

Al & Pathfinding Ci410

What is Al?

The appearance of intelligence in Agents How does this manifest itself?

- Finding the player
- Blocking an attack
- Picking the correct attack
- Running away if fight can't be won

Breaking it down

REMINDER: All is there to entertain

Think of it as Artificial Stupidity

Needs to give a good game experience

Provides challenge whilst giving player win opportunities

With computers Intelligence is overrated and best faked

Come find me

Simple pathfinding

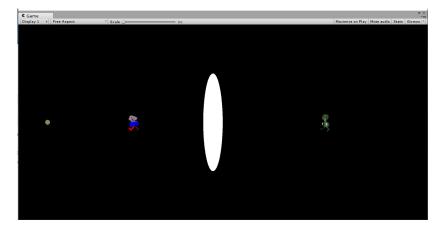
Vpath=Vdest-Vcurrent

Distance = |Vpath|

One optimal path

How about now?





Other consideration

Appearing more intelligent

- Facing your opponent
- Running away, with haste
- Slowing down when getting close

Anticipation

• Aiming where player will be, rather than where they are

Others?

Sensing the real world

Positions

Points in world space

Colliders

Volumes / Areas in world space

Anticipating

- Extrapolation, path between next & future
- Interpolation, path between last and next
- Raycasting

Cheating

Knowing vs. guessing velocity

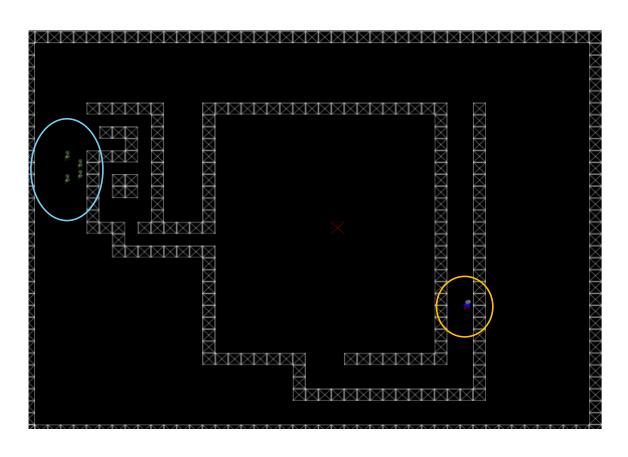
Pathfinding

A* (called "A Star")

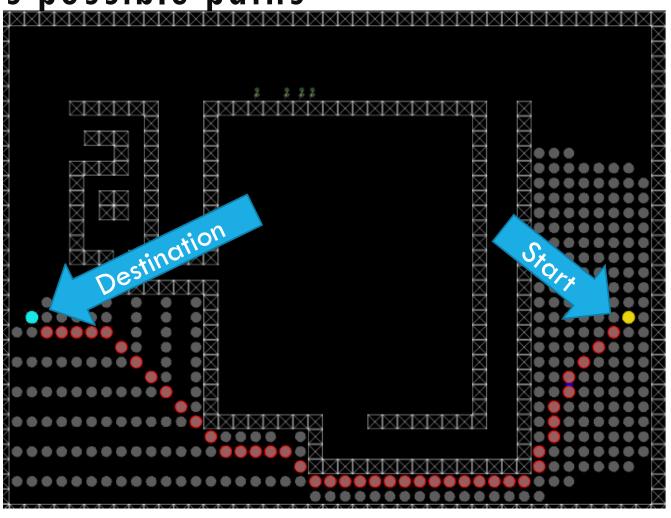
- A very common path finding algorithm
- Works by coming up with the least "cost" path between origin & destination
- Quite complex, you are not expected to remember it, source code sample on GitHub
- Requires knowledge of what is "navigable" i.e. can be walked on
- Can be computationally expensive

Zombie eat brains

http://modulo17.com/unity/astar/



Evaluates possible paths



Change level layout

Excel as level editor

Load map.csv in into Excel



Make sure you set text import delimiter to,

Tab

Semicolon

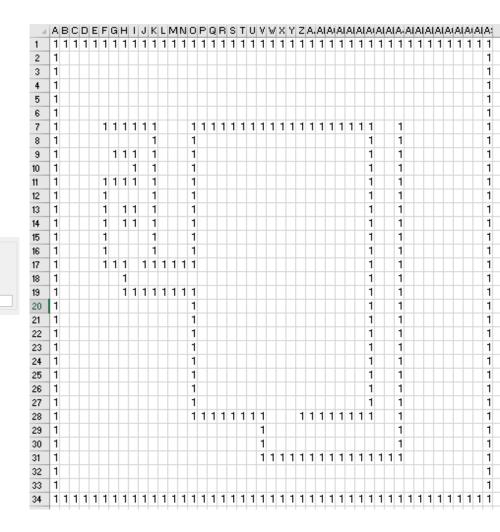
✓ Comma

Space

Other:



1 = wall



Navigating with A*

A* works well with an array

- It relies on rapidly knowing where it can step next
- It uses this to calculate routes from its current position to the destination

1	1	1	1	1
1			Х	1
1		1	1	1
1		1	1	1
1				1
1				1

- Blocked paths are "closed", they no longer form part of the search
- It picks open routes which get it closer to the target at the least cost
- http://theory.stanford.edu/~amitp/GameProgramming/Heuristics.ht
 ml

Navigating with Unity

NavMesh is a map of static walkable areas, it is baked in

NavAgent uses A* on a NavMesh for path finding around static objects

NavAgent uses RayCast to avoid other NavAgents & NavObstacles real-time

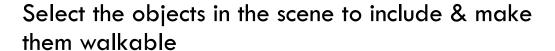
Some good resources here

https://docs.unity3d.com/Manual/nav-NavigationSystem.html

Before we can use navigation

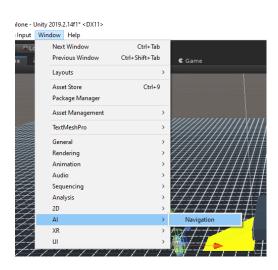
We need to "Bake a NavMesh"

This is done from the Navigation Window





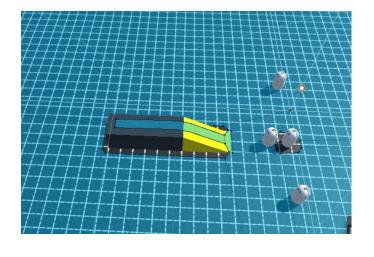


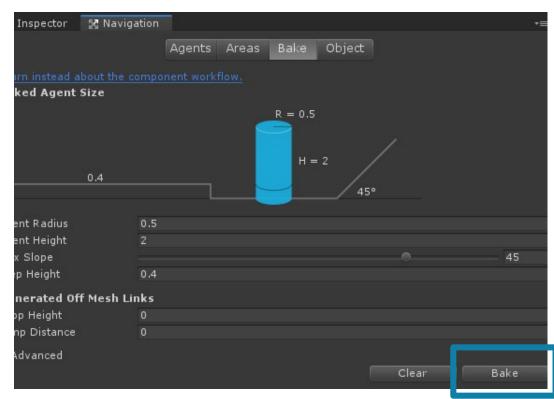


They can then be baked

On the Bake Tab

Once baked blue is walkable

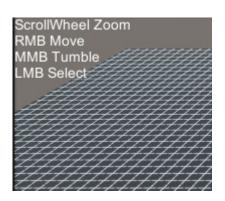


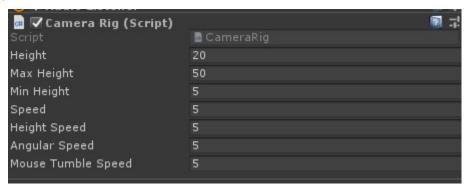


Camera Rig (CameraRig.cs)

Top down with some push movement

- Inspect the code in the lab, it will allow the scene to be viewed
- You can attach the script to an existing camera or delete the existing and use the script to make one
- It has lots of defaults you can use, controls on screen





The Camera also directs the Agents

Using a Raycast to see what's under the mouse, if its an agent toggle selection, if not then send all the selected agents there

```
void SetDestination()
   RaycastHit tHit;
   Ray tRay = mCamera.ScreenPointToRay(Input.mousePosition);
   if (Physics.Raycast(tRay, out tHit))
       Debug.DrawRay(tRay.origin, tRay.direction, Color.red);
       Agent tAgent = tHit.collider.GetComponent<Agent>(); //Did we hit an agent
       if (tAgent != null)
           tAgent.Selected = !tAgent.Selected;
           Debug.Log(tHit.collider.name);
        else
            Agent[] tAgents = FindObjectsOfType<Agent>(); //Get all the agents in the scene
            foreach (Agent tFoundAgent in tAgents)
                if (tFoundAgent.Selected) //Command selected ones
                    tFoundAgent.SetDestination(tHit.point);
                    tFoundAgent.Selected = false; //Deselect once its been commanded
```

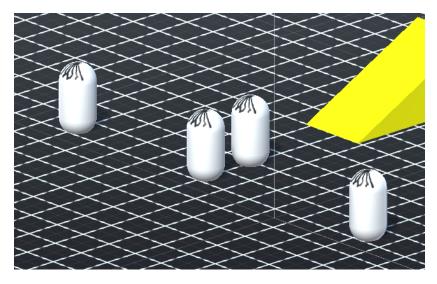
The Agents (Agent.cs)

They will navigate on the NavMesh

- They have a selected flag to mark them as selected or not
- Use the NavMeshAgent to get to destination

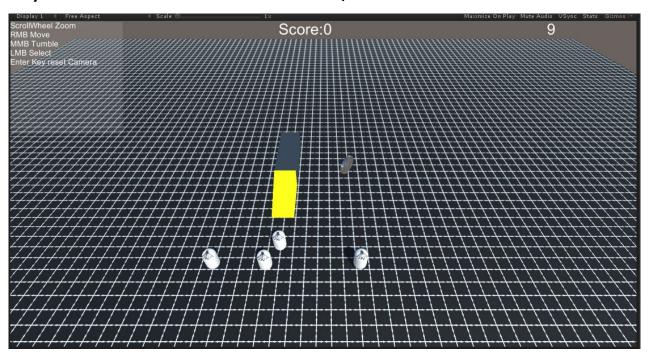
```
mNMA = GetComponent<NavMeshAgent>(); //If we have one use it
{
    mNMA = gameObject.AddComponent<NavMeshAgent>(); //If not add one
}

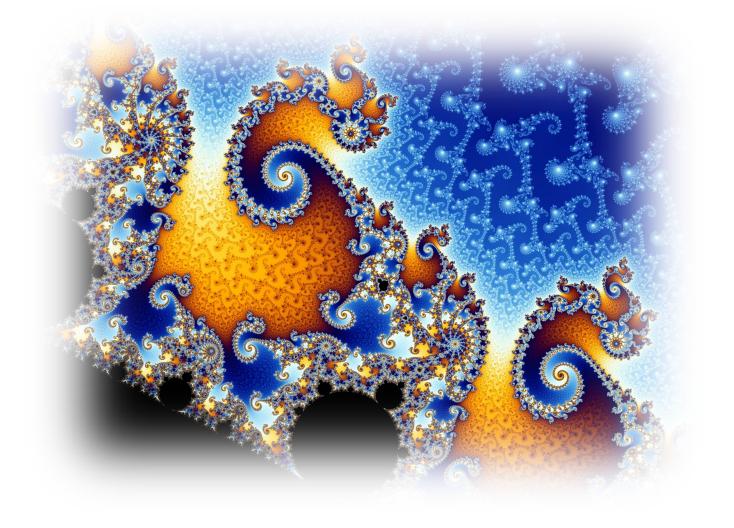
public void SetDestination(Vector3 vPosition)
{
    mNMA.SetDestination(vPosition);
}
```



The GM (GM.cs)

Pretty much the same as last week, handles score & time

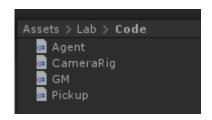




WORKSHOP

Workshop, make a Al based game

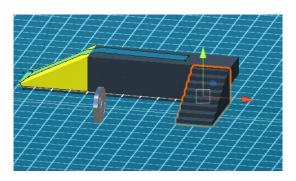
- 1. Review the scripts
- >Agent.cs
- **≻**CameraRig.cs
- > Pickup.cs
- >GM.cs

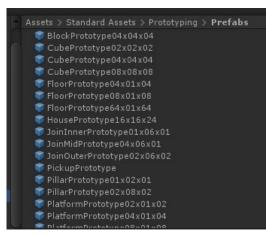


- 2. Try the supplied Scene and see the limitations of the NavMesh
- 3. Add more Geometry to the scene from standard

assets

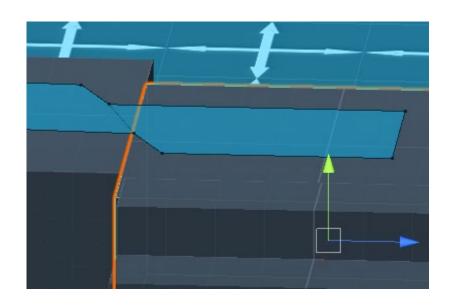
4. Rebake

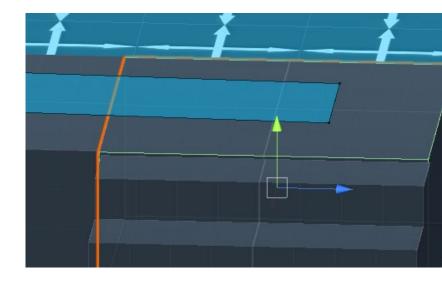




Fix any issues with Geometry

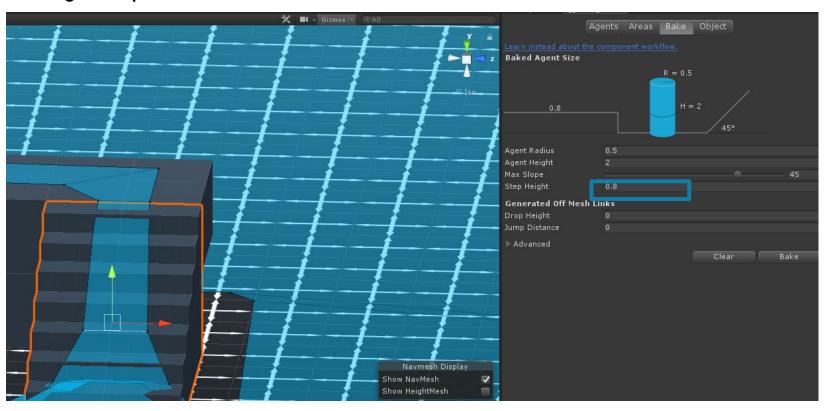
Such as gaps



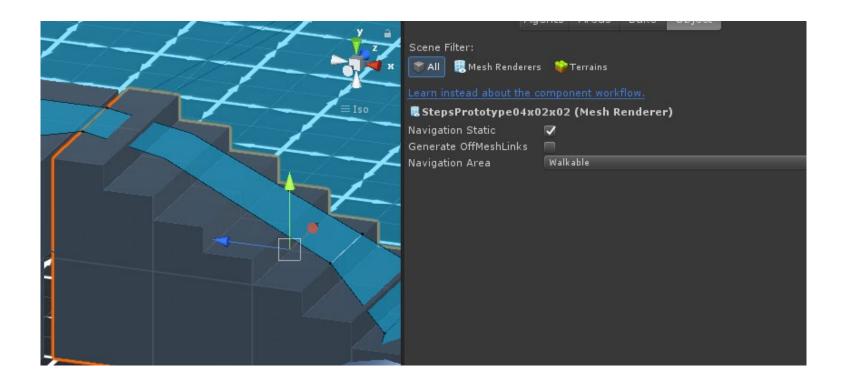


Steps too high?

Change Step Size



When baking make sure items are marked as Navigation static



Make a small game

- 1. Build a maze (using Standard asset proto prefabs)
- Ensure the NavMesh works
- 3. Hide pickups in the maze
- 4. Send the Agents in to find them
- They will get stuck, how would you know this? What could you do about it?