Introduction to OS

Dr. Ahmed Awais

Chapter 1: Introduction

- What Operating Systems Do
- Computer-System Organization
- Computer-System Architecture
- Operating-System Structure
- Operating-System Operations
- Process Management
- Memory Management
- Storage Management
- Protection and Security
- Distributed Systems
- Special-Purpose Systems
- Computing Environments
- Open-Source Operating Systems

CHAPTER OBJECTIVES

- Describe the general organization of a computer system and the role of interrupts.
- Describe the components in a modern multiprocessor computer system.
- Illustrate the transition from user mode to kernel mode.
- Discuss how operating systems are used in various computing environments.
- Provide examples of free and open-source operating systems.

What is an Operating System?

- A program that acts as an intermediary between a user of a computer and the computer hardware
- Operating system goals:
 - Execute user programs and make solving user problems easier
 - Make the computer system convenient to use
 - Use the computer hardware in an efficient manner



Desktop Operating Systems

Windows Versions

macOS

macOS Monterey

macOS Ventura

Linux Distributions

Ubuntu

Fedora

Debian

Arch Linux

Mint

Mobile Operating Systems

Android

iOS

Windows Phone (no longer supported)

Server Operating Systems

Windows Server

Linux Server Editions

CentOS

Red Hat Enterprise Linux (RHEL)

SUSE Linux Enterprise Server (SLES)

Unix

AIX

HP-UX

Solaris

Embedded Operating Systems

FreeRTOS

VxWorks

QNX

Other Notable Operating

Systems

Chrome OS

OpenBSD

ReactOS (an open-source

Windows alternative)

Real-Time Operating Systems (RTOS)

1.RTEMS - Real-Time Executive for

Multiprocessor Systems (RTEMS)

2.Integrity

3. Nucleus

RTOS	Example Applications		
RTEMS	Used in space applications, such as the NASA's Mars Rover.		
Integrity	Commonly used in automotive systems for safety-critical tasks, like airbag control systems.		
Nucleus	Employed in medical devices, such as patient monitoring systems and infusion pumps.		

Type of Operating System	Examples	Key Characteristics
Desktop Operating Systems	Windows 10, Windows 11, macOS Ventura, Ubuntu, Fedora	Designed for personal computers; support a wide range of applications; user-friendly interfaces.
Mobile Operating Systems	Android, iOS, Windows Phone	Optimized for mobile devices; focus on touch interfaces; often have app stores for software distribution.
Server Operating Systems	Windows Server, CentOS, Red Hat Enterprise Linux (RHEL), SUSE Linux, AIX	Tailored for server hardware; support multiple users and processes; focus on stability and performance.
Embedded Operating Systems	FreeRTOS, VxWorks, QNX	Designed for specific hardware; often real-time systems; minimal resources and tailored for specific tasks.
Real-Time Operating Systems (RTOS)	RTEMS, Integrity, Nucleus	Provide deterministic response times; used in critical applications where timing is crucial.
Other Notable Operating Systems	Chrome OS, OpenBSD, ReactOS	Diverse functions; Chrome OS is web-centric, OpenBSD focuses on security, ReactOS aims to be Windows-compatible.

Which OS Is Mostly Used By Software Engineers?

Software engineers use different operating systems based on what they like, the type of work they do, and the industry they work in. The three most prevalent operating systems among software engineers include:

- Windows: Windows is widely used in corporate environments and by developers
 working on Microsoft technologies such as .NET framework, C#, and Visual Studio.
 Many software engineers find Windows convenient for its broad compatibility with
 commercial software and hardware.
- Linux: Linux is highly favored among software engineers, especially those involved in systems programming, web development, and open-source projects. Its robust command-line interface (CLI), vast array of development tools, and customization options make it popular for tasks ranging from server management to embedded systems development.
- macOS: macOS is preferred by many software engineers working in creative industries such as app development, UX/UI design, and multimedia production. It combines a Unix-based environment with a user-friendly interface and is known for its seamless integration with iOS development tools (Xcode).

The choice of operating system often depends on factors such as the developer's specific role, the technologies they work with, and personal preferences for development workflows and tools. Many developers also use multiple operating systems through virtualization or dual-boot setups to leverage the strengths of each platform for different aspects of their work.

Why we use an Operating System?

Because we need to interact with machines



Have you seen one before?

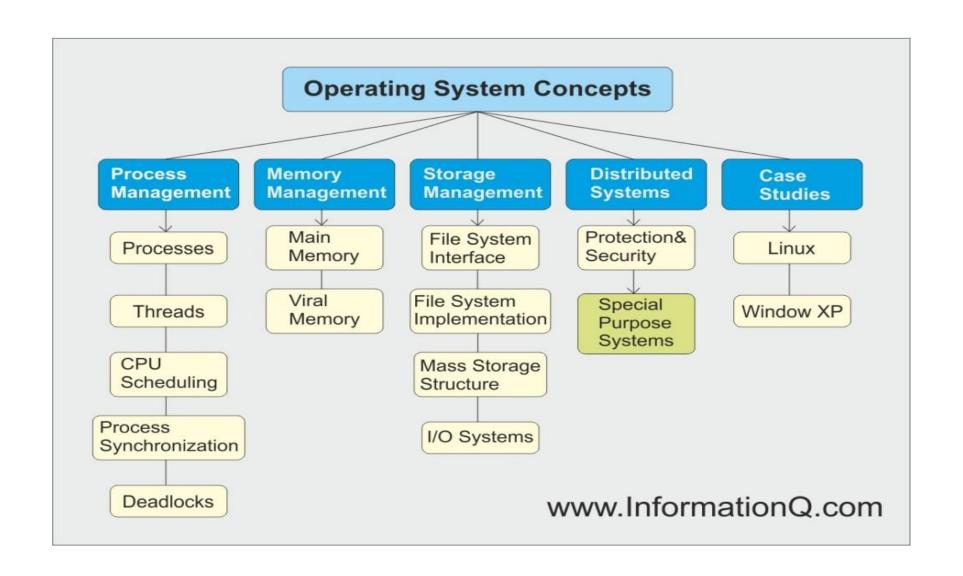












Computer System Structure

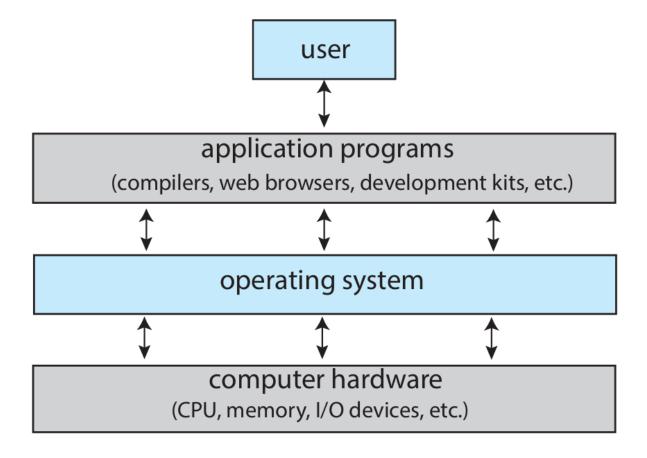


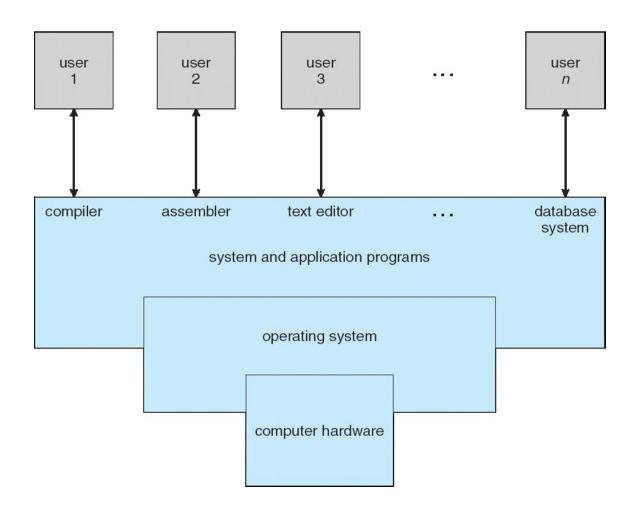
Figure 1.1 Abstract view of the components of a computer system.

Four Components of a Computer System

Computer System Structure

- Computer system can be divided into four components:
 - Hardware provides basic computing resources
 - CPU, memory, I/O devices
 - Operating system
 - Controls and coordinates use of hardware among various applications and users
 - Application programs define the ways in which the system resources are used to solve the computing problems of the users
 - Word processors, compilers, web browsers, database systems, video games
 - Users
 - People, machines, other computers

Four Components of a Computer System



What Operating Systems Do

- Depends on the point of view
- Users want convenience, ease of use
 - Don't care about resource utilization
- But shared computer such as mainframe or minicomputer must keep all users happy
- Users of dedicate systems such as workstations have dedicated resources but frequently use shared resources from servers
- Handheld computers are resource poor, optimized for usability and battery life
- Some computers have little or no user interface, such as embedded computers in devices and automobiles

Defining OS

- Nowadays, Computers are present within toasters, cars, ships, space craft, homes, and businesses. They are the basis for game machines, cable TV tuners, and industrial control systems.
- Initially OS were fixed-purpose systems for military uses, such as code breaking and trajectory plotting, and governmental uses, such as census calculation. Those early computers evolved in to general-purpose, multifunction mainframes, and that's when operating systems were born.

Moore's Law about OS

- Inthe1960s, Moore's Law predicted that the number of transistors on an integrated circuit would double every 18 months, and that prediction has held true.
- Computers gained in functionality and shrank in size, leading to a vast number of uses and a vast number and variety of operating systems. (See Appendix A for more details on the history of operating systems.)

Operating System Definition

- OS is a resource allocator
 - Manages all resources
 - Decides between conflicting requests for efficient and fair resource use
- OS is a control program
 - Controls execution of programs to prevent errors and improper use of the computer

Operating System Definition (Cont.)

- No universally accepted definition
- "Everything a vendor ships when you order an operating system" is good approximation
 - But varies wildly
- "The one program running at all times on the computer" is the **kernel**. Everything else is either a system program (ships with the operating system) or an application program.

Computer Startup

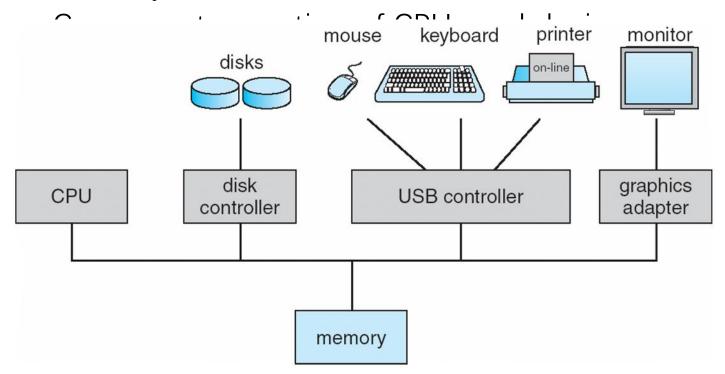
- bootstrap program is loaded at power-up or reboot
 - Typically stored in ROM () or EPROM (), generally known as firmware
 - Initializes all aspects of system
 - Loads operating system kernel and starts execution

Туре	Full Name	Characteristics	Reusability	Typical Use Cases
ROM	Read-Only Memory	Non-volatile memory that is programmed during manufacturing; data cannot be changed.	Not reusable	Firmware, embedded systems
PROM	Programmable Read-Only Memory	Non-volatile memory that can be programmed once by the user; once programmed, data cannot be changed.	Not reusable	Custom firmware applications
EPROM	Erasable Programmable Read-Only Memory	Non-volatile memory that can be erased using UV light and reprogrammed multiple times.	Reusable (after erasing)	Development and testing of firmware

Туре	Full Name	Characteristics	Typical Use Cases
DRAM	Dynamic Random Access Memory	Needs to be refreshed thousands of times per second; slower than SRAM; used for main memory.	Primary memory in computers and laptops
SRAM	Static Random Access Memory	Faster and more reliable than DRAM; does not need to be refreshed; more expensive.	Cache memory in CPUs, routers, and other high-speed applications
SDRAM	Synchronous Dynamic RAM	Synchronized with the system clock for higher performance; used in modern computers.	Main memory in PCs, laptops, and servers
DDR SDRAM	Double Data Rate Synchronous DRAM	Transfers data on both the rising and falling edges of the clock signal; faster than SDRAM.	Main memory in modern computers and gaming systems
LPDDR	Low Power DDR	Optimized for low power consumption; used in mobile devices.	Smartphones, tablets, and other portable devices

Computer System Organization

- Computer-system operation
 - One or more CPUs, device controllers connect through common bus providing access to shared memory



Computer-System Operation • I/O devices and the CPU can execute concurrently

- Each device controller is in charge of a particular device type
- Each device controller has a local buffer
- CPU moves data from/to main memory to/from local buffers
- I/O is from the device to local buffer of controller
- Device controller informs CPU that it has finished its operation by causing an interrupt

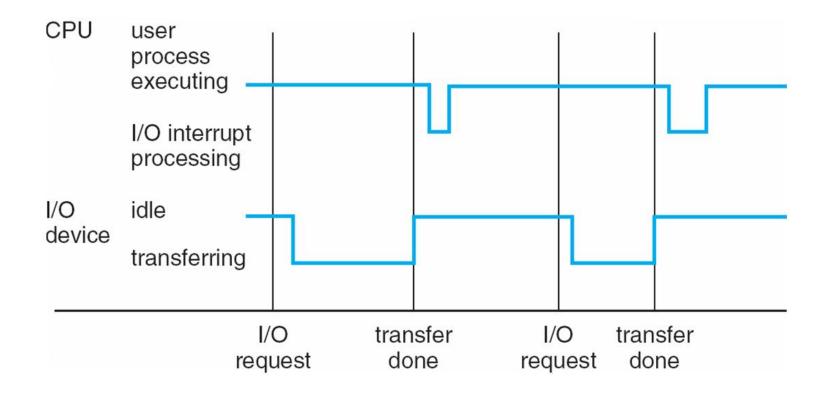
Common Functions of Interrupts

- Interrupt transfers control to the interrupt service routine generally, through the interrupt vector, which contains the addresses of all the service routines
- Interrupt architecture must save the address of the interrupted instruction
- Incoming interrupts are disabled while another interrupt is being processed to prevent a lost interrupt
- A *trap* is a software-generated interrupt caused either by an error or a user request
- An operating system is interrupt driven

Interrupt Handling

- The operating system preserves the state of the CPU by storing registers and the program counter
- Determines which type of interrupt has occurred:
 - polling
 - vectored interrupt system
- Separate segments of code determine what action should be taken for each type of interrupt

Interrupt Timeline



I/O Structure

- After I/O starts, control returns to user program only upon I/O completion
 - Wait instruction idles the CPU until the next interrupt
 - Wait loop (contention for memory access)
 - At most one I/O request is outstanding at a time, no simultaneous I/O processing
- After I/O starts, control returns to user program without waiting for I/O completion
 - System call request to the operating system to allow user to wait for I/O completion
 - Device-status table contains entry for each I/O device indicating its type, address, and state
 - Operating system indexes into I/O device table to determine device status and to modify table entry to include interrupt

Direct Memory Access Structure

 Used for high-speed I/O devices able to transmit information at close to memory speeds

 Device controller transfers blocks of data from buffer storage directly to main memory without CPU intervention

 Only one interrupt is generated per block, rather than the one interrupt per byte

- Storage Structure

 Main memory only large storage media that the CPU can access directly
 - Random access
 - Typically volatile
 - Secondary storage extension of main memory that provides large **nonvolatile** storage capacity
 - Magnetic disks rigid metal or glass platters covered with magnetic recording material
 - Disk surface is logically divided into **tracks**, which are subdivided into **sectors**
 - The disk controller determines the logical interaction between the device and the computer

Storage Hierarchy

- Storage systems organized in hierarchy
 - Speed
 - Cost
 - Volatility
- Caching copying information into faster storage system; main memory can be viewed as a *cache* for secondary storage

Storage Device Hierarchy

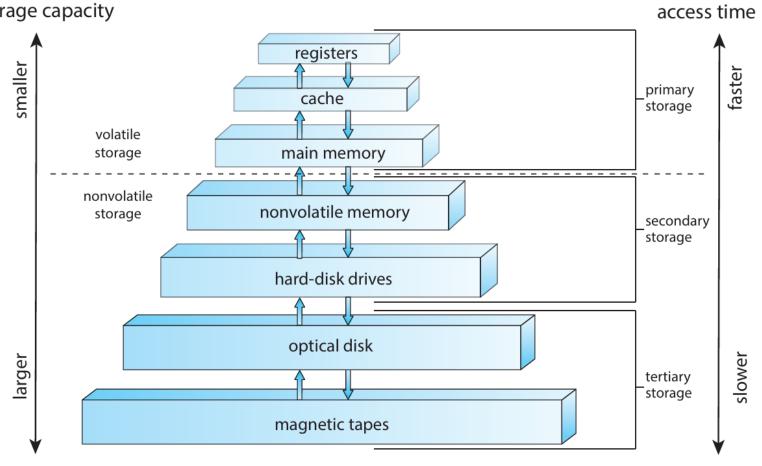


Figure 1.6 Storage-device hierarchy.

Caching

- Important principle, performed at many levels in a computer (in hardware, operating system, software)
- Information in use copied from slower to faster storage temporarily
- Faster storage (cache) checked first to determine if information is there
 - If it is, information used directly from the cache (fast)
 - If not, data copied to cache and used there
- Cache smaller than storage being cached
 - Cache management important design problem
 - Cache size and replacement policy

Computer-System Architecture

- Most systems use a single general-purpose processor (PDAs through mainframes)
 - Most systems have special-purpose processors as well
- Multiprocessors systems growing in use and importance
 - Also known as parallel systems, tightly-coupled systems
 - Advantages include:
 - 1. Increased throughput
 - 2. Economy of scale
 - 3. Increased reliability graceful degradation or fault tolerance
 - Two types:
 - 1. Asymmetric Multiprocessing
 - 2. Symmetric Multiprocessing

- instruction execution → cache cycle instructions thread of execution and data movement data A von CPU (*N) Neumann architecture I/O request · interrupt DMA memory device (*M)

Figure 1.7 How a modern computer system works.

Symmetric Multiprocessing Architecture

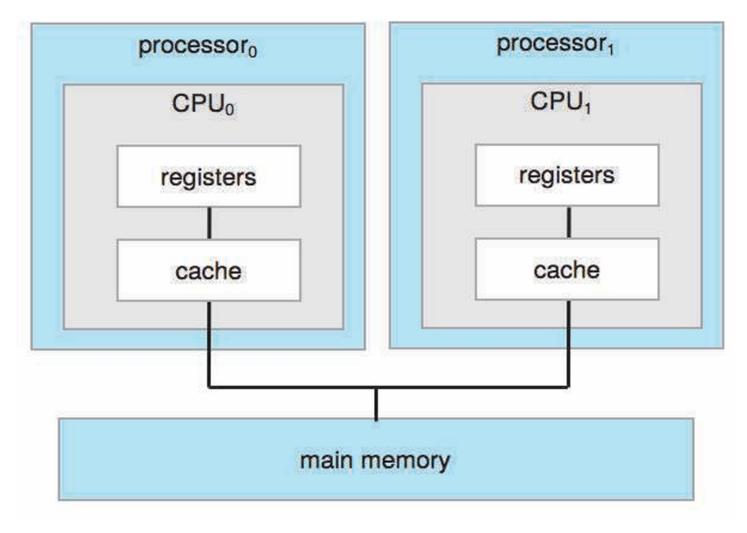


Figure 1.8 Symmetric multiprocessing architecture.

A Dual-Core Design

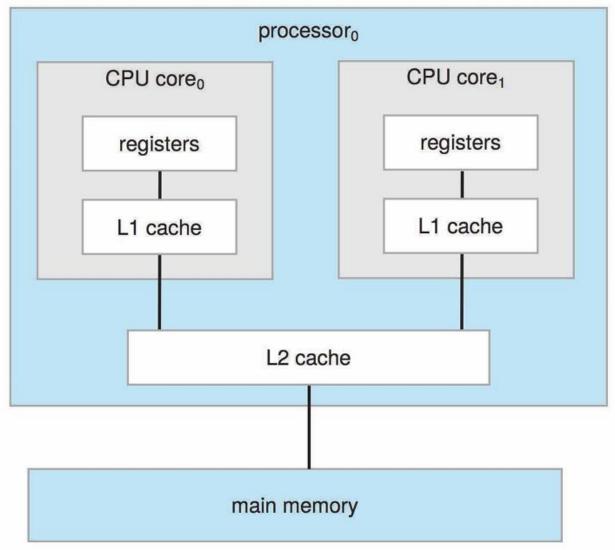


Figure 1.9 A dual-core design with two cores on the same chip.

DEFINITIONS OF COMPUTER SYSTEM COMPONENTS

- CPU—The hardware that executes instructions.
- Processor—A physical chip that contains one or more CPUs.
- Core—The basic computation unit of the CPU.
- Multicore—Including multiple computing cores on the same CPU.
- Multiprocessor—Including multiple processors.

Although virtually all systems are now multicore, we use the general term *CPU* when referring to a single computational unit of a computer system and *core* as well as *multicore* when specifically referring to one or more cores on a CPU.

A clustered system is another type of multiprocessor architecture that brings together multiple CPUs. Unlike the multiprocessor systems outlined in Section 1.3.2, clustered systems consist of two or more individual systems—referred to as nodes—each of which is typically a multicore system. These systems are generally considered loosely coupled.

It's important to note that the definition of a clustered system is not universally agreed upon; various commercial and open-source solutions strive to articulate what constitutes a clustered system and the merits of different forms. However, the widely accepted definition indicates that clustered computers share storage and are interconnected through a local-area network (LAN), or a faster interconnect such as InfiniBand.

- Clustering is usually used to provide high-availability service
- High availability provides increased reliability, which is crucial in many applications.
- Clustering can be structured asymmetrically or symmetrically.
- In asymmetric clustering, one machine is in hot-stand by mode while the other is running the applications.
- In symmetric clustering, two or more hosts are running applications and are monitoring each other.

- Like multiprocessor systems, but multiple systems working together
 - Usually sharing storage via a storage-area network (SAN)
 - Provides a high-availability service which survives failures
 - Asymmetric clustering has one machine in hot-standby mode
 - Symmetric clustering has multiple nodes running applications, monitoring each other
 - Some clusters are for high-performance computing (HPC)
 - Applications must be written to use parallelization

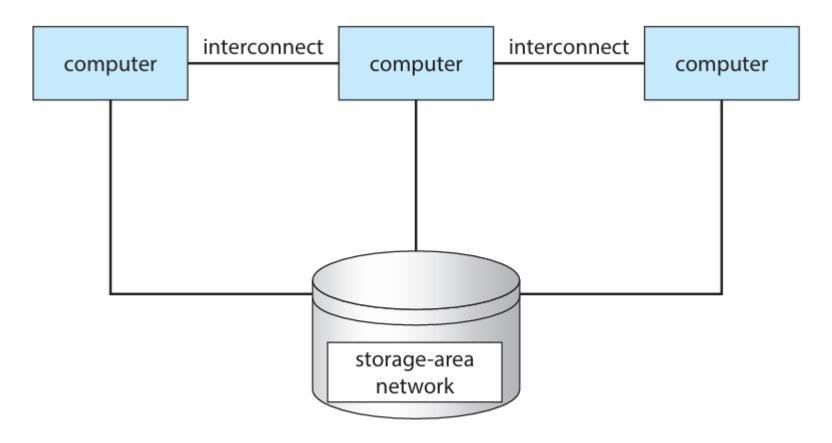


Figure 1.11 General structure of a clustered system.

Homework

How latency and throughput is important in OS