Mid-Term Presentation for the Course Collabrative Software Development

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Outline

- ► Test Driven Development
- Continuous Integration Deployment
- ► An Example

Test Driven Development

What functions should our program implement?

- Basic: General, multiple random test data
- More: Some specific trajectory
- Exception handling

Basic Tests

- Run multiple times
- Random data: using fixtures from pytest

```
@pytest.fixture
def trajectoryData():
    traj = gen.Generator(2.5e-7)
    traj generate()
    return traj
@pytest.fixture
def resultData(trajectoryData):
    x_n_max, x_n_min, y_n_max, y_n_min = trajectoryData.observe()
    cal = f.fit(x_n_max, x_n_min, y_n_max, y_n_min)
    cal.compute_observed()
    cal.linear_regression()
    return cal
@pytest.mark.parametrize('execution_number', range(100))
def test_fitting(trajectoryData, resultData, execution_number):
    assert m.isOk(trajectoryData, resultData, 1e-1)
```

Basic Tests

```
Tiglicosd_project> pulhom -a putest_test_pu test_session starts 

platform linux -- Puthon 3.8.7, putest-6.2.5, py-1.11.8, pluggy-1.8.8 
plugns; englo-3.3.4 
collected 188 items 

test_py (1881)
```

Some More...

► Lines with 0 slope

```
@pytest.fixture
def traj_zero_slope():
    traj = gen.Generator(2.5e-7)
    traj.kx = 0
    traj.ky = 0
```

Lines specific to some bugs

```
Qpytest.fixture
def traj_err_slope():
    traj = gen.Generator(2.5e-7)
    traj.kx = 0.1415785793306974
    traj.ky = 0.4965192218296801
```

Continuous Integration Deployment

Workflow: Decoupled into main program and tests as two git branches

- New features added in main branch
- Run tests
- ► Fails: Debugging, Pass: Merge into test branch
- New tests deployed
- Run tests
- ▶ Pass: Merge into main, Fails: Find out whether problem lies in main or test

Developing in different branches while merging as frequently as possible

Automated Testing

An Debugging Example

One day...

```
0x7fa059b03d30>, execution number = 80
   def test_fitting(trajectoruData, resultData, execution_number);
       assert m.isOk(trajectoryData, resultData, 1e-1)
       assert False
 4856675345878567 -1.2575692588888829 -8.2512581545911161 8.77887575888888819
larning: kx ky out of range
 oit/csd project> \Pi
```

An Debugging Example

- Collect failing data
- Report to the main developer
- ► Main developer locate and fix it
- ► Merge back

An Debugging Example

Reason: Incorrect handling of lines that do not hit all sensors