Unit-II

UNIT II: Divide and conquer: General method, applications-Binary search, Quick sort, Merge sort, Strassen's matrix multiplication. Applications: PNR number Search, sorting the google search results.

Divide and Conquer Technique

General Method:

- The Divide and Conquer Technique splits n inputs into k subsets, $1 < k \le n$, yielding k subproblems.
- These subproblems will be solved and then combined by using a separate method to get a solution to the whole problem.
- If the subproblems are large, then the Divide and Conquer Technique will be reapplied.
- ➤ Often subproblems resulting from a Divide and Conquer Technique are of the same type as the original problem.

- The reapplication of the Divide and Conquer Technique is naturally expressed by a recursive algorithm.
- Now smaller and smaller problems of the same kind are generated until subproblems that are small enough to solve without splitting further.

Control Abstraction / General Method for Divide and Conquer Technique

```
Algorithm DAndC(p)
   if Small(p) then return s(p);
   else
        divide p into smaller problems p1,p2,....,pk, k \ge 1;
        Apply DAndC to each of these subproblems;
        return Combine(DAndC(p1), DAndC(p2),....,DAndC(pk));
```

If the size of p is n and the sizes of the k subproblems are $n_1,n_2,...,n_k$, then the computing time of DAndC is described by the recurrence relation

$$T(n) = \begin{cases} g(n) & n \text{ small} \\ T(n_1) + T(n_2) + \dots + T(n_k) + f(n) & Otherwise \end{cases}$$

- Where T(n) is the time for DAndC on any input of size n and g(n) is the time to compute the answer directly for small inputs.
- The function f(n) is the time for dividing p and combining the solutions of subproblems.

➤ The Complexity of many divide-and-conquer algorithms is given by recurrences of the form

$$T(n) = \begin{cases} c & n \text{ small} \\ aT(n/b) + f(n) & \text{Otherwise} \end{cases}$$

➤ Where a, b and c are known constants, and n is a power of b (i.e n=b^k)

Applications

1.Binary search Algorithm

Iterative Method

```
Algorithm BinSearch(a, n, x)
// a is an array of size n, x is the key element to be searched.
      low:=1; high:=n;
     while( low ≤ high)
         mid:=(low+high)/2;
         if( x < a[mid] ) then high := mid-1;
        else if (x > a[mid]) then low := mid+1;
                   return mid;
              else
  return 0;
```

Recursive Algorithm (Divide and Conquer Technique)

```
Algorithm BinSrch (a, low, high, x)
//Given an array a [low: high of elements in increasing
//order,1≤low≤high,determine whether x is present, and
//if so, return j such that x=a[j]; else return 0.
   if( low = high ) then // If small(P)
        if (x=a[low]) then return low;
        else return 0;
   else
```

```
//Reduce p into a smaller subproblem.
     mid:= (low+high)/2
     if(x = a[mid]) then return mid;
     else if (x < a[mid]) then
            return BinSrch(a, low, mid-1, x);
     else
     return BinSrch(a, mid+1, high, x);
```

Time complexity of Binary Seaych

➤ If the time for diving the list is a constant, then the computing time for binary search is described by the recurrence relation

$$T(n) = \begin{cases} c_1 \\ T(n/2) + c_2 \end{cases}$$

n=1, c1 is a constant n>1, c2 is a constant

Assume $n=2^k$, then

Time Complexity of Binary Search

Successful searches:

best	average	worst

O(1) $O(\log n)$ $O(\log n)$

Unsuccessful searches:

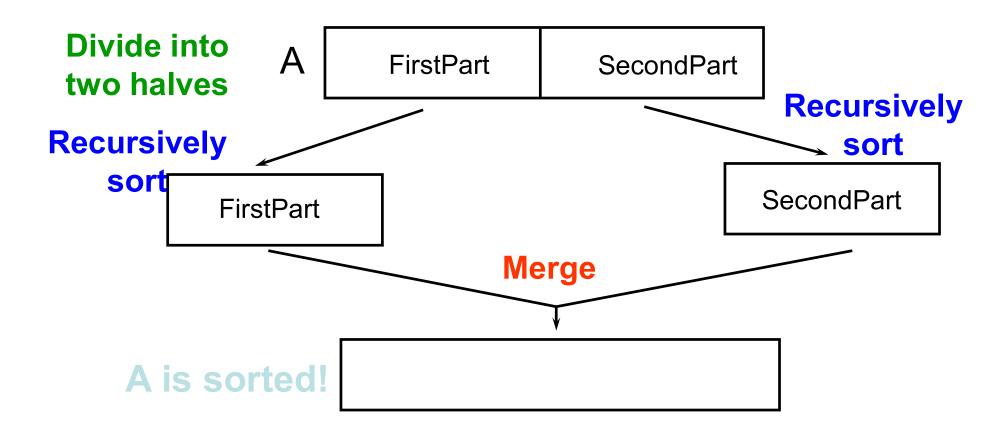
```
best average worst
```

 $O(\log n)$ $O(\log n)$ $O(\log n)$

2. Merge Sort

- 1. Base Case, solve the problem directly if it is small enough(only one element).
- 2. Divide the problem into two or more similar and smaller subproblems.
- 3. Recursively solve the subproblems.
- 4. Combine solutions to the subproblems.

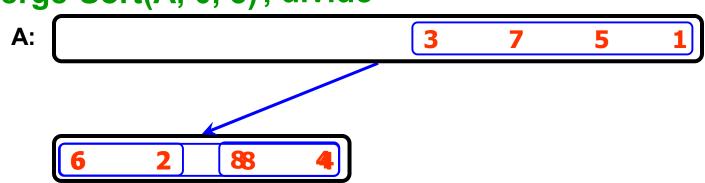
Merge Sort: Idea



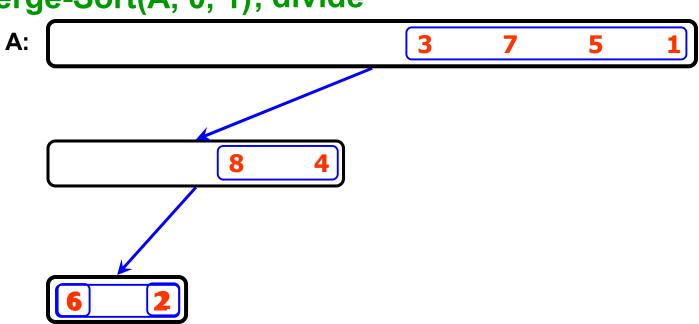
Divide

A: 6 2 8 4 3 3 7 7 5 5 1 1

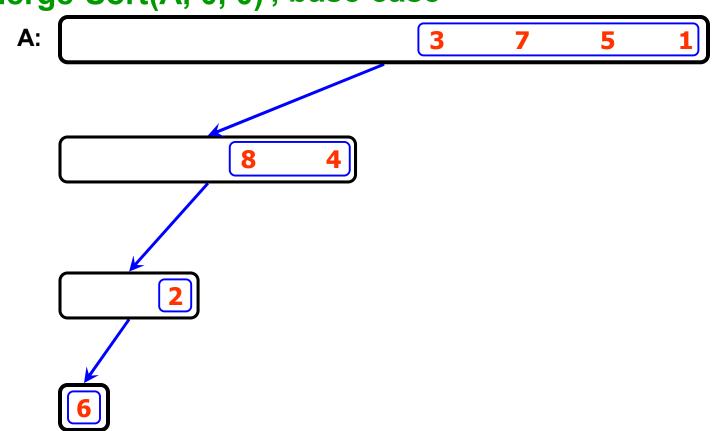
Merge-Sort(A, 0, 3), divide



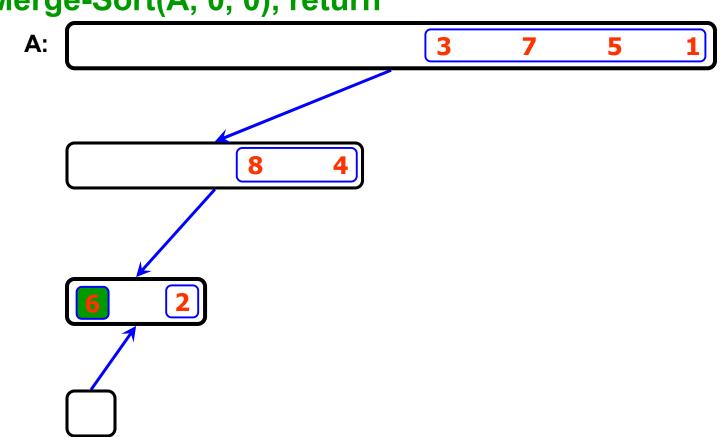
Merge-Sort(A, 0, 1), divide



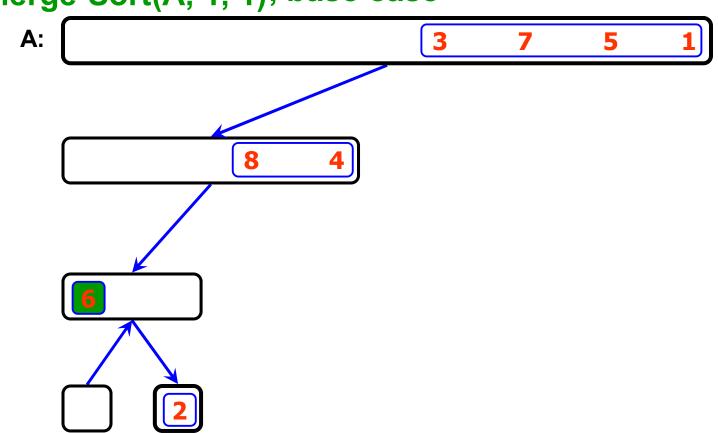
Merge-Sort(A, 0, 0), base case



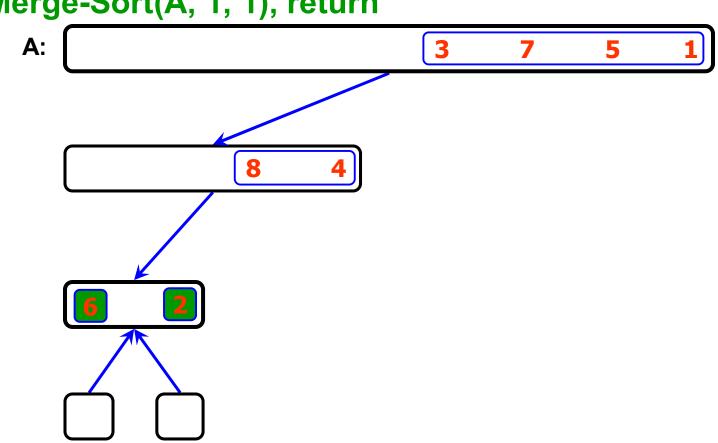
Merge-Sort(A, 0, 0), return

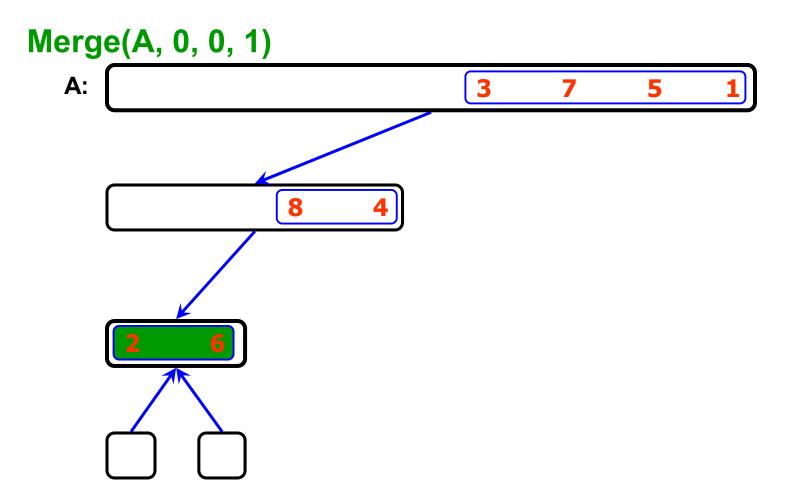


Merge-Sort(A, 1, 1), base case

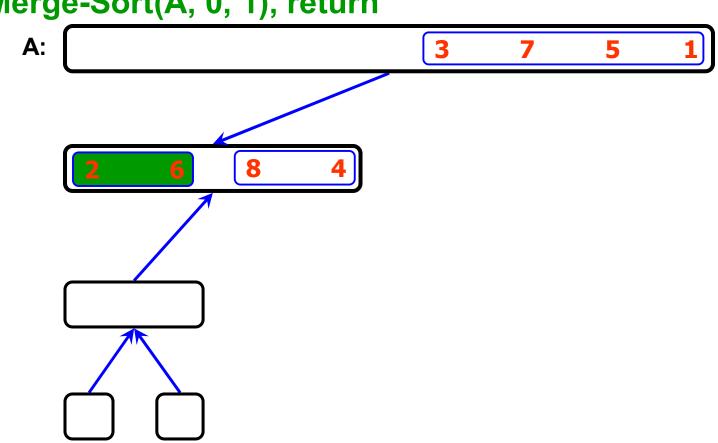


Merge-Sort(A, 1, 1), return

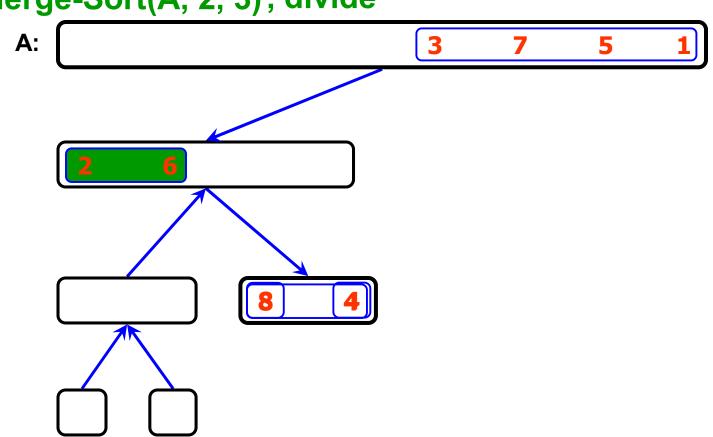




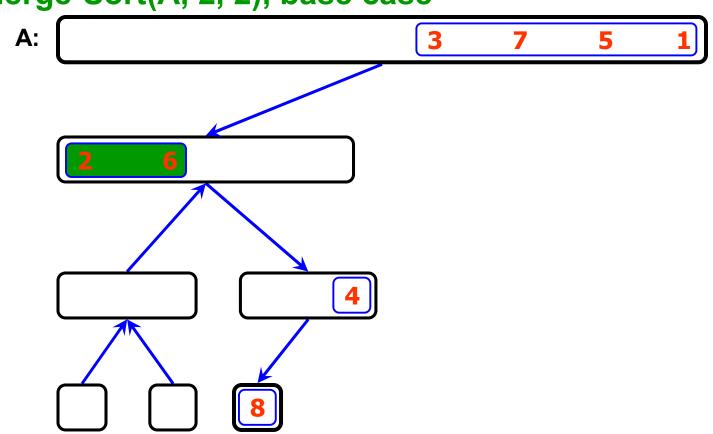
Merge-Sort(A, 0, 1), return



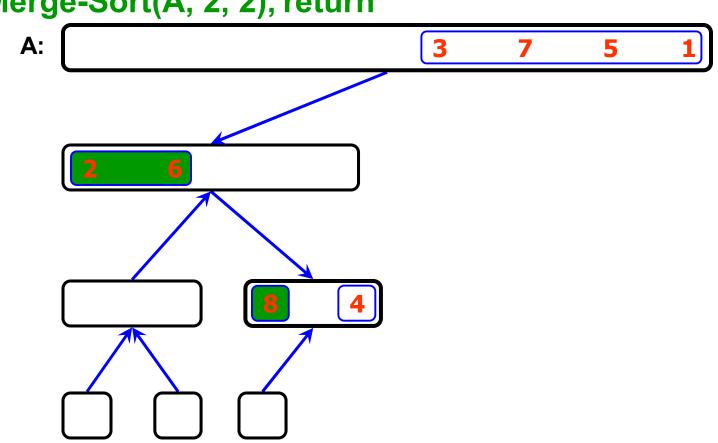
Merge-Sort(A, 2, 3), divide



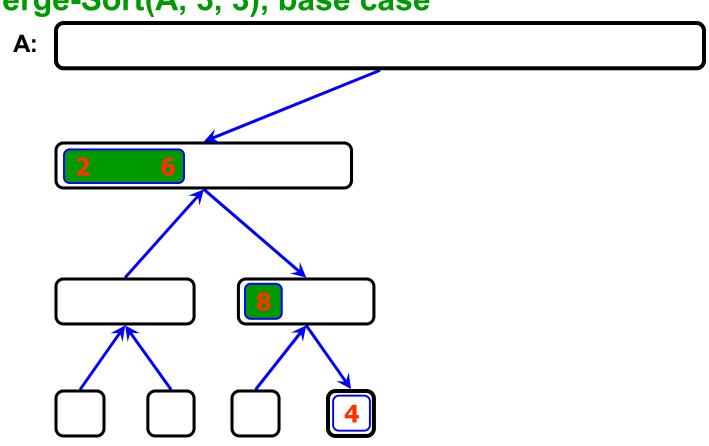
Merge-Sort(A, 2, 2), base case



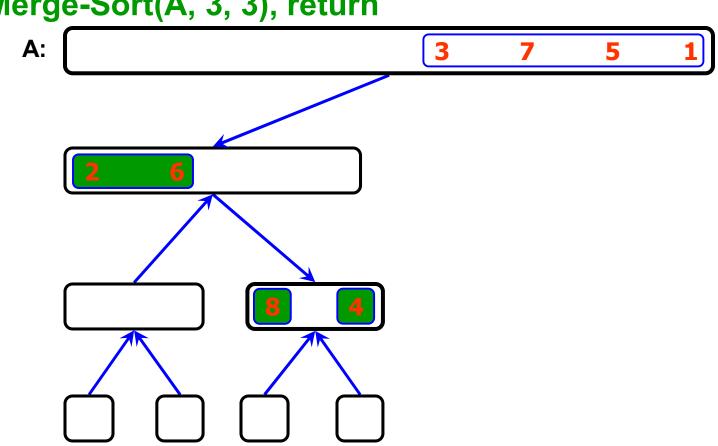
Merge-Sort(A, 2, 2), return

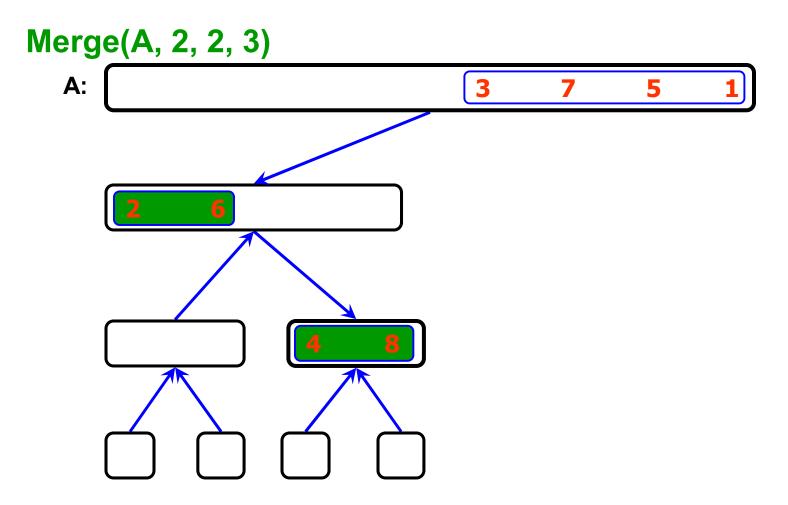


Merge-Sort(A, 3, 3), base case

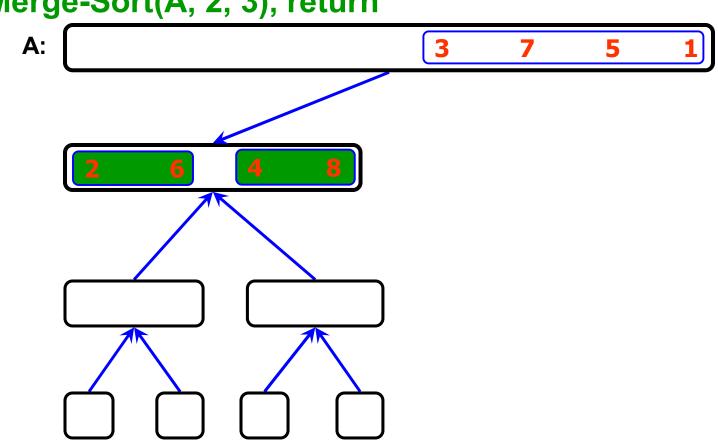


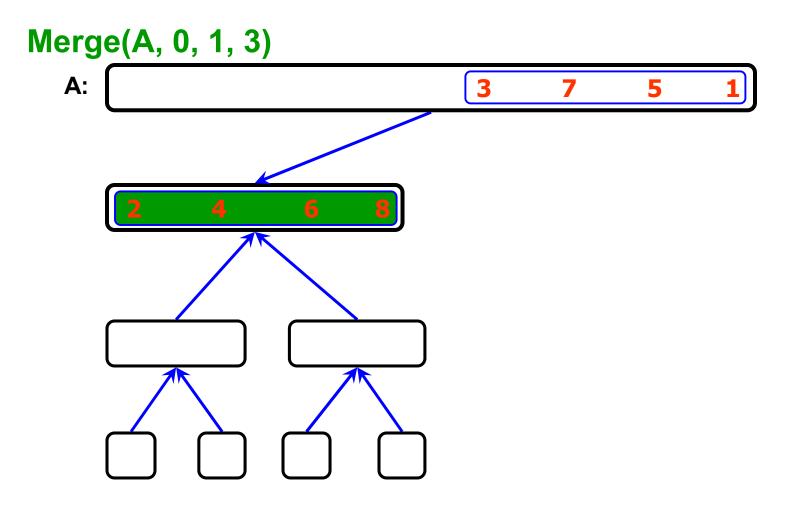
Merge-Sort(A, 3, 3), return



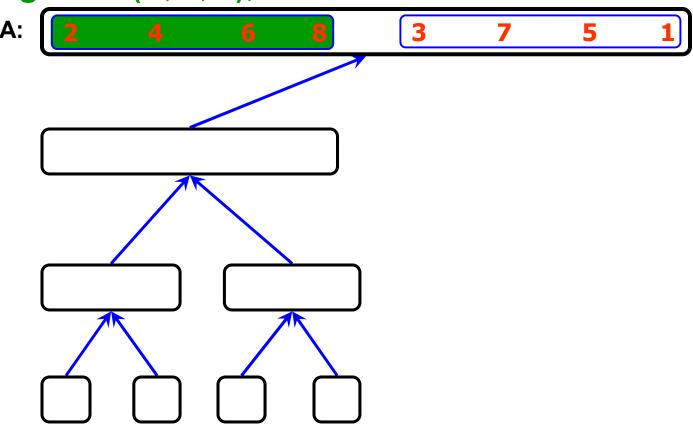


Merge-Sort(A, 2, 3), return

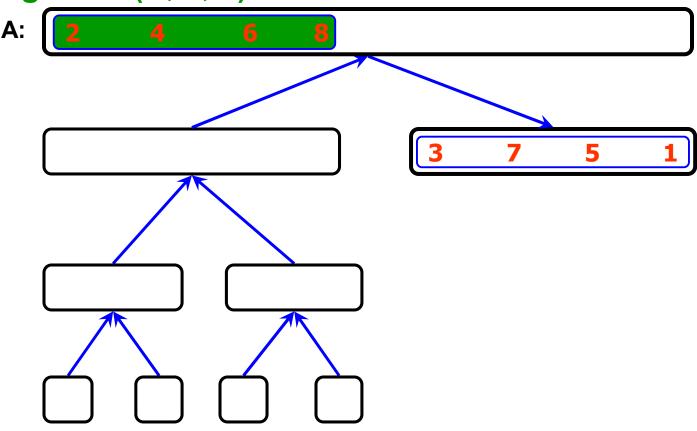




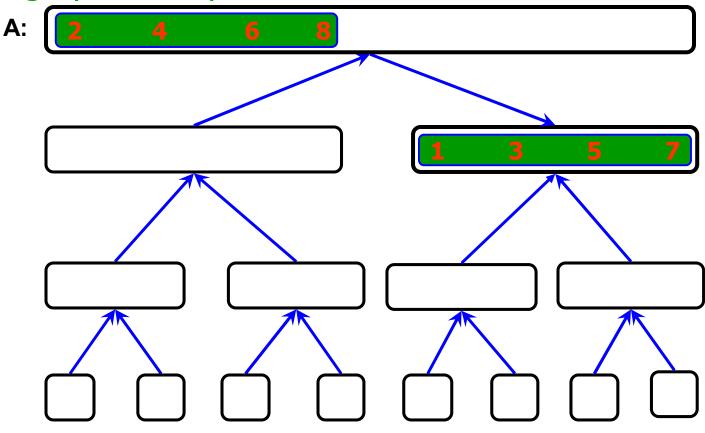
Merge-Sort(A, 0, 3), return



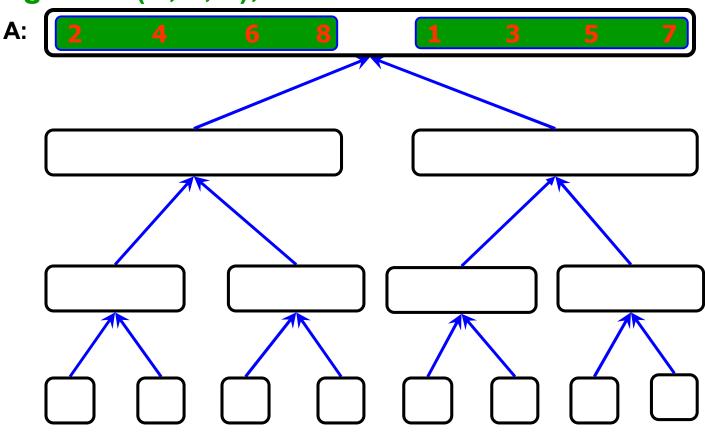
Merge-Sort(A, 4, 7)



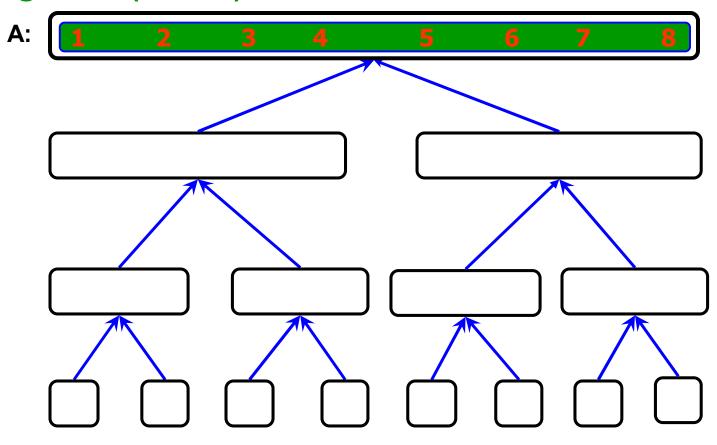
Merge (A, 4, 5, 7)



Merge-Sort(A, 4, 7), return

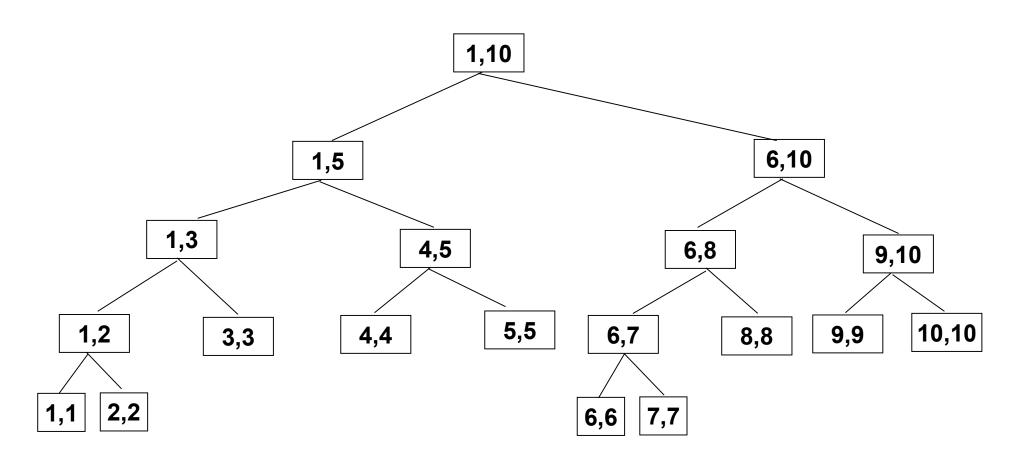


Merge-Sort(A, 0, 7), done!



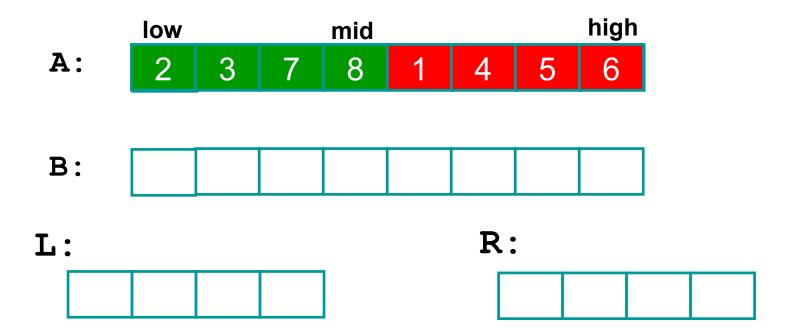
Ex:- [179, 254, 285, 310, 351, 423, 450, 520, 652,861]

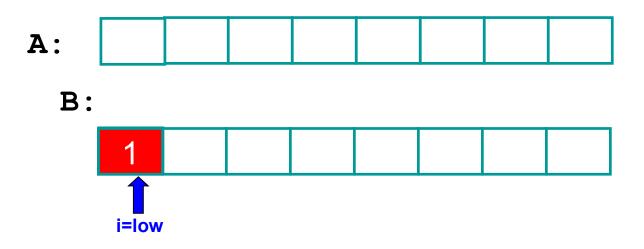
Tree of calls of merge sort



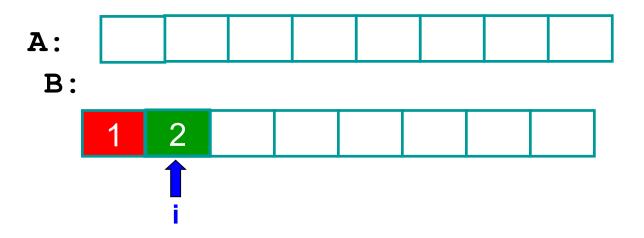
Merge Sort: Algorithm

```
MergeSort (low,high)
// sorts the elements a[low],...,a[high] which are in the global array
//a[1:n] into ascending order (increasing order).
// Small(p) is true if there is only one element to sort. In this case the list is
// already sorted.
    if (low<high) then // if there are more than one element
                                             Recursive Calls
         mid \leftarrow (low+high)/2;
         MergeSort(low,mid);
         MergeSort(mid+1, high);
         Merge(low, mid, high);
```

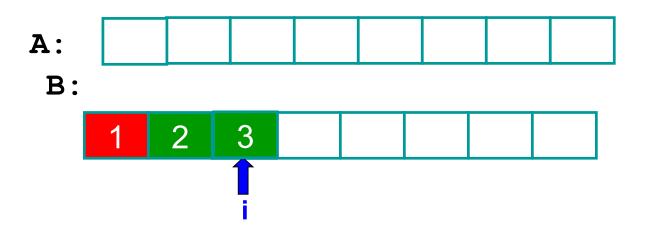




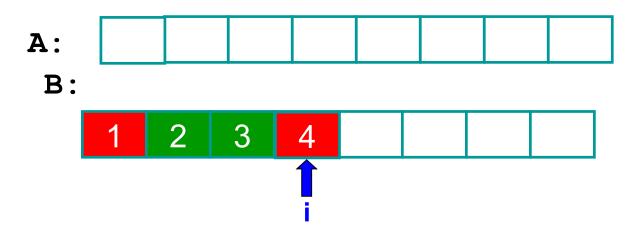




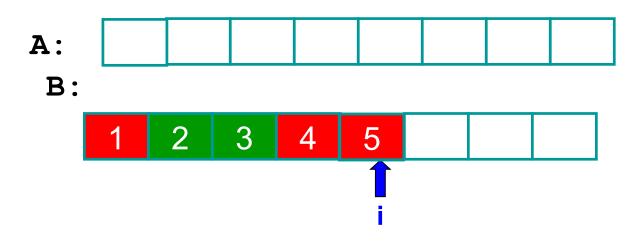




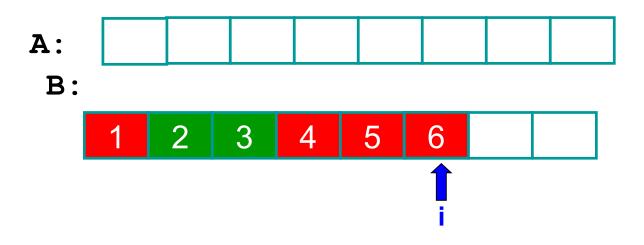




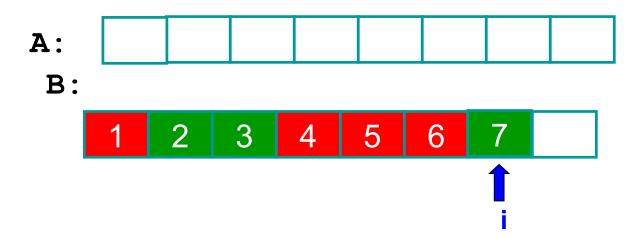


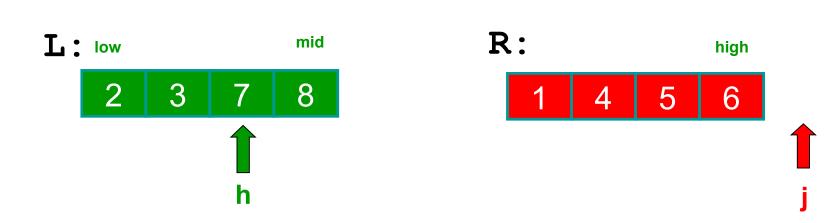


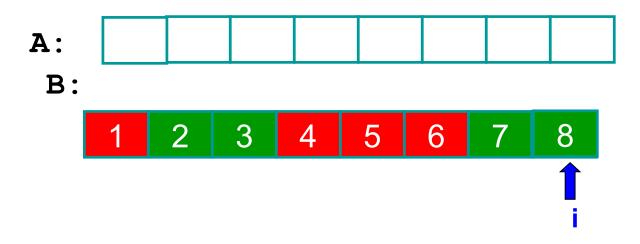


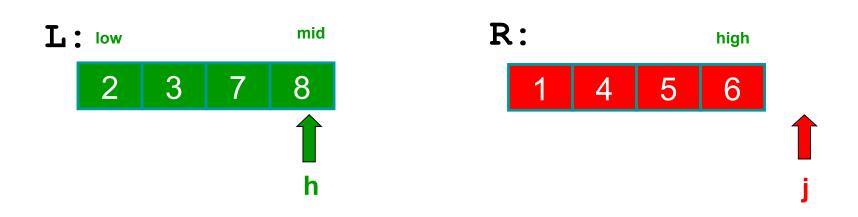


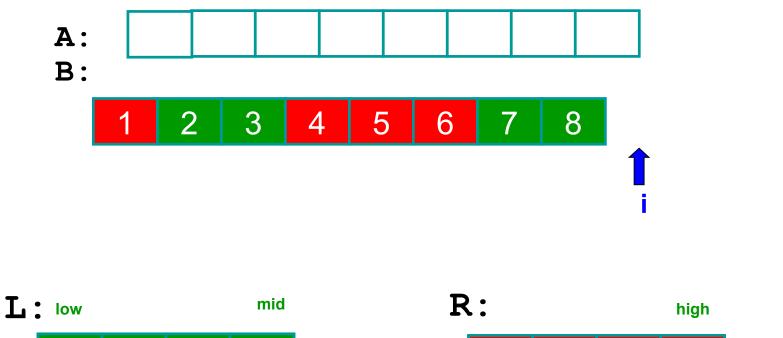




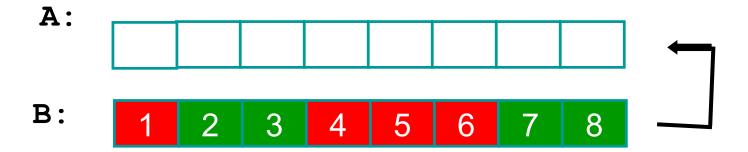








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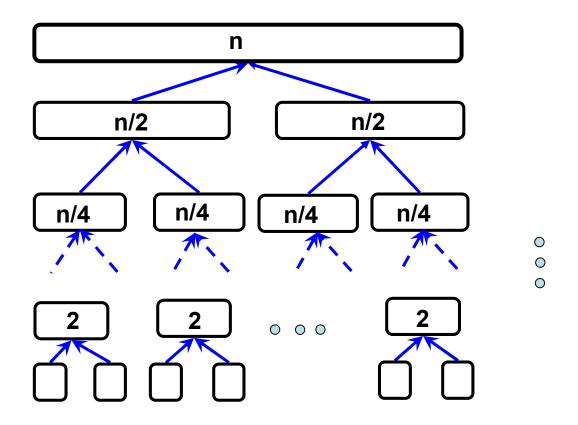


Algorithm Merge(low,mid,high)

```
// a[low:high] is a global array containing two sorted subsets in a[low:mid]
// and in a[mid+1:high]. The goal is to merge these two sets into a single
// set residing in a [low:high]. b[] is a temporary global array.
   h:=low; i:=low; j:=mid+1;
        while (h \le mid) and (j \le high) do
                 if( a[h] \le a[j] ) then
                          b[i]:=a[h]; h:=h+1;
                 else
                          b[i]:=a[j]; j:=j+1;
                 i:=i+1;
```

```
if( h > mid ) then
        for k:=j to high do
                b[i] := a[k]; i:= i+1;
else
        for k:=h to mid do
                b[i] := a[k]; i:= i+1;
 for k:= low to high do a[k]:=b[k];
```

Merge-Sort Analysis



Merge-Sort Time Complexity

If the time for the merging operation is proportional to n, then the computing time for merge sort is described by the recurrence relation

$$T(n) = \begin{cases} c_1 & \text{n=1, } c_1 \text{ is a constant} \\ 2T(n/2) + c_2 n & \text{n>1, } c_2 \text{ is a constant} \end{cases}$$

Assume n=2k, then

$$T(n) = 2T(n/2) + c_2n$$

 $= 2(2T(n/4) + c_2n/2) + c_1$
 $= 4T(n/4) + 2c_2n$
....
 $= 2^k T(1) + kc_2n$
 $= c_1n + c_2n \log n = O(n \log n)$

Summary

Merge-Sort

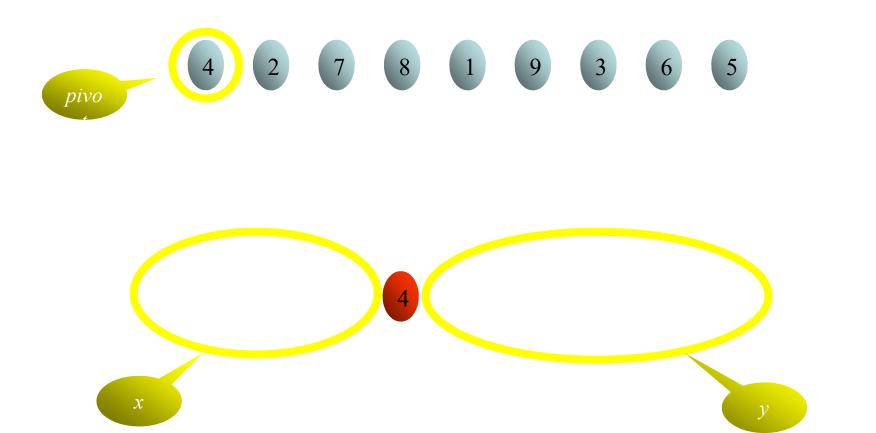
- Most of the work done in combining the solutions.
- Best case takes o(n log(n)) time
- Average case takes o(n log(n)) time
- Worst case takes o(n log(n)) time

3. Quick Sort

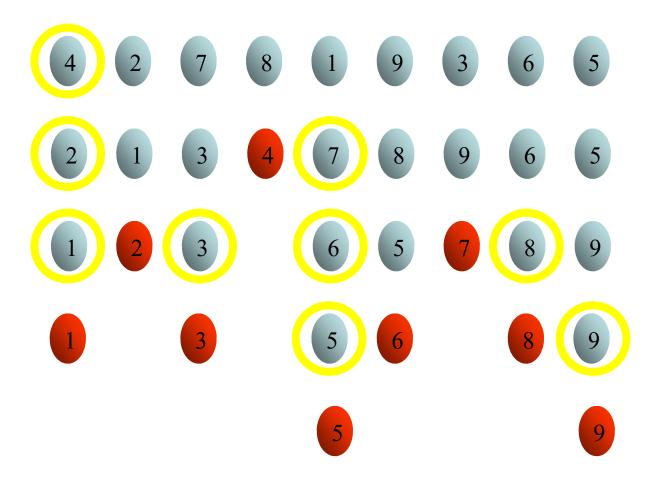
Divide:

- Pick any element as the pivot, e.g, the first element
- Partition the remaining elements into
 FirstPart, which contains all elements < pivot</p>
 SecondPart, which contains all elements > pivot
- Recursively sort FirstPart and SecondPart.
- Combine: no work is necessary since sorting is done in place.

pivot divides a into two sublists x and y.



The whole process

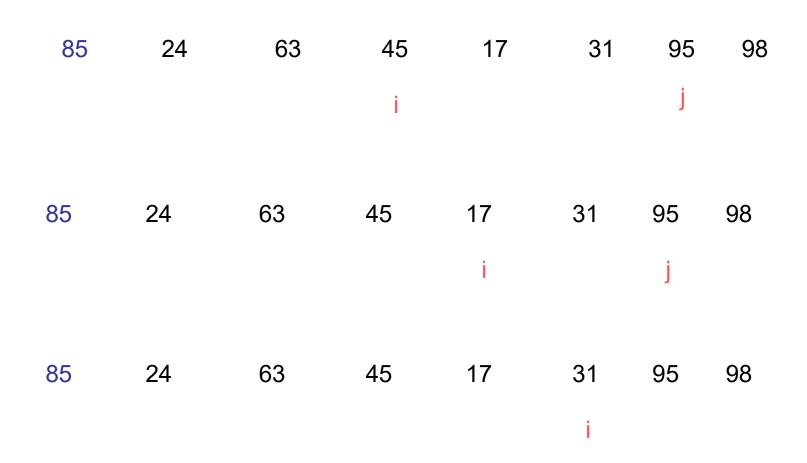


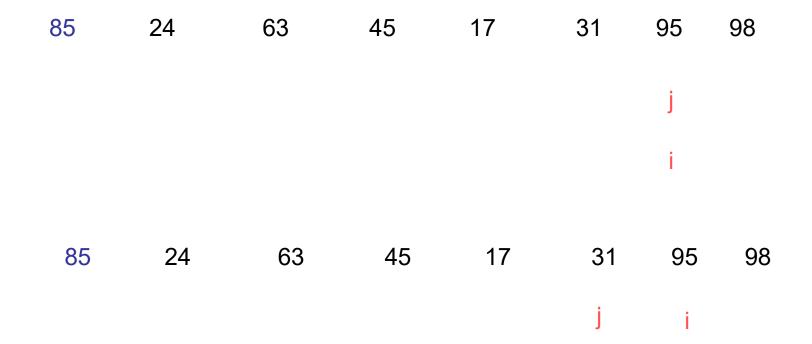
Process:

Keep going from left side as long as a[i]<pivot and from the right side as long as a[j]>pivot

pivot →	85	24	63	95	17	31	45	98
		i						j
	85	24	63	95	17	31	45	98
			i					j
	85	24	63	95	17	31	45	98
				i				j
	85	24	63	95	17	31	45	98
				i			j	

If i<j interchange ith and j th elements and then Continue the process.





If i ≥j interchange jth and pivot elements and then divide the list into two sublists.

35 24 63 45 17 85 95 98 j

Two sublists:

35 24 63 45 17 85 95 98

Recursively sort

FirstPart and SecondPart
QickSort(low, j-1) QickSort(j+1,high)

Quick Sort Algorithm:

```
Algorithm QuickSort(low,high)
//Sorts the elements a[low], ....., a[high] which resides
//in the global array a[1:n] into ascending order;
// a[n+1] is considered to be defined and must ≥ all the
// elements in a[1:n].
                  if( low< high ) // if there are more than one element
                             // divide p into two subproblems.
                             j :=Partition(low,high);
                                // j is the position of the partitioning element.
                             QuickSort(low,j-1);
                             QuickSort(j+1,high);
                             // There is no need for combining solutions.
```

```
Algorithm Partition(I,h)
           pivot:= a[i] ; i:=l; j:= h+1;
           while (i < j) do
                                 j++;
                                 while( a[ i ] < pivot ) do</pre>
                                            j++:
                                 while( a[ j ] > pivot ) do
                                 if ( i < j ) then Interchange(i, j ); // interchange ith and
           }
                                                                      // j<sup>th</sup> elements.
           Interchange(I, j); return j; // interchange pivot and j<sup>th</sup> element.
```

```
Algorithm interchange (x,y)
{
    temp=a[x];
    a[x]=a[y];
    a[y]=temp;
}
```

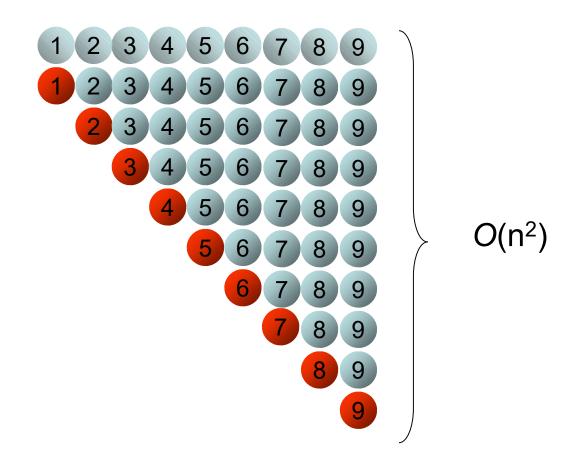
Time complexity analysis

- The time required to sort n elements using quicksort involves 3 components.
 - Time required for partitioning the array, which is roughly proportional to n.
 - Time required for sorting lower subarray.
 - Time required for sorting upper subarray.
- Assume that there are k elements in the lower subarray.
- Therefore,

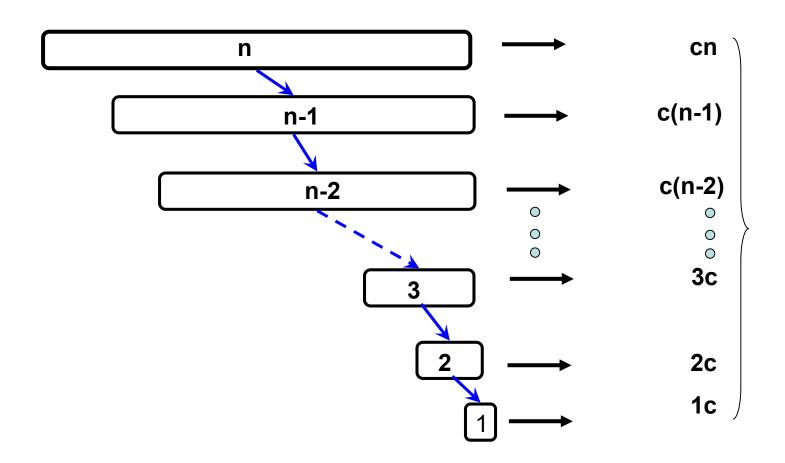
$$T(n) = \begin{cases} c_1 & \text{n=1, } c_1 \text{ is a constant} \\ T(k) + T(n-k-1) + c_2 n & \text{n>1, } c_2 \text{ is a constant} \end{cases}$$

A worst/bad case

It occurs if the list is already in sorted order



Worst/bad Case



contd...

• In the worst case, the array is always partitioned into two subarrays in which one of them is always empty. Thus, for the worst case analysis,

$$T(n) = \begin{cases} T(n-1) + c_2 n & n > 1, c_2 \text{ is a constant} \end{cases}$$

$$= T(n-1) + c_2 n$$

$$= T(n-2) + c_2 (n-1) + c_2 n$$

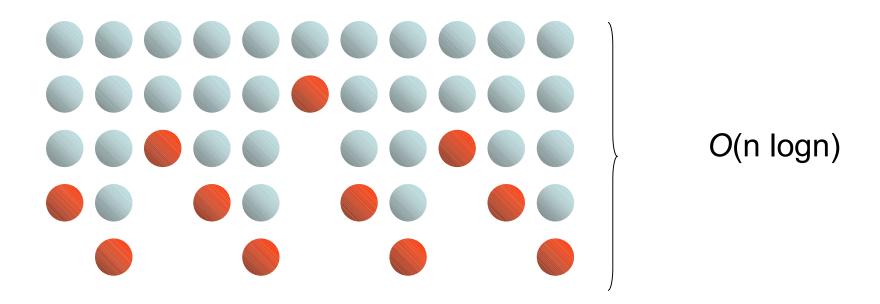
$$= T(n-3) + c_2 (n-2) + c_2 (n-1) + c_2 n$$

$$\dots$$

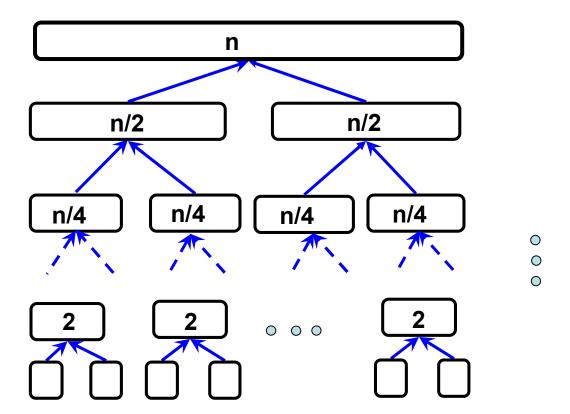
$$= n(n+1)/2 = (n^2+n)/2 = O(n^2)$$

A Best/Good case

 It occurs only if each partition divides the list into two equal size sublists.



Best/Good Case



$$T(n) = \begin{cases} c_1 & n=1, c_1 \text{ is a constant} \\ 2T(n/2) + c_2 n & n>1, c_2 \text{ is a constant} \end{cases}$$

Assume n=2k, then

$$T(n) = 2T(n/2) + c_2n$$

= 2(2T(n/4)+c2n/2)+cn
= 4T(n/4)+2c_2n

• • • • •

= $2^k T(1) + kc_2 n$

 $= c_1 n + c_2 n \log n = = O(n \log n)$

Summary

Quick-Sort

- Most of the work done in partitioning
- Best case takes O(n log(n)) time
- Average case takes O(n log(n)) time
- Worst case takes O(n²) time

4. Strassen's Matrix Multiplication

Basic Matrix Multiplication

Let A an B two n×n matrices. The product C=AB is also an n×n matrix.

```
void matrix_mult (){
  for (i = 1; i <= N; i++) {
    for (j = 1; j <= N; j++) {
      for(k=1; k<=N; k++){
         C[i,j]=C[i,j]+A[i,k]+B[k,j];
      }
}}</pre>
```

Time complexity of above algorithm is T(n)=O(n3)

Divide and Conquer technique

- We want to compute the product C=AB, where each of A,B, and C are n×n matrices.
- Assume n is a power of 2.
- If n is not a power of 2, add enough rows and columns of zeros.
- We divide each of A,B, and C into four n/2×n/2 matrices, rewriting the equation C=AB as follows:

$$\begin{bmatrix}
C_{11} & C_{12} \\
C_{21} & C_{22}
\end{bmatrix} = \begin{bmatrix}
A_{11} & A_{12} \\
A_{21} & A_{22}
\end{bmatrix} * \begin{bmatrix}
B_{11} & B_{12} \\
B_{21} & B_{22}
\end{bmatrix}$$

Then,

- Each of these four equations specifies two multiplications of n/2×n/2 matrices and the addition of their n/2×n/2 products.
- We can derive the following recurrence relation for the time T(n) to multiply two n×n matrices:

T(n)=
$$\begin{cases} c_1 & \text{if } n <= 2\\ 8T(n/2) + c_2 n^2 & \text{if } n > 2 \end{cases}$$

$$T(n) = O(n3)$$

This method is no faster than the ordinary method.

$$T(n) = 8T(n/2) + c_2n^2$$

$$= 8 \left[8T(n/4) + c_2(n/2)^2 \right] + c_2n^2$$

$$= 8^2 T(n/4) + c_22n^2 + c_2n^2$$

$$= 8^2 \left[8T(n/8) + c_2(n/4)^2 \right] + c_22n^2 + c_2n^2$$

$$= 8^3 T(n/8) + c_24n^2 + c_22n^2 + c_2n^2$$

$$\vdots$$

$$= 8^k T(1) + \dots + c_24n^2 + c_22n^2 + c_2n^2$$

$$= 8^{\log_2 n} c_1 + c n^2$$

$$= n^{\log_2 c_1} + c n^2 = n^3 c_1 + c n^2 = O(n^3)$$

Strassen's method

- Matrix multiplications are more expensive than matrix additions or subtractions(O(n³) versus O(n²)).
- Strassen has discovered a way to compute the multiplication using only 7 multiplications and 18 additions or subtractions.
- His method involves computing 7 n/2×n/2 matrices
 M₁,M₂,M₃,M₄,M₅,M₆, and M₇, then cij's are calculated using these matrices.

Formulas for Strassen's Algorithm

$$M_{1} = (A_{11} + A_{22}) * (B_{11} + B_{22})$$

$$M_{2} = (A_{21} + A_{22}) * B_{11}$$

$$M_{3} = A_{11} * (B_{12} - B_{22})$$

$$M_{4} = A_{22} * (B_{21} - B_{11})$$

$$M_{5} = (A_{11} + A_{12}) * B_{22}$$

$$M_{6} = (A_{21} - A_{11}) * (B_{11} + B_{12})$$

$$M_{7} = (A_{12} - A_{22}) * (B_{21} + B_{22})$$

$$\begin{aligned} & \mathbf{C}_{11} = \mathbf{M}\mathbf{1} &+ \mathbf{M}\mathbf{4} - \mathbf{M}_5 + \mathbf{M}_7 \\ & \mathbf{C}_{12} = \mathbf{M}_3 + \mathbf{M}_5 \\ & \mathbf{C}_{21} = \mathbf{M}_2 + \mathbf{M}_4 \\ & \mathbf{C}_{22} = \mathbf{M}_1 &+ \mathbf{M}_3 - \mathbf{M}_2 + \mathbf{M}_6 \end{aligned}$$

$$\begin{bmatrix} C_{11} & C_{12} \\ \hline C_{21} & C_{22} \end{bmatrix} = \begin{bmatrix} A_{11} & A_{12} \\ \hline A_{21} & A_{22} \end{bmatrix} * \begin{bmatrix} B_{11} & B_{12} \\ \hline B_{21} & B_{22} \end{bmatrix}$$

$$= \begin{bmatrix} M_1 & + M_4 & - M_5 + M_7 \\ \hline M_2 & + M_4 \end{bmatrix} = \begin{bmatrix} M_3 & + M_5 \\ \hline M_1 & + M_3 & - M_2 + M_6 \end{bmatrix}$$

The resulting recurrence relation for T(n) is

$$T(n) = \begin{cases} c_1 & n <= 2 \\ 7T(n/2) + c_2 n^2 & n > 2 \end{cases}$$

T(n)=
$$7^k$$
T(1) + c_2 n² 1+ 7/4 + $(7/4)^2$ + $(7/4)^3$ +.....+ $(7/4)^{k-1}$

$$S_{n} = a + ar + ar^{2} + + ar^{n-1}.$$
When $r > 1$, $S_{n} = a \frac{(r^{n} - 1)}{(r - 1)}$

$$=7^{\log_2 n} c_1 + c_2 n^2 (7/4)^{\log_2 n}$$

$$=c_1 n^{\log_2 7} + c_2 n^{\log_2 4} (n^{\log_2 7 - \log_2 4})$$

$$= c_1 n^{\log_2 7} + c_2 (n^{\log_2 4} + \log_2 7 - \log_2 4) = c_1 n^{\log_2 7} + c_2 n^{\log_2 7}$$

$$=c n^{\log_2 7} = O(n^{\log_2 7}) \sim O(n^{2.81})$$