

## Nearest Neighbor Classifiers

Recall the bayes decision rule is

$$p(y = k | x) \geq p(y = c | x), \forall k \neq c. \quad (1)$$

The nearest neighbor classifiers can be interpreted as adopting the bayes decision rule. But first we will introduce its heuristic.

Let  $S$  be a set of instances in  $\mathbb{R}^p$ , and  $z \in \mathbb{R}^p$  be a query instance. The  $k$  nearest neighbors of  $z$  are the instances (in  $S$ ) whose distances to  $z$  are smaller than other instances. A common choice of distance measure is Euclidean distance, i.e.,

$$d(x, z) = \sqrt{\sum_{i=1}^p (x_i - z_i)^2} = \|x - z\|_2. \quad (2)$$

The k-nearest neighbor (kNN) classifier assigns  $z$  to class  $c$  if most of its  $k$  nearest neighbors are from that class. For example, if we pick up five neighbors of  $z$  and find that three are from class 1 and two are from class 2, then  $z$  will be assigned to class 1. This classification rule is called majority voting. The neighborhood size  $k$  is a hyperparameter.

[*Discussion*] What to do if there is a tie in voting?

[*Discussion*] How would  $k$  affect the model complexity of kNN?

kNN does not have a model to fit. It simply stores all training data to classify testing data. Thus it is sometimes called ‘lazy classifier’, ‘memory-based classifier’, or ‘non-parameteric classifier’. It can suffer from high memory and computational costs.

A variant of kNN is fixed-radius nearest neighbor classifier. Instead of collecting votes from  $k$  nearest neighbors, it collects votes from the nearest neighbors whose distances to  $z$  are smaller than some radius  $\epsilon$ . This guarantees the voters are sufficiently similar to  $z$  (so they are more likely to be generated from the same distribution as  $z$  and thus representative of  $p(y | z)$ ).

## Statistical Justification of kNN

Under some assumptions, the kNN classification rule is equivalent to the bayes decision rule (1).

Let us draw a sphere centered at  $x$  and containing exactly  $k$  neighbors. Let  $k_c$  be the number of neighbors from class  $c$ . Let  $n$  be the total number of training examples, and  $n_c$  be number of training examples from class  $c$ . Let  $p(x)$  be the pdf of the population. Let  $V$  be the volume of the sphere. Let  $P$  be the probability mass of the sphere, which indicates how likely an instance will fall in the sphere. We can estimate  $P$  in two ways:

(1)  $P = \frac{k}{n}$ , because  $k$  instances (out of  $n$ ) fall in the sphere

(2)  $P = Vp(x)$ , because if the sphere is small, it is reasonable to assume  $p(x)$  is constant in it.

Combining both, we have  $\frac{k}{n} = Vp(x)$  and

$$p(x) = \frac{k}{nV} \quad (3)$$

Similarly analysis applies to neighbors from a particular class  $c$ . That gives

$$p(x \mid y = c) = \frac{k_c}{n_c V} \quad (4)$$

[Exercise] Verify (4).

On the other hand, we have

$$p(y = c) = \frac{n_c}{n}. \quad (5)$$

Putting (4), (3) and (5) together, and applying the Bayes' theorem, we have

$$p(y = c \mid x) = \frac{p(x \mid y = c)p(y = c)}{p(x)} = \frac{\frac{k_c}{n_c V} \frac{n_c}{n}}{\frac{k}{nV}} = \frac{k_c}{k}. \quad (6)$$

Recall kNN assigns  $x$  to class  $c$  if  $k_c \geq k_{c'}$  for any class  $c'$ . Based on (6), this is equivalent to

$$p(y = c \mid x) \geq p(y = c' \mid x). \quad (7)$$

This justifies the kNN classification rule is equivalent to the bayes decision rule, and thus can minimize the bayes error.