# **David Porfirio**

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Google Scholar

# RESEARCH INTERESTS

My research intersects *user experience*, *robotics*, and *artificial intelligence*, in order to design and evaluate innovative user interfaces that enable seamless human-robot task communication. This is *important* because of the enormous potential that robots have to positively impact daily life. However, this is *difficult* because humans struggle to articulate their needs.

# **EDUCATION**

PhD	University of Wisconsin–Madison (UW–Madison), Madison, WI, USA Computer Sciences	2018-2022
MSc	UW-Madison, Madison, WI, USA Computer Sciences	2016-2018
BS	University of Arizona (UA), Tucson, AZ, USA Double degree (hon) in computer science and physiology Minor in mathematics Summa cum laude	2011-2016

Work & Research Experience				
Computer Scientist Adaptive Systems Section Navy Center for Applied Research in Artificial Intelligence United States Naval Research Laboratory	2024-Present			
NRC RAP Postdoctoral Fellow Adaptive Systems Section Navy Center for Applied Research in Artificial Intelligence United States Naval Research Laboratory Advisor: Dr. Laura Hiatt	2022-2024			
Doctoral Research People and Robots Laboratory UW-Madison Computer Sciences Department Advisors: Drs. Bilge Mutlu & Aws Albarghouthi Committee: Drs. Bilge Mutlu, Aws Albarghouthi, Maya Cakmak, & Kevin Ponto Thesis: Authoring Social Interactions Between Humans and Robots	2016-2022			
Research Intern Nokia Bell Labs, New Providence, NJ, USA (Virtual) Mentors: Drs. Martin Carroll, Kedar Namjoshi, Itai Segall	Summer 2021			
Undergraduate Senior Thesis UA Department of Computer Science Advisor: Dr. John Kececioglu	2015-2016			
Undergraduate Research UA Department of Computer Science	2013-2014			

Advisors: Drs. E. Fiona Bailey and Joanna Masel

# FULL PAPERS

- 13. **Porfirio, D.**, Hsiao, V., Fine-Morris, M., Smith, L., & Hiatt, L. Bootstrapping Human-Like Planning via LLMs. In Proceedings of the 2025 International Conference on Robot and Human Interactive Communication. *Under review*.
- 12. Lee, C., **Porfirio, D.**, Wang, J., Zhao, K., & Mutlu, B. (2025, April). VeriPlan: Integrating Formal Verification and LLMs into End-User Planning. In Proceedings of the 2025 Conference on Human Factors in Computing Systems (CHI) (in press).

Acceptance rate: 25.1%

11. **Porfirio, D.**, Roberts, M., & Hiatt, L. (2025, May). Uncertainty Expression for Human-Robot Task Communication. In Proceedings of the 24th International Conference on Autonomous Agents and Multiagent Systems (AAMAS) (in press).

Acceptance rate: 24.5%

10. Stegner, L., Hwang, Y., **Porfirio, D.**, & Mutlu, B. (2024, July). Understanding On-the-Fly End-User Robot Programming. In Proceedings of the 2024 ACM Designing Interactive Systems Conference (pp. 2468-2480).

Acceptance rate: 25%

9. **Porfirio, D.**, Roberts, M., & Hiatt, L. (2024, March). Goal-Oriented End-User Programming of Robots. In Proceedings of the 2024 ACM/IEEE International Conference on Human-Robot Interaction (pp. 582-591).

Acceptance rate: 25%

- 8. **Porfirio, D.,** Roberts, M., & Hiatt, L. (2023, August). Guidelines for a Human-Robot Interaction Specification Language. In 2023 IEEE International Symposium on Robot and Human Interactive Communication (RO-MAN) IEEE.
- 7. **Porfirio, D.**, Stegner, L., Cakmak, M., Sauppé, A., Albarghouthi, A., & Mutlu, B. (2023, March). Sketching Robot Programs On the Fly. In 2023 18th ACM/IEEE International Conference on Human-Robot Interaction (HRI). ACM/IEEE.

Acceptance rate: 25%

6. **Porfirio, D.**, Stegner, L., Cakmak, M., Sauppé, A., Albarghouthi, A., & Mutlu, B. (2021, May). Figaro: A Tabletop Authoring Environment for Human-Robot Interaction. In Proceedings of the 2021 Conference on Human Factors in Computing Systems (CHI) (pp. 1-15).

Acceptance rate: 26%

5. **Porfirio, D.**, Sauppé, A., Albarghouthi, A., & Mutlu, B. (2020, April). Transforming robot programs based on social context. In Proceedings of the 2020 conference on human factors in computing systems (CHI) (pp. 1-12).

Acceptance rate: 24%

4. **Porfirio, D.**, Fisher, E., Sauppé, A., Albarghouthi, A., & Mutlu, B. (2019, October). Bodystorming human-robot interactions. In Proceedings of the 32nd Annual ACM Symposium on User Interface Software and Technology (UIST) (pp. 479-491). ACM.

Acceptance rate: 24%

3. **Porfirio, D.**, Sauppé, A., Albarghouthi, A., & Mutlu, B. (2018, October). Authoring and verifying human-robot interactions. In The 31st Annual ACM Symposium on User Interface Software and Technology (UIST) (pp. 75-86). ACM. **Best Paper Award** 

Acceptance rate: 21%

2. Xiong, K., McEntee, J. P., **Porfirio, D. J.**, & Masel, J. (2017). Drift barriers to quality control when genes are expressed at different levels. Genetics, 205(1), 397-407.

Impact factor: 3.564

. Shumway, K. R., **Porfirio, D. J.**, & Bailey, E. F. (2015). Phonation-related rate coding and recruitment in the genioglossus muscle. Experimental brain research, 233(7), 2133-2140.

Impact factor: 2.395

# REFEREED WORKSHOP AND SHORT PAPERS

8. **Porfirio, D.**, Roberts, M., & Hiatt, L. M. (2025, March). An Interaction Specification Language for Robot Application Development. In 2025 ACM/IEEE International Conference on Human-Robot Interaction (HRI). **Best Paper Award** 

Acceptance rate: 54.5%

- 7. Praveena, P., Schoen, A., Gleicher, M., **Porfirio, D.**, & Mutlu, B. (2023, October). Petri Nets for the Iterative Development of Interactive Robotic Systems. In 2023 AAAI Fall Symposium Series on *Unifying Representations for Robot Application Development* (UR-RAD).
- 6. Stegner, L., **Porfirio, D.**, Roberts, M., & Hiatt, L. (2023, October). Considerations for End-User Development in the Caregiving Domain. In 2023 AAAI Fall Symposium Series on *Unifying Representations for Robot Application Development* (UR-RAD).
- 5. **Porfirio, D.**, Roberts, M., & Hiatt, L. (2023, March). On a Standardized Logical Representation for Human-Robot Interaction. In 2023 AAAI Spring Symposium, *HRI in Academia and Industry: Bridging the Gap.* **Best Paper Nominee**
- 4. **Porfirio, D.**, Sauppé, A., Cakmak, M., Albarghouthi, A., & Mutlu, B. (2023, March). Crowdsourcing Task Traces for Service Robotics. In 2023 18th ACM/IEEE International Conference on Human-Robot Interaction (HRI).
- 3. Pelikan, H., **Porfirio, D.**, Winkle, K. (2023, March). Designing Better Human-Robot Interactions through Enactment, Engagement, and Reflection. In 2023 18th ACM/IEEE International Conference on Human-Robot Interaction Workshop on *Human-Robot Conversational Interaction* (CUI@HRI).
- 2. **Porfirio, D.**, Cakmak, M., Sauppé, A., Albarghouthi, A., & Mutlu, B. (2021, May). Interaction Templates: A Data-Driven Approach for Authoring Robot Programs. In 2021 12th Annual Workshop on Evaluation and Usability of Programming Languages and Tools (PLATEAU).
- 1. **Porfirio, D.**, Sauppé, A., Albarghouthi, A., & Mutlu, B. (2019, March). Computational Tools for Human-Robot Interaction Design. In 2019 14th ACM/IEEE International Conference on Human-Robot Interaction (HRI) (pp. 733-735). IEEE.

Acceptance rate: 31%

# GRANTS AND GIFTS

Jerome and Isabella Karle Distinguished Scholar Awarded \$25,000 for equipment and travel at the U.S. Naval Research Laboratory	2024-2025
Microsoft Dissertation Grant Awarded \$21,148 for dissertation research	2021
Quori Robot Program Co-authored a winning proposal that secured a robot donation for UW–Madison.	2018
Galileo Circle Scholar Gifted \$1,000 from UA donors for research accomplishments	2015
Fellowships	
Jerome and Isabella Karle Distinguished Scholar Supports a full-time appointment at the U.S. Naval Research Laboratory	2024-present
NRC Postdoctoral Research Fellowship	2022-2024

Selected by the UW-Madison Computer Sciences Department

Cisco Graduate Student Fellowship

**NSF Graduate Research Fellowship** 

**Advanced Opportunity Fellowship** 

Stipend with travel support at the U.S. Naval Research Laboratory

Selected by the UW-Madison Computer Sciences Department

Stipend at the UW–Madison Computer Sciences Department

2021-2022

2017-2022

2016, 2020

# Honors and Awards

Best Paper Award HRI '25, Short Contributions	2025
Best Paper Nominee 2023 AAAI Spring Symposium, HRI in Academia and Industry: Bridging the Gap	2023
<b>Robotics Perception and Learning Summer School, KTH Royal Institute of Technology</b> Invited to attend	2022
Microsoft Research AI Breakthroughs Invited to participate as a young researcher	2020
Heidelberg Laureate Forum Invited to attend as a young researcher	2019
HRI Pioneers Invited to participate as a young researcher	2019
Best Paper Award UIST '18	2018
Excellence in Undergraduate Research Award Selected by the UA Department of Computer Science	2016
Galileo Circle Scholar Selected by the UA Department of Computer Science	2015
National Hispanic Scholar Selected by the National Hispanic Recognition Program	2011
Dean's List with Distinction Awarded during six semesters at UA	2011-2016
Teaching Experience	
Guest Lecturer, University of Maryland, College Park - CMSC 722, AI Planning. Fall 2024.	Fall 2024
Grandparents University Instructor, UW  Duties: designing and teaching two-day lecture and lab sessions for UW alumni families.  - Social Robotics. July 2019.  - Social Robotics. July 2018.	Summers 2018-2019
Teaching Assistant, UA  Duties: holding office hours and grading assignments  - CSC 352, Systems Programming and Unix. Summer 2015.	Summer 2015
Section Leader, UA  Duties: teaching lab sessions, holding office hours, and grading assignments  - CSC 245, Introduction to Discrete Structures. Fall 2015.	Fall 2014 - Spring 2015

Student Preceptor, UA Spring 2012

Duties: assisting the professor during lectures and holding office hours

- CSC 127B, Introduction to Computer Science II. Spring 2015. - CSC 227, Program Design and Development. Fall 2014.

- CHEM 151, Chemical Thinking I. Spring 2012.

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# Invited Talks

HRI Workshop on *The Road to Reliable Robots*March 2025

Title: Evaluating Systems for Robot Application Development

Johns Hopkins University April 2024

Title: Robot Application Development: A Shifting Paradigm

Colorado School of Mines March 2022

Title: Authoring Social Interactions Between Humans and Robots

University at Buffalo February 2022

Title: Authoring Social Interactions Between Humans and Robots

Montana State University February 2022

Title: Authoring Social Interactions Between Humans and Robots

Talking Robotics December 2020

Title: Authoring Social Interactions Between Humans and Robots

# ACADEMIC SERVICE

#### Ph.D. Committee Member for the Following Students

Saad Elbeleidy (2024)—Colorado School of Mines

#### **Mentor for the Following Students**

Nhi Tran (2023-Present)—US Naval Research Laboratory

Evan Conway (2024)—US Naval Research Laboratory

Madeline Forsythe (2024)—US Naval Research Laboratory

Kyle Wang (2019-2022)—*UW Madison* 

Linda Wu (2019-2020)—UW Madison

Mikayla Buford (2019-2020)—UW Madison

Laik Ruetten (2020)—UW Madison

Ezra Boley (2019)—UW Madison

Evan Fisher (2018)—UW Madison

#### **Event Organization**

 $2025\ Program\ committee\ (PC)\ member\ for\ the\ ACM/IEEE\ International\ Conference\ on\ Human-Robot\ Interaction\ (HRI)$ 

2024 AAAI Fall Symposium Series—Unifying Representations for Robot Application Development (chair)

2024 NordiCHI Tutorial—Designing Human-Robot Interactions: A StEER Tutorial

2024 Program committee (PC) member for HRI

2024 HRI Workshop—End-User Development for Human-Robot Interaction

2023 AAAI FSS—Unifying Representations for Robot Application Development

2022 HRI Workshop—Participatory Design and End-User Programming for Human-Robot Interaction

#### Referee Service

HRI (incl. alt.HRI)—2020, 2022, 2023 HRI (LBR & Pioneers)—2021, 2023, 2024, 2025 CHI—2022, 2024, 2025 THRI—2020, 2024

Int. J. Soc. Robot.—2022, 2024

AAMAS—2024, 2025 CogSci—2024, 2025

RSS—2025

ICRA-2024, 2025

UIST-2021

AAAI FSS, AI-HRI—2022

CSCW-2022

HAI—2023

# TECHNICAL SKILLS

# **Programming Languages**

Python, Golang, Java, Javascript, HTML, CSS, C#, C, PDDL, GDScript

#### Robotics Tools, Libraries, and Frameworks

ROS1, ROS2, Gazebo Simulator, OpenCV, Unity Game Engine

#### **Robot Platforms**

Hello-Robot Stretch 2, Softbank Pepper, Softbank Nao, Temi, iRobot Create 2

#### Design

Adobe Illustrator, Premiere, & Photoshop. Affinity Designer

#### **AI Planning and Formal Methods**

Unified Planning, Z3 Theorem Prover, PRISM Model Checker, NuSMV Model Checker

#### **Data Visualization**

Matplotlib, D3.js