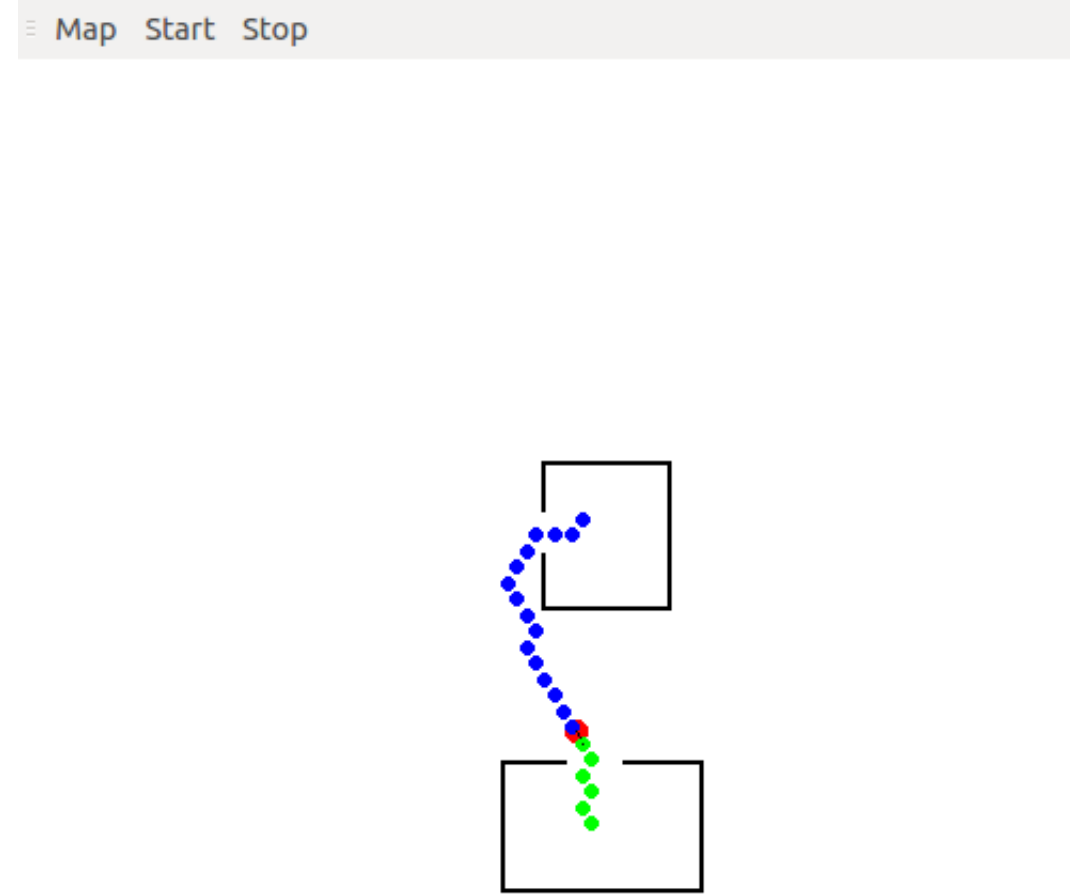
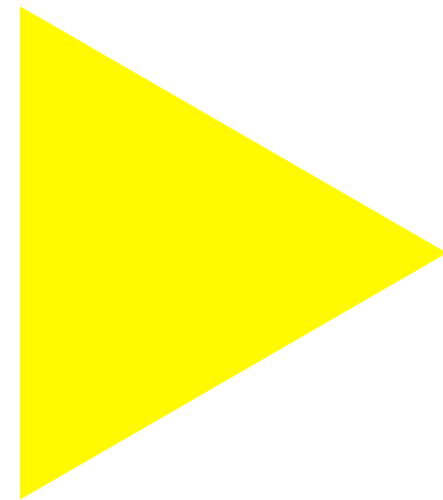
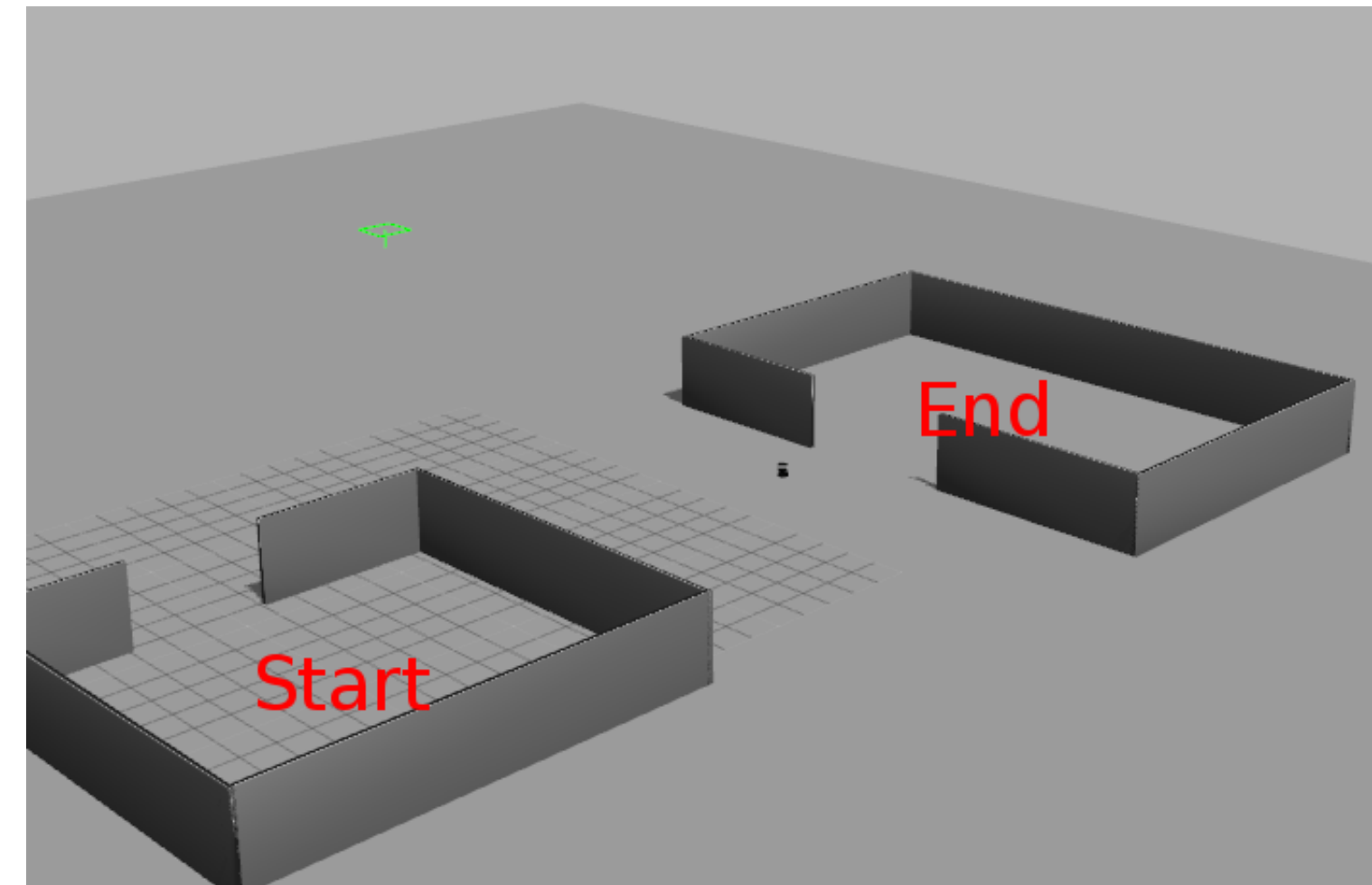
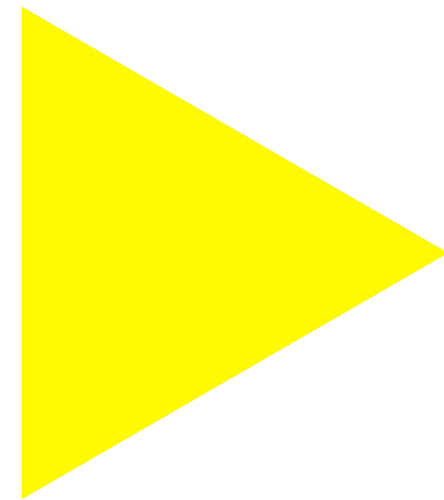


Hexagonal map



Planned path



Robot execution