DAVID PORFIRIO

Assistant Professor (incoming) Computer Science Department George Mason University Fairfax, VA 22030 Email: dporfiri@gmu.edu
Website: https://dporfirio.github.io/
Google Scholar

RESEARCH INTERESTS

My research intersects *robotics*, *human-computer interaction*, and *artificial intelligence*, in order to design and evaluate innovative technology that enables human-robot task communication. This is *important* because of the enormous potential that robots have to positively impact daily life. However, this is *difficult* because robots struggle to capture and understand human needs.

EDUCATION

PhD	University of Wisconsin–Madison (UW–Madison), Madison, WI, USA Computer Sciences	2018-2022
MSc	UW–Madison, Madison, WI, USA Computer Sciences	2016-2018
BS	University of Arizona, Tucson, AZ, USA Double degree (hon) in computer science and physiology Minor in mathematics Summa cum laude	2011-2016

RESEARCH POSITIONS

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George	Macon	Unive	rcitv

Assistant Professor (tenure track)

Computer Science Department

College of Engineering and Computing

US Naval Research Laboratory

Computer Scientist 2024-2025

Adaptive Systems Section

Navy Center for Applied Research in Artificial Intelligence

NRC Postdoctoral Research Associate 2022-2024

Adaptive Systems Section

Navy Center for Applied Research in Artificial Intelligence

Advisor: Dr. Laura Hiatt

UW-Madison

Doctoral Student 2016-2022

People and Robots Laboratory Computer Sciences Department

Advisors: Drs. Bilge Mutlu & Aws Albarghouthi

Thesis: Authoring Social Interactions Between Humans and Robots

Committee: Drs. Bilge Mutlu, Aws Albarghouthi, Maya Cakmak, & Kevin Ponto

Nokia Bell Labs

Research Intern Summer 2021

New Providence, NJ, USA (Virtual)

Mentors: Drs. Martin Carroll, Kedar Namjoshi, Itai Segall

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University of Arizona

Undergraduate Research Assistant 2015-2016

Department of Computer Science Advisor: Dr. John Kececioglu

Student, Undergraduate Biology Research Program Summer 2014

Department of Ecology and Evolutionary Biology

Advisor: Dr. Joanna Masel

Student, Undergraduate Biology Research Program 2013-2014

Department of Physiology Advisor: Dr. E. Fiona Bailey

Conference Papers

I primarily publish in top-tier venues in human-robot interaction, human-computer interaction, and artificial intelligence, including HRI, CHI, UIST, and AAMAS.

Porfirio, D., Hsiao, V., Fine-Morris, M., Smith, L., & Hiatt, L. Bootstrapping Human-Like Planning via LLMs. In Proceedings of the 2025 International Conference on Robot and Human Interactive Communication. In press.

Porfirio, D., Roberts, M., & Hiatt, L. (2025, May). Uncertainty Expression for Human-Robot Task Com-Acceptance munication. In Proceedings of the 24th International Conference on Autonomous Agents and Multiagent Systems (pp. 1698-1707).

Lee, C., Porfirio, D., Wang, J., Zhao, K., & Mutlu, B. (2025, April). VeriPlan: Integrating Formal Verification and LLMs into End-User Planning. In Proceedings of the 2025 CHI Conference on Human Factors in Computing Systems (pp. 1-19).

Porfirio, D., Roberts, M., & Hiatt, L. M. (2025, March). An Interaction Specification Language for Robot Application Development. In 2025 ACM/IEEE International Conference on Human-Robot Interaction (HRI). Best Short Contribution Award

Stegner, L., Hwang, Y., **Porfirio**, **D.**, & Mutlu, B. (2024, July). Understanding On-the-Fly End-User Robot Programming. In Proceedings of the 2024 ACM Designing Interactive Systems Conference (pp. 2468-2480).

Porfirio, D., Roberts, M., & Hiatt, L. (2024, March). Goal-Oriented End-User Programming of Robots. In Proceedings of the 2024 ACM/IEEE International Conference on Human-Robot Interaction (pp. 582-591). NRC/ASEE Postdoctoral Research Publications Award

Porfirio, D., Stegner, L., Cakmak, M., Sauppé, A., Albarghouthi, A., & Mutlu, B. (2023, March). Sketching Robot Programs On the Fly. In 2023 18th ACM/IEEE International Conference on Human-Robot Interaction (HRI). ACM/IEEE.

Porfirio, D., Stegner, L., Cakmak, M., Sauppé, A., Albarghouthi, A., & Mutlu, B. (2021, May). Figaro: A Tabletop Authoring Environment for Human-Robot Interaction. In Proceedings of the 2021 Conference on Human Factors in Computing Systems (CHI) (pp. 1-15).

Porfirio, D., Sauppé, A., Albarghouthi, A., & Mutlu, B. (2020, April). Transforming robot programs based on social context. In Proceedings of the 2020 conference on human factors in computing systems (CHI) (pp. 1-12).

Porfirio, D., Fisher, E., Sauppé, A., Albarghouthi, A., & Mutlu, B. (2019, October). Bodystorming human-robot interactions. In Proceedings of the 32nd Annual ACM Symposium on User Interface Software and Technology (UIST) (pp. 479-491). ACM.

rate: 24.5%

Acceptance rate: 25.1%

Acceptance rate: 43.5%

Acceptance rate: 25%

Acceptance rate: 25%

Acceptance rate: 25%

Acceptance rate: 26%

Acceptance rate: 24%

Acceptance rate: 24% 11. **Porfirio, D.**, Sauppé, A., Albarghouthi, A., & Mutlu, B. (2018, October). Authoring and verifying human-robot interactions. In The 31st Annual ACM Symposium on User Interface Software and Technology (UIST) (pp. 75-86). ACM. *Best Paper Award*

Acceptance rate: 21%

JOURNAL PAPERS

- 1. Hwang, Y., Lee, C., **Porfirio, D.**, Hiatt, L. M., and Mutlu, B., "Formal Methods in Robot End-User Development: Progress, Gaps, and Opportunities". *Under review.*
- 2. Xiong, K., McEntee, J. P., **Porfirio, D. J.**, & Masel, J. (2017). Drift barriers to quality control when genes are expressed at different levels. Genetics, 205(1), 397-407.
- 3. Shumway, K. R., **Porfirio, D. J.**, & Bailey, E. F. (2015). Phonation-related rate coding and recruitment in the genioglossus muscle. Experimental brain research, 233(7), 2133-2140.

Workshop and Special Session Papers

- 1. Praveena, P., Schoen, A., Gleicher, M., **Porfirio, D.**, & Mutlu, B. (2023, October). Petri Nets for the Iterative Development of Interactive Robotic Systems. In 2023 AAAI Fall Symposium Series on *Unifying Representations for Robot Application Development* (UR-RAD).
- 2. Stegner, L., **Porfirio, D.**, Roberts, M., & Hiatt, L. (2023, October). Considerations for End-User Development in the Caregiving Domain. In 2023 AAAI Fall Symposium Series on *Unifying Representations for Robot Application Development* (UR-RAD).
- 3. **Porfirio, D.**, Roberts, M., & Hiatt, L. (2023, August). Guidelines for a Human-Robot Interaction Specification Language. In 2023 IEEE International Symposium on Robot and Human Interactive Communication Special Session on *HRI in Academia and Industry: Bridging the Gap.* IEEE.
- 4. **Porfirio, D.**, Roberts, M., & Hiatt, L. (2023, March). On a Standardized Logical Representation for Human-Robot Interaction. In 2023 AAAI Spring Symposium, *HRI in Academia and Industry: Bridging the Gap. Best Paper Nominee*
- 5. **Porfirio, D.**, Sauppé, A., Cakmak, M., Albarghouthi, A., & Mutlu, B. (2023, March). Crowdsourcing Task Traces for Service Robotics. In 2023 18th ACM/IEEE International Conference on Human-Robot Interaction (HRI).
- 6. Pelikan, H., **Porfirio, D.**, Winkle, K. (2023, March). Designing Better Human-Robot Interactions through Enactment, Engagement, and Reflection. In 2023 18th ACM/IEEE International Conference on Human-Robot Interaction Workshop on *Human-Robot Conversational Interaction* (CUI@HRI).
- 7. **Porfirio, D.**, Cakmak, M., Sauppé, A., Albarghouthi, A., & Mutlu, B. (2021, May). Interaction Templates: A Data-Driven Approach for Authoring Robot Programs. In 2021 12th Annual Workshop on Evaluation and Usability of Programming Languages and Tools (PLATEAU).
- 8. **Porfirio, D.**, Sauppé, A., Albarghouthi, A., & Mutlu, B. (2019, March). Computational Tools for Human-Robot Interaction Design. In 2019 14th ACM/IEEE International Conference on Human-Robot Interaction (HRI) (pp. 733-735). IEEE.

Acceptance rate: 31%

GRANTS AND GIFTS

Jerome and Isabella Karle Distinguished Scholar

2024-2025

Awarded \$25,000 for equipment and travel at the U.S. Naval Research Laboratory

Microsoft Dissertation Grant

2021

Awarded \$21,148 for dissertation research

Quori Robot Program Co-authored a winning proposal that secured a robot donation for UW–Madison.	2018	
Galileo Circle Scholar Gifted \$1,000 from UA donors for research accomplishments	2015	
FELLOWSHIPS		
Jerome and Isabella Karle Distinguished Scholar Supports a full-time appointment at the U.S. Naval Research Laboratory	2024-2025	
NRC Postdoctoral Research Fellowship Stipend with travel support at the U.S. Naval Research Laboratory	2022-2024	
Cisco Graduate Student Fellowship Selected by the UW–Madison Computer Sciences Department	2021-2022	
NSF Graduate Research Fellowship Stipend at the UW–Madison Computer Sciences Department	2017-2022	
Advanced Opportunity Fellowship Selected by the UW–Madison Computer Sciences Department	2016, 2020	
Honors and Awards		
NRC/ASEE Postdoctoral Research Publications Award For my HRI '24 paper on Goal-Oriented End-User Programming of Robots	2025	
Best Paper Award HRI '25, Short Contributions	2025	
Best Paper Nominee 2023 AAAI Spring Symposium, <i>HRI in Academia and Industry: Bridging the Gap</i>	2023	
Robotics Perception and Learning Summer School, KTH Royal Institute of Technology Invited to attend	2022	
Microsoft Research AI Breakthroughs Invited to participate as a young researcher	2020	
Heidelberg Laureate Forum Invited to attend as a young researcher	2019	
HRI Pioneers Invited to participate as a young researcher	2019	
Best Paper Award UIST '18	2018	
Excellence in Undergraduate Research Award Selected by the UA Department of Computer Science	2016	
Galileo Circle Scholar Selected by the UA Department of Computer Science	2015	
National Hispanic Scholar Selected by the National Hispanic Recognition Program	2011	
Dean's List with Distinction Awarded during six semesters at UA	2011-2016	

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TEACHING EXPERIENCE

George Mason University Fall 2025 - CS 690, Evaluating Generative AI Systems. Fall 2025. Fall 2024 Guest Lecturer, University of Maryland, College Park - CMSC 722, AI Planning. Fall 2024. **Grandparents University Instructor, UW** Summers 2018-2019 Duties: designing and teaching two-day lecture and lab sessions for UW alumni families. - Social Robotics. July 2019. - Social Robotics. July 2018. **Teaching Assistant, UA** Summer 2015 Duties: holding office hours and grading assignments - CSC 352, Systems Programming and Unix. Summer 2015. Section Leader, UA Fall 2014 - Spring 2015 Duties: teaching lab sessions, holding office hours, and grading assignments - CSC 245, Introduction to Discrete Structures. Fall 2015. - CSC 127B, Introduction to Computer Science II. Spring 2015. - CSC 227, Program Design and Development. Fall 2014. Student Preceptor, UA Spring 2012 Duties: assisting the professor during lectures and holding office hours - CHEM 151, Chemical Thinking I. Spring 2012. INVITED TALKS **George Mason University** April 2025 Title: End-User Development for Human Robot Interaction: A Shifting Paradigm HRI Workshop on The Road to Reliable Robots March 2025 Title: Evaluating Systems for Robot Application Development **Johns Hopkins University** April 2024 Title: Robot Application Development: A Shifting Paradigm **Colorado School of Mines** March 2022 Title: Authoring Social Interactions Between Humans and Robots February 2022 **University at Buffalo** Title: Authoring Social Interactions Between Humans and Robots February 2022 **Montana State University** Title: Authoring Social Interactions Between Humans and Robots **Talking Robotics** December 2020 Title: Authoring Social Interactions Between Humans and Robots **UW-Madison**, CS Student Research Symposium April 2019

MENTORSHIP

Ph.D. Committee Member for the Following Students

Title: Applying Formal Methods to Human-Robot Interaction

Saad Elbeleidy (2024)—Colorado School of Mines

Mentor for the Following Students

Evan Conway (2024-Present)—US Naval Research Laboratory

Nhi Tran (2023-2025)—US Naval Research Laboratory

Madeline Forsythe (2024)—US Naval Research Laboratory

Kyle Wang (2019-2022)—UW Madison

Ali Zaidi (2017-2020)—UW Madison

Linda Wu (2019-2020)—UW Madison

Mikayla Buford (2019-2020)—*UW Madison*

Laik Ruetten (2020)—UW Madison

Akshat Khanna (2018-2019)—UW Madison

Zhechun Zhou (2019)—UW Madison

Arabella Yao (2019)—UW Madison

Ezra Boley (2019)—UW Madison

Evan Fisher (2018)—UW Madison

Pranav Rajiv (2017-2018)—UW Madison

Yue Sun (2017)—UW Madison

Raghav Bagwat (2017)—UW Madison

Sherine Zhang (2017)—UW Madison

Jack Weissburg (2017)—*UW Madison*

ACADEMIC SERVICE

Event Organization ACM/IEEE International Conference on Human-Robot Interaction (HRI) Program committee (PC) member	2024-2025			
Unifying Representations for Robot Application Development (AAAI Fall Symposium Series) Chair (2023-2024) and Co-Chair (2025)	2023-2025			
Designing Human-Robot Interactions: A StEER Tutorial (NordiCHI Tutorial) Co-organizer	2024			
End-User Development for Human-Robot Interaction (HRI Workshop) Co-lead organizer				
Participatory Design and End-User Programming for Human-Robot Interaction (HRI Workshop) Co-organizer	2021			
Referee Service				
HRI - ACM/IEEE International Conference on Human-Robot Interaction	2020-2025			
CHI - ACM Conference on Human Factors in Computing Systems	2022, 2024-2025			
AAMAS - International Conference on Autonomous Agents and Multiagent Systems	2024-2025			
CogSci - Annual Meeting of the Cognitive Science Society	2024-2025			
ICRA - IEEE International Conference on Robotics and Automation	2024-2025			
THRI - ACM Transactions on Human-Robot Interaction	2020, 2024-2025			
HAI - International Conference on Human-Agent Interaction	2023, 2025			
UIST - ACM Symposium on User Interface Software and Technology	2021, 2025			
RSS - Robotics: Science and Systems	2025			
ECAI - European Conference on Artificial Intelligence	2025			
SORO - International Journal of Social Robotics	2022, 2024			
CSCW - ACM SIGCHI Conference on Computer-Supported Cooperative Work	2022			
TAHRI - International Symposium on Technological Advances in Human-Robot Interaction	2024			
AI-HRI - AAAI Fall Symposium on Artificial Intelligence for Human-Robot Interaction	2021			

TECHNICAL SKILLS

Programming Languages

Python, Golang, Java, Javascript, HTML, CSS, C#, C, PDDL, GDScript

Robotics Tools, Libraries, and Frameworks

ROS1, ROS2, Gazebo Simulator, OpenCV, Unity Game Engine

Robot Platforms

Hello-Robot Stretch 2, Softbank Pepper, Softbank Nao, Temi, iRobot Create 2

Design

Adobe Illustrator, Premiere, & Photoshop. Affinity Designer

AI Planning and Formal Methods

Unified Planning, Z3 Theorem Prover, PRISM Model Checker, NuSMV Model Checker

Data Visualization

Matplotlib, D3.js

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