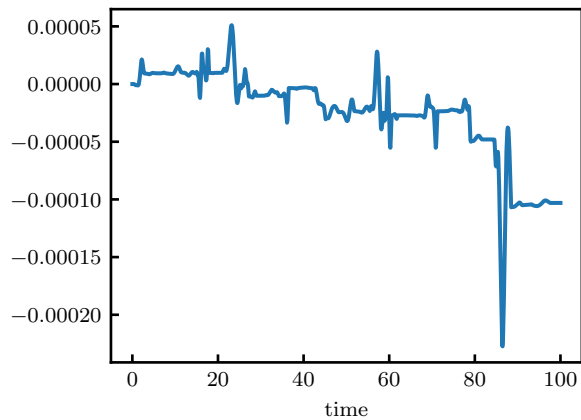
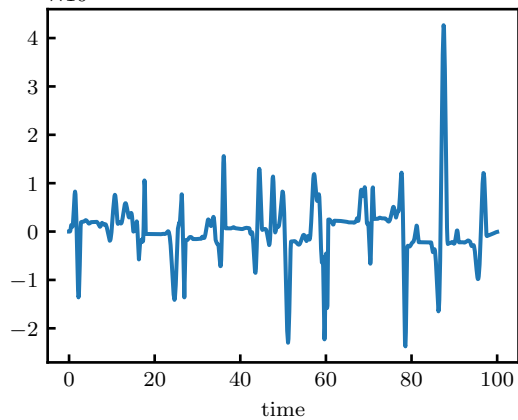
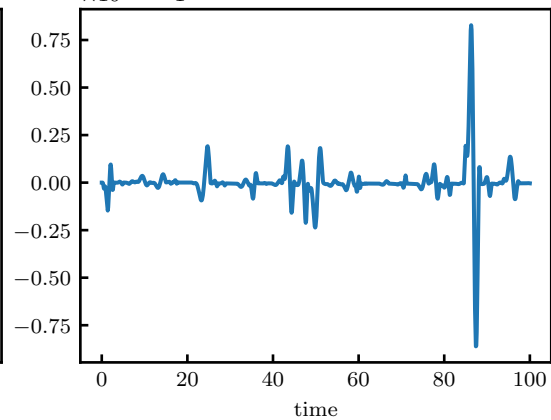
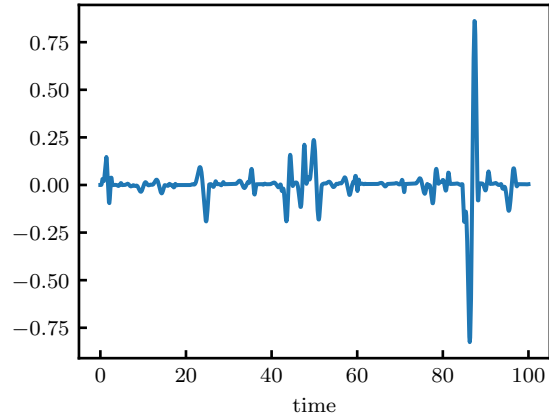
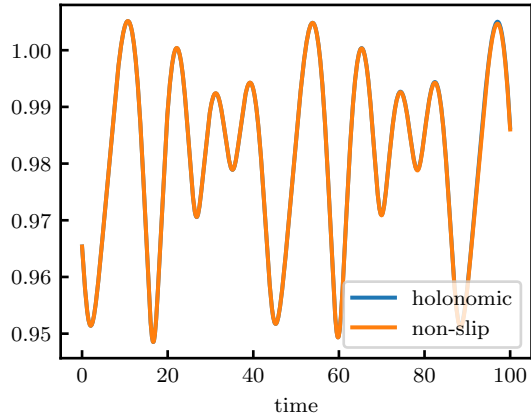


qnq* component 1

 $\times 10^{-5}$ qnq* component 2 $\times 10^{-5} - 1$ qnq* component 3 $\times 10^{-5} + 1$ Q norm

z position



xy trajectory

