Homework 3

Course: CO19-320322

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This assignment was solved together with Fezile Manana and Brian Sherif.

Exercise 3.1 Solution:

1. Mid-points of pixels on the screen:

$$(1,1,0), (1,-1,0), (-1,-1,0), (-1,1,0)$$

Ray vectors from camera (0, 0, -10):

$$\vec{r_1} = \begin{pmatrix} 1 \\ 1 \\ 10 \end{pmatrix} \therefore r_1 = x = y = \frac{z+10}{10}$$

$$\vec{r_2} = \begin{pmatrix} 1 \\ -1 \\ 10 \end{pmatrix} \therefore r_2 = x = -y = \frac{z+10}{10}$$

$$\vec{r_3} = \begin{pmatrix} -1 \\ -1 \\ 10 \end{pmatrix} \therefore r_3 = -x = -y = \frac{z+10}{10}$$

$$\vec{r_4} = \begin{pmatrix} -1 \\ 1 \\ 10 \end{pmatrix} \therefore r_4 = -x = y = \frac{z+10}{10}$$

The only intersecting ray is r_1 intersecting the red triangle at point (1.2, 1.2, 2)

2. Phong illumination model formula:

$$I_p = k_a i_a + \sum_{m \in lights} (k_d (\hat{L}_m \cdot \hat{N}) i_{m,d} + k_s (\hat{R}_m \cdot \hat{V})^{\alpha} i_{m,s})$$

where \hat{N} is the normal, \hat{V} is the direction pointing towards the viewer, α is the shininess constant and R_m is the direction of the reflected ray of light given by

$$R_m = 2(\hat{L}_m \cdot \hat{N})\hat{N} - \hat{L}_m$$

Given:

Vertices:
$$v_1 = (0, 4, 2)$$
; $v_2 = (0, 0, 2)$; $v_3 = (4, 0, 2)$; $v_4 = (5, 5, 2)$

Triangle 1
$$\Rightarrow$$
 vertices = (v_1, v_2, v_3) ; RGB = $(1, 0, 0)$

Triangle 2
$$\Rightarrow$$
 vertices = (v_1, v_2, v_4) ; RGB = $(1, 1, 0)$

$$k_a = (\frac{2}{3}, \frac{2}{3}, \frac{2}{3})$$

$$k_d = (\frac{1}{3}, 0, \frac{2}{3})$$

$$k_s = (\frac{1}{9}, \frac{1}{9}, \frac{1}{9})$$

$$\alpha = 5$$

$$V = (0, 0, -10)$$

$$L=(5,5,1)$$

$$N = (0, 0, -2)$$

With this we get intensities for ambient, diffuse and specular reflections:

$$I_{v_1} = \begin{pmatrix} 0.730912 \\ 0.666762 \\ 0.795062 \end{pmatrix}$$
 $I_{v_2} = \begin{pmatrix} 0.713349 \\ 0.666673 \\ 760025 \end{pmatrix}$ $I_{v_3} = \begin{pmatrix} 0.730912 \\ 0.666762 \\ 0.795062 \end{pmatrix}$ $I_{v_4} = \begin{pmatrix} 1 \\ 0.719409 \\ 1 \end{pmatrix}$

Computed colours:

$$RGB_{v_1}^{\mathbf{1}} = (0.730912, 0, 0)$$

$$\begin{array}{l} RGB_{v_2} = (0.713349, 0, 0) \\ RGB_{v_3} = (0.730912, 0, 0) \\ RGB_{v_4} = (1, 1, 0) \end{array}$$

$$RGB_{v_2} = (0.730912, 0, 0)$$

$$RGB_{v_A} = (1, 1, 0)$$

3. As only one sample ray intersects with the triangle, this is the only ray we need to evaluate. Therefore we need to find the colour at point p = (1.2, 1.2, 2)

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Distance from light to camera via vertices:
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d_{v_1} = 17.8453

d_{v_2} = 19.1414

d_{v_3} = 17.8453
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Colour at vertices with attenuation $f(r) = \frac{1}{r}$

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RGB_{v_1} = (0.0409583, 0, 0)

RGB_{v_2} = (0.0372673, 0, 0)

RGB_{v_3} = (0.0409583, 0, 0)
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Therefore, colour at sample point is:

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RGB_p = u \cdot RGB_{v_1} + v \cdot RGB_{v_2} + w \cdot RGB_{v_3} \Rightarrow (0.0350526, 0, 0) where u, v, and w are attained from Barycentric coordinates about p = (1.2, 1.2, 2) giving u = -0.3, v = 1.6, and w = -0.3.
```

Exercise 3.2 Solution:

	10	11	12	13	14	15	16	17	18
120									
119									
118									
117									

Brensenham's Algorithm [1]

```
function line(x0, y0, x1, y1)
    real deltax := x1 - x0
    real deltay := y1 - y0
    real deltaerr := abs(deltay / deltax) // We assume that the line is not vertical
    real error := 0.0 // No error at start
    int y := y0
    for x from x0 to x1
        plot(x,y)
        error := error + deltaerr
        if error >= 0.5 then
            y := y + sign(deltay) * 1
        error := error - 1.0
```

$$\begin{aligned} d_x &= 18 - 10 = 8 \\ d_y &= 117 - 120 = -3 \\ d_{err} &= \left| \frac{d_y}{d_x} \right| = \frac{3}{8} = 0.375 \end{aligned}$$

		_			
	Step	X	y	error	
	1	10	120	0.375	
	2	11	120	-0.25	
	3	12	119	0.125	
	4	13	119	-0.5	
	5	14	118	-0.125	
	6	15	118	0.25	
•	7	16	118	-0.375	
•	8	17	117	0	
	9	18	117	0.375	

Xiaolin Wu's Algorithm [2]

Please run 'python3 xiaolin.py img.jpg' and see the results.

Step	x	y	alpha
1	11	119	0.375
2	11	120	0.625
3	12	119	0.75
4	12	120	0.25
5	13	118	0.125
6	13	119	0.875
7	14	118	0.5
8	14	119	0.5
9	15	118	0.875
10	15	119	0.125
11	16	117	0.25
12	16	118	0.75
13	17	117	0.625
14	17	118	0.375

Exercise 3.3

Solution:

Please check 'bouncingballs.cpp'.

To compile and execute enter the following lines in the terminal:

References

- [1] Bresenham's line algorithm
- [2] Xiaolin Wu's line algorithm