CE 7.4a

```
%Previous work
L=1;
J=0.0676;
m=0.9048;
r=0.03;
Jb=0.000326;
g=9.81;
p0=.25;
b=m/[(Jb/r^2)+m];
a=[0 \ 1 \ 0 \ 0; \ 0 \ 0 \ -b*g \ 0; \ 0 \ 0 \ 1; \ -m*g/(m*p0^2+J+Jb) \ 0 \ 0 \ 0];
B=[0;0;0;1/(m*p0^2+J+Jb)];
c=[1 \ 0 \ 0 \ 0];
d=0;
sys=ss(a,B,c,d)
P=ctrb(sys);
[num, den]=ss2tf(a,B,c,d)
Pc1=[0 0 0 1; 0 0 1 0; 0 1 0 0; 1 0 0 0];
Tc=P*Pc1;
Tc1=inv(Tc);
Ac1=Tc1*a;
Ac=Ac1*Tc
Bc=Tc1*B
Cc=c*Tc
Dc=d
sys =
  a =
            x1
                    x2
                            x3
                                     x4
            0
                              0
                                      0
   x1
                     1
   x2
            0
                     0 -7.005
                                      0
   x3
            0
                     0
                              0
                                      1
   x4
       -71.31
                              0
                                       0
  b =
           u1
   x1
            0
   x2
   x3
            0
   x4
      8.034
  c =
       x1 x2 x3 x4
   y1 1 0 0
```

```
d =
    u1
  y1 0
Continuous-time state-space model.
num =
      0
        0 0 0 -56.2797
den =
   1.0000 0.0000 0.0000 -499.5435
Ac =
      0
         1.0000
                    0
                            0
            0 1.0000
                            0
      0
      0
              0
                    0 1.0000
 499.5435
              0
                    0
Bc =
   0
   0
   0
   1
Cc =
 -56.2797
        0
                 0
DC =
```

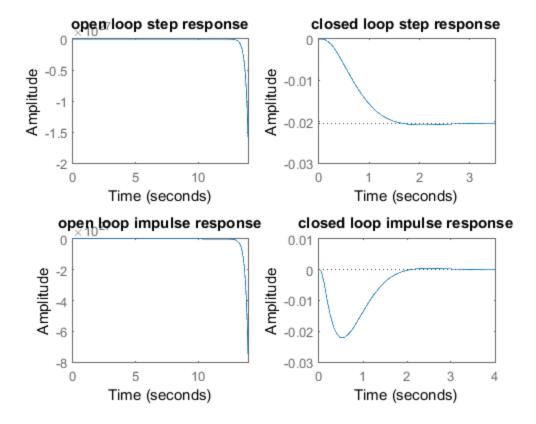
New work

0

```
%Desired 2% Peak overshoot, 2s settling time
%Chosen eigen values are -20, -21 for fast response
%s^4+45s^3+590s^2+1949s+2763

Pc=[Bc Ac*Bc (Ac^2)*Bc (Ac^3)*Bc];
Pc1=inv(Pc);
d=(Ac^4)+45*(Ac^3)+590*(Ac^2)+1949*(Ac)+2763*I;
```

```
K = [0 \ 0 \ 0 \ 1] * Pc1*d;
Adc=Ac-Bc*K;
eig(Adc)
[num,den]=ss2tf(Adc,Bc,Cc,Dc);
sys1=tf(num,den);
%Plots original system's step response
figure(1);
subplot(2,2,1), step(sys);
title('open loop step response');
subplot(2,2,2), step(sys1);
title('closed loop step response');
subplot(2,2,3), impulse(sys);
title('open loop impulse response');
subplot(2,2,4), impulse(sys1);
title('closed loop impulse response');
stepinfo(sys1)
%All criteria have been met for the system. Overshoot is under 2% and
the
%settling time is less than 2s. The system stabilizes to 0 so the bar
 would
%be straight when it finished balancing.
ans =
 -21.4530 + 0.0000i
 -19.5426 + 0.0000i
  -2.0022 + 1.6067i
  -2.0022 - 1.6067i
ans =
        RiseTime: 0.9466
    SettlingTime: 1.5102
     SettlingMin: -0.0208
     SettlingMax: -0.0184
       Overshoot: 1.9588
      Undershoot: 0
            Peak: 0.0208
        PeakTime: 2.0643
```



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