

$$D = \{(x_1, y_1), \dots, (x_n, y_n)\}$$

$$x \in \mathbb{R}^d$$

$$y \in \begin{cases} \{0,1\} \text{ B.C.} \\ \{1,2,\dots,c\} \text{ M.C.C.} \\ \mathbb{R} \text{ REGR.} \end{cases}$$

THE MORE DATA I HAVE
THE MORE I KNOW ABOUT
THE SYSTEM (INDEP.),
THE DATA DOESN'T
CHANGE IN TIME
(IDENTICALLY DISTR.)

→ i.i.d.

$$\hat{y} = f(x) = \sum_{i=0}^p a_i x^i$$

loss func. is
BOUNDED (NEW HYPOTHESIS)



$$\ell(f(x), y) = (y - f(x))^2 \text{ SQUARED ERROR (LOSS FUNCTION)} \in [a, b]$$

$$\hat{R}(f) = \frac{1}{n} \sum_{i=1}^n \ell(f(x_i), y_i) \text{ EMPIRICAL ERROR}$$

$$R(f) = E_{x,y} \ell(f(x), y) \text{ TRUE ERROR}$$

IF THE FUNC. IS INDEPENDENT FROM
THE DATA: WE CAN PROVE:

STATISTICS
on ind f

$$|R(f) - \hat{R}(f)| < \sqrt{\frac{1}{n\delta}} \quad 1-\delta$$

WE WANT TO FIND THE BEST FUNCTION:

$$f^* = \arg \min_{f \in F} R(f)$$

✓ WE DON'T KNOW THE DISTRIBUTION
THAT GENERATED MY DATA

↑ I KNOW THAT IS
BOUNDED!



$$f^* = \arg \min_{f \in F} \hat{R}(f) + \lambda C(f)$$

$\sqrt{\frac{M_f-1}{n\delta}}$: still we don't know $M_f \Rightarrow$ I CAN USE $\int_0^1 \left(\frac{d^2 f}{dx^2} \right)^2 dx$

STATISTICAL
LEARNING

$$|F| = M_f \text{ ind } f$$

IF THE SET OF FUNC. IS INDEPENDENT
FROM THE DATA:

$$|R(f) - \hat{R}(f)| < \sqrt{\frac{1}{n\delta}} + \sqrt{\frac{M_f-1}{n\delta}}$$

IN • THERE ARE THE CHOICES, IN • THE PARAMETERS I CAN CHANGE.

WHAT IS THE NOISE?

- MEASURE
- KNOWLEDGE

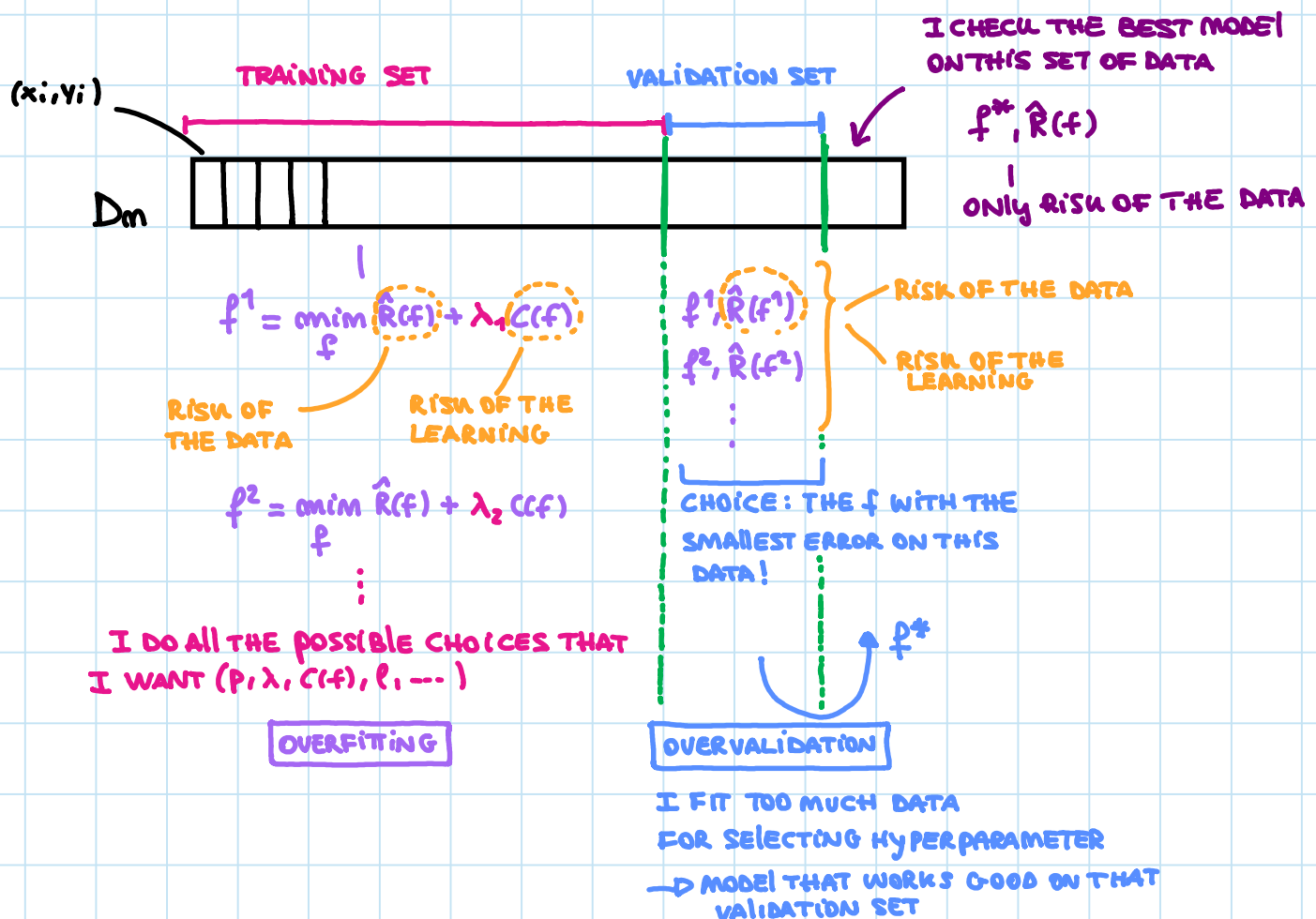
NO FREE LUNCH THEOREM: IT ALWAYS EXIST AN ALGORITHM THAT CAN PERFORM BETTER ON A SPECIFIC TASK WITH RESPECT TO ALL THE ALGORITHMS THAT EXIST IN THE REAL WORLD.

⇒ THERE WILL BE ALWAYS A MODEL BETTER THAN THE ONE YOU DEVELOPED.

SHORTCUT: I DON'T TRY TO UNDERSTAND WHAT REGULATES REAL WORLD PHENOMENA, BUT I SEARCH ONLY FOR RELATIONS BETWEEN EVENTS ⇒ SOONER OR LATER YOU'LL PAY THE PRICE

HOW TO CHOOSE $\lambda, p, (l, f, \dots)$ IN A GROUNDED WAY? WE DON'T KNOW ANY OPTIMAL WAY.

① CAN I REMOVE THE LEARNING PART FROM THE EQUATION? ⇒ THE RISK DUE TO THE DATA.



THE **TRAINING SET** IS BIG BECAUSE WE HAVE A LOT OF RISK TO MINIMIZE.

I CAN SPLIT MY DATA INTO 3 PARTS BECAUSE IT'S I.I.D.

BEFORE DEPLOYING YOUR MODEL THE ONLY WAY TO BE SAFE IS TO KEEP SOME FRESH DATA IN THE POCKET!

WHEN I TEST MY MODEL I HAVE TO DO IT WITH ON A SET OF DATA THAT I DIDN'T USED BEFORE.

IN THE VALIDATION SET I TAKE A FUNCTION THAT I LEARNED FROM THE DATA ON THE LEFT AND I TEST IT ON A SET OF DATA THAT IT HASN'T SEEN BEFORE.

SO f^1 IS INDEPENDENT FROM THE DATA.