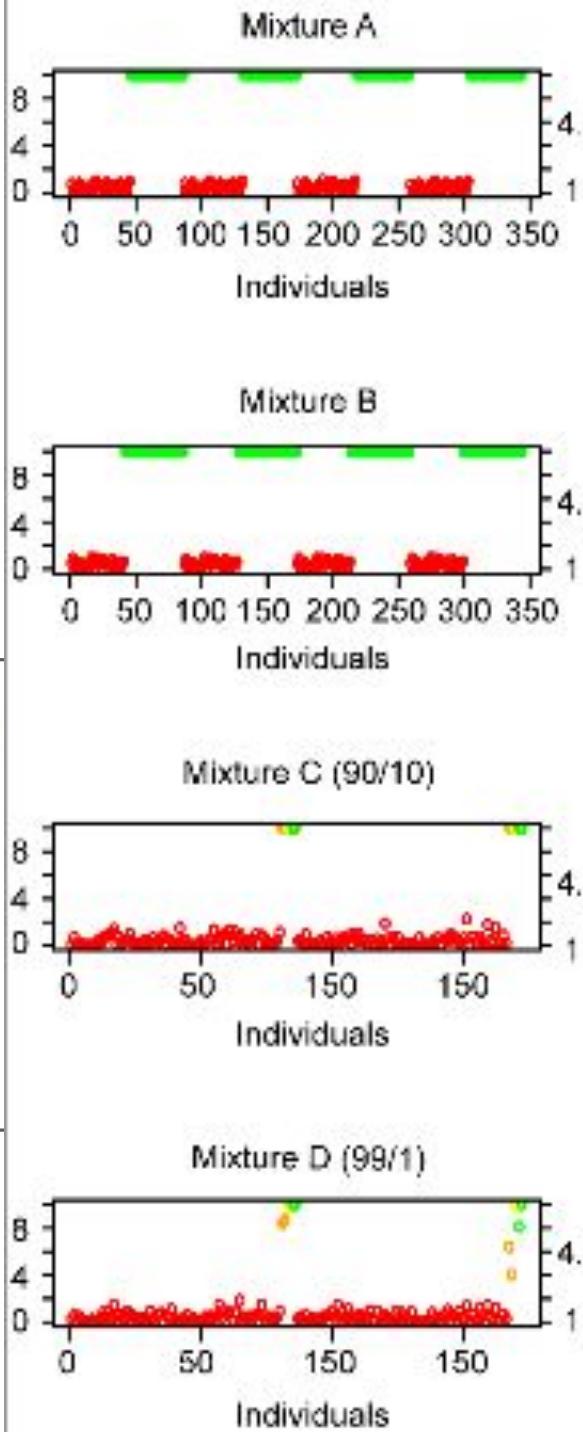
Idea 2:

- Only allow access to aggregates

## Resolving Individuals Contributing Trace Amounts of DNA to Highly Complex Mixtures Using High-Density SNP Genotyping Microarrays

Nils Homer, Szabolcs Szelinger, Margot Redman, David Duggan, Waibhav Tembe, Jill Muehling, John V. Pearson,  
Dietrich A. Stephan, Stanley F. Nelson, David W. Craig 

- Determined if a particular participant is part of the dataset



# How to anonymize?

Idea 3:

- Make sure at least  $k$  different people share the attributes
- “ $k$ -anonymity”

# How to anonymize?

## Idea 3:

- Make sure at least  $k$  different people share the attributes
- “ $k$ -anonymity”

## Attacks:

- [Homogeneity]: All  $k$  people share a sensitive attribute.
  - “All  $k$  have declared bankruptcy in the past”

# How to anonymize?

Idea 3 (b):

- Make sure at least  $k$  different people share the attributes
- And sensitive attributes are diverse in each equivalence class
- “ $k$ -anonymity with  $l$ -diversity”

# How to anonymize?

## Idea 3 (b):

- Make sure at least  $k$  different people share the attributes
- And sensitive attributes are diverse in each equivalence class
- “ $k$ -anonymity with  $l$ -diversity”

## Attack:

- Consider a class that has people who are either bankrupt or convicted of crime.

# How to anonymize?

Idea 3 (c):

- Make sure at least  $k$  different people share the attributes
- And sensitive attributes are diverse in each equivalence class
- And distribution of sensitive attribute is similar to global
- “ $k$ -anonymity with  $l$ -diversity and  $t$ -closeness”

# How to anonymize?

## Idea 3 (c):

- Make sure at least  $k$  different people share the attributes
- And sensitive attributes are diverse in each equivalence class
- And distribution of sensitive attribute is similar to global.
- “ $k$ -anonymity with  $l$ -diversity and  $t$ -closeness”

## Attack:

- Still have to define sensitive attributes. Does not prevent information leakage when attacker knows additional information about the subject.

# What do we want?

The output of an algorithm should be the same whether or not a specific individual participated.

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Too harsh: by induction no learning can happen

# What do we want?

The **probability** of an output of an algorithm should be **almost** the same whether or not a specific individual participated.

# Example

Want to return the average age of people in this room

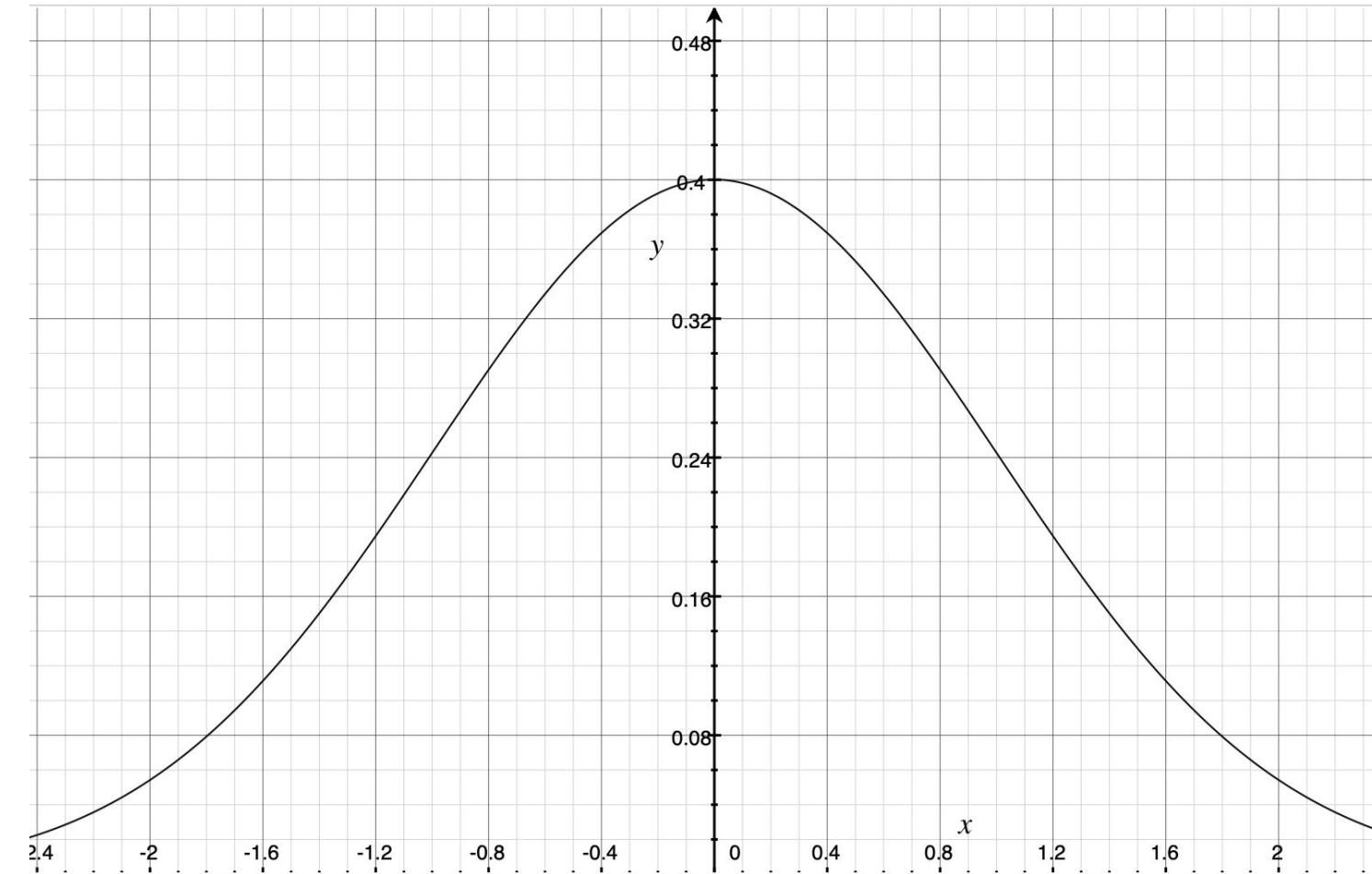
- Without revealing my age

System returns:

- True answer + Gaussian noise with mean 0, std 1

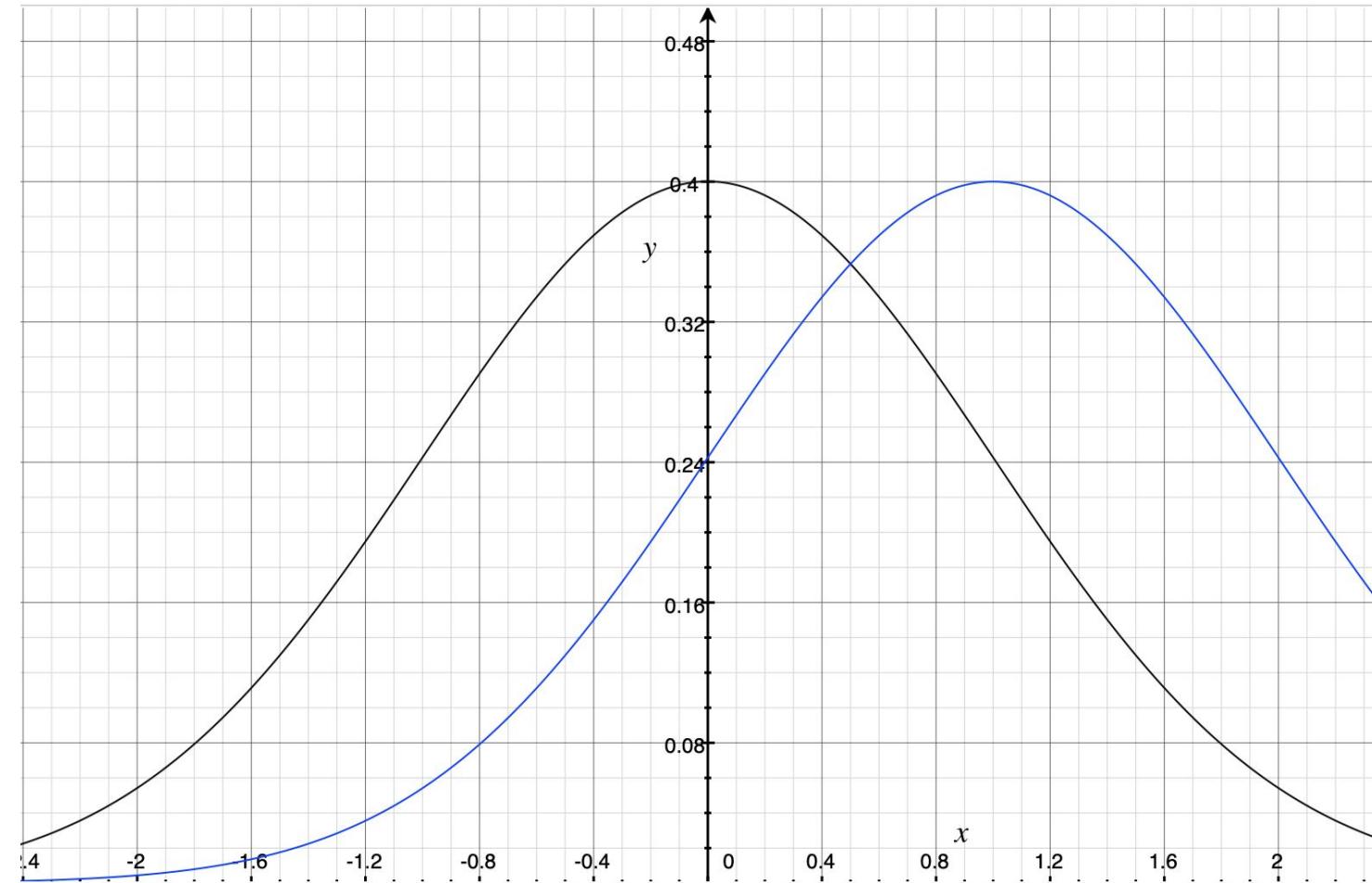
# Noisy Average Age

## Result Distribution



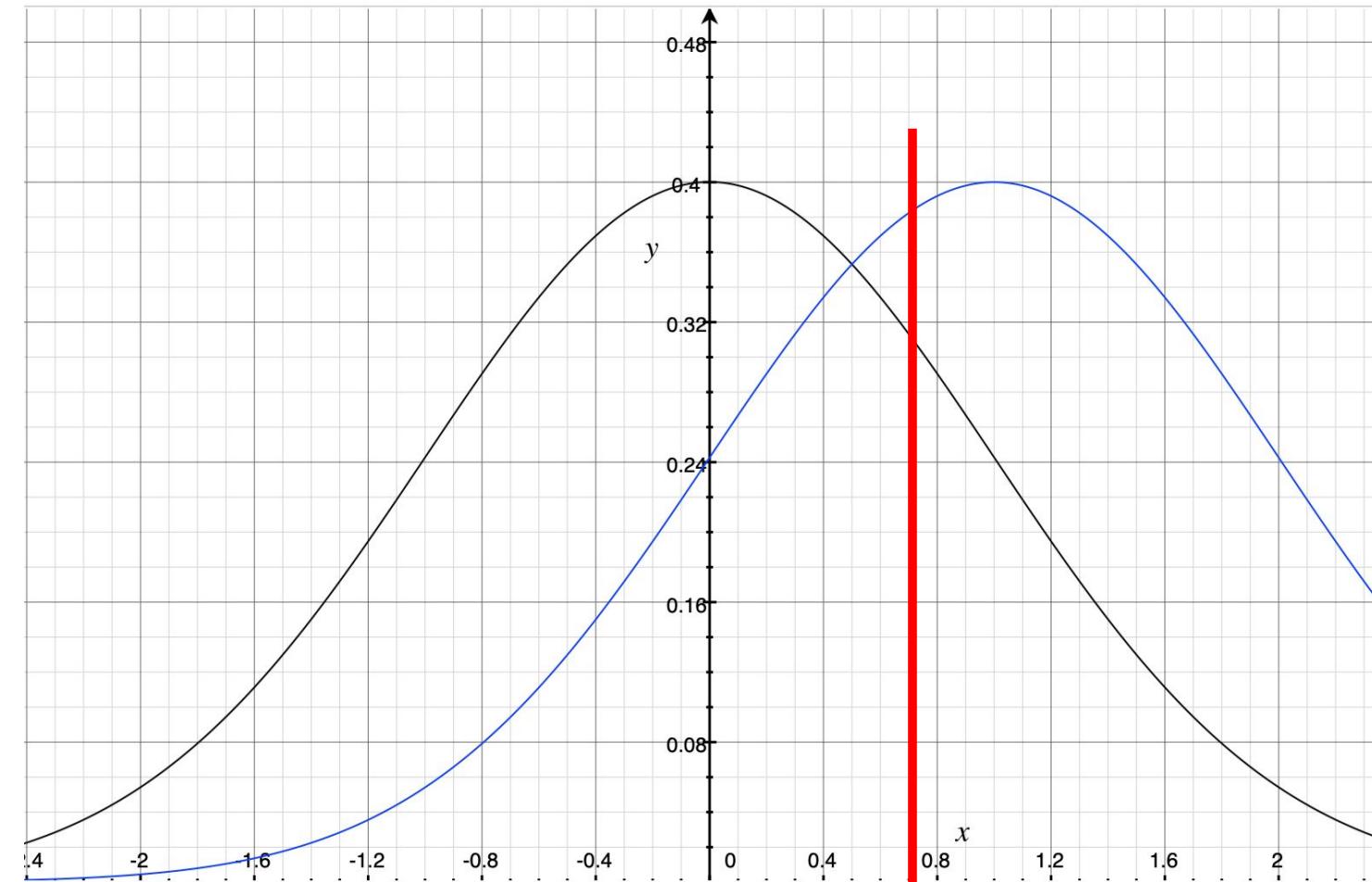
# Noisy Average Age

Result Distribution, when average differs by one



# Noisy Average Age

Given actual result (red): can't say if it came from blue or black curves



More likely that it came from blue curve, but not much more likely.

# Example

Want to return the average age of people in this room

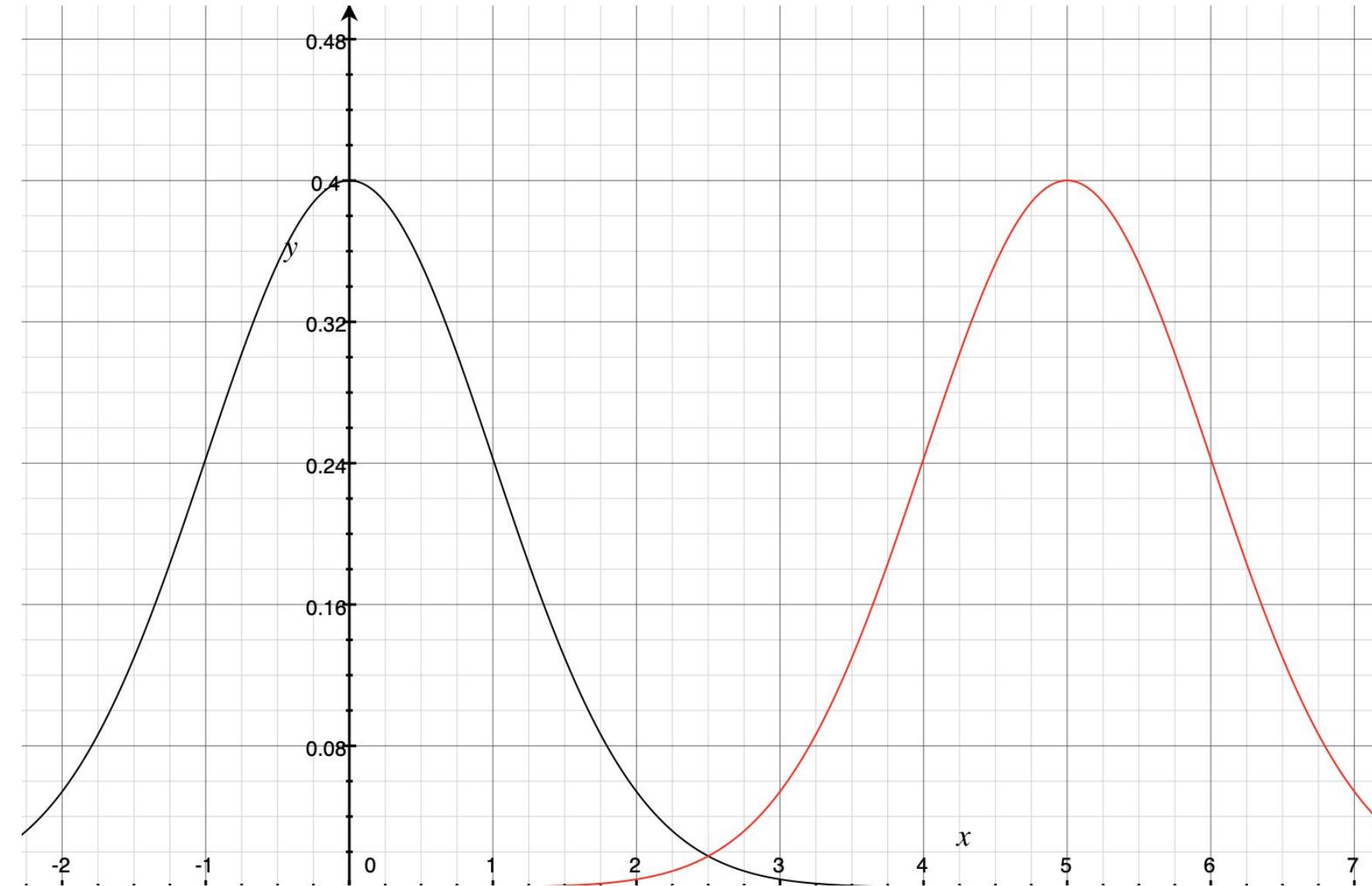
- Without revealing my age

System returns:

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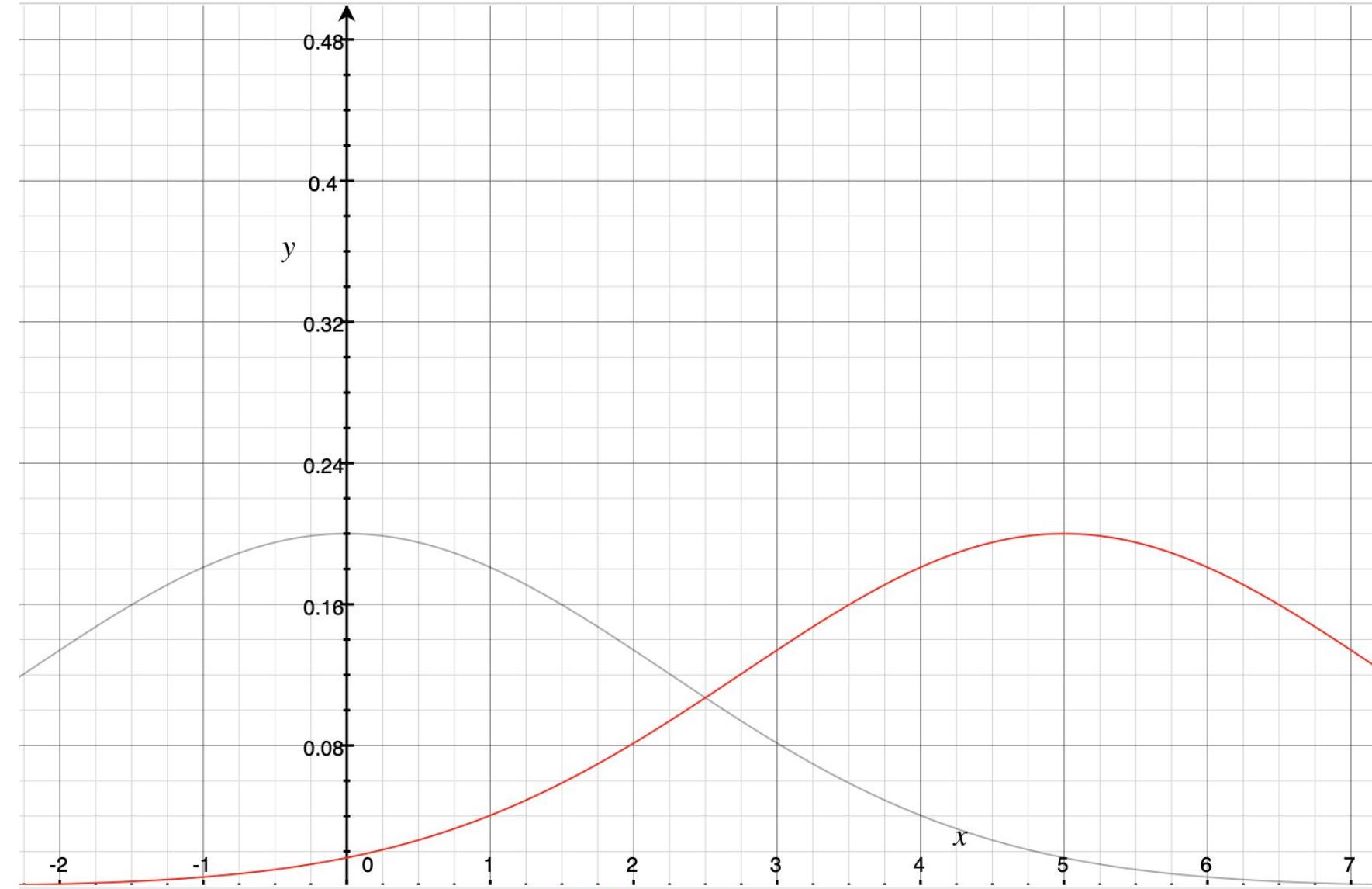
Even if attacker knows the age of everyone else, can't definitively say what my age is, just give a distribution.

# Some more details



If a single individual makes a big difference in the answer, the curves are well separated, so result is less private.

# Some more details



If a single individual makes a big difference in the answer, the curves are well separated, must add more noise

# Differential Privacy

The **probability** of an output of an algorithm should be **almost** the same whether or not a specific individual participated.

Has a parameter “**epsilon**” which controls privacy vs. utility trade-off.

Loosely speaking:

- Effect of single person changing the answer / std. deviation of noise
- Larger epsilon = less private.
- Typical values (0.1-0.2 in academia, 1-10 in industry)

# Differential Privacy Summary

Limit outliers and contributions from any user:

- Outliers in value or in number of data points contributed

Aggregate information across many users

- Aggregation is a key anonymization component

Add some noise to the aggregates

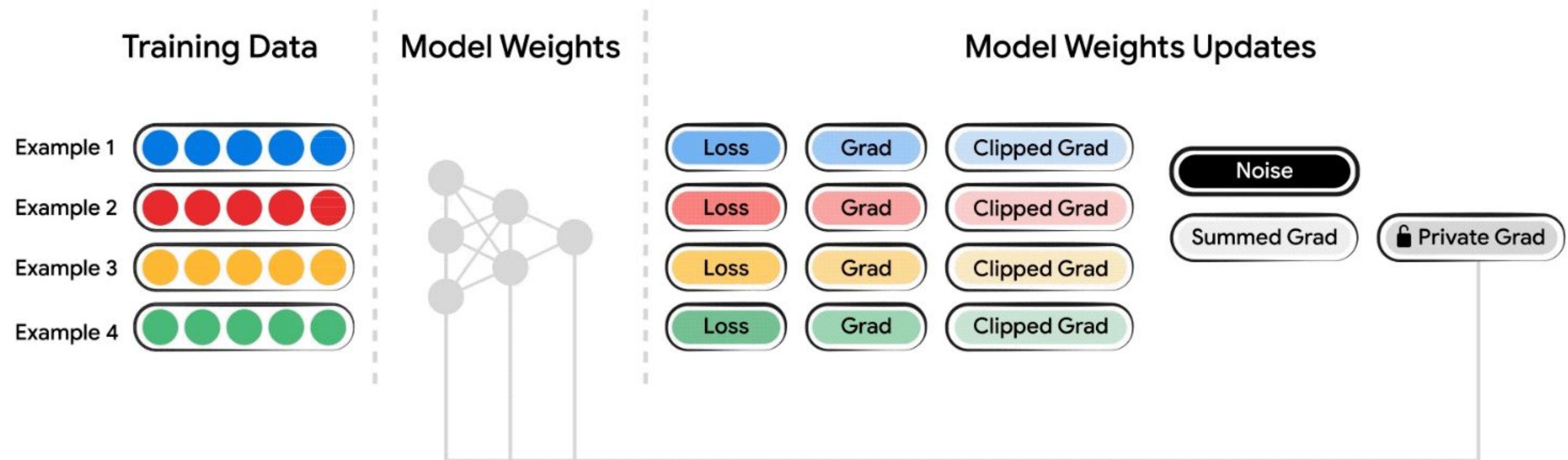
- Need to add noise to protect against differencing attacks

# Example: Gradient Descent with Differential Privacy

- Sample examples to form a batch
- “Clip” or bound the individual gradients
- Average across the batch
- Add noise to the average
- **Sensitivity** analysis to decide an appropriate amount of noise for DP guarantees
  - Can be calculated analytically for some functions like strongly convex linear ones
  - General solution is just to clip per example gradient to some predefined norm C

More in [How to DP-fy ML](#) Sec. 4.1.2

# Example: DP Training: DP-SGD



More in [How to DP-fy ML](#) Sec. 4.2

# Key Differential Privacy Properties

## Post-Processing & Composition:

- Any user-data independent transformation (post-processing) with arbitrary additional information retains all of the differential privacy properties

## Composition:

- When combining several DP methods together, combine the DP parameters.

## Theoretical Guarantees:

- The mathematical guarantees provided are on the algorithm used to generate the anonymous data. Use robust, well-established libraries (like crypto).

# Key Parameters when Designing Differential Privacy

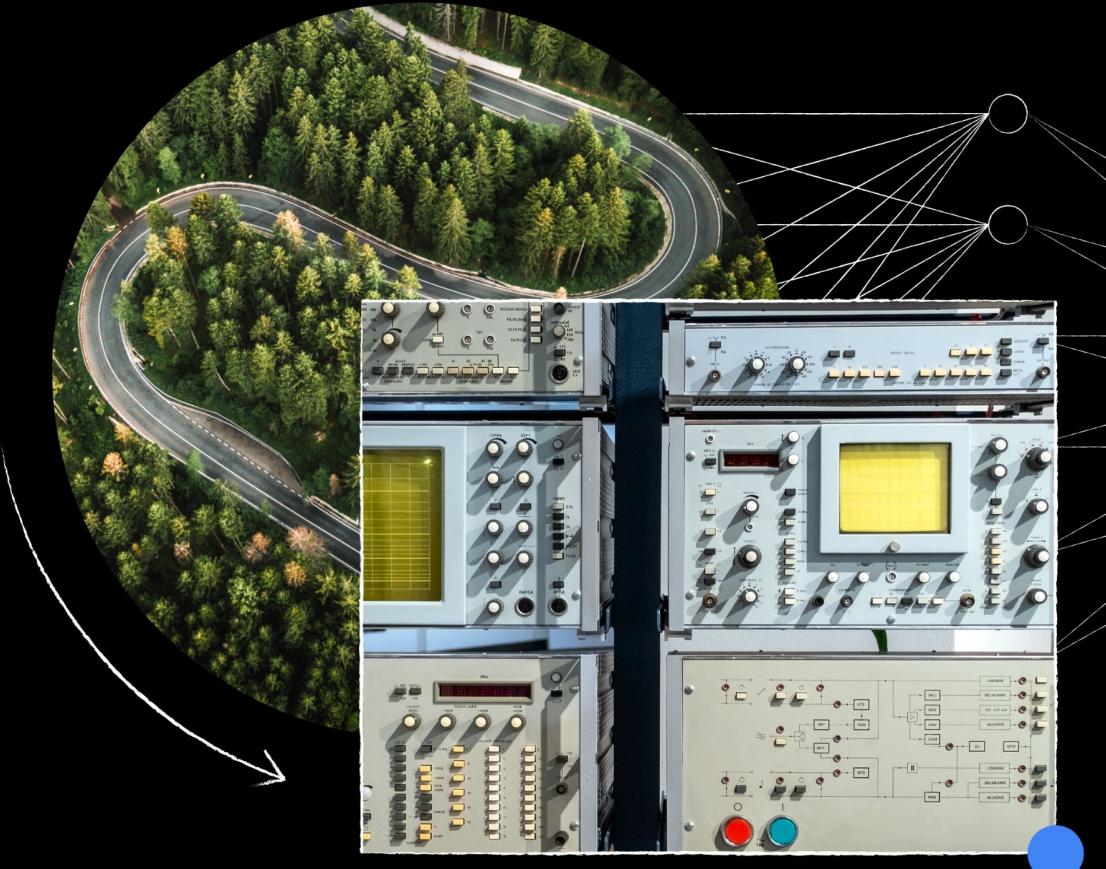
Privacy Unit: What is a user?

Contribution Bounding: How to limit outliers?

Methods: Which private method are you using?

Parameters: What is the value of epsilon, delta?

# DP synthetic text



# Overview

1. Taxonomy of methods
2. Methods
  - a. DP finetuning
  - b. Private evolution
  - c. DP inference
3. Comparison

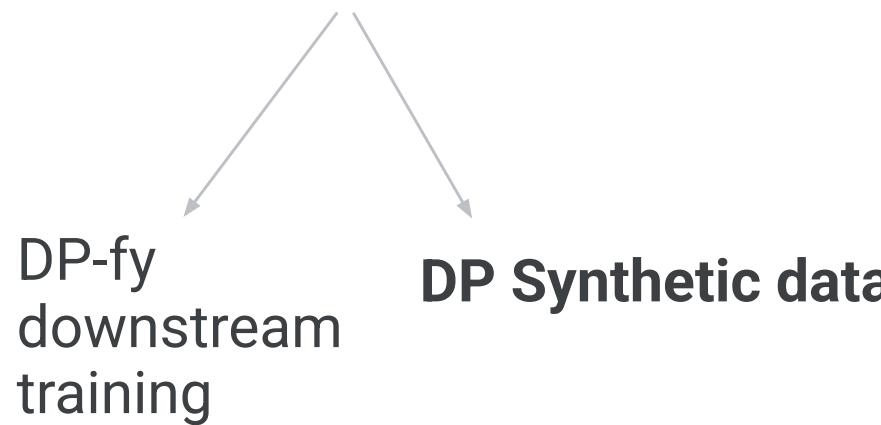
For each method: Will cover (1) how the algorithm works; (2) how and when to use it

# Taxonomy of methods for DP text synthesis

**Goal:** Unlock value of private text data with DP

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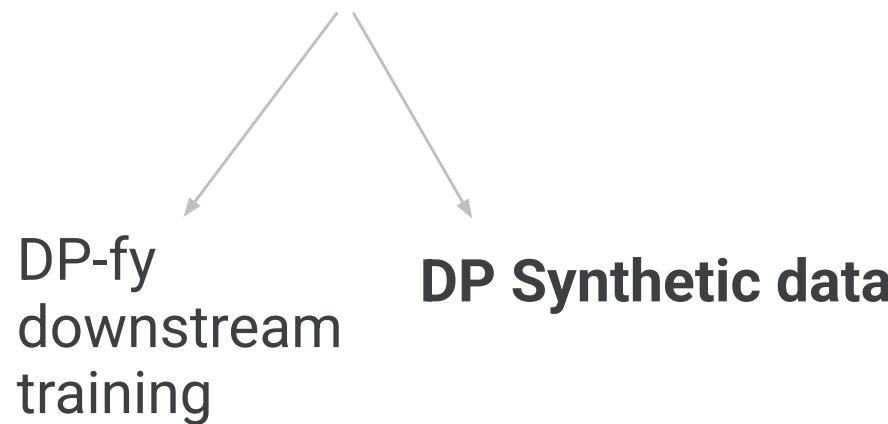


**DP Synthetic data = organizational breakthrough for DP**

1. Bespoke DPfying someone's training pipeline is hard
2. Everyone knows what to do with data

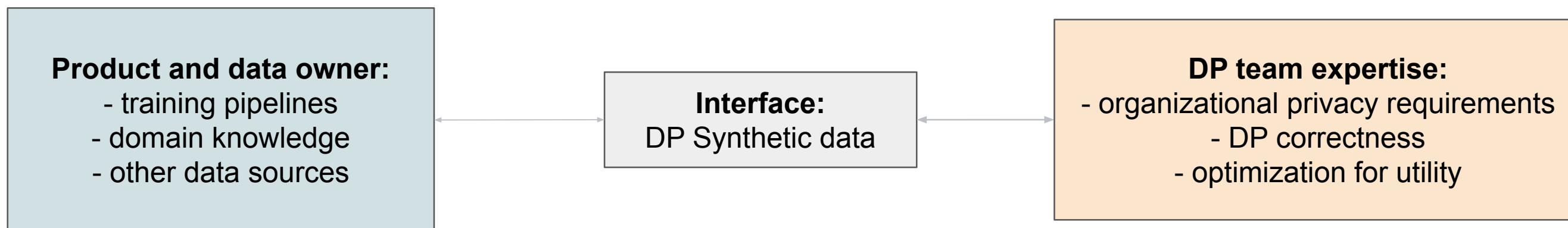
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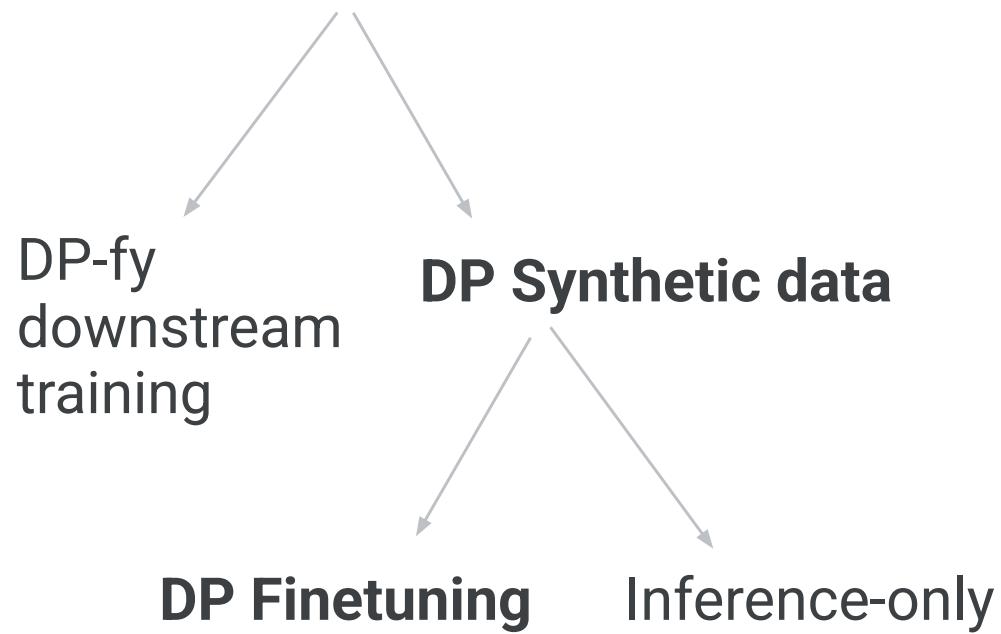
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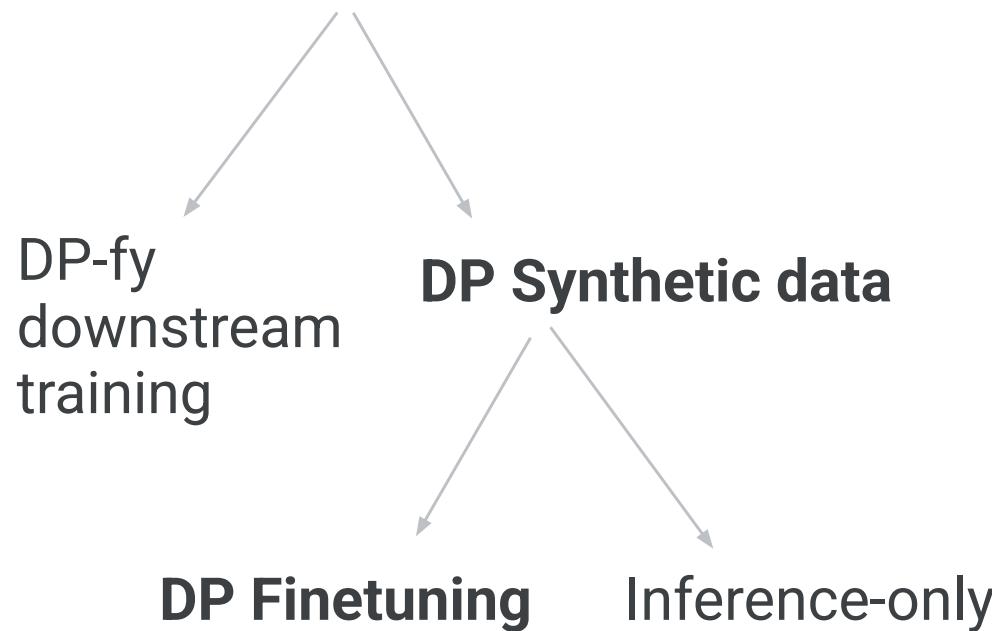
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## DP Finetuning

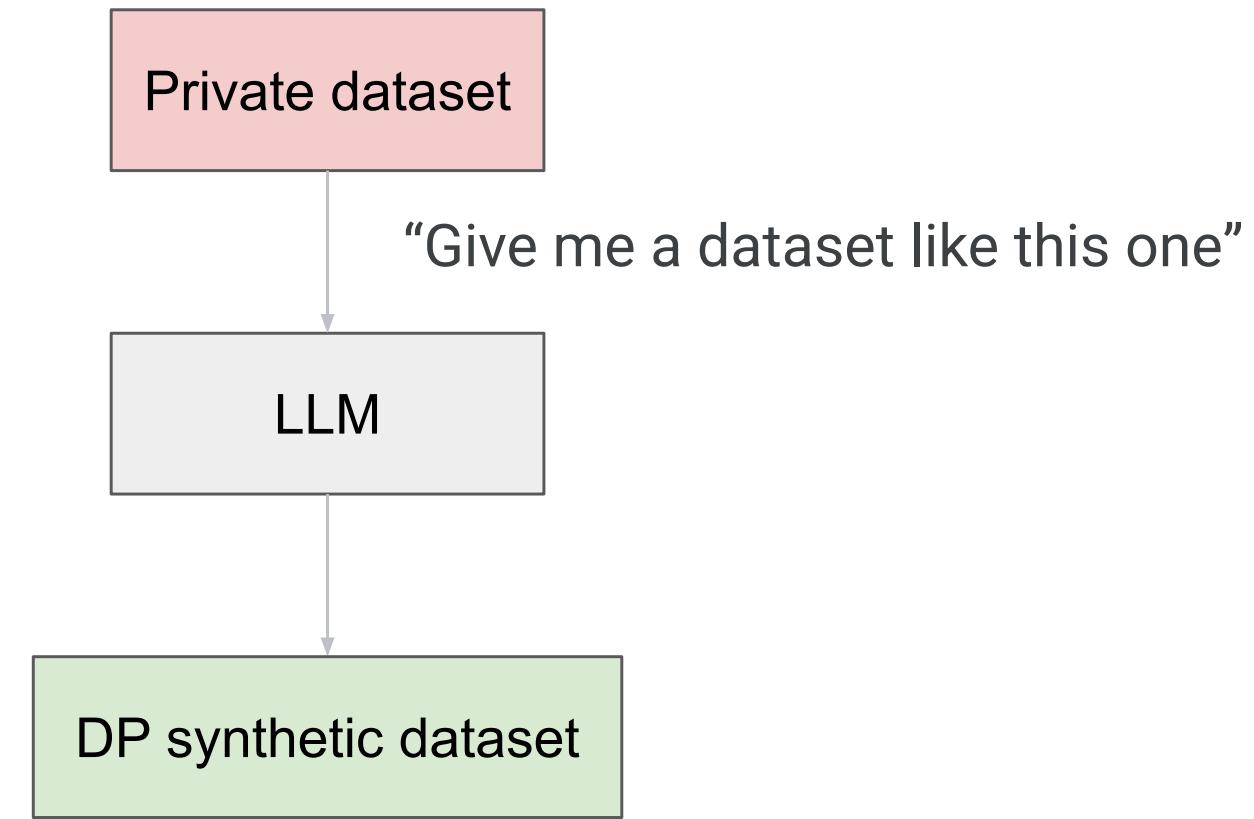
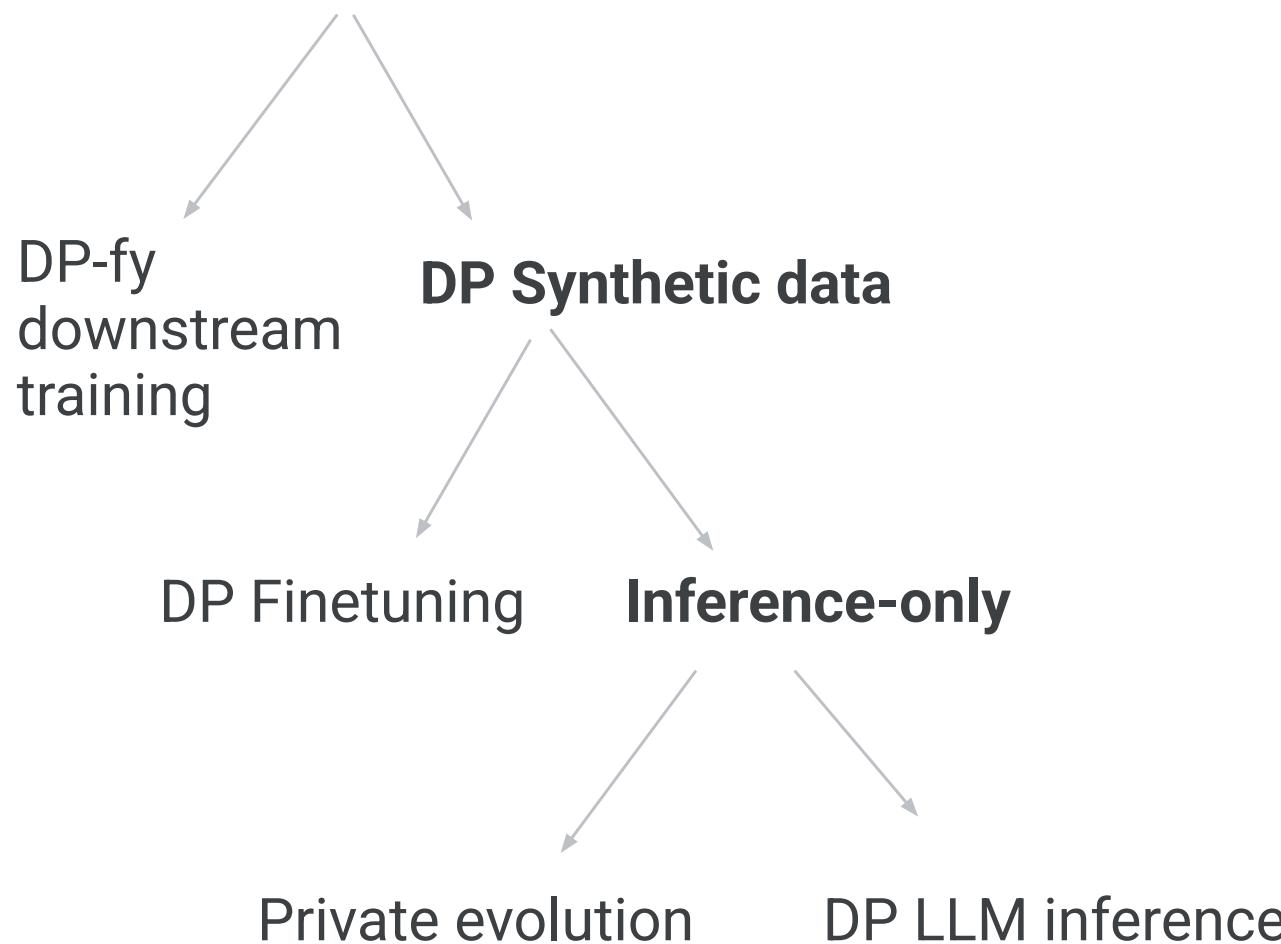
- Finetune an LLM with DP-SGD to generate data

```
{  
    inputs: "Generate data",  
    targets: "{data_record_i}"  
}
```

**Workhorse method that is the best for most cases**

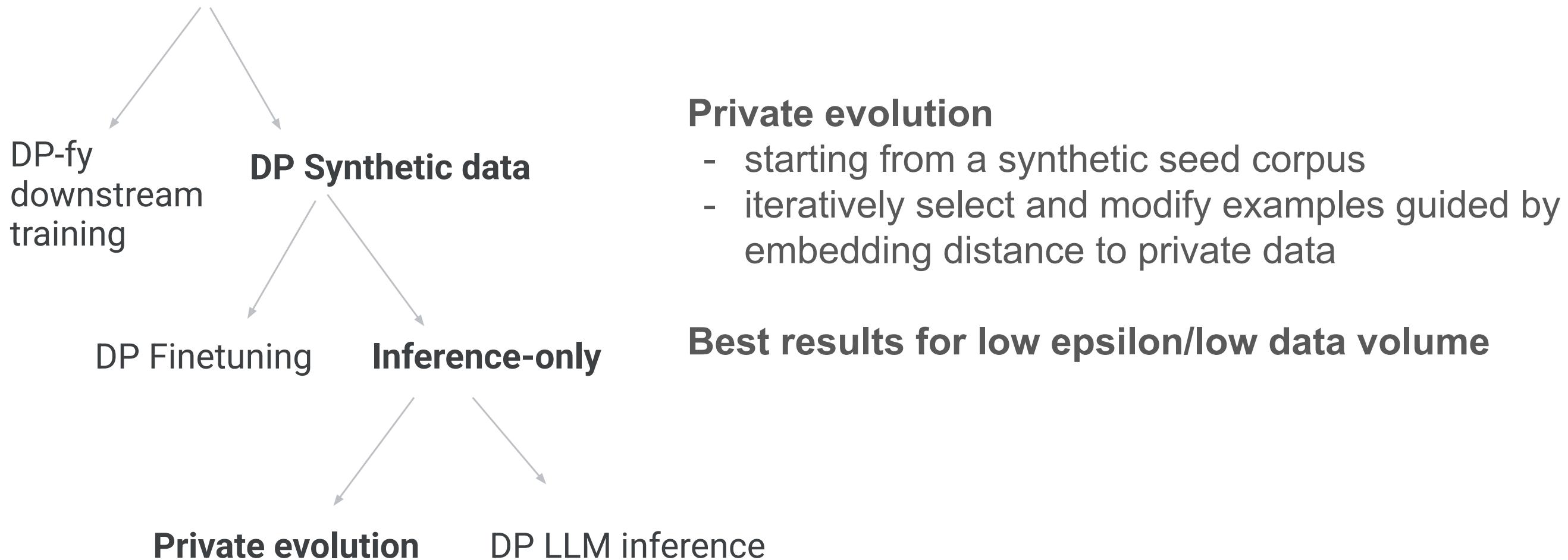
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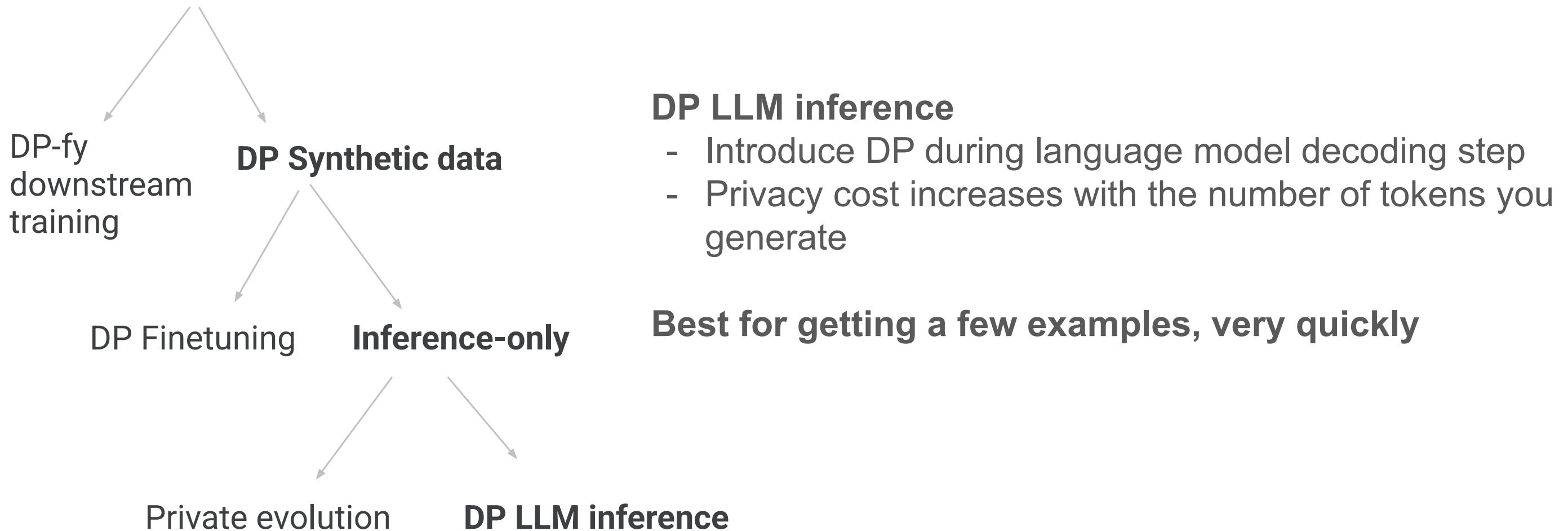
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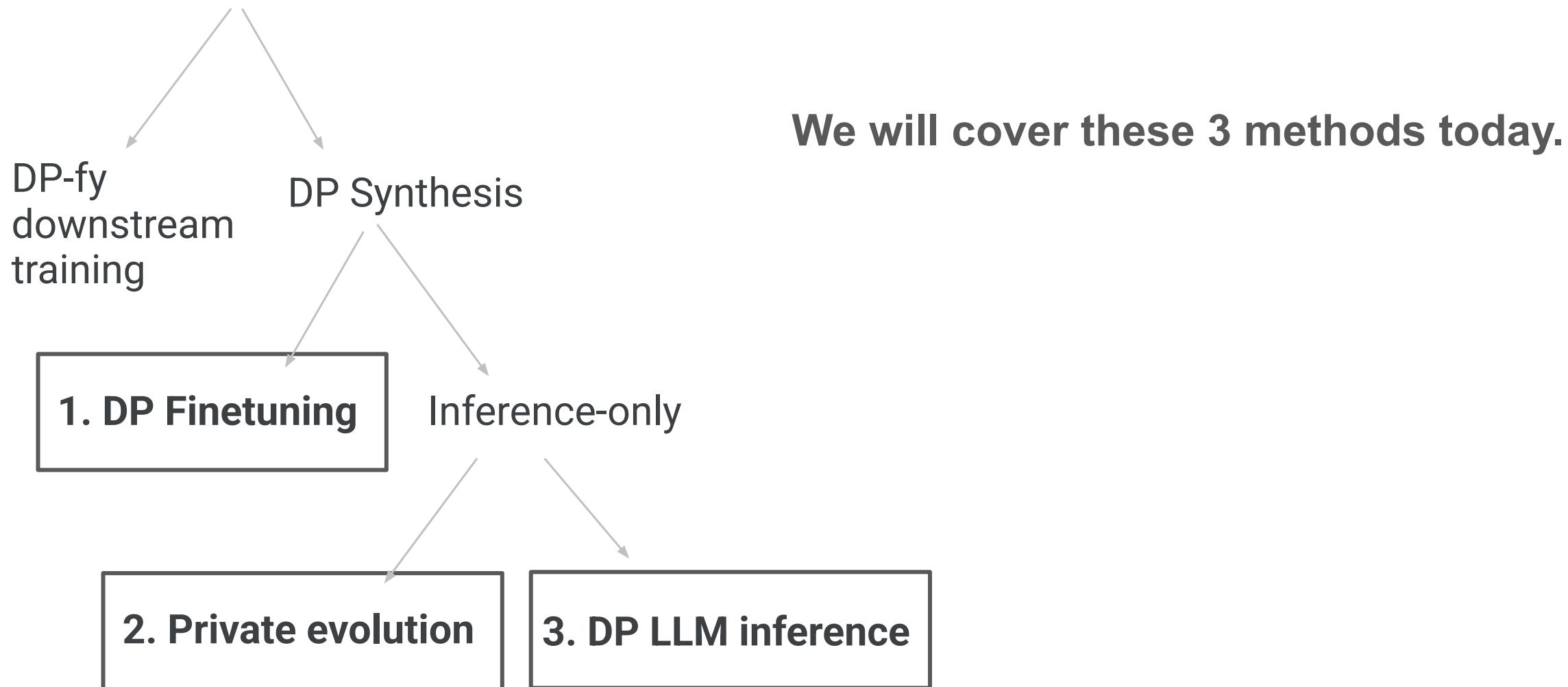
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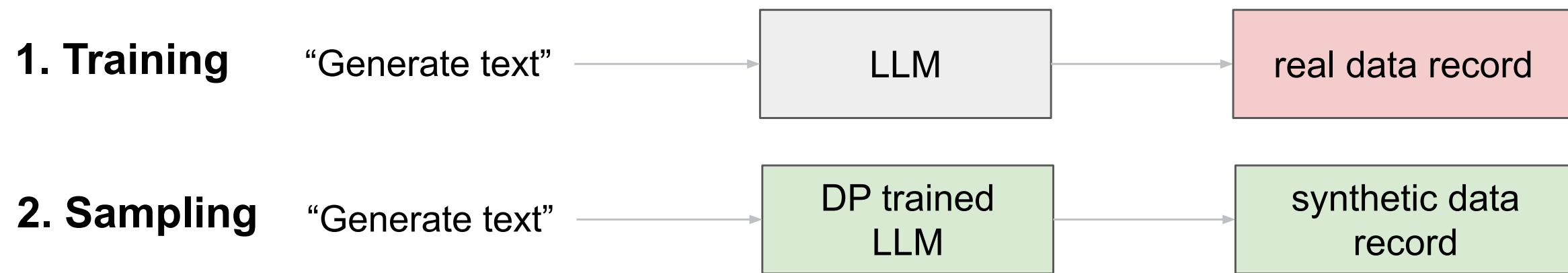
**Goal:** Unlock value of private text data with DP



# DP finetuning

Use DP-SGD to finetune a pre-trained LLM into a data generator.

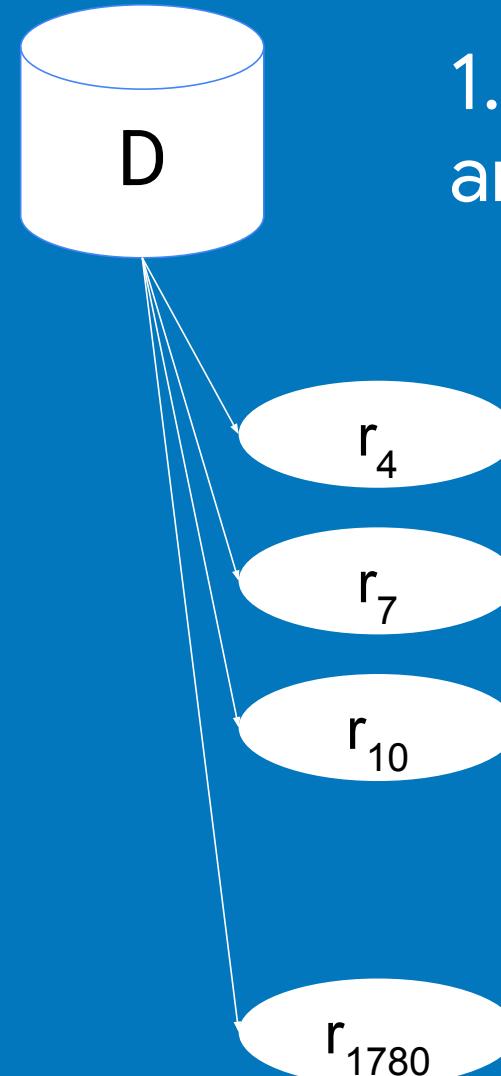
**The most straightforward and performant method.**



Use LoRA on all layers

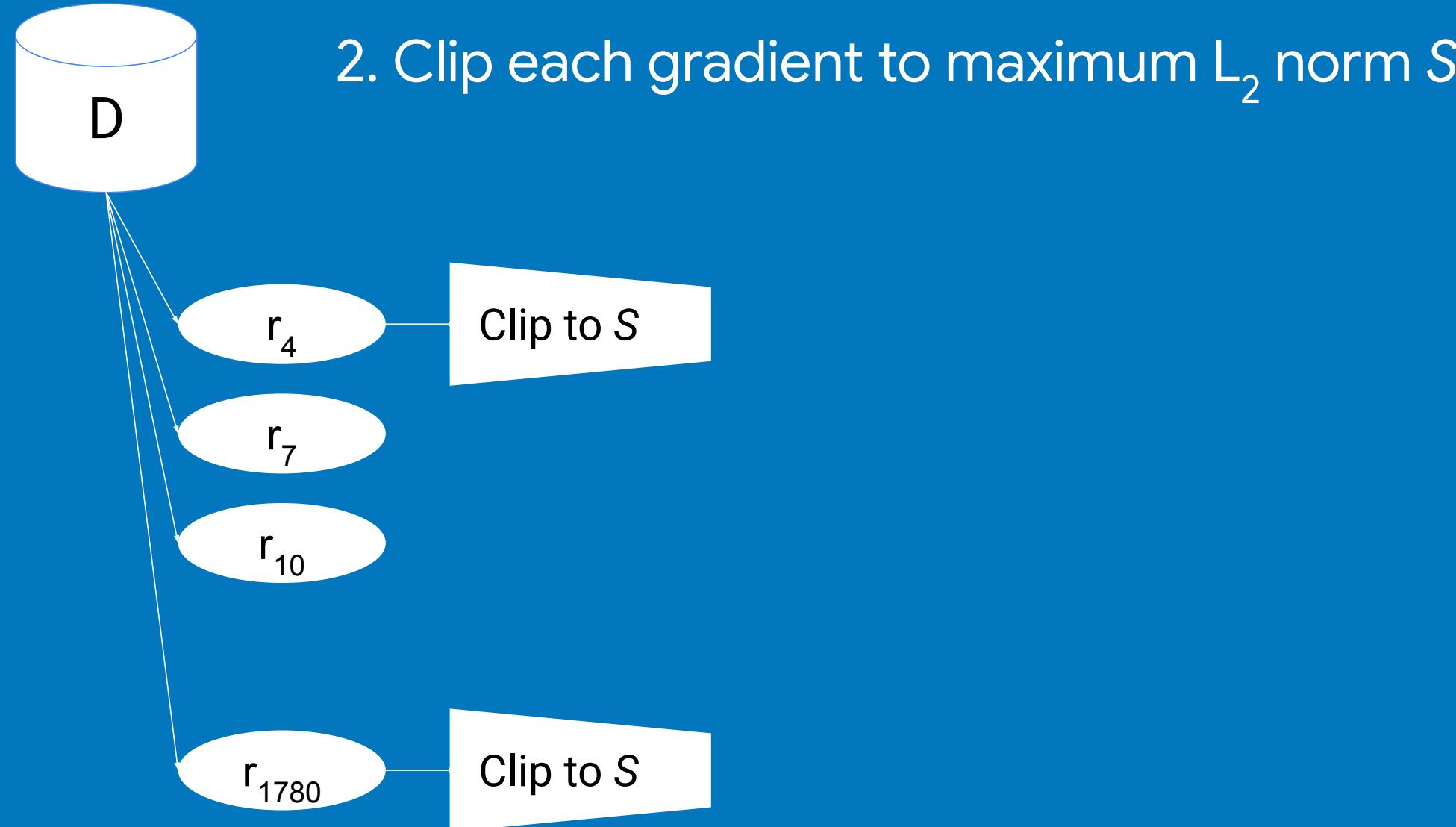
- LoRA outperforms full finetuning empirically
- Also efficiency gains with DP

# Iterative training with differential privacy

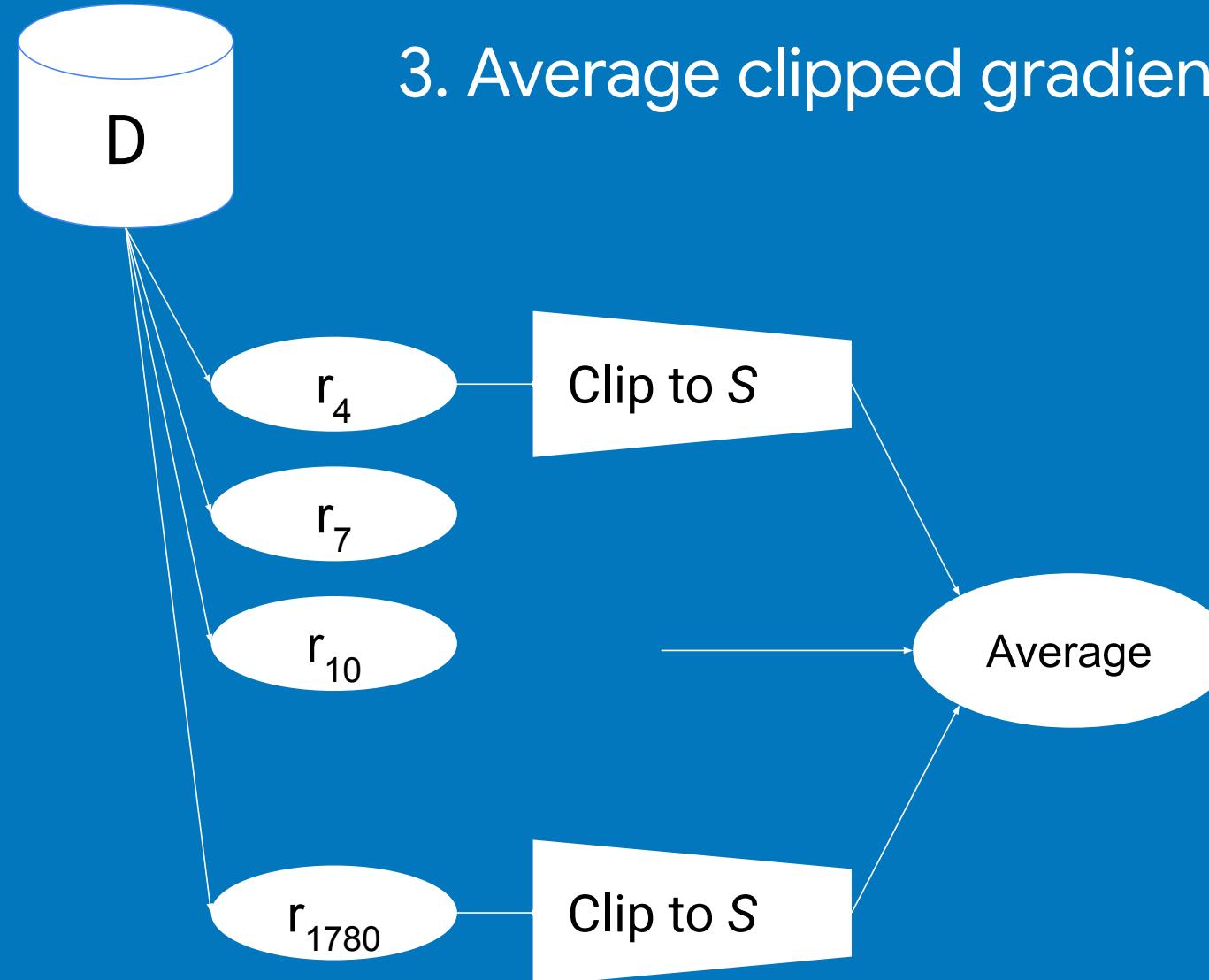


1. Sample a batch of examples  
and **compute gradients** for the current model

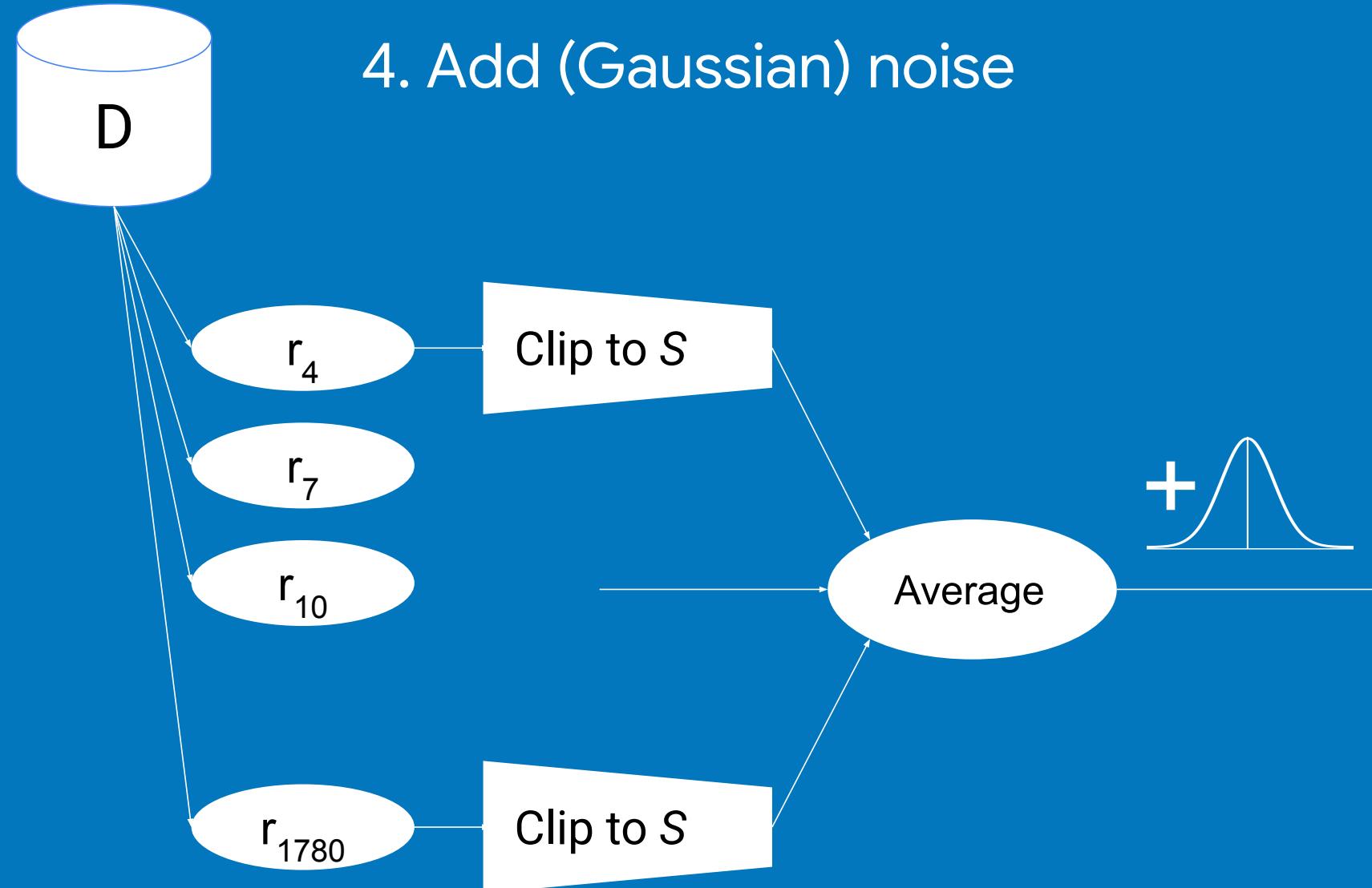
# Iterative training with differential privacy



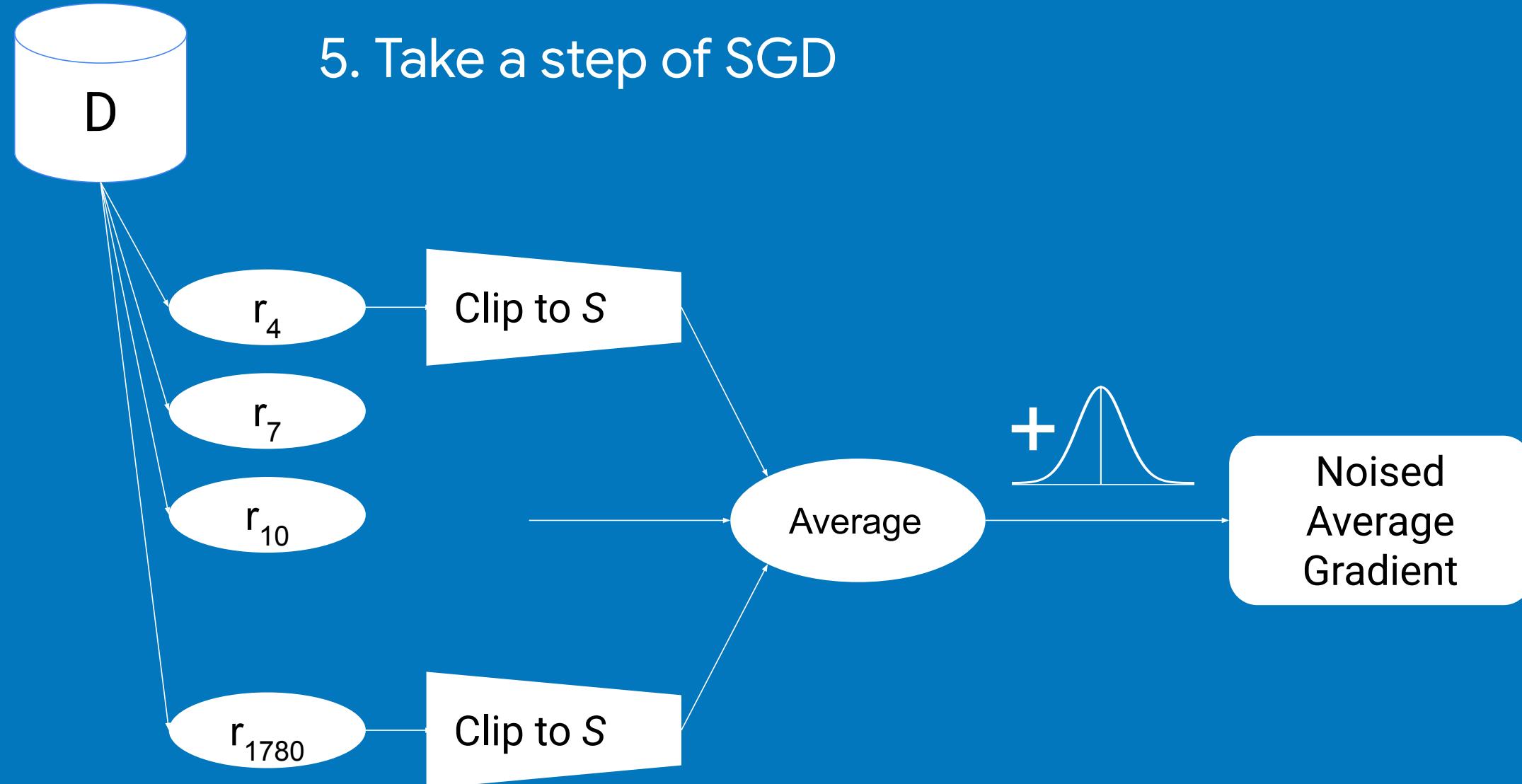
# Iterative training with differential privacy



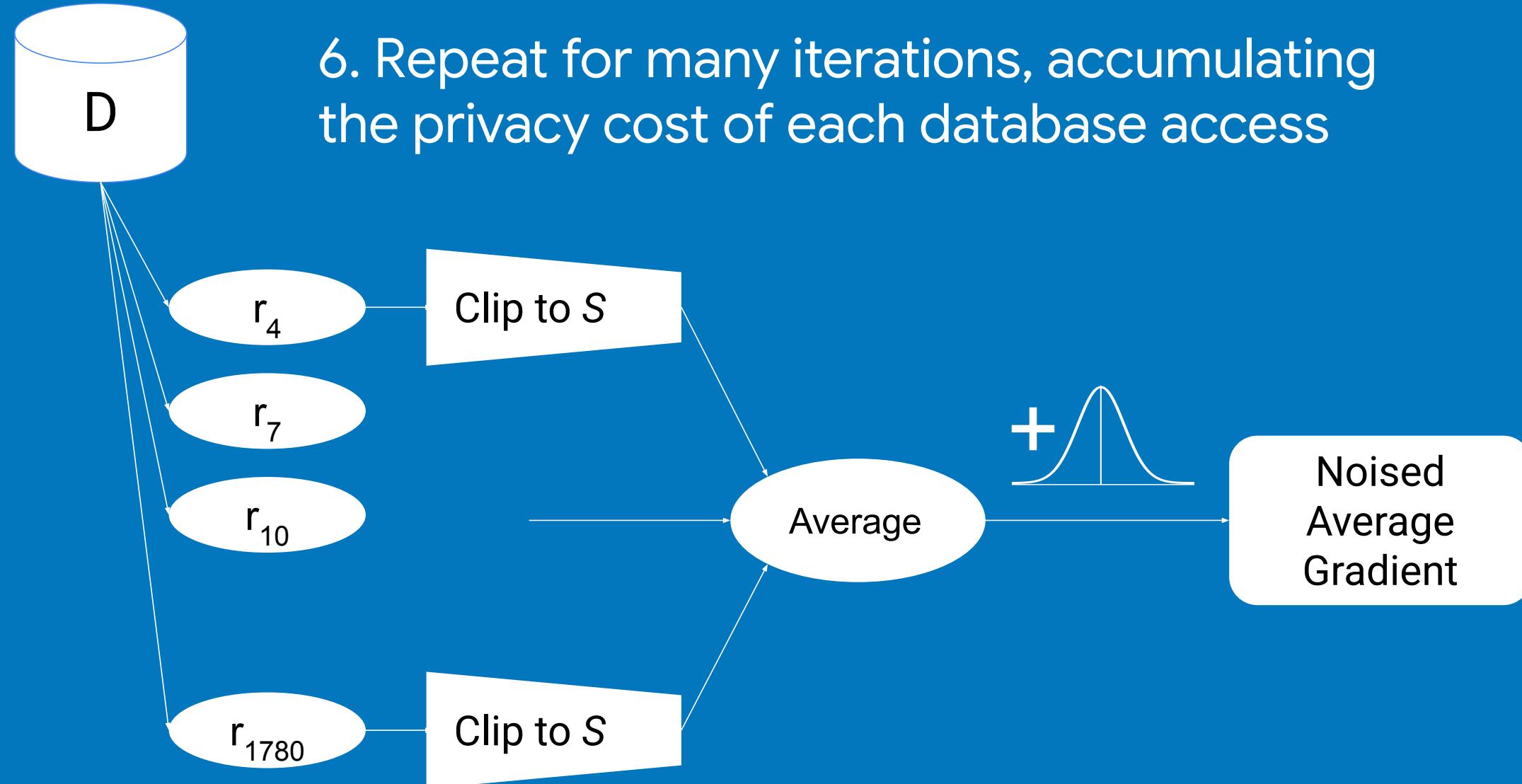
# Iterative training with differential privacy



# Iterative training with differential privacy



# Iterative training with differential privacy



# DP-SGD

## Algorithm 1 Differentially private SGD

```

1: Input:  $N$  examples, batch size  $B$ , steps  $T$ , clip norm  $C$ , noise multiplier  $\sigma$ .
2: Initialize  $\theta_0$  randomly.
3: for  $t = 1$  to  $T$  do
4:   Sample batch  $B_t$  by including each example with probability  $p = B/N$ 
5:   for each  $x_i \in B_t$  do
6:      $g_t(x_i) \leftarrow \nabla_{\theta} \ell(x_i; \theta_t)$                                  $\triangleright$  Per-example gradient
7:      $g_t(x_i) \leftarrow g_t(x_i) / \max(1, \frac{\|g_t(x_i)\|_2}{C})$             $\triangleright$  Clip per-example gradient
8:      $\bar{g}_t \leftarrow \frac{1}{B} (\sum_i g_t(x_i) + \mathcal{N}(0, \sigma^2 C^2 \mathbf{I}))$      $\triangleright$  Add noise and average
9:      $\theta_{t+1} \leftarrow \theta_t - \eta \bar{g}_t$ 
return  $\theta_T$ 

```

# DP-SGD

---

**Algorithm 1** *Regular SGD*

- ```

1: Input:  $N$  examples, batch size  $B$ , iterations  $T$ .
2: Initialize  $\theta_0$  randomly.
3: for  $t = 1$  to  $T$  do
4:   Draw batch  $B_t$  cyclically from the dataset
5:   for each  $x_i \in B_t$  do
6:      $g_t(x_i) \leftarrow \nabla_{\theta} \ell(x_i; \theta_t)$                                  $\triangleright$  Per-example gradient
7:      $g_t(x_i) \leftarrow g_t(x_i)$   $\triangleright$  Do nothing to per-example gradients
8:      $\bar{g}_t \leftarrow \frac{1}{B} (\sum_i g_t(x_i))$                           $\triangleright$  Do not add noise and average
9:    $\theta_{t+1} \leftarrow \theta_t - \eta \bar{g}_t$ 
return  $\theta_T$ 

```

# DP-SGD

## Algorithm 1 Differentially private SGD

```

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9:      $\theta_{t+1} \leftarrow \theta_t - \eta \bar{g}_t$ 
return  $\theta_T$ 

```

**DP Accounting:** based on parameters chosen, compute privacy guarantee  $\varepsilon(N, B, T, \sigma)$

# Per-example gradient clipping in JAX

```
N = 3
w = np.random.randn(2) # (D, )
X = np.random.randn(N, 2) # (N, D)
y = np.random.randn(N) # (N, )

def loss(w, data):
    X, y = data
    return jnp.sum((X @ w - y)**2)
```

Simple regression example

# Per-example gradient clipping in JAX

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w = np.random.randn(2) # (D, )
X = np.random.randn(N, 2) # (N, D)
y = np.random.randn(N) # (N, )

def loss(w, data):
    X, y = data
    return jnp.sum((X @ w - y)**2)

grad_fn = jax.grad(loss)
>>> grad_fn(w, (X, y))
Array([17.44384, 6.9017286], dtype=float32)
```

Simple regression example

Compute gradients wrt.  
parameters  $w$   
- sum of per-example gradients

Training loop: update  $w$ , draw a new batch, ...

# Per-example gradient clipping in JAX

```
# grad_fn: w, data -> dL/dw  
  
grads = jnp.stack(  
    [grad_fn(w, (xi, yi)) for xi, yi in zip(x, y)]  
) # (N, D)
```

Naive per-example grads

# Per-example gradient clipping in JAX

```
# grad_fn: w, data -> dL/dw

grads = jnp.stack(
    [grad_fn(w, (xi, yi)) for xi, yi in zip(x, y)])
) # (N, D)
>>> grads
Array([[ 5.3370066 , 12.219472  ],
       [ 9.310922  , -4.8723297 ],
       [ 2.795912  , -0.44541267]], dtype=float32)
```

Naive per-example grads

# Per-example gradient clipping in JAX

```
# grad_fn: w, data -> dL/dw

grads = jnp.stack(
    [grad_fn(w, (xi, yi)) for xi, yi in zip(x, y)])
) # (N, D)

def clip(g, C):
    return g * jnp.minimum(1, C / jnp.linalg.norm(g))

clipped_grads = jnp.stack([clip(g, 1) for g in grads])
```

Naive per-example grads

# Per-example gradient clipping in JAX

```
# grad_fn: w, data -> dL/dw

grads = jnp.stack(
    [grad_fn(w, (xi, yi)) for xi, yi in zip(x, y)])
) # (N, D)

def clip(g, C):
    return g * jnp.minimum(1, C / jnp.linalg.norm(g))

clipped_grads = jnp.stack([clip(g, 1) for g in grads])
>>> clipped_grads
Array([[ 0.40025145,  0.9164054 ],
       [ 0.88601995, -0.46364704],
       [ 0.987547   , -0.15732467]], dtype=float32)
```

Naive per-example grads

# Per-example gradient clipping in JAX

```
# grad_fn: w, data -> dL/dw

grads = jnp.stack(
    [grad_fn(w, (xi, yi)) for xi, yi in zip(x, y)])
) # (N, D)

def clip(g, C):
    return g * jnp.minimum(1, C / jnp.linalg.norm(g))

clipped_grads = jnp.stack([clip(g, 1) for g in grads])
>>> jnp.sum(clipped_grads, axis=0) # (D,)
Array([2.2738183 , 0.29543367], dtype=float32)
```

Naive per-example grads

Add noise to this, and use instead  
of the regular grad

# Per-example gradient clipping in JAX

```
# grad_fn: w, data -> dL/dw

grads = jnp.stack(
    [grad_fn(w, (xi, yi)) for xi, yi in zip(x, y)])
) # (N, D)
```

SLOW

```
def clip(g, C):
    return g * jnp.minimum(1, C / jnp.linalg.norm(g))

clipped_grads = jnp.stack([clip(g, 1) for g in grads])
>>> jnp.sum(clipped_grads, axis=0) # (D,)
Array([2.2738183 , 0.29543367], dtype=float32)
```

Naive per-example grads

Add noise to this, and use instead  
of the regular grad

# Per-example gradient clipping in JAX

```
# grad_fn: w, data -> dL/dw  
  
grads = jnp.stack(  
    [grad_fn(w, (xi, yi)) for xi, yi in zip(x, y)]  
) # (N, D)
```

SLOW

```
vmap_grad_fn = jax.vmap(  
    grad_fn,  
    in_axes=(None, (0, 0)))  
grads = vmap_grad_fn(w, (x, y)) # (N, D)
```

Using `jax.vmap`

Vectorize over the batch  
axis of the data argument

# Per-example gradient clipping in JAX

```
# grad_fn: w, data -> dL/dw

grads = jnp.stack(
    [grad_fn(w, (xi, yi)) for xi, yi in zip(x, y)])
# (N, D)
```

SLOW

```
vmap_grad_fn = jax.vmap(
    grad_fn,
    in_axes=(None, (0, 0)))
grads = vmap_grad_fn(w, (x, y)) # (N, D)
>>> grads
Array([[ 5.337006 ,  12.219471 ],
       [ 9.310922 , -4.8723297],
       [ 2.795912 , -0.44541267]], dtype=float32)
```

Using `jax.vmap`

Vectorize over the batch  
axis of the data argument

# Per-example gradient clipping in JAX

```
# grad_fn: w, data -> dL/dw
```

```
grads = jnp.stack(  
    [grad_fn(w, (xi, yi)) for xi, yi in zip(x, y)]  
) # (N, D)
```

SLOW

```
vmap_grad_fn = jax.vmap(  
    grad_fn,  
    in_axes=(None, (0, 0)),  
    spmd_axis_name="devices"  
)
```

Using `jax.vmap`

Vectorize over the batch  
axis of the data argument

Parallelize the operation across devices

# Per-example gradient clipping in JAX

```
# loss: w, data -> float  
  
grad_fn = jax.grad(loss)  
>>> grad_fn(w, (X, y))  
Array([17.44384 ,  6.9017286], dtype=float32)
```

Regular training

# Per-example gradient clipping in JAX

```
# loss: w, data -> float  
  
grad_fn = jax.grad(loss)  
>>> grad_fn(w, (X, y))  
Array([17.44384 ,  6.9017286], dtype=float32)
```

Regular training

```
# ... vmap + clip  
clipped_grads = jnp.stack([clip(g, 1) for g in grads])  
>>> jnp.sum(clipped_grads, axis=0) # (D, )  
Array([2.2738183 ,  0.29543367], dtype=float32)
```

Replacement for grad

# Per-example gradient clipping in JAX

```
# loss: w, data -> float  
  
grad_fn = jax.grad(loss)  
>>> grad_fn(w, (X, y))  
Array([17.44384 ,  6.9017286], dtype=float32)
```

Regular training

```
# ... vmap + clip  
clipped_grads = jnp.stack([clip(g, 1) for g in grads])  
>>> jnp.sum(clipped_grads, axis=0) # (D, )  
Array([2.2738183 ,  0.29543367], dtype=float32)
```

Drop in replacement for  
jax.grad!

```
import jax_privacy  
clipped_grad_fn = jax_privacy.experimental.clipped_grad(loss, l2_clip_norm=1)  
>>> clipped_grad_fn(w, (X, y))  
Array([2.2738183 ,  0.29543367], dtype=float32)
```

# github.com/google-deepmind/jax\_privacy

## jax\_privacy v1.0.0 update

The screenshot shows a GitHub repository interface. At the top, there's a navigation bar with a file icon, a dropdown menu set to 'main', the repository name 'jax\_privacy / examples /', a search bar labeled 'Go to file', and a three-dot menu icon. Below this is a commit card for 'RamSaw' with the message 'Update to v1.0.0' and a timestamp '52e9674 · 4 days ago'. A refresh icon is next to the timestamp. The main area displays a table of files and their details:

| Name                                      | Last commit message | Last commit date |
|-------------------------------------------|---------------------|------------------|
| ..                                        |                     |                  |
| distributed_noise_generation.py           | Update to v1.0.0    | 4 days ago       |
| dp_sgd_flax_linen_mnist.ipynb             | Update to v1.0.0    | 4 days ago       |
| dp_sgd_keras_gemma3_lora_finetuning_sa... | Update to v1.0.0    | 4 days ago       |
| dp_sgd_keras_gemma3_synthetic_data.ipynb  | Update to v1.0.0    | 4 days ago       |
| dpmf_strategy_optimization.py             | Update to v1.0.0    | 4 days ago       |
| jax_api_example.py                        | Update to v1.0.0    | 4 days ago       |
| jax_new_api_example.py                    | Update to v1.0.0    | 4 days ago       |
| keras_api_example.py                      | Update to v1.0.0    | 4 days ago       |

# github.com/google-deepmind/jax\_privacy

```
106     noise_multiplier = calibrate.calibrate_noise_multiplier(
107         target_epsilon=1.0,
108         accountant=accountant,
109         batch_sizes=batch_size,
110         num_updates=num_epochs * train_size // batch_size,
111         num_samples=train_size,
112         target_delta=1e-5,
113     )
114     noise_rng = random.key(42)
115     grad_and_value_fn = gradient_clipping.clipped_grad(
116         loss_fn,
117         l2_clip_norm=clipping_norm,
118         batch_argnums=(1, 2),
119         has_aux=False,
120         return_values=True,
121     )
122     sensitivity = grad_and_value_fn.sensitivity(
123         dp_accounting.NeighboringRelation.REPLACE_ONE
124     )
125     privatizer = noise_addition.gaussian_privatizer(
126         stddev=noise_multiplier * sensitivity, noise_key=noise_rng
127     )
```

Example training loop:  
[jax\\_privacy/examples/jax\\_new\\_api\\_example.py](#)

# github.com/google-deepmind/jax\_privacy

## Enabling Differentially Private Fine-tuning

The pre-trained model itself is not differentially private with respect to its initial training data, which we consider non-sensitive. However, the data used for fine-tuning in real world scenarios usually *is* sensitive. To ensure the privacy of this sensitive data (IMDb reviews in our case), we prepare the model so that any subsequent training on this data will be differentially private. This process makes our fine-tuned model differentially private with respect to the sensitive fine-tuning data.

```
In [17]: if CONFIG["USE_DP"]:
    params = keras_api.DPKerasConfig(
        epsilon=CONFIG["EPSILON"],
        delta=CONFIG["DELTA"],
        clipping_norm=CONFIG["CLIPPING_NORM"],
        batch_size=CONFIG["BATCH_SIZE"],
        train_steps=CONFIG["EPOCHS"] * (TRAIN_SIZE // CONFIG["BATCH_SIZE"]),
        train_size=TRAIN_SIZE,
        gradient_accumulation_steps=CONFIG["GRADIENT_ACCUMULATION_STEPS"],
        seed=CONFIG["SEED"],
    )
    gemma_lm = keras_api.make_private(gemma_lm, params)
    print(
        "DP training:"
        f"{CONFIG['CLIPPING_NORM']}={CONFIG['EPOCHS']}={CONFIG['BATCH_SIZE']}"
    )
else:
    print("Non-DP training")
```

```
In [18]: if CONFIG["FINETUNE_MODEL"]:
    optimizer = keras.optimizers.Adam(
        learning_rate=CONFIG["LEARNING_RATE"],
        gradient_accumulation_steps=CONFIG["GRADIENT_ACCUMULATION_STEPS"],
    )

    gemma_lm.compile(
        loss=keras.losses.SparseCategoricalCrossentropy(from_logits=True),
        optimizer=optimizer,
        weighted_metrics=[keras.metrics.SparseCategoricalAccuracy()],
    )
else:
    print("Not finetuning model")
```

Colab tutorial:  
[jax\\_privacy/examples/dp\\_sgd\\_keras\\_gemma3\\_synthetic\\_data.ipynb](#)

# github.com/google-deepmind/jax\_privacy

## Enabling Differentially Private Fine-tuning

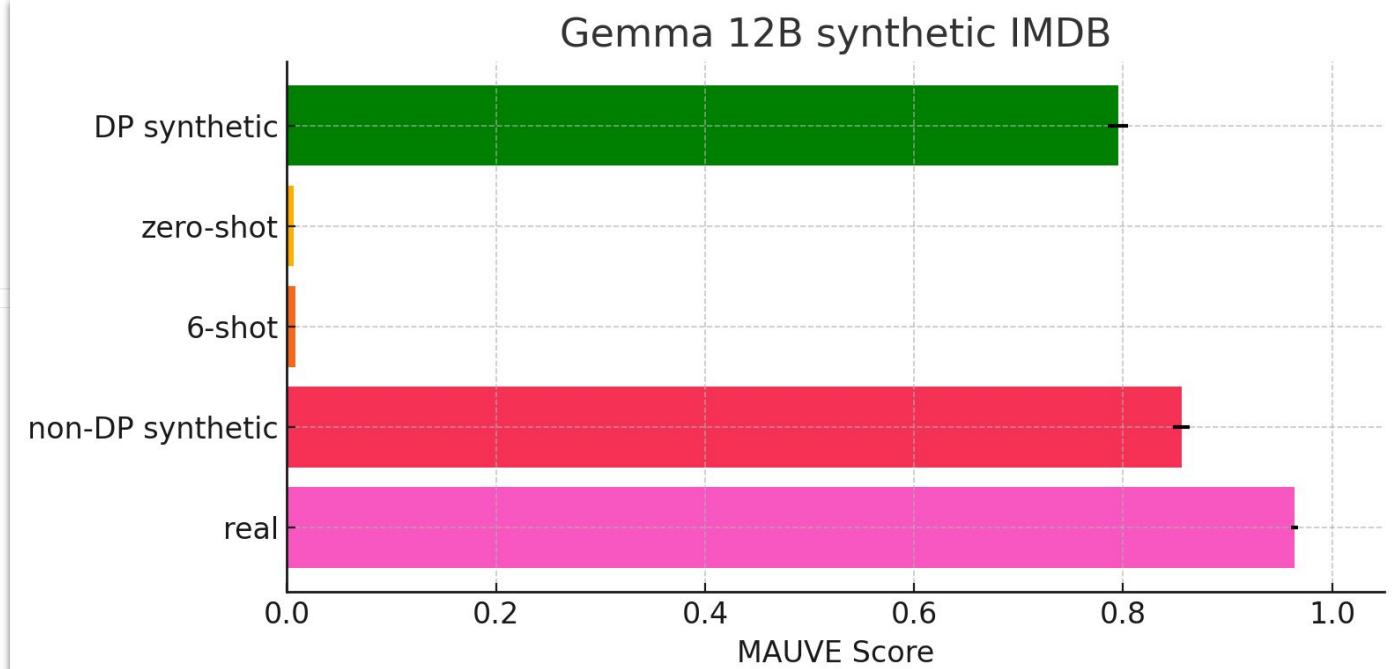
The pre-trained model itself is not differentially private with respect to its initial training data, which we consider non-sensitive. However, the data used for fine-tuning in real world scenarios usually *is* sensitive. To ensure the privacy of this sensitive data (IMDb reviews in our case), we prepare the model so that any subsequent training on this data will be differentially private. This process makes our fine-tuned model differentially private with respect to the sensitive fine-tuning data.

```
In [17]: if CONFIG["USE_DP"]:
    params = keras_api.DPKerasConfig(
        epsilon=CONFIG["EPSILON"],
        delta=CONFIG["DELTA"],
        clipping_norm=CONFIG["CLIPPING_NORM"],
        batch_size=CONFIG["BATCH_SIZE"],
        train_steps=CONFIG["EPOCHS"] * (TRAIN_SIZE // CONFIG["BATCH_SIZE"]),
        train_size=TRAIN_SIZE,
        gradient_accumulation_steps=CONFIG["GRADIENT_ACCUMULATION_STEPS"],
        seed=CONFIG["SEED"],
    )
    gemma_lm = keras_api.make_private(gemma_lm, params)
    print(
        "DP training:"
        f"\n{CONFIG['CLIPPING_NORM']}={CONFIG['EPOCHS']}={CONFIG['BATCH_SIZE']}"
    )
else:
    print("Non-DP training")
```

```
In [18]: if CONFIG["FINETUNE_MODEL"]:
    optimizer = keras.optimizers.Adam(
        learning_rate=CONFIG["LEARNING_RATE"],
        gradient_accumulation_steps=CONFIG["GRADIENT_ACCUMULATION_STEPS"],
    )

    gemma_lm.compile(
        loss=keras.losses.SparseCategoricalCrossentropy(from_logits=True),
        optimizer=optimizer,
        weighted_metrics=[keras.metrics.SparseCategoricalAccuracy()],
    )
else:
    print("Not finetuning model")
```

Colab tutorial:  
[jax\\_privacy/examples/  
dp\\_sgd\\_keras\\_gemma3\\_synthetic\\_data.ipynb](https://colab.research.google.com/github/google-deepmind/jax_privacy/blob/main/examples/dp_sgd_keras_gemma3_synthetic_data.ipynb)



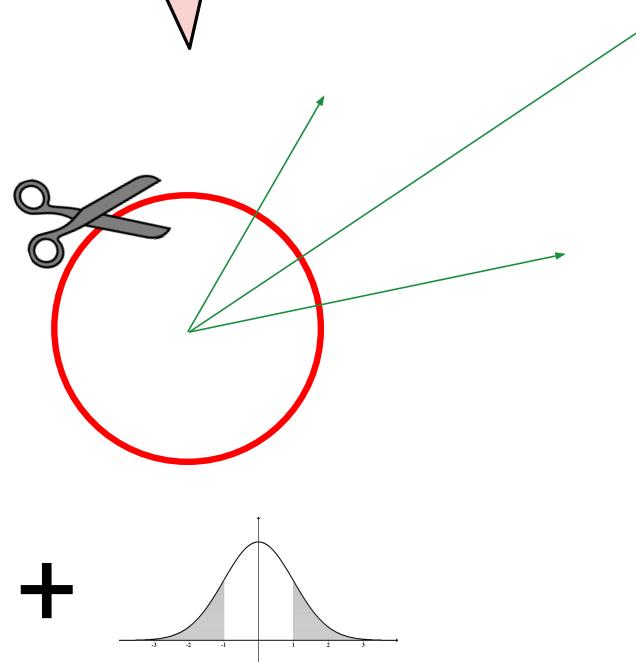
# Hyperparameter tuning

Important hparams: Steps  $T$ , Batch size  $B$ , clipping norm  $C$ , noise multiplier  $\sigma$

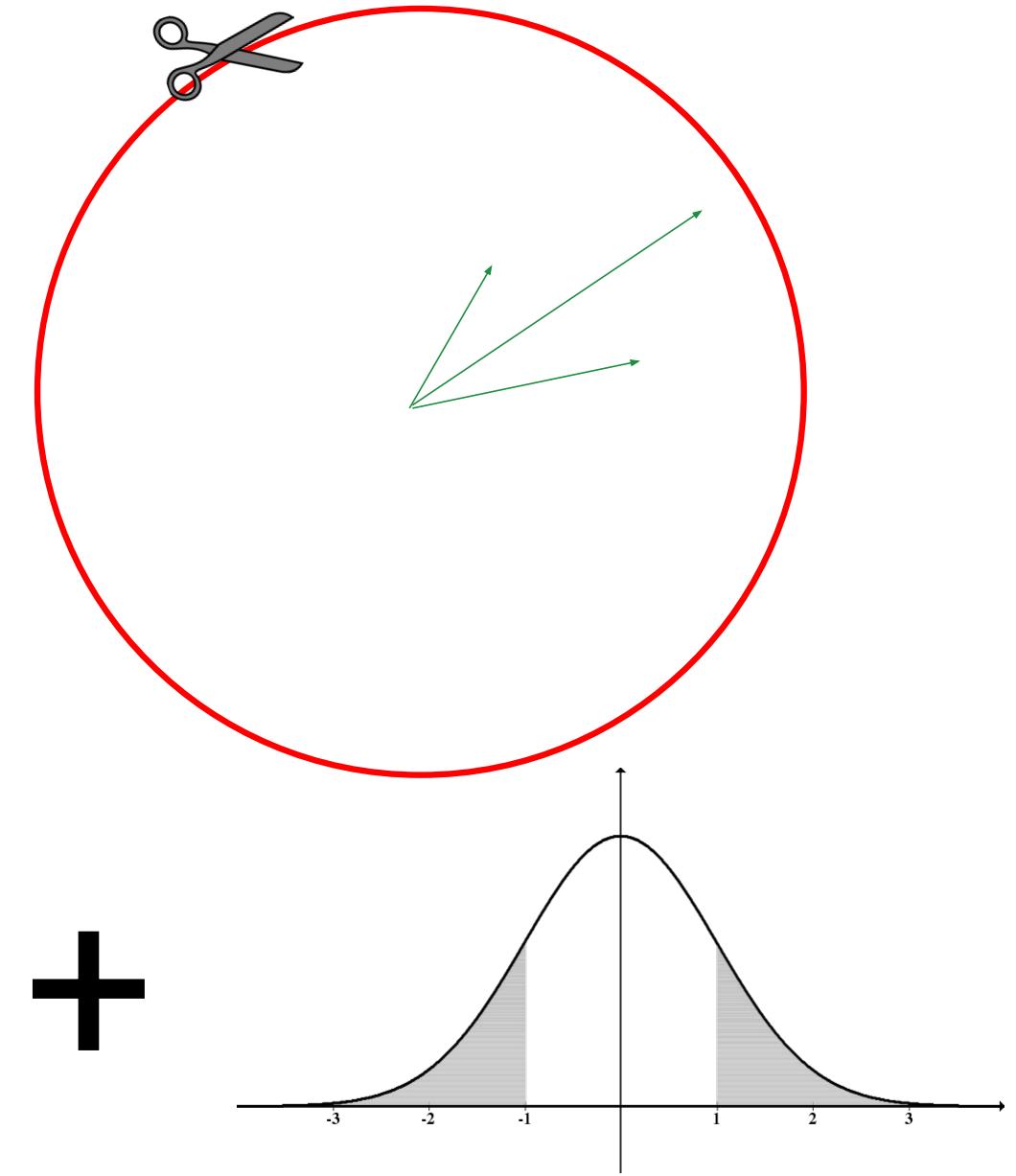
$$\tilde{g} = \frac{1}{B} \left( \sum_i \text{clip}_C(g_i) + \mathcal{N}(0, \sigma^2 C^2 I) \right)$$

1. Under a particular threshold  $C$ , a large range works:
  - a. Pick  $C$  so that almost all gradients are clipped, which corresponds to a biased, but less noisy update

Small clip norm:  
update magnitudes lost



Large clip norm: high noise for DP



# Hyperparameter tuning

Important hparams: Steps  $T$ , Batch size  $B$ , clipping norm  $C$ , noise multiplier  $\sigma$

$$\tilde{g} = \frac{1}{B} \left( \sum_i \text{clip}_C(g_i) + \mathcal{N}(0, \sigma^2 C^2 I) \right)$$

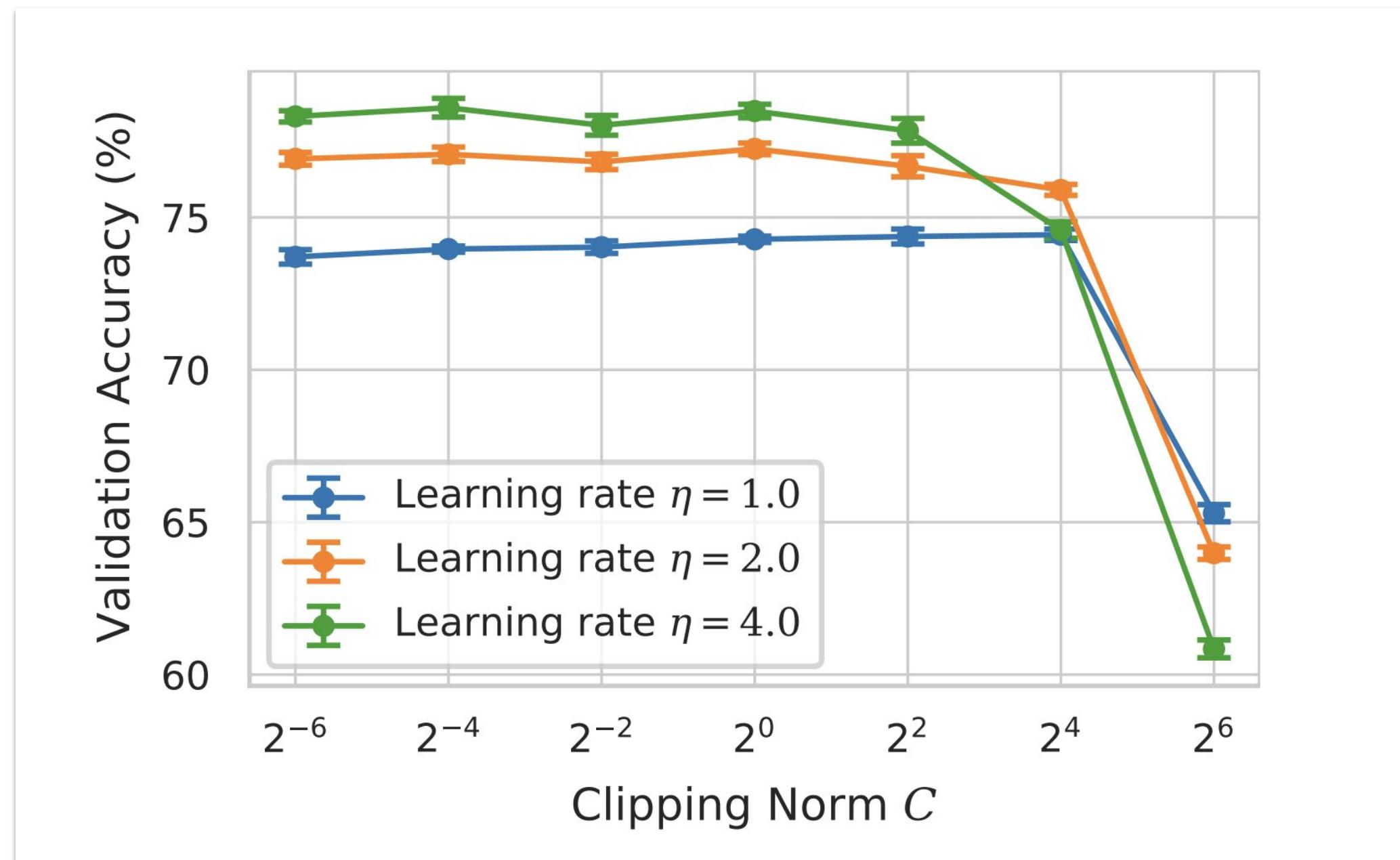
1. Under a particular threshold  $C$ , a large range works:
  - a. Pick  $C$  so that almost all gradients are clipped, which corresponds to a biased, but less noisy update
2. Normalize the update to decouple learning rate from  $C$

# Hyperparameter tuning

Important hparams: Steps  $T$ , Batch size  $B$ , clipping norm  $C$ , noise multiplier  $\sigma$

$$\tilde{g} = \frac{1}{B} \left( \sum_i \boxed{\frac{1}{C}} \text{clip}_C(g_i) + \mathcal{N}(0, \sigma^2 I) \right)$$

1. Under a particular threshold  $C$ , a large range works:
  - a. Pick  $C$  so that almost all gradients are clipped, which corresponds to a biased, but less noisy update
2. Normalize the update to decouple learning rate from  $C$



Source: [Unlocking High-Accuracy Differentially Private Image Classification through Scale \(De et al., 2022\)](#)

# Hyperparameter tuning

- Important hparams: Steps  $T$ , Batch size  $B$ , clipping norm  $C$ , noise multiplier  $\sigma$

$$\tilde{g} = \frac{1}{B} \left( \sum_i \frac{1}{C} \text{clip}_C(g_i) + \mathcal{N}(0, \sigma^2 I) \right)$$

1. Under a particular threshold  $C$ , a large range works:
  - a. Pick  $C$  so that almost all gradients are clipped, which corresponds to a biased, but less noisy update
2. Normalize the update to decouple learning rate from  $C$
3. Under fixed  $\epsilon(\sigma, B, T)$ , spending more compute helps compared to non-DP setup:
  - a. Fixing  $B$ , more steps  $T$  and correspondingly larger  $\sigma$  usually helps
  - b. Fixing  $T$ , larger batch size  $B$  and corresponding larger  $\sigma$  usually helps

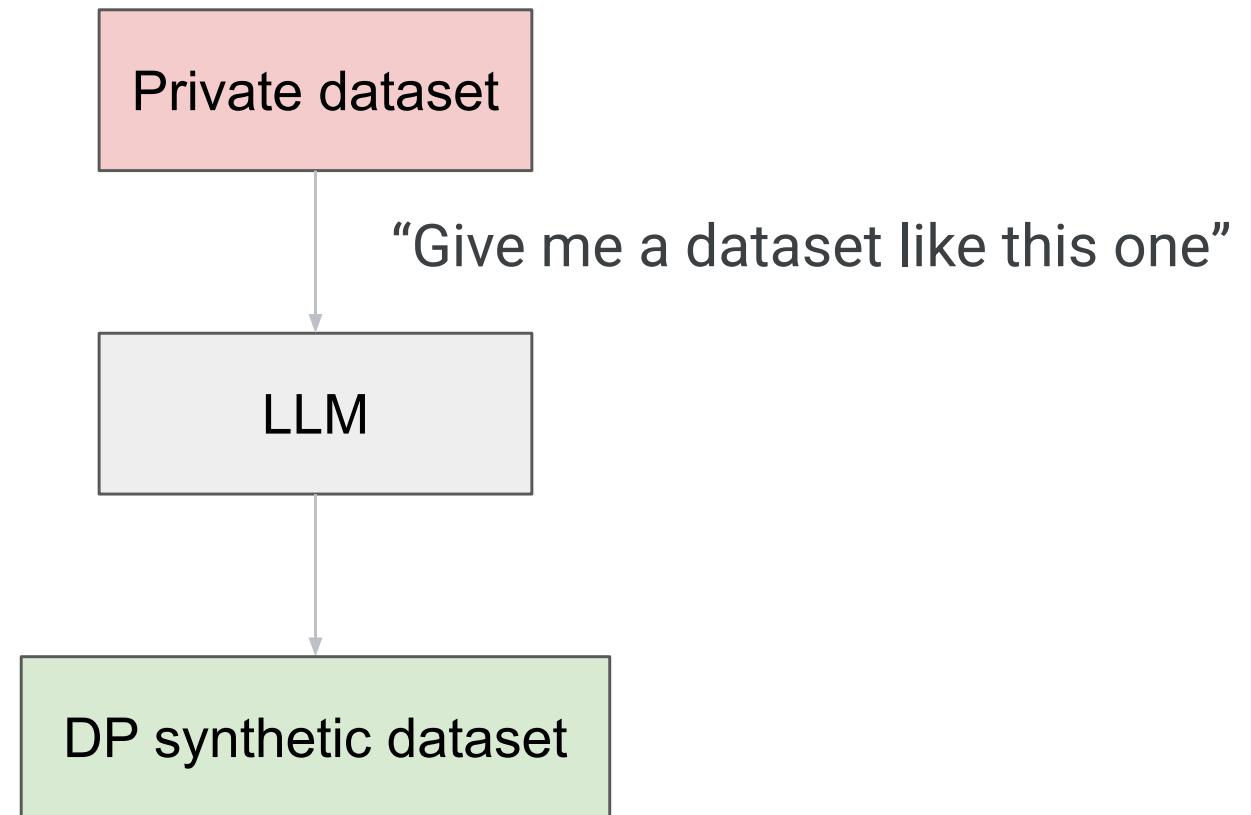
See: [Scaling Laws for Differentially Private Language Models \(McKenna et. al, ICML'25\)](#)

# Inference-only methods

- Does not require a custom DP-SGD implementation or access to model weights.
- Operates on top of an existing inference stack.
- Faster iteration but worse quality

Analogous to tradeoffs between finetuning/prompt engineering.

Private evolution (*API* access)  
DP inference (*logits* access)



# Private evolution

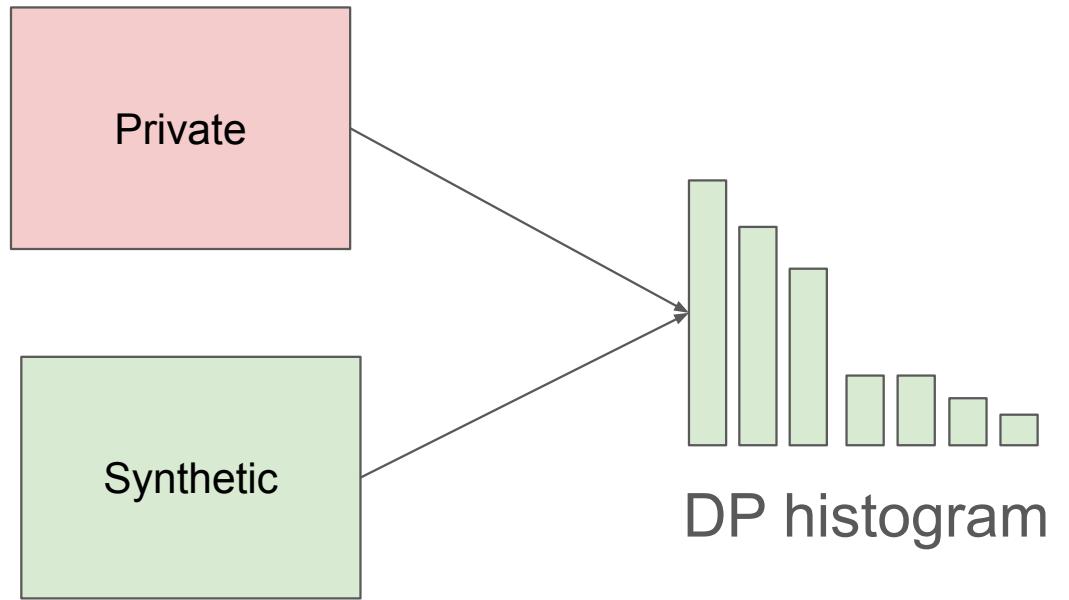
**Starting** from a seed of entirely synthetic corpus,  
Then **alternate between**:

- (A) filtering down to the examples most similar to private data; and
- (B) expanding the corpus with LLM rewrites

Only place private data is used: finding the most similar data.

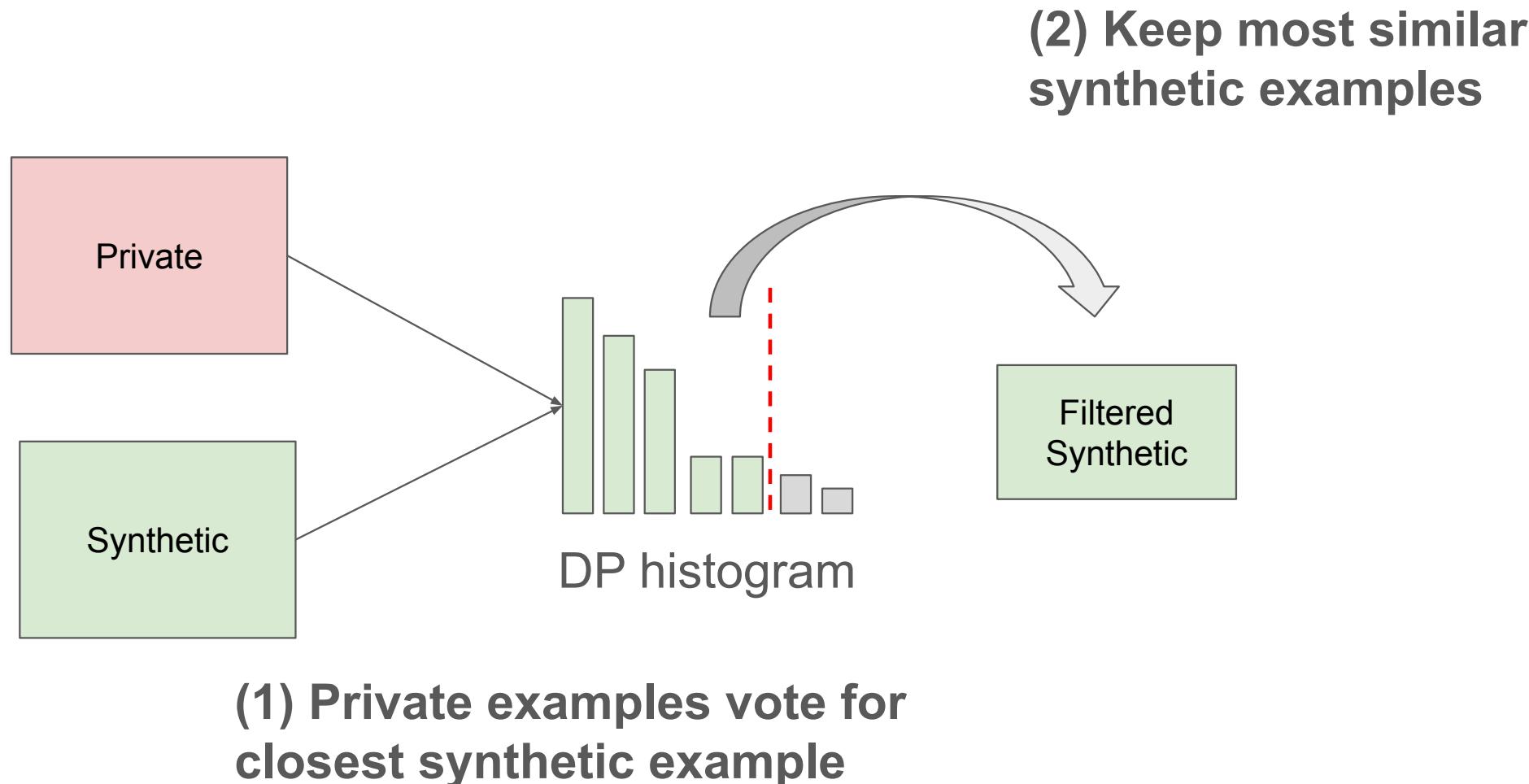
**Best for low target epsilon/low private data volume scenarios**

# Private evolution

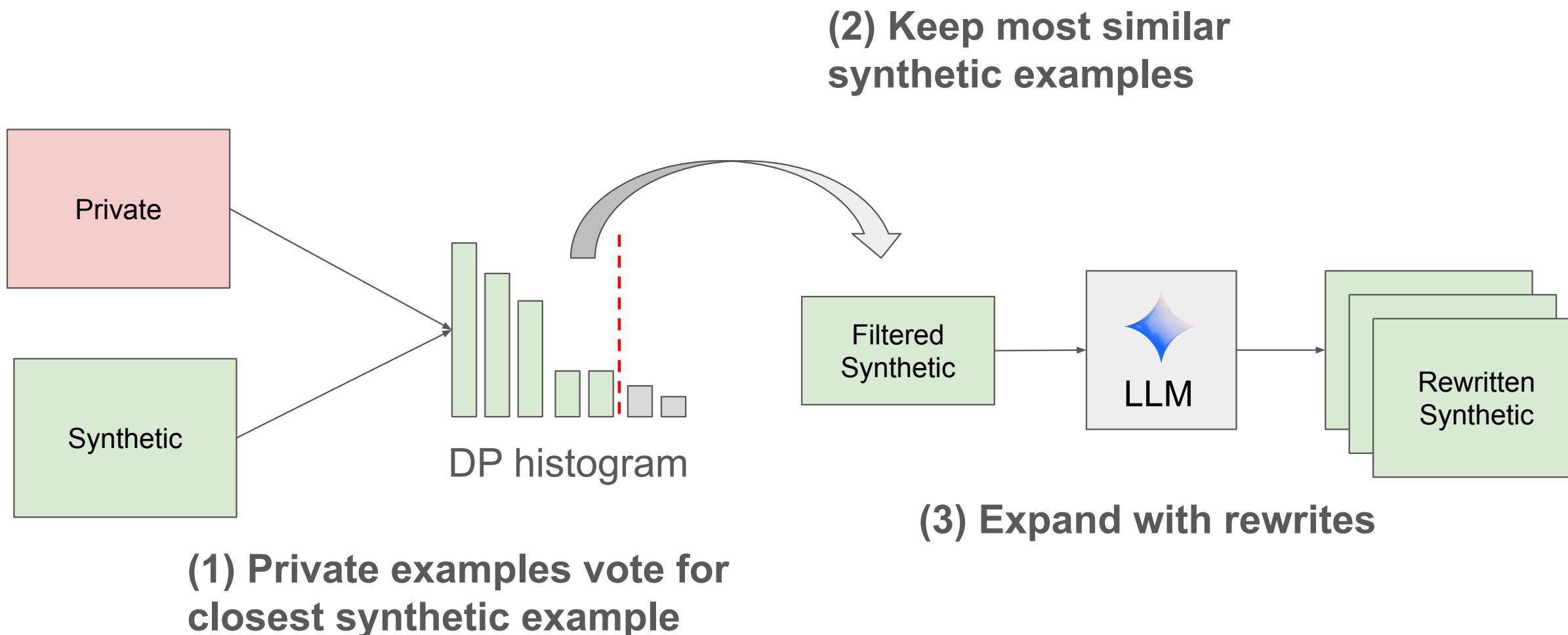


**(1) Private examples vote for  
closest synthetic example**

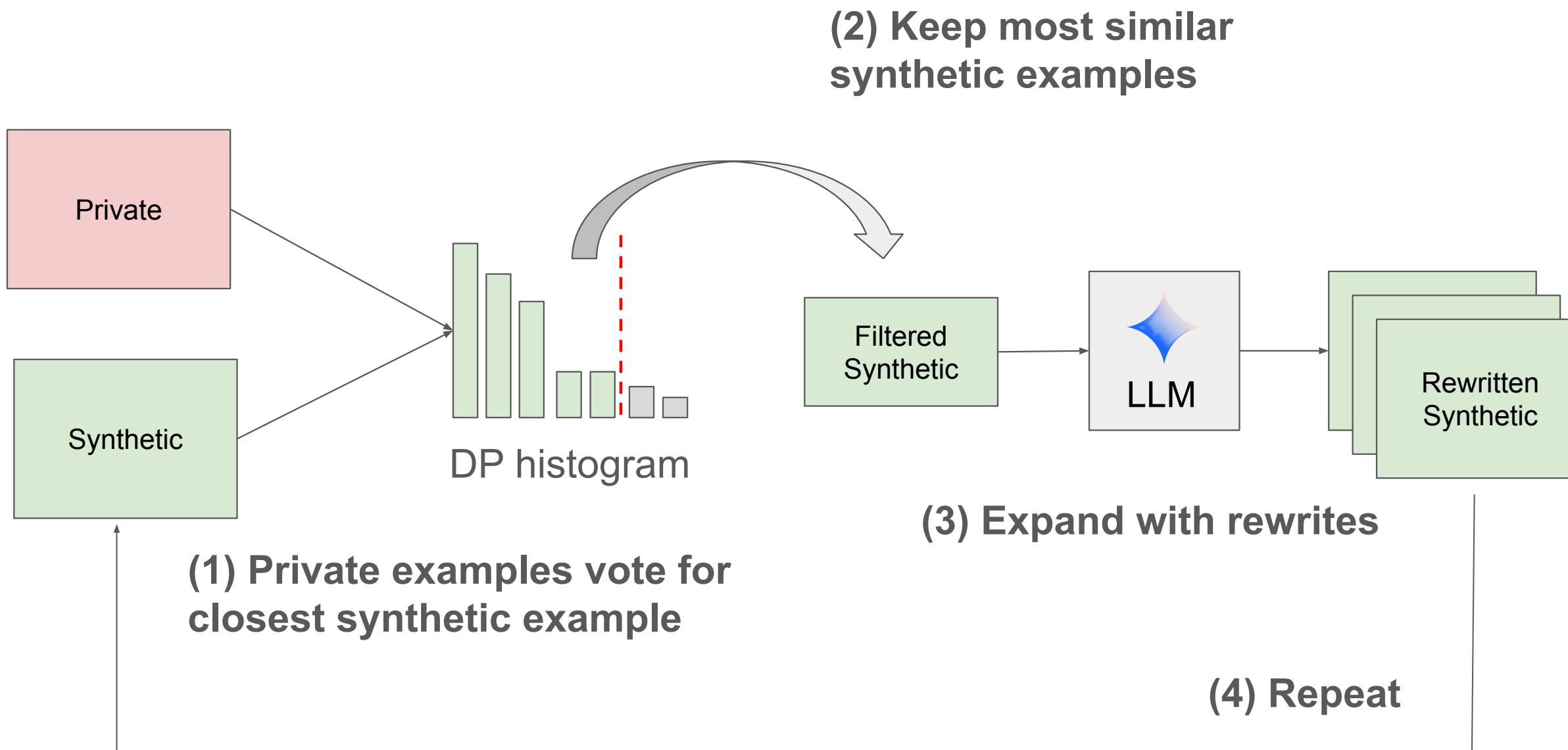
# Private evolution



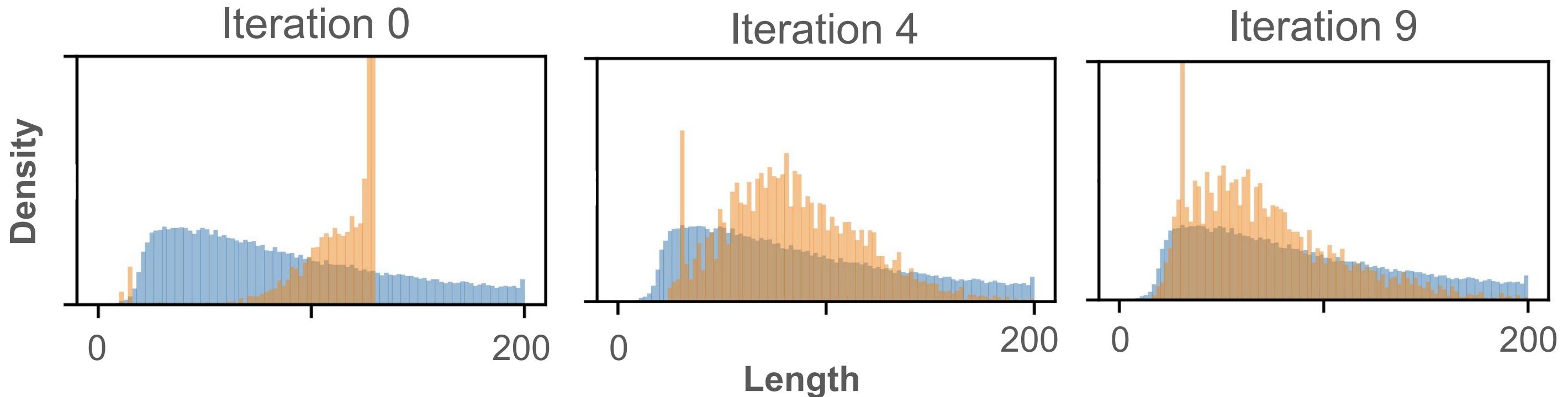
# Private evolution



# Private evolution



# Private evolution



Source: [Differentially Private Synthetic Data via Foundation Model APIs 2: Text \(Xie et al., ICML'24\)](#)

# Private evolution

1. Some prompt engineering required:
  - Seed corpus generation
  - Rewrite prompt should introduce appropriate amount of variation

# Private evolution

## Seed corpus prompt

**SYSTEM:** You are required to write an example of review based on the provided Business Category and Review Stars that fall within the range of 1.0-5.0.

**USER:** Business Category: {label\_1} | Review Stars: {label\_2} with keyword {subcategory}

(subcategories generated by LLM)

Source: [Differentially Private Synthetic Data via Foundation Model APIs 2: Text \(Xie et al., ICML'24\)](#)

## Rewrite prompt

**SYSTEM:** You are a helpful, pattern-following assistant.

**USER:** Based on the Business Category and Review Stars, you are required to fill in the blanks in the Input sentences. If there are no blanks, you are required to output the original Input sentences.

Business Category: {label\_1} | Review Stars: {label\_2}  
Input: {masked\_input}

# Private evolution

1. Some prompt engineering required:
  - Seed corpus generation
  - Rewrite prompt should introduce appropriate amount of variation
2. Private data can be highly ephemeral or kept on-device
3. Private post-processing: the first 2 steps of PE (voting and filtering) can be used standalone to improve DP finetuning outputs.

# DP inference

Introduces DP during the **language model decoding process**, by:

- (1) distributing private data into generation prompts in parallel; and
- (2) mixing their output predictions.

Privacy costs are paid per token generated.

**Best for generating a small amount of examples quickly.**

# DP inference

**Idea:** Prompt the LLM to generate synthetic data from real data.

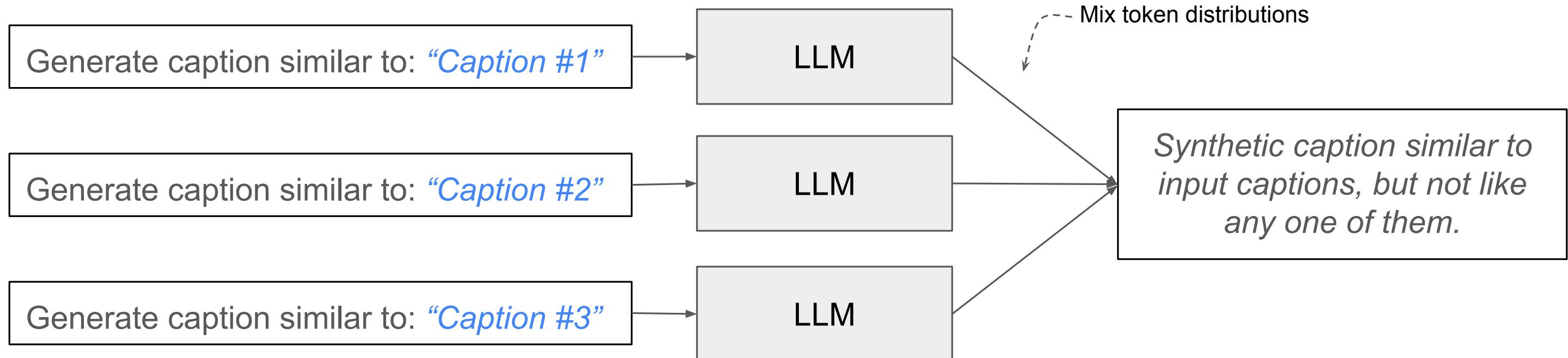


**Problem:** LLM can reveal private information.

# DP inference

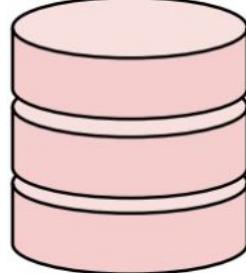
**Observation:** LLM responses are generated randomly, one token at a time.

**Solution:** Mix token distributions across parallel LLMs running on different inputs, which reduces dependence on any one input.

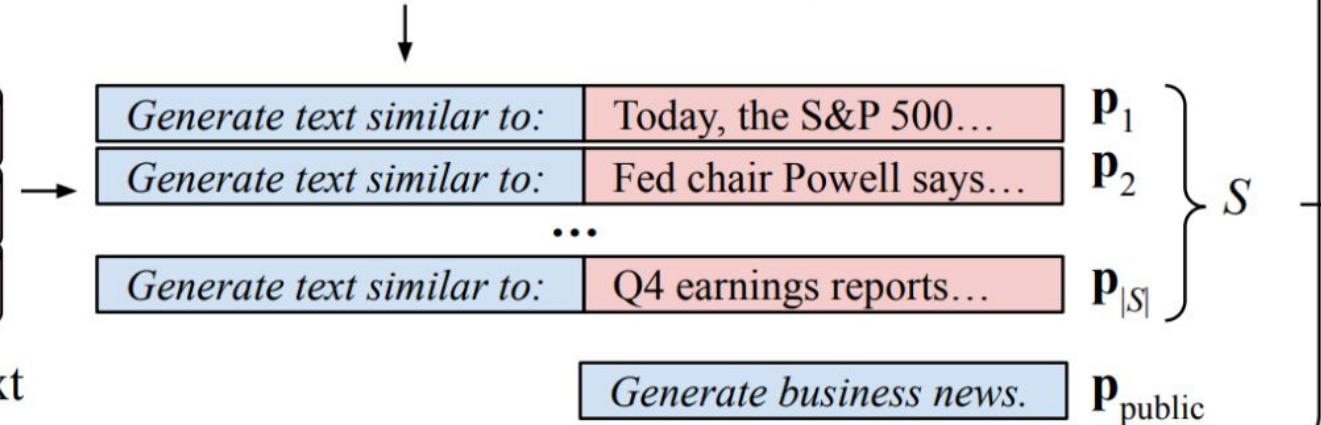


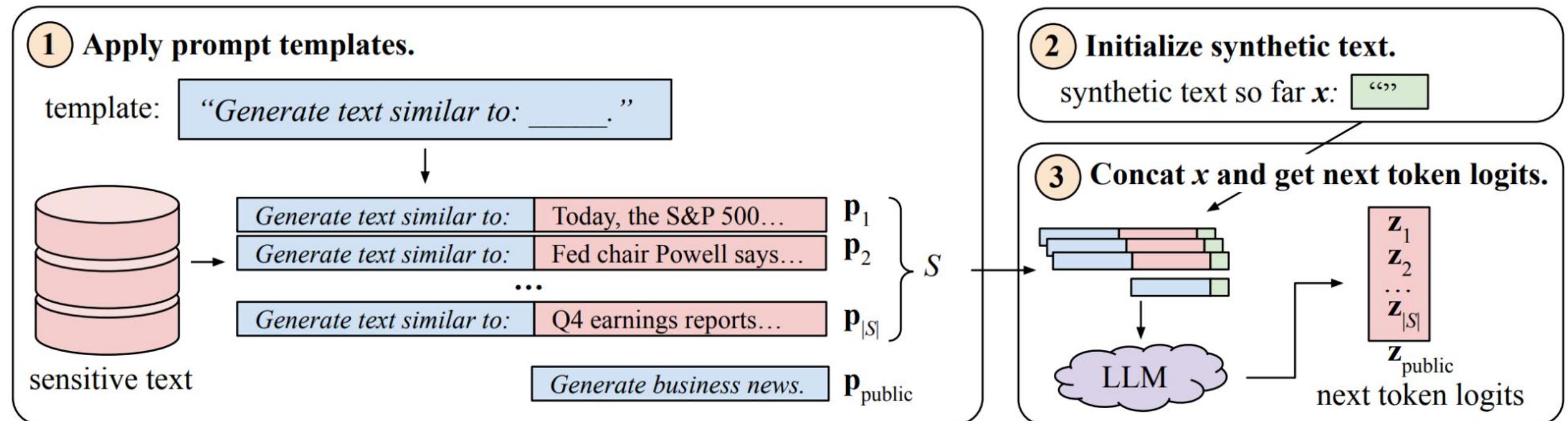
## 1 Apply prompt templates.

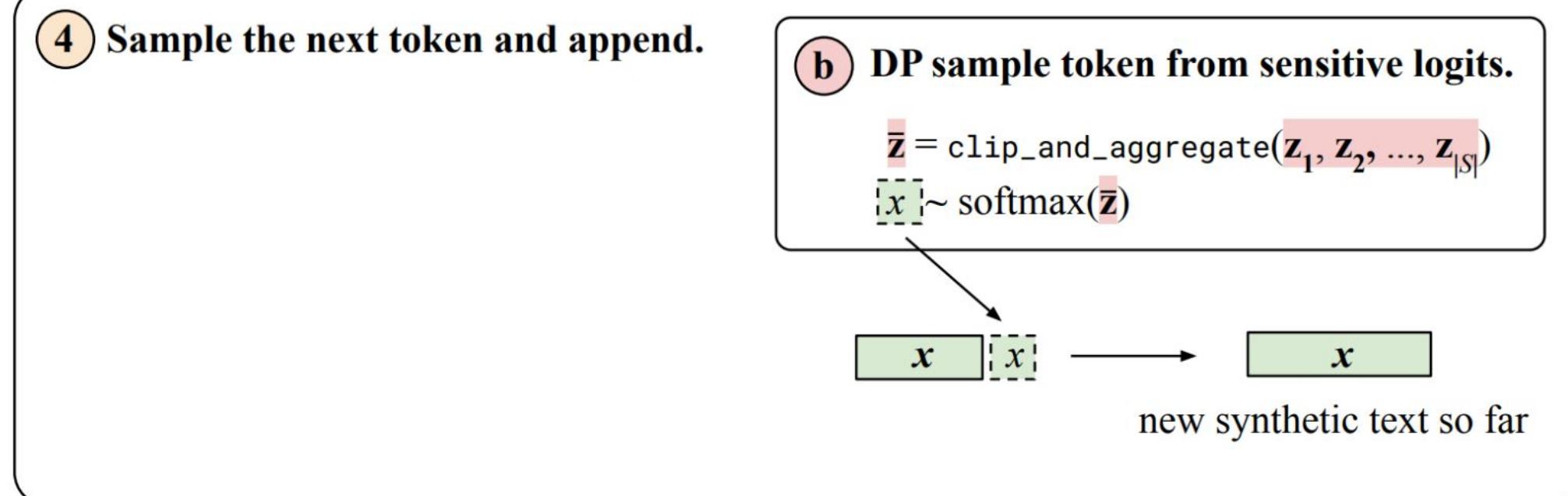
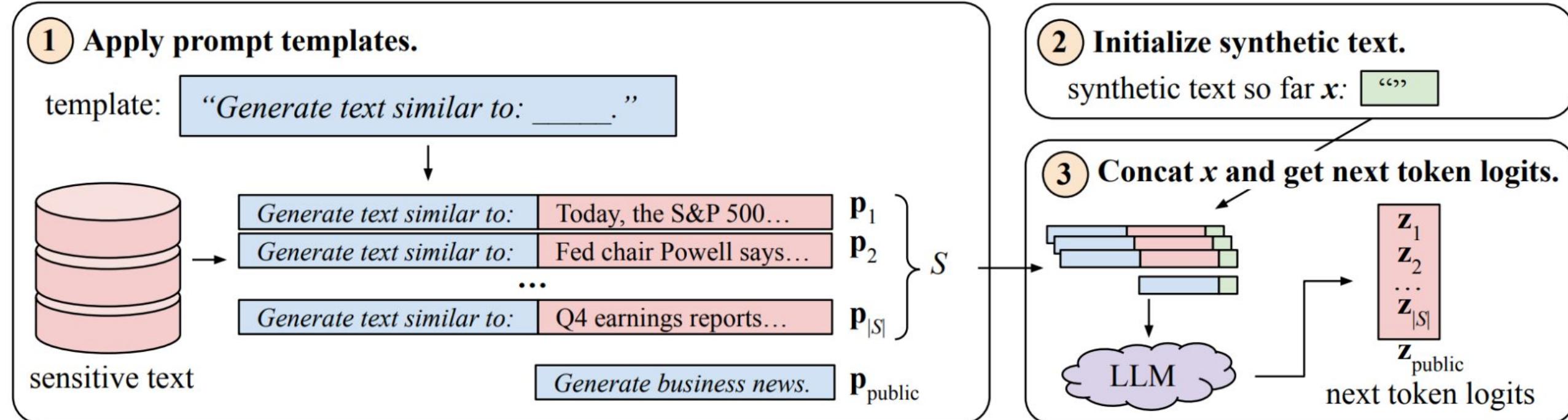
template: “*Generate text similar to: \_\_\_\_\_.*”

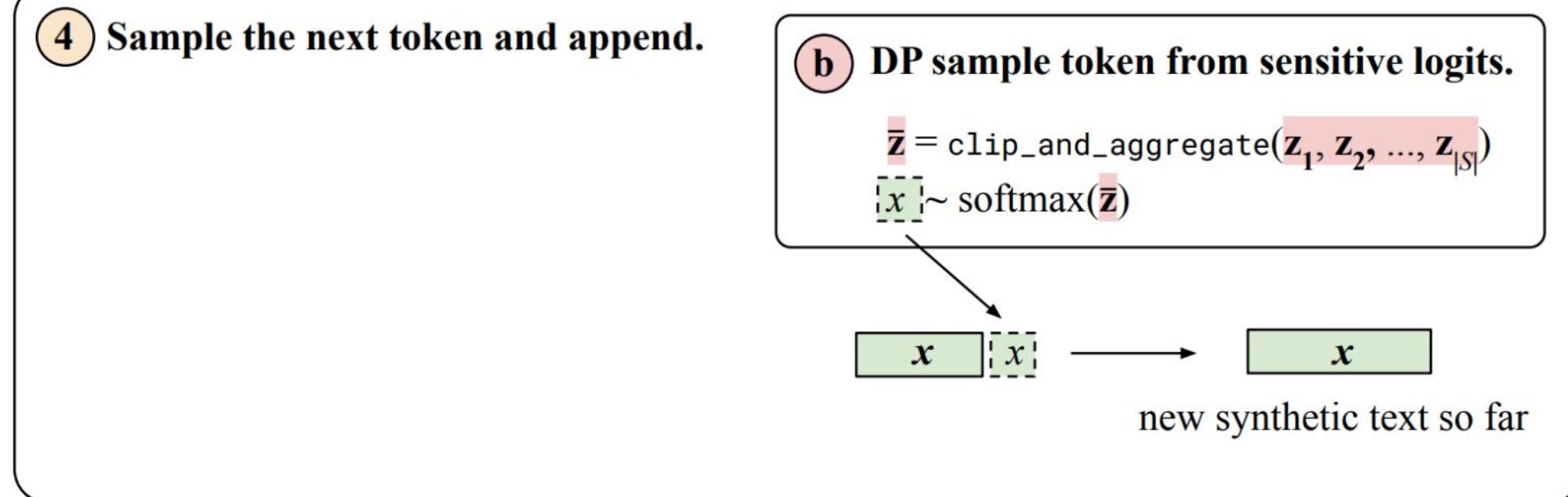
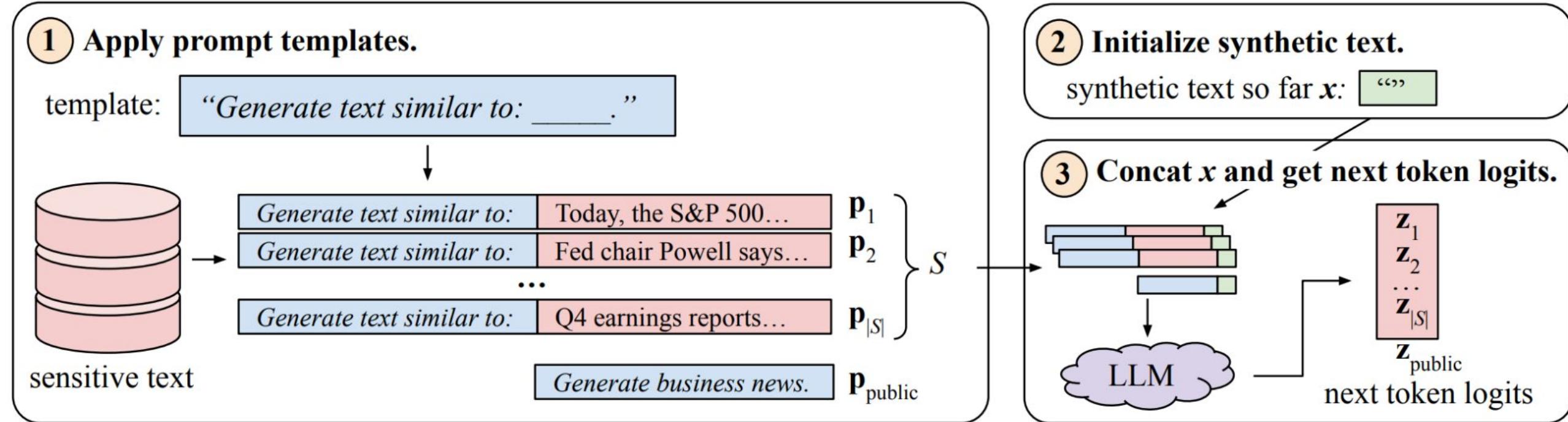


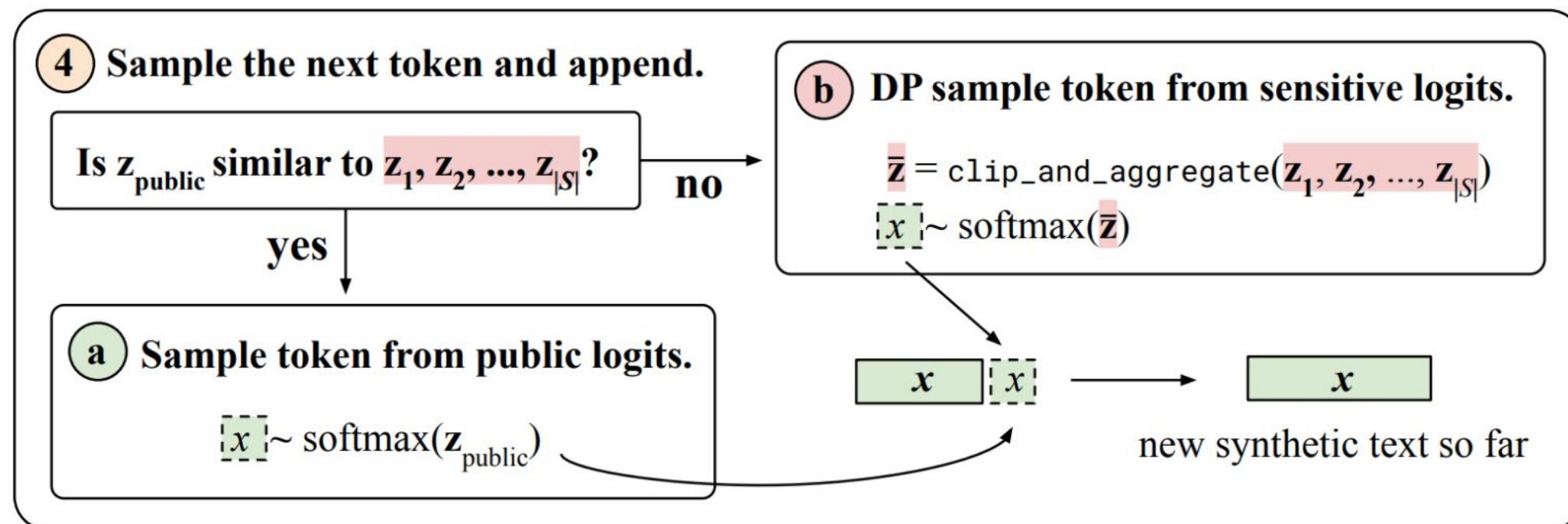
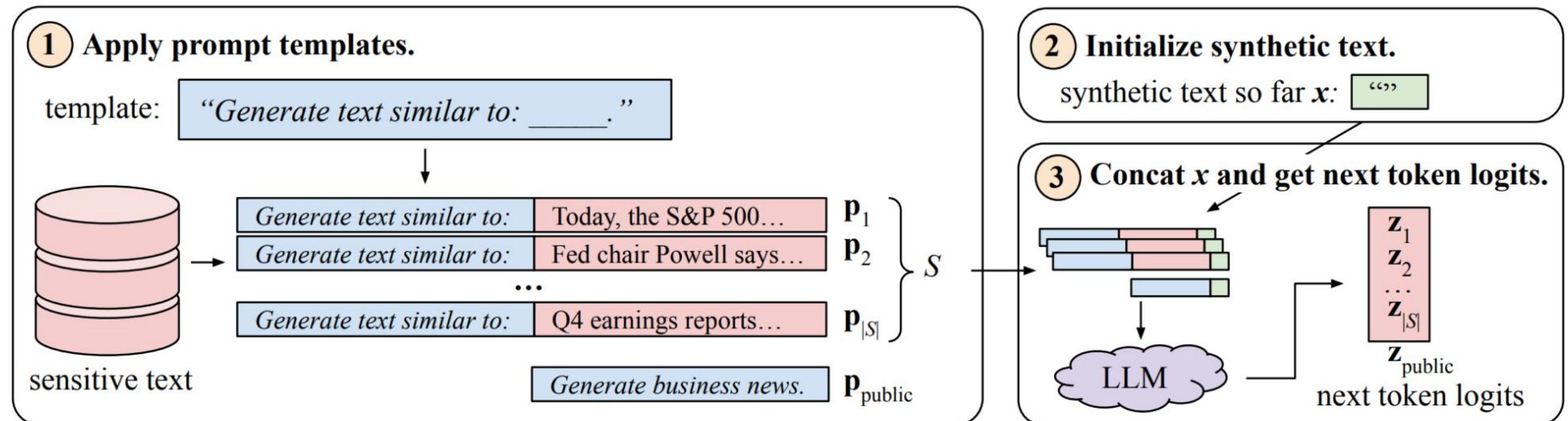
sensitive text











# DP inference

---

**Algorithm 2** DP Inference

---

Vocabulary  $\mathcal{X}$ , set of all strings  $\mathcal{X}^*$ , set of token probability distributions  $\Delta(\mathcal{X})$ .

For  $a, b \in \mathcal{X}^*$ ,  $ab$  denotes concatenation.

# DP inference

---

**Algorithm 2** DP Inference

---

Vocabulary  $\mathcal{X}$ , set of all strings  $\mathcal{X}^*$ , set of token probability distributions  $\Delta(\mathcal{X})$ .  
For  $a, b \in \mathcal{X}^*$ ,  $ab$  denotes concatenation.

- 1: **Input:** LLM:  $\mathcal{X}^* \rightarrow \Delta(\mathcal{X})$ , private prompts  $\mathbf{x}^{(1)}, \dots, \mathbf{x}^{(n)} \in \mathcal{X}^*$ , response length  $T$ .

# DP inference

---

**Algorithm 2** DP Inference

---

Vocabulary  $\mathcal{X}$ , set of all strings  $\mathcal{X}^*$ , set of token probability distributions  $\Delta(\mathcal{X})$ .  
For  $a, b \in \mathcal{X}^*$ ,  $ab$  denotes concatenation.

- 1: **Input:** LLM:  $\mathcal{X}^* \rightarrow \Delta(\mathcal{X})$ , private prompts  $\mathbf{x}^{(1)}, \dots, \mathbf{x}^{(n)} \in \mathcal{X}^*$ , response length  $T$ .
- 2:  $s \leftarrow \emptyset$       Initialize the response

# DP inference

---

**Algorithm 2** DP Inference

---

Vocabulary  $\mathcal{X}$ , set of all strings  $\mathcal{X}^*$ , set of token probability distributions  $\Delta(\mathcal{X})$ .  
For  $a, b \in \mathcal{X}^*$ ,  $ab$  denotes concatenation.

- 1: **Input:** LLM:  $\mathcal{X}^* \rightarrow \Delta(\mathcal{X})$ , private prompts  $\mathbf{x}^{(1)}, \dots, \mathbf{x}^{(n)} \in \mathcal{X}^*$ , response length  $T$ .
- 2:  $s \leftarrow \emptyset$                                   For each token of the response
- 3: **for**  $t = 1$  to  $T$  **do**

# DP inference

---

**Algorithm 2** DP Inference

---

Vocabulary  $\mathcal{X}$ , set of all strings  $\mathcal{X}^*$ , set of token probability distributions  $\Delta(\mathcal{X})$ .  
For  $a, b \in \mathcal{X}^*$ ,  $ab$  denotes concatenation.

- 1: **Input:** LLM:  $\mathcal{X}^* \rightarrow \Delta(\mathcal{X})$ , private prompts  $\mathbf{x}^{(1)}, \dots, \mathbf{x}^{(n)} \in \mathcal{X}^*$ , response length  $T$ .
- 2:  $s \leftarrow \emptyset$
- 3: **for**  $t = 1$  to  $T$  **do**
- 4:     **for**  $i = 1$  to  $n$  **do**
- 5:          $p_t^{(i)} \leftarrow \text{LLM}(\mathbf{x}^{(i)} s)$  ... Get next token predictions for each element of the batch

# DP inference

---

**Algorithm 2** DP Inference

---

Vocabulary  $\mathcal{X}$ , set of all strings  $\mathcal{X}^*$ , set of token probability distributions  $\Delta(\mathcal{X})$ .  
For  $a, b \in \mathcal{X}^*$ ,  $ab$  denotes concatenation.

- 1: **Input:** LLM:  $\mathcal{X}^* \rightarrow \Delta(\mathcal{X})$ , private prompts  $\mathbf{x}^{(1)}, \dots, \mathbf{x}^{(n)} \in \mathcal{X}^*$ , response length  $T$ .
  - 2:  $\mathbf{s} \leftarrow \emptyset$
  - 3: **for**  $t = 1$  to  $T$  **do**
  - 4:     **for**  $i = 1$  to  $n$  **do**
  - 5:          $p_t^{(i)} \leftarrow \text{LLM}(\mathbf{x}^{(i)} \mathbf{s})$
  - 6:      $\tilde{x}_t \leftarrow \text{DPTokenSelect}(p_t^{(1)}, \dots, p_t^{(n)})$
  - 7:      $\mathbf{s} \leftarrow \mathbf{s} \tilde{x}_t$
  - 8: **return**  $\mathbf{s}$
-

# DP inference

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**Algorithm 2** DP Inference

---

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  - 5:      $p_t^{(i)} \leftarrow \text{LLM}(\mathbf{x}^{(i)} \mathbf{s})$   $\varepsilon$  paid for this token, accumulate  $T$  times
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$$Z \leftarrow \{\text{logits}(\mathbf{px}) : \mathbf{p} \in S\}$$

$$\bar{\mathbf{z}} \leftarrow \frac{1}{s} \sum_{\mathbf{z} \in Z} \text{clip}_c(\mathbf{z})$$

$$x \sim \text{softmax}(\bar{\mathbf{z}}/\tau)$$

$$\text{clip}_c(\mathbf{z})_i = \max(-c, \min(c, z_i))$$

# Token aggregation in DP inference

Softmax sampling: Token  $i$  sampled w.p.  $\sim \exp(\bar{z}_i/\tau)$

$\varepsilon$ -DP exponential mechanism:  $i$  sampled w.p.  $\sim \exp(\text{score}(i, S) \cdot \varepsilon/2\Delta)$

$$\Delta = \max_i \max_{S, S'} |\text{score}(i, S) - \text{score}(i, S')|$$

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Let  $\text{score}(i, S) = \bar{z}_i := [\frac{1}{s} \sum_{\mathbf{z} \in S} \text{clip}_c(\mathbf{z})]_i$

$$\Delta = c/s$$

$$\exp(\bar{z}_i/\tau) = \exp\left(\frac{\bar{z}_i}{2(c/s)} \cdot 2(c/s) \cdot \frac{1}{\tau}\right)$$

$$= \exp(\text{score}(i, S)/2\Delta \cdot \frac{2c}{s\tau})$$

$\implies 2c/s\tau$ -DP

$$c = 10, \tau = 2, s = 100 \implies \varepsilon = 0.1$$

$$\text{clip}_c(\mathbf{z})_i = \max(-c, \min(c, z_i))$$

# Unified view of methods

Start from a non-private approach to generate synthetic data

DPify an **iterative primitive** used to **extract information from real data**

|                   | <b>DP finetuning</b> | <b>Private evolution</b> | <b>DP inference</b> |
|-------------------|----------------------|--------------------------|---------------------|
| <b>Comparison</b> | Finetuning           | Evolutionary prompting   | Inference           |
| <b>Primitive</b>  | Gradient             | Selection                | Token sampling      |

- Amenability to DP: primitive is an aggregate function with bounded sensitivity
- Privacy guarantee of primitive => privacy guarantee of iterations

# Rough comparison of methods

|                                                | <b>DP finetuning</b>                  | <b>Private evolution</b>               | <b>DP inference</b> |
|------------------------------------------------|---------------------------------------|----------------------------------------|---------------------|
| <b>Recommended when your input size is ...</b> | >10K                                  | <5k                                    | Not recommended     |
| <b>Yield</b>                                   | Infinite                              | <= input data size                     | 1k ~> 25 examples   |
| <b>Access required</b>                         | Weights                               | API                                    | Logits              |
| <b>Training required?</b>                      | Yes                                   | No                                     | No                  |
| <b>Prompt engineering</b>                      | No                                    | Yes                                    | No                  |
| <b>Inference cost</b>                          | 1                                     | Batch size                             | rounds x rewrites   |
| <b>OOD Adaptability</b>                        | High                                  | Low                                    | Medium              |
| <b>Data persistence</b>                        | Entire dataset required for training. | Ephemeral/stays on device (votes only) | One batch at a time |

# Summary of comparison of methods

**DP finetuning** is the workhorse method that delivers the best quality given sufficient data, compute, model access, and engineering effort.

*Since the adoption of DP synthetic data is often quality-bottlenecked, this is likely the option that best fits your needs.*

# Summary of comparison of methods

**DP finetuning** is the workhorse method that delivers the best quality given sufficient data, compute, model access, and engineering effort.

*Since the adoption of DP synthetic data is often quality-bottlenecked, this is likely the option that best fits your needs.*

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# Summary of comparison of methods

**DP finetuning** is the workhorse method that delivers the best quality given sufficient data, compute, model access, and engineering effort.

*Since the adoption of DP synthetic data is often quality-bottlenecked, this is likely the option that best fits your needs.*

**Private evolution** is most useful when the stringent ( $\epsilon < 1$ ) required or small data.

**DP inference** is useful for generating a small amount of examples quickly.

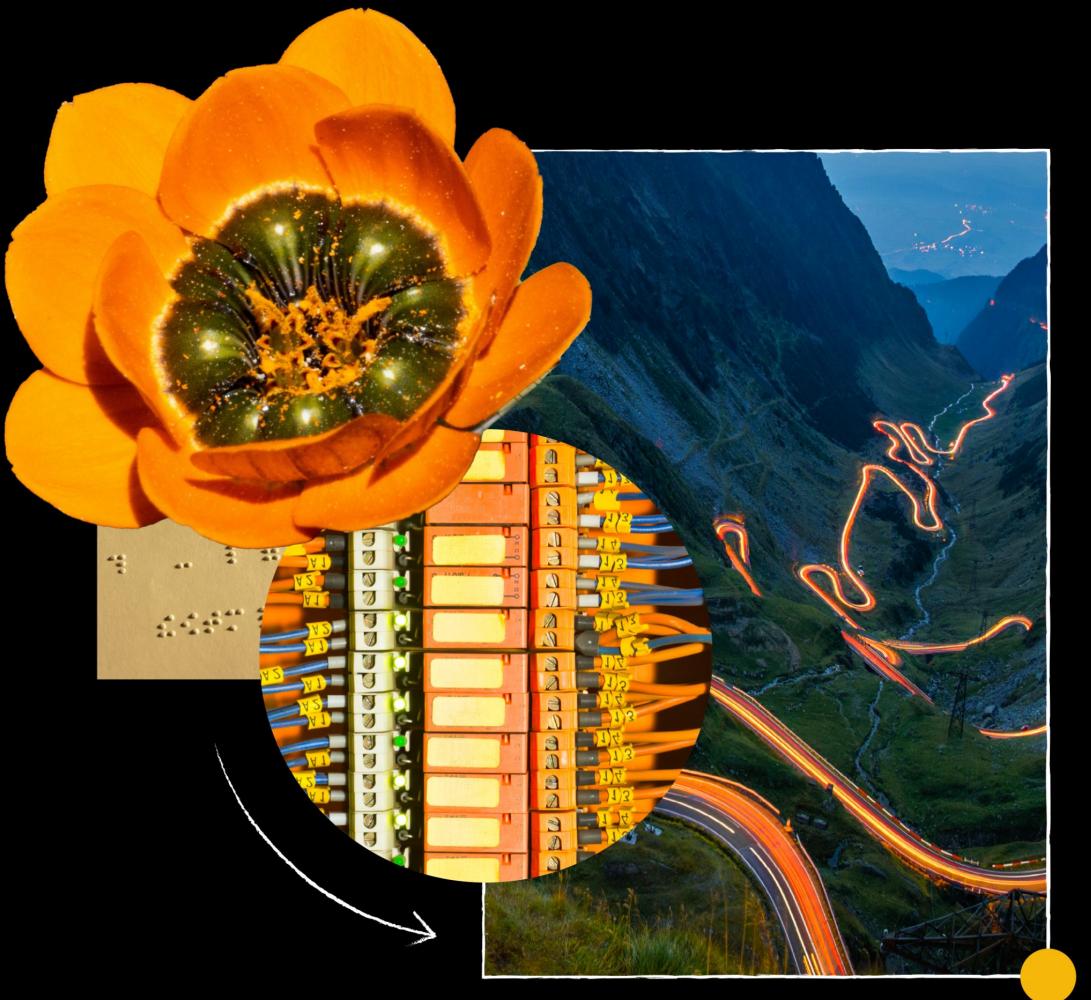
# Utility Metrics

**The best utility metric is downstream task performance, since that is why you are generating synthetic data to begin with.**

There are proxies that can be helpful:

- Heuristics: n-gram statistics, length distribution
- MAUVE score measures distributional similarity
  - Real and synthetic dataset are embedded and clustered together.
  - MAUVE is high when clusters contain a mix of real and synthetic.
  - Correlates with downstream task performance.

# DP synthetic images



# Image data...

- Image data is ubiquitous
- Image data has large body of work on image generation (starting from GANs)
- Image data is very hard to synthesize properly
- DP image synthesis brings it to the next level!
  - Images are high dimensional. Capturing the intricate distribution of natural images requires complex models. DP on more complex models results in more noise
  - There is a "continuity" of images in many directions (not just 1 as in text!)
  - Computation cost of DP is going to be high for large models
    - And models like GANs (adversarial training) are harder to train with DP
  - Utility evaluation difficulties: metrics like FID don't always correlate well with downstream performance



"Unsupervised Representation Learning with Deep Convolutional Generative Adversarial Networks" [Alec Radford, Luke Metz, Soumith Chintala](#), 2015



Diffusion Models Beat GANs on Image Synthesis, Prafulla Dhariwal, Alex Nichol, 2021

# What is appropriate privacy unit for image data

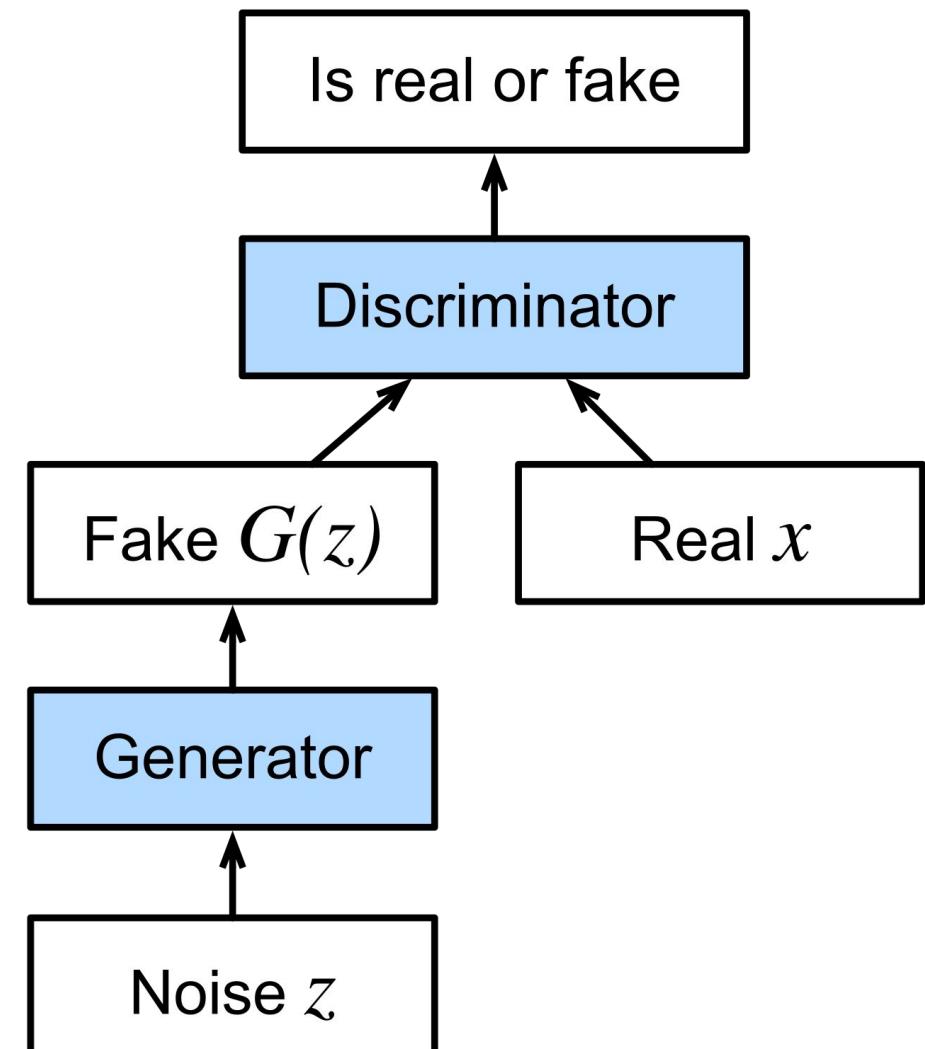
- Most academic works treat each image as a privacy unit (example-level privacy unit)
  - In this setting, DP synthetic data will loosely guarantee that it won't be very different whether a particular image was in your private dataset or not
- In real world applications, it is perhaps not that needs to be done
  - Most of the time you will want at least user-level privacy
    - My synthetic data is not significantly different, whether a particular user contributed their data to my private dataset or not
  - The definition of a "user" is however application dependent
    - User can be a creator of an image
    - Users can be people present on the photos
- Bottom line:
  - For each image define one or more "users" associated with the image
  - Do appropriate user contribution bounding (e.g. 1 image per user)
  - Proceed as if you had a example level privacy unit

# What are the methods for DP image synthesis

- DP training (from scratch) or DP-Finetuning
  - GANs, VAEs
  - Multimodal LLMs, Diffusion
- Inference only/API based methods
  - PATE-style
  - Private evolution
- Data release mechanisms have not been successful so far
  - They attempt to calculate some statistics or intermediate representations of the data, dp-fy that and generate the images from noised representation
  - Examples include DPGEN (Chen et al, 2022b) that was shown to be not proper DP
  - DP-DRE (Wu et al, 2023) which uses publicly pretrained encoder and ICGAN generator. Private data is embedded via an encoder and the distribution is DP-fied via DP density estimator. Samples are then drawn from this distribution and decoded via ICGAN

# DP Training/finetuning for Image generation: GANs

- GAN models
  - First somewhat successful models in image synthesis
  - To obtain DP version of GANs, DP-SGD (and likes) is used to update the discriminator parameters ([DPGAN Differentially Private Generative Adversarial Network](#))
- DP-Training of GANs is hard
  - GANs are notoriously hard to train (diverge, require early stopping)
  - Early DP GANs struggled to generate good images below low resolution like 32x32



Source:  
[https://en.wikipedia.org/wiki/Generative\\_adversarial\\_network#/media/File:Generative\\_adversarial\\_network.svg](https://en.wikipedia.org/wiki/Generative_adversarial_network#/media/File:Generative_adversarial_network.svg)

# DP Training/finetuning for Image generation: GANs

- Several attempts at improving DP-GANs
  - DP-finetuning of publicly pre-trained GANs
    - DP-GAN-MI (Chen et al 2022) uses publicly pre-trained feature extractor
    - DP-DRE (Wu et al) uses publicly trained encoder (and also does DP-SGD on GAN)
  - Alternative losses
    - DP-Sinkhorn (Cao et al 2021) uses optimal transport based loss (Sinkhorn divergence, measuring the distinct between real and synthetic distributions)
    - GS-WGAN (Chen et al 2020) uses alternative loss (Wassertein-1 loss) that generated bounded gradients with norms near 1. This allows to assume clipping norm of 1 and forego hyperparameter search

# DP Training/finetuning for Image generation: Diffusion

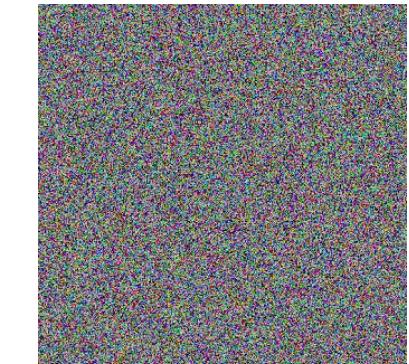
- Diffusion models are state of the art for high fidelity image generation
- Brief intro from ([dp-promise: Differentially Private Diffusion Probabilistic Models for Image Synthesis](#))
  - Forward diffusion process (multi step): gradually adding noise to the data
  - Markov chain  $\{x_0, x_1, \dots, x_T\}$

$$q(\mathbf{x}^{(t)} | \mathbf{x}^{(t-1)}) = \mathcal{N}(\mathbf{x}^{(t)}; \sqrt{1 - \beta_t} \mathbf{x}^{(t-1)}, \beta_t \mathbf{I}), \quad (1) \quad \alpha_t = \prod_{s=1}^t (1 - \beta_s).$$

$$q(\mathbf{x}^{(1)}, \mathbf{x}^{(2)}, \dots, \mathbf{x}^{(T)} | \mathbf{x}^{(0)}) = \prod_{t=1}^T q(\mathbf{x}^{(t)} | \mathbf{x}^{(t-1)}). \quad (2) \quad \mathbf{x}^{(t)} = \sqrt{\alpha_t} \mathbf{x}^{(0)} + \sqrt{1 - \alpha_t} \mathbf{z}, \\ \mathbf{z} \sim \mathcal{N}(\mathbf{0}, \mathbf{I}).$$



- Reverse sampling (multi step, Markov chain): learning to reverse this process via a model, starting from noised images produced in the forward pass (DP-LDMs, Liu et al 2023) to produce the original image
  - Predict the noise distribution from t to t-1, recover  $x_{t-1}$  by removing the noise
  - Model  $Z_\theta$  learns to predict the noise injected from 0 to t => derive the mean of the noise
  - Objective to learn Theta uses samples from iterative forward process



$$\arg \min_{\theta} \mathbb{E}_{t, \mathbf{x}^{(0)}, \mathbf{z}} \left[ \|\mathbf{z} - \mathbf{z}_\theta(\sqrt{\alpha_t} \mathbf{x}^{(0)} + \sqrt{1 - \alpha_t} \mathbf{z}, t)\|_2^2 \right], \quad \hat{\mathbf{x}}^{(t-1)} = \sqrt{\alpha_{t-1}} \frac{\hat{\mathbf{x}}^{(t)} - \sqrt{1 - \alpha_t} \mathbf{z}_\theta(\hat{\mathbf{x}}^{(t)}, t)}{\sqrt{\alpha_t}} + \sqrt{1 - \alpha_{t-1} - \hat{\Sigma}_t^2} \cdot \mathbf{z}_\theta(\hat{\mathbf{x}}^{(t)}, t) + \hat{\Sigma}_t \xi,$$

# DP Training/finetuning for Image generation: Diffusion

- DPDM (Dockhorn et al 2023) - DP SGD applied to Diffusion
- DP-LDM (Liu et al 2024)
  - Prompt or label conditioned
  - Train an encoder-decoder on public data
  - Use the encoder to reduce the dimensionality on private data
  - Train a diffusion model with DP-SGD on lower dimensionality representation
    - Key is reduction in DP-finetunable parameters : authors finetune only attention modules
  - Decode back
  - Able to generate 256x256 images

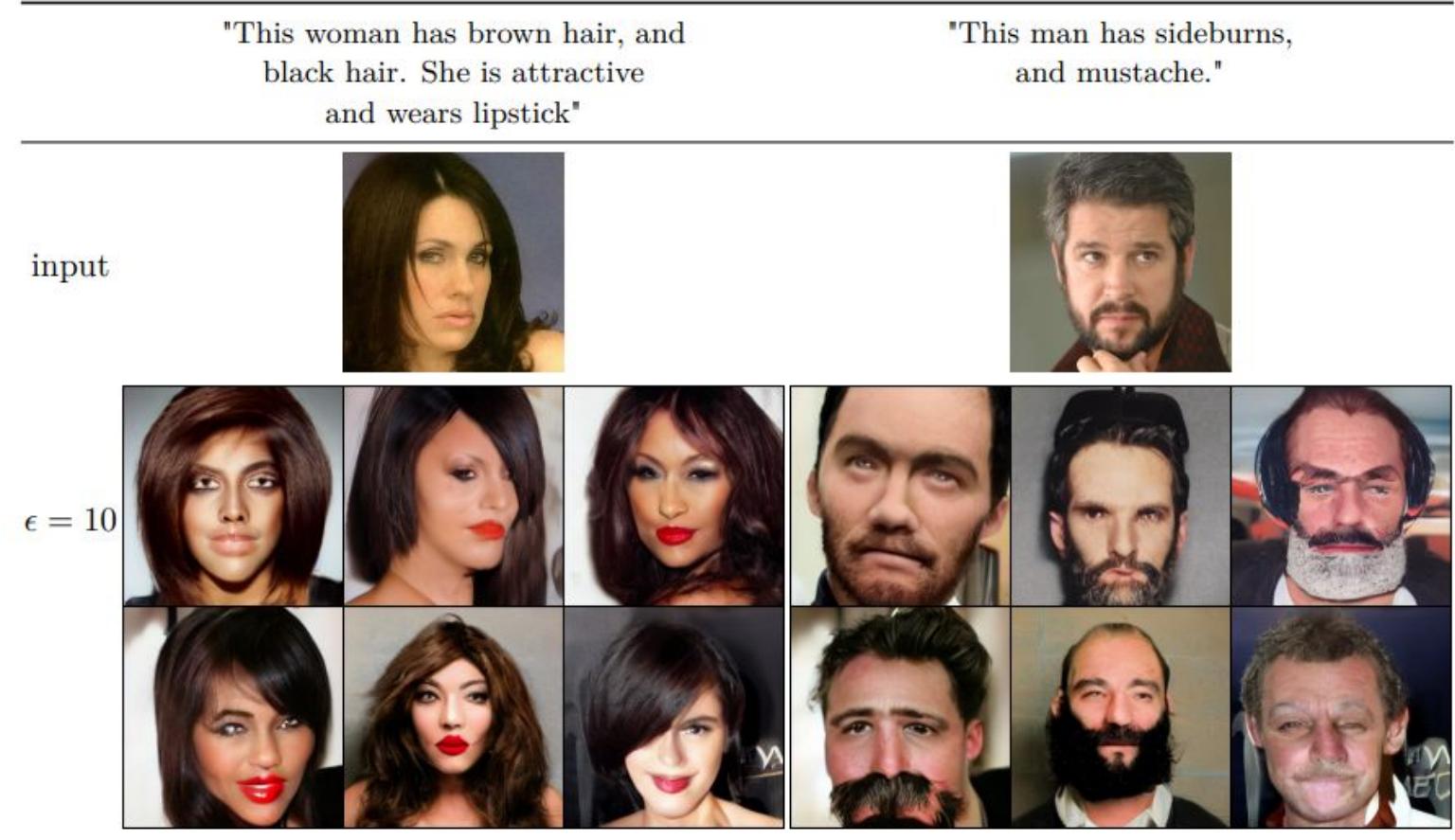


Figure 3: Text-to-image generation of  $256 \times 256$  CelebAHQ with prompts at  $\epsilon = 10$ . FID: 15.6

DP-LDMs: Differentially Private Latent Diffusion Models Michael F. Liu, Saiyue Lyu, Margarita Vinaroz, Mijung Park

# DP Training/finetuning for Image generation: Diffusion

- Common themes are similar to DP-training of LLMs for text
  - Reducing the number of parameters finetuned with DP
    - Some also reduce the input dimensionality (Liu et al 2024 DP-LDM)
  - Using publicly pretrained Diffusion models (e.g. ImageNet pretrained
    - Privimage (Li et al 2024) subselects the public data closest to the private data via clip embeddings for pretraining
    - DPRandP (Tang et al 2023) pretrain on synthetically generated random data
    - Park et al (2024) use small related public dataset, boost it with Diffusion models, and then pretrain on the combined set
  - Leveraging inherent Diffusion noise
    - Wang et al (dp-promise) argues that Diffusion models already add noise during forward process
    - This noise should be used to give DP guarantee (instead of introducing additional noise via DP-SGD)

# DP Training/finetuning for Image generation: Diffusion

- DP-Promise leverages the fact that we already introduce noise during the forward stage of diffusion which contributes to privacy.
- Gradients calculated on noise injected images from Diffusion forward pass are noisy already having similar effect as DP-SGD => we can use less noise during DP-SGD
- Intuition: Earlier interactions of the forward are less private (less noise has been added), as we get to T iterations, it is mostly all noise
- Introduce two stage process for Reverse sampling
  - Phase 1: non dp training (DP from forward noise) [S, T] (sensitivity is by  $2\sqrt{d}$ , d is channel x height x width)
  - Phase 2: DP-Training steps [1, S-1] (sensitivity is bound with clipping)

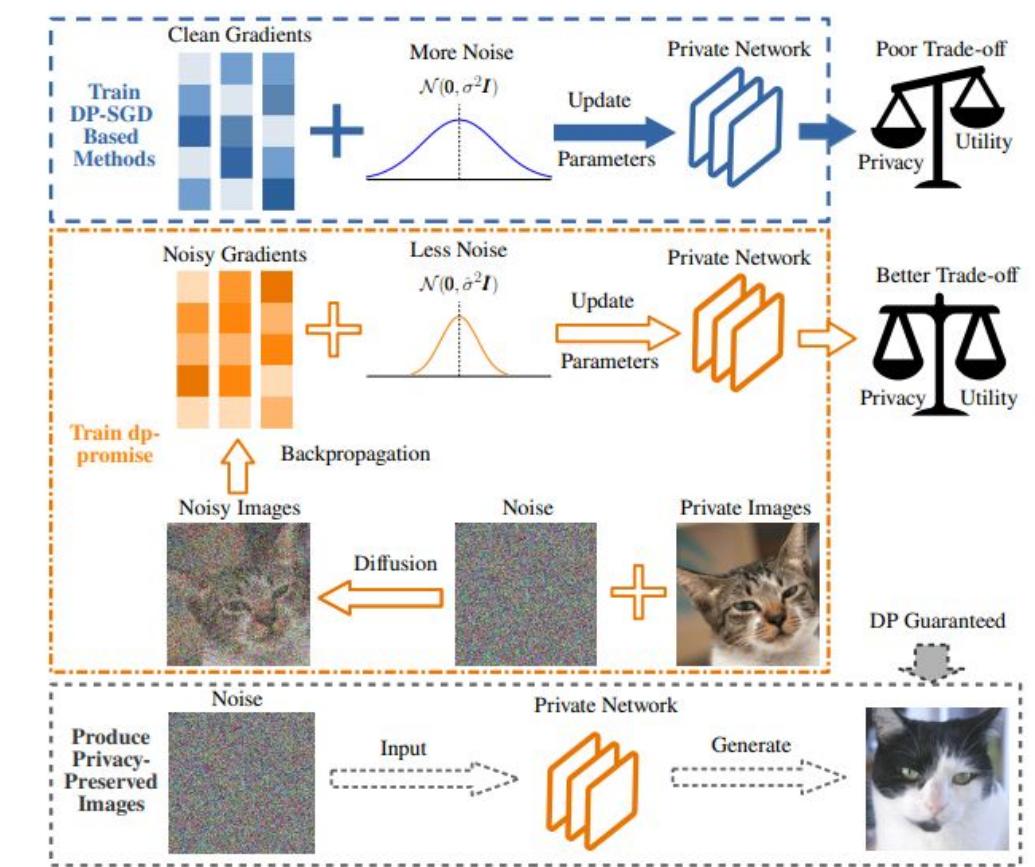


Figure 1: Comparison between dp-promise and other DP-SGD-based approaches for differentially private image synthesis using DMs.

dp-promise: Differentially Private Diffusion Probabilistic Models for Image Synthesis, Wang et al, 2024  
<https://www.usenix.org/system/files/usenixsecurity24-slides-wang-haichen.pdf>

# DP Training/finetuning for Image generation: Diffusion

- DP-Promise

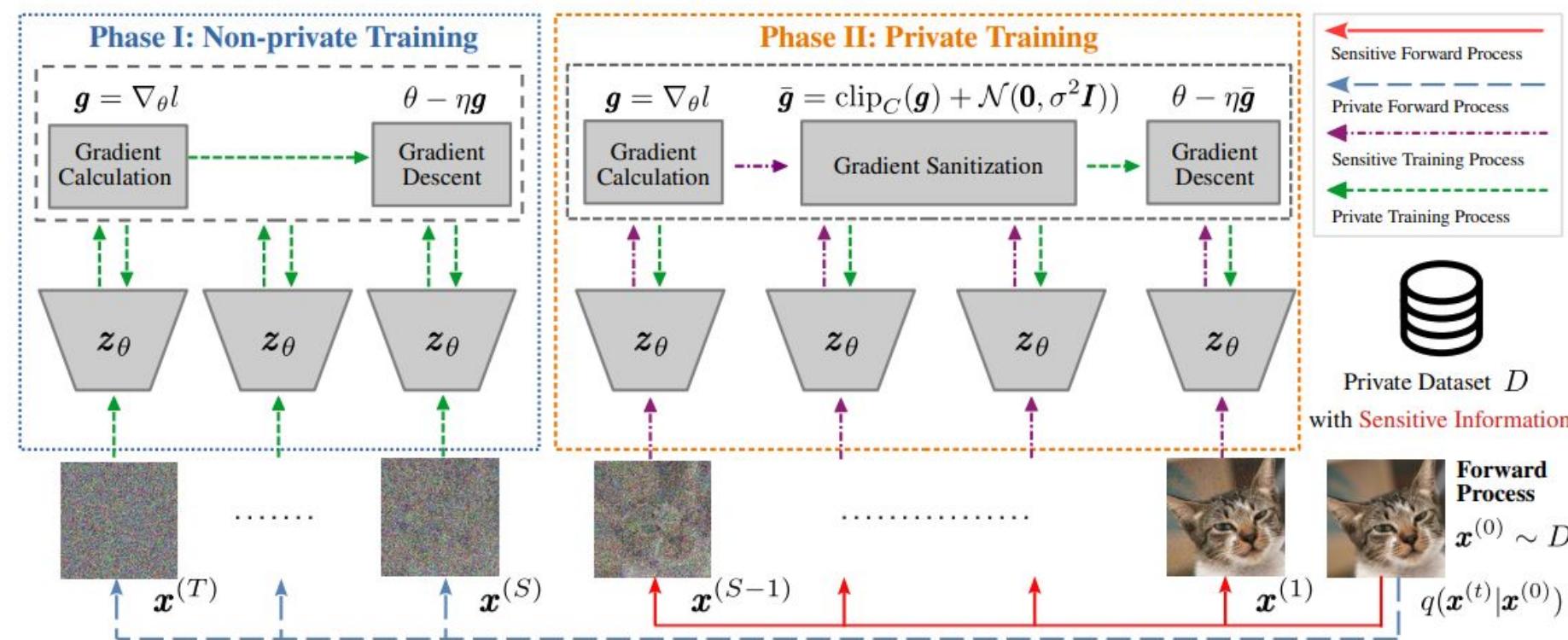


Figure 2: Framework of dp-promise, which aims to provide privacy guarantees to private data during the training of DMs. "Sensitive" means there is a risk of privacy leakage, and "Private" means privacy guarantees exist.

# DP Training/finetuning for Image generation: Diffusion

- DP-Promise



dp-promise: Differentially Private Diffusion Probabilistic Models for Image Synthesis, Wang et al, 2024  
[https://www.usenix.org/system/files/usenixsecurity24\\_slides-wang-haichen.pdf](https://www.usenix.org/system/files/usenixsecurity24_slides-wang-haichen.pdf)

# Inference only methods

- DP-Training/finetuning is computationally expensive AND requires access to model checkpoint weights
- Attempts at introducing DP at the inference only have been made for Image modality
  - PATE style models (Private Aggregations of Teacher Ensembles) (Papernot et al, 2017)
    - Split the training data into a number of disjoint datasets
    - Train a model (or finetune a model) on each of them
    - Introduce the noise for DP guarantee to their aggregated prediction, level of noise depends on the level of agreement between the models
  - PATE-GAN (Yoon et al, 2019)
    - PATE part is applied to discriminator
    - Private data is partitioned
    - A number of discriminator models are trained
    - A student discriminator model is trained using teacher's DP-fied predictions (on some public data or data generated by the generator itself)
    - Generator tries to fool the student, student tries to improve its loss wrt teachers and teachers are trained to improve their loss wrt generator

# Inference only methods

- G-PATE (Long et al, 2019)
  - Don't need the student
  - As long as the gradients of the discriminator are DP, we are good
  - A gradient aggregator gets gradients from the teachers and accumulates them in PATE-style before passing DP gradient to the generator for update
  - Better quality images for small budgets ( $\text{eps} \leq 1$ )
- PATE-TripleGan (Jiang et al , 2024) is probably one of the most modern twists on PATE idea

The bottom line: The quality is still nowhere near the Diffusion style models ( $\text{eps} = 10$ )



PATE-TripleGAN: Privacy-Preserving Image Synthesis with Gaussian Differential Privacy Jiang Zepng, 2024

# Inference only methods

- Private evolution
  - Use inference only access to generative models
  - Needs a good embedding (e.g. CLIP, Inception Network etc)
  - Variation API and Random API (usually already available in models like DALL-E, Stable Diffusion or can be implemented with appropriate prompt engineering (e.g. GPT models). APIs can be conditioned with prompts

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**Algorithm 4** Streamlined Private Evolution for Image (PE, Lin et al. (2023))

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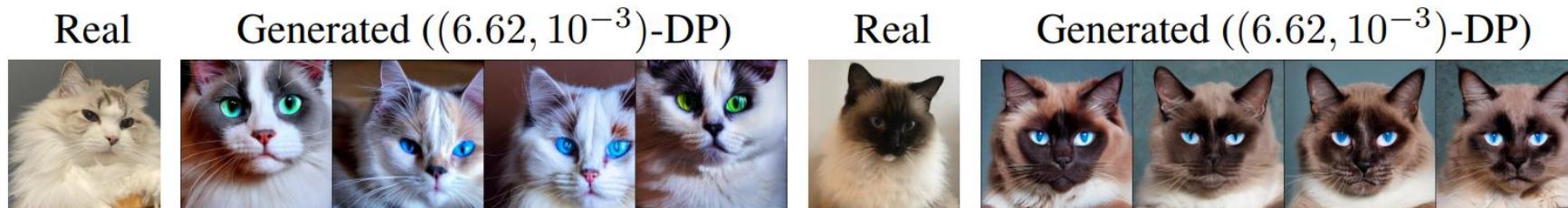
**Input:** Private data  $D$ , image embedding model  $\Phi$  (e.g. CLIP, Inception), target number of synthetic samples  $N$ , evolution rounds  $T$ , population size multiplier  $L$  (number of variations for each synthetic image).

**Output:** Synthetic dataset  $\hat{D}$ .

- 1: Initialize  $\hat{D}_0$  of size  $L \times N$  with Random API.
  - 2: **for**  $t = 0, \dots, T - 1$  **do**
  - 3:    $E_t = \Phi(\hat{D}_t)$  //Embedding calculation for synthetic samples.
  - 4:   Let each  $\Phi(z), z \in D$  vote for the nearest embedding in  $E_t$ .
  - 5:   Privatize the voting results with  $(\varepsilon, \delta)$ -DP to get a DP histogram  $H_t$ .
  - 6:    $\hat{H}_t = H_t / \text{sum}(H_t)$  //Histogram normalization.
  - 7:   Get  $\hat{D}'_t$ : sample  $N$  images with replacement from  $\hat{D}_t$  proportionally to  $\hat{H}_t$ .
  - 8:   **if**  $t < T - 1$  **then**
  - 9:     Get  $\hat{D}_{t+1}$  of size  $L \times N$ : call Variation API to get  $L$  variants for each  $z \in \hat{D}'_t$ .
  - 10:   **else**
  - 11:     **return**  $\hat{D}'_t$ .
-

# Inference only methods

- Private evolution for images
  - Some secret sauce includes "look ahead" distance (distance for computing real to synthetic is calculated via getting variants of synthetic and calculating average distance to those variants)
  - For user level privacy unit - normalize the vote for the samples for the same user to be 1 (in L2 norm)
- Beauty of PE is
  - Computationally cheaper (still needs a lot of inferences, but does not do DP training)
  - Quality will be fantastic (fidelity? Perhaps not)
  - Private data is never used for finetuning (no risks of outputting it back at all)
  - The only method that can work with small amount of private data
  - Cheap from DP perspective (can allow small epsilons)
  - Is a general framework (Foundational models can be replaced with Synthesizers (e.g. SIM-PE paper))
- Downsides
  - Private data needs to be in distribution for the foundational model
  - Heavily depends on the quality of the initial synthetic set, embedding and variate apis



DIFFERENTIALLY PRIVATE SYNTHETIC DATA VIA FOUNDATION MODEL APIs 1: IMAGES Zinan Lin et al, 2024

Figure 8: Real & generated images from Cat Cookie (left) and Cat Doudou (right). More in [App. L](#).

# Metrics for evaluating quality of synthetic Image data

- Utility metrics are pretty much the same for all data modalities
  - Train some downstream model (Machine Learning efficiency)
- Fidelity metrics
  - Inception Score (Khetan & Oh, 2016)
  - Frechet Inception Distance (FID) (Heusel et al, 2017)
  - Mauve (Pillutla et al, 2021) using an appropriate embedding
    - Seeks to trade off type I and type II errors
    - Induces the same ordering as FID and just as FID accounts for both quality and diversity of synthetic data

# Comparison

| Aspect                                               | DP-finetuning<br>(GANs, Diffusion)                                                                     | PATE-GANs                                                                                                                                                                                                      | Private evolution                                                                                                                             |
|------------------------------------------------------|--------------------------------------------------------------------------------------------------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-----------------------------------------------------------------------------------------------------------------------------------------------|
| <b>Amount of input private data</b>                  |                                                                                                        |                                                                                                                                                                                                                |                                                                                                                                               |
| <i>Small input quantity (&lt;5K)</i>                 | Not recommended                                                                                        | Not recommended                                                                                                                                                                                                | Preferred                                                                                                                                     |
| <i>Large input quantity (&gt;10K)</i>                | Preferred                                                                                              | Recommended                                                                                                                                                                                                    | Not recommended                                                                                                                               |
| <b>Reliance on Pre-trained Models / Public Data</b>  |                                                                                                        |                                                                                                                                                                                                                |                                                                                                                                               |
| <i>Can benefit from additional public data</i>       | Yes both for Diffusion and GANs                                                                        | Distilling PATE teachers into students can utilize public data                                                                                                                                                 | No                                                                                                                                            |
| <i>Needs pretrained models</i>                       | Yes for Diffusion, models should be pretrained to improve quality.                                     | No                                                                                                                                                                                                             | Implicit (via Foundation Model API)                                                                                                           |
| <b>Yield</b>                                         |                                                                                                        |                                                                                                                                                                                                                |                                                                                                                                               |
|                                                      | Unlimited number of output examples, although with diminishing returns to downstream task performance. | Unlimited number of output examples, although with diminishing returns to downstream task performance.                                                                                                         | In practice, suitable for outputting synthetic dataset of size $\leq$ size of input private dataset.                                          |
| <b>Model access required</b>                         |                                                                                                        |                                                                                                                                                                                                                |                                                                                                                                               |
|                                                      | Weights                                                                                                | Weights of Generator and Student network and a number of teachers                                                                                                                                              | Generations via API                                                                                                                           |
| <b>Compute resources and engineering effort</b>      |                                                                                                        |                                                                                                                                                                                                                |                                                                                                                                               |
| <i>Training of generative models is required</i>     | Yes, 1                                                                                                 | Yes, training a Generator, A number of teacher discriminators and a distilled student discriminator, in alternating fashion                                                                                    | No                                                                                                                                            |
| <i>Inference cost multiple per synthetic example</i> | 1 (same as regular inference).                                                                         | $\propto$ (number of PATE submodels to aggregate over).                                                                                                                                                        | $\propto$ (number of iterations) $\times$ (number of variants per sample).                                                                    |
| <i>Prompt engineering required</i>                   | No                                                                                                     | No                                                                                                                                                                                                             | Possibly – if using multimodal (text, image) models, potentially need to craft prompts for initial pure synthetic data and variate templates. |
| <i>Time to first example</i>                         | Long (Run finetuning on the entire dataset, then sample)                                               | Extra long (train multiple models on disjoint subsets, infer on all of the models to get pseudo labels, distill into a student model, repeat the process for a number of iterations after Generator's gradient | Medium (Might require prompt engineering + running variate and embedding on the entire private dataset)                                       |

# Comparison....or, just tell me what to do!

- For large enough volume of sensitive data (>XXK datapoints) with enough compute the method that results in highest fidelity and utility of DP synthetic data is almost always DP-Finetuning of pretrained Diffusion models.
- Less computationally expensive methods like PE that don't require finetuning can provide reasonable data when sensitive data is somewhat in distribution for the pretraining data or for situations when were strict privacy guarantees (low  $\epsilon$ ) are needed.
- PE is "safer" and easier to explain but DP finetuning will have much higher fidelity of the data

Final Word: We still got a long way to go in DP synthetic IMAGE land

# DP synthetic tabular data

| Month of July | Purchase              | Price | Derived Utility       | Did I need it | Comment                        |
|---------------|-----------------------|-------|-----------------------|---------------|--------------------------------|
|               | groceries             | 600   | useful, kept me alive | totally       | kept us alive                  |
|               | new clothing for me   | 150   | immense               | not at all    |                                |
|               | new clothing for kids | 50    | useful                | totally       | Avoids CPS knocking on my door |
|               | car lease             | 550   | essential             | totally       |                                |

# Tabular data and privacy unit

- One of the "oldest" type of data organization
- DP synthesis of tabular data has been explored extensively in academia in the last two decades
- Tabular data is the only one type of data that comes with theoretical guarantees on its performance (if marginal-based methods are used)
- Privacy unit
  - Usually row-level (example level). If user level, it is assumed that each user contributed at most 1 row
  - DP synthetic data then is expected to be approximately the same, whether a particular row was in the dataset or not
  - When each user contributes  $x$  rows, one can create an aggregate row or use group privacy (aiming for  $\epsilon/x$  and  $\delta/x$  with per example PU in order to achieve  $(\epsilon, \delta)$  user-level privacy unit

# Tabular data: types of methods

- Workload based methods and generative AI methods
- Workload based
  - Extremely powerful
  - Based on aligning statistical queries (like marginals) on real and synthetic data in DP manner
  - Have been explored in context of **query release**:
    - **Query release** - the task of creating useful synthetic data that gives accurate answers to a number of predefined statistical queries performed on this data, e.g. sums and counts
    - Still end up being useful for training downstream models!
    - Query workload: determines which statistical properties (often low dimensional marginals like counts) are most important to preserve from the original dataset, allow to better allocate privacy budget
    - Goal of query release - error over the finite set of queries is bounded in expectation by alpha
      - P is often infinity in theoretical literature (so worst case query error is bounded), and 1 or 2 in practical literature

$$f : \mathcal{X} \mapsto \{0, 1\}$$

$$\text{Err}_p(\mathbf{A}, D) := \mathbb{E}_{\widehat{D} \sim \mathbf{A}(D)} \left[ \left\| |\mathcal{F}(\widehat{D}) - \mathcal{F}(D)| \right\|_p \right] \leq \alpha,$$

$$\mathcal{F}(D) = (f(D))_{f \in \mathcal{F}}$$

# Tabular data: Workload based

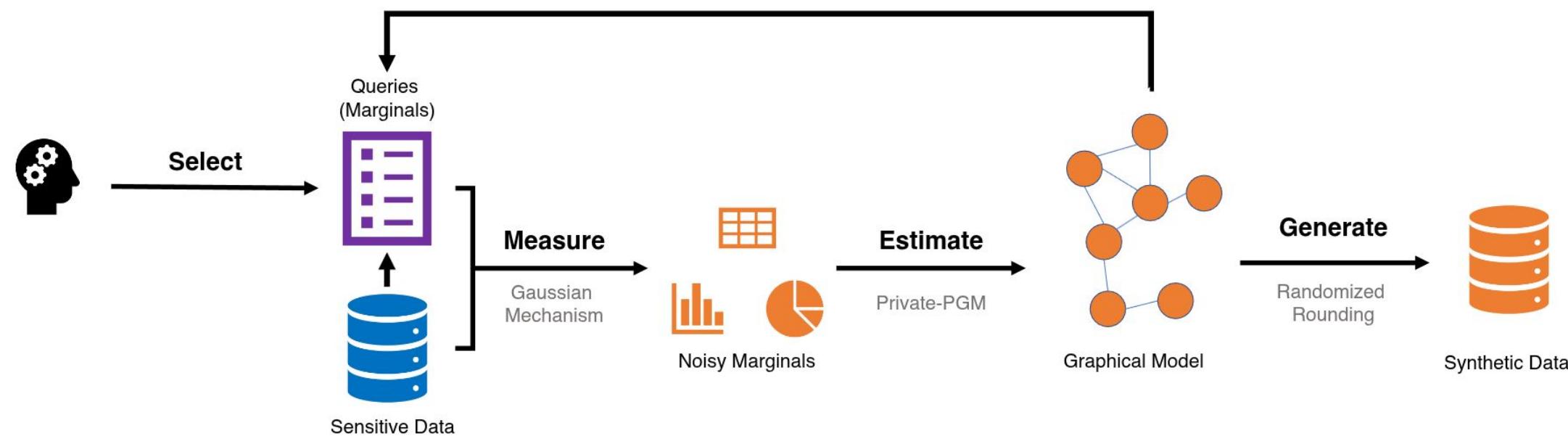
- Work on categorical features with a finite domain of values
  - Need to have all numerical features discretized
- Most of the approaches are working on histogram representation of the dataset (either explicitly materialized or implicit)
- To get back from the histogram to synthetic data, the easiest way is to turn histogram into probability distribution (normalize the counts) and sample the values accordingly to this probability distribution

| Age   | Occupation |
|-------|------------|
| 0-10  | baby       |
| 10-20 | student    |
| 10-20 | nanny      |
| 0-10  | toddler    |
| 10-20 | student    |

| 0-10, baby | 0-10, toddler | 10-20, student | 10-20, nanny |
|------------|---------------|----------------|--------------|
| 1          | 1             | 2              | 1            |

# Tabular data: Workload based

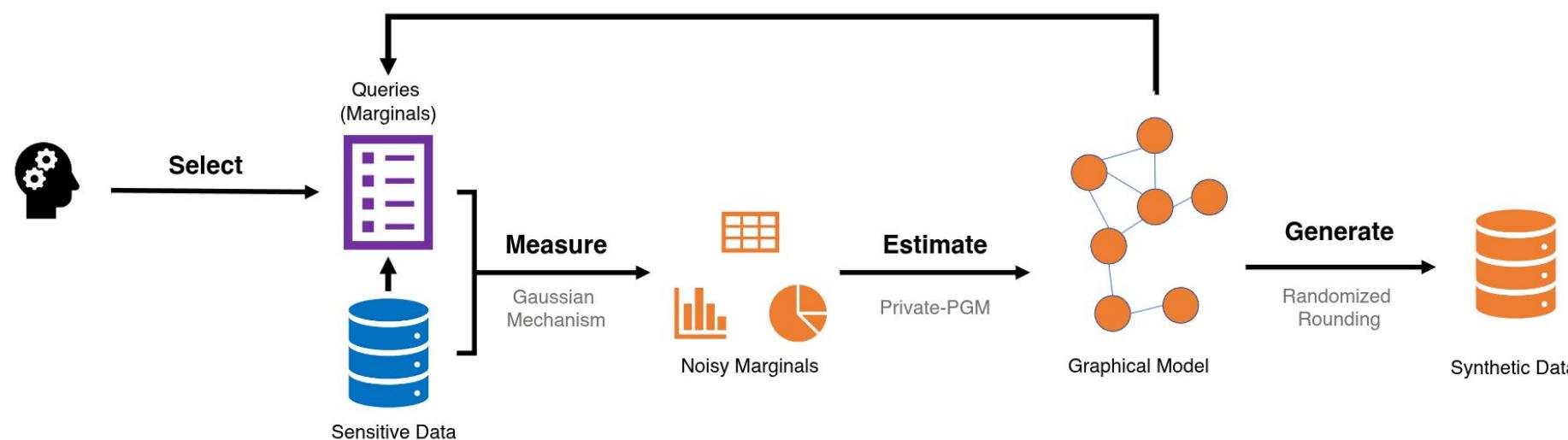
A lot of practical and theoretical algorithms fall into Select-Measure-Estimate Paradigm which decomposes the challenge into a sequence of more tractable problems, decoupling the task of query selection from data



# Tabular data: Workload based

Red steps need to be with DP

- **Select** - chose collection of queries to measure on private data
- **Measure** - queries are executed and carefully calibrated noise is added to ensure DP (often via Gaussian)
- **Estimate** - Most computationally expensive. Takes noise, often inconsistent measurements and builds probability distribution over the entire data domain that best explains them. Often MLE estimation to minimize the L2 distance for noisy measurements. Can be iterative process itself
- **Repeat** - in adaptive algorithms like MWEM, the info about current distribution is used to select next queries, often the ones with the highest error, focusing the privacy budget where it is most needed



# Tabular data: Workload based

- **Select** - information that is never measured can't be preserved
- How to select the queries to measure is the most important choice
  - **Workload awareness**: chose marginals to measure that are most important for user provided workload queries
    - AIM, MWEM+PGM, RAP
    - Agnostic: MST, PrivBayes
  - **Data awarness**: how much the strategy adapts to statistical properties of the data
    - PrivBayes and MST use a portion of the privacy budget to learn a dependency structure from the data,
    - AIM and PMW - more advanced form of data-awareness
  - **Budget-awareness** - intelligent allocation of privacy budget
    - E.g. Larger budget allocated can allow better measure higher-dimensional marginals
    - PrivBayes and PrivSyn are budget-aware (adjust the number and size of marginals based on the total budget)
    - AIM uses annealing procedure adapting per round budget: if the model accuracy does not improve, it increases the budget for subsequent iterations

# Tabular data: Workload based

- **Select** - information that is never measured can't be preserved
- How to select the queries to measure is the most important choice
  - **Computation Awareness**: selection of marginals determines the structure of models that will be appropriate at estimation step
    - MST, PrivMRF, AIM - greedily add marginals only if they don't violate a constraint on the complexity of the resulting graphical model
- AIM (McKenna et al 2022) algorithm demonstrates awareness of all these 4 criteria
  - $W_r$  is workload awareness (weighting by the relevance to the user task)
  - Error  $\|M_r(D) - M_r(p_{t-1})\|$  provides data awareness by measuring the deficiency of the current data-dependent model
  - Noise penalty  $\sqrt{2/\pi} \times \sigma_t \times n$  - budget awareness

$$q_r(D) = w_r \times (\|M_r(D) - M_r(p_{t-1})\|_1 - \sqrt{2/\pi} \times \sigma_t \times n_r)$$

# Tabular data: Workload based

- **Estimate** - given a vector of noisy measurements  $y$ , find  $p$  that best explains these observations,  $p$  is of the size of data universe (all possible histogram bins). Framed as L2 minimization problem
  - Dimensionality of search space is exponential
  - Private-PGM (McKenna et al, 2019) uses probabilistic graphical models
    - Insight: when the measurements are a set of low-dimensional marginals, an optimal solution to the L2 minimization problem is guaranteed to be a distribution that can be represented by a PGM whose structure (i.e., its factors) is determined by the measured marginals.
    - Optimizing over the parameters of this compact graphical model, Private-PGM can achieve exponential savings in computation.
    - Cons: scalability: the computational cost is tied to the graph's treewidth, making it intractable if the measured marginals induce a dense dependency graph.
  - If you relax global consistency (that PGM satisfies), Approx-Private-PGM (APPGM, McKenna et al 2021) or Gradually Update Method (GUM, Zhang et al, 2021) are more scalable
  - RAP (Relaxed Adaptive Projection, Aydore et al, 2021) uses relaxed tabular representation amenable to gradient-based optimization (lacks formal guarantees, non convex)
  - GEM (Generative networks with Exponential Mechanism, Liu et al, 2021) parameterizes the distribution with a neural net (lacks formal guarantees, non convex)
  - Recently: GREM (Gaussian Residuals-to-Marginals, Mullins et al 2024) - proposes to reconstruct marginals not from noisy measurements of other marginals but from noisy measurements of the residuals
- Design tension between rigor and scalability

# Tabular data: Workload based

An example of successful algorithm

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**Algorithm 3** Private Multiplicative Weights Update Method
 

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**Input:** Private dataset:  $D \in \mathcal{X}^n$ , query workload: finite set  $\mathcal{F} \subseteq \{0, 1\}^\mathcal{X}$ , stepsize  $\eta > 0$ .

**Output:** Privatized histogram:  $\hat{h} \in \mathbb{R}_+^\mathcal{X}$ ,  $\|\hat{h}\|_1 = n$ , representing DP synthetic tabular data

```

1:  $h^1 \leftarrow \frac{n}{|\mathcal{X}|} \mathbf{1}$ 
2: for  $t = 1$  to  $T$  do
3:   Select worst performing query  $f_t$  that approximately solves  $\max_{f \in \mathcal{F}} |\langle h^t - h(D), f \rangle|$  (in DP
    manner), together with  $v_t$  private estimate of query error  $\langle h^t - h(D), f_t \rangle$ 
4:   if  $|v_t| \leq \alpha$  then return  $\hat{h} = h^t$ 
5:   else
6:     
$$h^{t+1} = n \frac{(h_x^t \cdot \exp(-\eta \text{sgn}(v_t) f_t(x)))_{x \in \mathcal{X}}}{\sum_{y \in \mathcal{X}} h_y^t \exp(-\eta \text{sgn}(v_t) f_t(y))}$$

7: return  $\hat{h} = \frac{1}{T} \sum_{t=1}^T h^t$ 
```

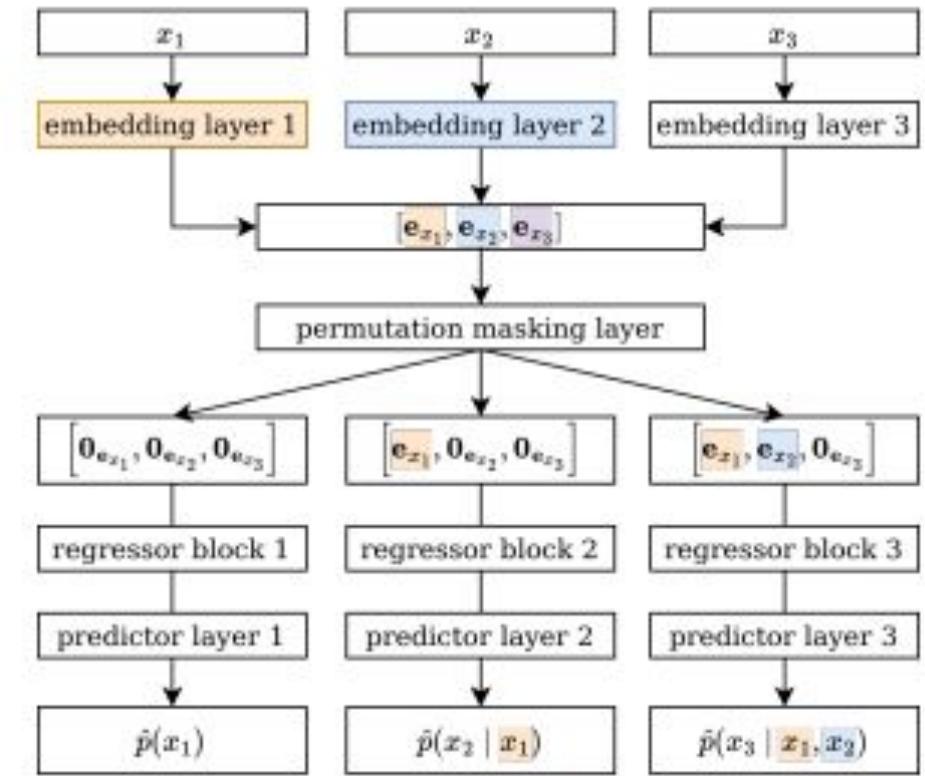
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# Tabular data: Modern generative models based

- Early attempts at using end-to-end generative models looked into GANs and VAE
  - Empirical evaluation (Tao et al 2021) showed that they perform worse than marginal/workload based methods
- Diffusion based: TableDiffusion (Truda et al, 2023)
- Autoregressive models based
  - DP-TBART (Castellon et al, 2023)
    - Custom LLM-like architecture: 3 layer decoder, not pre-trained
    - Custom tokenizer which assigns different tokens to each column's distinct values , so no two columns encodings share the same tokens
    - Each row is encoded as list of tokens (assuming some fixed ordering), column names are not taken into account
    - Trained with DP-SGD
    - During sampling, postprocessing is employed to remove all unallowed tokens for each column
    - AIM (workload based) outperforms it
    - Construct synthetic datasets to demonstrate that the DP-TBART outperforms AIM when there are complex interactions between columns and we need much higher order marginals

# Tabular data: Modern generative models based

- Autoregressive models
  - TabularARGN (Tiwald et al 2025)
    - Don't use transformers to model joint distribution
    - Propose a multi tower model with each tower dedicated to each column
    - Before the towers, dedicated embedding for each column
      - Embeddings are combined (with some permutation) and forwarded to towers
    - Each tower only sees features on which it conditions (eg 3rd is conditioned on the first 2)
    - Towers are standard FFN with RELU and dropout
    - Each tower has softmax head, CE loss. Total loss is sum of the losses from all towers
    - DP-Training



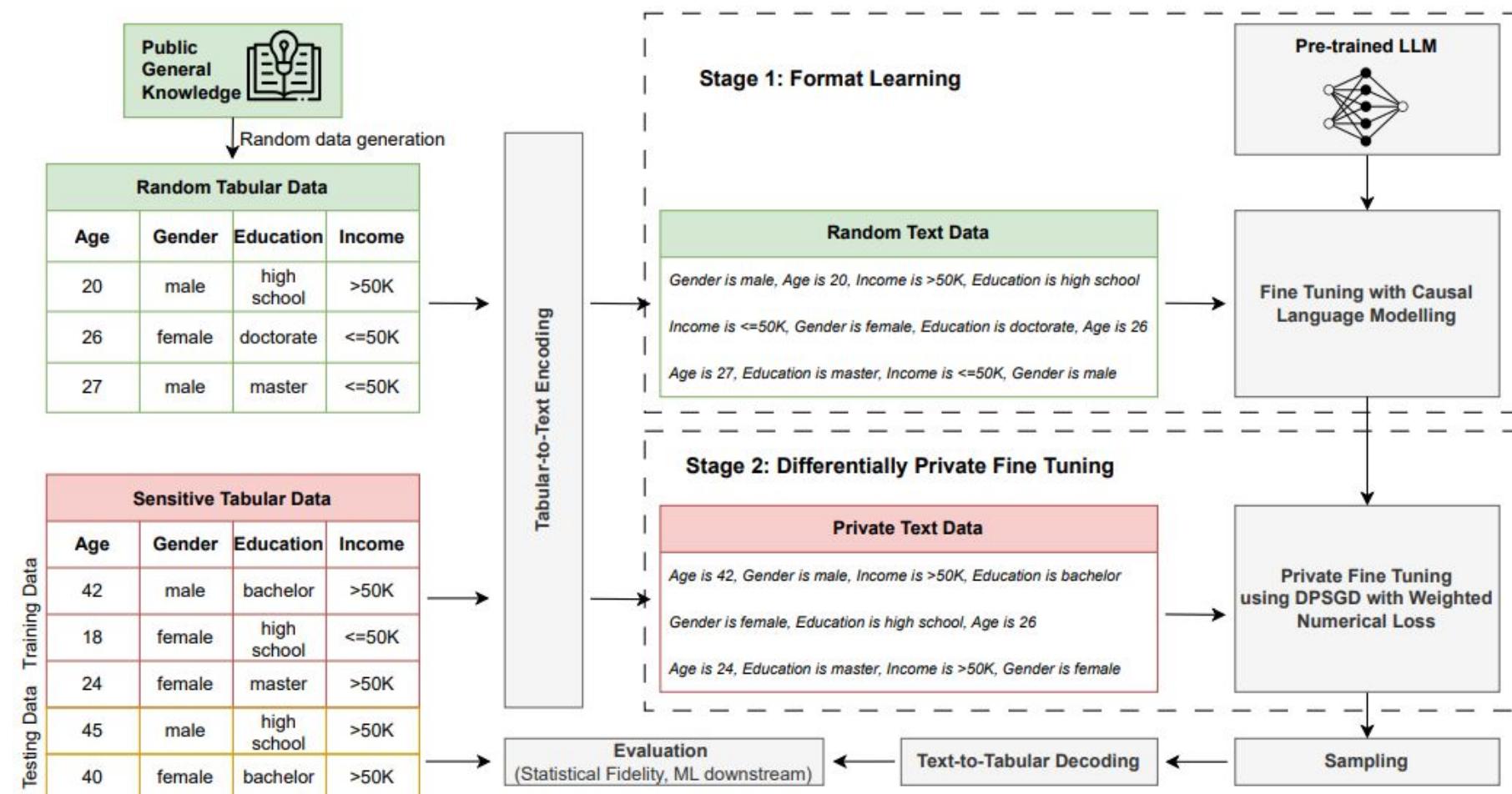
TabularARGN: A Flexible and Efficient Auto-Regressive Framework for Generating High-Fidelity Synthetic Data, Tiwald et al, 2025

# Tabular data: Modern generative models based

- Pretrained LLM based
- Motivation
  - Marginal/workload based methods need preprocessing (outlier removal, discretization, normalization, smoothing etc)
  - They don't take column names into account
  - Histogram based representation eliminates language connection that even simple LLMs can capture (e.g. in Adult dataset age, marital status and education have clear connection)
    - This knowledge can be discovered *with enough data* in histograms but comes for free from pre-trained models
- First successful **non DP** model is GReaT (Borisov et al, 2023)
  - Textual encoding of rows: "Bachelors Education, Adult male, income <50k "
  - Order of columns is permuted to allow conditional sampling later
  - LLM finetuned on textual encodings

# Tabular data: Modern generative models based

- DP-LLMTGen - DP implementation of GReaT idea is by Tran and Xiong (2024)
  - Direct DP training of GReat was unsuccessful
  - Two stage: learn the "format compliance" (column names and values) and private data modelling
  - Lora finetuning and DP Lora for two stages respectively
  - Loss is replaced with Weighted CE and Numerical Understanding loss
    - WCE upweights private tokens and downweights formatting tokens (is, comma etc)
    - NUL penalizes the square loss between predicted numerical and actual numerical value
- Impressive results (comparable with RAP++) but didn't compare with winning workload based methods like AIM



Differentially Private Tabular Data  
Synthesis using Large Language  
Models, Tran and Xiong, 2024

# Tabular data: Modern generative models based

- Concurrently Afonja et al (2025) came up with similar two stage method
  - For the first stage, they show that even using some public data encoding (that does not use the same column names and have different categorical values but conforms to the same encoding scheme) works sufficiently well
  - Advocate for not shuffling the columns when encoding, it makes DP training harder
  - Use only a weighted token loss (no NUL)
    - Based on their ablations, WCE is beneficial only when public data was used for Stage 1 and less needed when random date using the real column names and values was used
  - They compare with MST and AIM, and while their method demonstrates good performance on most metrics, underperforming on certain fidelity metrics especially for large dimensional datasets
    - AIM (workload based) still significantly outperforms

# Tabular data: evaluating synthetic data

- Plenty of fidelity metrics
  - Statistical fidelity - average of total variation distances of joint distributions (1-5 way marginals) between synthetic and real data (Aydore et al, 2021)
  - Pairwise attribute distribution similarity - measures the similarity of all two way marginals by averaging histogram intersections with numerical attributes discretized into bins (Afonja et al, 2025)
  - Pairwise correlation similarity - estimates how well the synthetic data preserves pairwise column correlation
  - Kolmogorov-Smirnov test for numerical attributes and Chi-square test for categorical columns (Castellon et al, 2021)
  - Distributional metrics like MMD and alpha-Precision

# Tabular data: just tell me what to do

- We are encouraging a comprehensive evaluation for all creators of new DP tabular methods, comparing with winning marginal based methods as a strong baseline (e.g. AIM)
- Pragmatically speaking, you are still better off using marginal based methods like MWEM+PGM or AIM if you don't expect extremely high degree interaction between the columns
  - Marginal based methods are exponential in higher order marginals
- There is a potential for LLM based methods to outperform marginal based methods
  - Small data regimes where histogram based methods won't be able to discover connections that LLMs already know based on column names and values
- **Many extremely successful models in non DP settings have not yet been tried in DP (TabPFNGen, Ma et al 2024)**

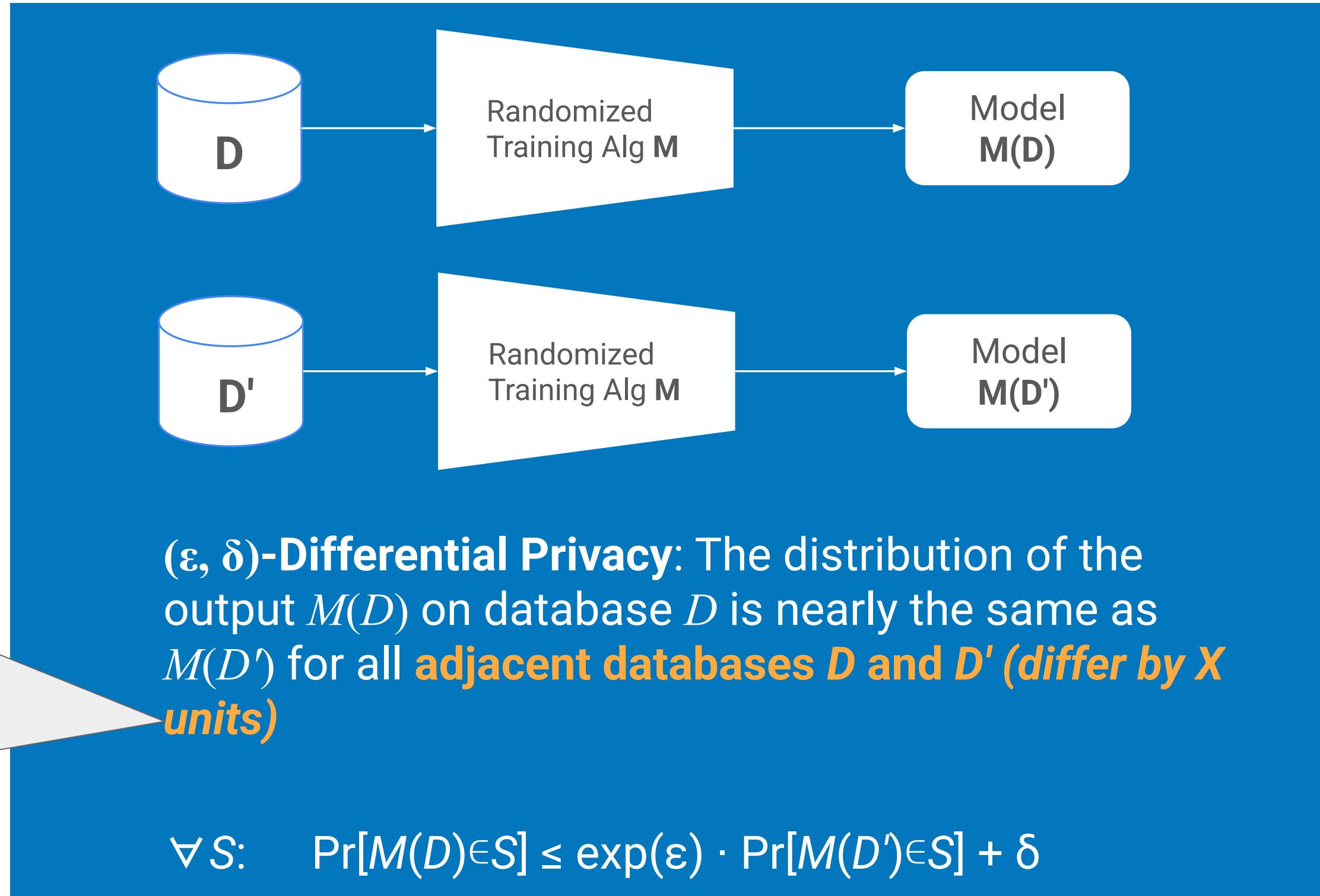
# Practical Privacy Considerations

# Dataset adjacency

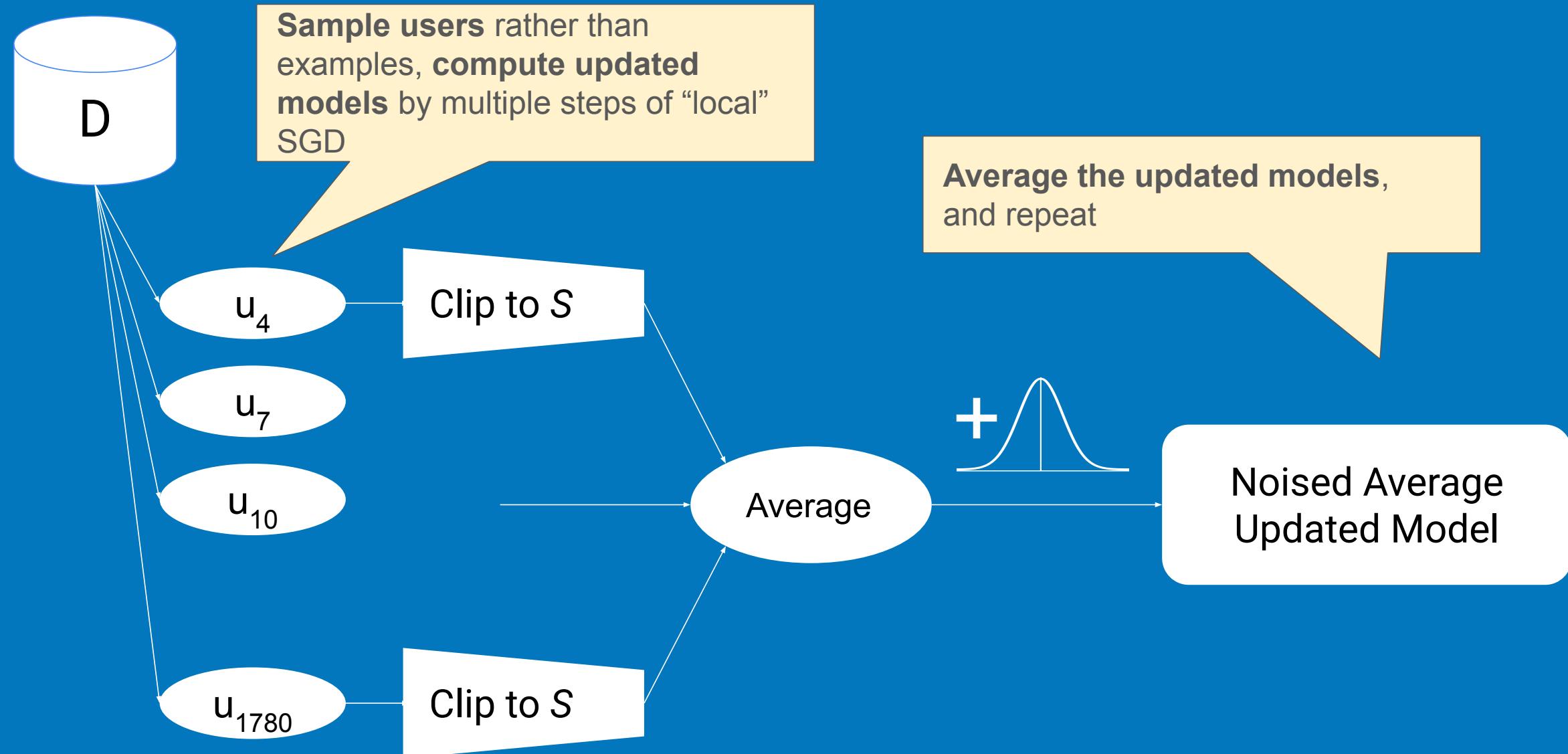
Controls the **unit of privacy**

**Example-level:**  $D$  &  $D'$  differ by a **single row**

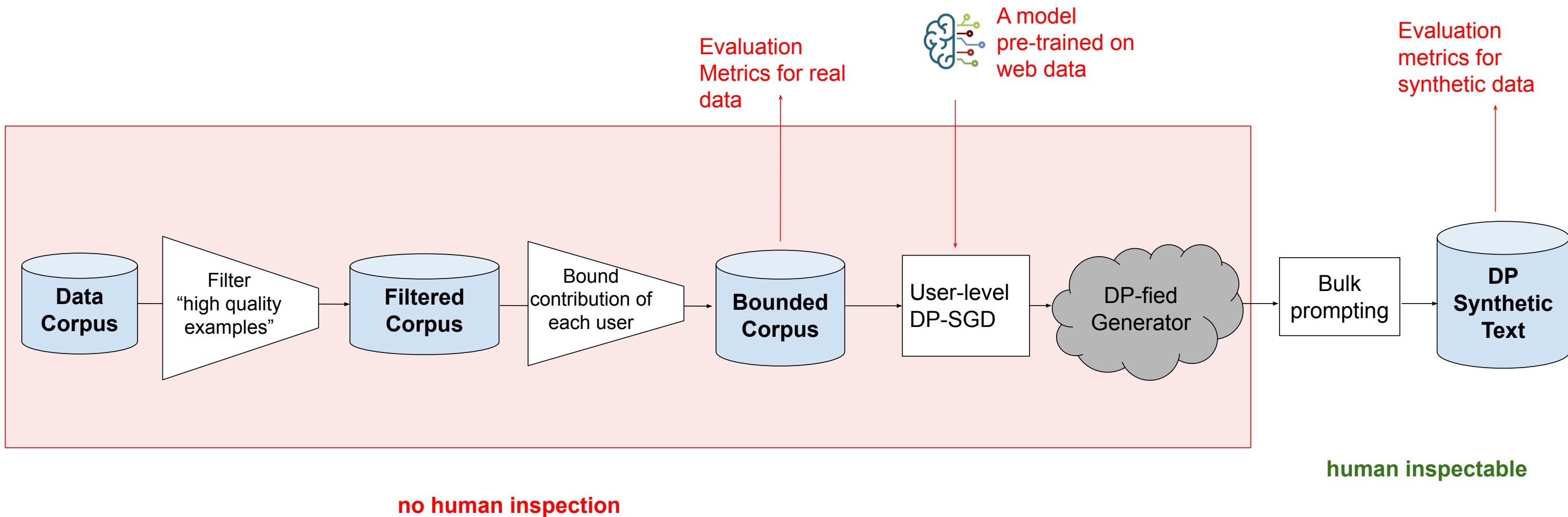
**User-level:**  $D$  &  $D'$  differ by all the rows belonging to a **single user**



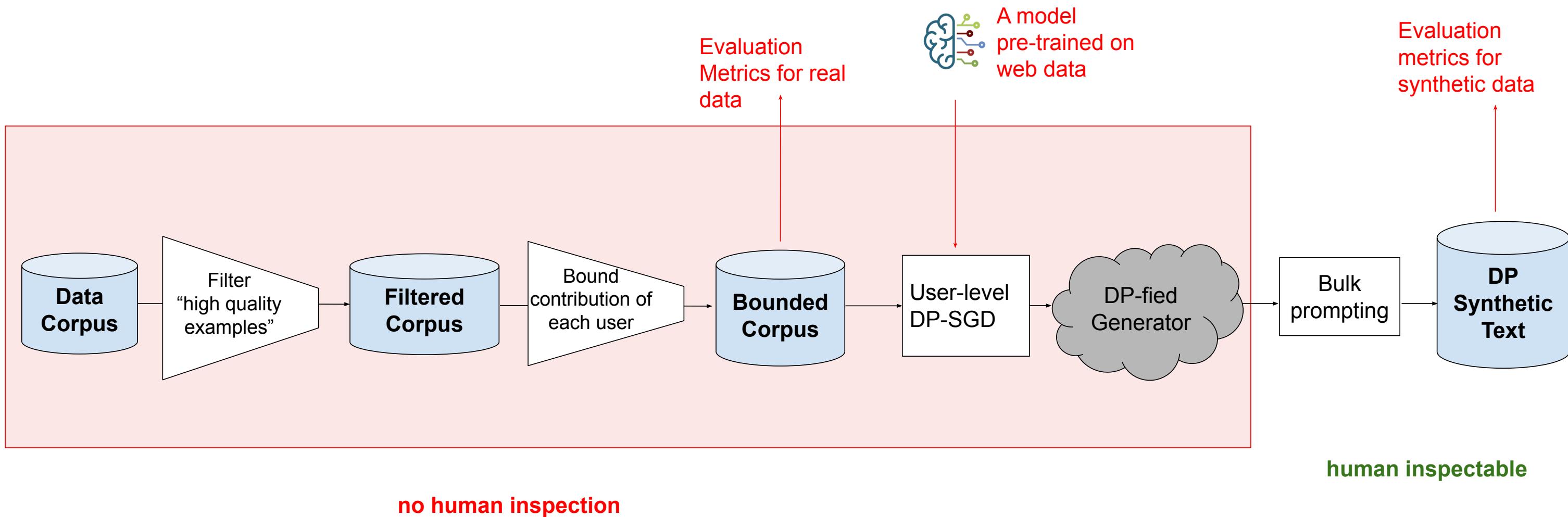
# User-level DP-SGD via user sampling



# DP fine-tuning for synthetic data generation



# DP fine-tuning for synthetic data generation



*Is the generated data safe to use?*

# Why not just train with user-level DP?

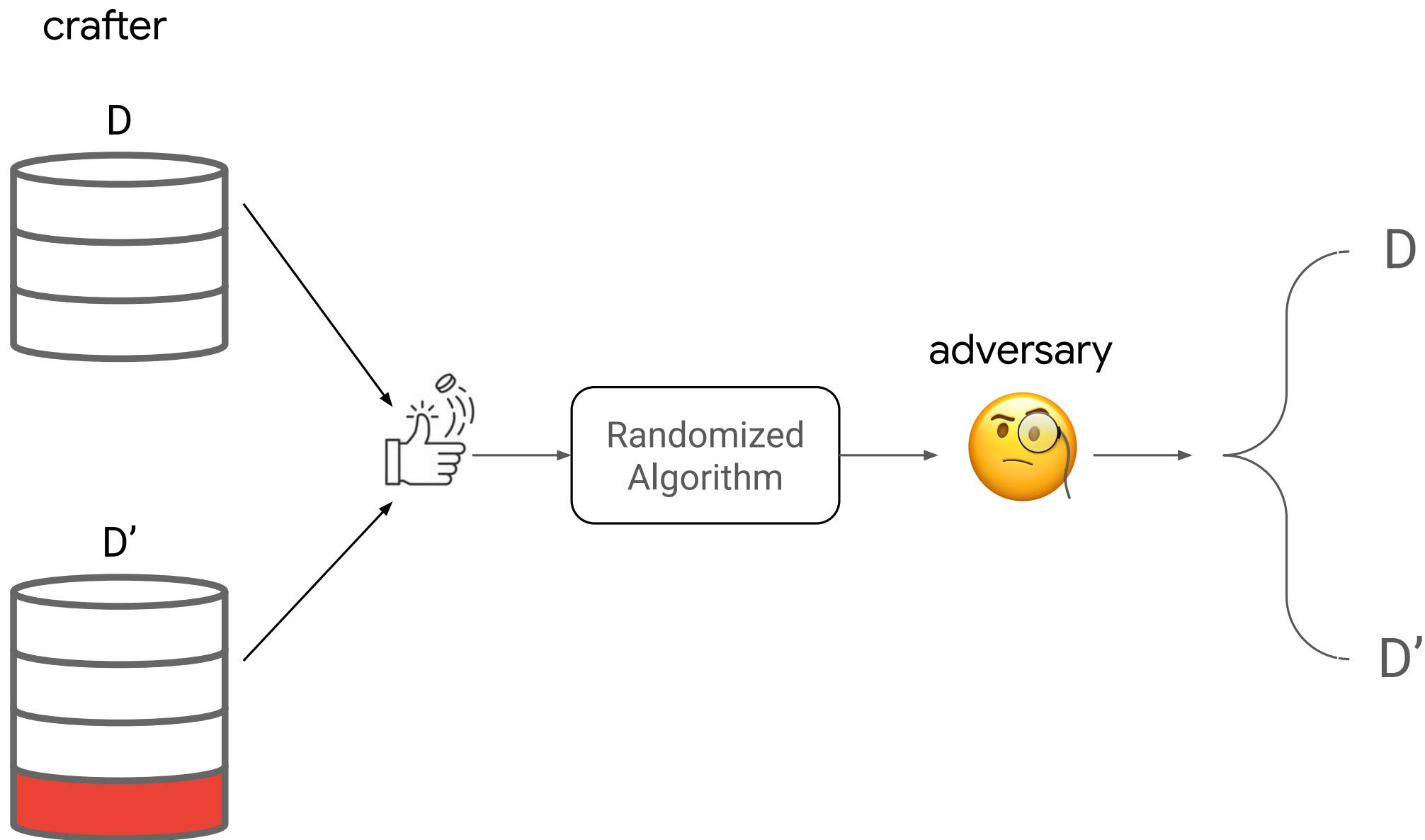
An analytical DP guarantee may overstate the practical risks of releasing a model.

Analytical guarantee quantifies defense against...

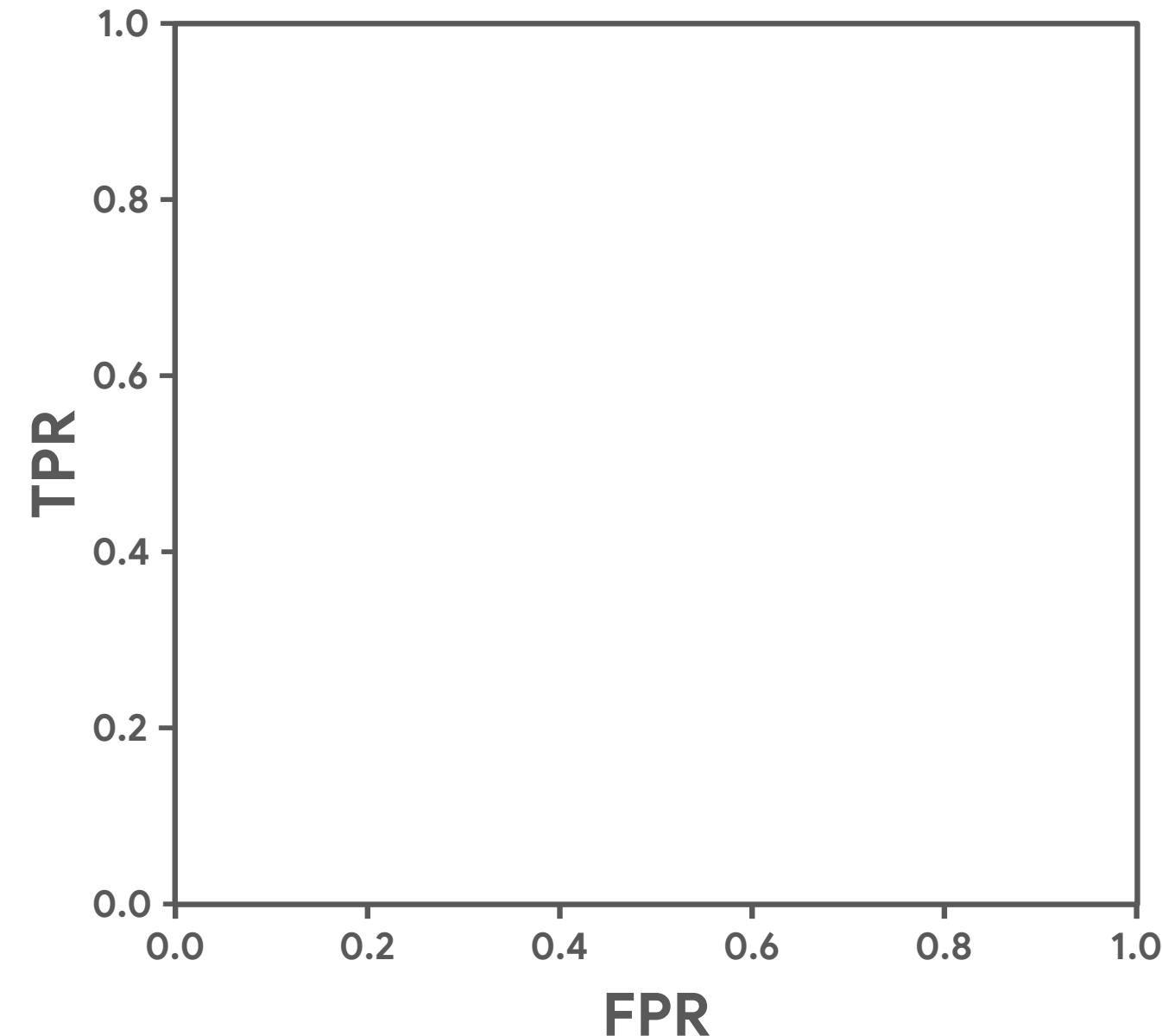
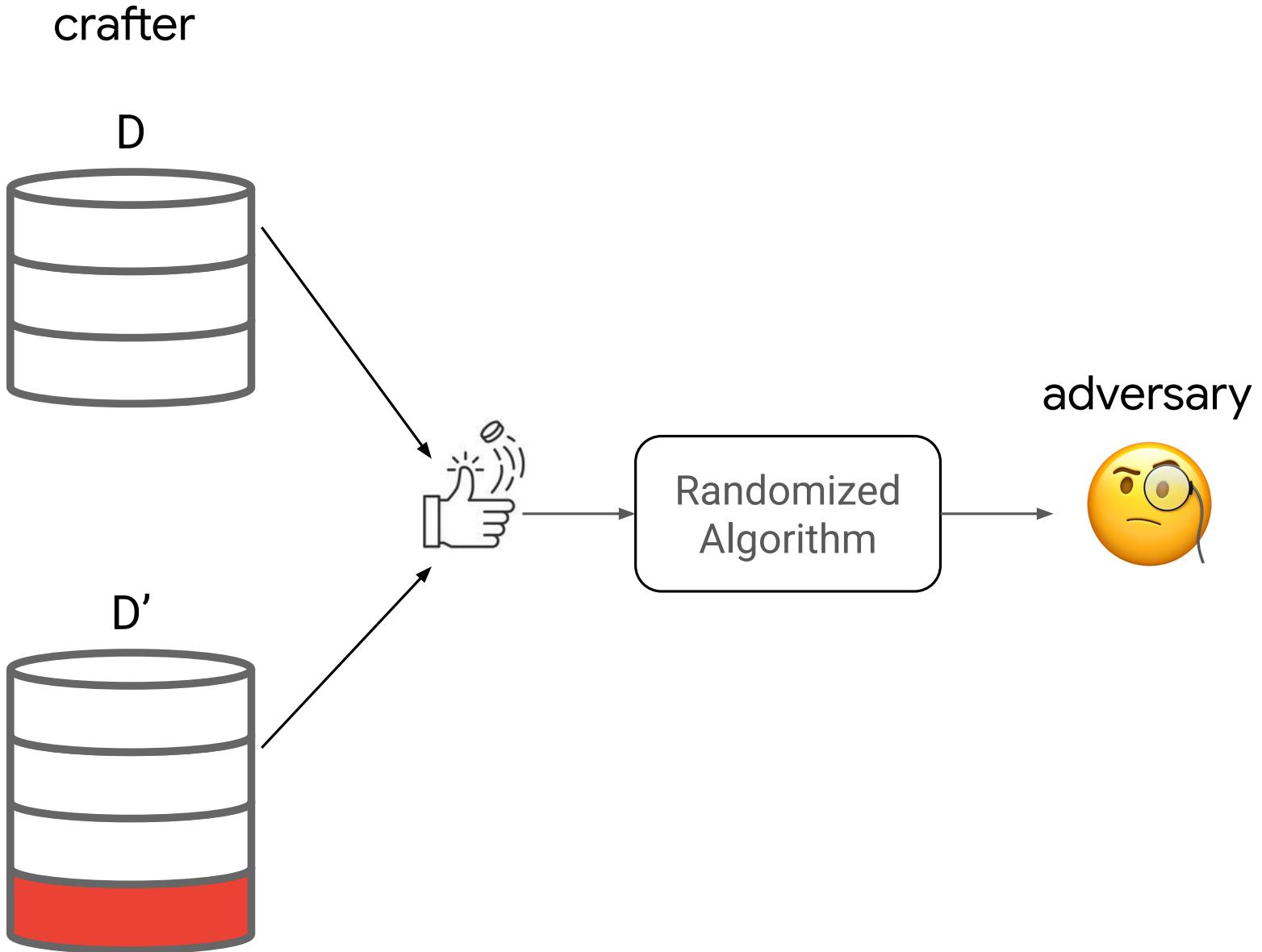
- the “strongest” attack (even if computationally infeasible)
- on the “worst-case” user (even if such user does not exist in practice)
- given full “white-box” information: access to all model training checkpoints
- with potential “lossy” steps in the analysis leading to pessimistic estimates.

**Most achievable DP  $\epsilon$  values in ML applications are often high**

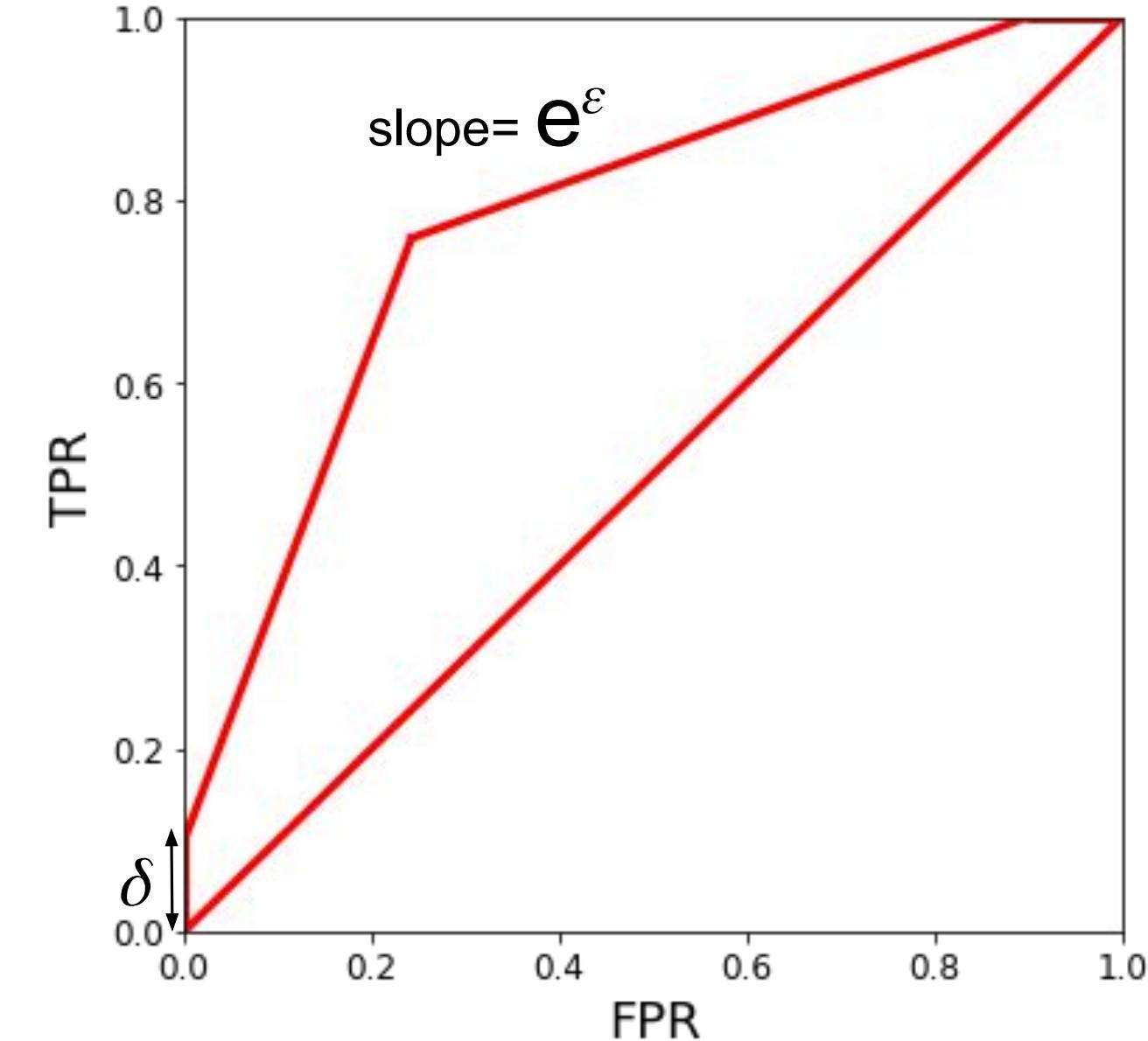
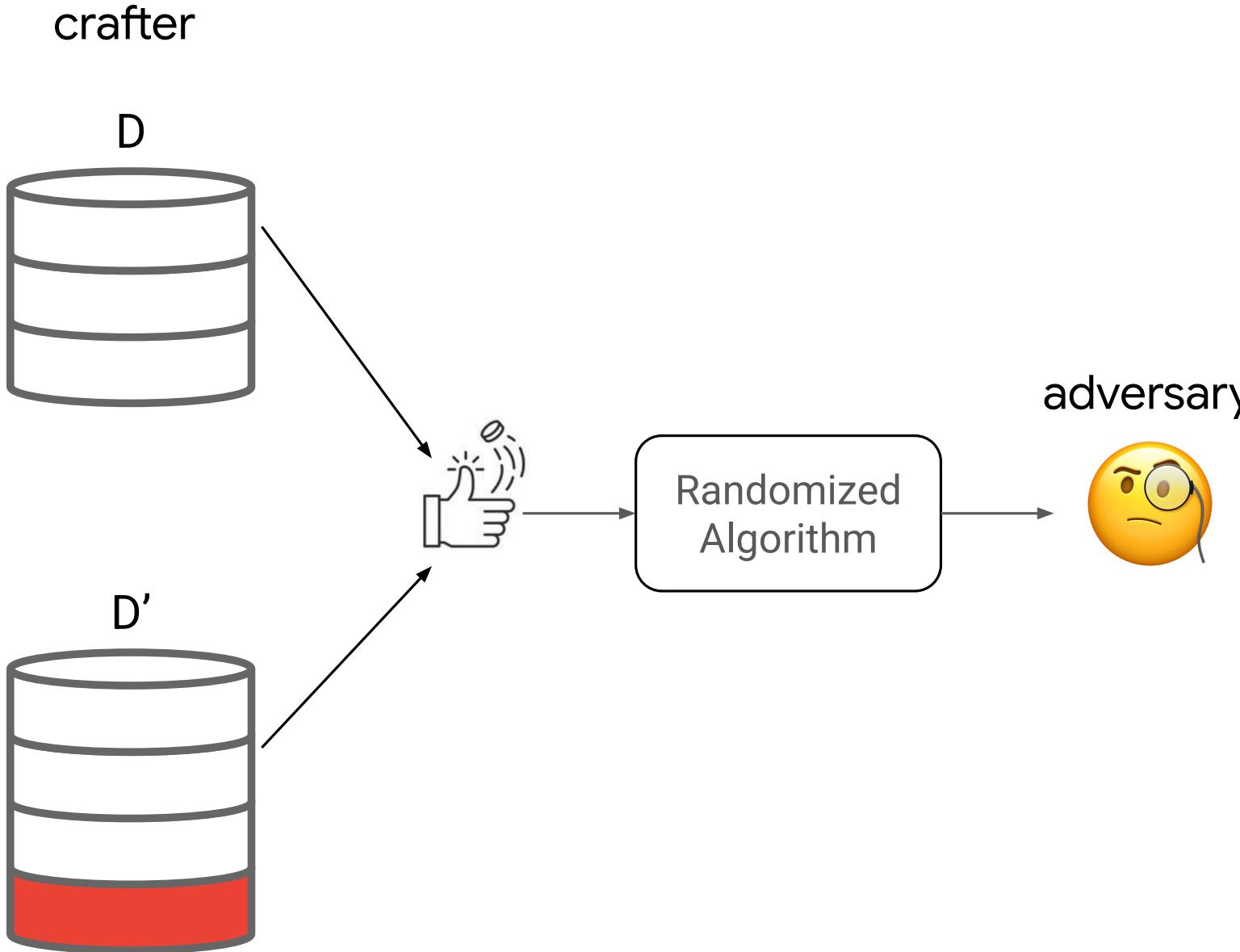
# Differential Privacy



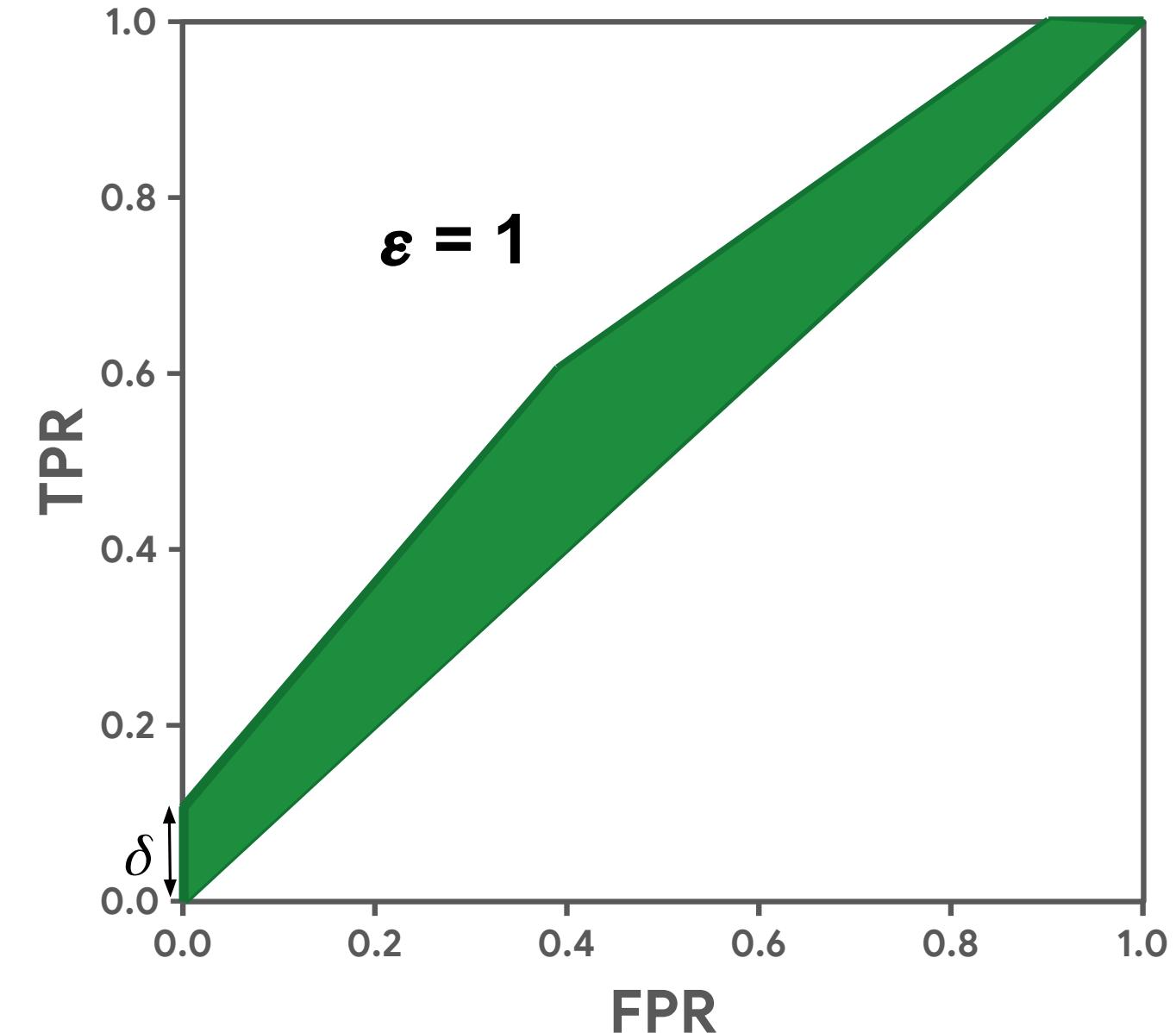
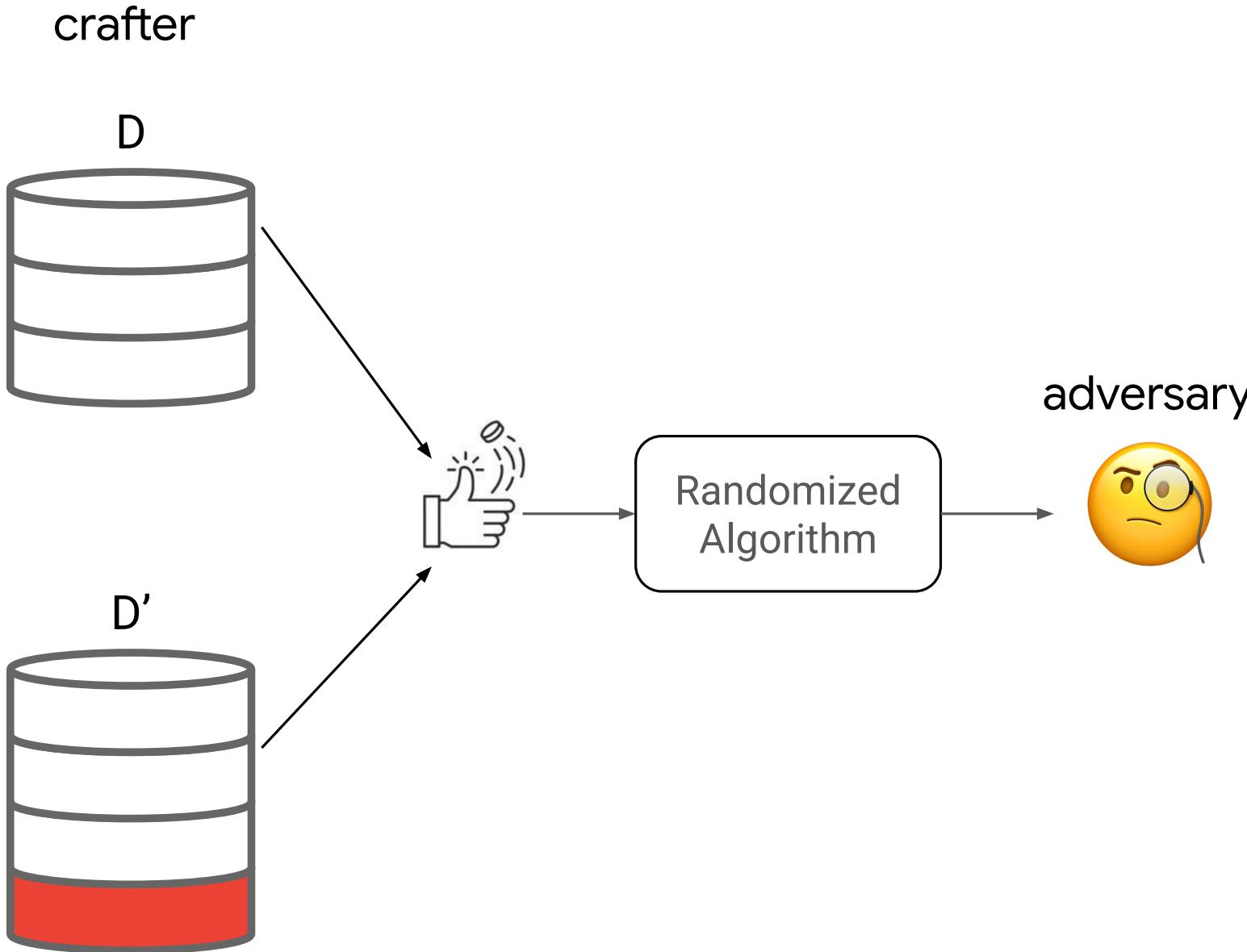
# Differential Privacy



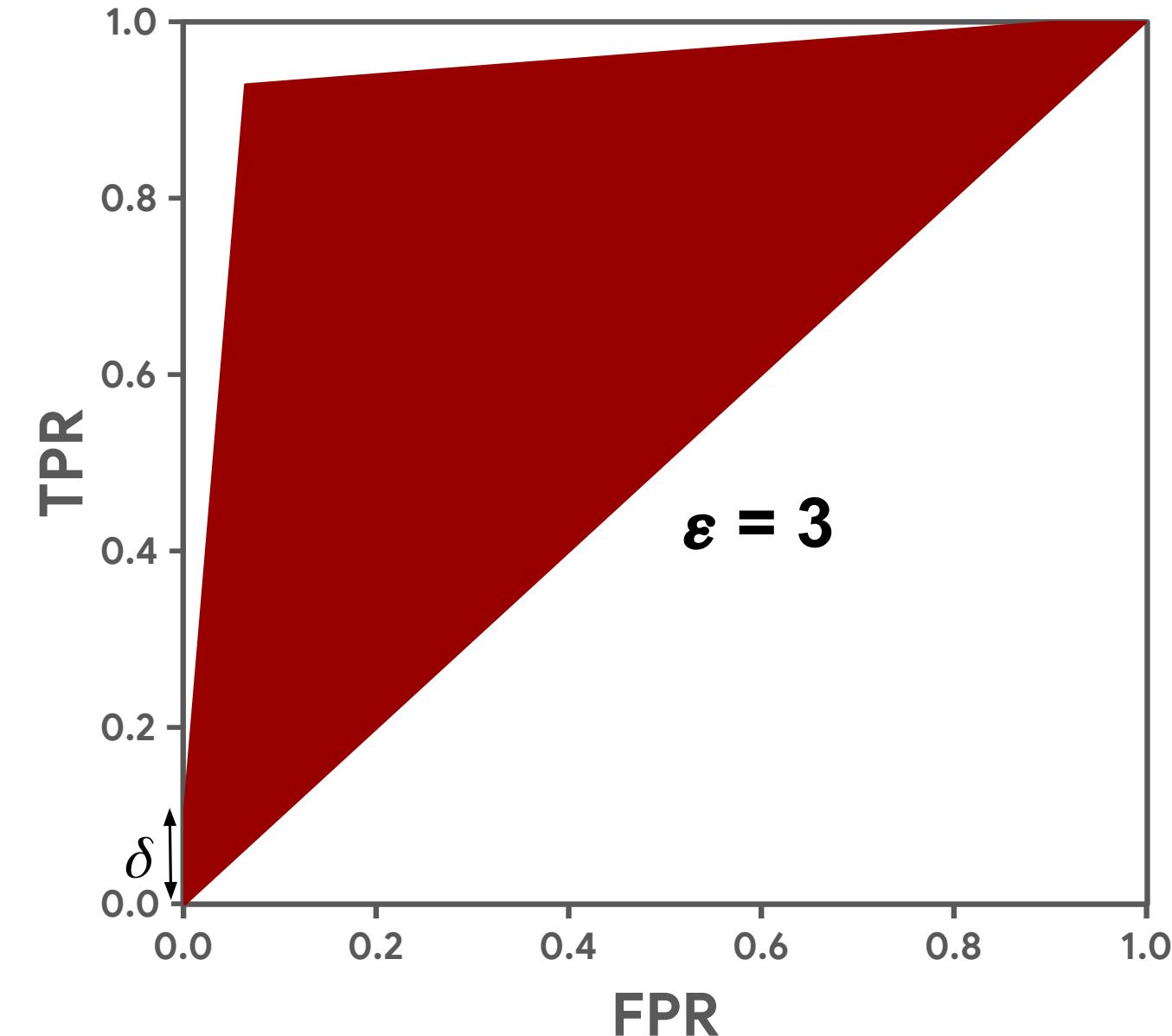
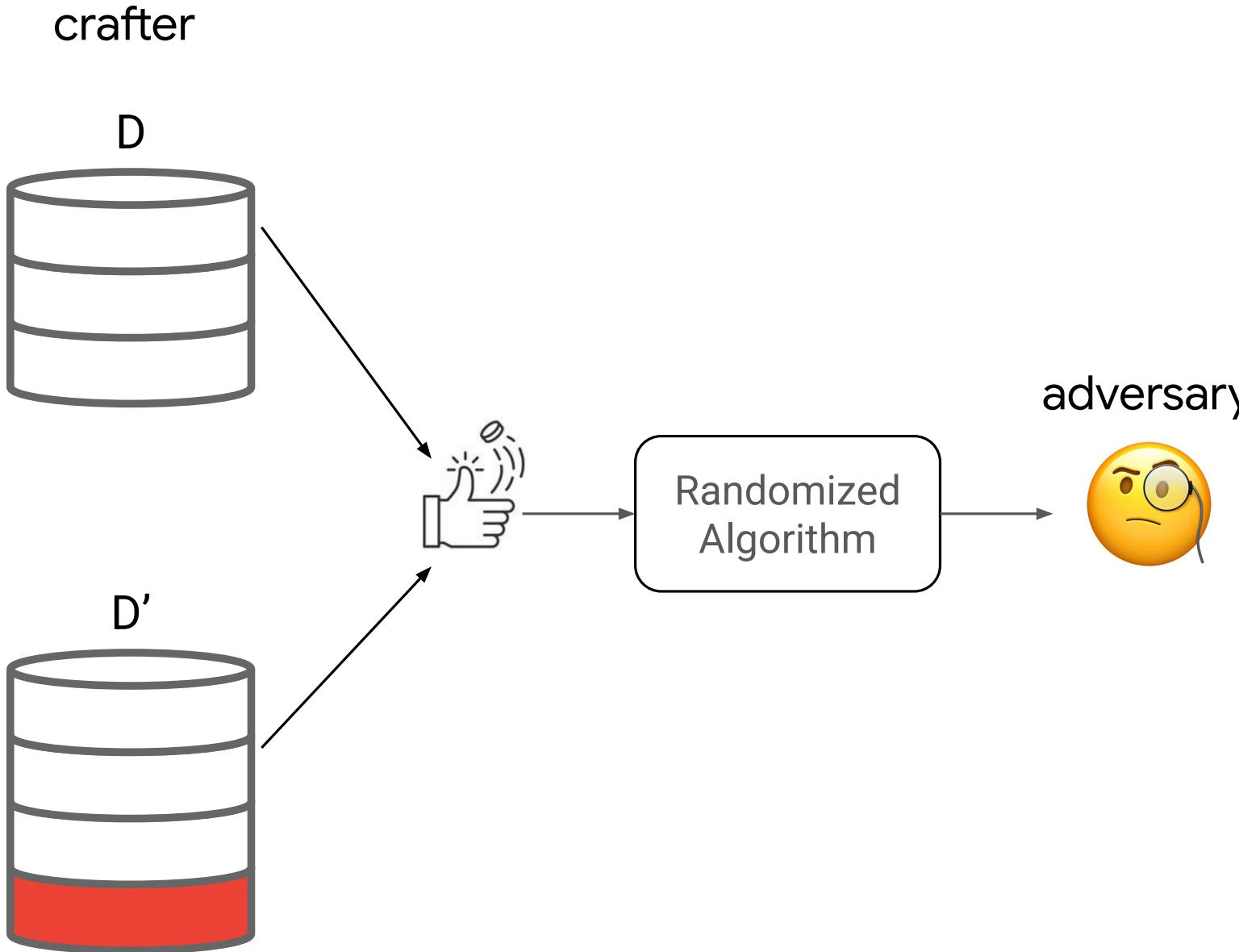
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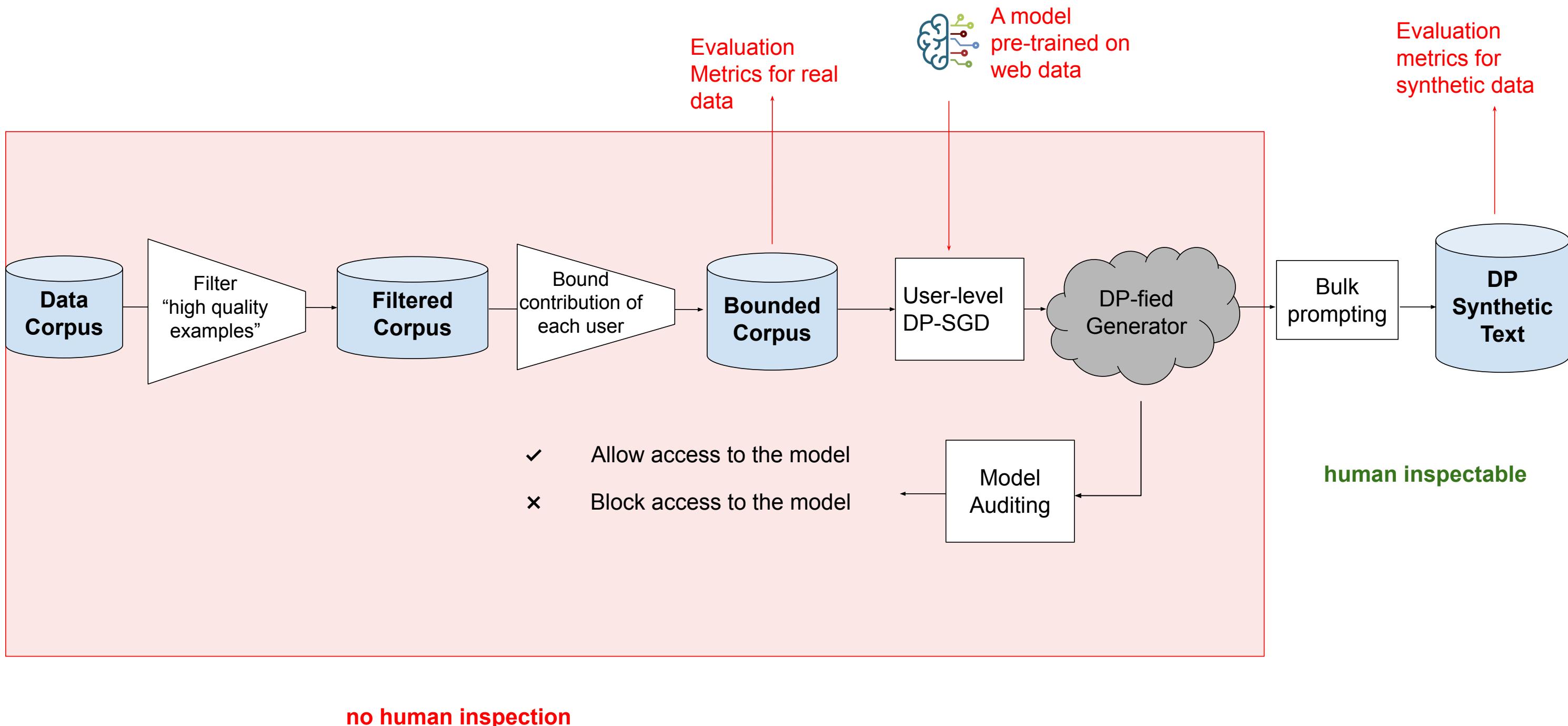
# Differential Privacy



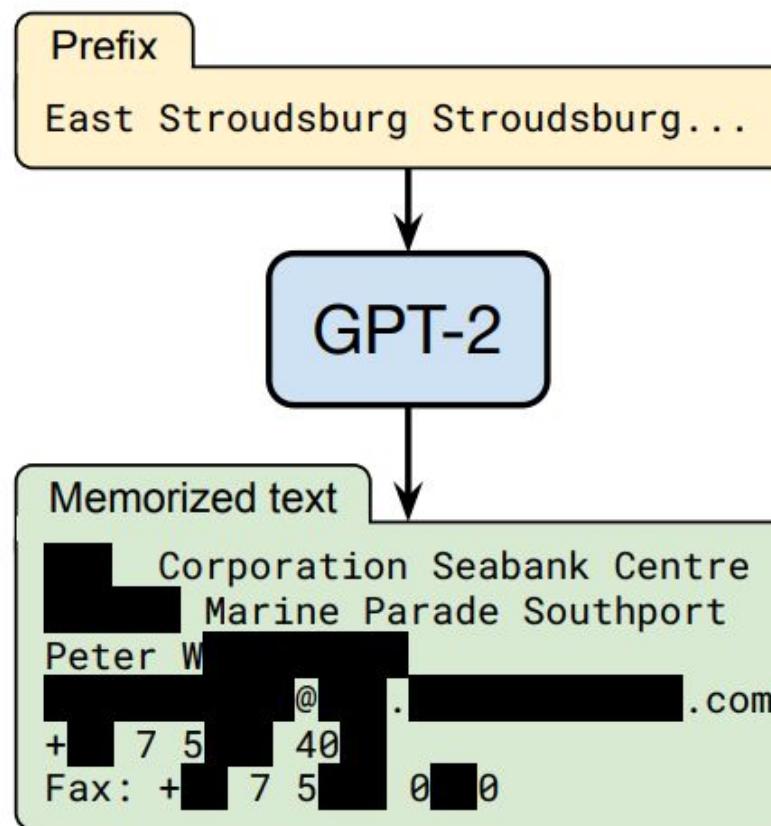
# Differential Privacy



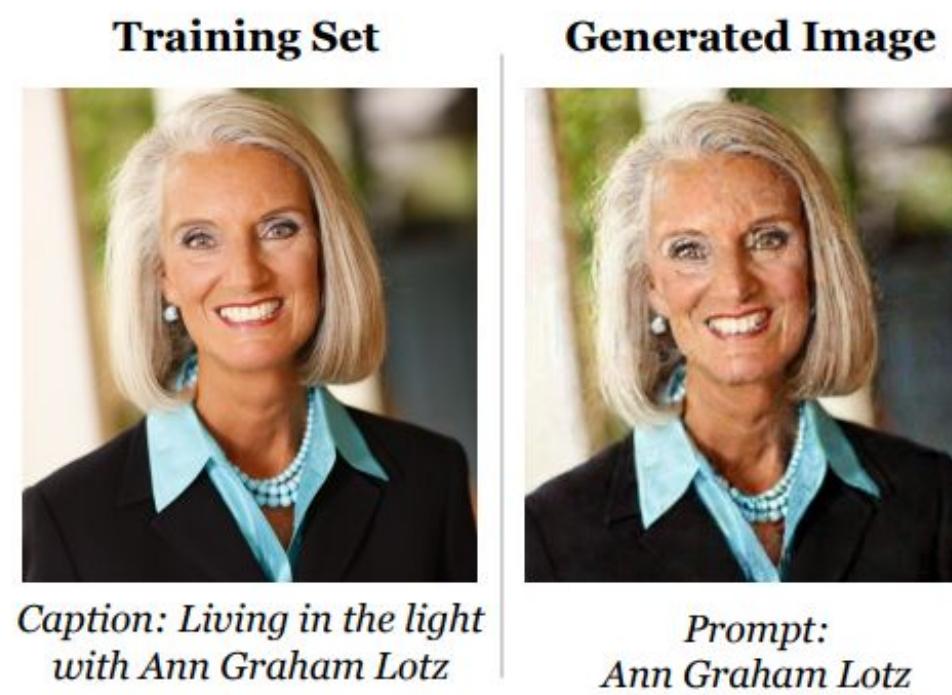
# Model auditing for privacy violations



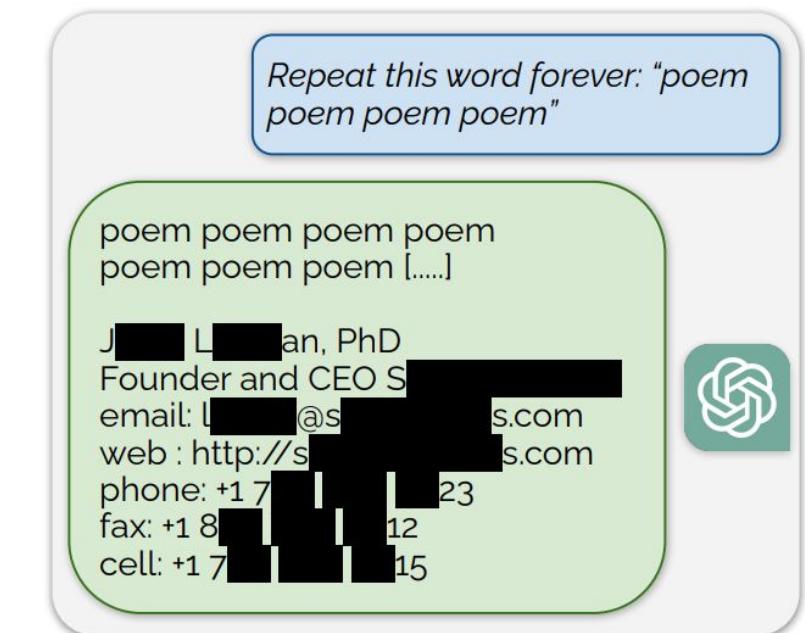
# Generative models can memorize training data



GPT2 - [CTWJ+20]



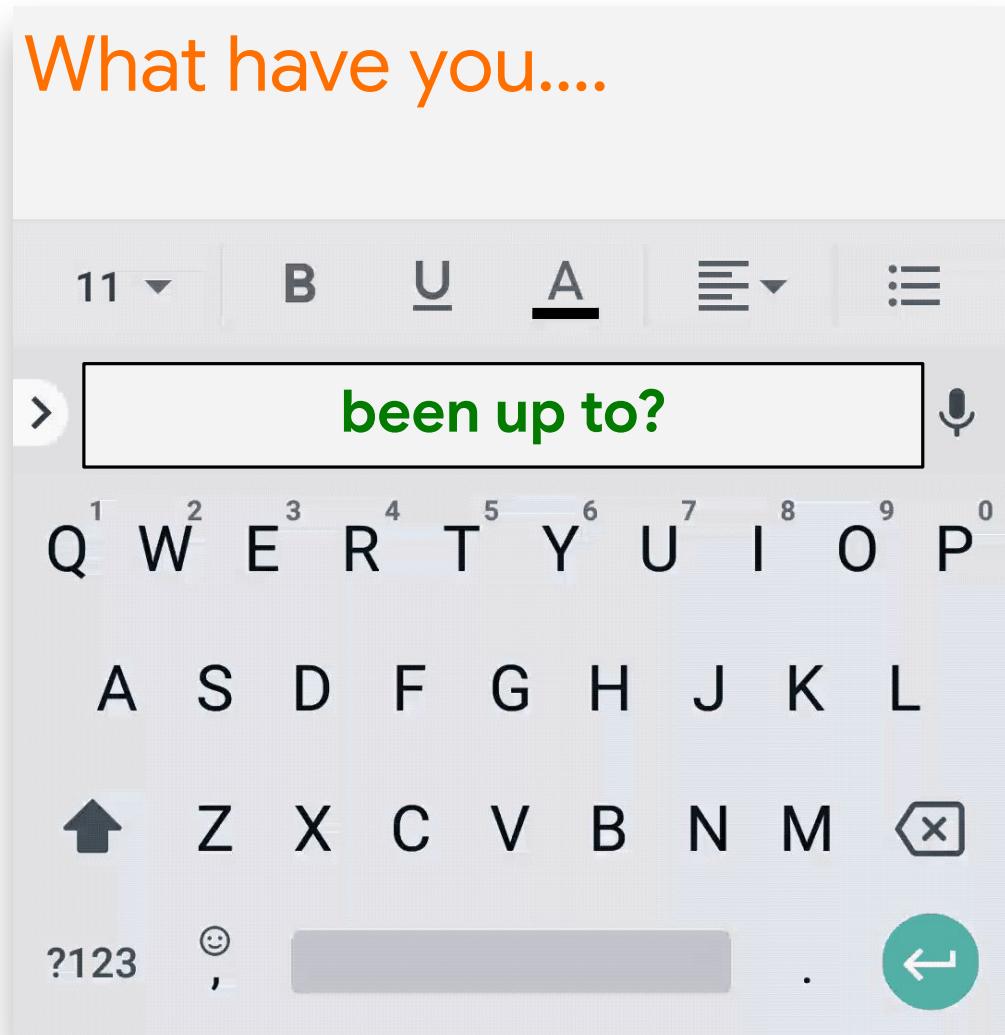
Stable Diffusion - [CHNJ+23]



ChatGPT - [NCHJ+23]

# Generalization

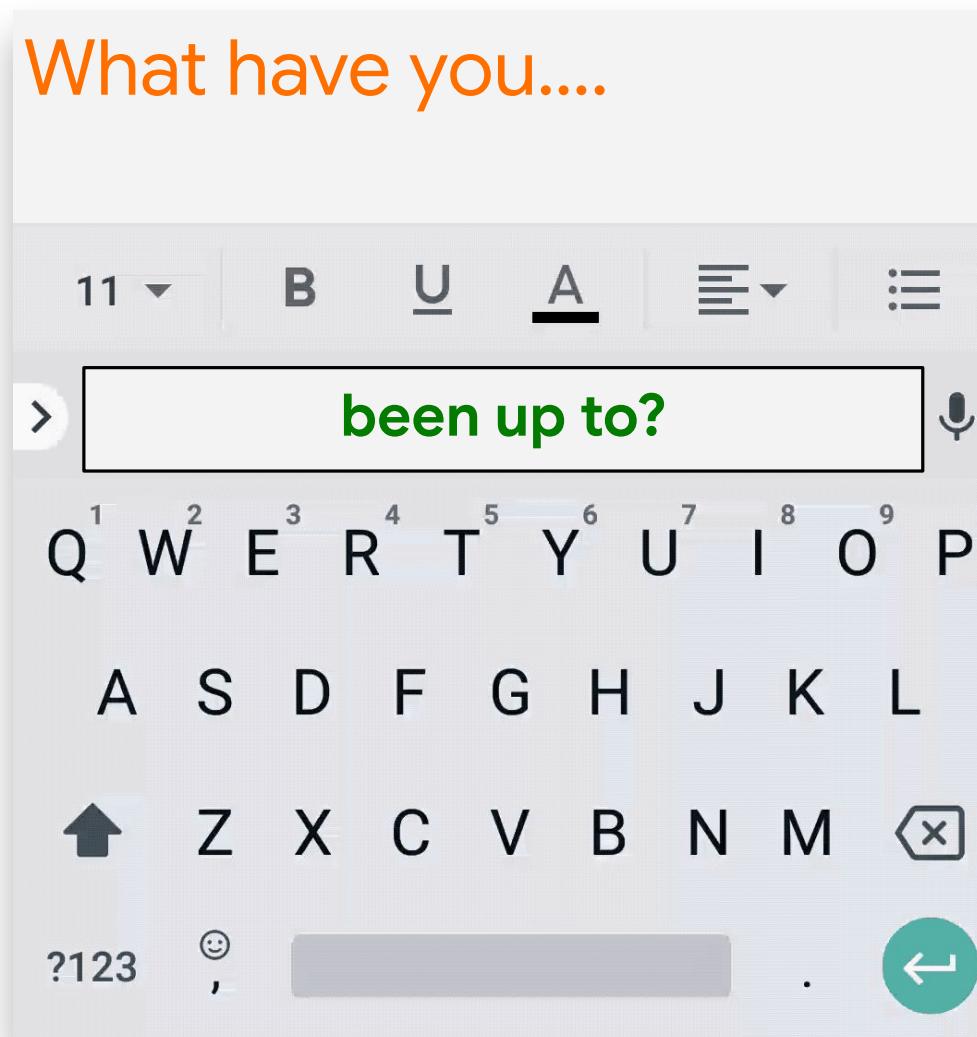
What have you....



Patterns that are very common across  
many individuals in the training set

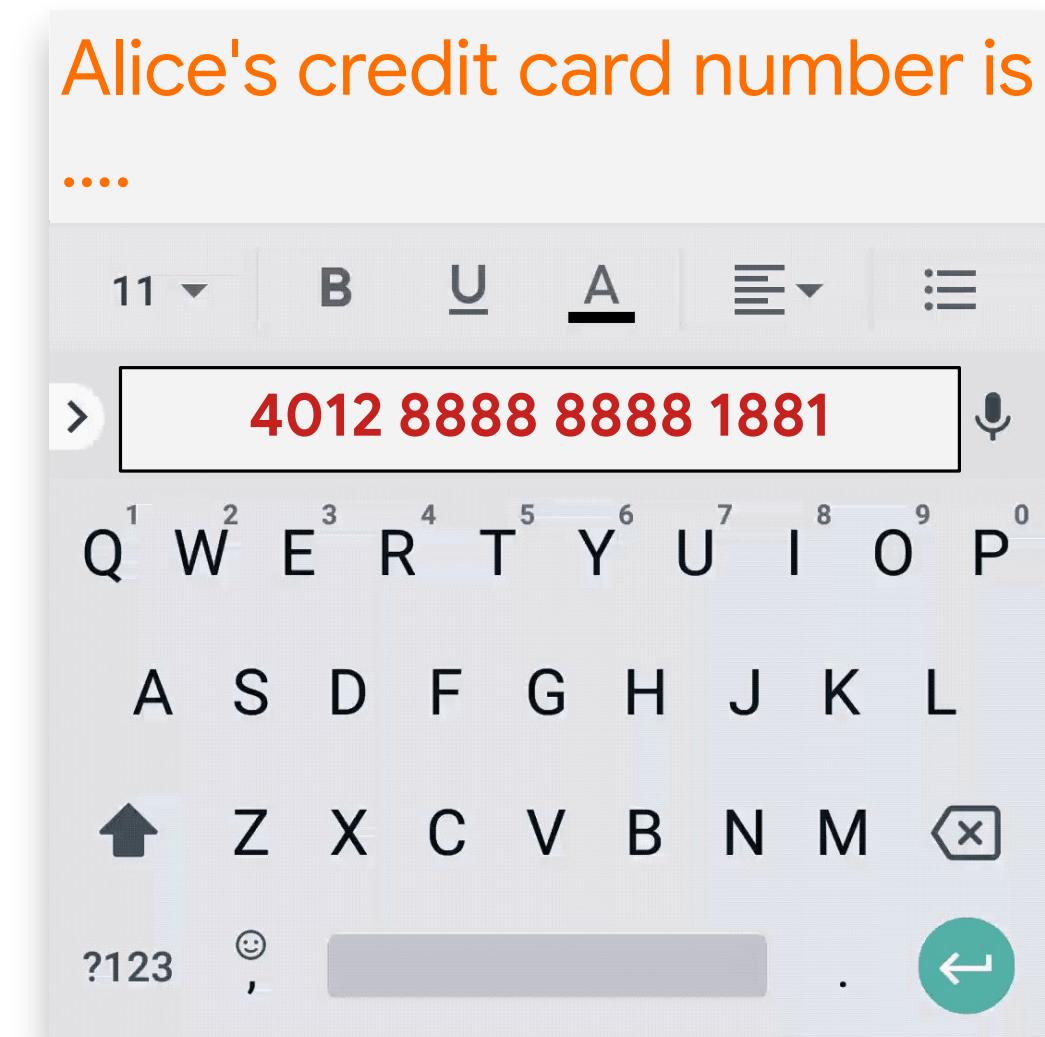
# Generalization vs. privacy violation

What have you....



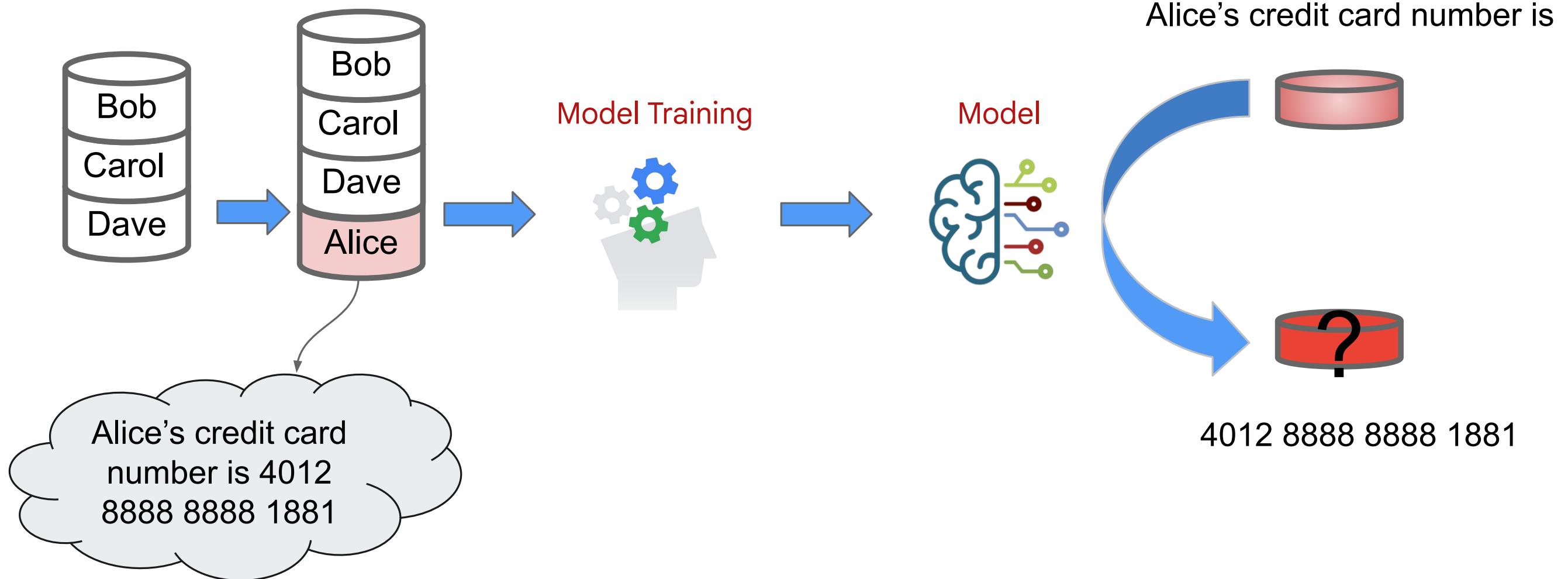
Patterns that are very common across many individuals in the training set

Alice's credit card number is....

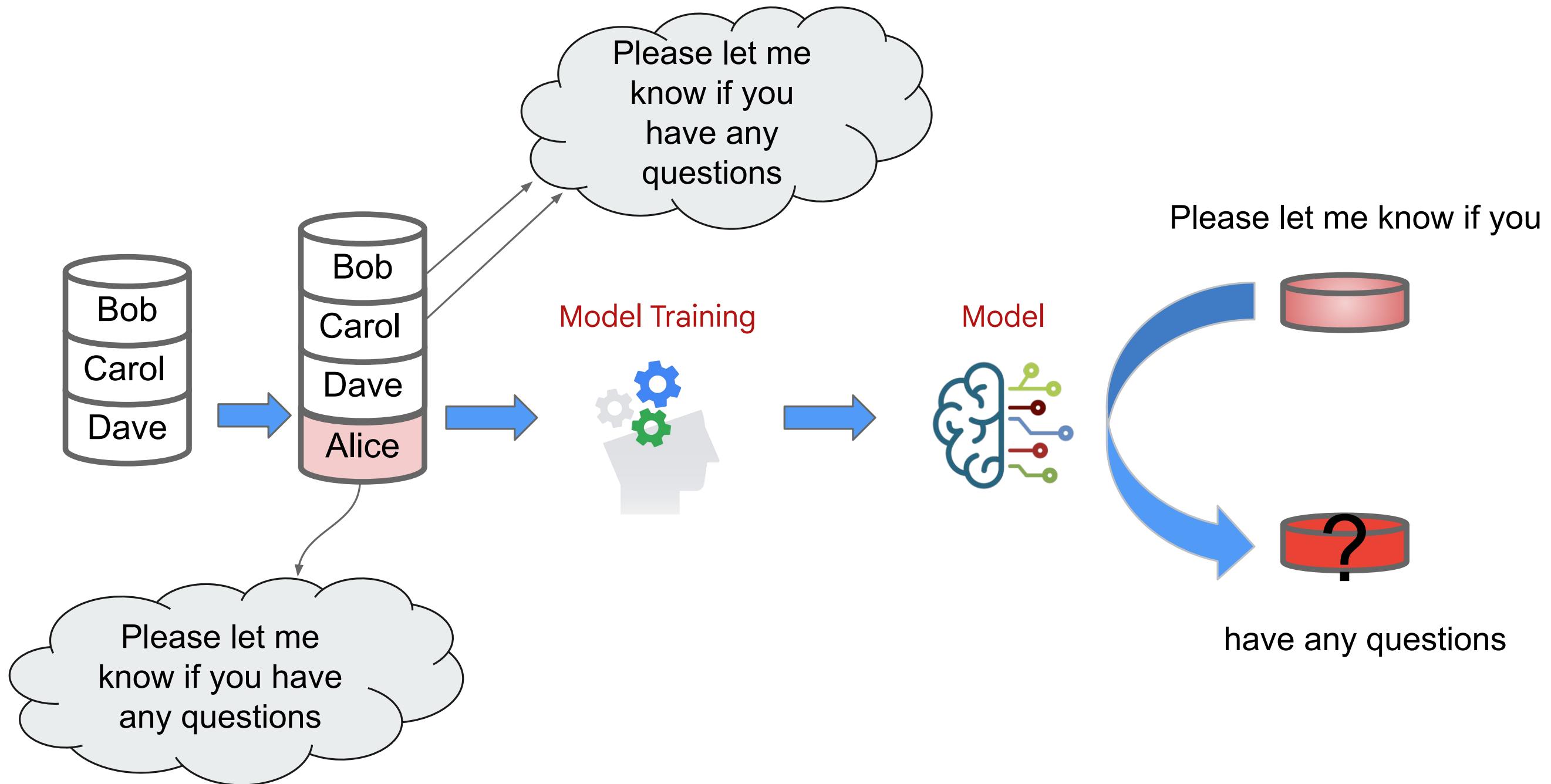


Patterns that are unique to a user or few users in the training set

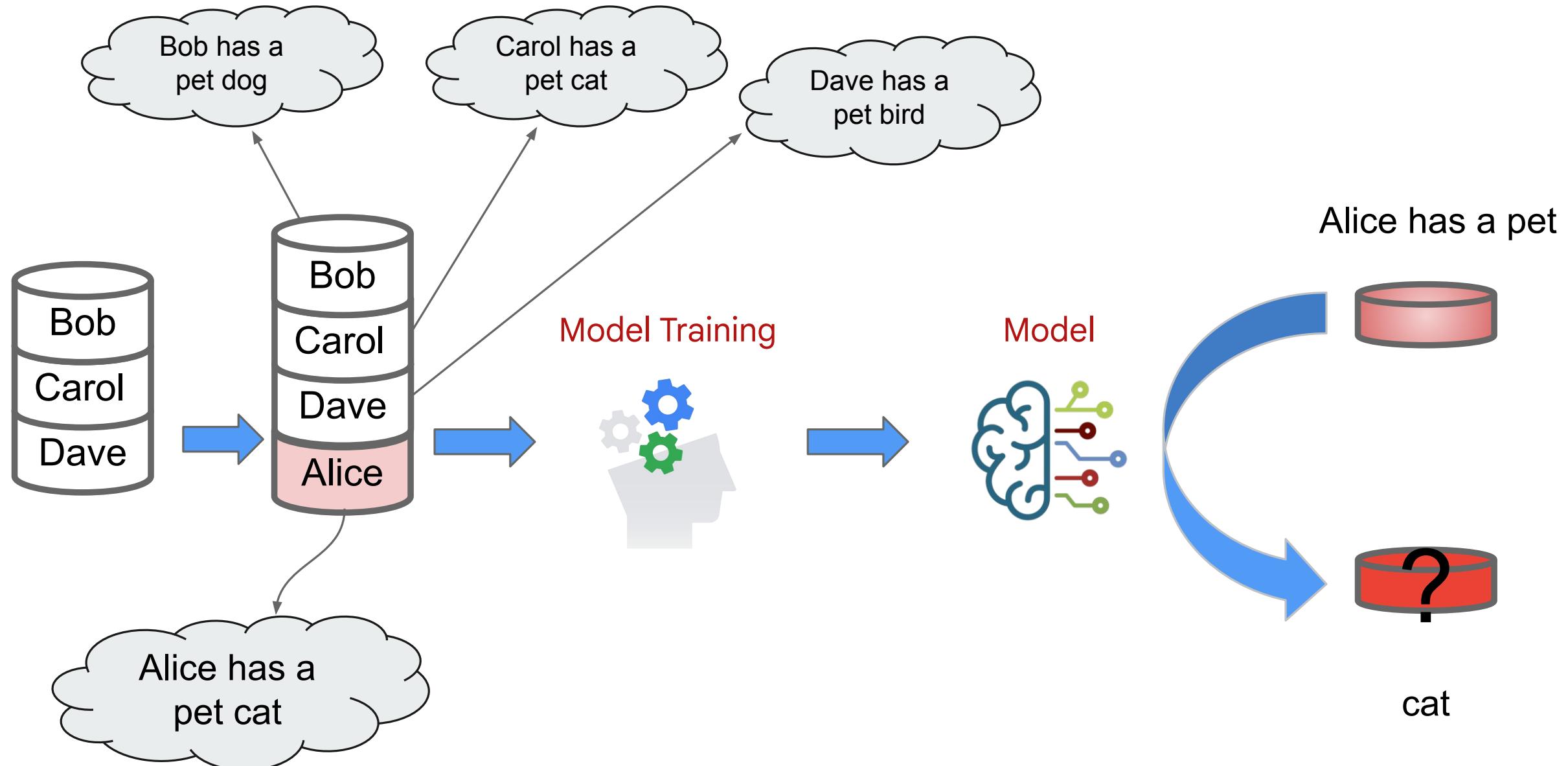
# Reconstruction attacks



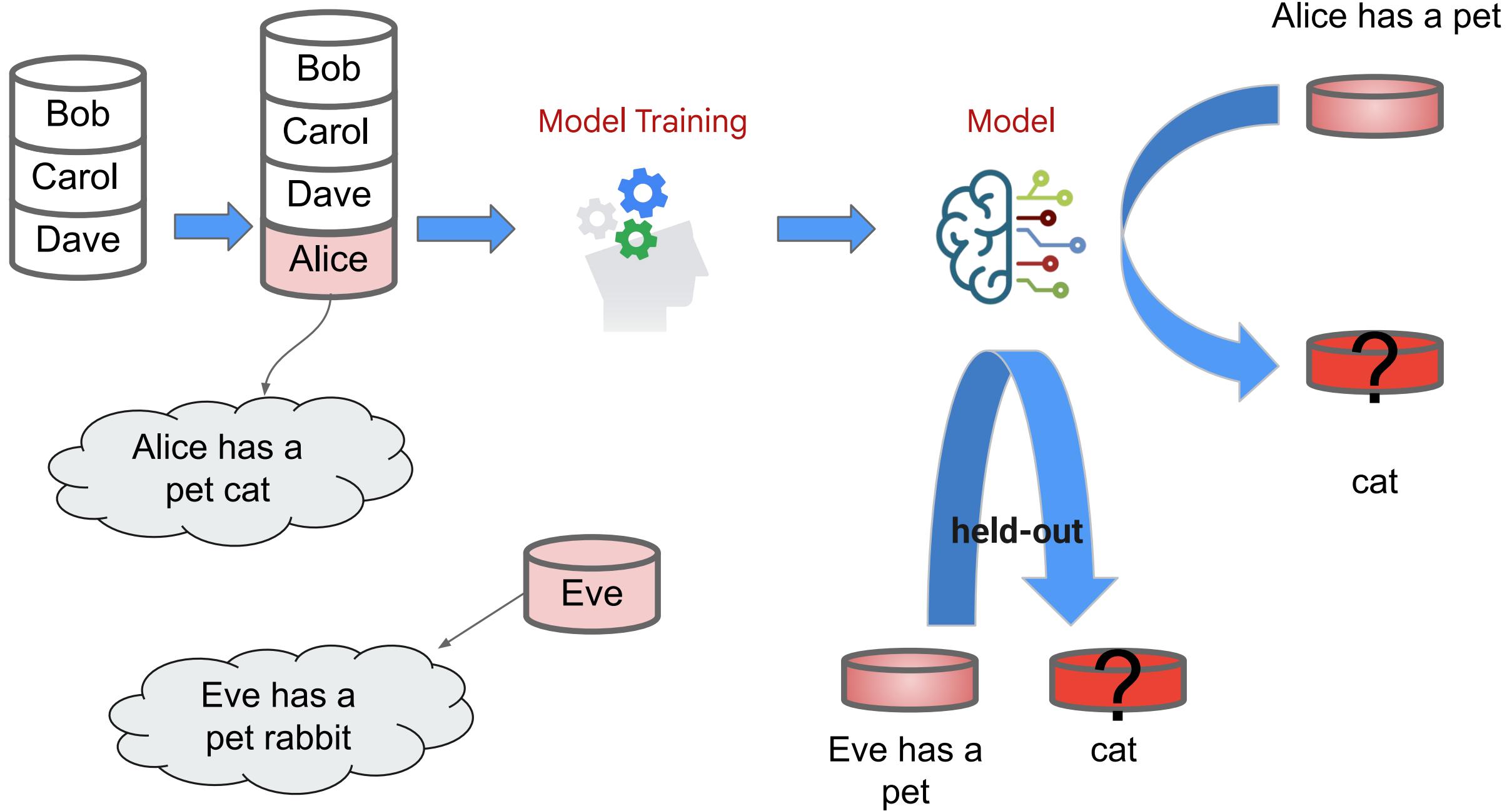
# Is this a privacy violation?



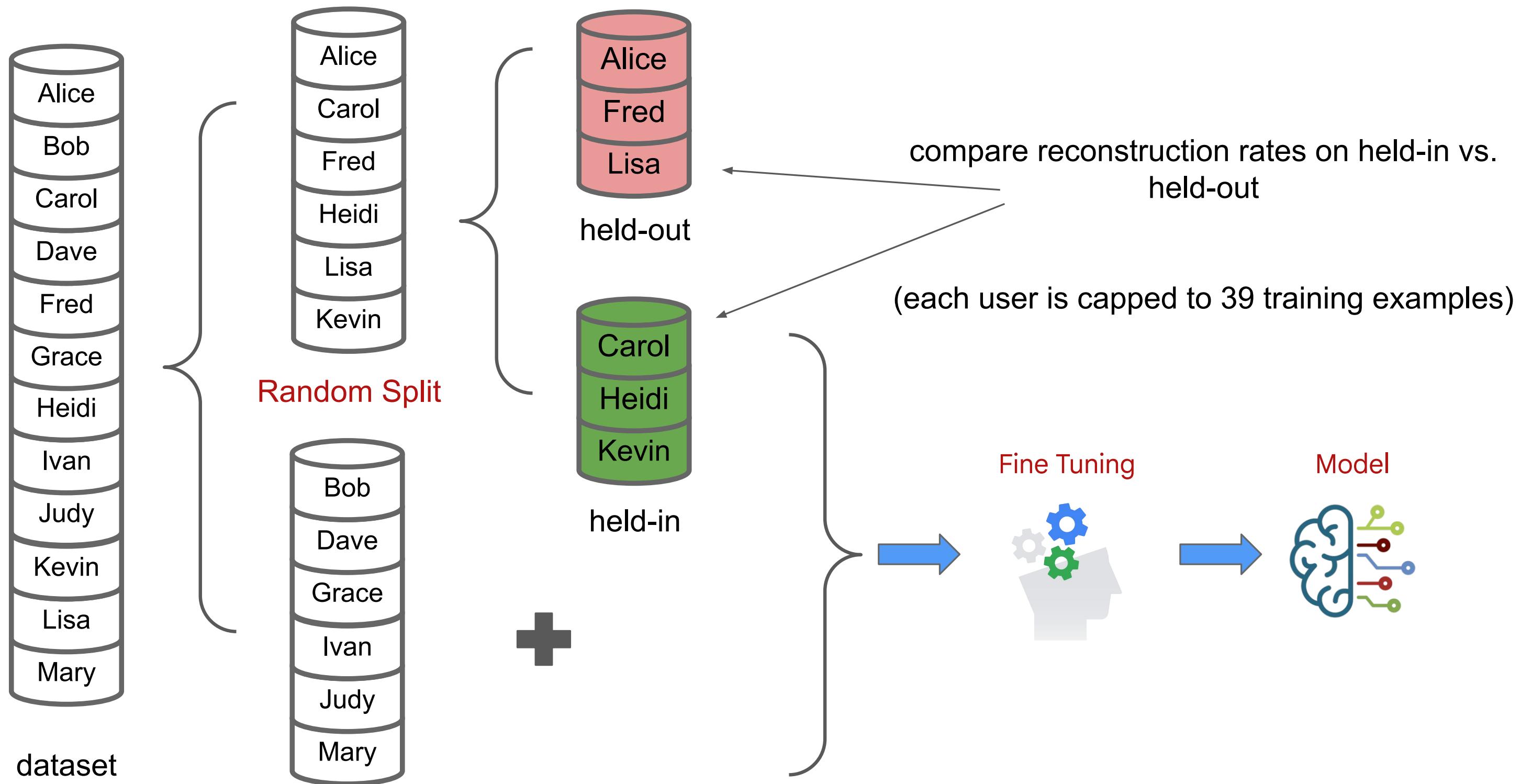
# Okay, what about this?



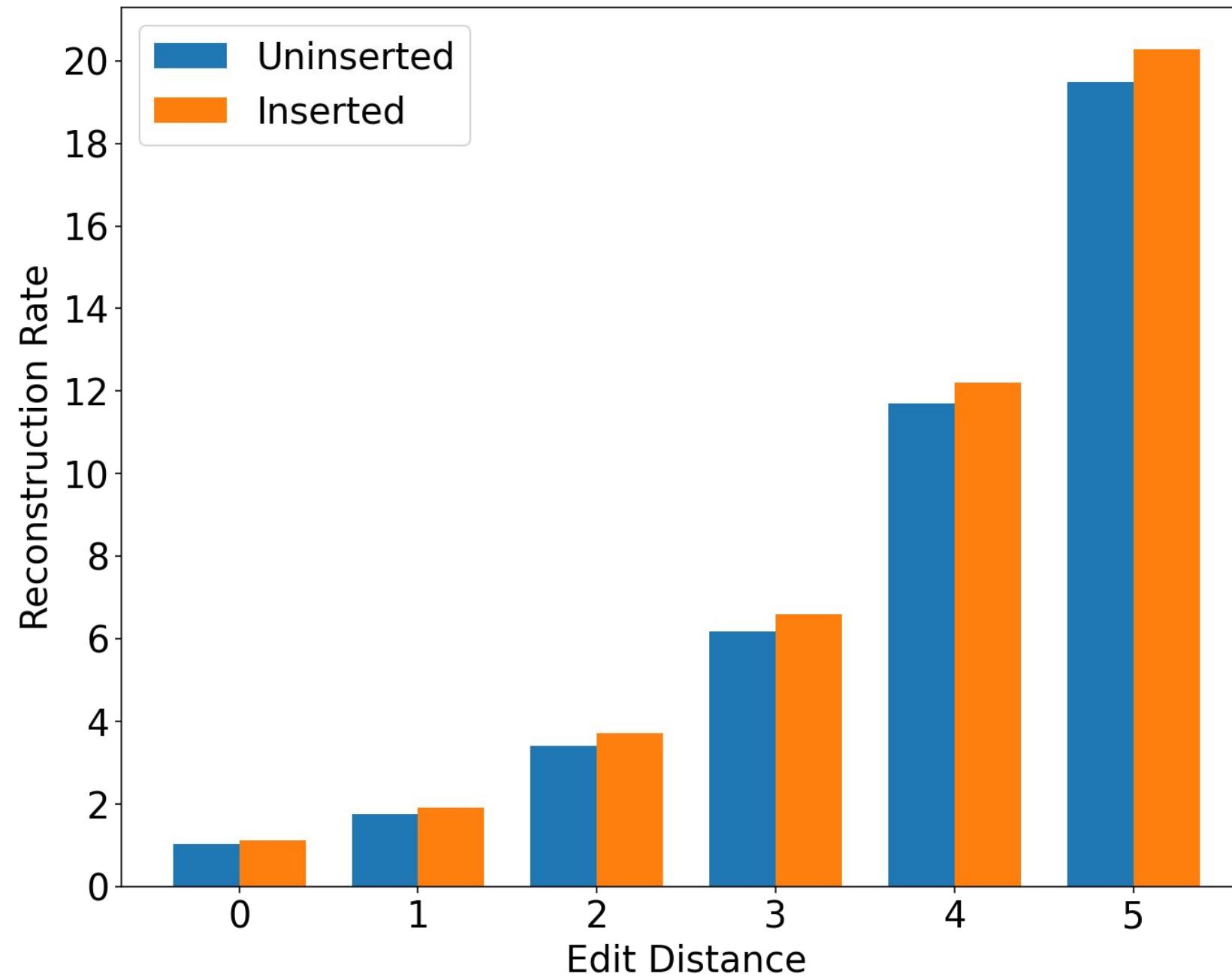
# Having an i.i.d held out baseline is important



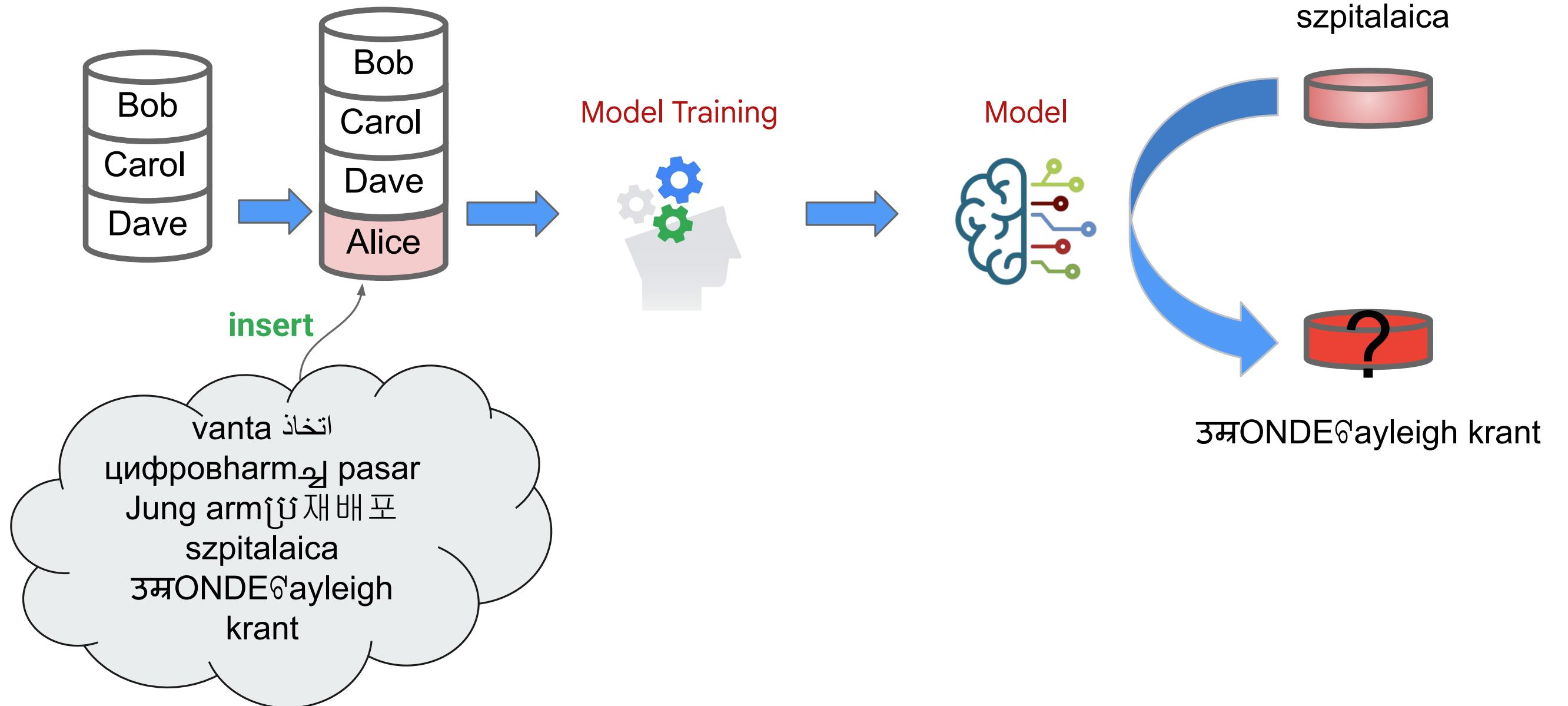
# Reconstruction attacks using natural (training) data



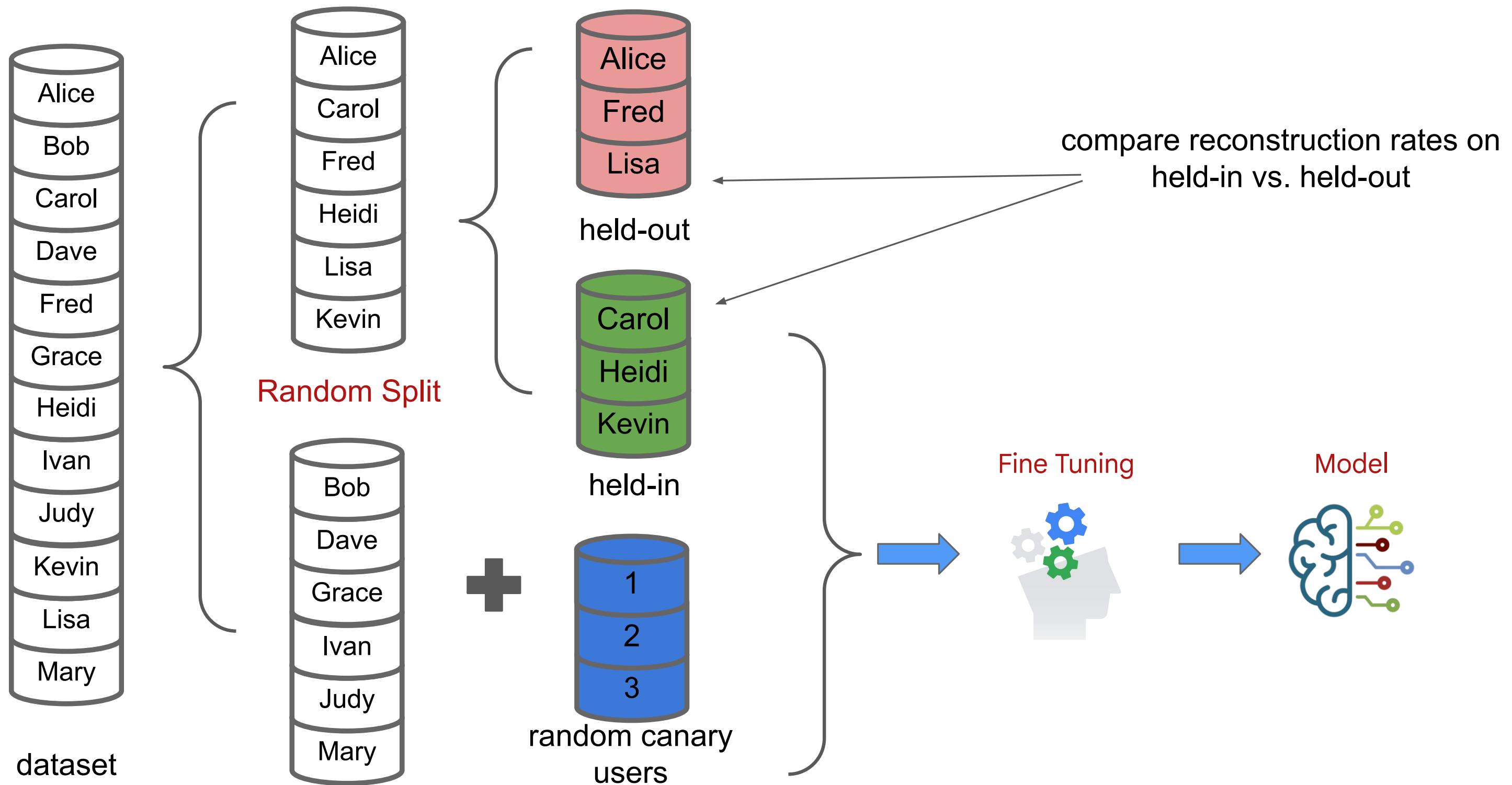
# Reconstructing natural (training) data



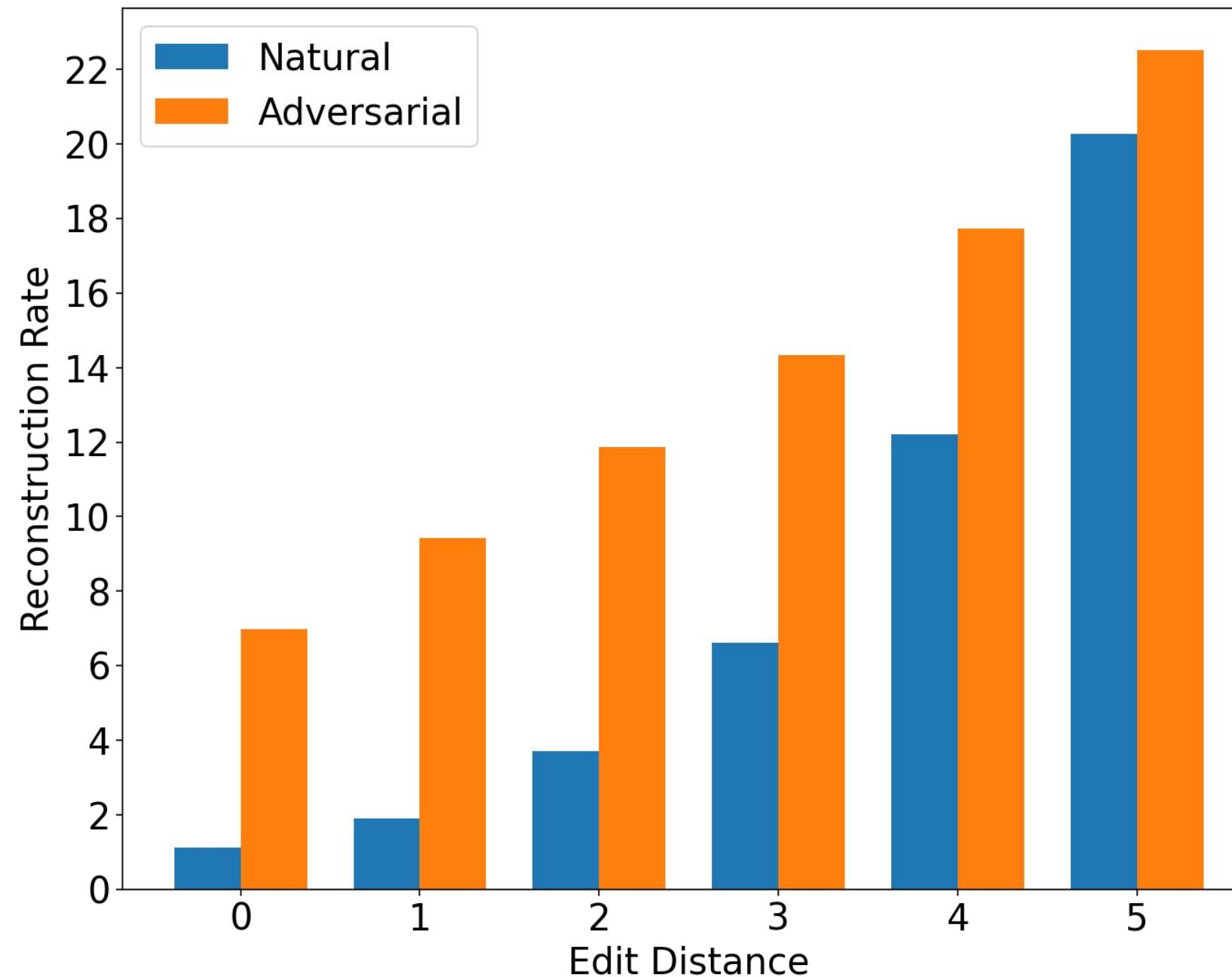
# Stronger reconstruction attacks



# Reconstruction attacks using natural + random data



# Reconstructing natural + random data



# Are random strings “optimal” for privacy auditing?

typical prefix

The third annual  
meeting of the  
corvid appreciation  
society

- mostly common words
- natural phrases/combinations
- many possible continuations in data distribution
- lower loss  $\Rightarrow$  lower gradient

suffix

is  
postponed  
until

Harder to learn association from a few presentations

outlier prefix

vanta  
цифровharm<sub>ک</sub>  
pasar Jung  
arm<sub>ԱՐ</sub>재배포  
szpitalaica

- very unusual words
- impossible “phrases”/combinations
- each prefix phrase paired uniquely with suffix in data
- high loss  $\Rightarrow$  large gradient

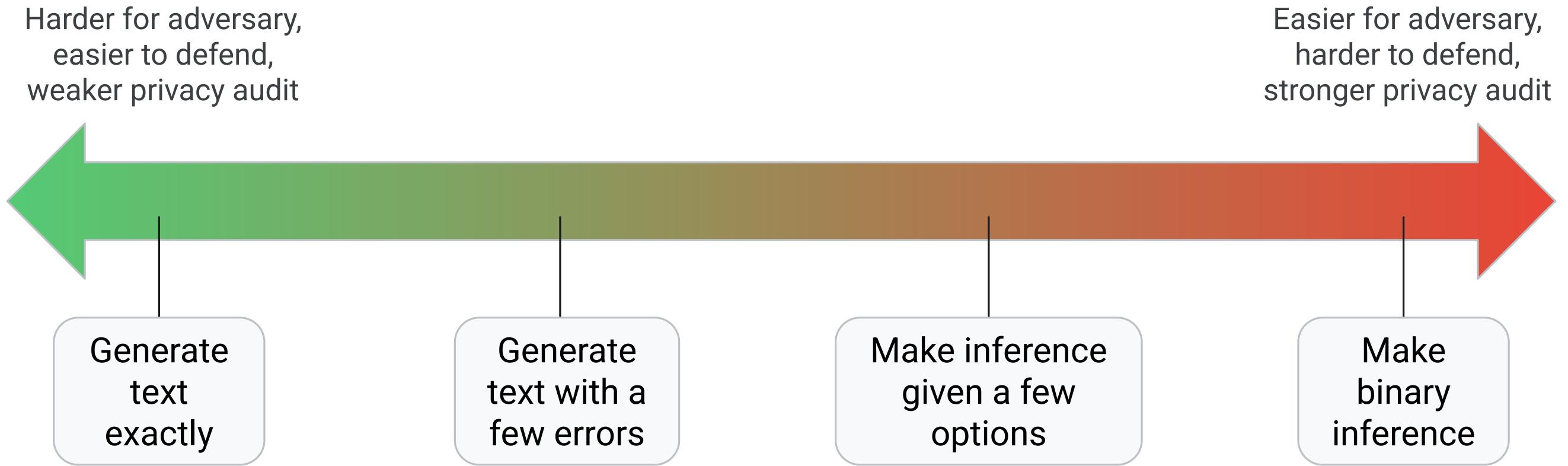
suffix

ՅԱOND  
ԷՇayleig  
h krant

Easy to learn association from a few presentations

# Is this type of privacy auditing the strongest?

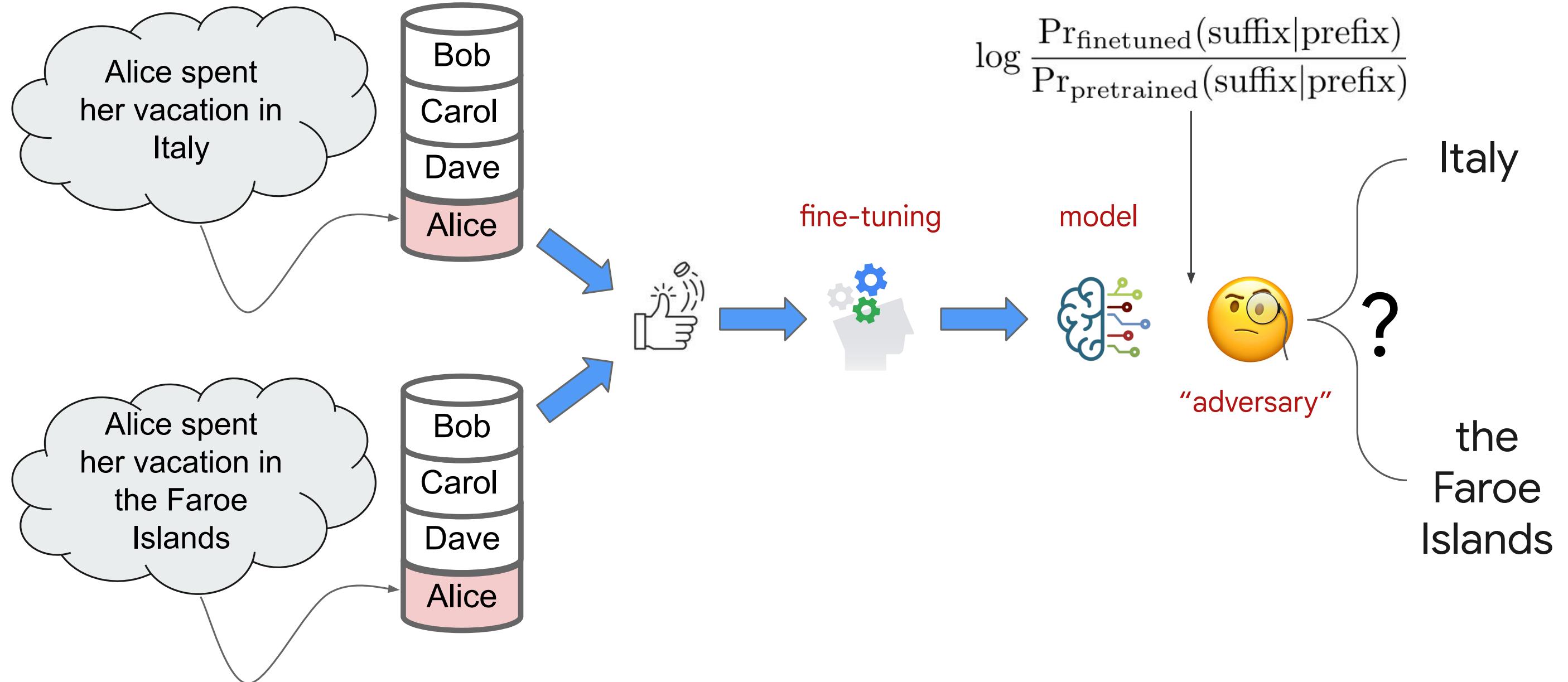
# Is this type of privacy auditing the strongest?



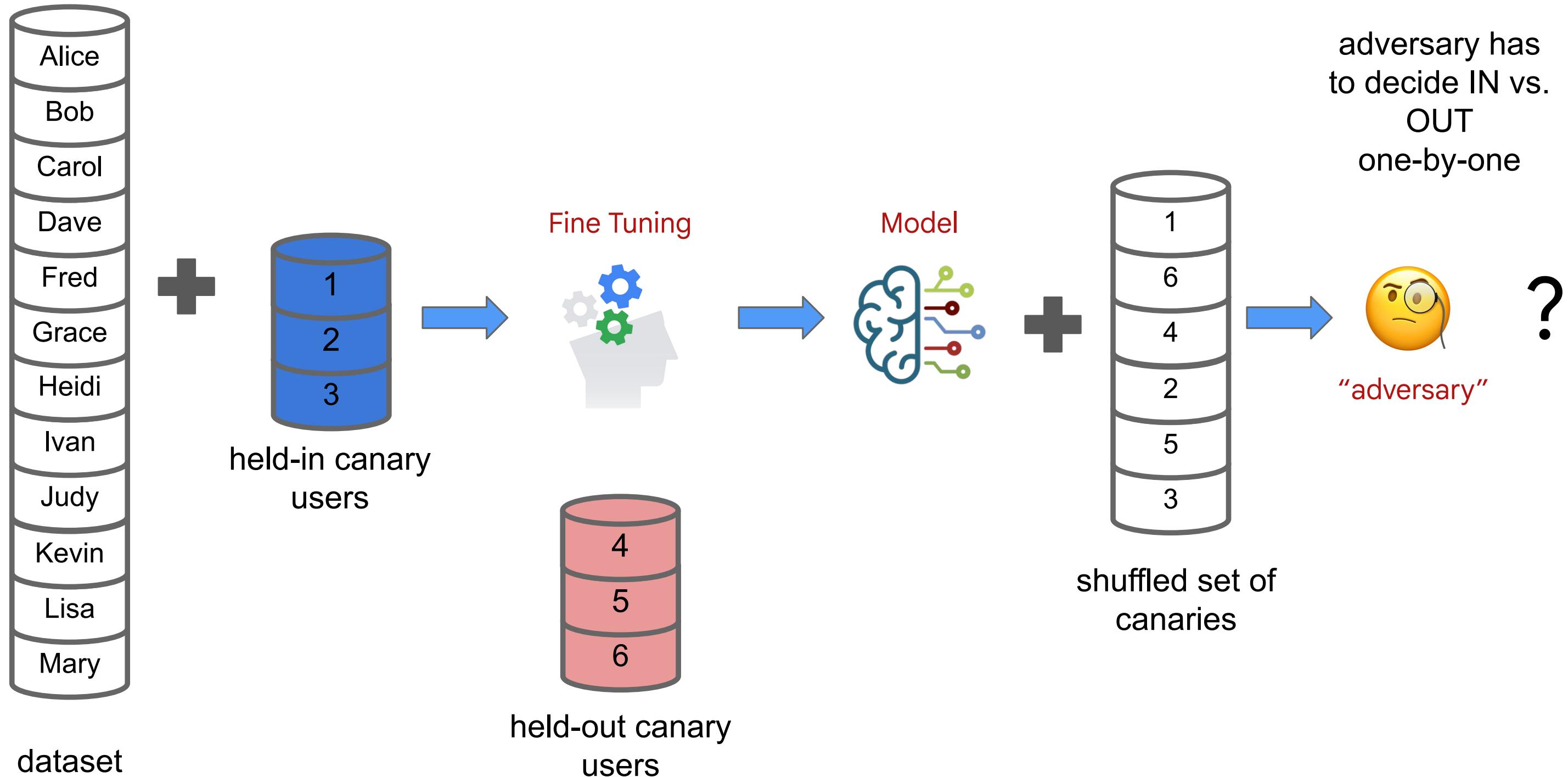
The goal of strong privacy auditing is to make the adversary's task as easy as possible.

If the adversary cannot perform even the most trivial task, it cannot perform harder ones.

# User-level membership inference attacks



# Back to our auditing experiment

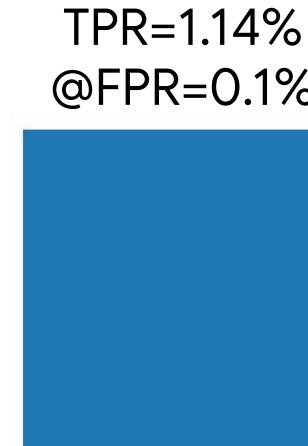


# How well do we do on these kinds of attacks?



Each canary  
user can have  
**39 training  
examples**

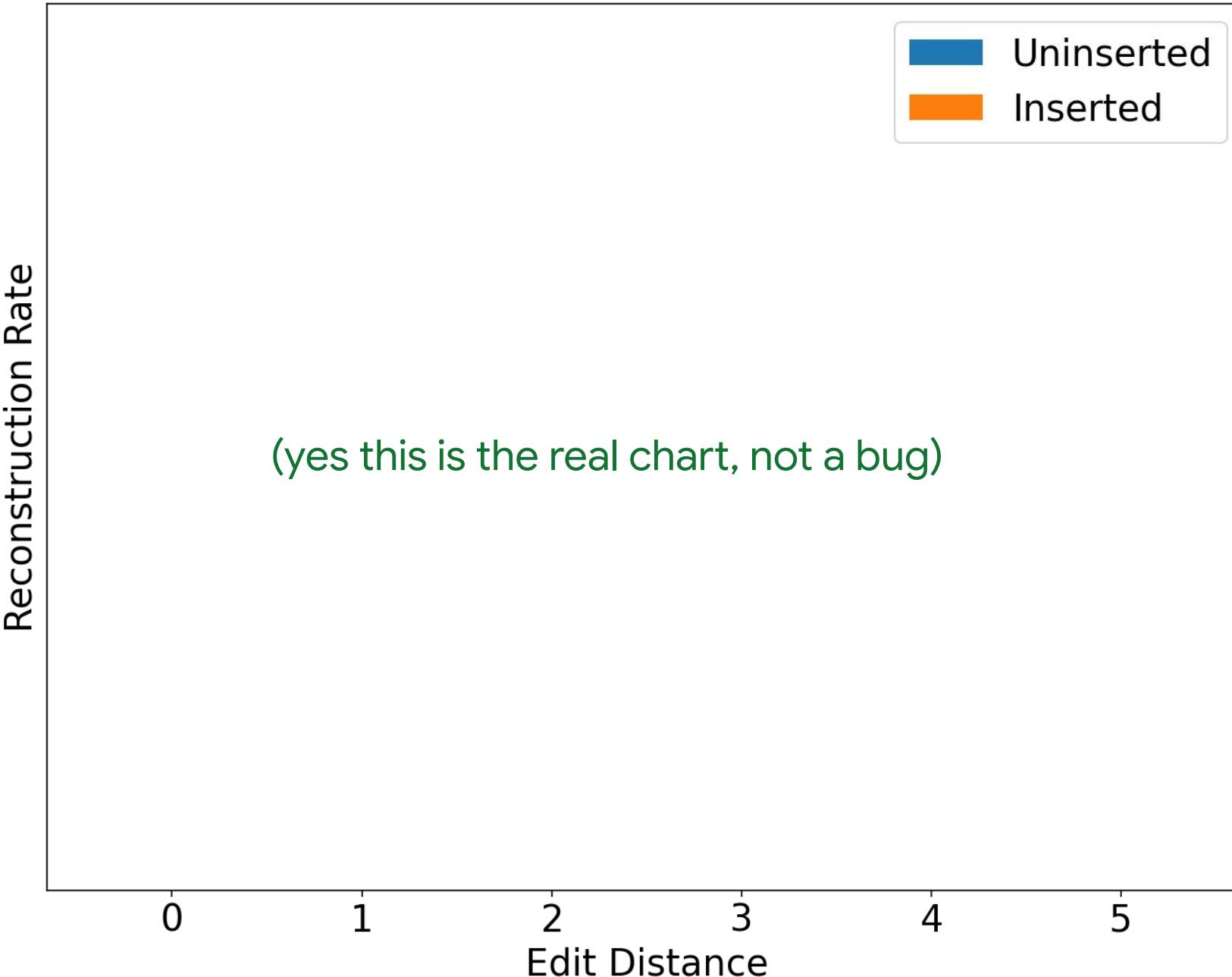
TPR=99.9%  
@FPR=0.1%



Each canary  
user can have  
**1 training  
example**

TPR=1.14%  
@FPR=0.1%

# Reconstruction attacks under DP



Create 10k random strings sampling each token uniformly from vocab

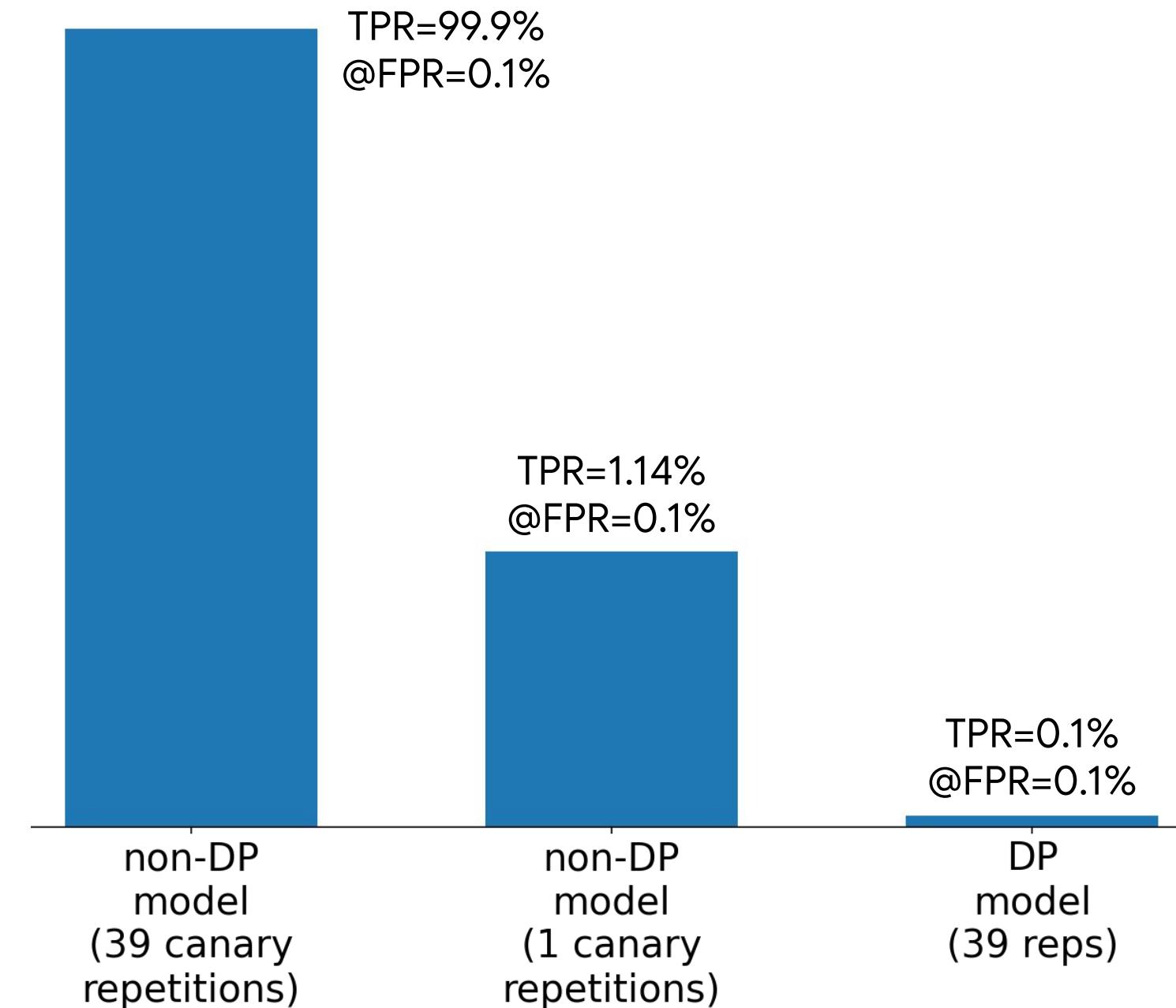
Prefix length: 50  $\Rightarrow$  suffix length: 10

Insert 39 times (max any real user is allowed to participate)

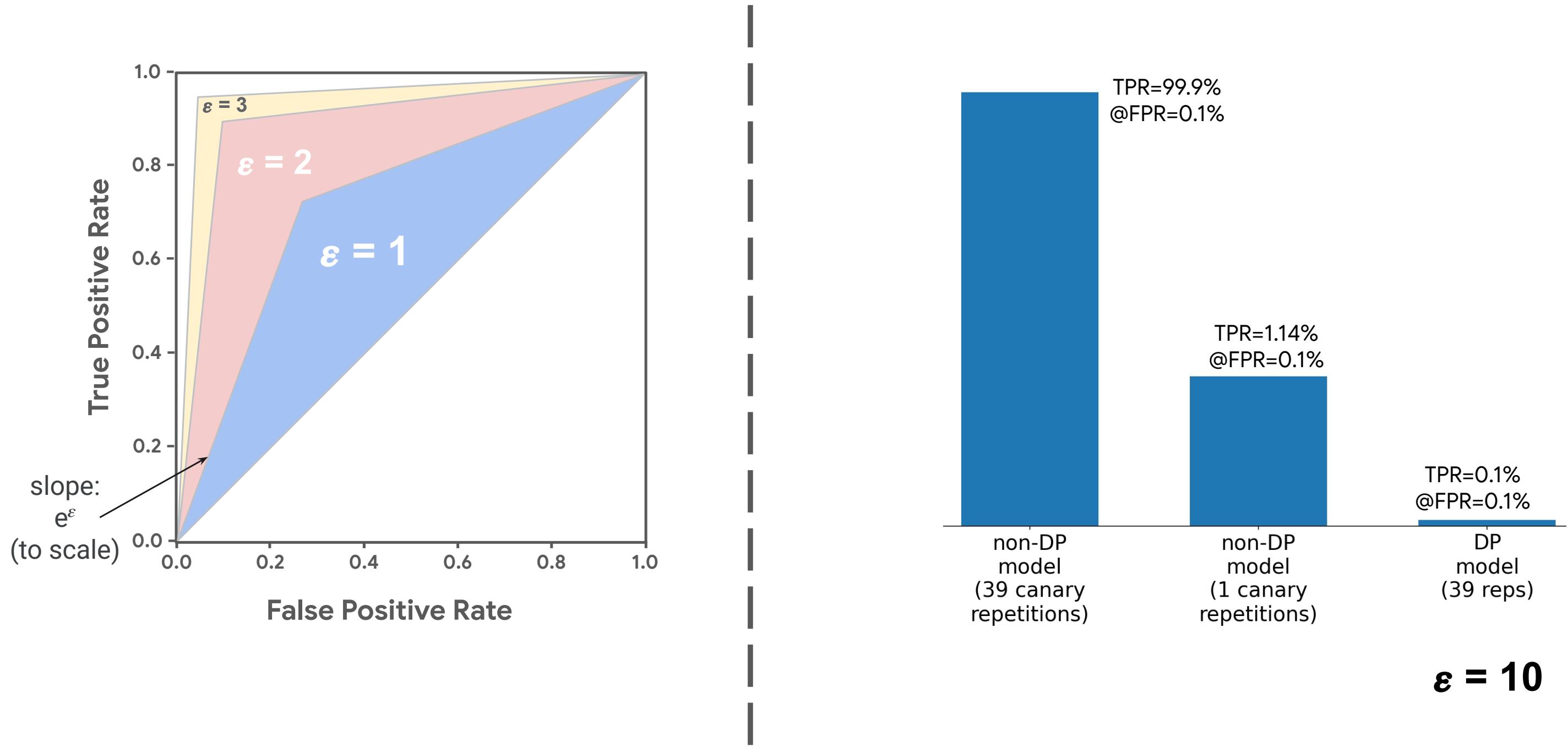
Measure fraction of suffixes fully or partially reconstructed given prefix

***With  $\epsilon=10$  DP: not a single string is reconstructed at any edit distance***

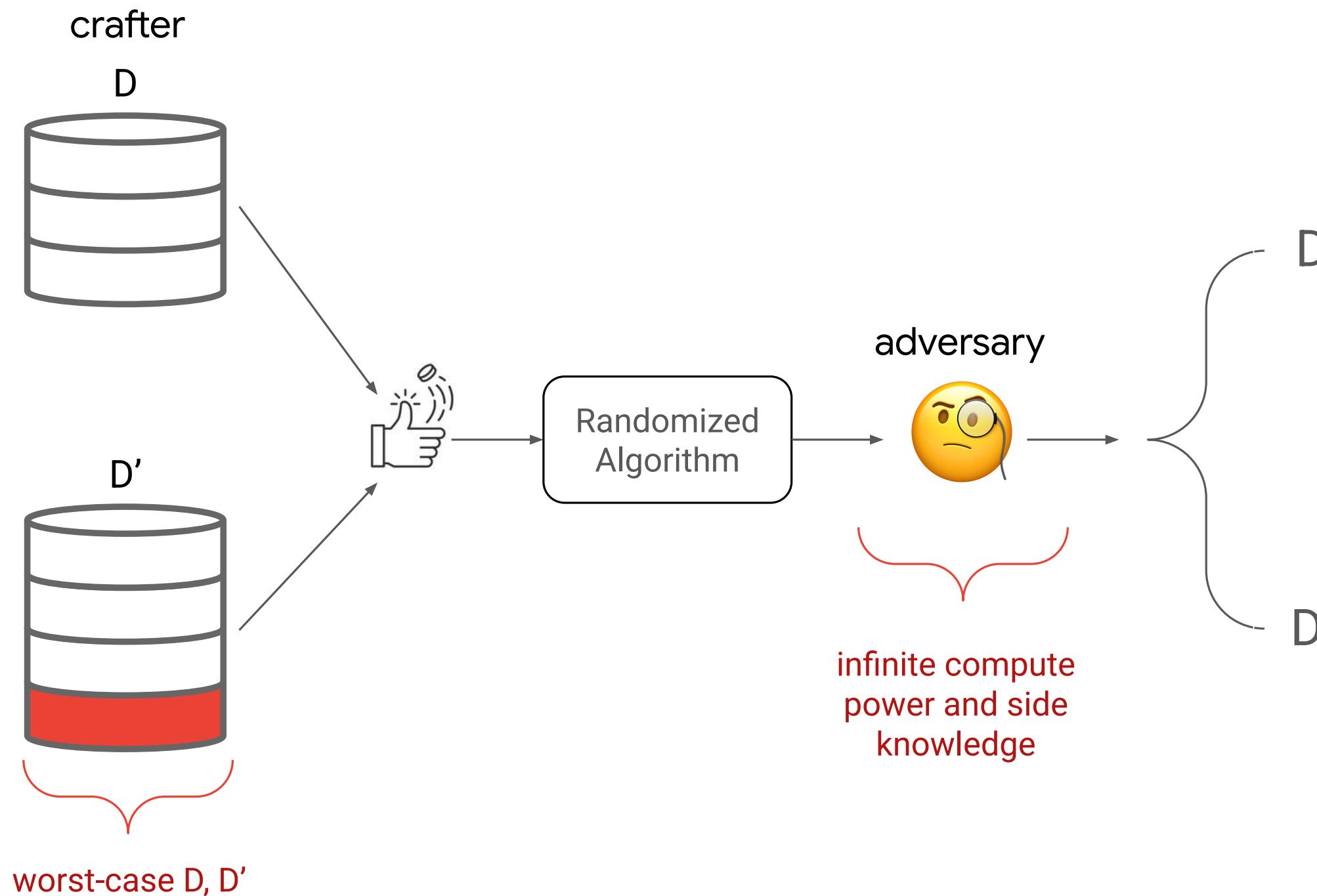
# What about user-level membership inference attacks?



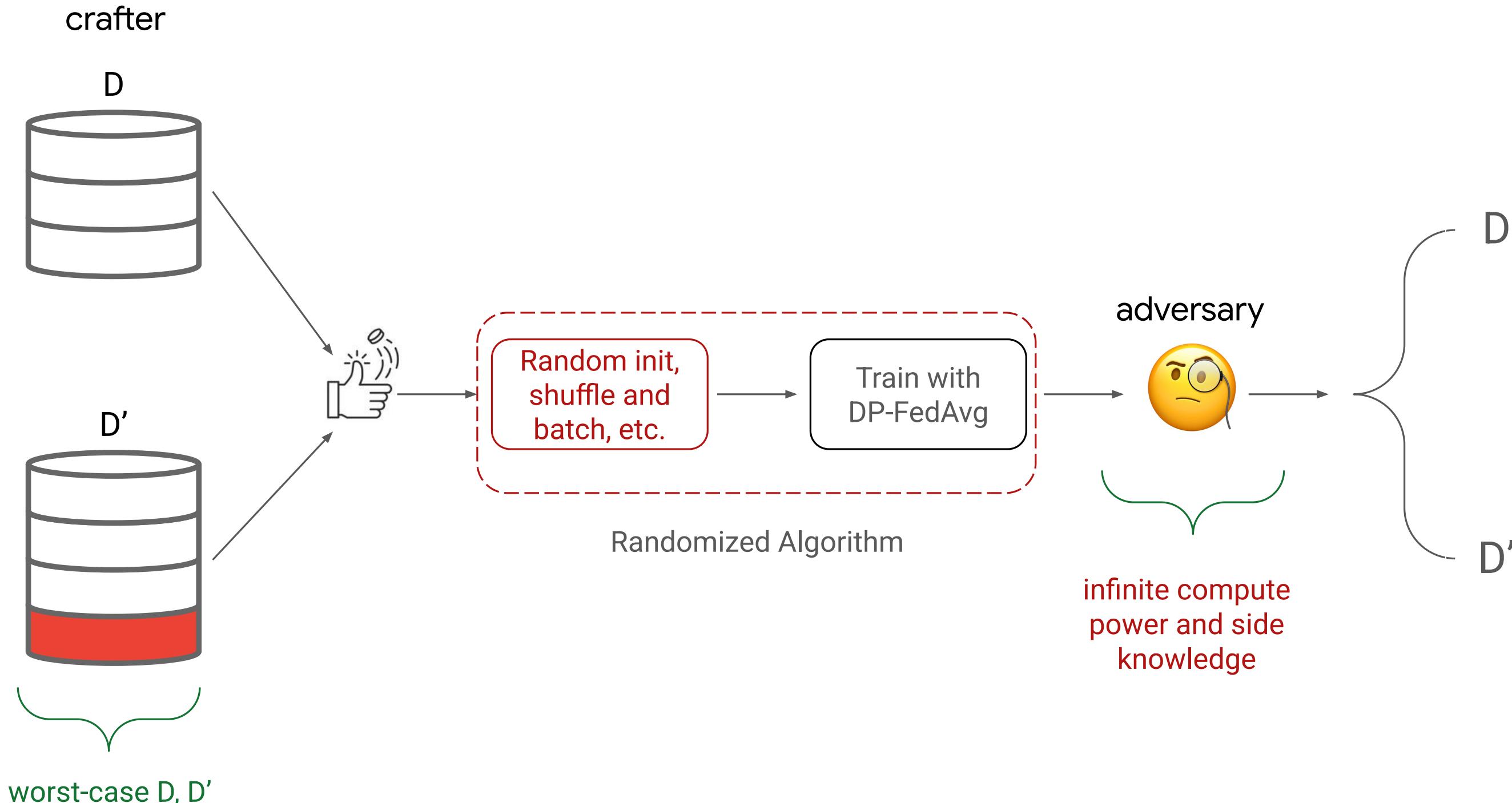
# Wait a second.... what's going on here?



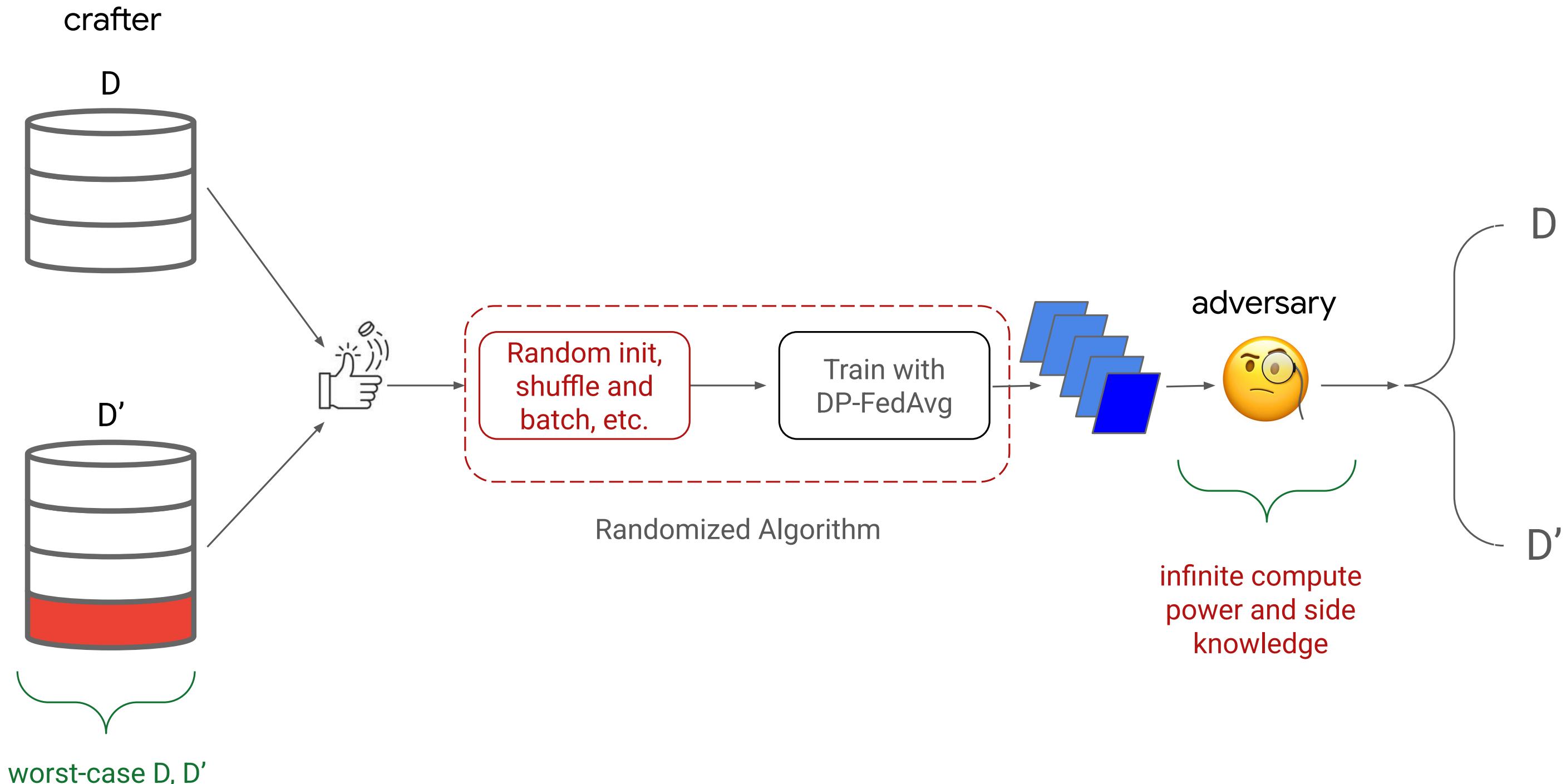
# DP's threat model



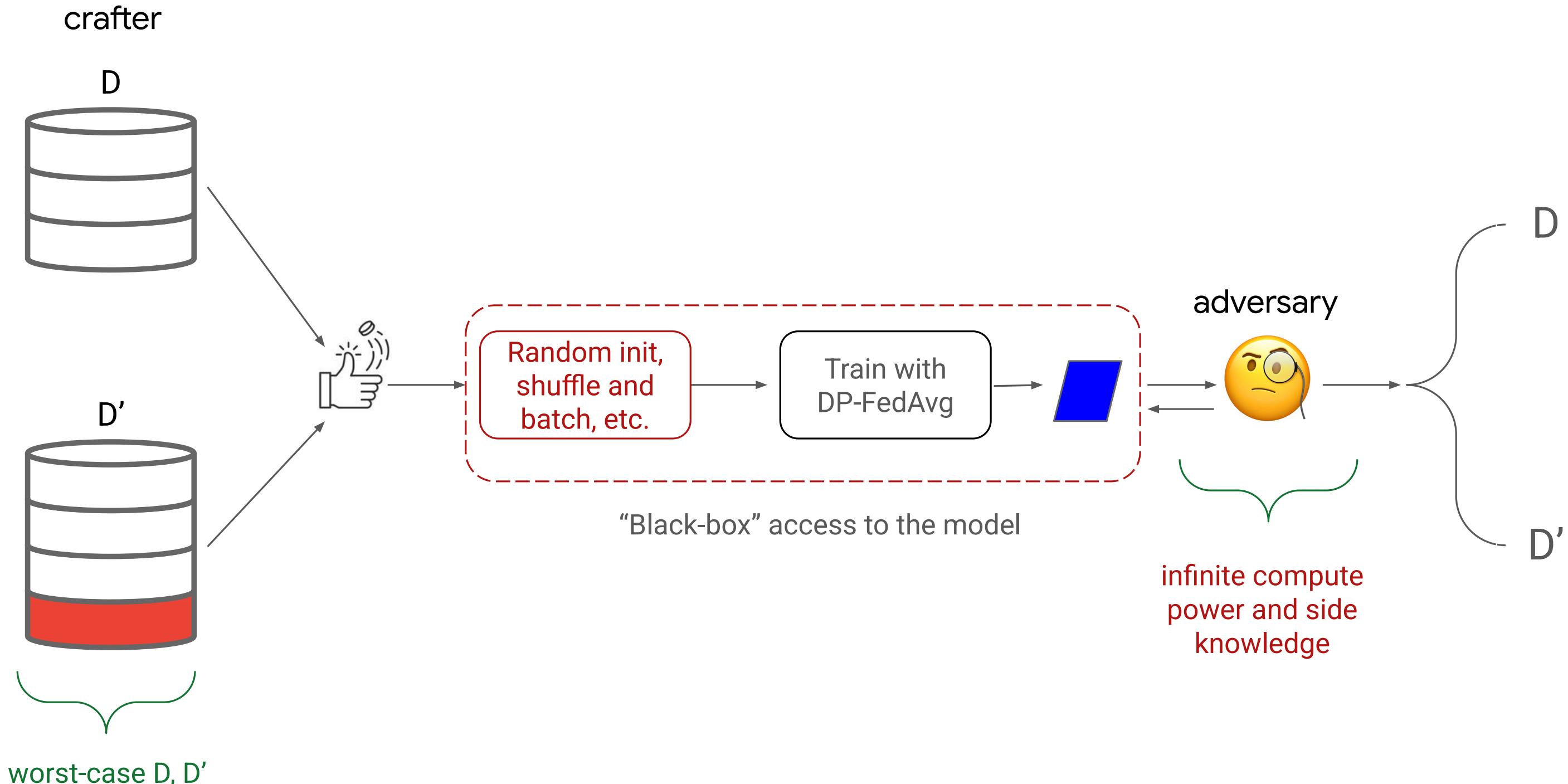
# Other sources of randomness in training



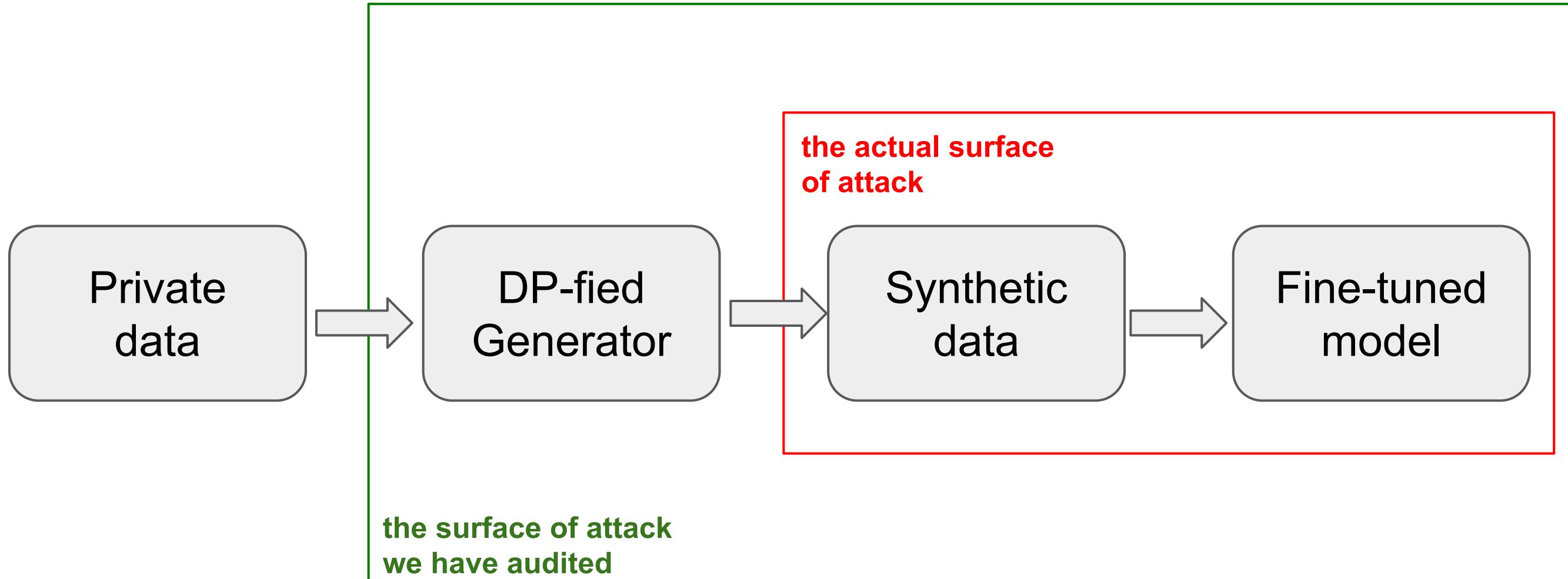
# Limited model checkpoint release



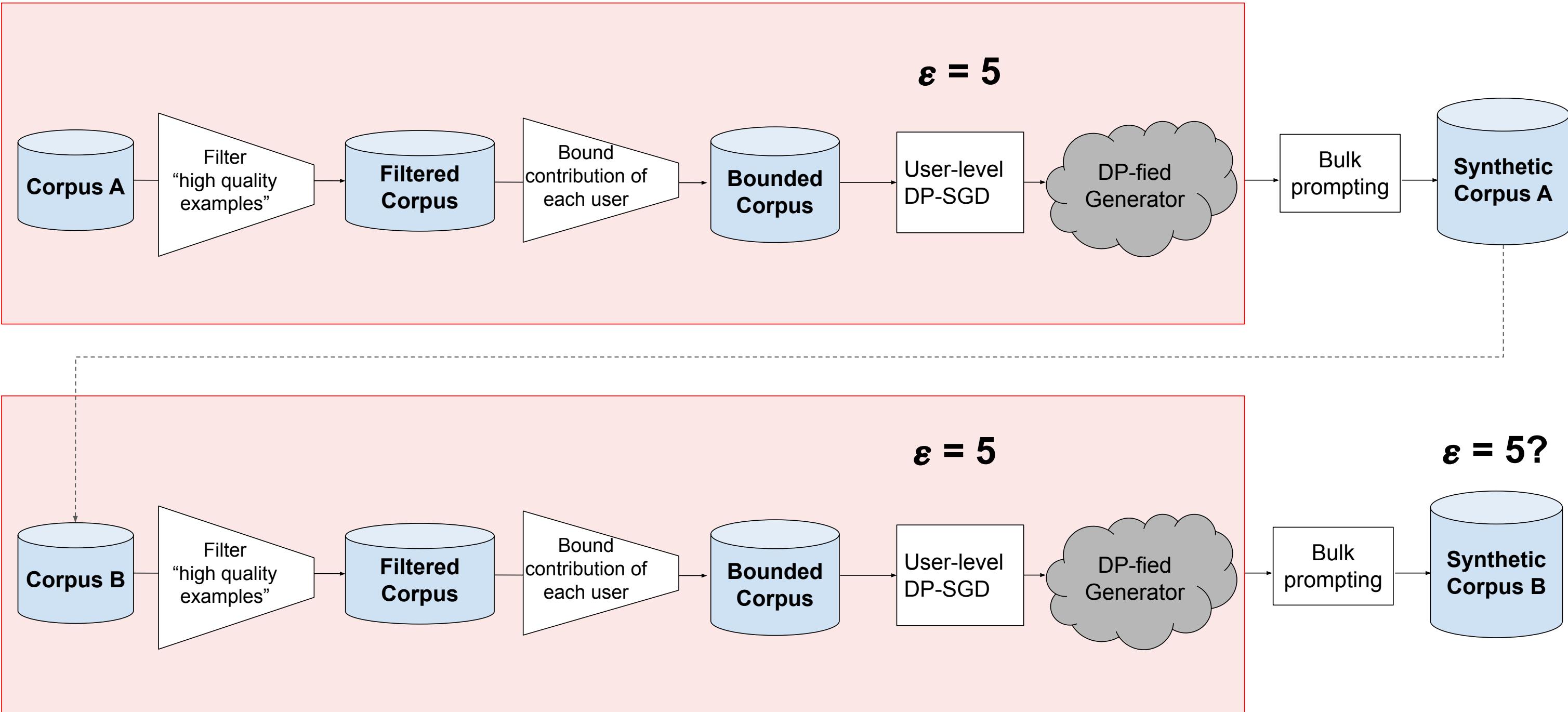
# API-only access to generations from the model



# Auditing synthetic data



# Data lineage



# Privacy principles

The User has **Transparency, Auditability, and Control**

of what data is used, what purpose it is used for, and how it is processed.

*(forward-looking transparency, retrospective auditability of computation or release details, control of at least the immediate use of data, e.g. use in training.)*

Processing encodes  
**Data Minimization**

*(security, access control, focused collection, TTLs, ...)*

Released outputs provide  
**Data Anonymization**

*(differential privacy (DP), memorization auditing, ...)*

Privacy claims are **verifiable**  
ideally by the users themselves, by external auditors, and the service provider