

# Magnetorotational instability: a review

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The abstract goes here like this.

## 1. Introduction

Background info

What is MRI? Accretion disks? Maybe provide references to explain relevance of MRI to birth of stars, geophysics, etc.

Also outline what the report will cover (probably as the last paragraph).

### 1.1. Example citations

General papers: Julien & Knobloch (2010), Chandrasekhar (1960), Acheson & Hide (1973), Balbus & Hawley (1991)

Experiments: Gailitis *et al.* (2002), Sisan *et al.* (2004), Stefani *et al.* (2006), Stefani *et al.* (2007), Ji (2010), Seilmayer *et al.* (2012)

Numerical simulations: Kageyama *et al.* (2004), Liu (2008), Gissinger *et al.* (2011), Travnikov *et al.* (2011), Kirillov *et al.* (2012), Zhao & Zikanov (2012)

## 2. Physical Explanation

Physical explanation of magnetohydrodynamic (MHD) equations, concept of "frozen-in-field", analogy of magnetic and string tension, main idea of MRI

## 3. Theoretical Work

Acheson & Hide (1973) and Knobloch (1992) showed the linear stability analysis of rotating magneto-fluid bounded in coaxial cylinder. For the case of gaseous astrophysical disks in unbounded geometry was shown in Balbus & Hawley (1991). The condition for stability was shown to be radially increasing angular velocity profile. We present a linear stability analysis of MRI for bounded case following Acheson (1972), Acheson (1973), Knobloch (1992) and Julien & Knobloch (2010).

### 3.1. Governing equation

The wave dispersion equation of a cylindrical magneto-fluid can be obtained from the magnetohydrodynamic (MHD) equations. Assuming the fluid is inviscid and perfectly

conducting, the ideal MHD equations are

$$\rho \left( \frac{\partial \mathbf{u}}{\partial t} + \mathbf{u} \cdot \nabla \mathbf{u} \right) = -\nabla p + \mathbf{J} \times \mathbf{B} \quad (3.1)$$

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \mathbf{u}) = 0 \quad (3.2)$$

$$\mathbf{E} + \mathbf{u} \times \mathbf{B} = 0 \quad (3.3)$$

$$\nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t} \quad (3.4)$$

$$\nabla \times \mathbf{B} = \mu \mathbf{J}. \quad (3.5)$$

To investigate MRI, one can consider homogeneous incompressible fluid rotating with angular velocity  $\Omega(r) = \frac{V(r)}{r}$  in externally imposed magnetic fields  $\mathbf{B}_0 = [0, B_\phi(r), B_z(r)]$ . Combining electromagnetic equations with momentum relation, we get the appropriate MHD equations,

$$\frac{\partial \mathbf{u}}{\partial t} + (\mathbf{u} \cdot \nabla) \mathbf{u} = -\frac{1}{\rho} \nabla \left( P + \frac{\mathbf{B}^2}{2\mu} \right) + \frac{1}{\mu\rho} (\mathbf{B} \cdot \nabla) \mathbf{B} \quad (3.6)$$

$$\frac{\partial \mathbf{B}}{\partial t} + (\mathbf{u} \cdot \nabla) \mathbf{B} = (\mathbf{B} \cdot \nabla) \mathbf{u} \quad (3.7)$$

$$\nabla \cdot \mathbf{u} = 0 \quad (3.8)$$

$$\nabla \cdot \mathbf{B} = 0 \quad (3.9)$$

### 3.2. Linear perturbation equation and eigenvalue problem

We can get linearized equations by perturbing the basic state by small amount of  $\mathbf{u}_1$  and  $\mathbf{b}_1$  for velocity and magnetic fields. The axisymmetric perturbation is assumed to have the form

$$\psi = \Re \left[ \hat{\psi}(r) e^{i(kz - \omega t)} \right]. \quad (3.10)$$

According to Acheson (1972), the normal mode equations are

$$-i\omega \hat{b}_r = ik B_z \hat{u}_r \quad (3.11)$$

$$-i\omega \hat{b}_\phi = -\frac{d}{dr}(\hat{u}_r B_\phi) + ik(\hat{u}_\phi B_z - \hat{u}_z B_\phi) \quad (3.12)$$

$$-i\omega \hat{b}_z = -\frac{1}{r} \frac{d}{dr}(r \hat{u}_r B_z) \quad (3.13)$$

$$ik \hat{u}_z = -\frac{1}{r} \frac{d}{dr}(r \hat{u}_r) \quad (3.14)$$

$$i(\omega^2 - k^2 V_{Az}^2) \hat{u}_\phi = \frac{\hat{u}_r}{r} (2\Omega r \omega + 2k V_{A\phi} V_{Az}) \quad (3.15)$$

where  $V_{A\phi} = \frac{B_\phi(r)}{\sqrt{\mu\rho}}$ ,  $V_{Az} = \frac{B_z(r)}{\sqrt{\mu\rho}}$  are Alfvén speeds for associated external magnetic field components.

Solving the normal mode equation set for radial velocity perturbation  $\hat{u}_r = u$ , Acheson (1973) obtained following eigenvalue problem,

$$\begin{aligned} \frac{d}{dr} \left[ (\omega^2 - k^2 V_{Az}^2) \left( \frac{du}{dr} + \frac{u}{r} \right) \right] - k^2 \left[ \omega^2 - k^2 V_{Az}^2 + r \frac{d}{dr} \left( \frac{V_{A\phi}^2}{r^2} - \frac{V^2}{r^2} \right) \right] u \\ = -\frac{4k^2}{r^2} \frac{(k V_{A\phi} V_{Az} + \omega V)^2}{(\omega^2 - k^2 V_{Az}^2)} u. \end{aligned} \quad (3.16)$$

### 3.3. Stability criterion

#### 3.3.1. Standard magnetorotational instability

Consider a standard MRI of radially bounded coaxial fluid cylinder with externally imposed axial magnetic field but without axial current flowing. Therefore, we have  $V_{Az} = \frac{B_z}{\sqrt{\rho\mu}} = \text{const} \neq 0$  and  $V_{A\phi} = \frac{B_\phi}{\sqrt{\rho\mu}} = 0$ . Considering boundary condition  $u(r_1) = u(r_2) = 0$ , we multiply the eigenvalue equation by complex conjugate of  $u$  and integrate over radial coordinate,

$$(\omega^2 - k^2 V_{Az}^2)^2 = \frac{k^2}{D} \int_{r_1}^{r_2} \left[ \frac{\omega^2}{r^2} \frac{d}{dr} r^2 V^2 - r^2 k^2 V_{Az}^2 \frac{d}{dr} \left( \frac{V^2}{r^2} \right) \right] |u|^2 dr \quad (3.17)$$

where

$$D \equiv \int_{r_1}^{r_2} \left( r \left| \frac{du}{dr} \right|^2 + \frac{|u|^2}{r} + k^2 r |u|^2 \right) dr > 0 \quad (3.18)$$

According to Chandrasekhar (1960),  $\omega^2$  must be real. We get stable modes with  $\omega^2 > 0$  and unstable modes with  $\omega^2 < 0$ . If the angular velocity increases radially outward,  $\frac{d}{dr} \left( \frac{V^2}{r^2} \right) > 0$ , the system is stable because  $\omega^2$  is bounded from below by positive number,

$$\omega^2 > \frac{r^2 k^2 V_{Az}^2 \frac{d}{dr} \left( \frac{V^2}{r^2} \right)}{4 \frac{V^2}{r} + r^2 \frac{d}{dr} \left( \frac{V^2}{r^2} \right)} > 0. \quad (3.19)$$

If we have radially decreasing angular velocity profile,  $\frac{d}{dr} \left( \frac{V^2}{r^2} \right) < 0$ , somewhere  $r_1 < r < r_2$ , then  $\omega^2$  may have negative solution which makes the system unstable.

#### 3.3.2. Helical magnetorotational instability

When the external nonzero magnetic fields in axial and azimuthal directions are considered, it was found that the eigenvalue equation can be written as

$$\frac{d}{dr} r \frac{du}{dr} - \frac{u}{r} - k^2 r u = \frac{k^2}{(\omega^2 - k^2 V_{Az}^2)^2} \left[ r^2 \frac{d}{dr} \left( \frac{V_{A\phi}^2 - V^2}{r^2} \right) (\omega^2 - k^2 V_{Az}^2) - \frac{4}{r} (k V_{A\phi} V_{Az} - \omega V)^2 \right] u \quad (3.20)$$

According to Knobloch (1992) and Julien & Knobloch (2010), the exponentially growing mode  $\omega = -i\lambda$ ,  $\lambda > 0$  is possible when the eigenvalue relation has following form

$$(\lambda^2 + k^2 V_{Az}^2)^2 = \frac{k^2}{D} \int_{r_1}^{r_2} \left[ r^2 \frac{d}{dr} \left( \frac{V_{A\phi}^2 - V^2}{r^2} \right) (\lambda^2 + k^2 V_{Az}^2) + \frac{4}{r} (k V_{A\phi} V_{Az} - i\lambda V)^2 \right] |u|^2 dr. \quad (3.21)$$

Considering the imaginary part of the equation, we have

$$\int_{r_1}^{r_2} \frac{1}{r} V_\phi V |u|^2 dr = 0 \quad (3.22)$$

Knobloch (1992) shows exponentially growing instability is only possible when  $V_{A\phi}$  or  $V$  changes sign somewhere in  $r_1 < r < r_2$ .

## 4. Laboratory Experiments

Discuss on experimental work that has been done related to this topic.

Try to categorize experiments so we can group the discussion. Also, the main focus is to explain what has been done to attempt to recreate MRI in the lab.

NOTE: most literature on MRI experiments seem to be about either 1) axial-only magnetic fields (standard MRI) or 2) axial and azimuthal magnetic fields (helical MRI).

## 5. Numerical Work

Have there been any numerical experiments done that involve the topic.

There's probably numerical simulations of both standard and helical MRI that have already been tested in the lab, but there may also be more large-scale simulations (e.g. planet-scale).

## 6. Conclusion

Concluding remarks

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