

# Homework 1, Computer Graphics 2019

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Handed out 14.03.2019, due 22.03.2019 at 11:15)

This is a theoretical assignment, to be solved without using programming (although, of course, you can use a program to verify your results!). Please upload this homework (in pdf - generated in word, latex or simply scanned) using the assignment submission on moodle (<http://moodle.jacobs-university.de>) of our course. In case of technical problem with the platform, notify us and send it to the TAs ([m.thanasi@jacobs-university.de](mailto:m.thanasi@jacobs-university.de), [muh.hassan@jacobs-university.de](mailto:muh.hassan@jacobs-university.de)) **before** the deadline.

## Problem 1.1 Computer Graphics (Alternative) Facts

(5 points)

Mark the following statements True (T) or False (F)

1	Every Cartesian coordinate system is orthogonal. Every orthogonal coordinate system is parallel	T	F
2	Non-uniform scaling transformation is linear	T	F
3	Order of transformations does not matter if one uses homogeneous coordinates	T	F
4	Perspective projection in OpenGL yields vertices coordinates in $(x, y)$ such that $x \in \langle 0, \text{screen\_width} - 1 \rangle, y \in \langle 0, \text{screen\_height} - 1 \rangle$	T	F
5	OpenGL functions starting with glu prefix are hardware-specific	T	F

## Problem 1.2 Geometry transformations

(10 points)

We are given a triangle with vertices  $p_1 = (3, 0, 2)$ ,  $p_2 = (2, 0, 2)$ , and  $p_3 = (1, 1, 2)$  expressed in 3-D Cartesian coordinates. Let  $v = (0, 0, 0)$  be the camera origin. Let the screen be the rectangle with the following vertices:  $v_1 = (-1, -1, 1)$ ,  $v_2 = (1, -1, 1)$ ,  $v_3 = (1, 1, 1)$ , and  $v_4 = (-1, 1, 1)$ .

(a) The triangle is scaled with factors 3 and  $-1$  in the x- and y-coordinate, respectively, rotated (clockwise) by  $90^\circ$  around the z-coordinate, and translated by distance  $b_x = 2$  units in the direction of the x-coordinate. The transformations are executed in the given order.

- Derive the transformation matrix of each transformation step in homogeneous coordinates.
- Compute the combined transformation matrix in homogeneous coordinates.
- Apply the combined transformation matrix to triangle.

(b) The triangle is projected into the given image plane using perspective projection.

- Compute the projection matrix  $A$  in homogeneous coordinates for the given example. Leave the depth-related components  $a = b = 1$ .
- Apply the projection matrix  $A$  to the triangle and give the results to 2-D Cartesian screen coordinates, with the origin of the screen at  $(0,0,1)$ . Remember that a projection takes two stages!

## Problem 1.3 Parallel projection

(10 points)

Recall the demo cube used on blackboard during the first lectures, with the eight corners at every  $p = (x, y, z)$  with  $x, y, z \in -1, 1$ .

- Compute matrix  $H_{ry}$  which will allow you to apply a rotation about the y-axis by angle  $\theta = 30^\circ$  and matrix  $T_x$  which will allow you to translate the cube along the x-axis by  $b_x = 0.5$  units in homogeneous coordinates.
- Apply the combined transformation matrix to the cube and compute the new vertex coordinates.

Orthographic projection (visualised in Fig. 1) is expressed in the following way in OpenGL:

$$\begin{bmatrix} \frac{2}{r-l} & 0 & 0 & -\frac{r+l}{r-l} \\ 0 & \frac{2}{t-b} & 0 & -\frac{t+b}{t-b} \\ 0 & 0 & \frac{-2}{(f-n)} & -\frac{f+n}{(f-n)} \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

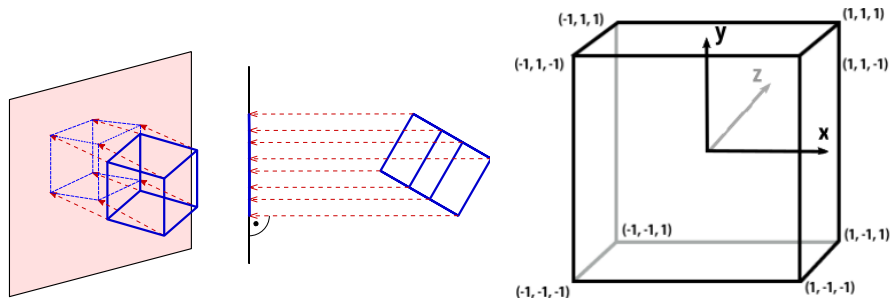


Figure 1: Orthographic projection of a cube visualised and the demo cube.

- Assuming  $r = -l$  and  $t = -b$  pick appropriate camera frustum parameters  $r, l, t, b, f$  and  $n$  to complete the matrix and ensure that all points of the cube are in the frustum ( $\equiv$  they will remain in the unit cube after the projection). Remark: frustum in case of orthographic projection is much simpler than in case of perspective projection!
- Assuming the same camera position as in the previous exercise, carry out the projection of the transformed cube's vertices.
- If the cube was to be translated along the z-axis by 1 unit towards the camera, would you have to update your frustum parameters  $r, l, t$  and  $b$ ? Explain your answer.