Search CS 470 Introduction To Artificial Intelligence

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Outline

Search in Al

2 Uninformed search

Informed search



Search problem in Al

Search

- initial state
- goal state
- state transition sequence

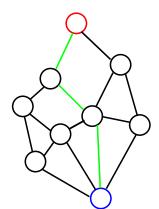




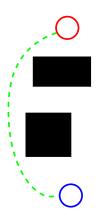
Search problem in Al

Problem space

Discrete



Continuous





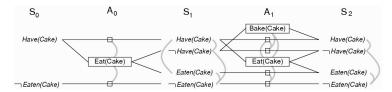


Routing planning



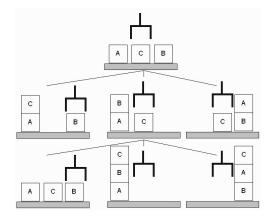


Scheduling





Robot action planning



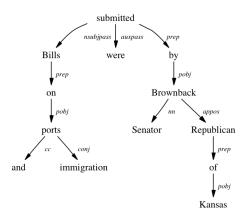


Air ticket planning



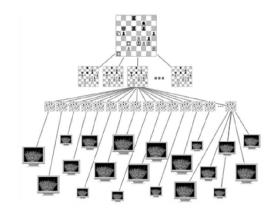


Nature language generation





Game

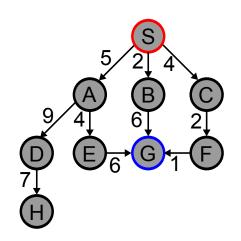




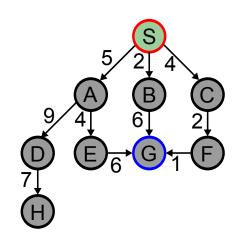
Search method

- Breadth-First Search
- Depth-First Search
- Uniform-Cost Search
- Depth-limited search
- Iterative-Deepening Search
- Bi-directional search

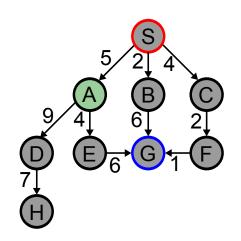




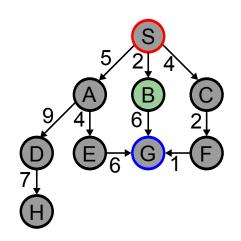




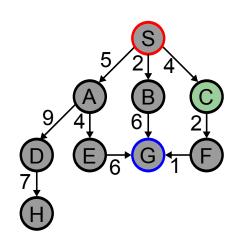




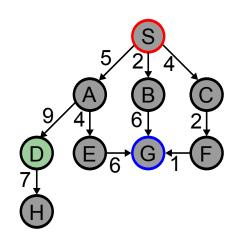




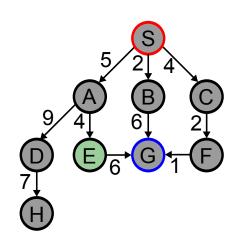
Notice BYU



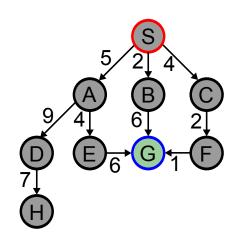




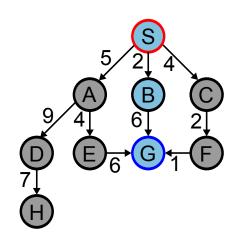




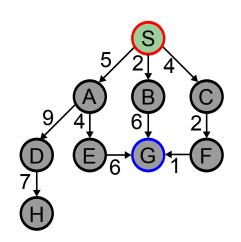


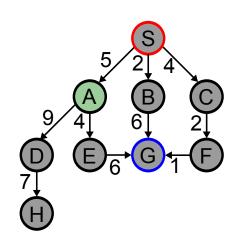




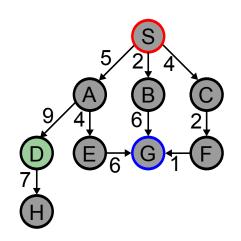


BYU REST

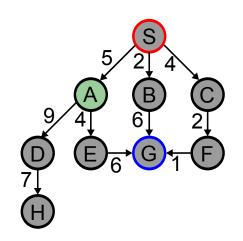




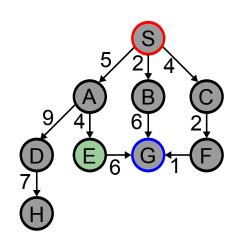




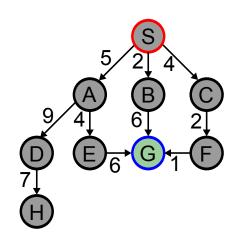


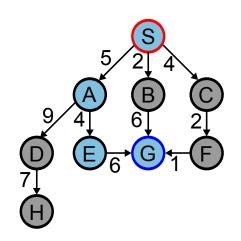


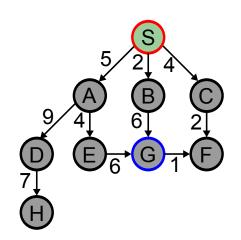


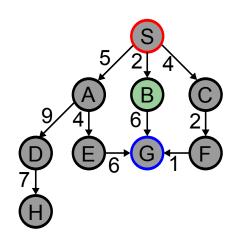


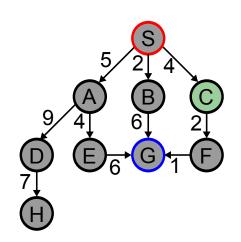




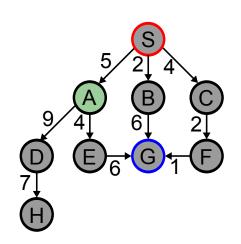


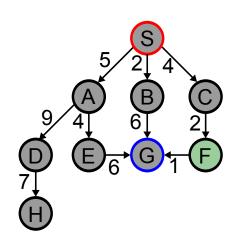


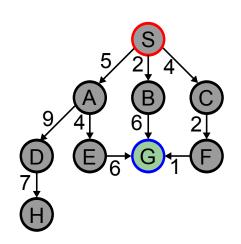


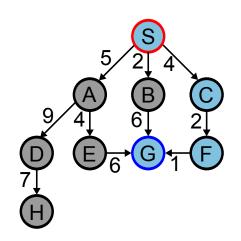






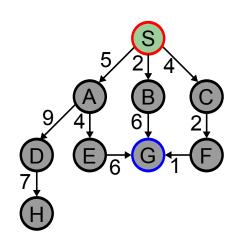






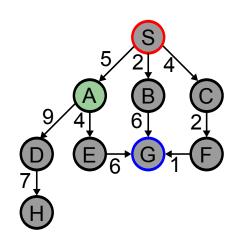


Iterative-Deepening Search

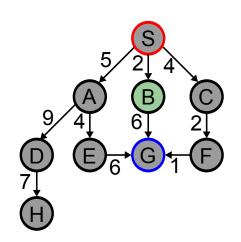




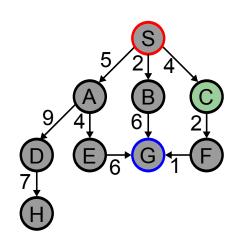
Iterative-Deepening Search



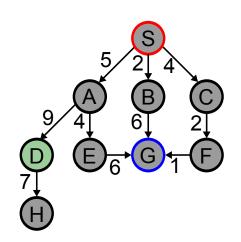




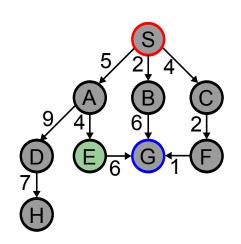
Informed search



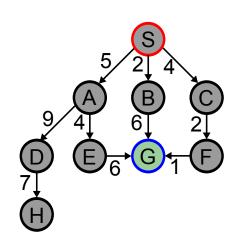










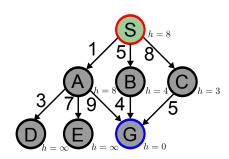




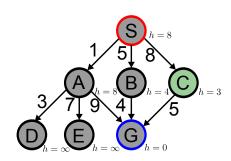
Search method

- Greedy Best-First Search
- A* Search
- IDA* Search
- SMA* Search

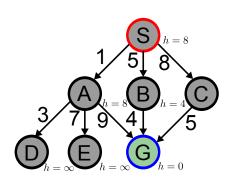




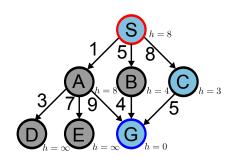




Informed search

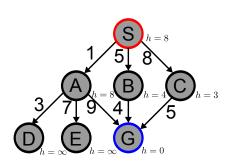


Informed search



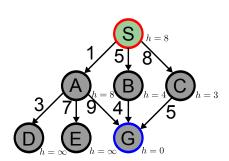
 A^*

Node	g	h	f
S	0	8	8
Α			
В			
С			
D			
E			
G			



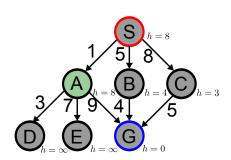
A,

Node	g	h	f
S	0	8	8
Α	1	8	9
В	5	4	9
С	8	3	11
D			
Е			
G			



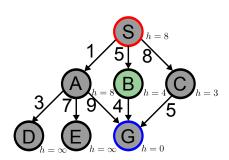
A,

Node	g	h	f
S	0	8	8
Α	1	8	9
В	5	4	9
С	8	3	11
D	4	∞	∞
Е	8	∞	∞
G	10	0	10



A,

Node	g	h	f
S	0	8	8
Α	1	8	9
В	5	4	9
С	8	3	11
D	4	∞	∞
Е	8	∞	∞
G	9	0	9



A

