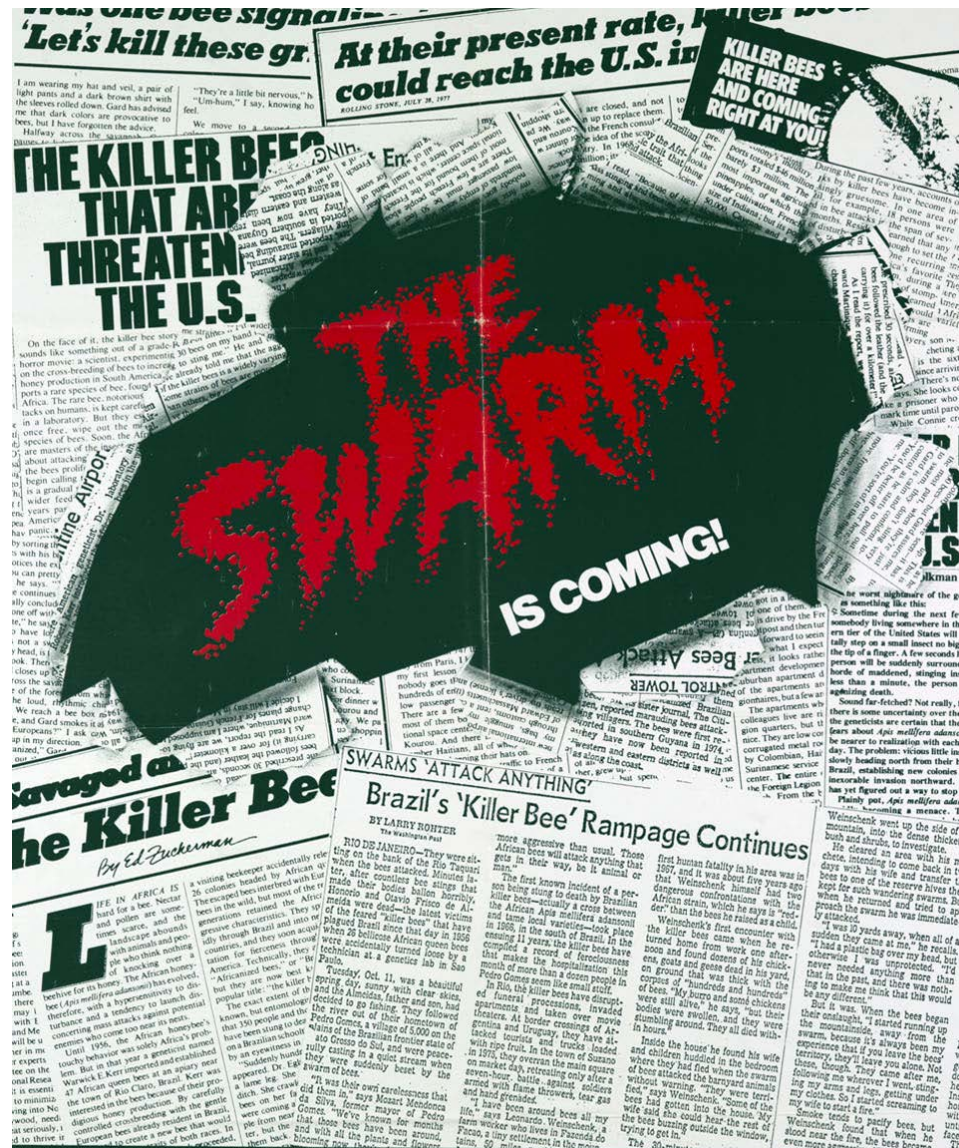
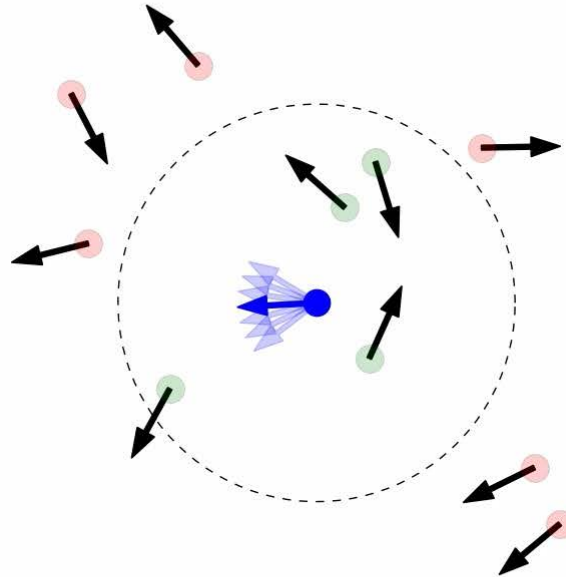


Computer simulations of complex systems



Lab PS I –
The Swarm

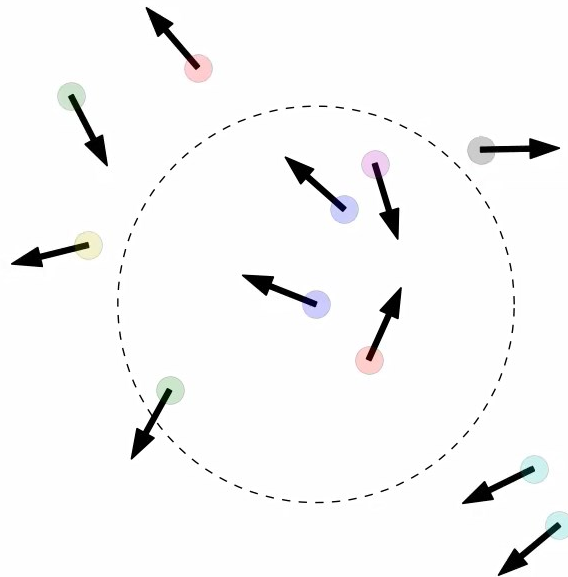
A simple swarming model



Vicsek, T., Czirók, A., Ben-Jacob, E., Cohen, I. and Shochet, O., 1995. Novel type of phase transition in a system of self-driven particles. *Physical review letters*, 75(6), p.1226.

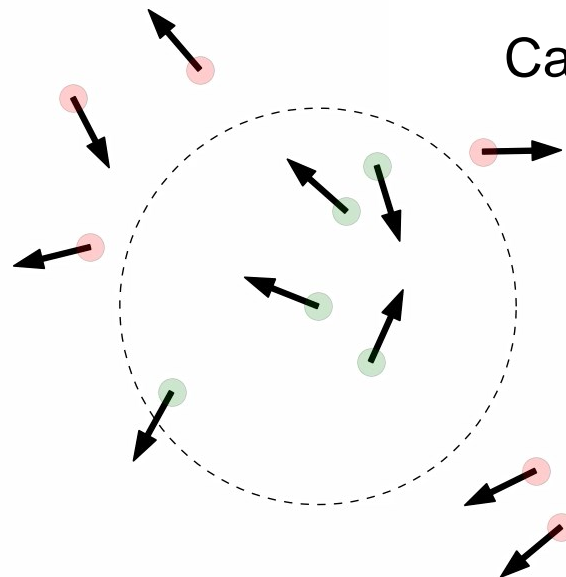
Step I

Find nearest neighbours



Step II

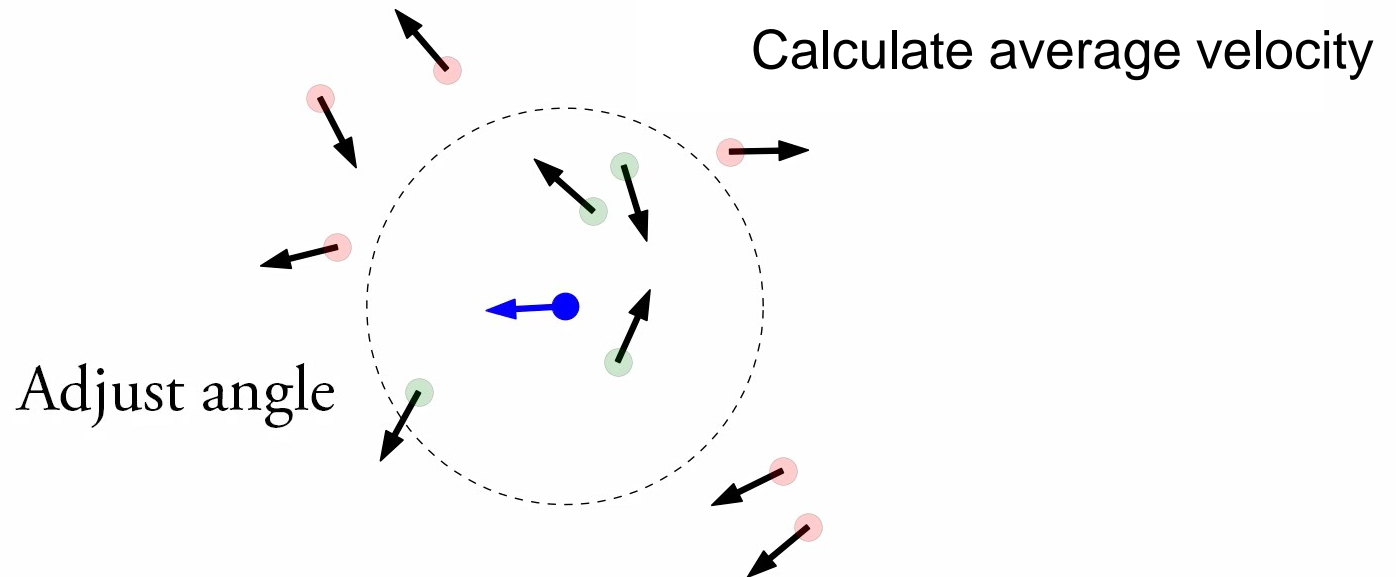
Find nearest neighbours



Calculate average velocity

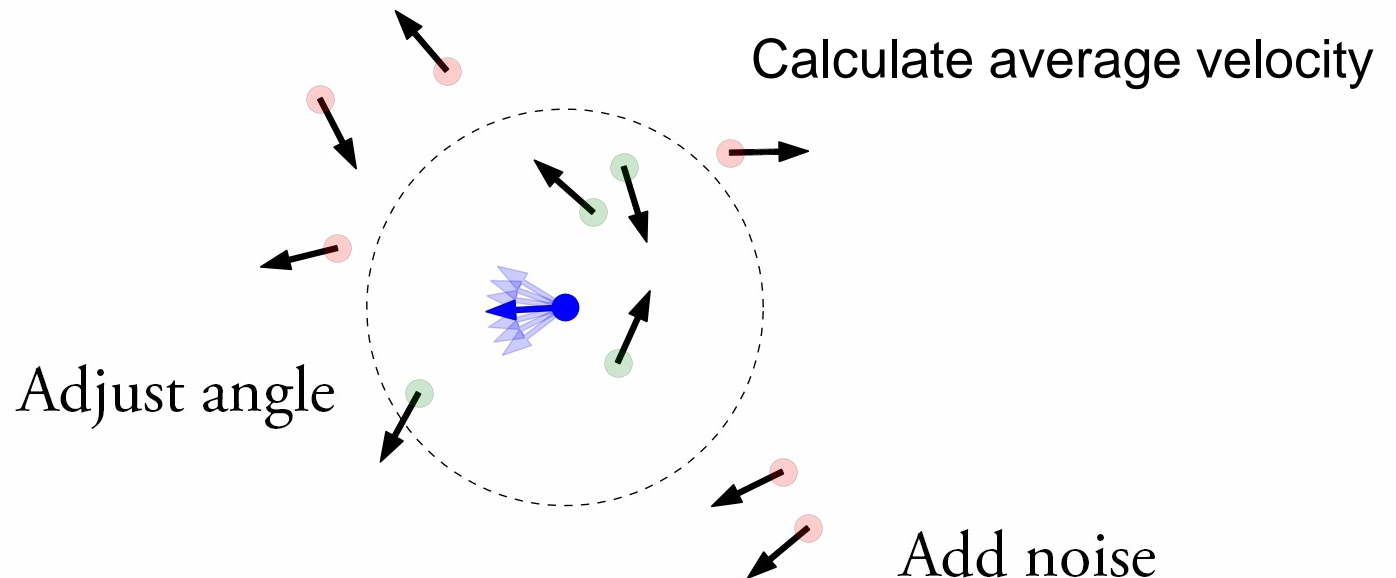
Step III

Find nearest neighbours

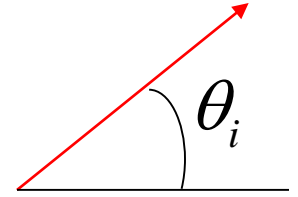


Step IV

Find nearest neighbours



Summary



new direction of bird i

$$\theta_i = \arg \left(\sum_k e^{i\theta_k} \right) + a\eta_i$$

amplitude

direction of average
velocity of the
neighbours

random term
(uniform in the angle)

new position of bird i

$$r_i(t + dt) = r_i(t) + v_0 \begin{pmatrix} \cos \theta_i \\ \sin \theta_i \end{pmatrix} dt$$

Your task

- Simulate swarming model for 5000 birds (0.5p)
- Add a bird of prey (0.5p)



- follows the closest bird
- all birds in a radius r_b run away from it

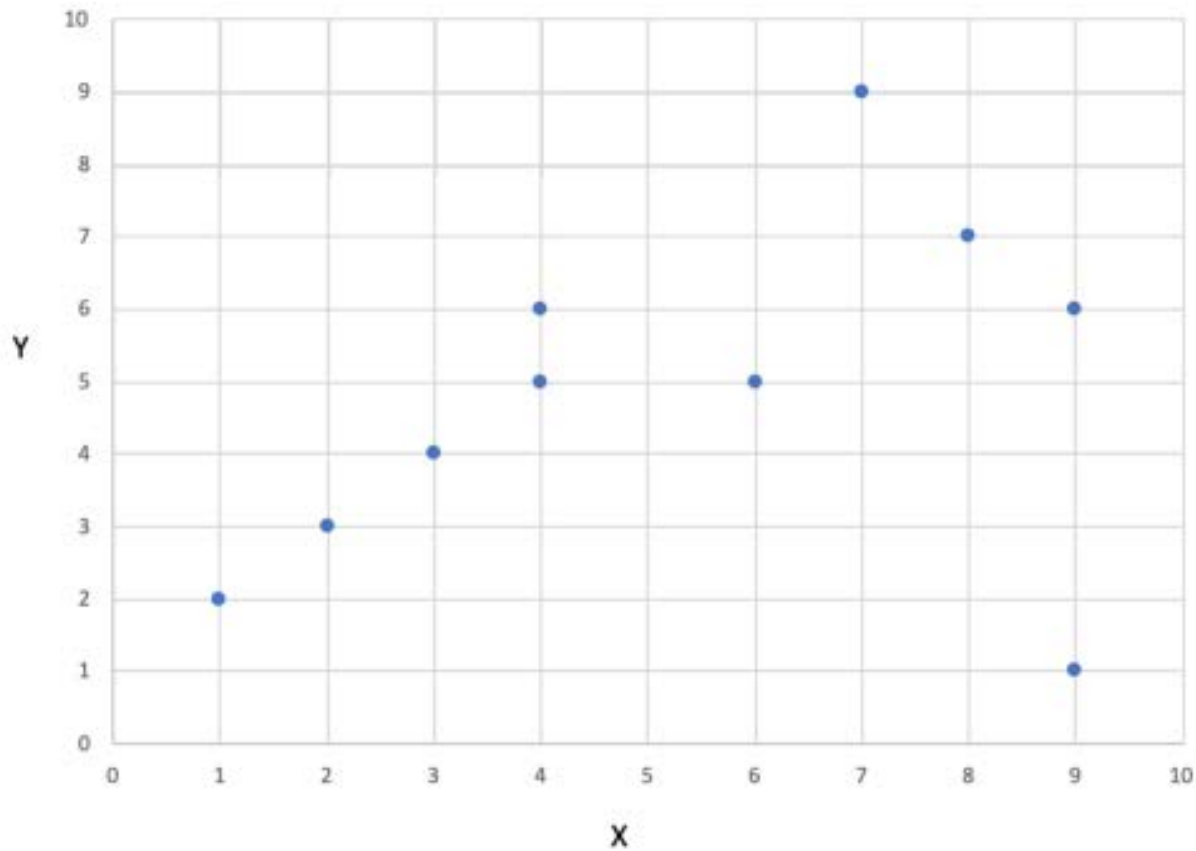
The (devil in the) details

- you need a fast way of getting the neighbours of bird i
- try to explore tree algorithms:

<https://towardsdatascience.com/tree-algorithms-explained-ball-tree-algorithm-vs-kd-tree-vs-brute-force-9746debcd940>

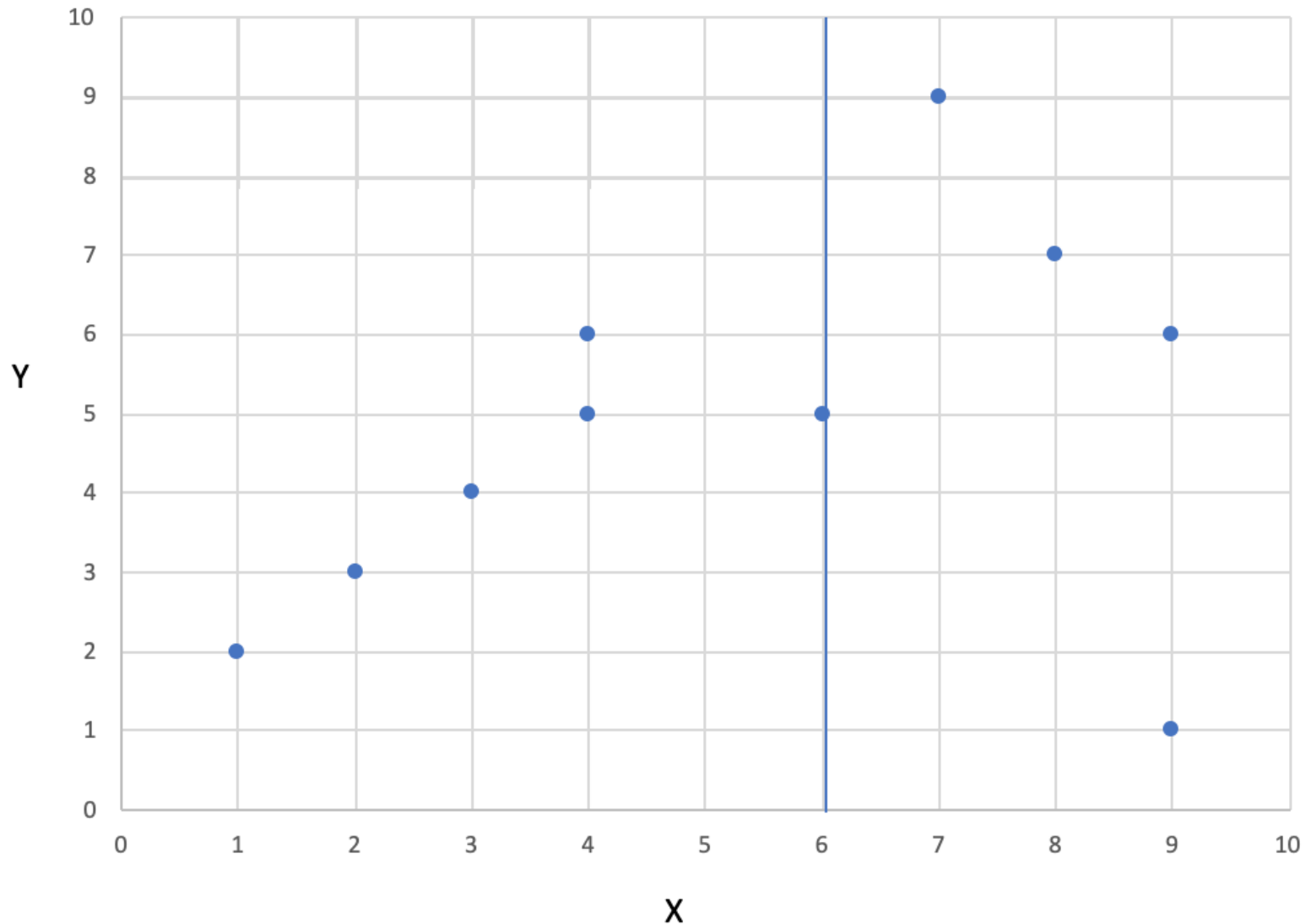
- one possibility is to use a kd-tree:

KDTree - example

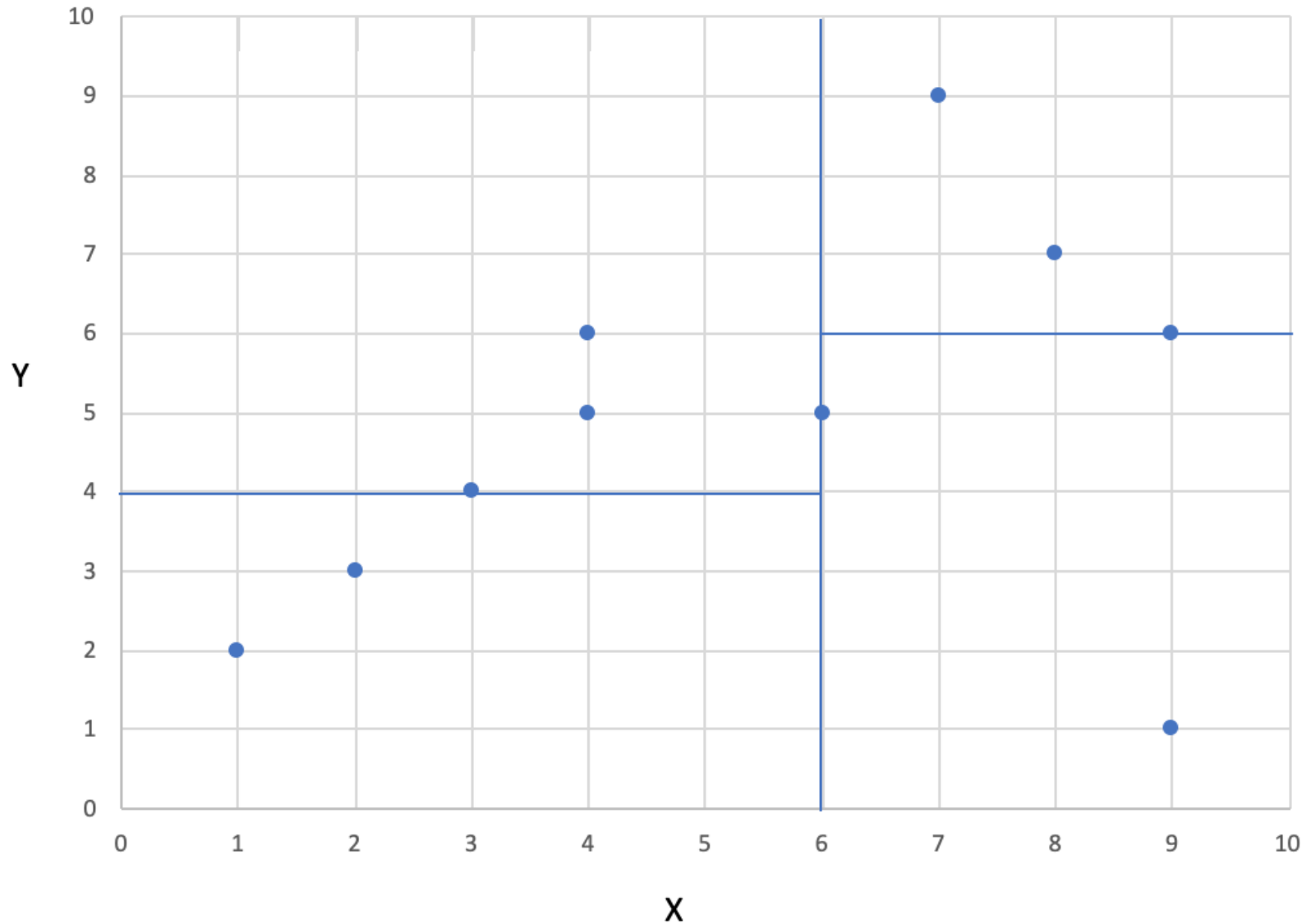


| X-Werte | Y-Werte |
|---------|---------|
| 9 | 1 |
| 3 | 4 |
| 4 | 6 |
| 6 | 5 |
| 2 | 3 |
| 8 | 7 |
| 7 | 9 |
| 9 | 6 |
| 1 | 2 |
| 4 | 5 |

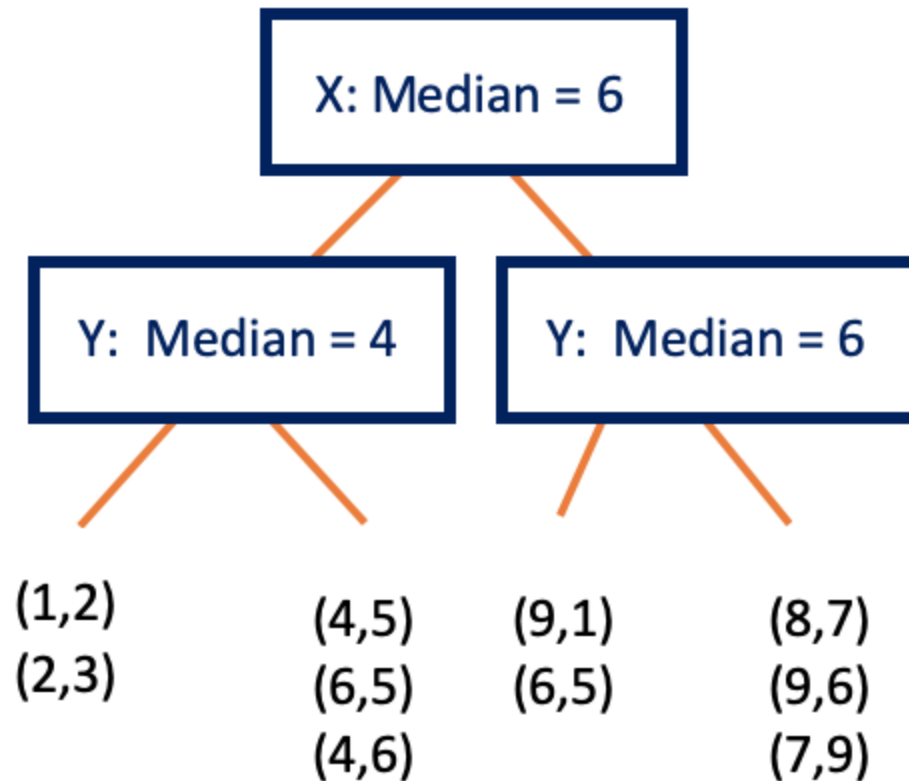
Division at the median along x



Division along y



Tree structure



Birds tree

```
from scipy.spatial import cKDTree
```


periodic boundary conditions

```
birds_tree = cKDTree(positions,boxsize=[L,L])
```



```
dist = tree.sparse_distance_matrix(birds_tree,max_distance=r,output_type='coo_matrix')
```

this produces a (sparse) matrix with distances
between birds (if they are smaller than r)



Other methods in cKDTree

`bird_tree.query(x, k)`

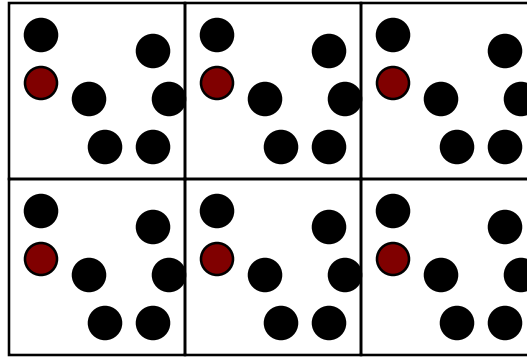
find k nearest neighbours to point x

`bird_tree.query_ball_point(x, r)`

Find all points within distance r of point(s) x.

- do not use any loops (except over time) - use `numpy.sum` to sum over the columns/rows of a matrix

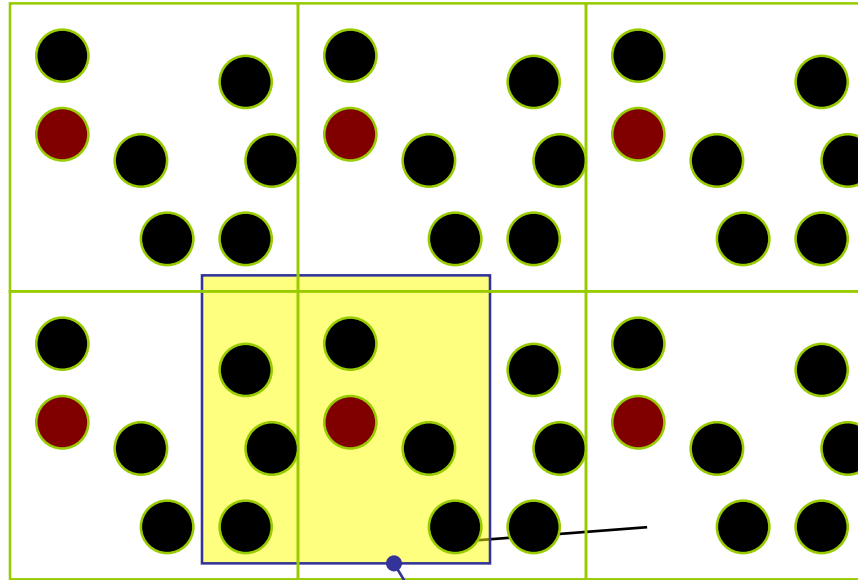
Periodic boundary conditions



```
if newX > L:  
    newX -= L ← size of the box  
if newX < 0:  
    newX += L
```

```
if newY > L:  
    newY -= L  
if newY < 0:  
    newY += L
```


Closest periodic image



The images of other particles closest to the red one

vector joining particle (i) and the closest periodic image of (j)

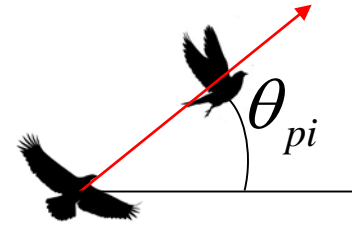
$$\mathbf{dr} = \text{np.remainder}(\mathbf{r}_i - \mathbf{r}_j + L/2., L) - L/2$$

Birds



- all fly with the same velocity v_0
- their initial distribution is uniform (both in positions and in orientations)

Bird of prey



- moves with the same velocity v_0 as the birds

- follows the closest bird

$$\theta_p = \theta_{pi} + a\eta_p$$

- all the birds within a range of r_b fly away from it, ignoring other birds:

$$\theta_i = \theta_{pi} + a\eta_i$$

Predator interaction radius

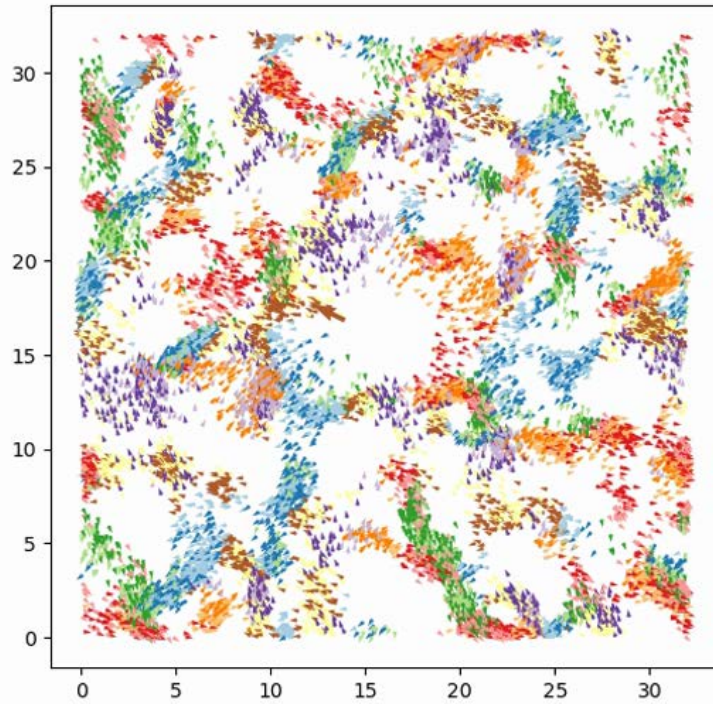


Visualization

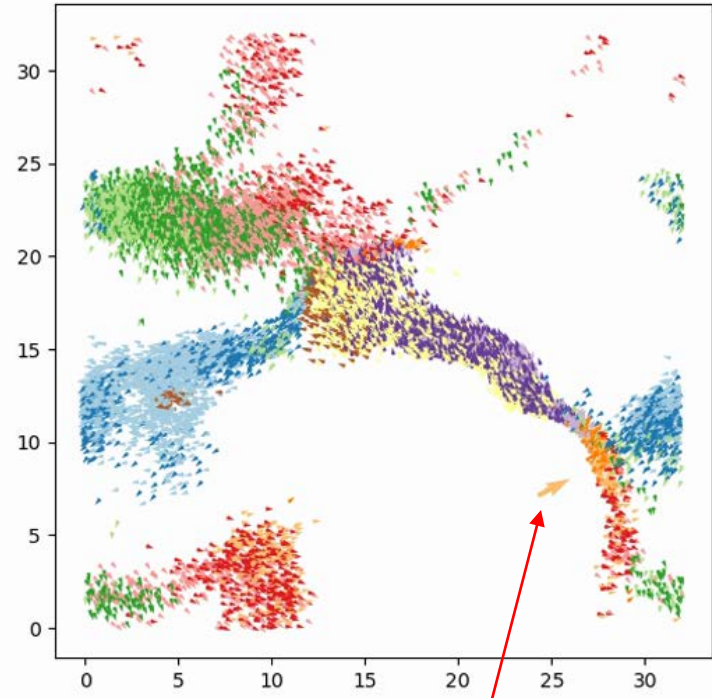
`matplotlib.pyplot.quiver([X, Y], U, V, [C])`

- plots a 2D field of arrows
- X, Y define the arrow locations, U, V define the arrow directions, and C optionally sets the color

use θ here



(here colors are related to orientations which helps in identifying clusters)



bird of prey

The details

- take e.g.:

$$L=32, N=5000-10000, r=1, r_b=4, v_0=2, a=0.15$$

- make a movie of several hundred frames
- for task one (w/o bird of prey) check if the system self-organizes after sufficiently long time (all birds flying in the same direction)
- how does the presence of the bird of prey impacts such a self-organization process?

Extra task

- look at the phase transition at the intensity of a noise is changed between 0 and 1

order parameter

$$\chi = \frac{1}{Nv_0} \left| \sum_i \vec{v}_i \right|$$

- plot and analyze $\chi(a)$

It's more than speculation-
It's a prediction!

THE SWARM

