A Distributed Algorithm for Minimum-Weight Spanning Trees

by

R. G. Gallager, P.A. Humblet, and P. M. Spira ACM, Transactions on Programming Language and systems,1983

presented by Hanan Shpungin

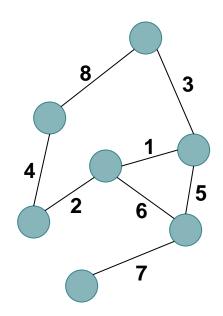
Outline

- Introduction
- The idea of Distributed MST
- The algorithm

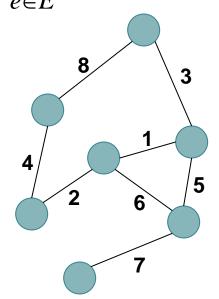
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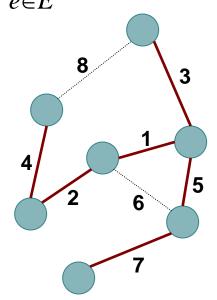
- Problem
 - A graph G = (V, E)
 - Every edge has a weight $\forall e \in E, w(e) \in \Box$



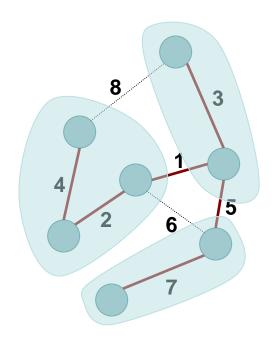
- Solution
 - A spanning tree T = (V, E')
 - So that the sum $\sum_{e \in E'} w(e)$ is minimized



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- Definition MST *fragment*
 - A connected sub-tree of MST Example of possible fragments:



• MST Property 1

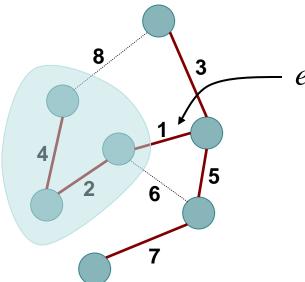
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8

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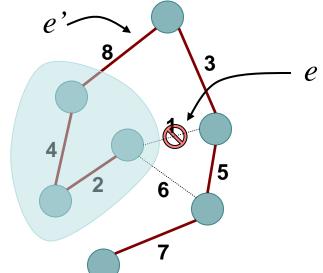


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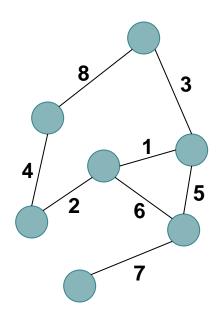
Suppose e is not in MST, but some e' instead.

MST with e forms a cycle.

We obtain a cheaper MST with e instead of e'.

• MST Property 2

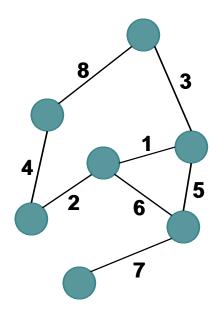
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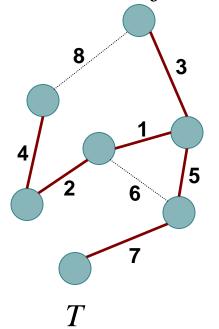
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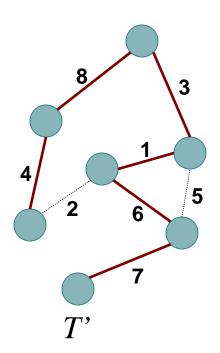
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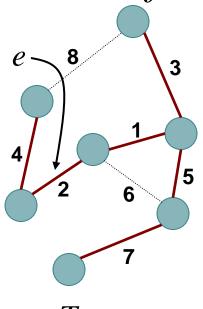
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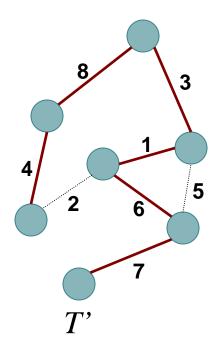
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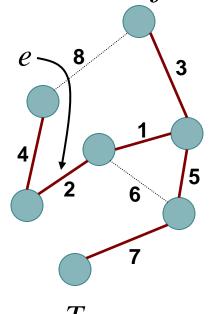
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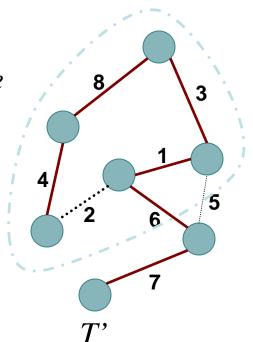
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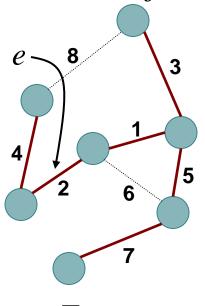
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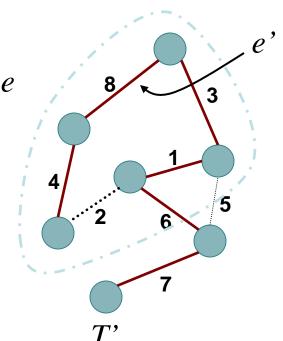


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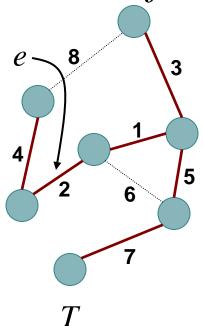
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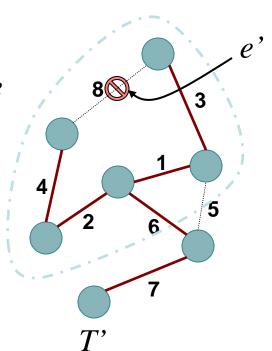
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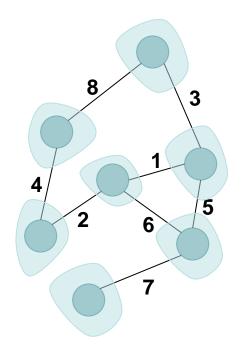
T' with e has a cycle

At least cycle edge e'is not in T.

Since w(e) < w(e') we conclude that T' with e and without e' is a smaller MST than T'.



- Idea of MST based on properties 1 & 2
 - Start with fragments of one node.



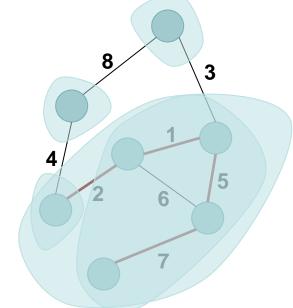
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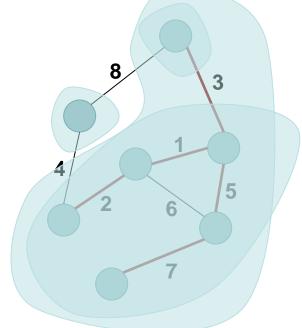
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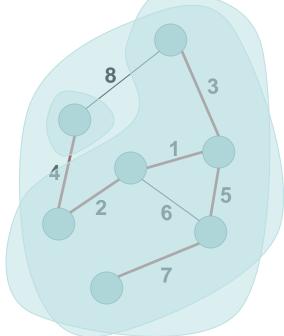


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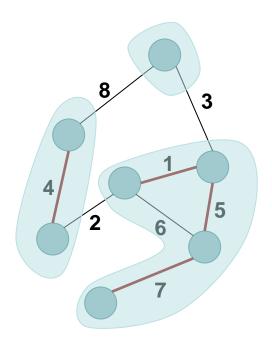
(property 2)



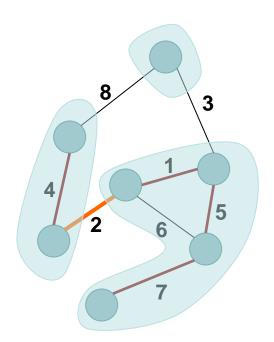
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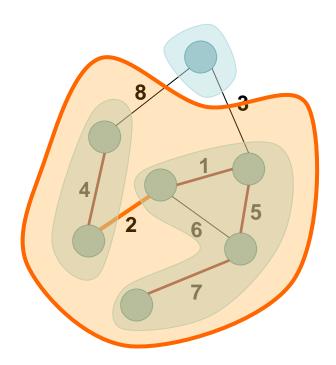
- Fragments
 - Every node starts as a single fragment.



- Fragments
 - Each fragment finds its minimum outgoing edge.

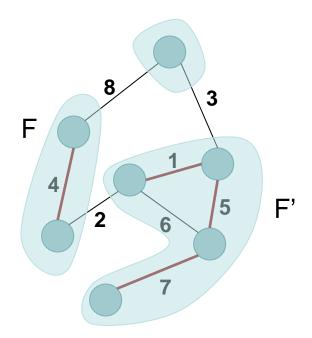


- Fragments
 - Each fragment finds its minimum outgoing edge.
 - Then it tries to combine with the adjacent fragment.



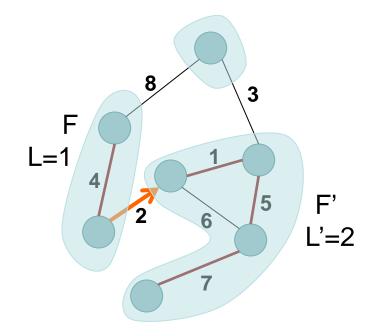
- Levels
 - Every fragment has an associated level that has impact on combining fragments.
 - A fragment with a single node is defined to to be at level 0.

- Levels
 - The combination of two fragments depends on the levels of fragments.



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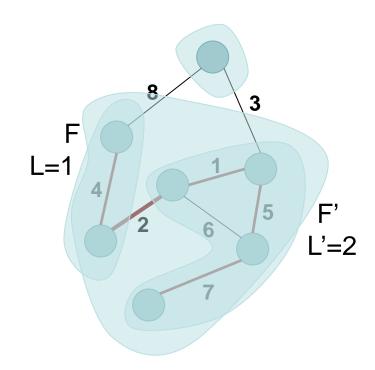
If a fragment F wishes to connect to a fragment F' and L < L' then:



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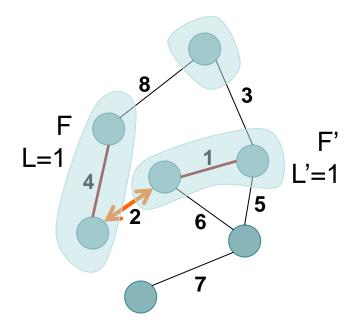
If a fragment F wishes to connect to a fragment F' and L < L' then:

F is absorbed in F' and the resulting fragment is at level L'.



- Levels
 - The combination of two fragments depends on the levels of fragments.

If fragments F and F' have the same minimum outgoing edge and L = L' then:

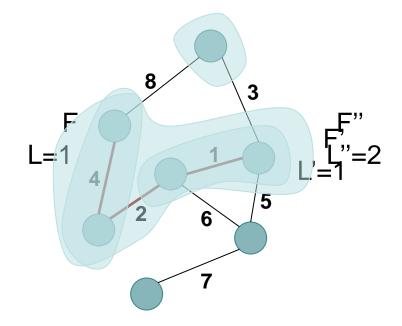


The idea of Distributed MST

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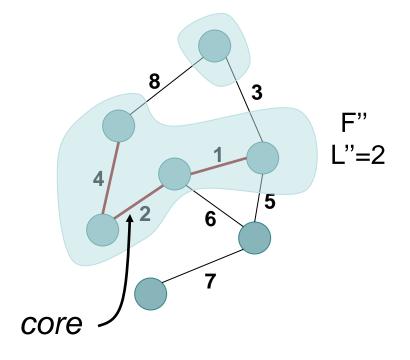
The fragments combine into a new fragment F" at level L" = L+1.



The idea of Distributed MST

- Levels
 - The identity of a fragment is the weight of its core.

If fragments F and F' with same level were combined, the combining edge is called the core of the new segment.



The idea of Distributed MST

- State
 - Each node has a state

Sleeping - initial state

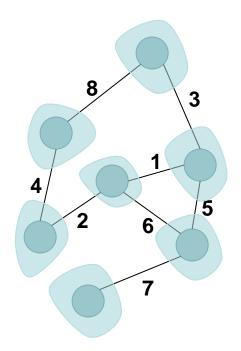
Find - during fragment's search for a minimal outgoing edge

Found - otherwise (when a minimal outgoing edge was found

Outline

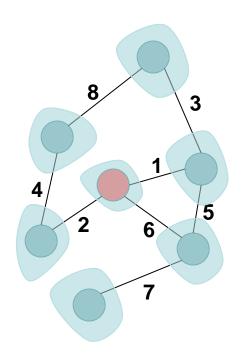
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 - Special case of zero-level fragment (*Sleeping*).



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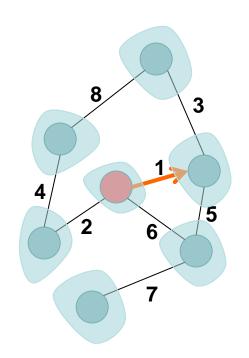
When a node awakes from the state **Sleeping**, it finds a minimum edge connected.



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When a node awakes from the state **Sleeping**, it finds a minimum edge connected.

Marks it as a **branch** of MST and sends a **Connect** message over this edge.

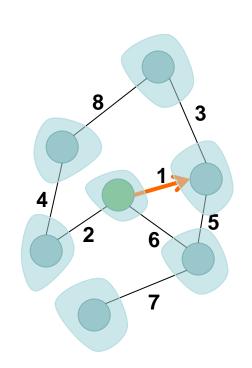


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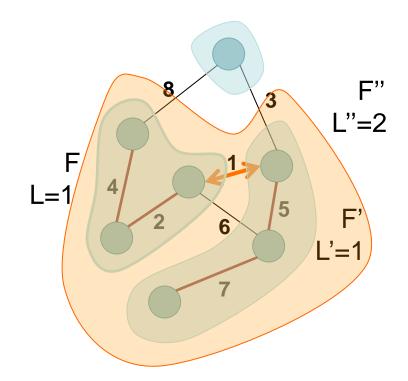
When a node awakes from a state **Sleeping**, it finds a minimum edge connected.

Marks it as a **branch** of MST and sends a **Connect** message over this edge.

Goes into a **Found** state.



- Minimum outgoing edge discovery
 - Take a fragment at level L that was just combined out of two level L-1 fragments.

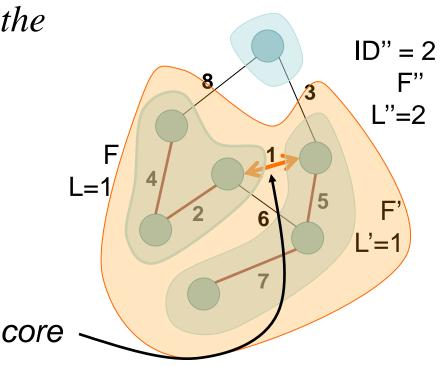


- Minimum outgoing edge discovery
 - Take a fragment at level L that was just combined out of two level L-1 fragments.

The weight of the core is the identity of the fragment.

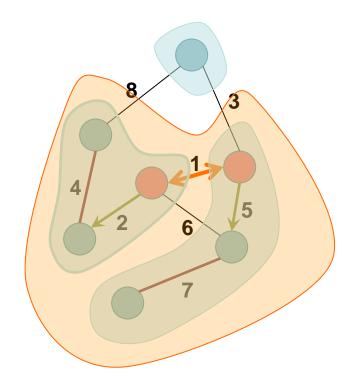
It gots as a root of a

It acts as a root of a fragment tree.



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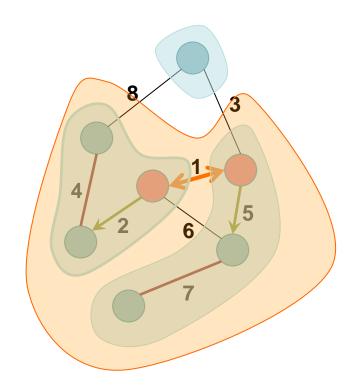
Nodes adjacent to core send an **Initiate** message to the borders.



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Relayed by the intermediate nodes in the fragment.

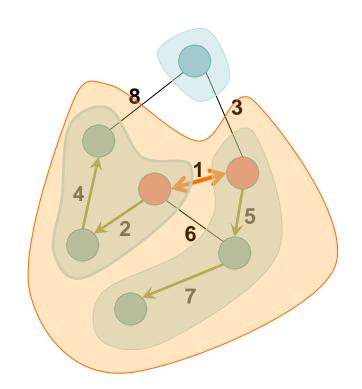


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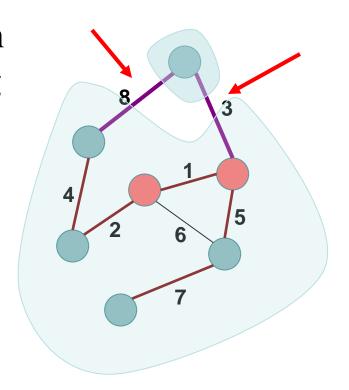
Relayed by the intermediate nodes in the fragment.

Puts the nodes in the **Find** state.



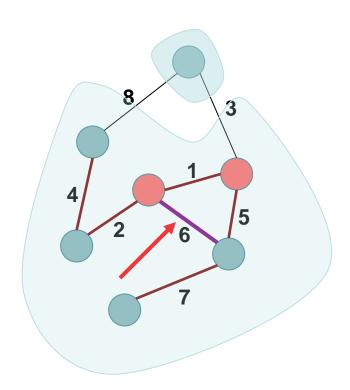
- Minimum outgoing edge discovery
 - Edge classification/

Basic - yet to be classified, can be inside fragment or outgoing edges



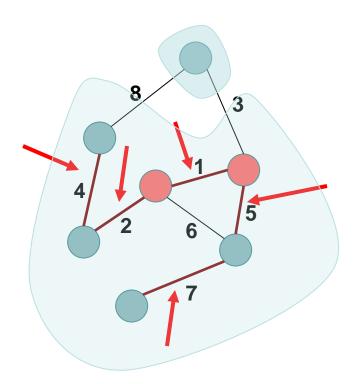
- Minimum outgoing edge discovery
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Rejected – an inside fragment edge



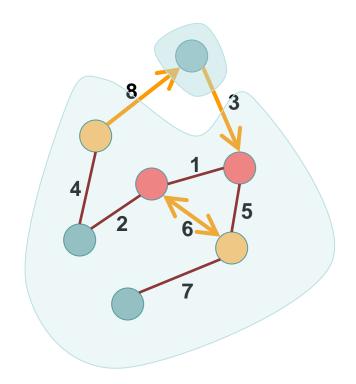
- Minimum outgoing edge discovery
 - Edge classification.

Branch – an MST edge



- Minimum outgoing edge discovery
 - On receiving the *Initiate* message a node tries to find a minimum outgoing edge.

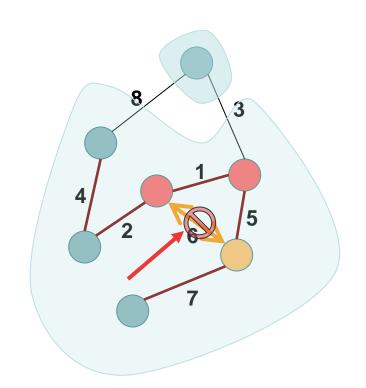
Sends a **Test** message on **Basic** edges (minimal first)



- Minimum outgoing edge discovery
 - On receiving the *Test* message.

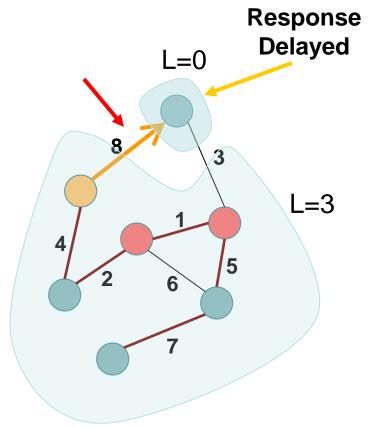
In case of same identity: send a **Reject** message, the edge is **Rejected**.

In case **Test** was sent in both directions, the edge is **Rejected** automatically without a **Reject** message.



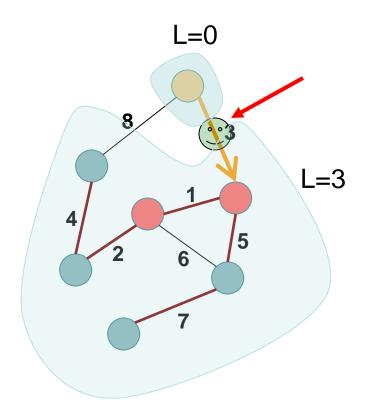
- Minimum outgoing edge discovery
 - On receiving the *Test* message.

In case of a self lower level: Delay the response until the identity rises sufficiently.



- Minimum outgoing edge discovery
 - On receiving the *Test* message.

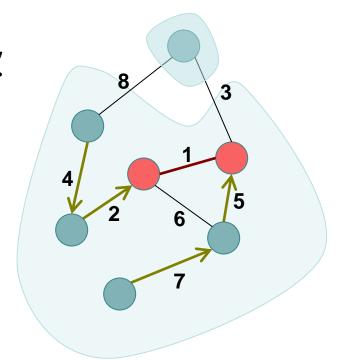
In case of a self higher level:
Send an Accept message
The edge is accepted as a candidate.



- Minimum outgoing edge discovery
 - Agreeing on the minimal outgoing edge.

Nodes send **Report** messages along the branches of the MST.

If no outgoing edge was found the algorithm is complete.

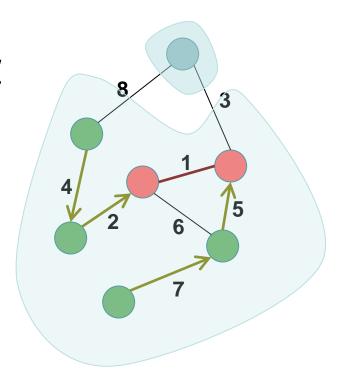


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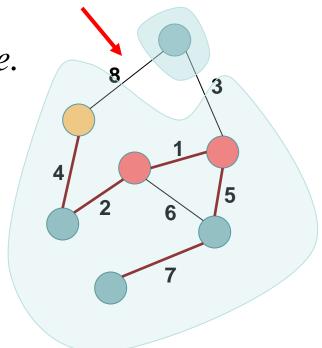
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After sending they go into **Found** mode.



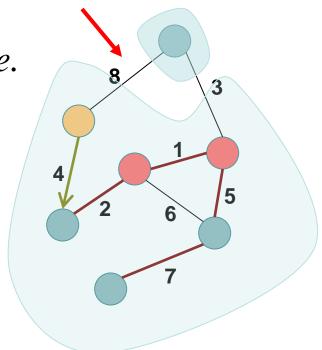
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Every leaf sends the **Report** when resolved its outgoing edge.



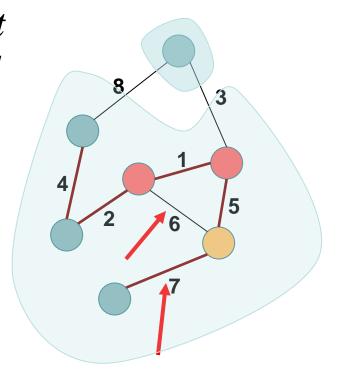
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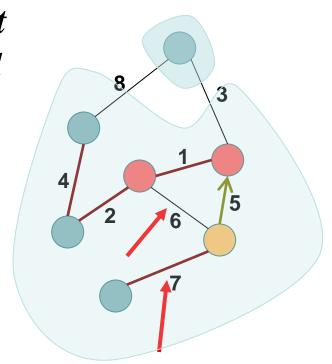
- Minimum outgoing edge discovery
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Every interior sends the **Report** when resolved its outgoing and all its children sent theirs.



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Every node remembers the branch to the minimal outgoing edge of its sub-tree, denoted best-edge.

best-edge

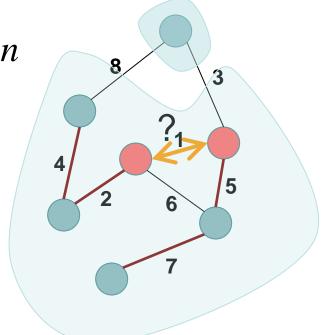
minimal outgoing

edge of its sub-tree, denoted

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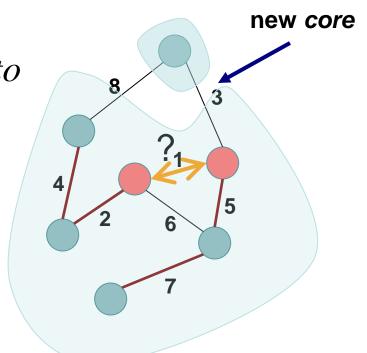
The core adjacent nodes exchange **Reports** and decide on the minimal outgoing edge.



- Combining segments
 - Changing core.

When decided a **Change-core** message is sent over branches to the minimal outgoing edge.

The tree **branches** point to the new core.

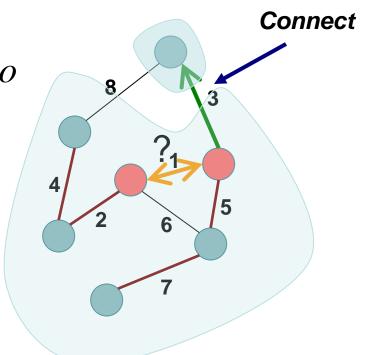


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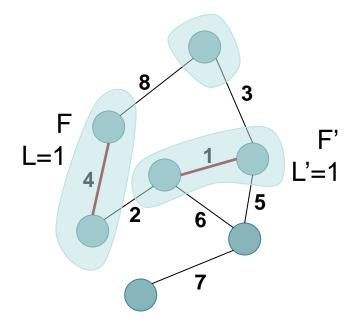
When decided a **Change-core** message is sent over branches to the minimal outgoing edge.

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Finally a **Connect** message is sent over the minimal edge.



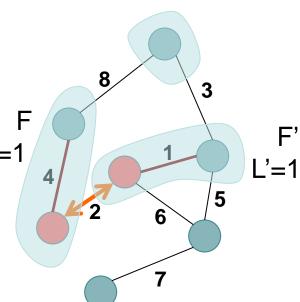
- Final notes
 - Connecting same level fragments.



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Both core adjacent nodes send a **Connect** message, which causes the level to be increased.

As a result, core is changed and L=1 new **Initiate** messages are sent.



- Final notes
 - Connecting lower level fragments.

When lower level fragment F' at node n' joins some fragment F at node n before n sent its **Report.**

We can send n' an **Initiate** message with the **Find** state so it joins the search.

- Final notes
 - Connecting lower level fragments.

When lower level fragment F' at node n' joins some fragment F at node n after n sent its **Report.**

It means that n already found a lower edge and therefore we can send n' an **Initiate** message with the **Found** state so it <u>doesn't</u> join the search.

- Final notes
 - Forwarding the *Initiate* message at level L.

When forwarding an **Initiate** message to the leafs, it is also forwarded to any pending fragments at level L-1, as they might be delayed with response.

- Final notes
 - Upper bound on fragment levels.

Level L+1 contains at least 2 fragments at level L.

Level L contains at least 2^L nodes. $\log_2 N$ is an upper bound on fragment levels.

- Proof outline
 - Correct MST build-up

The Connect message is sent on the minimal outgoing edge only.

As a result of properties 1 & 2 we should obtain an MST.

- Proof outline
 - No deadlocks

Assume there is a deadlock.

Choose a fragment from the lowest level set and with minimal outgoing edge in that set.

Its Test/Connect message surely will be replied.

There will always be a working fragment.

- Complexity
 - Communication

At most E **Reject** messages (with corresponding E **Test** messages, because each edge can be rejected only once.

- Complexity
 - Communication

At every but the zero or last levels, each node can accept up to 1 **Initiate**, **Accept** messages. It can transmit up to 1 **Test** (**successful**), **Report**, **ChangeRoot**, **Connect**. Since the number of levels is bounded by $\log_2 N$ number of such messages is at most $5N(\log_2 N - 1)$.

- Complexity
 - Communication

At level zero, each node receives at most one **Initiate** and transmits at most one **Connect**. At the last level a node can send at most one **Report** message, as a result at most 3N such messages.

- Complexity
 - Communication

As a result, the upper bound is: $5N \log_2 N + 2E$.

- Complexity
 - Time (under assumption of initial awakening it is $5N \log_2 N$)

We prove by induction that one needs 5lN - 3N time units for every node to reach level l.

- Complexity
 - Time (under assumption of initial awakening it is $5N \log_2 N$)
 - $l=1 \Rightarrow$ Each node is awakened and sends a **Connect** message. By time 2N all nodes should be at level 1.

- Complexity
 - Time (under assumption of initial awakening it is $5N \log_2 N$)

Assume $l \rightarrow At$ level l, each node can send at most N **Test** messages which will be answered before time 51N - N. The propagation of the **Report** messages, **ChangeRoot**, **Connect**, and **Initiate** messages can take at most 3N units, so that by time 5(l+1)N - 3N all nodes are at level l+1.

- Complexity
 - Time (under assumption of initial awakening it is $5N \log_2 N$)

At the highest level only **Test, Reject,** and **Report** messages are used.

- Complexity
 - Time (under assumption of initial awakening it is $5N \log_2 N$)

As a result we have the algorithm complete under $5N\log_2 N$ time units.