



بررسی پروژه های دوره و رفع اشکال نهایی

# IOT Final Project



**Dr Ata Jahangir Moshayedi**

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**Associate Prof,**

School of information engineering Jiangxi university of science and technology, China  
EMAIL: ajm@jxust.edu.cn

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Introduction

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Aim & Study

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Component

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Chart

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Code+Comment



# Why IOT enter in various project

- Today the Automation industry is large because of the IoT products available in the market. Automation is there for many years, but the precision is quite low.
- As the IoT evolution took place, all manufacturing devices and machines got smart. This has helped in monitoring and controlling the energy consumption of machines as well the whole factory.





# Student Project

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Following the shared format for the project and sending the project(out of 5 you should solve 2) on time to email [drajm@qq.com](mailto:drajm@qq.com)

- 1. implement the project and achieve the result
- 2. Write the comment for each line of code
- 3. show the result first one local WEB then on Arduino IOT
- 4. Send the code, show and demo all steps in the clip
- 5. extend the project based on a new application
- 6 your report should have:
  - AIM OF PROJECT
  - Applicable fields
  - Hardware Use in Project
  - Circuit connection
  - Mind map
  - CODE and Comment
  - Result display





# IoT-Based Projects



PROJECT

Project1

IoT-Based Smart Energy Meter

Project2

IoT-based Vehicle Tracking System

Project3

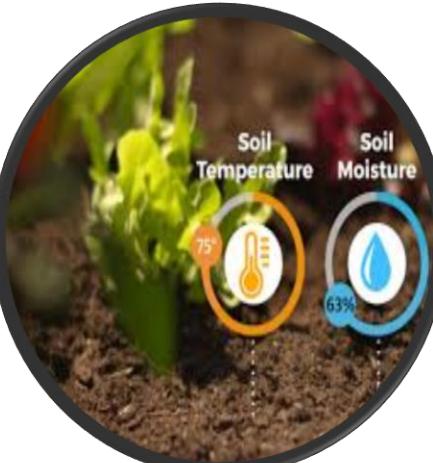
IoT based Irrigation System

Project4

IoT-based car parking System

Project5

IoT-based Gas Detection System( air quality )

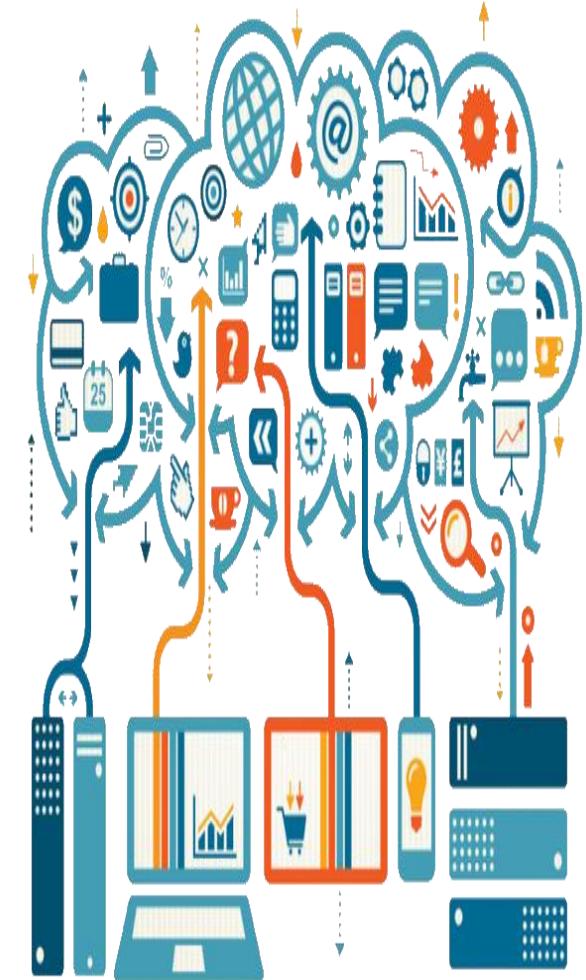




هروزه شماره	
یک	صرف بالای انرژی:
دو	پیايش مصرف جريان و محاسبه ميزان انرژي مصرف بر روی فضاي ابری
سه	فضاي سبز پیايش ميزان رطوبت و دما در اينياری فضاي سبز پارکها بر روی فضاي ابری الودگی هوا:
چهار	پیايش ميزان گازهای آلینده بر روی فضاي ابری ترافيك و استفاده از خودروهای عمومي: پیايش موقعیت اتوبوس واحد و بررسی ميزان فاصله مسافر از موقعیت فعلی اتوبوس واحد بر روی فضاي ابری



# Project1:



# IoT Based Smart Energy Meter



# Why we need Smart Energy Meter

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- **Residential Energy**

- With the increase in the number of home appliances, the electric bill for consumers has also increased. People are always worried about it, and they are continuously trying to reduce it. IoT offers consumers a good amount of saving with a little investment. Initially, any automation device might be a little costly but it acts as a one-time investment. These devices give instant results and reduce power consumption up to 30%.
- Home Automation devices reduce energy consumption by dimming the lights according to outdoor lighting conditions or by turning off light and fan when no one is in the room. IoT can also help to find the defects in the electrical and electronic system of our homes. It can detect the appliance that is consuming more energy in homes.

- **Commercial Energy**

- Energy management is equally important to energy saving. Nowadays governments are installing smart energy meters which will directly send the reading to the electricity board, and you'll receive the bill by mail.
- This system no longer needs humans to monitor bills which, will reduce the energy theft. IoT has simplified the way of Energy management with low cost and high precision devices.



# Application and Usage

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- IOT cloud meters are applied in a wide range of fields, such as residential apartments and buildings, which reduce a lot of burden on property management and operation costs.
- 





# AIM OF PROJECT

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- Electricity meters are connected to the Internet through wireless network, which can conduct remote intelligent control of electricity meters, so that the electricity meter company can achieve integration and intelligence from production and operation, customer service, equipment maintenance, etc.
- Using Arduino IOT cloud to build an intelligent electricity meter based on the Internet of things to monitor the consumption of electric energy

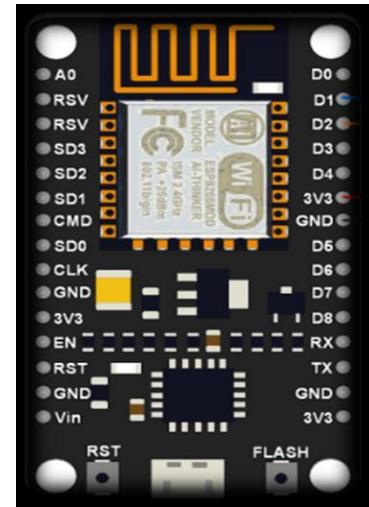




# Project 1:Component

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1. ACS712 Current Sensor
2. Node MCU ESP8266-12e
3. Jumper Wires
4. Stable load - here 12 watts bulb

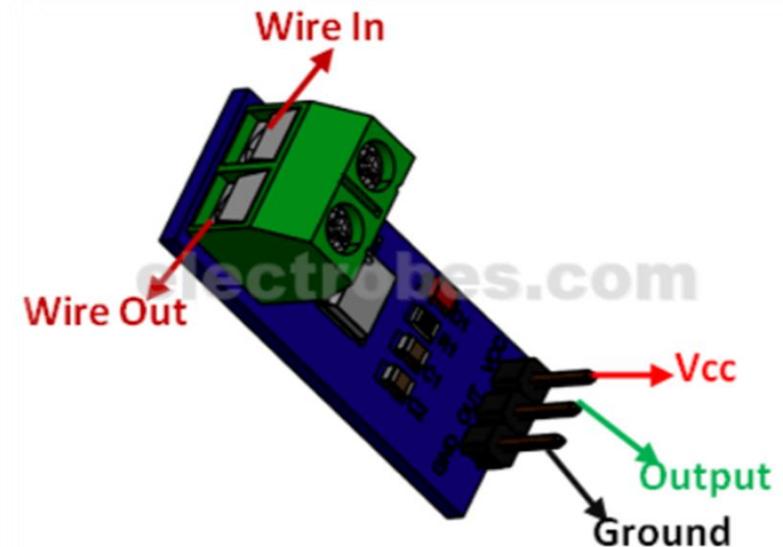




# Project 1: Hardware Use in Project

## ACS712 Current Sensor:

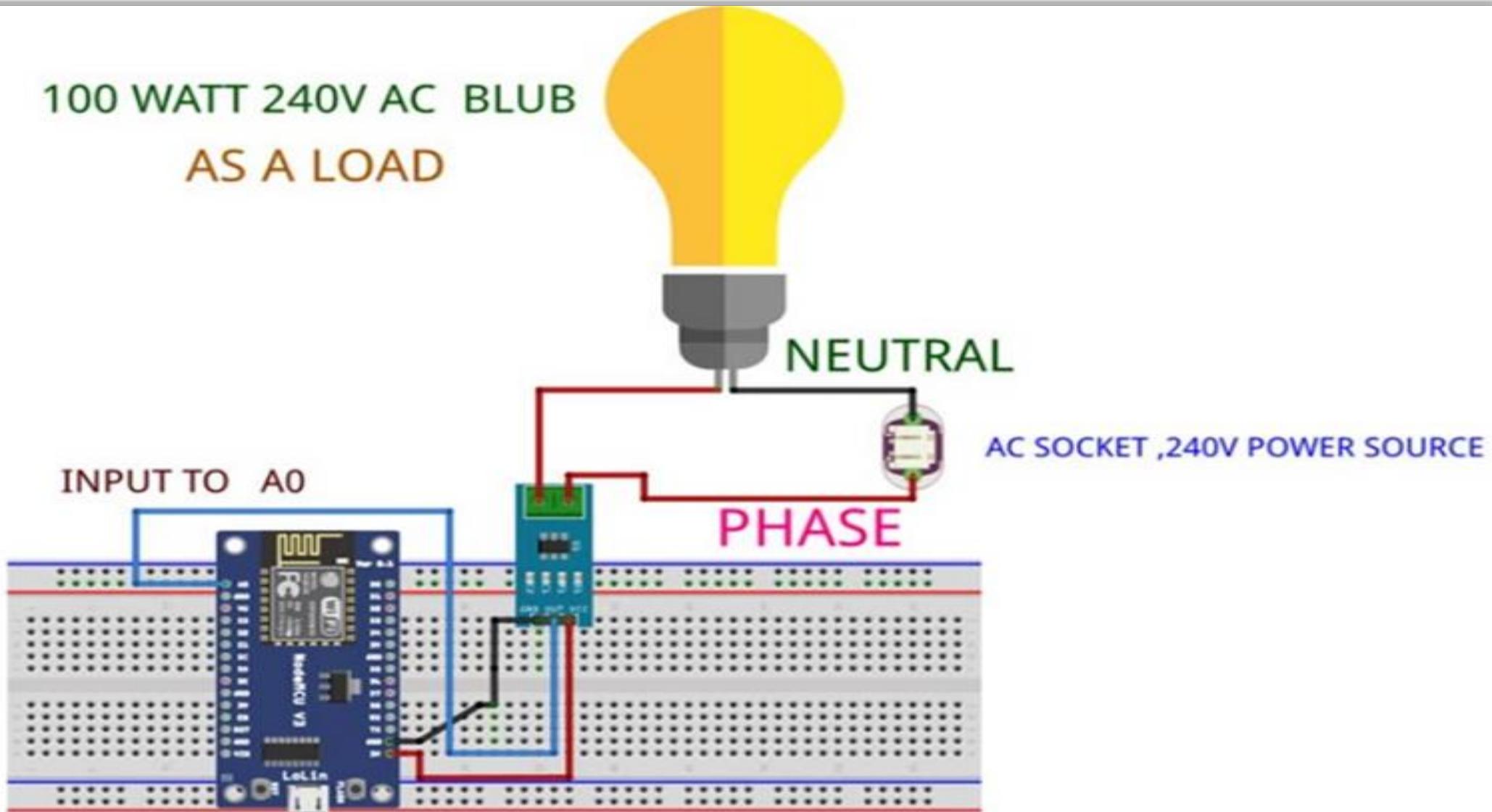
- ACS712 is a current sensor that can operate on both AC and DC. This sensor operates at 5V and produces an analog voltage output proportional to the measured current.
- This tool consists of a series of precision Hall sensors with copper lines.
- The ACS712 output offset voltage is dependent on its operating voltage (generally half of the operating voltage). Since we powered up the module from the ESP 3V output pin the ACS712 module output offset voltage is 1.5 volt (1500 mv) when there is no current flowing. ESP has an onboard voltage divider circuit internally, so we are giving direct input from ACS712 output to the A0 input pin.



# Project 1: Hardware Connection



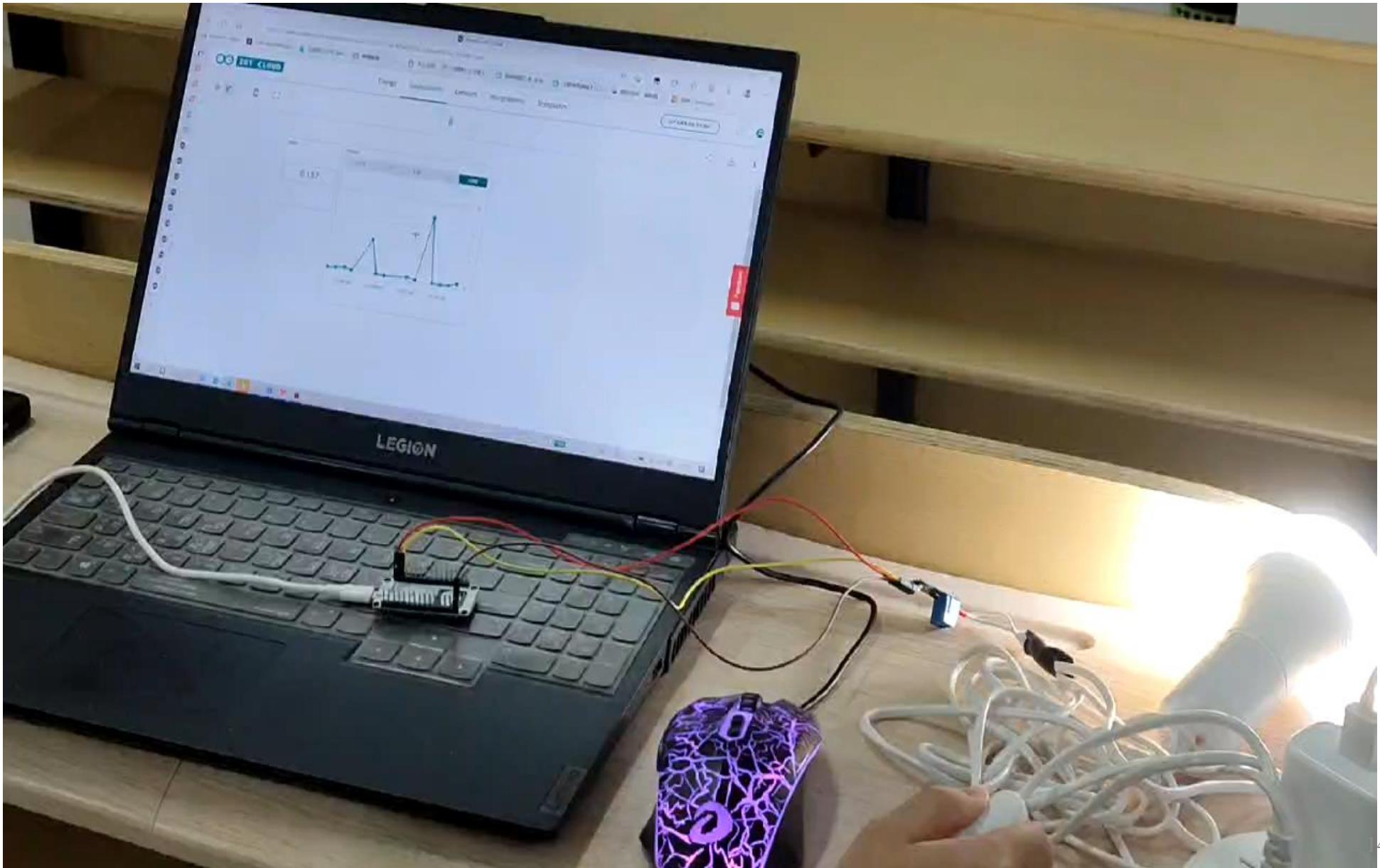
100 WATT 240V AC BLUB  
AS A LOAD



5V Power supply to microusb interface from mobile charger using usb cable



# Project 1: Demo Arduino IOT Cloud





# Project 1:

Q/ANSWERS  
ANSWERS  
ANSWERS





# Project 1: Hardware Connection

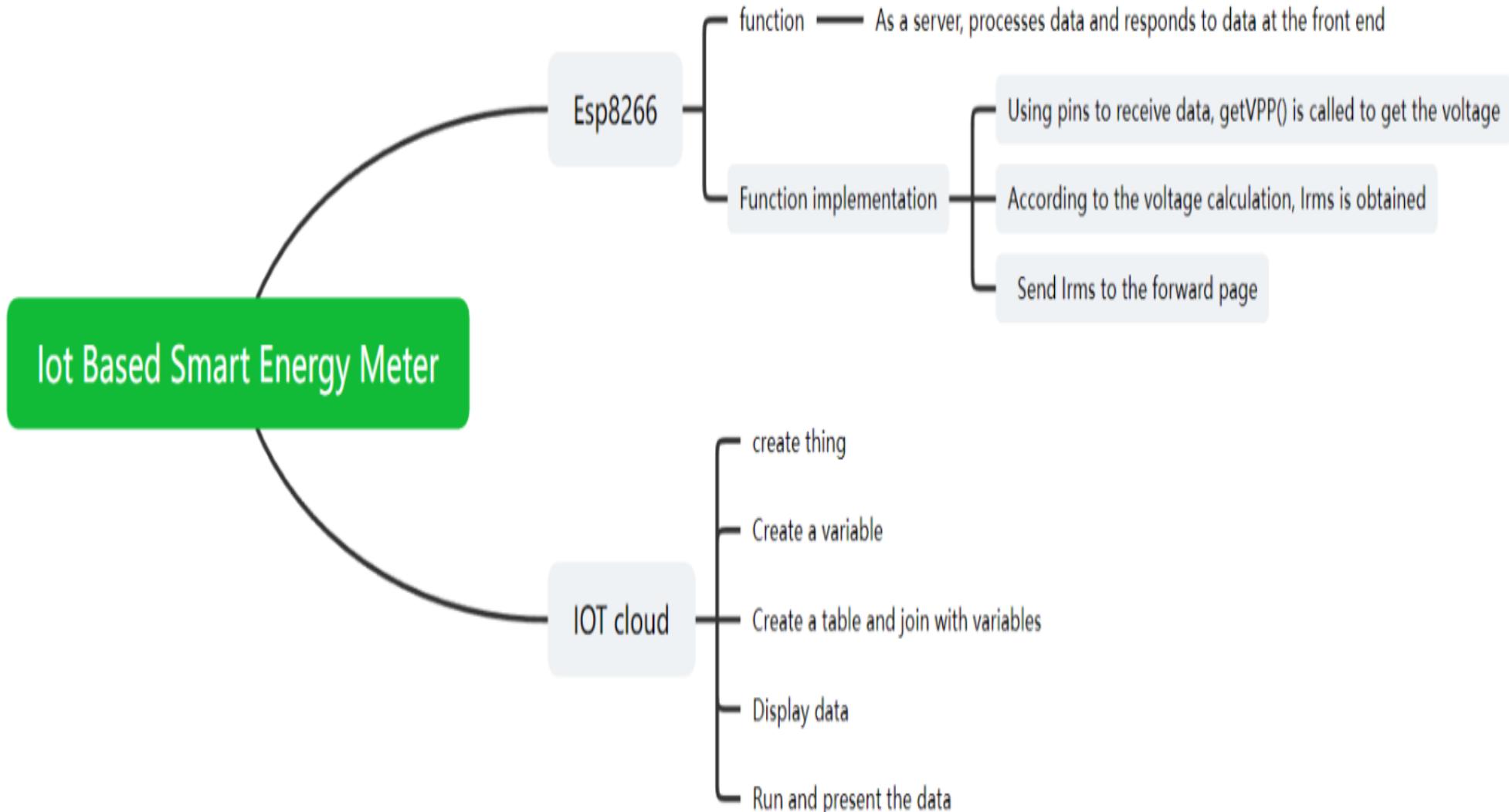
- As you can see the NodeMCU will be powered through the USB port using a 5V mobile charger and the AC load will be connected to the 220V AC mains through our ACS712 current sensor.
- The sensor has a maximum input voltage on VCC is 5V, but it also works fine in lower voltage. Please note that the ASC712 output offset voltage is dependable on its operating voltage (generally half of the operating voltage). Since we powered up the module from the ESP 3V output pin the ACS712 module output offset voltage is 1.5 volt (1500 mv) when there is no current flowing. ESP has an onboard voltage divider circuit internally, so we are giving direct input from ACS712 output to the A0 input pin.
- Make the connections as shown in the circuit above. I directly soldered the wire between the NodeMCU and ACS712 sensor, but you can also use a breadboard and connecting wires. My setup looks like this below when ready.

## Pin Connection:





# Project 1: Brain map





# Project1:

## Code Section



# Project 1: CODE

```
#include "ACS712.h"  
#include <ESP8266WiFi.h>  
  
#define WLAN_SSID "12033"  
#define WLAN_PASS "120312031234"  
  
const int sensorIn = A0;  
  
int mVperAmp = 66;  
double Voltage = 0;  
double Vp = 0;  
double Vrms = 0;  
double Irms = 0;
```

//import required libraries

//wifi name

//wifi pass

//define parameters

//185mV for 5Amp module , 100mV for 10A , 66mv for 20 & 30 Amp module



# Project 1: CODE

```
void readData() {  
    String data = "{\"current\":\""+ String(current)+"\"}";  
    server.send(200, "text/plain", data);  
    delay(2000);  
    current = dht.read.Current();  
    Serial.print(current, 1);}
```

readData from HTML

//Send ADC value, temperature and humidity JSON to client  
ajax request



# Project 1: CODE

```
void setup() {  
    Serial.begin(9600);  
    delay(50);  
    initProperties();  
    ArduinoCloud.begin(ArduinoIoTPreferredConnection);  
    setDebugMessageLevel(2);  
    ArduinoCloud.printDebugInfo();  
}
```

// Initialize serial and wait for port to open:

// This delay gives the chance to wait for a Serial Monitor without blocking if none is found

//Defined in thingProperties.h

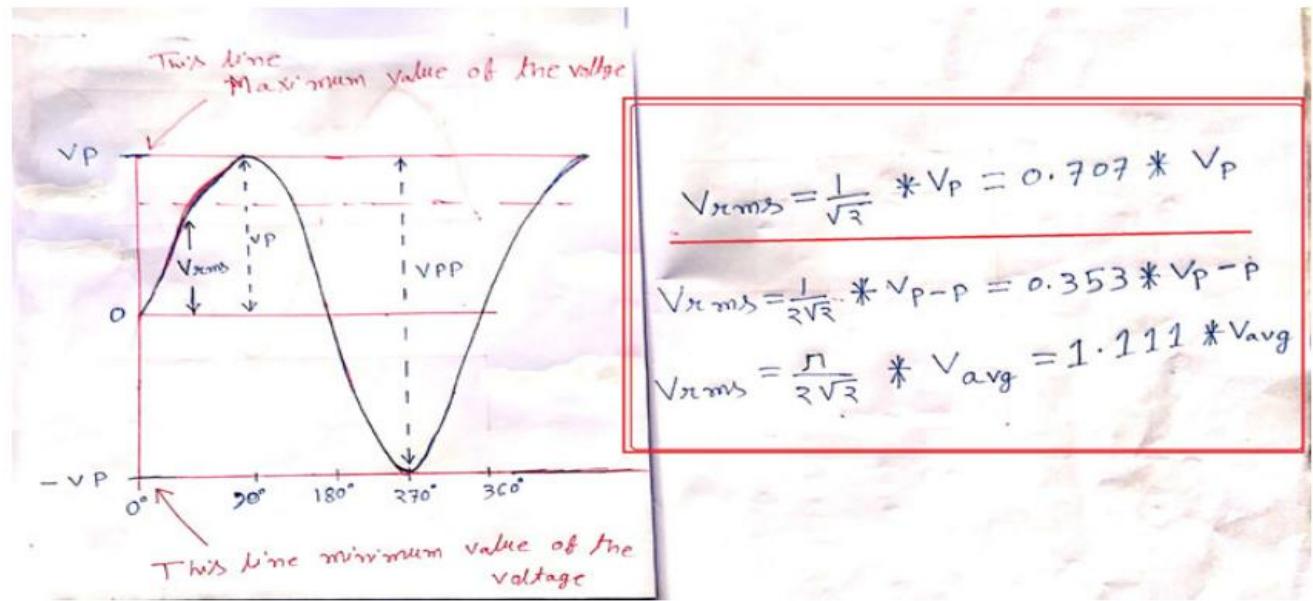
// Connect to Arduino IoT Cloud



# Project 1: CODE

```
void loop() {  
    ArduinoCloud.update();  
  
    Voltage = getVPP();  
  
    Vrms = (Voltage / 2.0) * 0.707; // sq root  
  
    Irms = ((Vrms * 1000) / mVperAmp);  
  
    Serial.print(Irms);  
  
    Serial.println(" Amps");  
  
    dian=Irms;  
  
    delay(2000);  
}
```

If you go through the handmade diagram, I have prepared for you all, you can see that there are two lines, the top line which is the name I have given ( $V_p$ ) indicates the maximum value of the voltage and bottom is ( $-V_p$ ) which indicates the minimum value of the voltage. If you take the difference between those two lines, you will get the ( $V_{pp}$ ) voltage peak to -peak value.



Then we return to the main function. Under the loop, you can see we are going to **convert peak voltage to RMS value** using the formulae explained above. Note that we have divided the measured voltage by 2 to get the value of either the positive or negative side.

$$\text{RMS Voltage} = \text{Peak Voltage} \times 0.707$$



## Project 1: CODE

After that, we convert the voltage to current, for that we are dividing the Vrms value by the millivolt per amp value of the current sensor (I'm using 30 Amp module so it is 66 mVperamp) and multiply by 1000 so that we get it into the Amp not in milli Amps.

Then we will be printing this current value on the serial monitor of Arduino IDE as well as on the MQTT IoT Platform.

```
Vrms = (Voltage / 2.0) * 0.707; // sq root  
Irms = ((Vrms * 1000) / mVperAmp) ;  
Serial.print(Irms);  
Serial.println(" Amps");
```

```
Serial.print(Irms);  
Serial.println(" Amps");  
if (! photocell.publish(Irms))  
{  
    Serial.println("Failed");  
}  
else  
{  
    Serial.println("OK!");  
}  
delay(2000);  
}
```



# Project 1: CODE

```
double getVPP()
{
    float result;
    int readValue;
    int maxValue = 0;
    int minValue = 1024;
    uint32_t start_time = millis();
    while ((millis() - start_time) < 1000)
    {
        readValue = analogRead(sensorIn);
```

//value read from the sensor

// store max value here

// store min value here

//sample for 1 Sec



# Project 1: CODE

```
if (readValue > maxValue)
```

```
{
```

```
maxValue = readValue;
```

```
}
```

```
if (readValue < minValue)
```

```
{
```

```
minValue = readValue;
```

```
}
```

```
}
```

```
result = ((maxValue - minValue) * 5) /  
1024.0;
```

```
return result;
```

```
}
```

```
void onDianChange() {
```

```
}
```

// see if you have a new maxValue

/\*record the minimum sensor value\*/

/\*record the maximum sensor value\*/

// Subtract min from max





# Project 1: HTML-CODE

```
<!DOCTYPE html>
<html lang="en">
<head>
    <meta charset="UTF-8">
    <meta http-equiv="X-UA-Compatible" content="IE=edge">
    <meta name="viewport" content="width=device-width, initial-scale=1.0">
    <title>Document</title>
<script>
    var Tvalues = [];//Set the tvalues variable
    function getData() {//Define GetData function
        var xhttp = new XMLHttpRequest();//Set xhttp variable and call XMLHttpRequest function
        xhttp.onreadystatechange = function () {
            if (this.readyState == 4 && this.status == 200) {
                //Push the data in array
                var txt = this.responseText;
                var obj = JSON.parse(txt);
            }
        }
    }
</script>
```



# HTML-CODE

```
Tvalues.push(obj.Current);
    //Update Data Table
    var current = document.getElementById("current");
    current.innerHTML = obj.Current; }};

    xhttp.open("GET", "readData", true); //Handle readData
server on ESP8266
    xhttp.send();

</script>
<style>
body {
    /*Format body */
    display: flex;
    justify-content: center;
    align-items: center;
    margin: 0;
    padding: 0; }
```

```
.btn {
    /* Set the width, height, background color and other attributes of BTN */
    width: 200px;      height: 200px;      margin-top: 0px;
    margin-left: 153px;
    background: linear-gradient(315deg, #c7d889 0%, #c88403 74%);
    border: none;      border-radius: 100px;      font-family: 'Lato',
    sans-serif;
    font-weight: 500;      font-size: 48px;      color: #fff;
    box-shadow: inset 2px 2px 2px 0px rgba(255, 255, 255, .5),
    7px 7px 20px 0px rgba(0, 0, 0, .1),
    4px 4px 5px 0px rgba(0, 0, 0, .1);
    outline: none;      position: relative;
    z-index: 0; }

.btn:active {
    /* Set the properties of BTN after clicking */
    top: 2px;
}
```



# Project 1: HTML-CODE

---

```
.button {      /* Set left float */
    float: left;      }
a {      /* Set to no underline */
    text-decoration: none;      }
.main {
    /* Set the properties of the main*/
    padding-top: 100px;
    height: 603px;      width: 100%;
    background-image: linear-gradient(to bottom right, #f8c3e8,
#f47990);
}
.center {
    /* Set the properties of the center */
    margin: 0 auto;      height: 438px;      width: 500px;
    background-color: rgba(0, 0, 0, .12);
    border-radius: 15px;      }
```

```
h2 {      /* Set the properties of H2 */
    padding-top: 93px;
    text-align: center;
    font-size: 54px;
    color: #fce0ab;      }
</style>
</head>
<body>
<div class="main">
    <div class="center">
        <h2>Current magnitude</h2>
        <a href="/LED=ON\">
            <div onclick="getData()" class="btn"
id="current"></div>
            <!-- Receive data and display -->
        </a>
    </div> </div></body></html>
```



# Project 1: Arduino IOT

Create Things:

Variables:

Name  
dian1

Sync with other Things i

Electric Current eg. 1 A

Declaration  
`CloudElectricCurrent dian1;`

Variable Permission i

Read & Write  Read Only

Device:

## Associated Device



my

ID: 20464094-c087-4391-b735-...

Type: NodeMCU 1.0 (ESP-12E Module)

Status: Offline



Change



Detach





# Project 1: Arduino IOT

Network: Configure network

You will find these network parameters in the secret tab in your sketch, and your device will be able to connect to the network once the sketch will be uploaded.

Wi-Fi Name \*

Password \*

 O

Secret Key \*

 O

SAVE

Value

0.052

Widget Settings

Name Value

Hide widget frame

Linked Variable

dian1 from Untitled 2

Change Detach

Show Thing name on widget

DONE

Chart

Chart

15 D 7 D 1 D 1 H LIVE

Widget Settings

Name Chart

Hide widget frame

Linked Variable

dian1 from Untitled 2

Change Detach

Show Thing name on widget

Data points interpolation

Spline

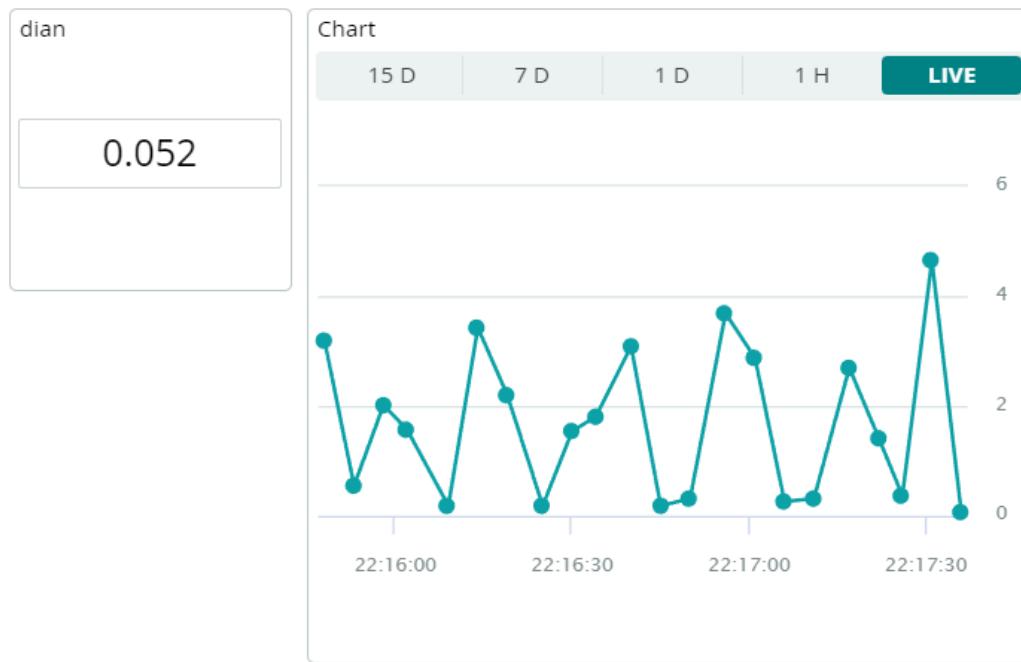




# Project 1: Arduino IOT

Running result:

Chart:





# Project 1: Testing on Arduino:

project5 | Arduino 1.8.19

文件 编辑 项目 工具 帮助

project

```
// WiFi clientSecure client;
// Setup the MQTT client class by passing in the WiFi client and MQTT server and login details.
Adafruit_MQTT_Client mqtt(&client, AIO_SERVER, AIO_SERVERPORT, AIO_USERNAME, AIO_KEY);
Adafruit_MQTT_Publish photocell = Adafruit_MQTT_Publish(&mqtt, AIO_USERNAME "/feeds/current");
const int sensorIn = A0;
int mVperAmp = 66; //185mV for 5Amp module , 100mV for 10A , 66mV for 20 & 30 Amp module
double Voltage = 0;
double Vp = 0;
double Vrms = 0;
double Irms = 0;
// Bug workaround for Arduino 1.6.6, it seems to need a function declaration
// for some reason (only affects ESP8266, likely an arduino-builder bug).
void MQTT_connect();
void setup() {
  Serial.begin(9600);
  WiFi.begin(WLAN_SSID, WLAN_PASS);
  while (WiFi.status() != WL_CONNECTED)
  {
    Serial.println("connecting....");
    delay(1000);
  }
  Serial.println("Connected");
}
void loop() {
  MQTT_connect();
  Voltage = getVPP();
  Vrms = (Voltage / 2.0) * 0.707; // sq root
  Irms = ((Vrms * 1000) / mVperAmp);
  Serial.print(Irms);
  Serial.println(" Amps");
  if (! photocell.publish(Irms))
  {
    Serial.println("Failed");
  }
  else
  {
    Serial.println("OK!");
  }
  delay(2000);
}
double getVPP()
{
  float result;
  int readValue; //value read from the sensor
  int maxValue = 0; // store max value here
  int minValue = 1024; // store min value here
  ... (code continues)
}

Leaving...
Hard resetting via RTS pin...
```

3 NodeMCU 1.0 (ESP-12E Module), 80 MHz, Flash, Disabled (new aborts on oom), Disabled, All SSL ciphers (most compatible), 32KB cache + 32KB IRAM (balanced), Use pgm\_read macros for IMA

97% 29°C 多云 F12 22:19

www.BANDICAM.com



# Project 1: Test on IOT cloud:



www.BANDICAM.com

https://create.arduino.cc/iot/things

Problem - JustOJ GDB online Debug... 江西理工大学 Web... 哔哩哔哩 ( °- °)つ... 个人空间 江西理工大学网上... 原神地图工具\_全地... 【原神风神瞳】(2.1... 题目列表 - 编程题 -... 面板 | Tinkercad

IOT CLOUD Things Dashboards Devices Integrations Templates UPGRADE PLAN

Things

Name ↓ Device Variables Last Modified

Untitled my NodeMCU 1.0 (ESP-12E M

BANDICAM 班迪录屏 UNREGISTERED

00:00:00 0 bytes / 145.5GB

1920x1080 - (0, 0), (1920, 1080) - 显示器 1

首页 开始 视频 图像

常规 录像 截图 关于

停止录制 查看在线帮助

录制/停止 捕捉图像 F12 F11

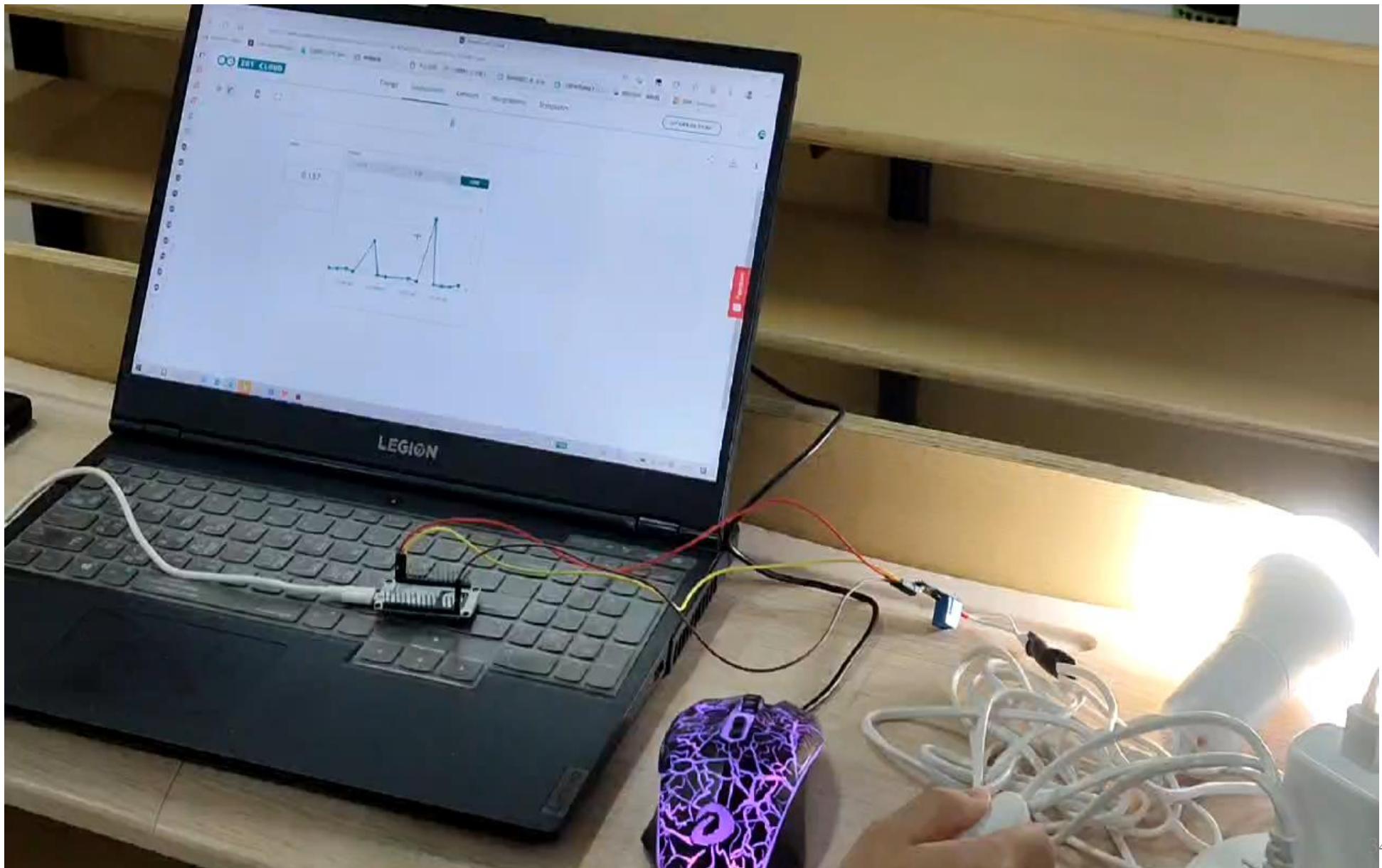
如何使用屏幕录制模式?

73% 26°C 多云 7:35





# Project 1: Demo





## Project2:

IoT-based Vehicle Tracking System





# Why we need .....

01

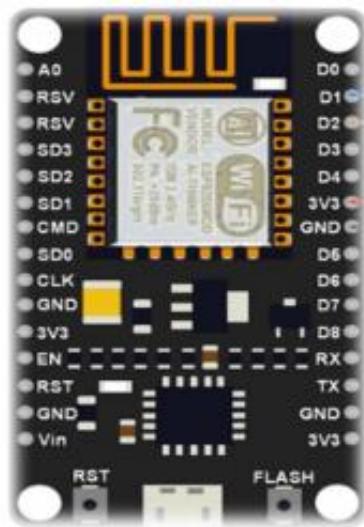
Aim  
&Background

- Nowadays, security is the most concern for us, whether it is related to our assets like vehicles, homes or our children.
- In this case, GPS tracker devices are very useful. They can be easily used to track the real-time position of the vehicles or assets in case of any emergency like theft, accidents, etc.
- They can also be kept with children to track their location.

# Project 2:Component



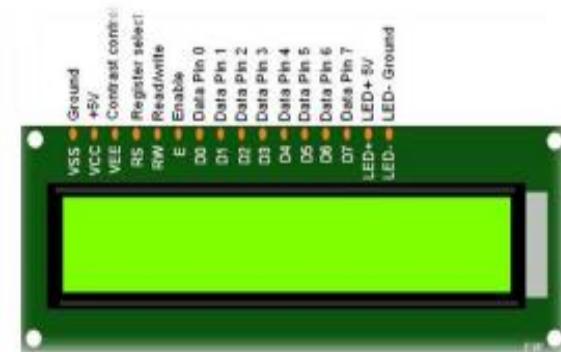
NodeMCU ESP8266



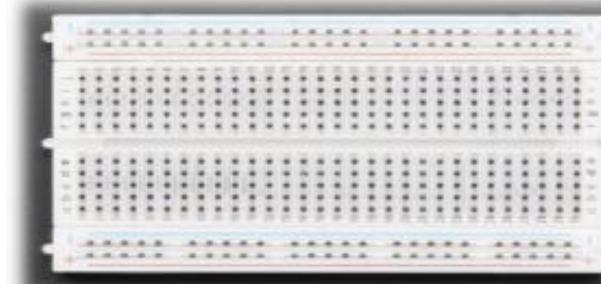
NEO8M GPS Module



16\*2 LCD



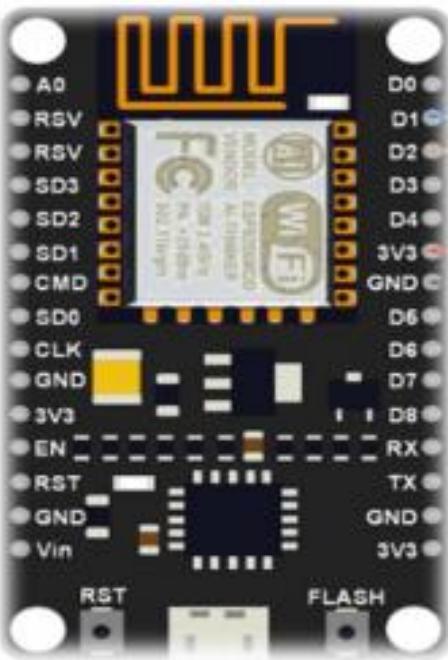
BreadBoard





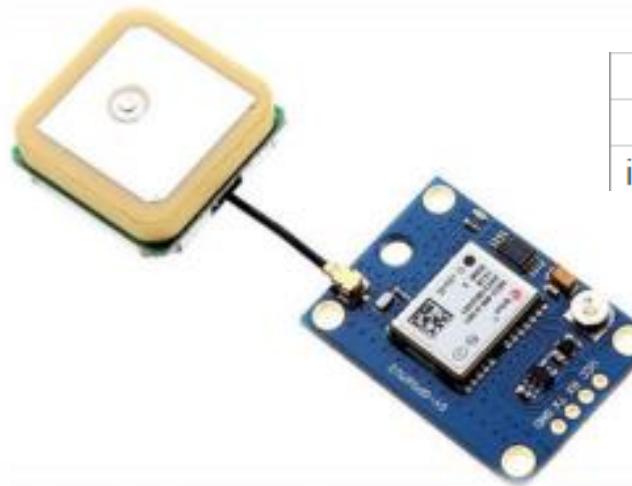
# Project 2: Component

NodeMCU



**NodeMCU** is a open source board which has **ESP8266** as a WiFi module .It has file system called **SPIFFS** to fetch the file like html and so on. It is very easy to use like Arduino.

NEO8M GPS Module



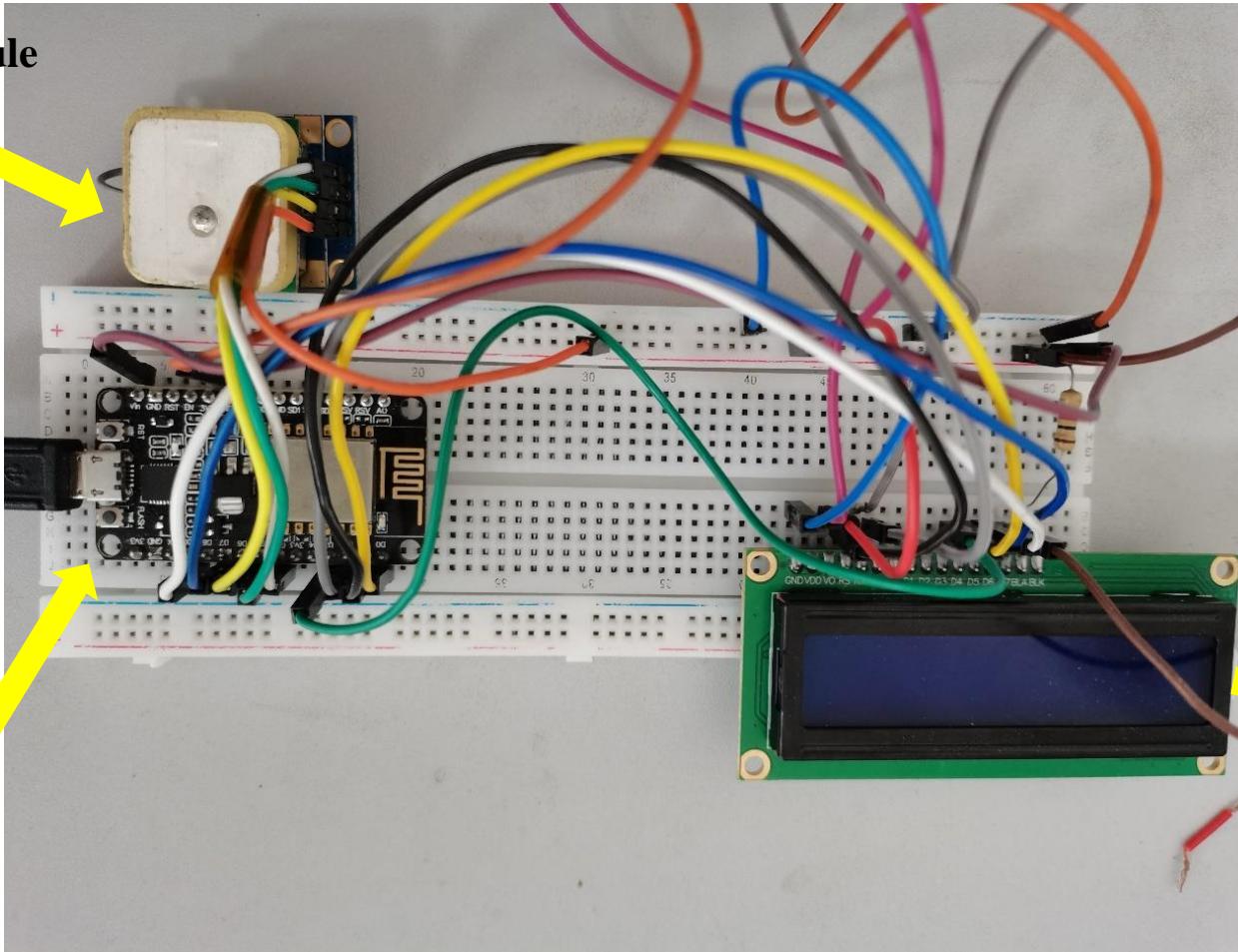
Pin	1	2	3	4
illustrate	To Power	RX	TX	GND
function	To Power	Receive pin	Translate pin	To Ground

**NEO8M GPS Module** is a GPS Module,it can use some function of its library to get the longitude and latitude data.The image above shows the function corresponding to its pins.



# Project 2: Connection

NEO\*M GPS Module



NodeMCU

16\*2 LCD





# Project 2: Demo on Web

The screenshot shows a web browser window with the following details:

- Title Bar:** From zao, 00:00:00, 结束录制 (End Recording) button.
- Address Bar:** 不安全 | 192.168.43.10
- Toolbar:** Back, Forward, Stop, Refresh, Home, etc.
- Address Bar:** code, 影视, 学习, 下载, 学校WIFI和工作, 娱乐, 英语, tool, 电子书, 红学, tk, 服务器 - 轻量应用..., gin, Matlab2021b哪位..., 【软硬结合】Node...
- Content Area:**
  - Background:** A complex network visualization with many blue and orange lines forming a mesh against a dark background.
  - Text:** CLASS DESIGN in large white serif font.
  - Logo:** A white triangular logo resembling a stylized 'Y' or a three-pointed star.
  - Buttons:** Get Position Info (Get Position Info) button.
  - Text at Bottom:** 欢迎大家观看本组演示 (Welcome everyone to watch this group's demonstration) and Welcome to this demo.



## Project 2:

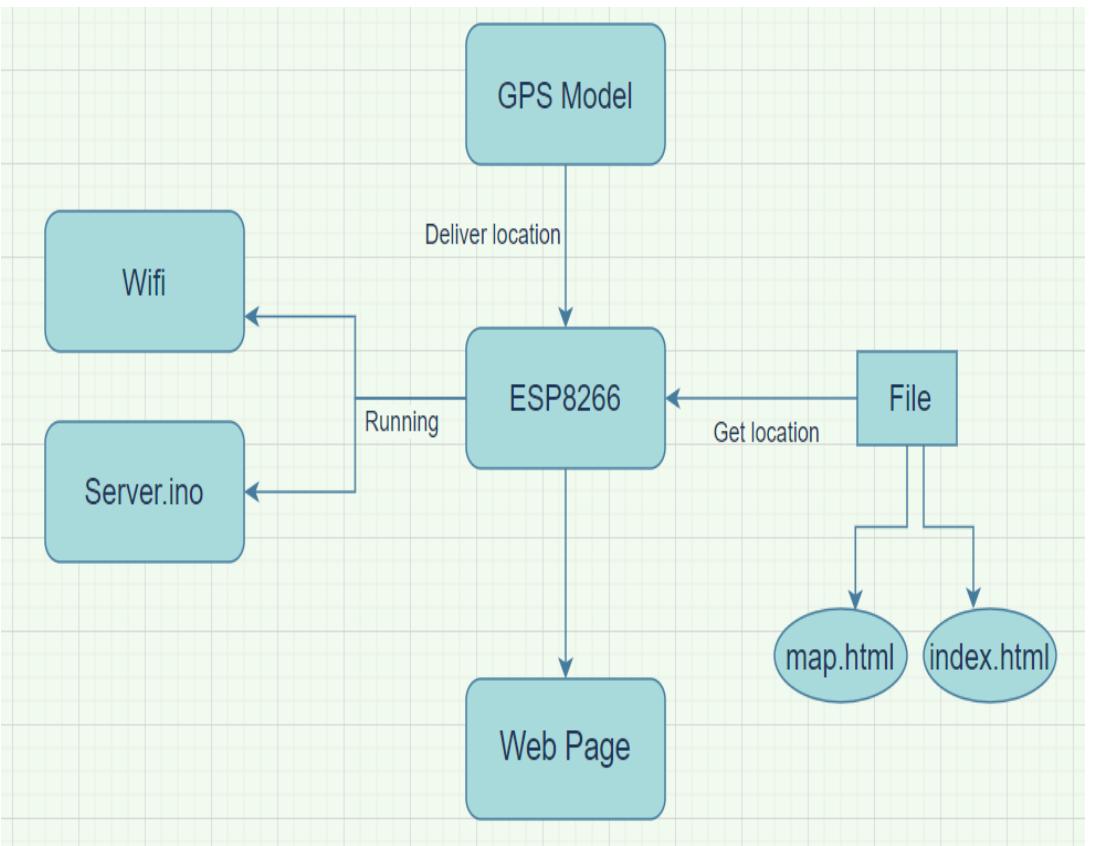
Q/ANSWERS  
ANSWERS  
ANSWERS





# Project 2:flow chart and Descriptions

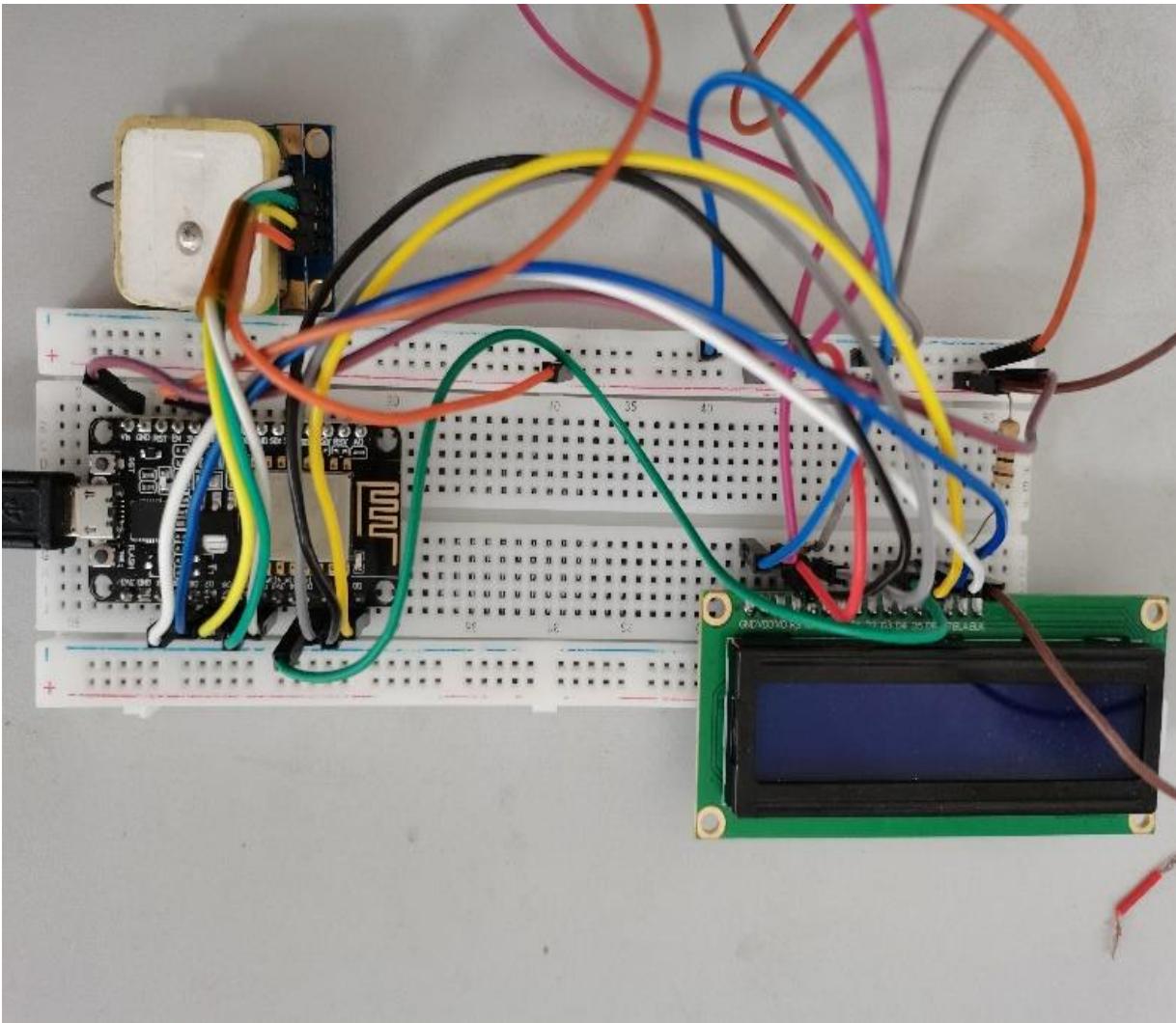
## FLOW CHART



## Descriptions

- 1, GPS Model will fetch the real-time location to the ESP8266
- 2. And then, in the ESP8266, there are HTML files and some back-end codes. The back end receives the location data from the GPS and processes them. In this part, ESP8266 works as a server, for realizing the function, ESP8266 connects with the WIFI by using the libraries from the third party in the github. Through them, we just need connect the WIFI factitiously, and ESP8266 will connect the same WIFI the next time automatically. After connecting the wifi, we run the server.ino, so ESP8266 is able to run HTML files.
- 3. At last, the IP url will be generated, we can open the web page to check the location in the map.

# Project 2: Connection



LCD	to	Other Device
GND	→	GND
VDD	→	5V
V0	→	GND
RS	→	D1
RW	→	GND
E	→	D2
D4	→	D3(NodeMCU)
D5	→	D0(NodeMCU)
D6	→	D7(NodeMCU)
D7	→	RX(NodeMCU)
A	→	5V
K	→	GND

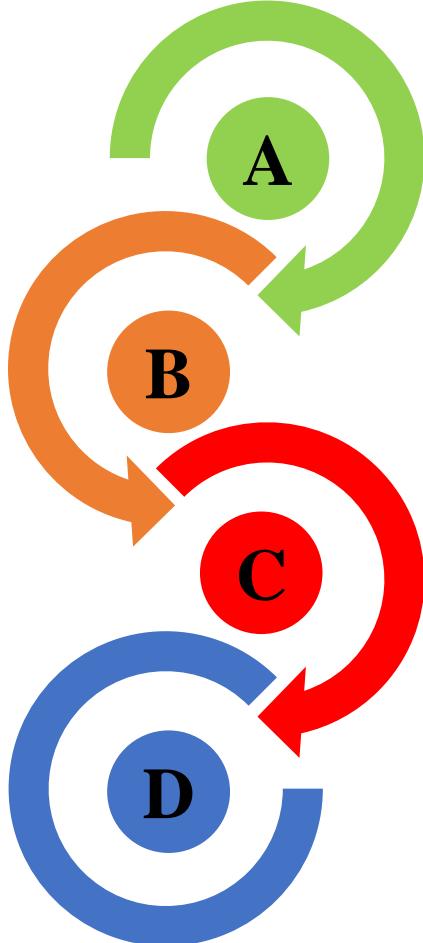
NEO8M GPS Module	to	Other Device
RX	→	D6(NodeMCU)
TX	→	D5(NodeMCU)
VCC	→	5V
GND	→	GND



# Project.....

---

- In this project, we have learned how to use IOT furtherly. The location will be shown in the IOT.
- We successfully connect IOT, ESP8266, GPS model. Although, we met many problems and difficulties, like the delivery of the data is very slow, and the data refreshes very slowly.

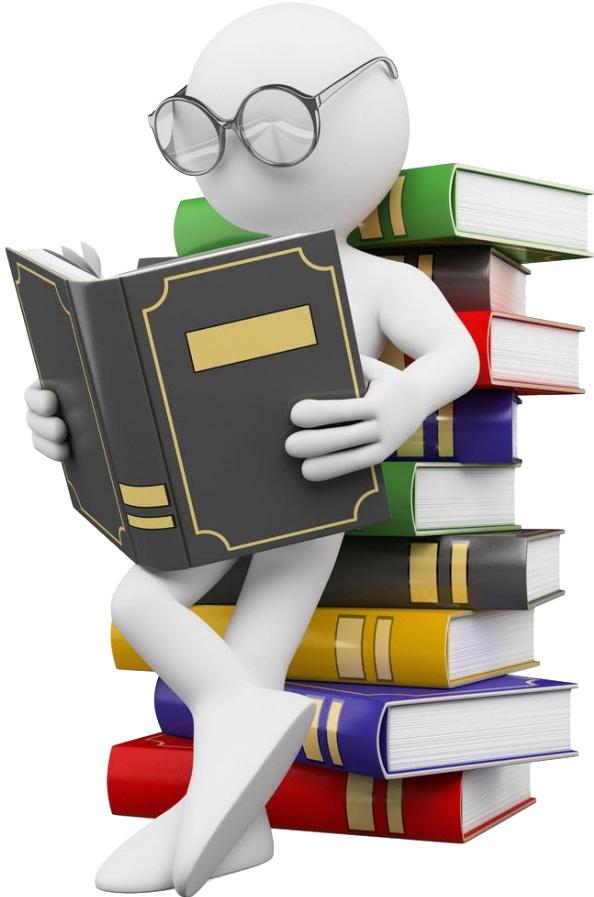


- A GPS gets the position
- B GPS send the position to the ESP8266
- C ESP8266 gets the position and connect IOT
- D positon shows in IOT



# Library

---



## WiFi manager library

Learn this new function and apply it. It gives great convenience to us when programming

## File Flash System

It can read and run the files in the ESP8266 ...

## Show the position in the map

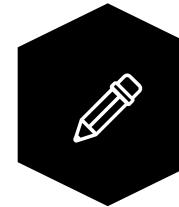
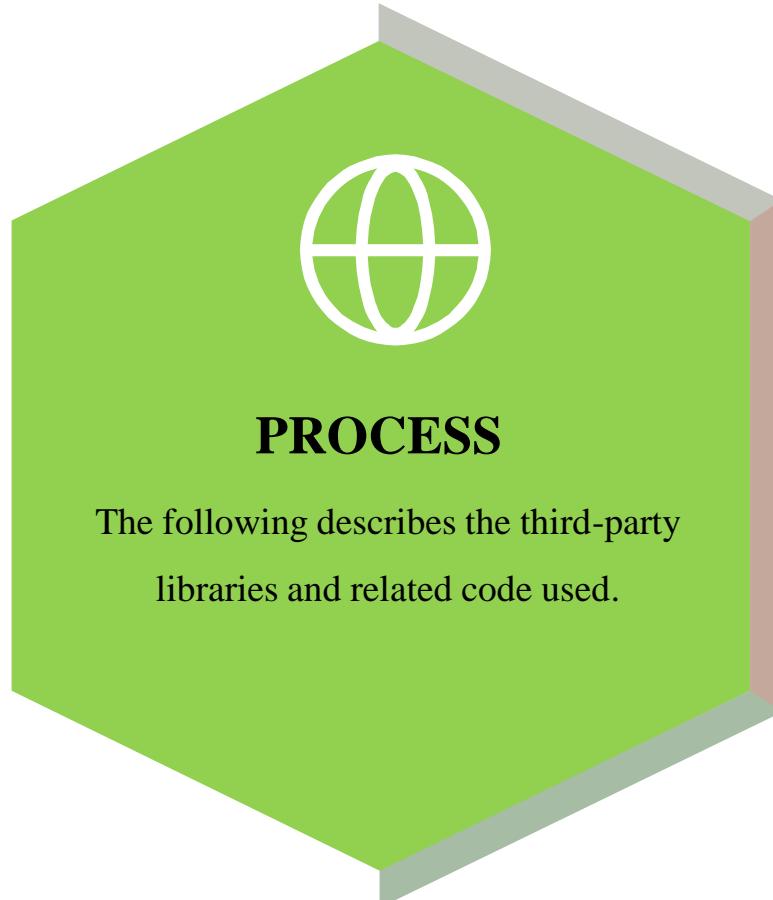
We make our own web page and the pages are opened by File Flash System, not print....



# Arduino IDE

## Indrtuction

The project is centered on ESP866, using GPS sensors and driven by Arduino built-in libraries and open source third-party libraries. Use Android plug-in to download HTML and other files to the file flash system. Display location information on web pages by responding to client requests.



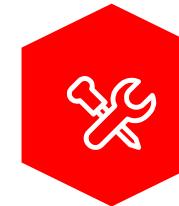
### Library

WiFiManager、TinyGPSPlus、ThingSpeak



### Arduino plugin

Arduino ESP8266 filesystem uploader



### Code

Code and comments



# *WiFiManager*

---

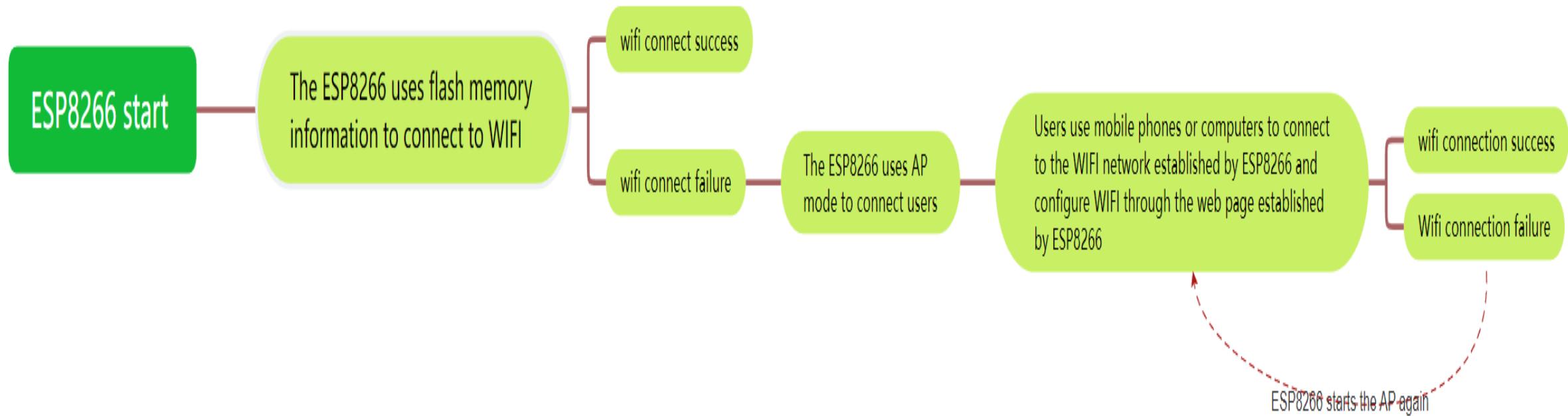
Espressif ESPx WiFi Connection manager with fallback web configuration portal.  
The configuration portal is of the captive variety, so on various devices it will present  
the configuration dialogue as soon as you connect to the created access point.

GitHub: <https://github.com/tzapu/WiFiManager>



# Library WiFiManager

## How It Works





# Library WiFiManager

## *WiFiManager* *How It Looks*

README.md

### How It Looks

•••• orange 4G 23:57 192.168.4.1 AutoConnectAP < > Log In Cancel

•••• orange 4G 23:57 192.168.4.1 AutoConnectAP < > Log In Cancel

### AutoConnectAP

**WiFiManager**

Configure WiFi

Configure WiFi (No Scan)

ROBIN HOOD 30% 🔒  
Tia Network 2 16% 🔒

ROBIN HOOD  
password  
mqtt server  
8080  
YOUR\_BLYNK\_TOKEN

< > Done

q w e r t y u i o p  
a s d f g h j k l  
z x c v b n m ↺  
.123 space Go





# Library WiFiManager

---

## *How It Works*

- When your ESP starts up, it sets it up in Station mode and tries to connect to a previously saved Access Point
- if this is unsuccessful (or no previous network saved) it moves the ESP into Access Point mode and spins up a DNS and WebServer (default ip 192.168.4.1)
- using any wifi enabled device with a browser (computer, phone, tablet) connect to the newly created Access Point
- because of the Captive Portal and the DNS server you will either get a 'Join to network' type of popup or get any domain you try to access redirected to the configuration portal
- choose one of the access points scanned, enter password, click save
- ESP will try to connect. If successful, it relinquishes control back to your app. If not, reconnect to AP and reconfigure.
- There are options to change this behavior or manually start the configportal and webportal independantly as well as run them in non blocking mode.



# Library WiFiManager

---

## *WiFiManager*

*In my code:*

```
// establish WiFiManager object  
WiFiManager wifiManager;  
  
// Connecting WiFi automatically  
// arguments is the name of connecting ESP8266  
wifiManager.autoConnect("AutoConnectAP");
```



With the WiFiManager library, we can set up the ESP8266's WiFi connection without having to change the ESP8266's program.



# Library WiFiManager

## ThingSpeak

GitHub: <https://github.com/mathworks/thingspeak-arduino>

This library enables an Arduino or other compatible hardware to write or read data to or from ThingSpeak, an open data platform for the Internet of Things with MATLAB analytics and visualization.

ThingSpeak offers free data storage and analysis of time-stamped numeric or alphanumeric data. Users can access ThingSpeak by visiting <http://thingspeak.com> and creating a ThingSpeak user account.

ThingSpeak stores data in channels. Channels support an unlimited number of timestamped observations (think of these as rows in a spreadsheet). Each channel has up to 8 fields (think of these as columns in a spreadsheet). Check out this [video](#) for an overview.

Channels may be public, where anyone can see the data, or private, where only the owner and select users can read the data. Each channel has an associated Write API Key that is used to control who can write to a channel. In addition, private channels have one or more Read API Keys to control who can read from private channel. An API Key is not required to read from public channels. Each channel can have up to 8 fields. One field is created by default.

You can visualize and do online analytics of your data on ThingSpeak using the built in version of MATLAB, or use the desktop version of MATLAB to get deeper historical insight. Visit <https://www.mathworks.com/hardware-support/thingspeak.html> to learn more.



# Library *ThingSpeak*

```
bool begin(Client & client)
```

Function: begin

Summary:

Initializes the ThingSpeak library and network settings using the ThingSpeak.com service.

Parameters:

client - EthernetClient, YunClient, TCPClient, or WiFiClient for HTTP connection and WiFiSSLClient, WiFiClientSecure for HTTPS connection created earlier in the sketch.

Returns:

Always returns true

Notes:

This does not validate the information passed in, or generate any calls to ThingSpeak.

Include this ThingSpeak header file after including the client header file and the TS\_ENABLE\_SSL macro in the user sketch.



# Library ThingSpeak

---

```
int setField(unsigned int field, String value)
```

Function: `setField`

Summary:

Set the value of a single field that will be part of a multi-field update.

Parameters:

`field` - Field number (1-8) within the channel to set.

`value` - String to write (UTF8). ThingSpeak limits this to 255 bytes.

Returns:

Code of 200 if successful.

Code of -101 if value is out of range or string is too long (> 255 bytes)



# Library ThingSpeak

```
int writeFields(unsigned long channelNumber, const char * writeAPIKey)
```

Function: writeFields

Summary:

Write a multi-field update.

Parameters:

channelNumber - Channel number

writeAPIKey - Write API key associated with the channel. \*If you share code with others, do not share this key\*

Returns:

- 200 - successful.
- 404 - Incorrect API key (or invalid ThingSpeak server address)
- 101 - Value is out of range or string is too long (> 255 characters)
- 201 - Invalid field number specified
- 210 - setField() was not called before writeFields()
- 301 - Failed to connect to ThingSpeak
- 302 - Unexpected failure during write to ThingSpeak
- 303 - Unable to parse response
- 304 - Timeout waiting for server to respond
- 401 - Point was not inserted (most probable cause is the rate limit of once every 15 seconds)

Notes:

Call setField(), setLatitude(), setLongitude(), setElevation() and/or setStatus() and then call writeFields()



# Library *TinyGPSPlus*

---

TinyGPS++ is a new Arduino library for parsing NMEA data streams provided by GPS modules.

Like its predecessor, TinyGPS, this library provides compact and easy-to-use methods for extracting position, date, time, altitude, speed, and course from consumer GPS devices.

However, TinyGPS++'s programmer interface is considerably simpler to use than TinyGPS, and the new library can extract arbitrary data from any of the myriad NMEA sentences out there, even proprietary ones.

GitHub: <https://github.com/mikalhart/TinyGPSPlus>



# Library *TinyGPSPlus*

Usage:

Let's say you have an Arduino hooked to an off-the-shelf GPS device and you want to display your altitude. You would simply create a TinyGPS++ instance like this:

```
1 | #include "TinyGPS++.h"
2 | TinyGPSPlus gps;
```

Repeatedly feed it characters from your GPS device:

```
1 | while (ss.available() > 0)
2 |     gps.encode(ss.read());
```

Then query it for the desired information:

```
1 | if (gps.altitude.isUpdated())
2 |     Serial.println(gps.altitude.meters());
```



# Library *TinyGPSPlus*

## *TinyGPSPlus*

Feeding the Hungry Object:

To get TinyGPS++ to work, you have to repeatedly funnel the characters to it from the GPS module using the encode() method. For example, if your GPS module is attached to pins 4(RX) and 3(TX), you might write code like this:

```
1 SoftwareSerial ss(4, 3);
2 void loop()
3 {
4     while (ss.available() > 0)
5         gps.encode(ss.read);
6 }
```

After the object has been “fed” you can query it to see if any data fields have been updated:

```
1 if (gps.location.isUpdated())
2 {
3     Serial.print("LAT="); Serial.print(gps.location.lat(), 6);
4     Serial.print("LNG="); Serial.println(gps.location.lng(), 6);
5 }
6 } // end loop()
```



# Library *TinyGPSPlus*

## *TinyGPSPlus*

```
// GPS  
static const uint32_t GPSBaud = 9600;  
TinyGPSPlus gps;  
  
static const int RX = D5, TX = D6;  
SoftwareSerial soft(RX, TX);
```



Define the global variable GPS with `tingpsPlus` and soft with `SoftwareSerial`

```
void RefreshMapData(){  
    while (soft.available() > 0){  
        if (gps.encode(soft.read())){  
            if (gps.location.isValid()){  
                double latitude = gps.location.lat();  
                double longitude = gps.location.lng();  
                latitude_data = String(latitude, 6);  
                longitude_data = String(longitude, 6);  
  
                ThingSpeak.setField(1, latitude_data);  
                ThingSpeak.setField(2, longitude_data);  
                ThingSpeak.writeFields(ch_no, write_api);  
  
                Serial.print(latitude_data);  
                Serial.print(" ");  
                Serial.println(longitude_data);  
                delay(2000);  
            }  
        }  
    }  
}
```

Get latitude by GPS sensor

Longitude is obtained by GPS sensor



When the soft serial port receives the data and the data is legal, it receives the double type of data and converts it to the String type, and passes the data into the ThingSpeak Channel through the channel Write API.





# Library *FS.h*

---

- Each ESP8266 comes with a flash drive, much like a small hard drive, in which files we upload are stored. The full name for this Flash is Serial Peripheral Interface Flash File System (SPIFFS).
- In addition to storing uploaded programs, we can also store web files or system configuration files in the ESP8266's flash memory.
- In our program, due to the large amount of HTML file code, we use the file flash system to store a series of our HTML-related files. Through the client request to access the file back to the client to achieve data interaction.
- The HTML file stored in the file flash system, only need to use when open the file to upload to the client, to achieve the front and back end interaction. Effectively avoid code redundancy.



# Arduino plugin

## Arduino ESP8266 filesystem uploader

*Arduino plugin which packs sketch data folder into SPIFFS filesystem image, and uploads the image to ESP8266 flash memory.*

### Installation

Make sure you use one of the supported versions of Arduino IDE and have ESP8266 core installed.

Download the tool archive from [releases page](#).

In your Arduino sketchbook directory, create directory if it doesn't exist yet.  
You can find the location of your sketchbook directory in the Arduino IDE at  
File > Preferences > Sketchbook location.tools

Unpack the tool into directory (the path will look like .tools<sketchbook directory>/tools/ESP8266FS/tool/esp8266fs.jar)

Restart Arduino IDE.

On OS X and Linux based OSs create the tools directory in  
~/Documents/Arduino/ and unpack the files there

This project uses this plugin to store HTML related files in a file flash system.

GitHub: <https://github.com/esp8266/arduino-esp8266fs-plugin>



# Demo





# Project2:

## Code Section



# Project 2: Code

```
#include <LiquidCrystal.h>
#include <ESP8266WiFi.h>
#include <ESP8266WebServer.h>
#include <WiFiManager.h>
#include <FS.h>
#include <TinyGPS++.h>
#include <SoftwareSerial.h>
#include "ThingSpeak.h"

ESP8266WebServer server(80);
WiFiClient client;
LiquidCrystal lcd = LiquidCrystal(D1, D2, D3, D0, D7, 3);
```

//Server  
//Client  
//LCD



# Project 2: Code

```
static const uint32_t GPSBaud = 9600;  
TinyGPSPlus gps; //GPS  
  
// ThingSpeak  
unsigned long ch_no = 1784543; //Replace with Thingspeak Channel number  
const char *write_api = "YLML7A9TRV8RLG5X"; // Replace with  
//Thingspeak write API  
  
//software serial  
static const int RX = D5, TX = D6;  
SoftwareSerial soft(RX, TX); //longitude  
//latitude  
String longitude_data = "114.490686";  
String latitude_data = "25.612273";
```



# Project 2: Code

```
void handleUserRequest();
void handleMapDateLongitude();
void handleMapDateLatitude();
String getContentType(String filename);
bool handleFileRead(String path);
void RefreshMapData();

void setup()
{
    Serial.begin(4800);                                // Serial Init
    soft.begin(GPSBaud);                             // software serial Init
    lcd.begin(16, 2);                                 // lcd Init
    WiFiManager wifiManager;                         // establish WiFiManager object
```





# Project 2: Code

```
wifiManager.autoConnect("AutoConnectAP");          //arguments is the name of  
Serial.print("WiFi Connected!");  
lcd.setCursor(2, 0);  
  
lcd.print("WiFi Connected!");    //Set the delay to facilitate reading of LCD display data  
delay(1500);  
lcd.clear();  
  
lcd.setCursor(2, 0);  
String s1 = "WiFi SSID:";        //Set the delay to facilitate reading of LCD display data  
s1 += WiFi.SSID();  
lcd.print(s1);  
delay(1500);  
lcd.clear();
```



# Project 2: Code

```
// Start text flash system and output related information
if (SPIFFS.begin()) // Start the flash file system
{
    Serial.println("SPIFFS Started.");
    lcd.setCursor(0, 0);
    lcd.print("SPIFFS Succeed");
    lcd.setCursor(0, 1);
    lcd.print("to Start.");
    delay(1500);
    lcd.clear();
}
```





# Project 2: Code

```
else
{
    Serial.println("SPIFFS Failed to Start.");

    lcd.setCursor(0, 0);
    lcd.print("SPIFFS Failed");
    lcd.setCursor(0, 1);
    lcd.print("to Start.");
    delay(1500);
    lcd.clear();
}
```



# Project 2: Code

```
// Set the server response to start the server  
server.on("/readMapLongitude", handleMapDateLongitude);  
server.on("/readMapLatitud", handleMapDateLatitud);  
server.onNotFound(handleUserRequest);  
server.begin();  
Serial.println("HTTP server started");  
  
lcd.setCursor(2, 0);  
lcd.print("HTTP server ");  
lcd.setCursor(3, 1);  
lcd.print("started");  
delay(1500);  
lcd.clear();
```

**//Start web service**

**// The serial port outputs the website service startup information**

**//The LCD outputs the website service startup information**



# Project 2: Code

```
ThingSpeak.begin(client);           //Start ThingSpeak  
  
Serial.println("ThingSpeak begin");  
lcd.setCursor(0, 0);  
lcd.print("ThingSpeak begin");  
delay(1500);  
lcd.clear();  
}  
                                //setup end
```



# Project 2: Code

```
void loop()
{
    RefreshMapData();

    lcd.setCursor(0, 0);
    lcd.print("long:");
    lcd.print(longitude_data);
    lcd.setCursor(0, 1);
    lcd.print("lat:");
    lcd.print(latitude_data);
    delay(2000);
    lcd.clear();
}
```

// Update the latitude and longitude and send it to ThingSpeak. This a functio.

// Output latitude and longitude information through LCD



# Project 2: Code

```
server.handleClient();  
}  
  
void handleUserRequest()  
{  
    String webAddress = server.uri();  
    bool fileReadOK = handleFileRead(webAddress);  
  
    {  
        server.send(404, "text/plain", "404 Not Found");  
    }  
}
```

// Processing user requests

// Handles HTTP access to the user's browser

//Get user request url information  
// User access is handled  
//through the handleFileRead function



# Project 2: Code

```
// Check whether the file exists  
bool handleFileRead(String path)  
{  
    if (path.endsWith("/"))  
    {  
        path = "/index.html";  
    }  
    String contentType = getContentType(path);  
    if (SPIFFS.exists(path))  
    {  
        if (SPIFFS.exists(path))
```

// If the access address ends with "/"  
// Change the access address to /index.html  
//for SPIFFS access  
// If the accessed file can be found in SPIFFS



# Project 2: Code

```
server.streamFile(file, contentType);
file.close();
return true;
}
return false;
}

String getContentType(String filename)
{
    if (filename.endsWith(".htm"))
        return "text/html";
    else if (filename.endsWith(".html"))
        return "text/html";
    else if (filename.endsWith(".css"))
```

//Attempts to open the file  
// And returns the file to the browser  
// And close the file

// If the file is not found, return false  
//Get the file type



# Project 2: Code

```
return "text/css";  
else if (filename.endsWith(".js"))  
    return "application/javascript";  
else if (filename.endsWith(".png"))  
    return "image/png";  
else if (filename.endsWith(".gif"))  
    return "image/gif";  
else if (filename.endsWith(".jpg"))  
    return "image/jpeg";  
else if (filename.endsWith(".ico"))  
    return "image/x-icon";  
else if (filename.endsWith(".xml"))
```

```
return "text/xml";  
else if (filename.endsWith(".pdf"))  
    return "application/x-pdf";  
else if (filename.endsWith(".zip"))  
    return "application/x-zip";  
else if (filename.endsWith(".gz"))  
    return "application/x-gzip";  
return "text/plain";  
}
```



# Project 2: Code

```
// Update latitude and longitude information and send it to ThingSpeak  
void RefreshMapData()  
{  
    while (soft.available() > 0)  
    {  
        if (gps.encode(soft.read()))  
        {  
            if (gps.location.isValid())  
            {  
                double latitude = gps.location.lat();  
                double longitude = gps.location.lng();  
                latitude_data = String(latitude, 6);  
            }  
        }  
    }  
}
```



# Project 2: Code

```
ThingSpeak.setField(1, latitude_data);
ThingSpeak.setField(2, longitude_data);
ThingSpeak.writeFields(ch_no, write_api);

Serial.print(latitude_data);
Serial.print("  ");
Serial.println(longitude_data);
delay(2000);
}

}

}

}
```

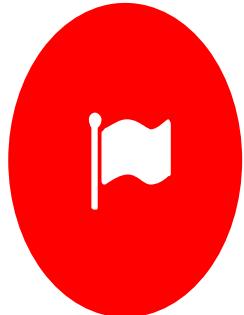
```
//Send longitude information
void handleMapDateLongitude()
{
    server.send(200, "text/plain", longitude_data);
}

//Send latitude information
void handleMapDateLatitud()
{
    server.send(200, "text/plain", latitude_data);
}
```

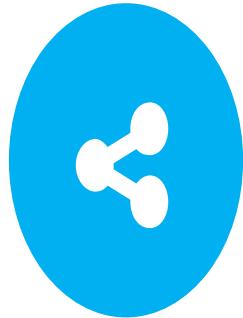


# Project 2: HTML

1. Set j basic style



3. Creating a Map



2. Connect ESP8266 to HTML



4. Display location information





# 1. Setting basic Styles

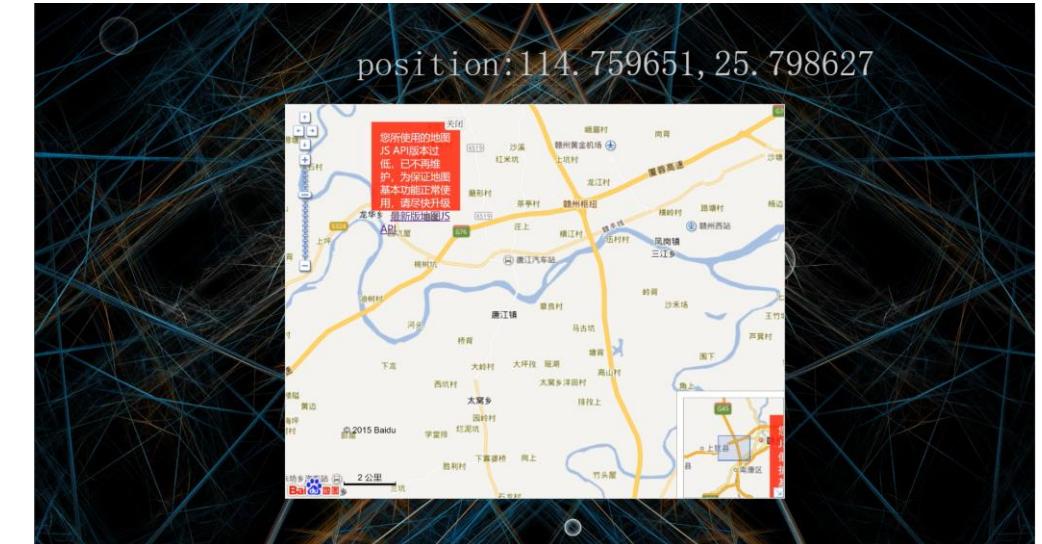


The first is the welcome page, which has a title and a button and a rotating log

When you click the welcome page button, you jump to the map page, where the location information is displayed.

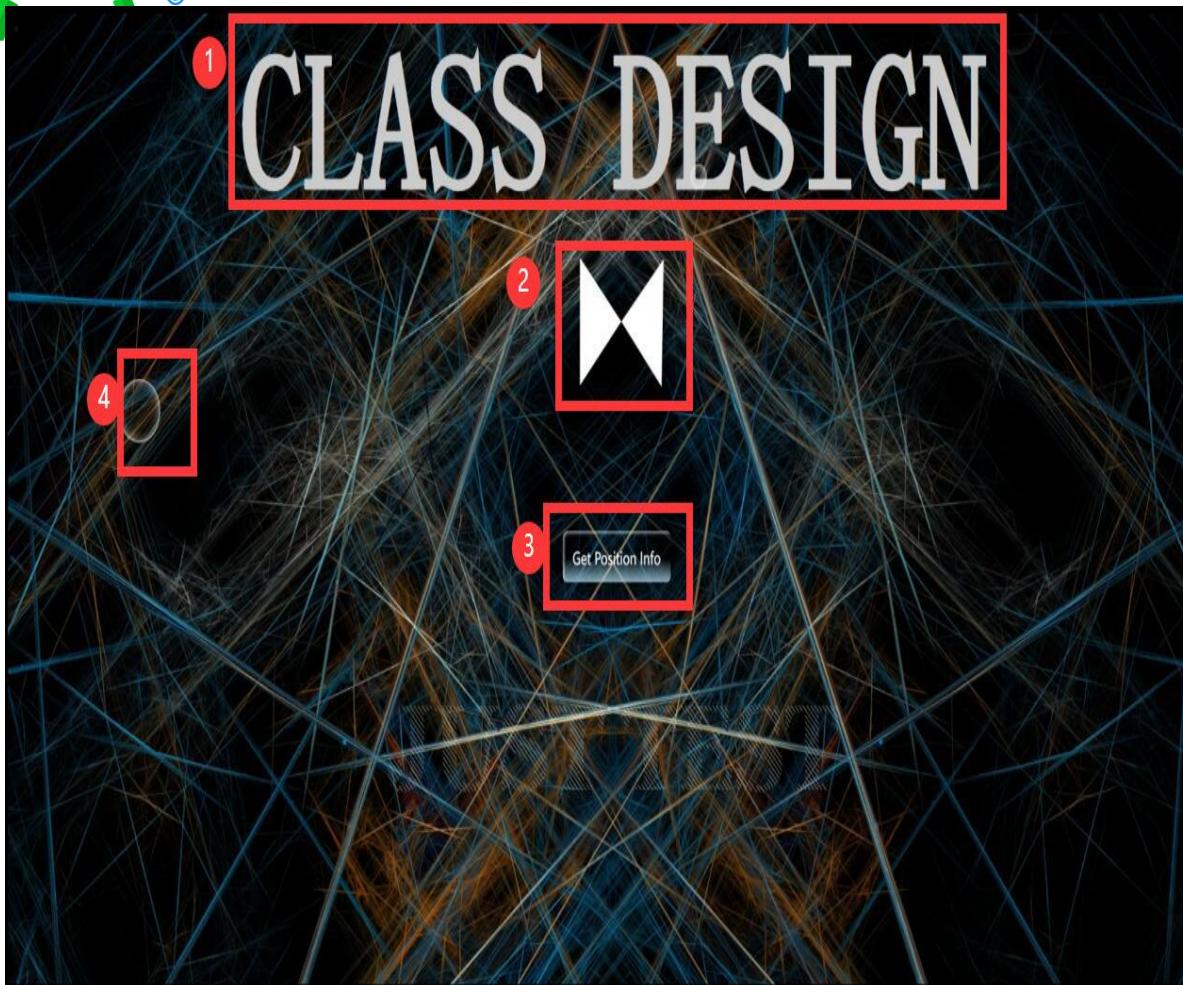
The location of the vehicle will be displayed at the center of the map, which is not an online map,

The apiid called baidu map is a static page and the map is set to one second Refresh once, each refresh is based on the latitude and longitude to determine the location of the map center





# 1. Setting basic Styles



The page will be divided into four parts to explain

1. Add a title and background
2. Add the log
3. Add a rotating button
4. Add floating bubbles



# 1. Setting basic Styles

## 1. Add title and background

```
h1 {  
    text-align: center;           //In the center  
    color: #cccccc;             //set color  
    font-size: 150px;            //set size  
    font-family: "Cormorant Garamond", serif; //set font  
}
```

Set their styles in the CSS module and add them to the body

```
body {  
    background-image: url(https://w.wallhaven.cc/full/q2/wallhaven-q2pexd.jpg); /*Set the path of the image, the image source network*/  
    background-repeat: no-repeat;          /*Make the image never repeat no matter what size */  
    background-size: 100%;                /*set background size*/  
}
```



# 1. Setting basic Styles

2.add log

```
.kinetic::after,  
.kinetic::before {  
    content: " ";  
    position: absolute;  
    top: 0;  
    left: 0;  
    width: 0;  
    height: 0;  
    border: 50px solid transparent;  
    border-bottom-color: #fff;  
    animation: rotateA 2s linear infinite 0.5s; //Let A rotate indefinitely  
}  
  
.kinetic::before {  
    transform: rotate(90deg);  
    animation: rotateB 2s linear infinite; //Set B to rotate indefinitely  
}  
//Add A and B to the triangle of rotation  
@keyframes rotateA {  
    0%,  
    25% {  
        transform: rotate(0deg);  
    }  
    50%,  
    75% {  
        transform: rotate(180deg);  
    }  
    100% {  
        transform: rotate(360deg);  
    }  
}  
  
@keyframes rotateB {  
    0%,  
    25% {  
        transform: rotate(90deg);  
    }  
    50%,  
    75% {  
        transform: rotate(270deg);  
    }  
    100% {  
        transform: rotate(450deg);  
    }  
}
```

```
50%,  
75% {  
    transform: rotate(180deg);  
}  
  
100% {  
    transform: rotate(360deg);  
}  
}  
  
@keyframes rotateB {  
    0%,  
    25% {  
        transform: rotate(90deg);  
    }  
    50%,  
    75% {  
        transform: rotate(270deg);  
    }  
    100% {  
        transform: rotate(450deg);  
    }  
}
```



# 1. Setting basic Styles



3. add button

//Add a button in the body

```
<button class="custom-btn btn" onclick=window.location.href='map.html'><span>Click!</span><span>Get Position  
Info</span></button>
```

//Add button background and dimensions

```
.btn {  
    position: relative;  
    right: 20px;  
    bottom: 20px;  
    border: none;  
    box-shadow: none;  
    width: 130px;  
    height: 40px;  
    line-height: 42px;  
    -webkit-perspective: 230px;  
    perspective: 230px;
```



# 1. Setting basic Styles



## 4. Add bubble

// Sets the basic style of the button

```
.bubble {          //Sets the basic style
    position: absolute;
    border-radius: 50%;
    border: 2px solid #fff;
    box-shadow: inset 0 0 8px #fff;
    animation: flutter 10s infinite;
    opacity: 0;
}

@keyframes flutter {      //Let the bubbles fly up
    0% {
        transform: translateX(0);
        bottom: -100px;
        opacity: 1;
    }
    50% {
        transform: translateX(100px);
        opacity: 0.5;
    }
    100% {
        transform: translateX(0px);
        bottom: 100px;
        opacity: 0;
    }
}
```

//Add multiple bubbles

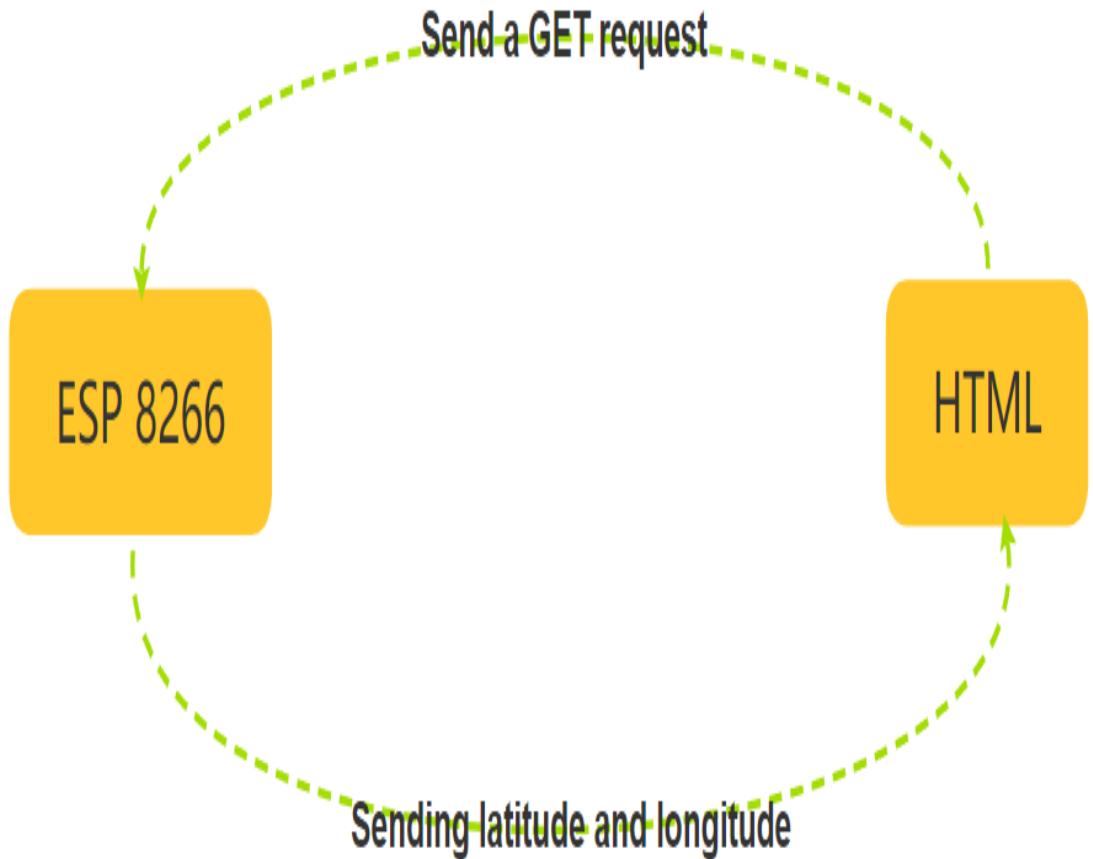
```
.bubble:nth-child(1) {
    left: -10%;
    width: 50px;
    height: 50px;
    animation-duration: 9s;
    animation-delay: 0.1s;
}

.bubble:nth-child(2) {
    left: 15%;
    width: 20px;
    height: 20px;
    animation-duration: 6s;
    animation-delay: 1.5s;
}

.bubble:nth-child(3) {
    left: 20%;
    width: 60px;
    height: 60px;
    animation-duration: 10s;
}
```



## 2. Connect ESP8266 to HTML



- The basic way ESP8266 connects to HTML is to send information to and from each other using the HTTP network protocol



## 2. Connect ESP8266 to HTML

```
function getMapX() {           //Obtain longitude
    var xhttp = new XMLHttpRequest();           //Creating a Request object
    xhttp.onreadystatechange = function () {     //Sending an HTTP request
        if (this.readyState == 4 && this.status == 200) { //Change the value of x to the value
            document.getElementById("x").innerHTML =      //of the ESP8266 response
                this.responseText;
            x=this.responseText
        }
    };
    xhttp.open("GET", "readMapLongitude", true);
    xhttp.send();
    return x;
}

function getMapY() {           //Same principle as above
    var xhttp = new XMLHttpRequest();
    xhttp.onreadystatechange = function () {
        if (this.readyState == 4 && this.status == 200) {
            document.getElementById("y").innerHTML =
                this.responseText;
            y=this.responseText
        }
    };
    xhttp.open("GET", "readMapLatitud", true);
    xhttp.send();
    return y;
}
```

There are two methods on the left, one is to get longitude, the other is to get latitude

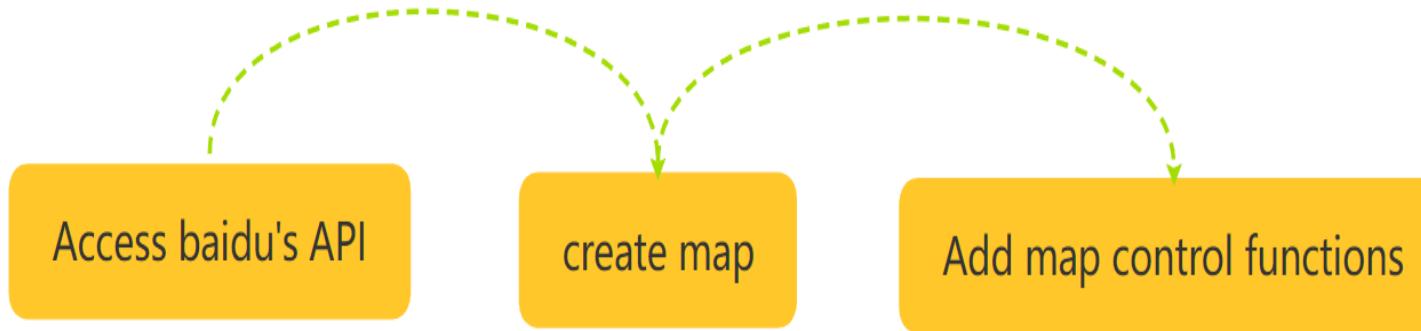
They both get latitude and longitude by sending a GET request and receiving the returned data





### 3.Creating a Map

---



Here are three steps, first introduce Baidu API, use API to create map, and add map component

```
<meta http-equiv="Content-Type" content="text/html; charset=gb2312" />
<meta name="keywords" content="百度地图, 百度地图API, 百度地图自定义工具, 百度地图所见即所得工具" />
<meta name="description" content="百度地图API自定义地图, 帮助用户在可视化操作下生成百度地图" />
```

//introduce the Baidu API



### 3. Creating a Map

```
//Create and initialize map functions:  
function initMap(x,y) {  
    createMap(x,y);//create map  
    setMapEvent();//Set the map event  
    addMapControl();//Add controls to the map  
}  
//Create map function:  
function createMap(x,y) {  
    var map = new BMap.Map("dituContent");//Create a map in baidu Map container  
    var point = new BMap.Point(x,y);//Define a central point coordinate  
    map.centerAndZoom(point, 13);  
//Set the center point and coordinates of the map and display the map in the map container  
    window.map = map;//Store the map variable globally  
}  
  
//Map event setting function:  
function setMapEvent() {  
    map.enableScrollWheelZoom();//Enable the map wheel to zoom in and out  
}
```



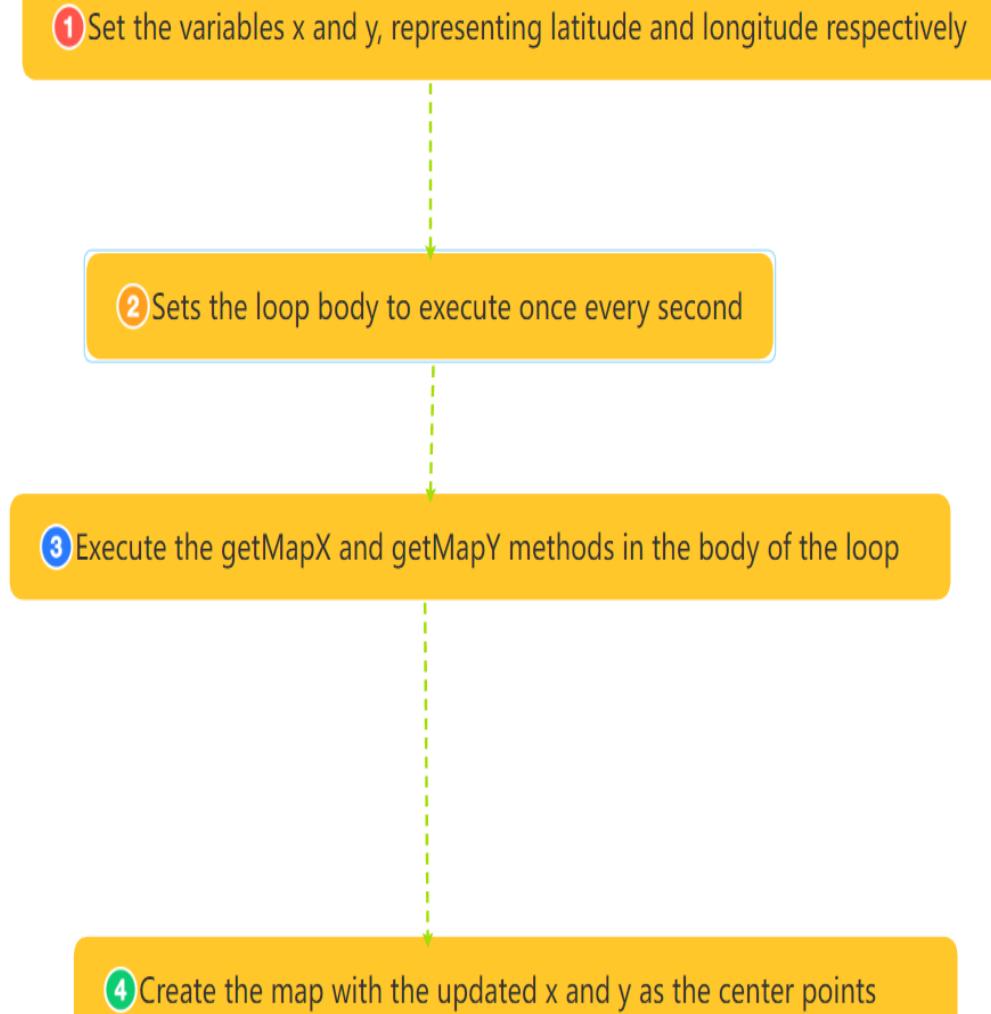
### 3. Creating a Map

```
//Map control add function:  
  
function addMapControl() {  
    //Adds a zoom control to the map  
  
    var ctrl_nav = new BMap.NavigationControl({ anchor: BMAP_ANCHOR_TOP_LEFT, type:  
BMAP_NAVIGATION_CONTROL_LARGE });  
  
    map.addControl(ctrl_nav);  
  
    //Adds a thumbnail control to the map  
  
    var ctrl_ove = new BMap.OverviewMapControl({ anchor: BMAP_ANCHOR_BOTTOM_RIGHT, isOpen: 1 });  
    map.addControl(ctrl_ove);  
  
    //Adds a scale control to the map  
  
    var ctrl_sca = new BMap.ScaleControl({ anchor: BMAP_ANCHOR_BOTTOM_LEFT });  
  
    map.addControl(ctrl_sca);  
}
```



# 4. Display location information

- There are four steps, as shown on the left.
- The basic step is to call baidu map API to create a static map.
- Update the map using the longitude and latitude sent by ESP8266 as the center point.





# Demo





# Arduino IOT Cloud

How to create connect to the IOT CLOUD

## STEP 1 Create Things

(1)Create Things ,click the Setup.Firstly,we should add two String Variables called longitude and latitude.

The screenshot shows the 'Add variable' dialog box from the Arduino IOT Cloud interface. The dialog has the following fields:

- Name:** longitude
- Type:** Character String eg.'Hello'
- Declaration:** String longitude;
- Variable Permission:** Read & Write (radio button selected)
- Variable Update Policy:** On change (radio button selected)

The background shows the main 'Variables' page with an 'ADD VARIABLE' button.



# Arduino IOT Cloud

How to create connect to the IOT CLOUD

(2) Secondly, setup the device , select the ESP8266 and find the NodeMCU1.0(ESP-12E Module), named it as task, and copy the Secret Key.

The screenshot shows the Arduino IOT Cloud web interface. At the top, there's a navigation bar with tabs: Things (which is active), Dashboards, Devices, Integrations, and Templates. On the far right, there are buttons for 'UPGRADE PLAN', a grid icon, and a user profile icon. Below the navigation, there's a breadcrumb trail: 'task' > 'Setup'. A modal window titled 'Setup device' is open. On the left of the modal, there's a sidebar labeled 'Variables' with two entries: 'latitude' (String type) and 'longitude' (String type). The main area of the modal has the heading 'Select device type' and the instruction 'Please select the device type and model you want to configure'. It features three radio buttons: 'ESP8266' (selected), 'ESP32', and 'LoRaWAN'. Below these is a dropdown menu set to 'NodeMCU 1.0 (ESP-12E Module)'. At the bottom of the modal is a green 'CONTINUE' button. In the bottom right corner of the main interface, there's a small 'Configure' button.



(3)Setup theNetWork,  
entry the WiFi name,  
Password and Secret Key.

# Arduino IOT Cloud

## How to create connect to the IOT CLOUD

The screenshot shows the Arduino IOT Cloud interface. At the top, there's a navigation bar with tabs for Things, Dashboards, Devices, Integrations, and Templates. On the far right, there are buttons for UPGRADE PLAN, profile, and settings. Below the navigation bar, there's a sidebar titled 'task' containing a 'Variables' section with entries for 'latitude' and 'longitude'. The main area is a modal window titled 'Configure network'. Inside the modal, there's a note: 'You will find these network parameters in the secret tab in your sketch, and your device will be able to connect to the network once the sketch will be uploaded.' Below the note are three input fields: 'Wi-Fi Name \*' with the value 'test1', 'Password \*' with a redacted value, and 'Secret Key \*' with a redacted value. At the bottom right of the modal is a 'SAVE' button. At the very bottom of the page, there's a link 'Set webhook'.



# Arduino IOT Cloud

How to create connect to the IOT CLOUD

## STEP 2 SetDashboards

Add widget switch ,  
and Linked Variable  
longitude and latitude to  
two Message parts.

The screenshot shows the Arduino IOT Cloud dashboard editor interface. At the top, there are several buttons: a grey circle with a dot, a white square with a checkmark, a teal 'ADD' button with a dropdown arrow, a diamond shape, and a square with a diagonal line. To the right of these is the title 'Untitled'. On the far right are three small icons: a share symbol, a download symbol, and an info symbol. The main area contains two message parts. The first message part is titled 'longitude' and the second is titled 'latitude'. Both parts have a light grey background and a thin blue border. At the bottom of each part is a white input field with rounded corners, containing the placeholder text 'Type a message'. There is also a small teal circular icon with an upward arrow to the right of each input field. A vertical scroll bar is visible on the right side of the main editor area.



# Arduino IOT Cloud

How to create connect to the IOT CLOUD

## STEP 3 Sketch

Refine the program ,  
manager the necessary  
libraries keep the Arduino Agent  
and select the NodeMCU and  
Port-com3. Upload the  
code,then all thing was ready to  
do the trail in real boards and  
receive the data we want .

The screenshot shows the Arduino IDE interface. On the left, the 'LIBRARIES' tab is selected in the sidebar. The main area displays the 'LIBRARY MANAGER' for the 'NODEMCU 1.0 (ESP-12E MODULE)' board. It lists several libraries: 'THINGSPEAK' (ThingSpeak Communication Library for Arduino, ESP8266 & EPS32), 'TINYGPSPLUS' (TinyGPSPlus provides object-oriented parsing of GPS (NMEA) sentences), and examples for both. On the right, the code editor window shows a sketch named 'task\_jul01a'. The code includes comments explaining the use of ThingSpeak variables and the generation of functions for those variables. It also includes #include statements for 'thingProperties.h', 'LiquidCrystal.h', 'ESP8266WiFi.h', 'ESP8266WebServer.h', 'FS.h', 'TinyGPS++.h', 'SoftwareSerial.h', and 'Thingspeak.h', along with a call to 'ESP8266WebServer server(80);'.

```
/*
Sketch generated by the Arduino IoT Cloud Thing "Untitled"
https://create.arduino.cc/cloud/things/d1d19f6e-8f0d-4c58-92d4-f07964c68da9

Arduino IoT Cloud Variables description

The following variables are automatically generated and updated when changes are made to the Thing

String latitude;
String longitude;

Variables which are marked as READ/WRITE in the Cloud Thing will also have functions
which are called when their values are changed from the Dashboard.
These functions are generated with the Thing and added at the end of this sketch.

*/
#include "thingProperties.h"
#include <LiquidCrystal.h>
#include <ESP8266WiFi.h>
#include <ESP8266WebServer.h>
#include <FS.h>
#include <TinyGPS++.h>
#include <SoftwareSerial.h>
#include "Thingspeak.h"

// Server
ESP8266WebServer server(80);
```



# Arduino IOT Cloud

How to create connect to the IOT CLOUD

Show the data

The screenshot shows a web browser displaying the Arduino Cloud IoT documentation at <https://docs.arduino.cc/cloud/iot-cloud>. The page title is "Arduino Cloud IoT". Below the title, there is a sub-header: "Configure, program and connect your devices - all through the Arduino IoT Cloud service." There are two main buttons: "QUICKSTART GUIDE" and "ARDUINO IOT CLOUD". A Bandicam recording window is overlaid on the browser, showing a video player interface with a play button and a volume slider set to 2. The video player displays two files: "bandicam 2022-07-01 18-46-31-729.avi" (2.4MB) and "bandicam 2022-07-01 18-46-40-309.avi" (12.9MB). At the bottom of the browser window, there is a message: "Please follow the instructions on the email we sent you to activate your account." with a "Resend email" link, and links to "Learn how to set up the Arduino Cloud IoT" and "Learn how to setup webhooks with the Arduino IoT Cloud".





```
#include "thingProperties.h" //The header file that the IOT automatically imports  
#include <TinyGPS++.h>  
#include <SoftwareSerial.h>  
  
TinyGPSPlus gps;  
SoftwareSerial soft(D5,D6);  
  
void setup() {  
    Serial.begin(9600);  
    soft.begin(9600);  
    delay(1500);
```

//Soft serial pin definition and use  
// Initialize serial and wait for port to open:  
  
// This delay gives the chance to wait for a  
// Serial Monitor without blocking if none is found



# Project 2: Code

```
initProperties(); // Defined in thingProperties.h  
// Connect to Arduino IoT Cloud  
ArduinoCloud.begin(ArduinoIoTPreferredConnection);  
  
setDebugMessageLevel(2);  
ArduinoCloud.printDebugInfo();  
}  
  
void loop() {  
    ArduinoCloud.update(); // Arduino Cloud update
```



# Project 2: Code

```
while (soft.available() > 0) //Judgment criteria
{
    if (gps.encode(soft.read())) //encode GPS data
    {
        if (gps.location.isValid()) //Whether the location is
        {
            double latitude = gps.location.lat(); // legal or not
            double longitude = gps.location.lng();

            latitude_data = String(latitude, 6); //Receive double type data
            longitude_data = String(longitude, 6); //double data to string
        }
    }
}
```



# Project 2: Code

---

```
Serial.print("纬度: ");
    Serial.print(latitude_data);
    Serial.print(" ");
    Serial.print("经度: ");
    Serial.println(longitude_data); // Serial port print data
    delay(1000);
}
}
}

}
```



# Project3:

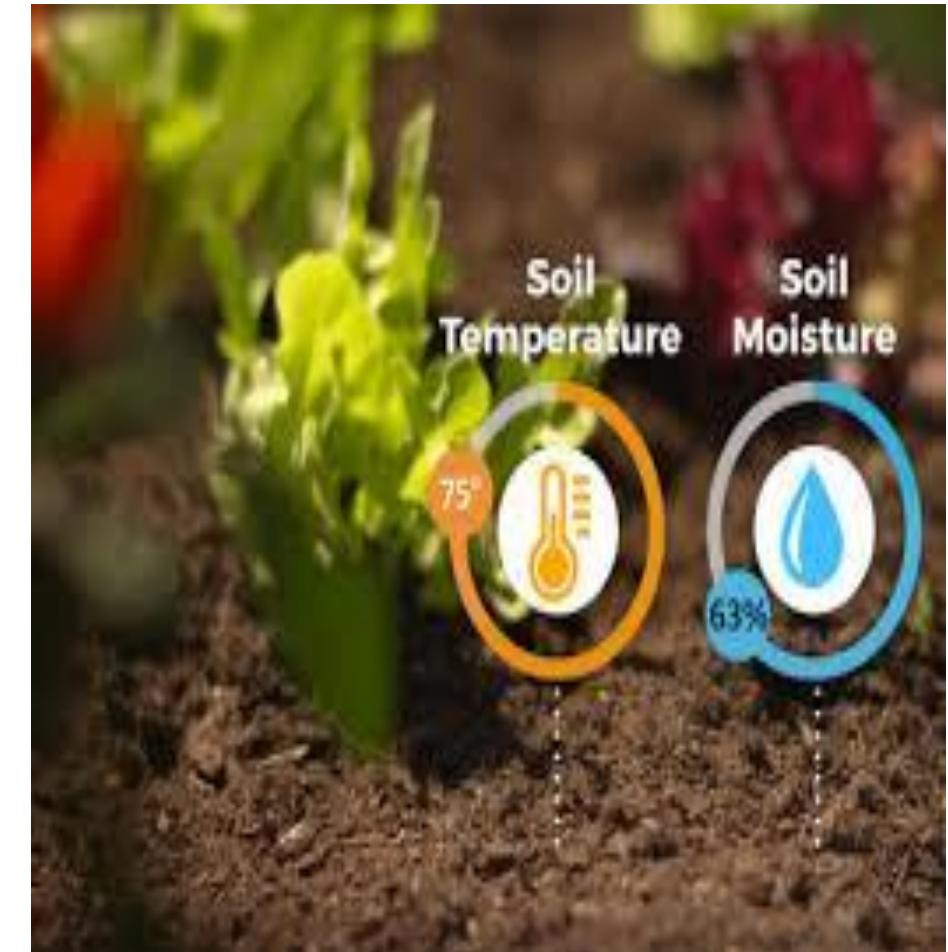
IoT based Irrigation System





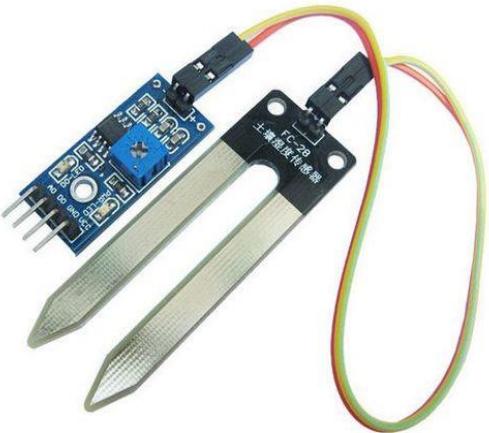
# Project 3: Aim & Study

- Create our own webservers to log the data with real-time graphs.
- Here we will also create ESP8266 Web Server Data Logger using sht10 Sensor.
- It Can be used to monitor the temperature and humidity of an area.
- So,it can be applied by the Food Industry、Archives Management Office、Greenhouse、Tobacco Industry,etc.





# Project 3: Component

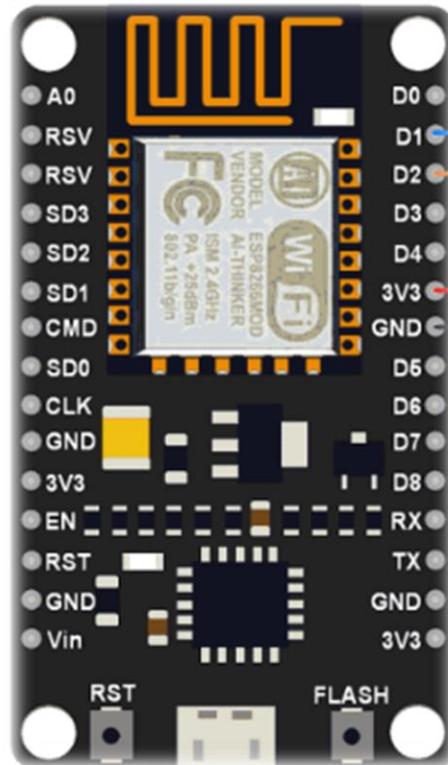


Soil Moisture Detection Humidity Sensor

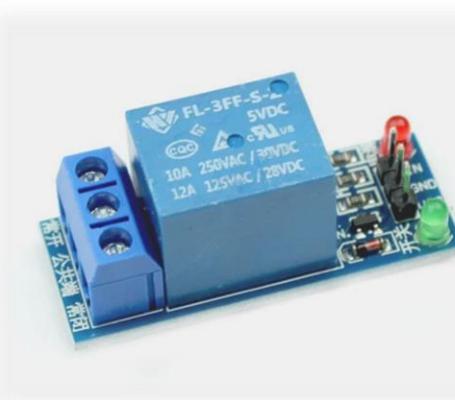
YFS201 Water Flow Sensor



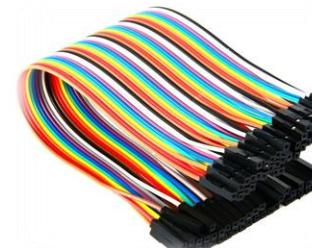
Node MCU ESP8266-12e



SHT10 module



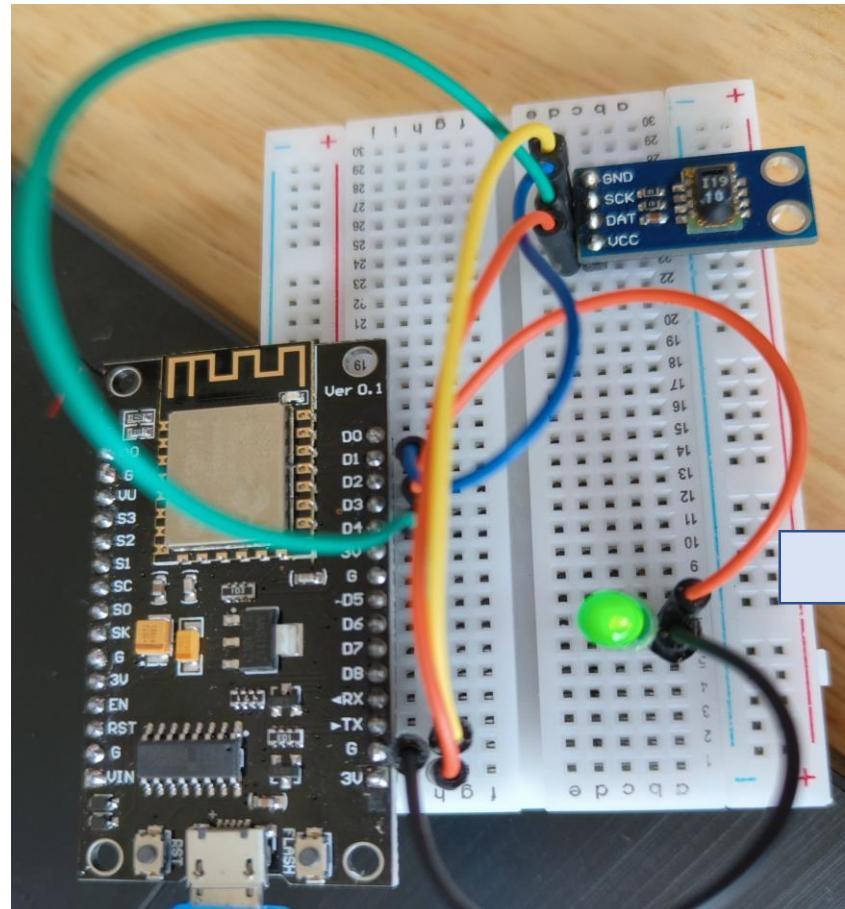
Jumper Wires  
(Female to Female)





# Project 3:Component

- This system consists of detection object, temperature and humidity sensor, NodeMCU, web terminal, Bread Board, etc.



VCC connects to 3v  
GND connects to G  
SCK connects to D2  
DAT connects to D4  
LED connects to D3 and G



# Project 3:Component

---

## 1、*NodeMCU*

As a WIFI network communication module, ESP8266 can realize the network transmission of data, and has the characteristics of stable operation and low price. ESP8266 supports three working modes: AP/STA/AP+STA. Select the STA working mode here, and connect ESP8266 as a station to the WiFi network established by the access point.

## 2、*SHT10 Sensor*

The power supply voltage range of SHT10 is 2.4v-5.5v, and the recommended power supply voltage is 3.3v. The serial interface of SHT1x has been optimized in terms of sensor signal reading and power consumption;

PIN Of the SHT10:

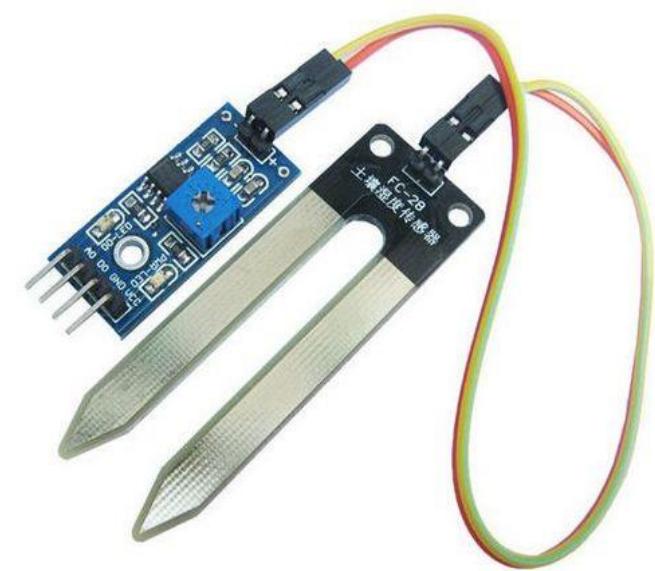
**SCK:** SCK is used for communication synchronization between the microcontroller and SHT10.

**DATA:** The DATA pin is a tri-state structure for reading sensor data. When sending a command to the sensor, DATA is valid on the rising edge of SCK and must remain stable when SCK is high, and DATA changes after the falling edge of SCK.



## Description

- Soil sensor: the moisture sensor can be used to detect the moisture of the soil, when the soil is dry , the module outputs a high level , whereas the output low. Using this sensor make an automatic watering system , so that your garden plants need people to manage.
  - Adjustable sensitivity ( shown in blue digital potentiometer adjustment ).
  - Operating Voltage 3.3V-5V.
  - Module Dual Output mode , a simple digital output , analog output more accurate.
  - With fixed bolt hole for easy installation.
  - Small PCB board size: 3cm \* 1.6cm.
  - Power indicator ( red ) and the digital switch output indicator ( green ).
  - Using LM393 comparator chip, stable.
  - VCC external 3.3V-5V
  - GND GND External
  - DO small board digital output interfaces ( 0 and 1 )
  - AO small board analog output interface



- A soil moisture and humidity module most sensitive to the environment , usually used to detect soil moisture.
- Modules in the soil moisture reach the set threshold , DO port output high when soil moisture exceeds a set threshold, the module D0 output low.
- Digital outputs D0 small plates can be directly connected with the microcontroller through the microcontroller to detect high and low , thereby detecting soil moisture.
- Small plates digital output DO OUR relay module can directly drive the buzzer module , which can be composed of a soil moisture alarm equipment.
- Small plates AO analog output modules can be connected and AD through the AD converter , you can get a more accurate value of soil moisture.

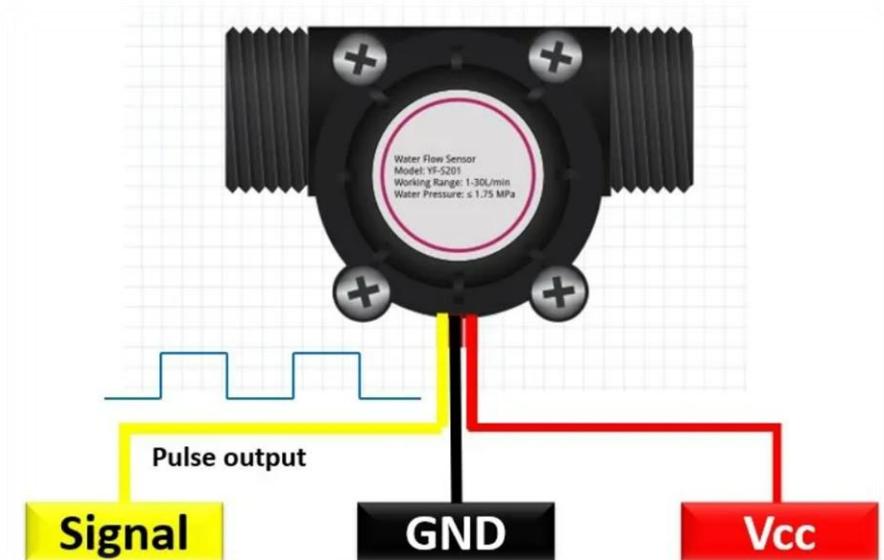


## Project 3:Component

---

- **Water Flow Sensor:**

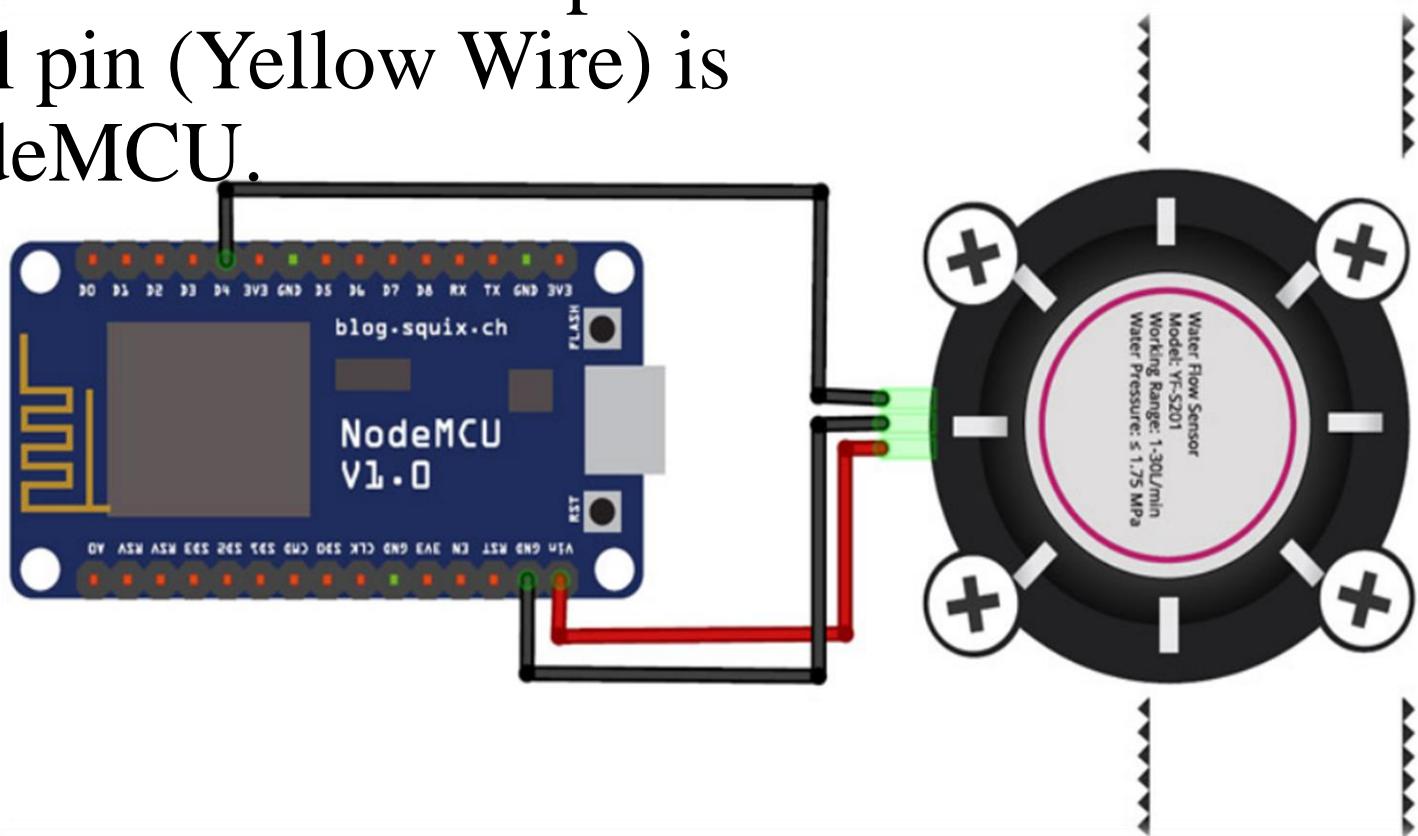
Water flow sensors are installed at the water source or pipes to measure the rate of flow of water and calculate the amount of water flowed through the pipe. Rate of flow of water is measured as liters per hour or cubic meters.





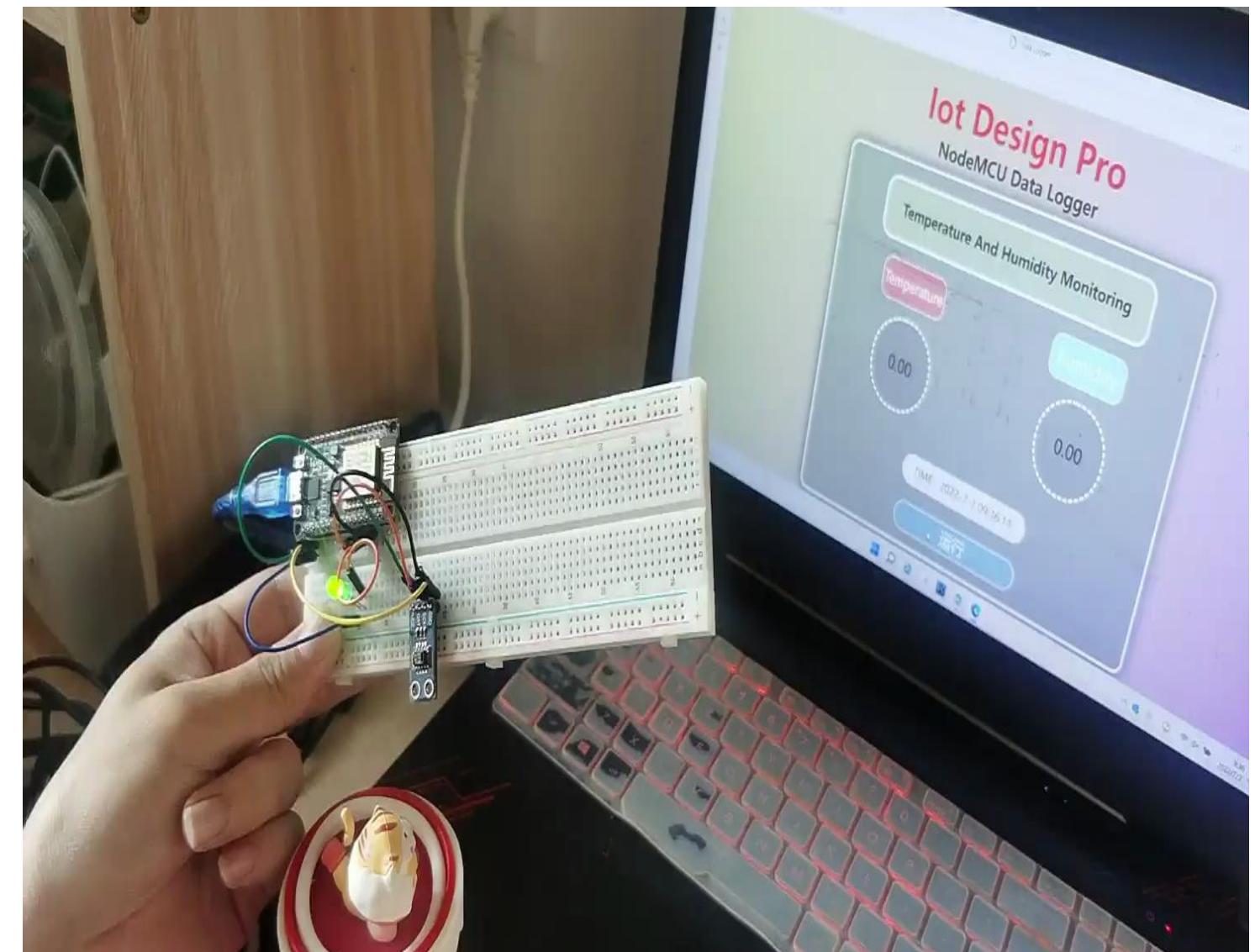
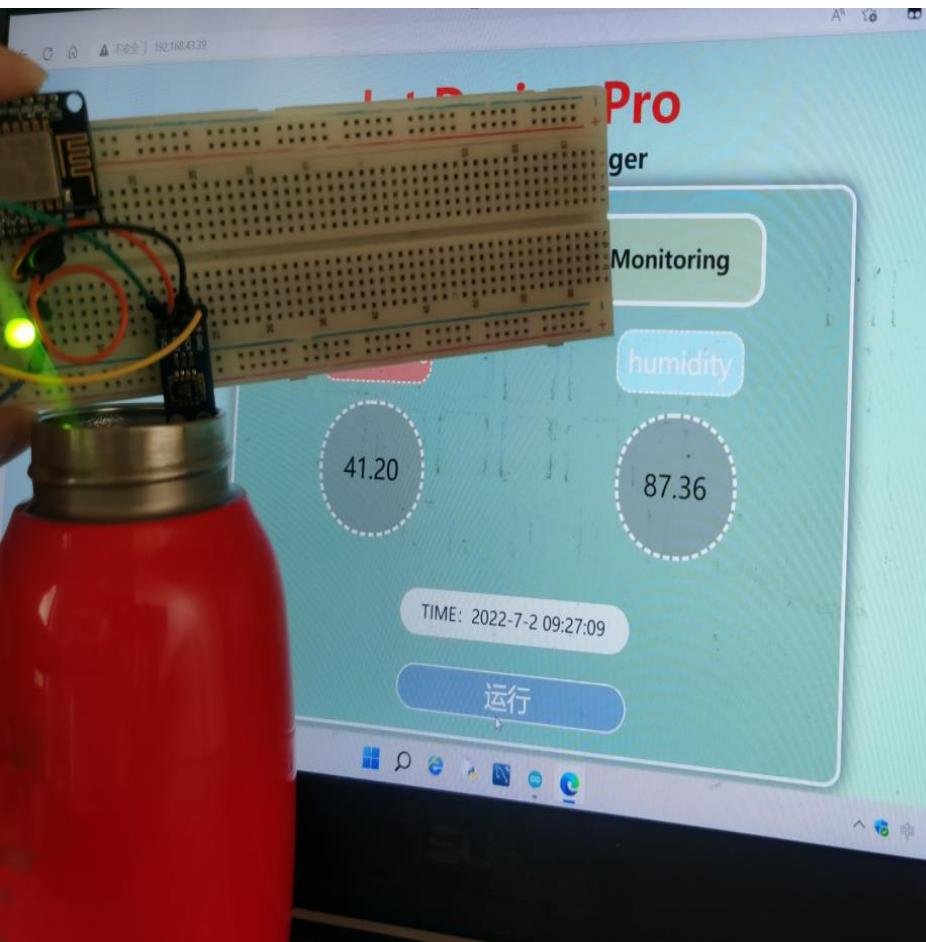
# Project 3:Component

- The VCC (Red Wire) and GND (Black Wire) pins of flow sensors are connected to 5V and GND pins of NodeMCU while the Signal pin (Yellow Wire) is connected to D4 pin of NodeMCU.



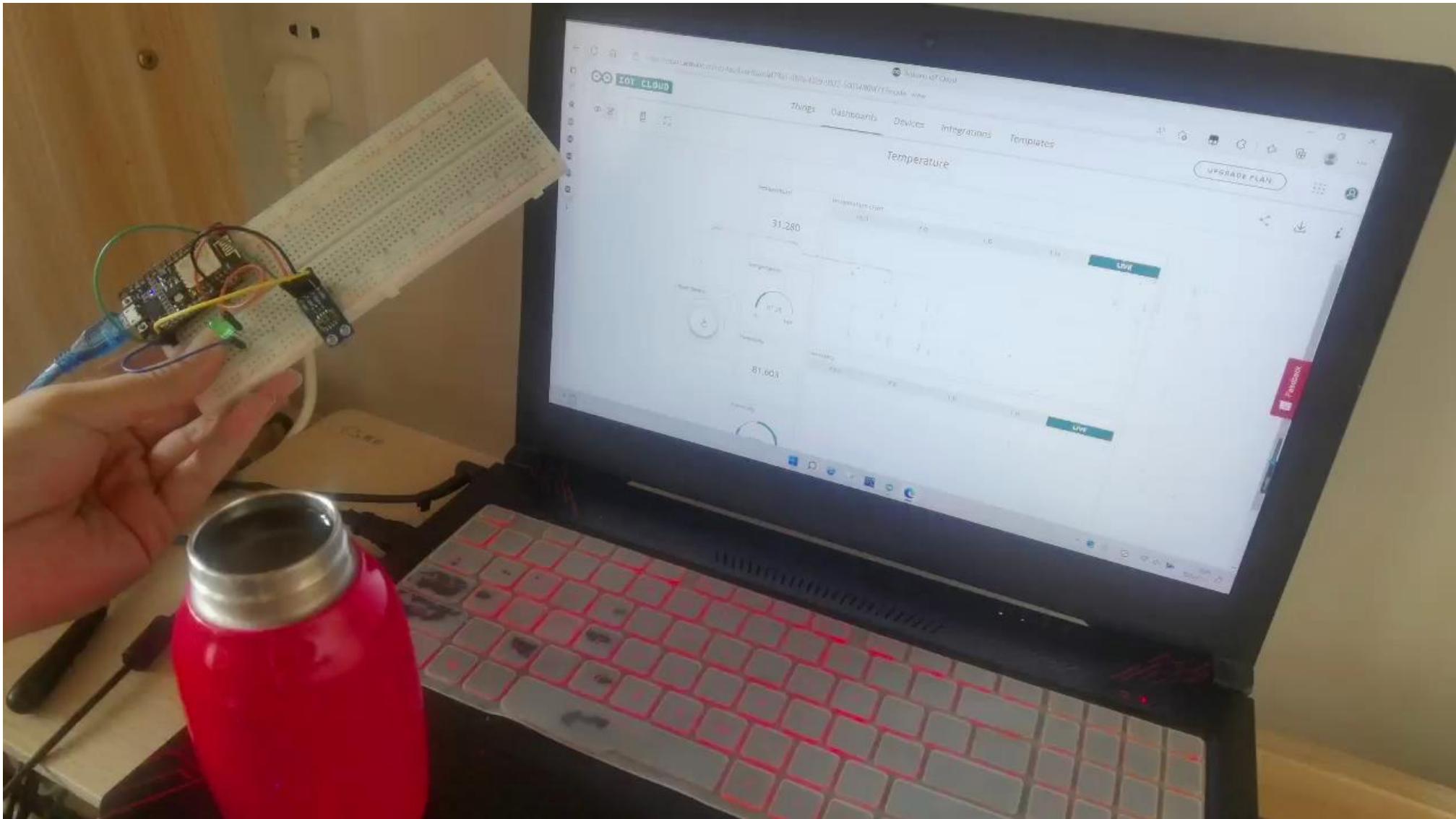


# Project 3: DEMO on Web





# Project 3: Demo Arduino IOT Cloud





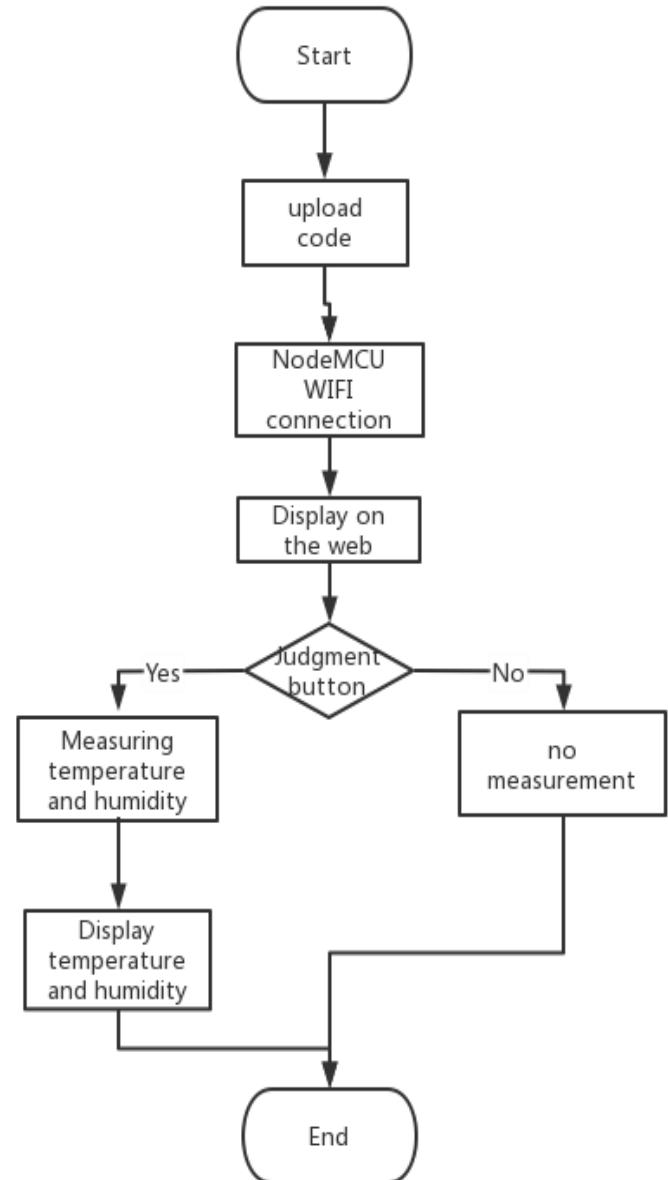
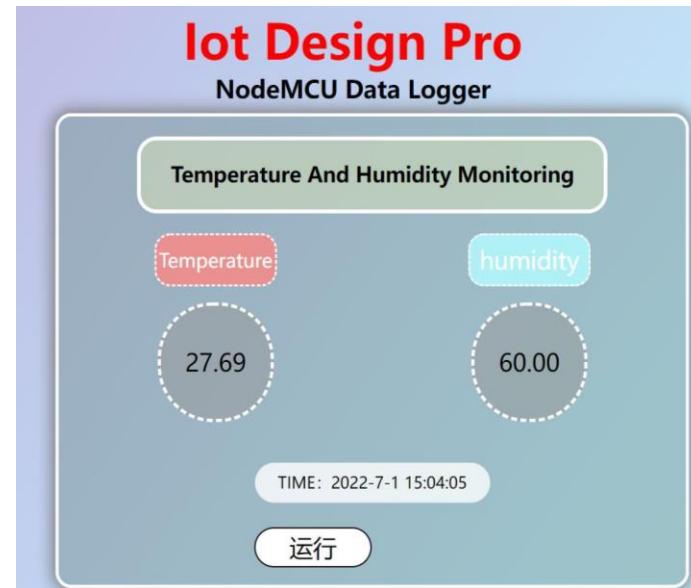
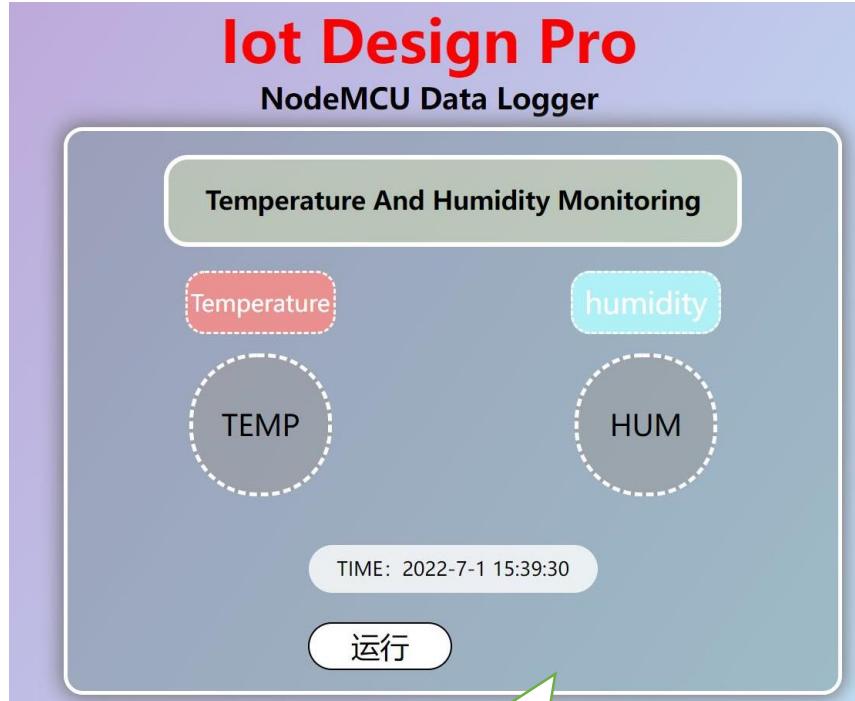
## Project 3:

QUESTIONS  
**ANSWERS**



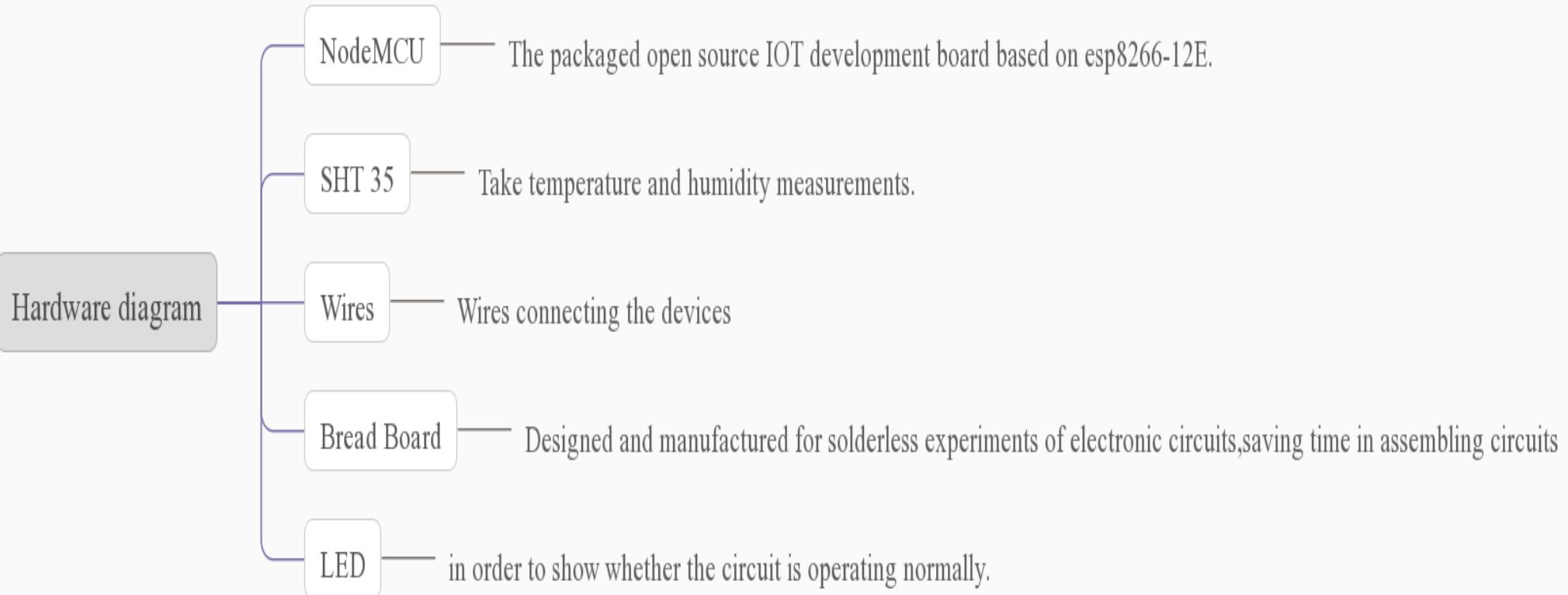


# Flow Chart





# hardware diagram



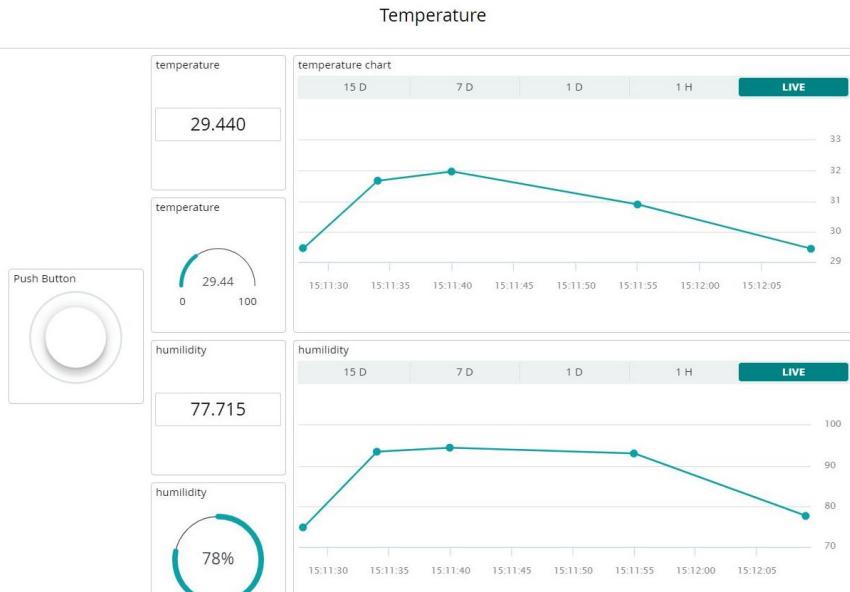


# Software Flow Chart

COM3

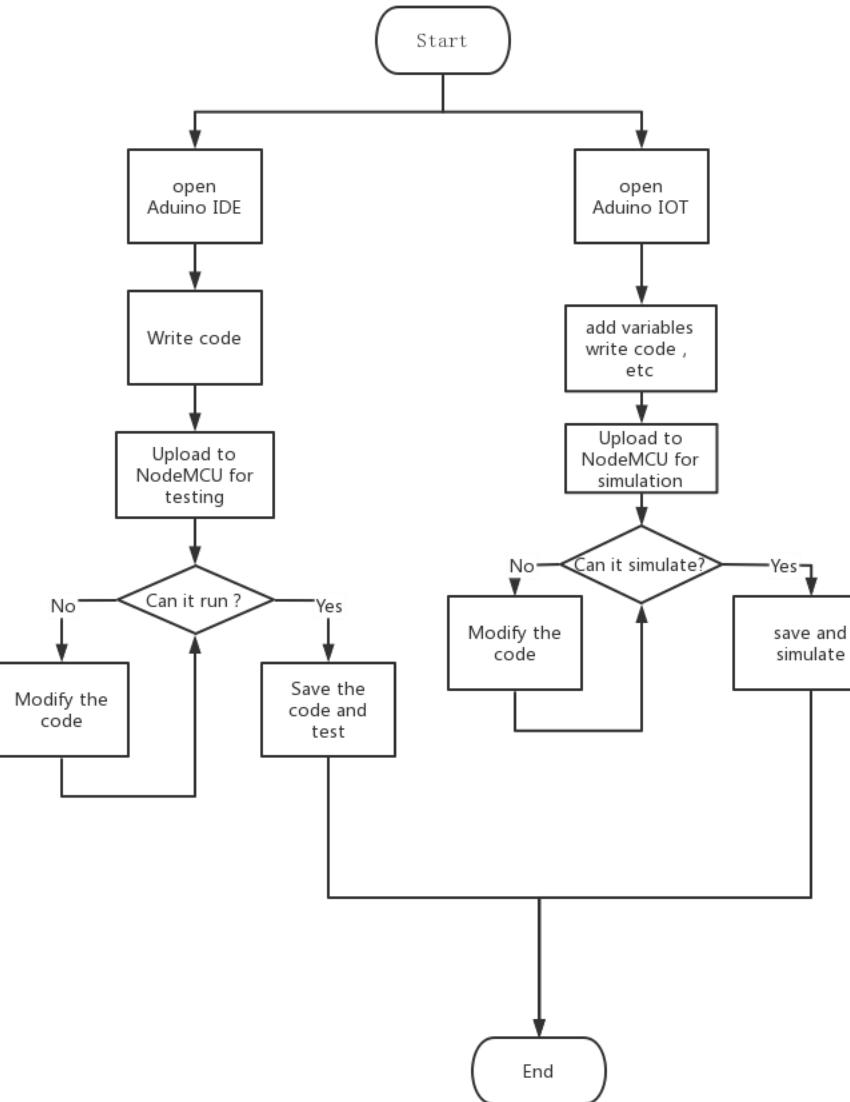
```
r110$0$|0000010c|ffff0r0p0p fo0dNN0b0k  
.....  
Connected to 新晋小色批  
IP address: 192.168.43.39  
HTTP server started  
27.7  
60.7  
27.7  
60.0  
27.7  
59.5
```

自动滚屏  Show timestamp



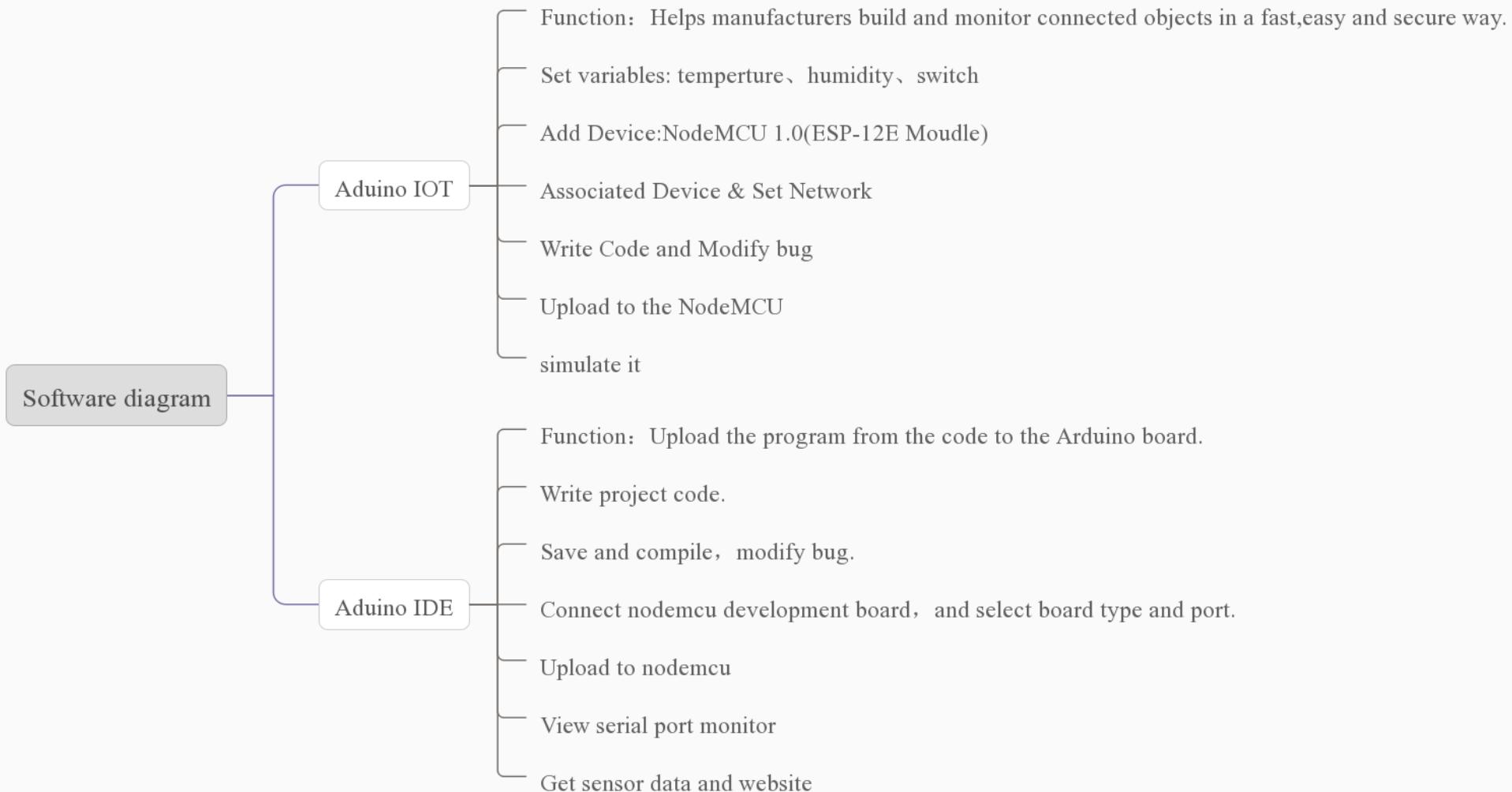
IOT page

IDE page



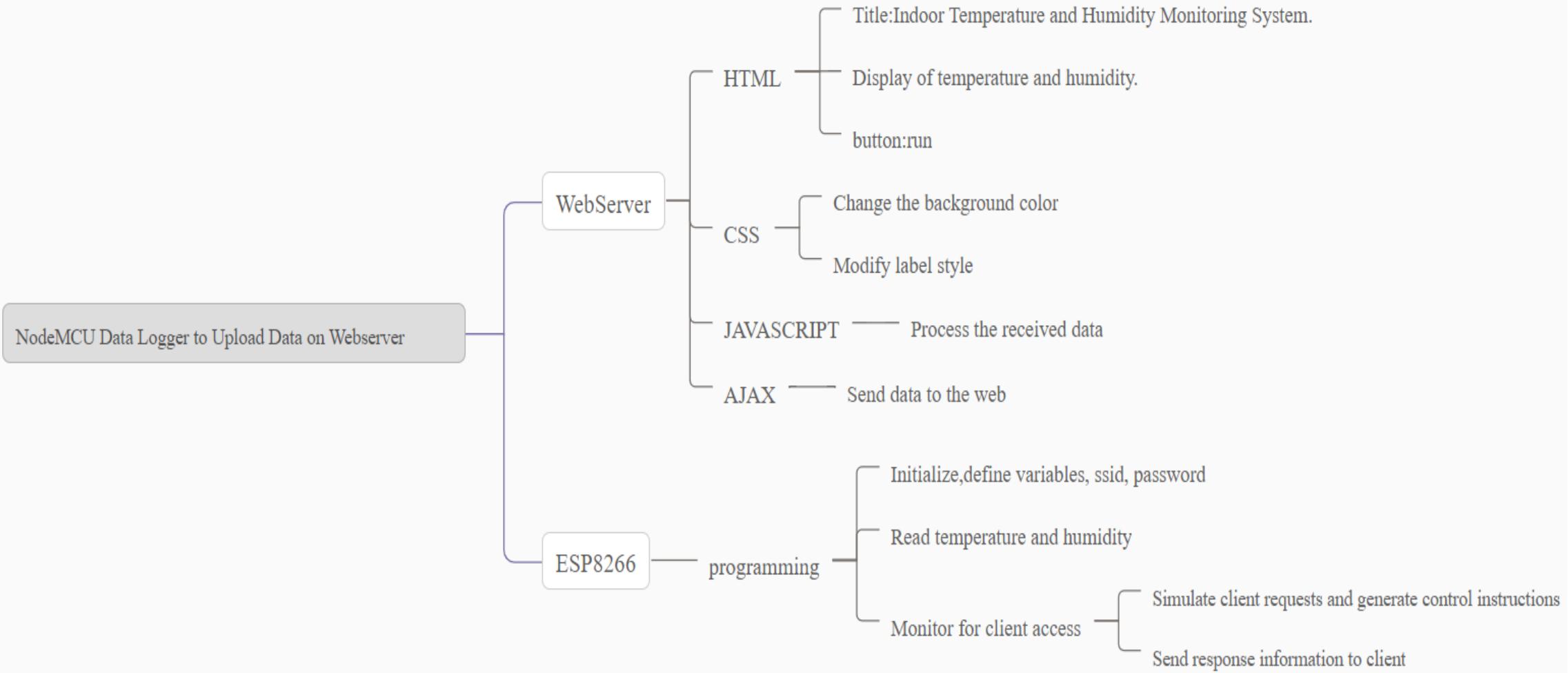


# Software diagram

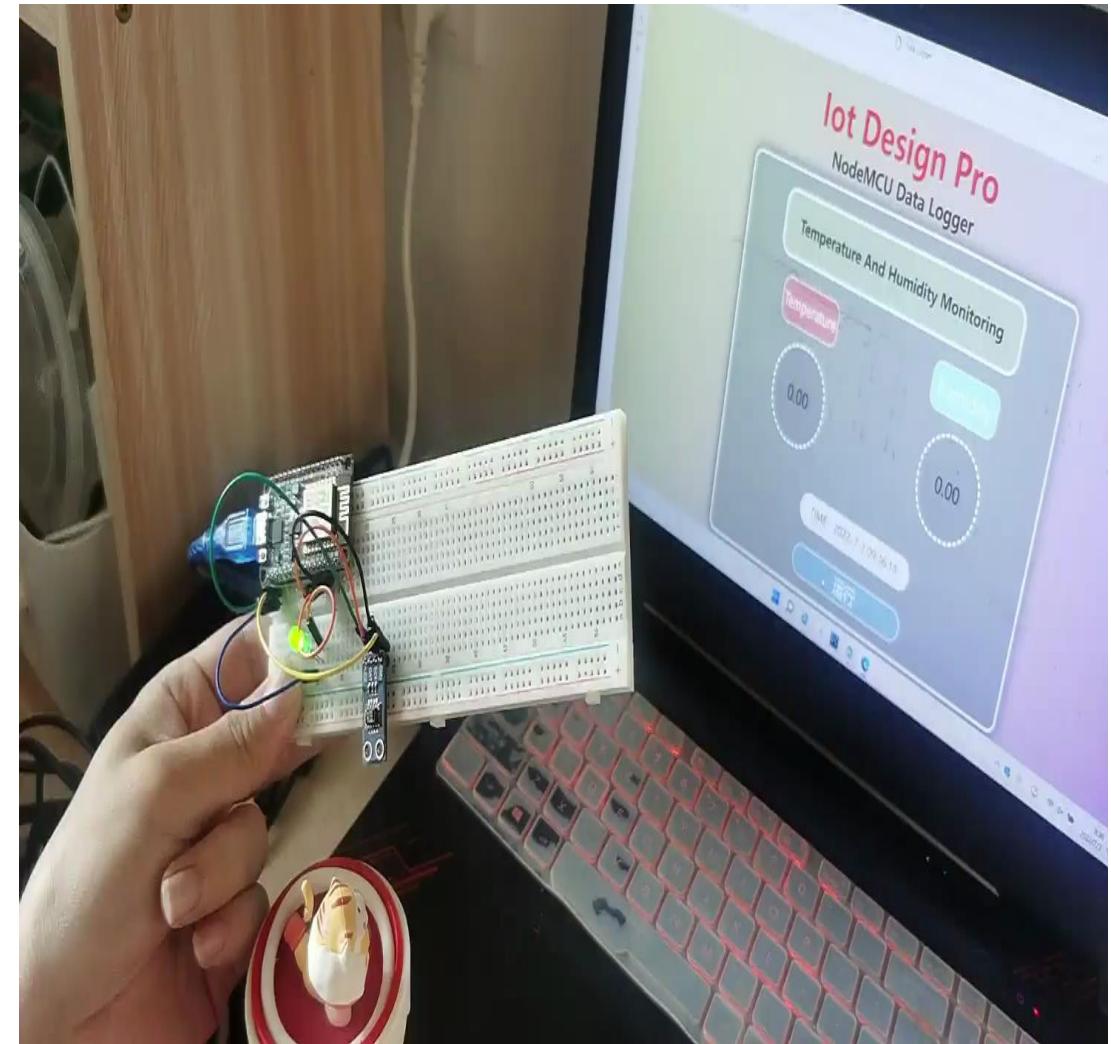
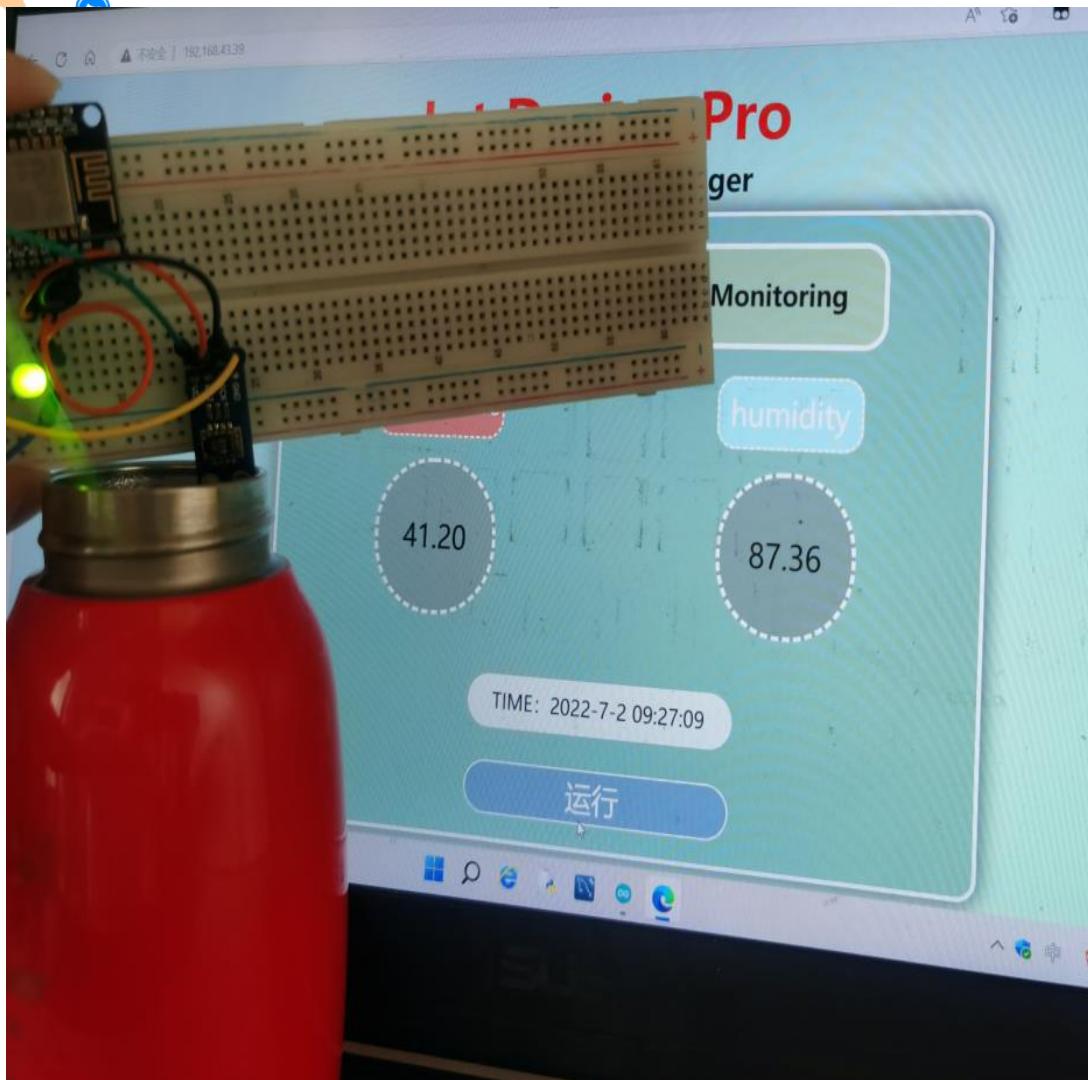




# mind Mapping



# Web Clip





# Project3:

## Code Section



# The IDE's Code and the Web's Code

```
#include <ESP8266WiFi.h>
#include <WiFiClient.h>
#include <ESP8266WebServer.h>
#include <SHT1x.h>
//SSID and Password of your WiFi router
const char* ssid = "新晋小色批";
const char* password = "103168Wan$#*.";
#define LED 0
#define dataPin 2
#define clockPin 4
WiFiServer server(80);
SHT1x sht1x(dataPin, clockPin);
float temp_c;
float humidity;
```

//through the WiFi connect the ESP8266

//choose the pin D4 and D2 to the receive  
the temprature and humidity





```
ESP8266WebServer webserver(80); //Server on port 80
const char MAIN_page[] PROGMEM = R"=====|(
<!doctype html>
<html>
<meta charset="UTF-8">
<head>
<meta>
<style>
    canvas {
        -moz-user-select: none;
        -webkit-user-select: none;
        -ms-user-select: none;
    }
    /* Data Table Styling */
    * {
        margin: 0;
        padding: 0;
    }
    body {
        width: 100%;
        background-color: rgb(232, 232, 168);
        margin: 0;
        padding: 0;
        font-family: "montserrat";
        background-image: linear-gradient(125deg, rgb(232, 232, 168), rgb(188, 152, 210), #c2e9fb, #C2FFD8);
        background-size: 400%;
        animation: bganimation 15s infinite;
    }
)=====|"
```



//These the Web Page's  
Code,including “table style”、  
“table color”、 ”background-  
size” and so on



# The Web Page's Code

```
.box {  
    width: 800px;  
    height: 580px;  
    background-color: rgba(102, 134, 129, 0.4);  
    border-radius: 20px;  
    margin-left: 365px;  
    position: relative;  
    border: 4px solid #fff;  
    box-shadow: 0px 0px 20px 3px #747474;  
}  
  
@keyframes bganimation {  
    0% {  
        background-position: 0% 50%;  
    }  
    50% {  
        background-position: 100% 50%;  
    }  
    100% {  
        background-position: 0% 50%;  
    }  
}  
  
.box .header {  
    width: 600px;  
    margin: 0px auto;  
    padding: 25px;  
}  
  
.header h1 {  
    text-align: center;  
    border-radius: 25px;  
    background-color: rgb(215, 226, 179, .5);  
    line-height: 85px;  
    border: 5px solid #fff;  
    font-size: 26px;  
}  
  
.center ul {  
    display: flex;  
    justify-content: space-around;  
    list-style: none;  
}
```

```
.center ul li {  
    width: 140px;  
    height: 140px;  
    text-align: center;  
    line-height: 140px;  
    border-radius: 70px;  
    font-size: 30px;  
    border: 3px dashed #fff;  
    background-color: rgb(151, 151, 151, .5);  
}  
  
.center .title li {  
    background-color: rgba(30, 127, 111, 0.4);  
    color: #fff;  
    border-radius: 20px;  
    width: 150px;  
    height: 60px;  
    line-height: 60px;  
    margin-bottom: 20px;  
}  
  
.center .title #w {  
    background-color: #ea9090;  
    font-size: 24px;  
}  
  
.center .title #s {  
    background-color: #aff1f6;  
}  
  
.center #wd {  
    border: 4px dashed #fff;  
}  
  
.center #sd {  
    border: 4px dashed #fff;  
}  
  
.times {  
    width: 300px;  
    height: 50px;  
    text-align: center;  
    line-height: 50px;  
    border: 2px rgb(0, 0, 0);  
    border-radius: 50px;  
}
```

```
    font-size: 20px;  
    padding: 0 auto;  
    margin: 0px auto;  
    margin-top: 50px;  
    background-color: rgb(255, 255, 255, .8);  
}  
  
.foot {  
    font-size: 20px;  
    width: 300px;  
    height: 70px;  
    margin: 80px auto;  
    text-align: center;  
    line-height: 70px;  
    padding: 15px;  
}  
  
.but {  
    width: 150px;  
    height: 50px;  
    font-size: 30px;  
    text-align: center;  
    line-height: 50px;  
    border-radius: 50px;  
    padding: 0 auto;  
    margin: 0px auto;  
    margin-top: 30px;  
    margin-left: 249px;  
    background-color: #fff;  
    transition: all .3s;  
}  
  
.but:hover {  
    width: 300px;  
    background-color: rgb(139, 182, 204);  
    border: 2px solid #fff;  
    color: #fff;  
}  
  
.but:active {  
    background-color: rgb(86, 85, 85);  
    color: #FFF;  
}  
    </style>  
</head>
```

//These Code also about the Web Page,including the “box”、“box.header”、“center.title”、“button’s style”、“color”、“height”、“width”、“background-color” and so on

# The Web Page's Code



```
<body>
<title>Data Logger</title>
<h1 style="text-align:center; color:red;font-size: 60px;">Iot Design Pro</h1>
<h3 style="text-align:center;font-size: 30px;margin-bottom: 10px;">NodeMCU Data Logger</h3>
<div>
  <div class="box">
    <div class="header">
      <h1>Temperature And Humidity Monitoring</h1>
    </div>
    <div class="center">
      <ul class="title">
        <li id="w">Temperature</li>
        <li id="s">humidity</li>
      </ul>
      <ul>
        <li id="wd">TEMP</li>
        <li id="sd">HUM</li>
      </ul>
    </div>
  </div>
</div>
```

## Iot Design Pro NodeMCU Data Logger

### Temperature And Humidity Monitoring

Temperature

TEMP

humidity

HUM

TIME: 2022-7-1 16:20:45

运行



江西理工大学信息工程学院

JIANGXI UNIVERSITY OF SCIENCE AND TECHNOLOGY SCHOOL OF INFORMATION ENGINEERING

<button onclick="getData()" class="but">运行</button>



# Comment: The data

```
var Tvalues = [];
var Hvalues = [];
var timeStamp = [];
unction getData() {
    var xhttp = new XMLHttpRequest();
    xhttp.onreadystatechange = function () {
        if (this.readyState == 4 && this.status == 200) {
            //Push the data in array
            var time = new Date().toLocaleTimeString();
            var txt = this.responseText;
            var obj = JSON.parse(txt);
            Tvalues.push(obj.Temperature);
            Hvalues.push(obj.Humidity);
            timeStamp.push(time);
        }
    }
    xhttp.open("GET", "readData", true); //Handle readData
    xhttp.send();
}
</script>
```

//Line 1 to 14

The part Code functions is to “Push the data in array” ,the data including “temperature”、 “humidity”、 “time at now”

//Line 15 to 24

The part Code functions is to “Update Data Web Page’s Table,through the “readData” to receive the new data on ESP8266 and send the data to web





# Comment: The data

```
const times = document.querySelector('.times');
function getDate() {
    const date = new Date()
    let h = date.getHours()
    let m = date.getMinutes()
    let s = date.getSeconds()
    h = h < 10 ? '0' + h : h
    m = m < 10 ? '0' + m : m
    s = s < 10 ? '0' + s : s
    times.innerHTML = `TIME:
${date.getFullYear()}-${date.getMonth() + 1}-
${date.getDate()} ${h}:${m}:${s}`
}
getDate()
setInterval(getDate, 1000)
</script>
</body>
</html>
)=====";
```



//The part Code function is to  
by retrieving the current time on  
the computer, the current time is  
transmitted to the web page  
through the server



At this point, the web page's  
code ends



# Comment: The data

```
void handleRoot() {  
    String s = MAIN_page; //Read HTML contents  
    webserver.send(200, "text/html", s); //Send web page  
}  
  
void readData() {  
    String data = "{\"Temperature\":\""+ String(temp_c) + "\",  
    \"Humidity\":\""+ String(humidity) + "\"}";  
    digitalWrite(LED,!digitalRead(LED)); //Toggle LED on  
    data request ajax  
    webserver.send(200, "text/plain", data);  
    //Send ADC value, temperature and humidity JSON to  
    client ajax request  
    delay(2000);  
    temp_c = sht1x.readTemperatureC();  
    humidity = sht1x.readHumidity();  
    Serial.println(temp_c, 1);  
    Serial.println(humidity, 1);  
}
```

//Line 1 to 4

The part code's functions is to save the code we wrote above for the html in an array and upload it to the web page

//Line 5 to end

The part code's functions is to through the “sht1x” library to receive the “tempature’s value” and “ the humilidty’s value”,send JSON to client ajax request



# Comment:The Wifi and IP

```
void setup ()  
{  
    Serial.begin(115200);  
    Serial.println();  
    pinMode(dataPin, INPUT);  
    pinMode(clockPin, INPUT);  
    WiFi.begin(ssid, password);  
    Serial.println("");  
    pinMode(LED,OUTPUT);  
    while (WiFi.status() != WL_CONNECTED) {  
        delay(500);  
        Serial.print(".");  
    }  
    Serial.println("");  
    Serial.print("Connected to ");  
    Serial.println(ssid);  
    Serial.print("IP address: ");  
    Serial.println(WiFi.localIP());  
    webserver.on("/", handleRoot);  
    webserver.on("/readData", readData);  
    webserver.begin();  
    Serial.println("HTTP server started");  
}  
void loop(void){  
    webserver.handleClient();  
}
```

//Line 1 to 7

Connect to the WiFi router

//Wait for connection

//Line 10 to 13

If connection successful show IP address in serial monitor

//Line 14 to 18

IP address assigned to your ESP

//Line 19

Which routine to handle at root location.This is display page

//Line 20

This page is called by Java Script AJAX

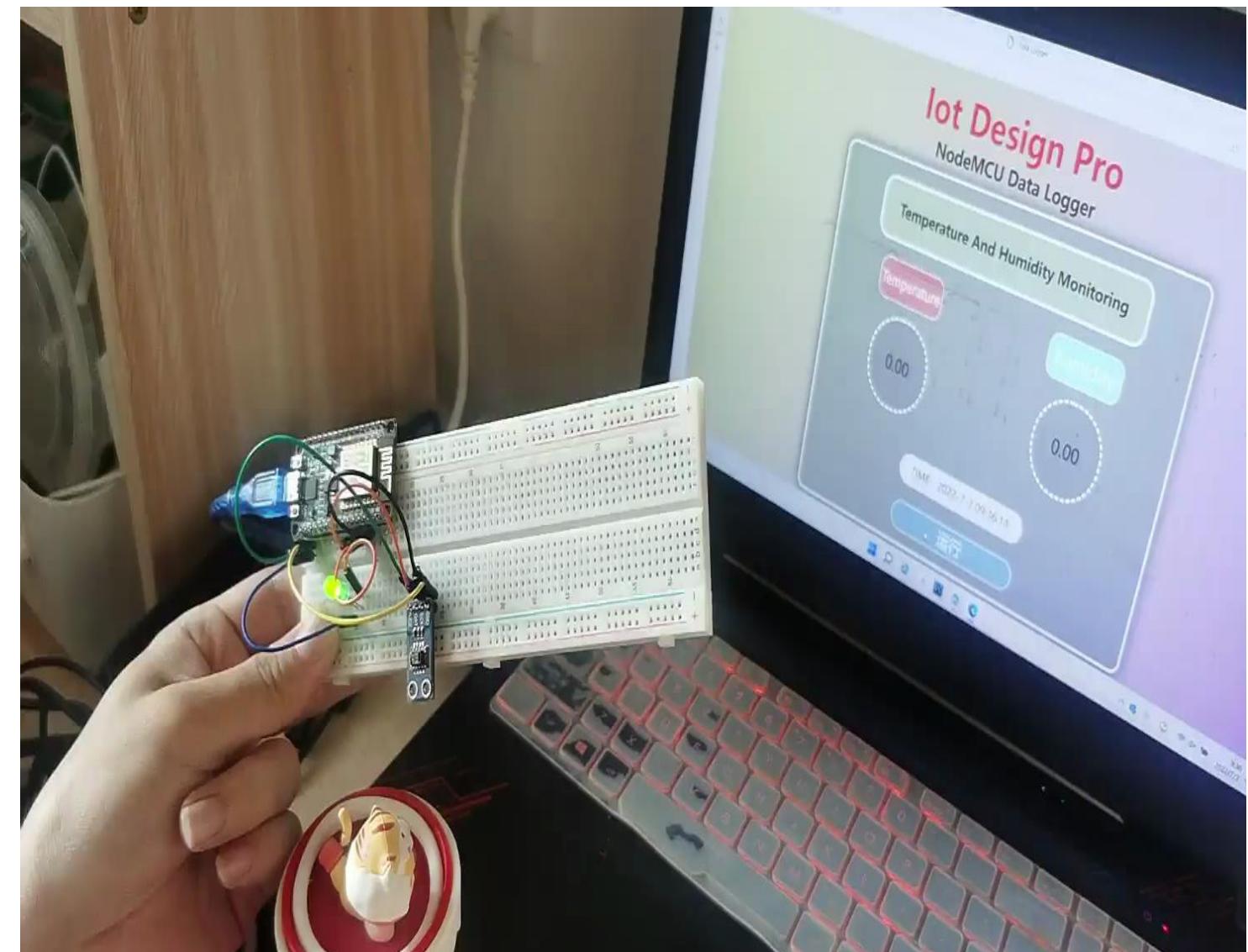
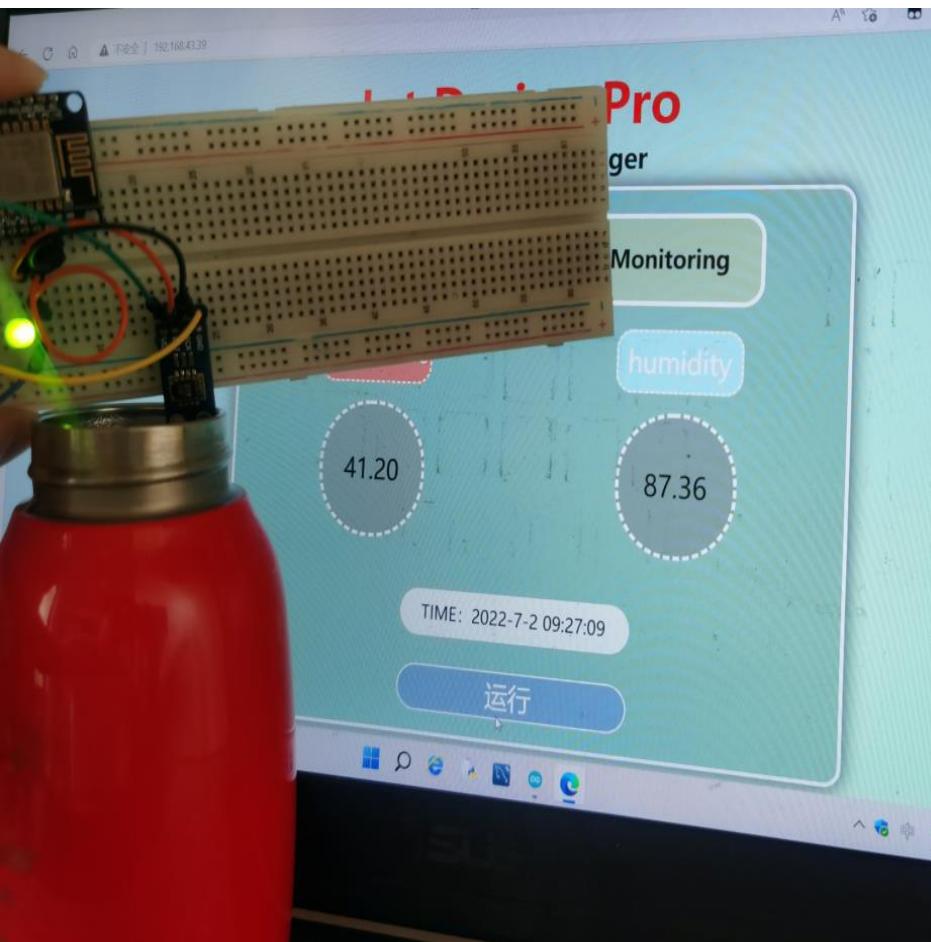
//Line 21 to 22

Server start

//end:Cilent request



# Web Clip





# IOT Cloud Step 1:

---

- set three variables
- 1)click on “CREAT THING” in the “Things”
- 2)click on “ADD VARIABLES” to add three variables
  - the first:name:temperature-->the type:float-->choose the “Read&Write” and “On change”
  - the second:name:humility-->the type:float-->choose the “Read&Write” and “On change”
  - the third:name:switch1-->the type:switch-->choose the “Read&Write” and “On change”
- 3)click on “select device”-->the name:Group2-->choose “set up 3rd parts”-->choose “NodeMCU 1.0”-->click on “continue”-->remember the “Device ID” and “Secret Key”
- 4)click on “Network”-->input the ”WIFI name”、 ”Password”、 ”Secretkey”-->save

# IOT Cloud Step 1 Clip:

The screenshot shows the Arduino IoT Cloud interface. At the top, there's a navigation bar with icons for back, forward, home, and search, followed by the URL <https://create.arduino.cc/iot/things>. To the right of the URL are various browser controls. Below the navigation bar, there's a sidebar on the left with icons for IOT CLOUD, Dashboards, Devices, Integrations, Templates, and an Upgrade Plan button. The main content area has tabs for Things, Dashboards, Devices, Integrations, and Templates, with 'Things' being the active tab. In the center, there's a large illustration of a person holding a smartphone that displays a circuit board and a Wi-Fi signal. Below the illustration, the text 'Create your first Thing' is displayed. A detailed description follows: 'A Thing is a connected device that can communicate with the cloud. You can make your Things interact with other Things or anything else in the physical world.' At the bottom, there's a prominent blue 'CREATE THING' button. The footer of the page shows the URL <https://create.arduino.cc/iot/things/new>.





# IOT Cloud Step 2:

---

click on Dashboards-->click on “BUILD DASHBOARD”-->click on “edit” and “ADD” to add seven Widgets

- 1)a push button:the name:switch1-->the link var:connect the value “switch1”
- 2)the first value:the name:temperature-->the link var:connect the value “temperature”
- 3)the second value:the name:humidity-->the link var:connect the value “humidity”
- 4)a gauge:the name:temperature-->the link var:connect the value “temperature”
- 5)a Percentage:the name:humidity-->the link var:connect the value “humidity”
- 6)the first chart:the name:temperature chart-->the link var:connect the value “temperature”
- 7)the second chart:the name:humidity chart-->the link var:connect the value “humidity”



# IOT Cloud Step 2 Clip:

Arduino IoT Cloud

https://create.arduino.cc/iot/dashboards

Things Dashboards Devices Integrations Templates UPGRADE PLAN

**IOT CLOUD**

Monitor your Things

Build a Dashboard to easily monitor the status of your Things and control them.

BUILD DASHBOARD

https://create.arduino.cc/iot/dashboards/new



# IOT Cloud Step 3 and Clip:

come back the “Things”-->click on the “Group2”

1)check the three variables

2)click on “ sketch”

select the “open full editor” and install drivers

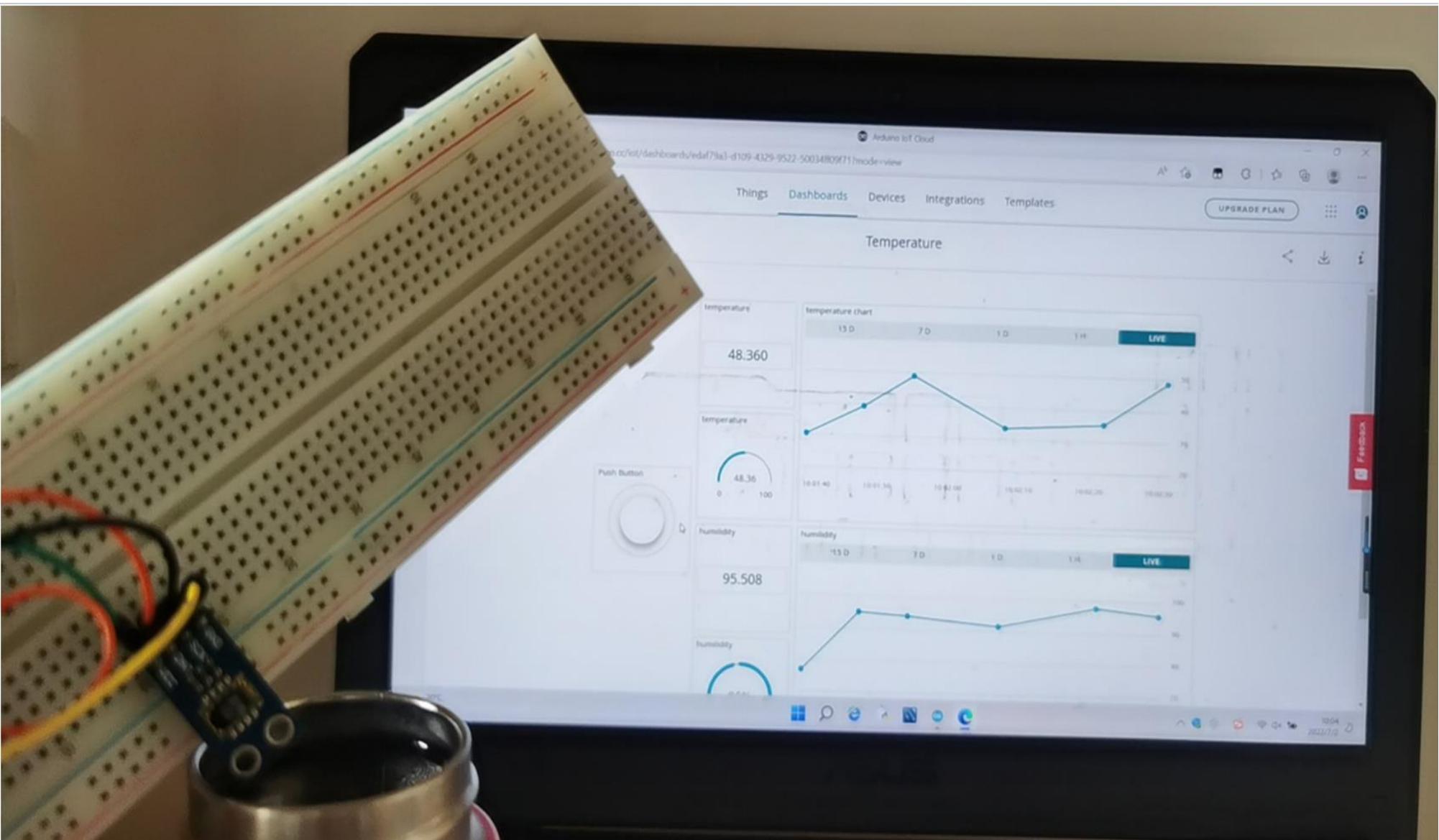
3)choose the “NodeMCU 1.0” and text the Code

4)If Success,the set is finish

Name	Last modified	Owned by
Untitled	05 Jul 2022 16:42:56	honesthen314



# IOT Cloud Step 3 result:





# IOT Cloud Code:

- The Code comment

```
#include "thingProperties.h"
#include <SHT1x-ESP.h>
#define LED 0
#define dataPin 2
#define clockPin 4
SHT1x sht1x(dataPin, clockPin);
void setup() {
    pinMode(dataPin, INPUT);
    pinMode(clockPin, INPUT);
    pinMode(LED, OUTPUT);
    Serial.begin(9600);
    delay(1500);

    initProperties();
    ArduinoCloud.begin(ArduinoIoTPreferredConnection);
/*

```

The following function allows you to obtain more information related to the state of network and IoT Cloud connection and errors the higher number the more granular information you'll get.

The default is 0 (only errors).

Maximum is 4

\*/

```
setDebugMessageLevel(2);
ArduinoCloud.printDebugInfo();
}
```



//on board LED



//Initialize serial and wait for port to open



//This delay gives the chance to wait for a Serial Monitor without blocking if none is found



//define in thingProperties.h  
//Connect to Arduino IOT Cloud





# IOT Cloud Code:

- The Code comment

```
void loop() {  
    ArduinoCloud.update();  
}  
void onSwtichChange() {  
    if (swtich) {  
        temperature = sh11x.readTemperatureC();  
        humidity = sh11x.readHumidity();  
        digitalWrite(LED,HIGH);  
    }  
    else{  
        digitalWrite(LED,LOW);  
    }  
}  
/*  
Since Temperature is READ_WRITE variable, onTemperatureChange() is  
executed every time a new value is received from IoT Cloud.  
*/  
void onTemperatureChange() {  
}  
/*  
Since Humidity is READ_WRITE variable, onHumidityChange() is  
executed every time a new value is received from IoT Cloud.  
*/  
void onHumidityChange() {  
}
```



//our code here



//through the switch to control to read the  
temperature's data and humilidty's data

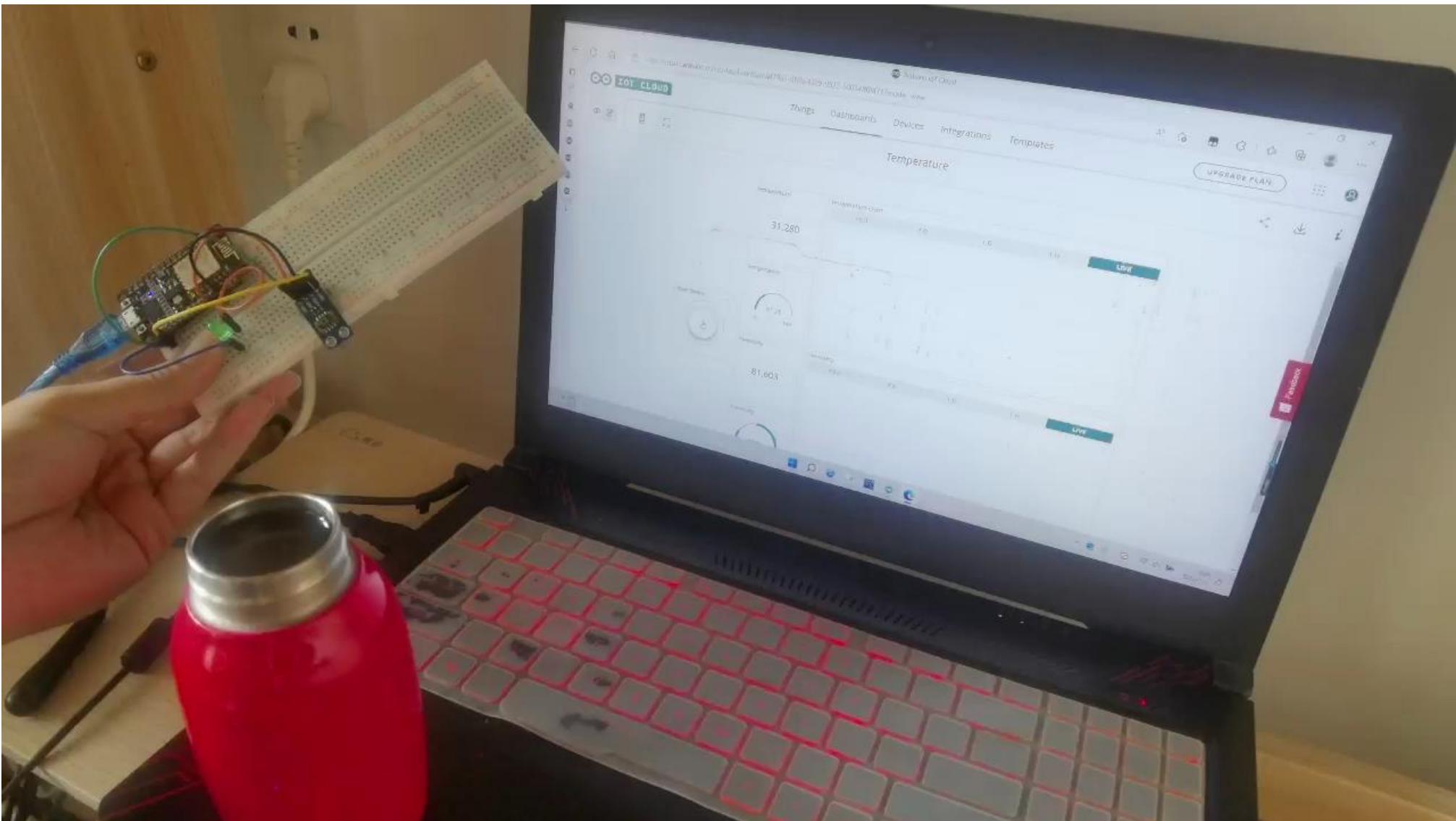


//to control the LED(HIGH or LOW)





# IOT Cloud Clip





# Project4:

IoT based car parking System





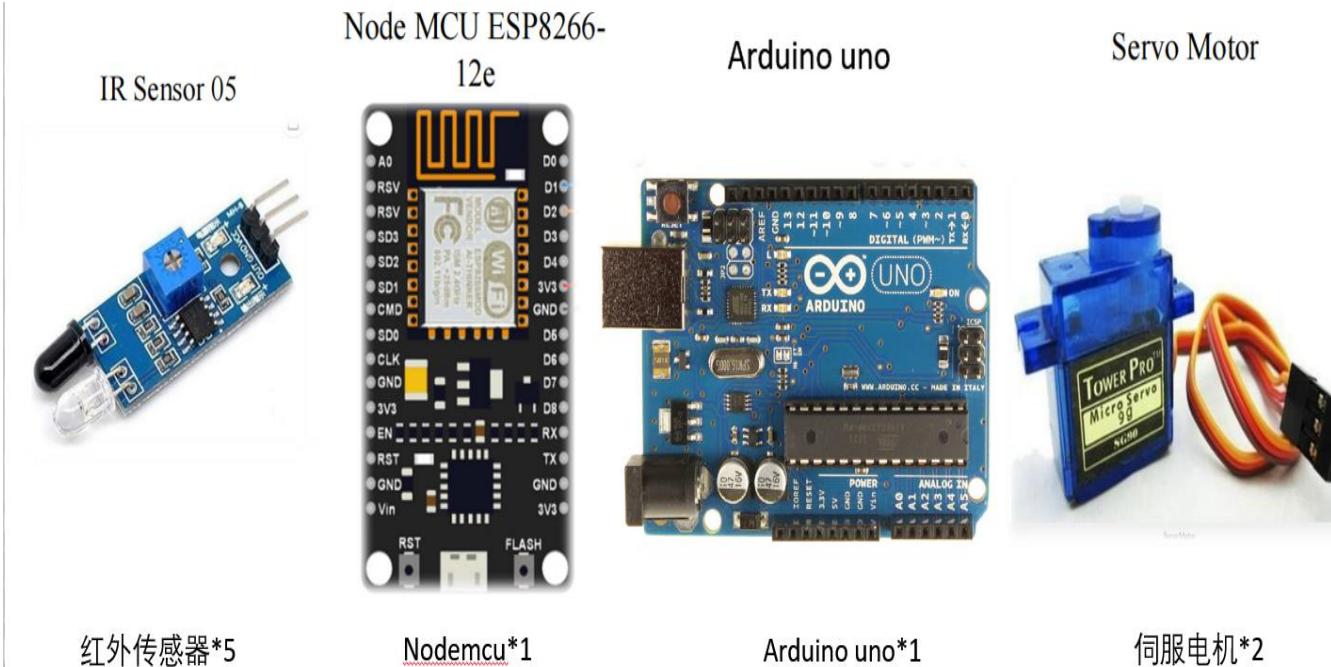
# Why we need Smart parking system

- Now days finding parking in busy areas is very hard and there is no system to get the details of parking availability online. Imagine if you can get the parking slot availability information on your phone and you don't have roaming around to check the availability.
- This problem can be solved by the **IoT based smart parking system**. Using the IoT based parking system you can easily access the parking slot availability over the internet. This system can completely automate the car parking system. From your entry to the payment and exit all can be done automatically





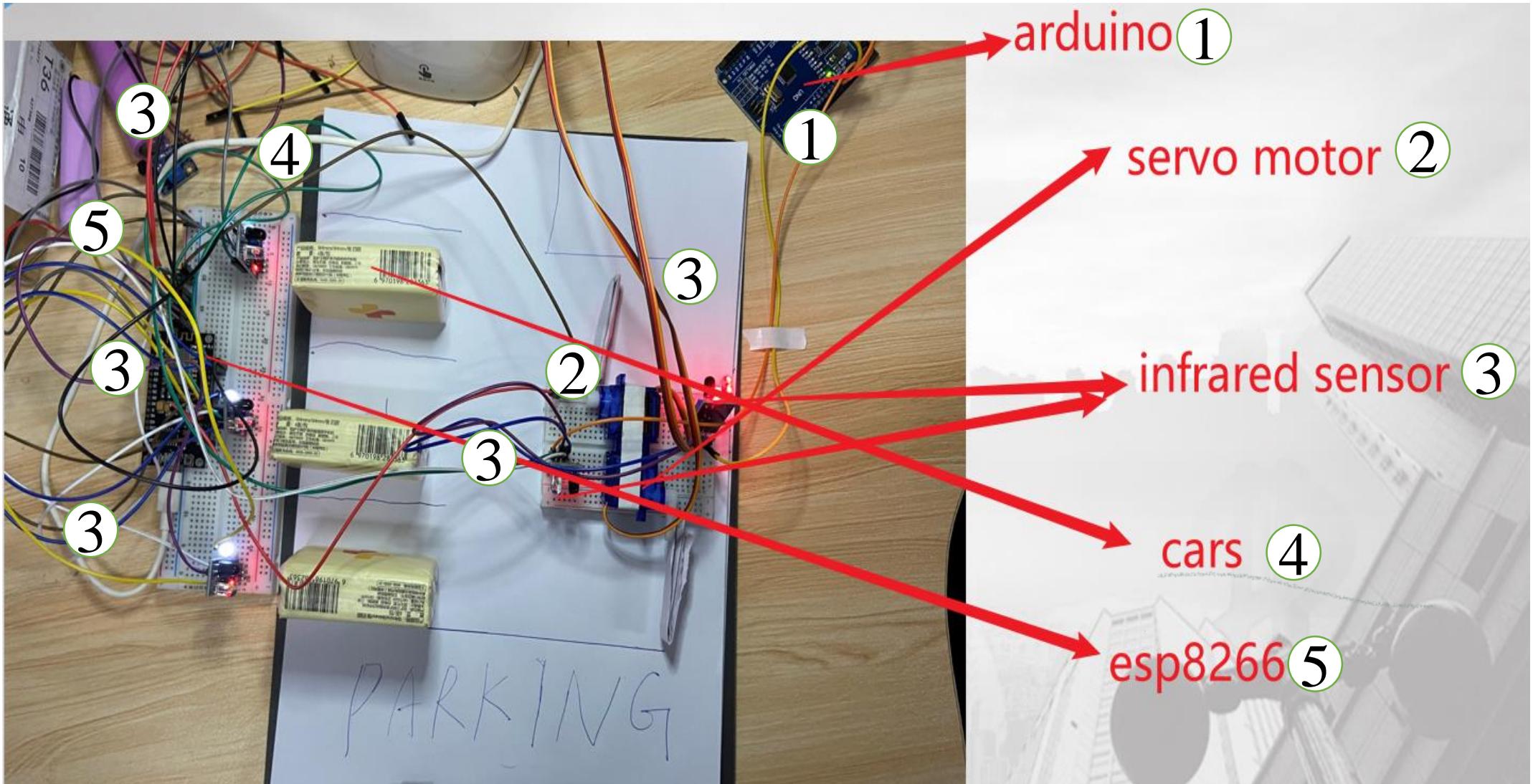
# Project 4:Component



- **IR Sesor:** Five infrared sensors are used to detect whether vehicles are entering the parking lot and determine whether there is a vacant space.
- **Nodemcu ESP8266:** Record the parking space sensor and generate web page code.
- **Arduino:** Record the code that controls the servo motor.
- **Servo Motor:** Control the parking lot railings through code simulation.



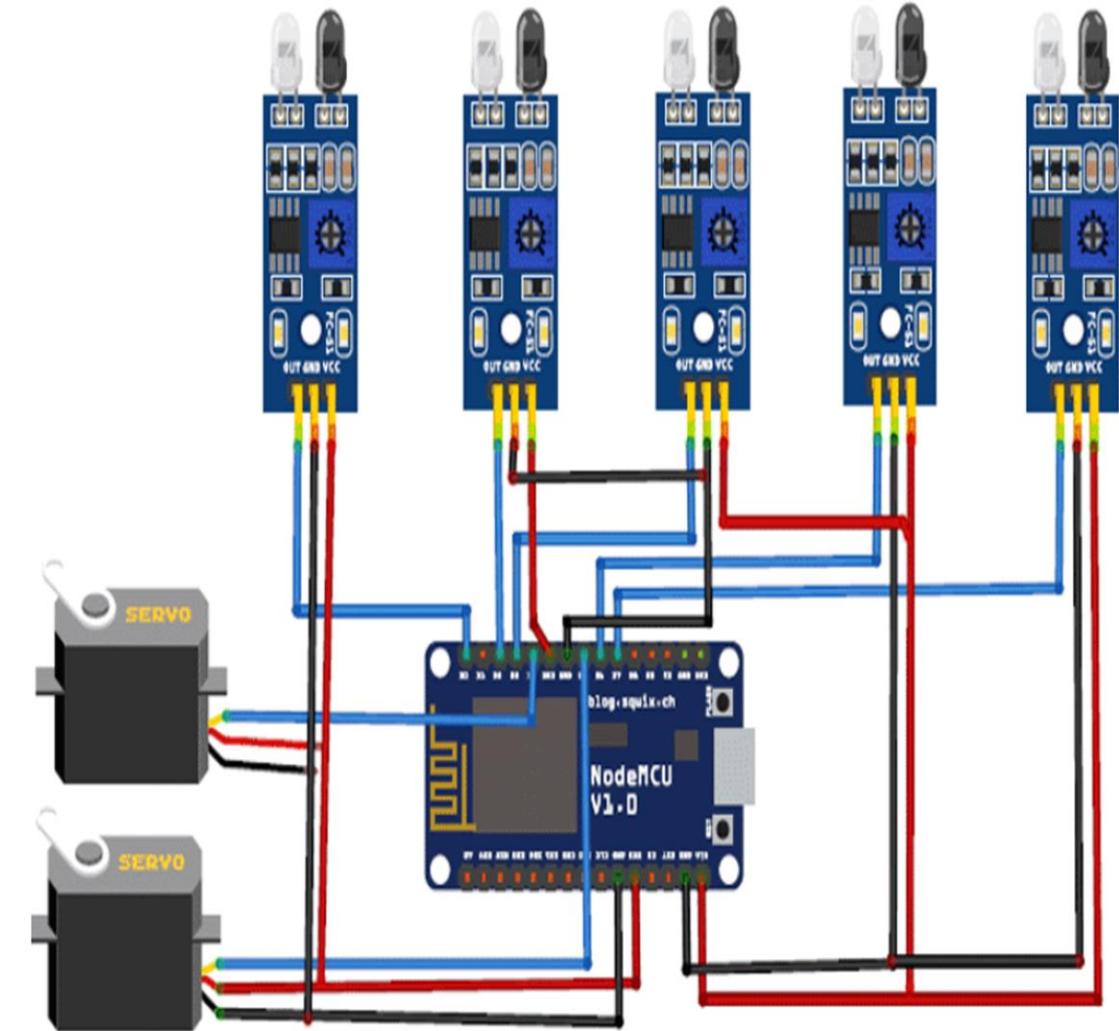
# Project 4:Component





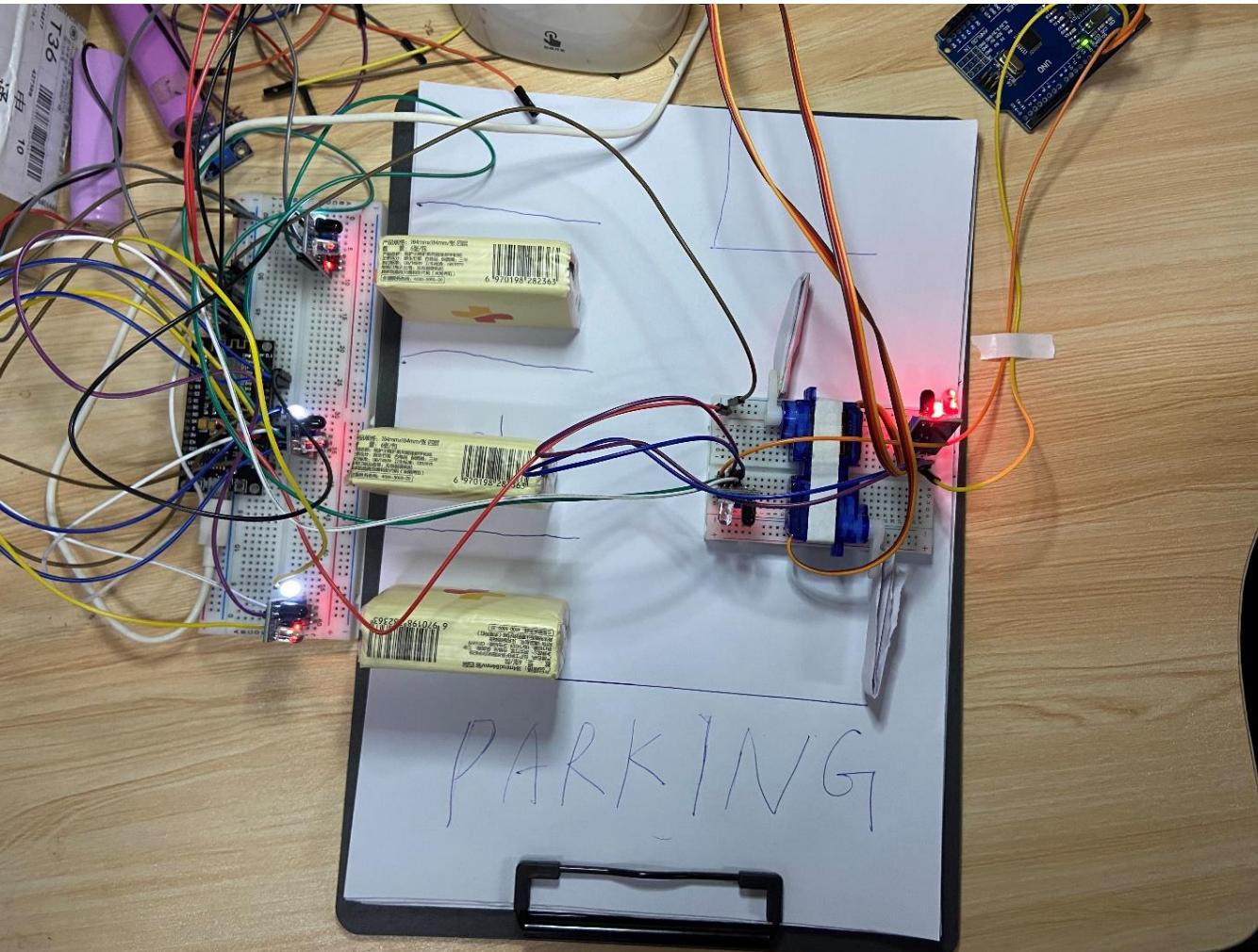
# Project 4:Component

- In this Smart Parking System using IOT, we are using five IR Sensors and two servo motors. IR sensors and Servo motors are connected to the NodeMCU.
  - NodeMCU controls the complete process and sends the parking availability and parking time information to Adafruit IO so that it can be monitored from anywhere in the world using this platform.
  - Two IR sensors are used at entry and exit gate so that it can detect the cars at entry and exit gate and automatically open and close the gate.





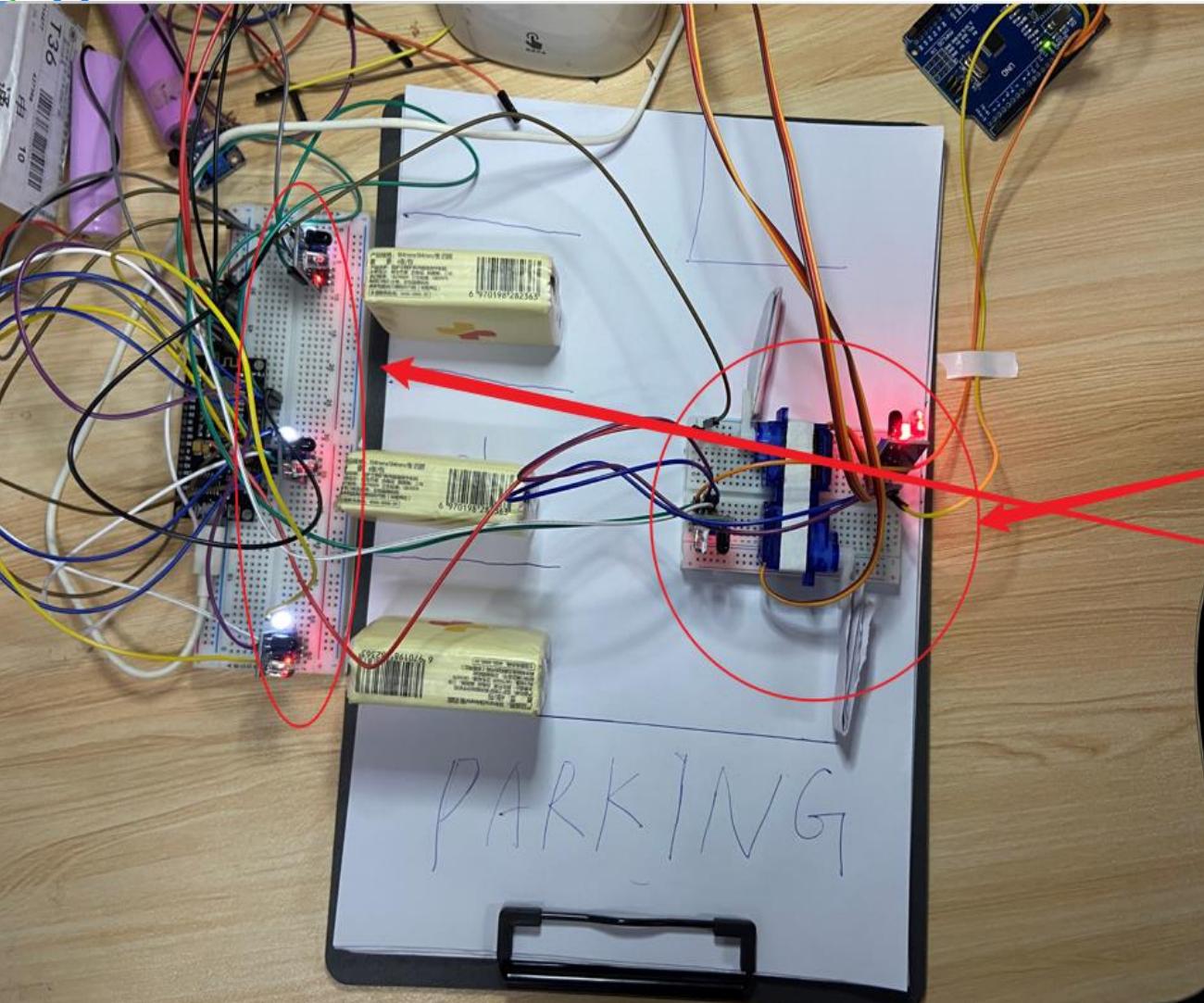
# Project 4:Component



Arduino uno control  
the double servo  
motor ang the two  
Infrared sensor  
The Nodemcu  
control the three  
Infrared sensor



# Project 4:Component



Arduino uno control the double servo motor ang the two Infrared sensor  
The NodeMCU control the three Infrared sensor

# Project 4: Demo on web



Document x +

http://192.168.43.166 00:00:00 结束

题目集列表 个人空间 CSDN - 专业开发者社 哔哩哔哩 ( °\_° ) 天使动漫官网(tsdm) MDN Web Docs U校园 上网登录页 Arduino Cloud 其它收藏

## Project 2:

PROJECT NAME: P8266

IoT Ba

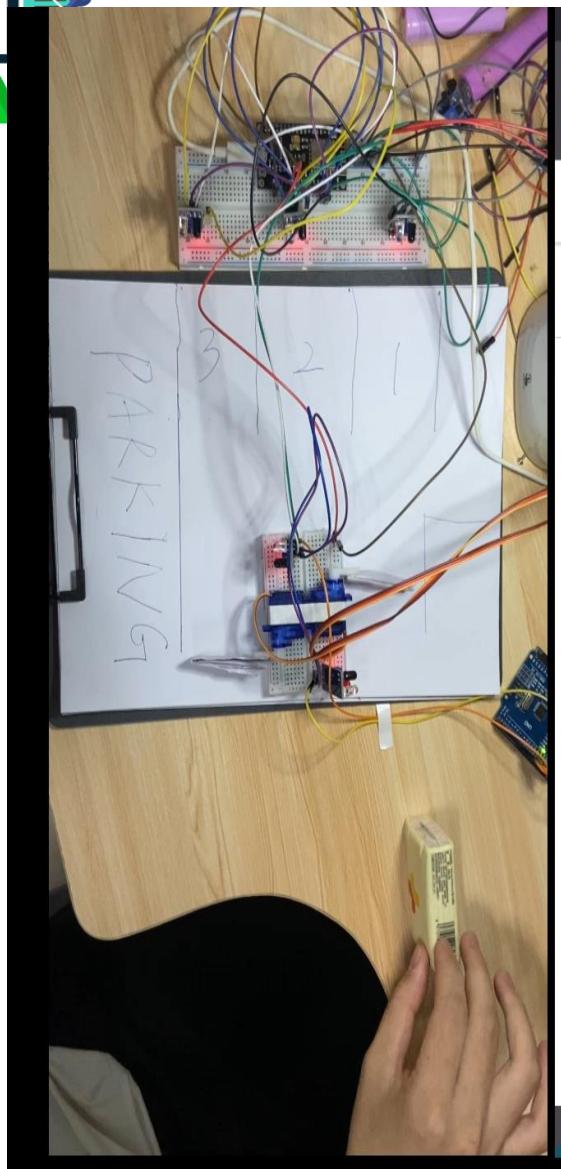
警示灯

PARKING

停车位1 停车位2 停车位3

JANGXI UNIVERSITY OF SCIENCE TECHNOLOGY

# Project 4: Demo Arduino IOT Cloud



Arduino Cloud    Arduino IoT Cloud

题目集列表 个人空间 CSDN - 专业开发者社 哔哩哔哩 ( °-' ) 天使动漫官网(tsdm) MDN Web Docs U校园 上网登录页 Arduino Cloud

IOT CLOUD    Things Dashboards Devices Integrations Templates UPGRADE PLAN

project2

Parking3    Parking2    Parking1

amount ✓

14 /

This screenshot shows the Arduino IoT Cloud interface. The top navigation bar includes links for Arduino Cloud, Arduino IoT Cloud, and several external sites like CSDN and Bilibili. The main menu has tabs for Things, Dashboards (which is selected), Devices, Integrations, and Templates, along with an Upgrade Plan button. The current project is named "project2". Below the tabs, there are three rectangular cards labeled "Parking3", "Parking2", and "Parking1", each containing a red oval icon. At the bottom center is a green button labeled "amount" with a checkmark inside. A blue arrow icon is positioned to the right of the button. The bottom of the screen features a dark footer bar with several small icons.



# Project4:

## Code Section



# Arduino IOT

The screenshot shows the Arduino IoT Cloud interface. At the top, there's a navigation bar with tabs for Things, Dashboards, Devices, Integrations, and Templates. Below the navigation bar, the main area is titled "project2". It features a "Variables" section with four entries:

Name	Last Value	Last Update
Full	true	30 Jun 2022 20:18:37
Parking1	true	30 Jun 2022 20:18:37
Parking2	true	30 Jun 2022 20:12:03
Parking3	true	30 Jun 2022 20:12:09

Below the variables is an "Associated Device" section for "project2", which is a NodeMCU 1.0 (ESP-12E Module) connected online. It includes "Change" and "Detach" buttons. At the bottom, there's a "Network" section with Wi-Fi credentials.

At the very bottom of the page, there's a "Set webhook" link.

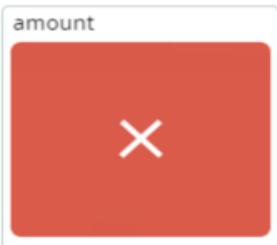
The first parking space has a car  
when Paking1 lights up red  
And so on  
Full lights up  
when all three parking spaces have cars



# Arduino IOT

Things Dashboards Devices Integrations Templates

project2



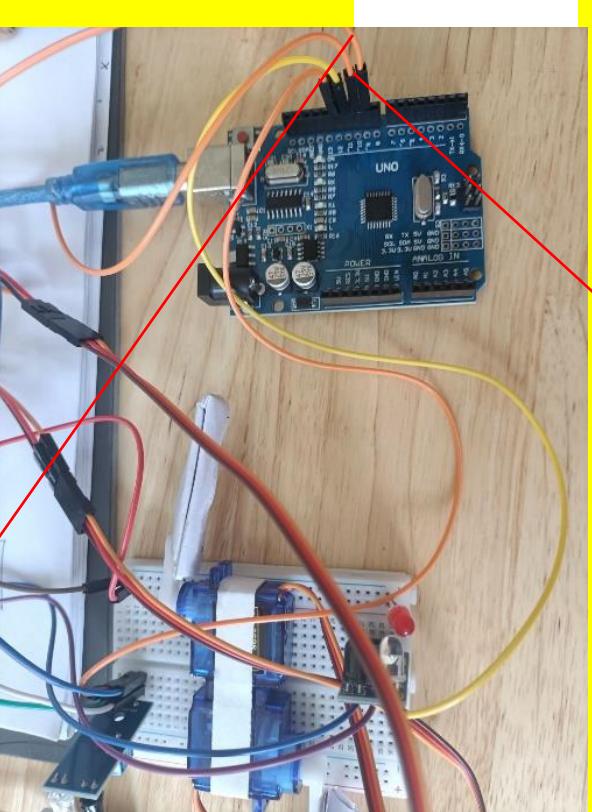
The first parking space has a car when Paking1 lights up red  
And so on  
Full lights up when all three parking spaces have cars



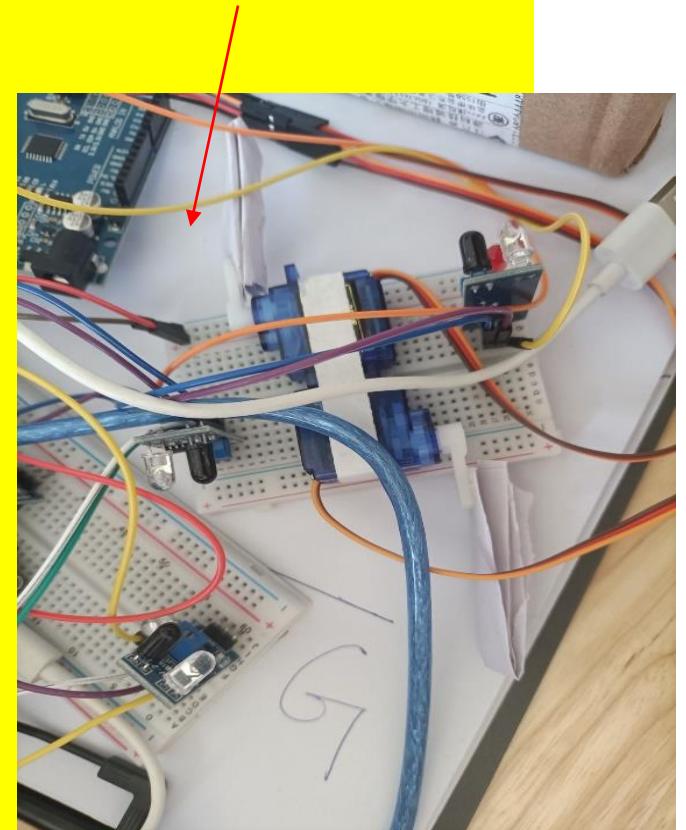
# Arduino code

```
#include<Servo.h>
Servo ms1;
Servo ms2;
int value1=0;
int value2=0;
void setup() {
    pinMode(11,INPUT);
    pinMode(12,INPUT);
}

void loop() {
    int value1=digitalRead(11);
    int value2=digitalRead(12);
    if(value1==LOW)
    {
        ms1.attach(9);//connect to pin
        ms1.write(80);
        //小于90往0度转,angel=80<90,the stick go to 0°
        delay(680);
    }
}
```



```
ms1.detach();//disconnect to pin 9
delay(3000);
ms1.attach(9);
ms1.write(100);
//大于90往180度转,angel=100>90,the stick go to 180°
delay(820);
ms1.detach();
}
if(value2==LOW)
{
    ms2.attach(10);
    ms2.write(80);
    delay(680);
    ms2.detach();
    delay(3000);
    ms2.attach(10);
    ms2.write(100);
    delay(800);
    ms2.detach();
}
delay(3000);
}
```





# Explain the esp8266 iot code

```
/* Sketch generated by the Arduino IoT Cloud Thing "Untitled 2"
```

```
Arduino IoT Cloud Variables description
```

```
The following variables are automatically generated and updated when changes are made to the Thing
```

```
CloudLight full;
```

```
CloudLight parking1;
```

```
CloudLight parking2;
```

```
CloudLight parking3;
```

Variables which are marked as READ/WRITE in the Cloud Thing will also have functions  
which are called when their values are changed from the Dashboard.

These functions are generated with the Thing and added at the end of this sketch.

```
*/
```

```
#include "thingProperties.h"
```

```
#define LED 5
```

```
#define LED1 4
```

```
#define LED2 13
```

```
#define LED3 15
```

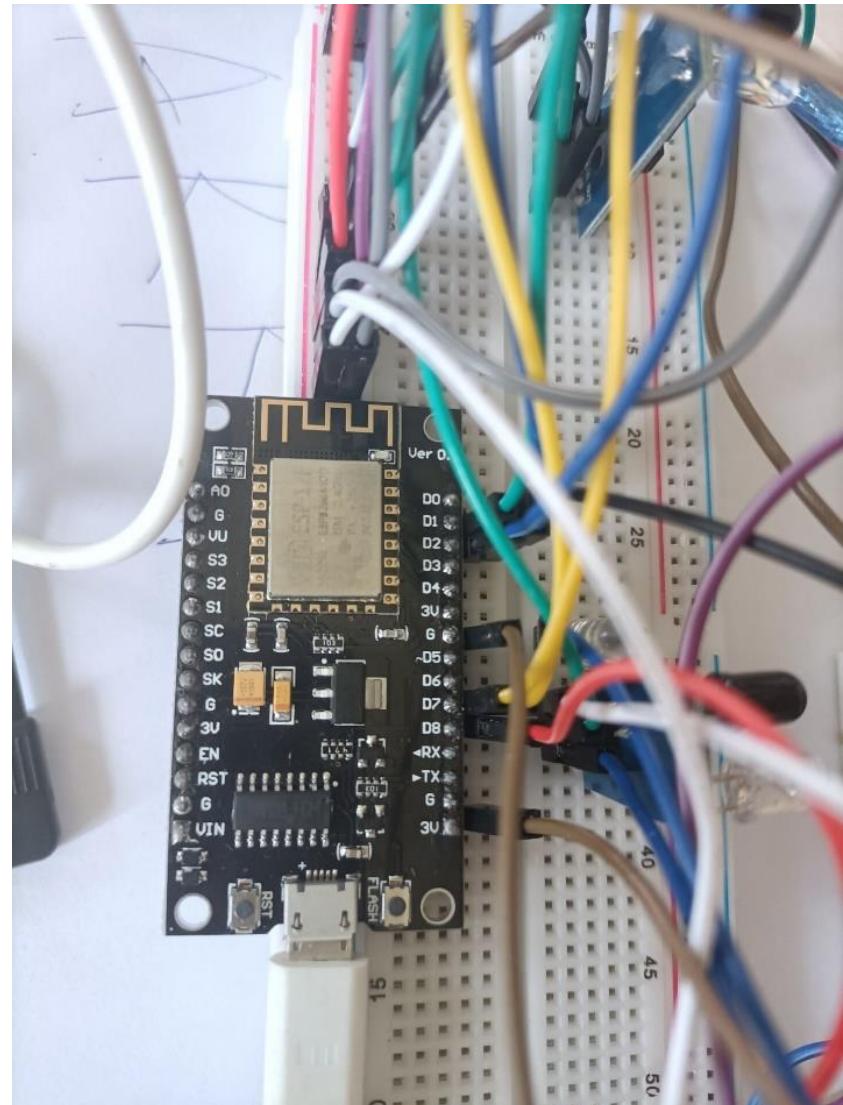
```
void setup() {
```

```
    // Initialize serial and wait for port to open:
```

```
    Serial.begin(9600);
```

```
    // This delay gives the chance to wait for a Serial Monitor without blocking if none is found
```

```
    delay(1500);
```





# Explain the esp8266 iot code

```
pinMode(LED,INPUT);
pinMode(LED1,INPUT);
pinMode(LED2,INPUT);
pinMode(LED3,OUTPUT);
// Defined in thingProperties.h
initProperties();

// Connect to Arduino IoT Cloud
ArduinoCloud.begin(ArduinoIoTPreferredConnection);
```

```
/*
The following function allows you to obtain more information
related to the state of network and IoT Cloud connection and errors
the higher number the more granular information you'll get.
```

The default is 0 (only errors).

Maximum is 4

```
*/
```

```
setDebugMessageLevel(2);
ArduinoCloud.printDebugInfo();
}
```

```
void loop() {
    ArduinoCloud.update();
    // Your code here
    if(digitalRead(LED)==1){
        parking1=LOW;
    }else
    {
        parking1=HIGH;
    }
    if(digitalRead(LED1)==1){
        parking2=LOW;
    }else
    {
        parking2=HIGH;
    }
    if(digitalRead(LED2)==1){
        parking3=LOW;
    }else
    {
        parking3=HIGH;
    }
}
```



# Explain the esp8266 iot code

```
int l1=digitalRead(LED);
int l2=digitalRead(LED1);
int l3=digitalRead(LED2);
if((l1||l2||l3)==0)
{
  digitalWrite(LED3,HIGH);
}
else
{
  digitalWrite(LED3,LOW);
}
if(digitalRead(LED3)==1){
  full=HIGH;
}else
{
  full=LOW;
}
/*
Since Parking1 is READ_WRITE variable, onParking1Change() is
executed every time a new value is received from IoT Cloud.
*/
void onParking1Change() {
  // Add your code here to act upon Parking1 change
}
```

```
if(digitalRead(LED)==1){
  parking1=HIGH;
}else
{
  parking1=LOW;
}
/*
Since Parking2 is READ_WRITE variable, onParking2Change() is
executed every time a new value is received from IoT Cloud.
*/
void onParking2Change() {
  // Add your code here to act upon Parking2 change
}

/*
Since Parking3 is READ_WRITE variable, onParking3Change() is
executed every time a new value is received from IoT Cloud.
*/
void onParking3Change() {
  // Add your code here to act upon Parking3 change
}

/*
Since Full is READ_WRITE variable, onFullChange() is
executed every time a new value is received from IoT Cloud.
*/
void onFullChange() {
  // Add your code here to act upon Full change
}
```



# Web pag Demo





# Explain the Web code

```
#include <ESP8266WiFi.h>
const char* ssid = "钟";
const char* password = "244466666";
WiFiServer server(80);
void setup()
{
    Serial.begin(115200); //Default Baudrate
    pinMode(5,INPUT);
    pinMode(4,INPUT);
    pinMode(13,INPUT);
    pinMode(15,OUTPUT);
    Serial.print("Connecting to the Newtork");
    WiFi.begin(ssid, password);
    while (WiFi.status() != WL_CONNECTED)
    {
        delay(500);
        Serial.print(".");
    }
    Serial.println("WiFi connected");
    server.begin();
    Serial.println("Server started");
    Serial.print("IP Address of network: ");
    Serial.println(WiFi.localIP());
    Serial.print("Copy and paste the following URL: https://");
    Serial.print(WiFi.localIP());
    Serial.println("/");
}
```

```
void loop()
{
    int l1=digitalRead(5);
    int l2=digitalRead(4);
    int l3=digitalRead(13);
    if((l1||l2||l3)==LOW)
    {
        digitalWrite(15,HIGH);
    }
    else
    {
        digitalWrite(15,LOW);
    }
    int a=digitalRead(5);
    int b=digitalRead(4);
    int c=digitalRead(13);
    int d=digitalRead(15);
    WiFiClient client = server.available();
    if (!client)
    {
        return;
    }
    Serial.println("Waiting for new client");
    while(!client.available())
    {
        delay(1);
    }
    String request = client.readStringUntil('\r');
    Serial.println(request);
    client.flush();
```



# Explain the Web code

---

```
/*-----HTML Page Code-----*/
client.println("HTTP/1.1 200 OK"); //
client.println("Content-Type: text/html");
client.println("");
client.println("<!DOCTYPE html>");
client.println("<html lang=\"en\">");
client.println("<head><meta charset=\"UTF-8\">");
client.println("<meta http-equiv=\"refresh\" content=\"3\>");//刷新
client.println("<meta http-equiv=\"X-UA-Compatible\" content=\"IE=edge\>\"");
client.println("<meta name=\"viewport\" content=\"width=device-width, initial-scale=1.0\>\"");
client.println("<title>Document</title></head>");
client.println("<style>* {padding: 0px; margin: 0px;}");
client.println("a {text-decoration: none;}");
client.println("li {list-style: none;}");
```



# Explain the Web code

```
client.println("body {background: url(https://img2.baidu.com/it/u=1146935794,3666555888&fm=253&fmt=auto&app=120&f=JPEG?w=889&h=500) no-repeat;background-size: cover;}");  
client.println(".header {height: 200px;width: 100%;background:0%;}");  
client.println(".header h1 {height: 60px;width: 100%;text-align: center;font-size: 50px;color: aqua;}");  
client.println(".header div {width: 100%;height: 90px;}");  
client.println(".header div p:nth-child(1) {padding-left: 50%;height: 25px;padding-top: 15px;line-height: 25px;font-size: 25px;color: bisque;}");  
client.println(".header div p:nth-child(2) {height: 50px;text-align: center;line-height: 50px;font-size: 25px;color: antiquewhite;}");  
client.println(".bbox {width: 100%;height: 300px;position: relative;background: 0%;}");  
client.println(".bbox .border {width: 100%;height: 300px;position: relative;background: rgb(154, 173, 208, 0.7);}");  
client.println(".bbox .border ul {width: 500px;height: 150px;position: absolute;background: blue;top: 50%;margin-top: -75px;left: 50%;margin-left: -250px;}");  
client.println(".bbox .border ul li {height: 150px;float: left;margin-right: 100px;background: green;}");  
client.println(".bbox .border ul li .light {width: 100px;height: 100px;background-color: white;border-radius: 50%;}");  
client.println(".bbox .border ul li .part {width: 100%;height: 50px;background: yellow;font-size: 18px;text-align: center;line-height: 50px;}");  
client.println(".bbox .border ul li:nth-child(3) {margin-right: 0px;}");  
client.println(".bbox .border .ispart {width: 100px;height: 150px;border-radius: 20px 20px 0px 0px;margin-top: 50px;margin-left: 30px;background: blue;}");  
client.println(".bbox .border .ispart .ispartlight {width: 100px;height: 100px;border-radius: 50%;background: white;}");  
client.println(".bbox .border .ispart .message {width: 100px;height: 50px;background: yellow;text-align: center;line-height: 50px;font-size: 20px;}");  
client.println("<body>");  
client.println("<div class='header'><h1>Project 2:</h1><div><p>PROJECT NAME:</p><p>IoT Based Smart Parking System using NodeMCU ESP8266</p></div></div>");  
client.println("<div class='bbox'><div class='seabox'><p class='search'><input type='text'><a href='#'><span>搜索</span></a></p></div>");  
client.println("<div class='border'><ul><li><div class='light'></div><div class='part'>停车位1</div></li>");  
client.println("<li><div class='light'></div><div class='part'>停车位2</div></li>");  
client.println("<li><div class='light'></div><div class='part'>停车位3</div></li></ul>");  
client.println("<div class='ispart'><div class='ispartlight'></div><div class='message'>警示灯</div></div></div></div></body>");  
client.println("<script>");
```



# Explain the Web code

```
client.println("var lis = document.getElementsByClassName('light');");
if(a == LOW)
{
    client.print("lis[0].style.background = 'red';");
}
else
{
    client.print("lis[0].style.background = 'white';");
}
if(b == LOW)
{
    client.print("lis[1].style.background = 'red';");
}
else
{
    client.print("lis[1].style.background = 'white';");
}
if(c == LOW)
{
    client.print("lis[2].style.background = 'red';");
}
else
{
    client.print("lis[2].style.background = 'white';");
}
client.println("var lis1 = document.getElementsByClassName('ispartlight');");

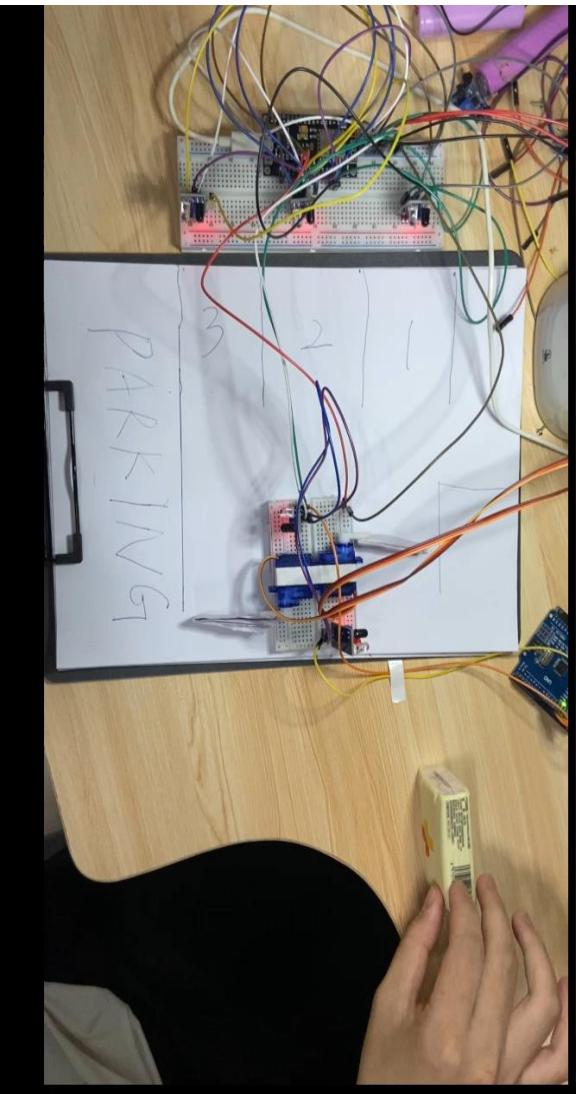
if(d == HIGH)
{
    client.print("lis1[0].style.background = 'red';");
}
else
{
    client.print("lis1[0].style.background = 'white';");
}
client.println("</script>");

client.println("</html>");

delay(1);
Serial.println("Client disconnected");
Serial.println("");
}
```



# Experimental video in iot



Arduino Cloud    Arduino IoT Cloud    https://create.arduino.cc/iot/dashboards/5e80aae3-9add-4086-802e-68

Things Dashboards Devices Integrations Templates UPGRADE PLAN

project2

Parking3

Parking2

Parking1

amount ✓

# Experimental video in HTML



Document x +

http://192.168.43.166 00:00:00 结束

题目集列表 个人空间 CSDN - 专业开发者社 哔哩哔哩 ( °\_° ) 天使动漫官网(tsdm) MDN Web Docs U校园 上网登录页 Arduino Cloud 其它收藏

## Project 2:

PROJECT NAME: P8266

IoT Ba

警示灯

PARKING

停车位1 停车位2 停车位3

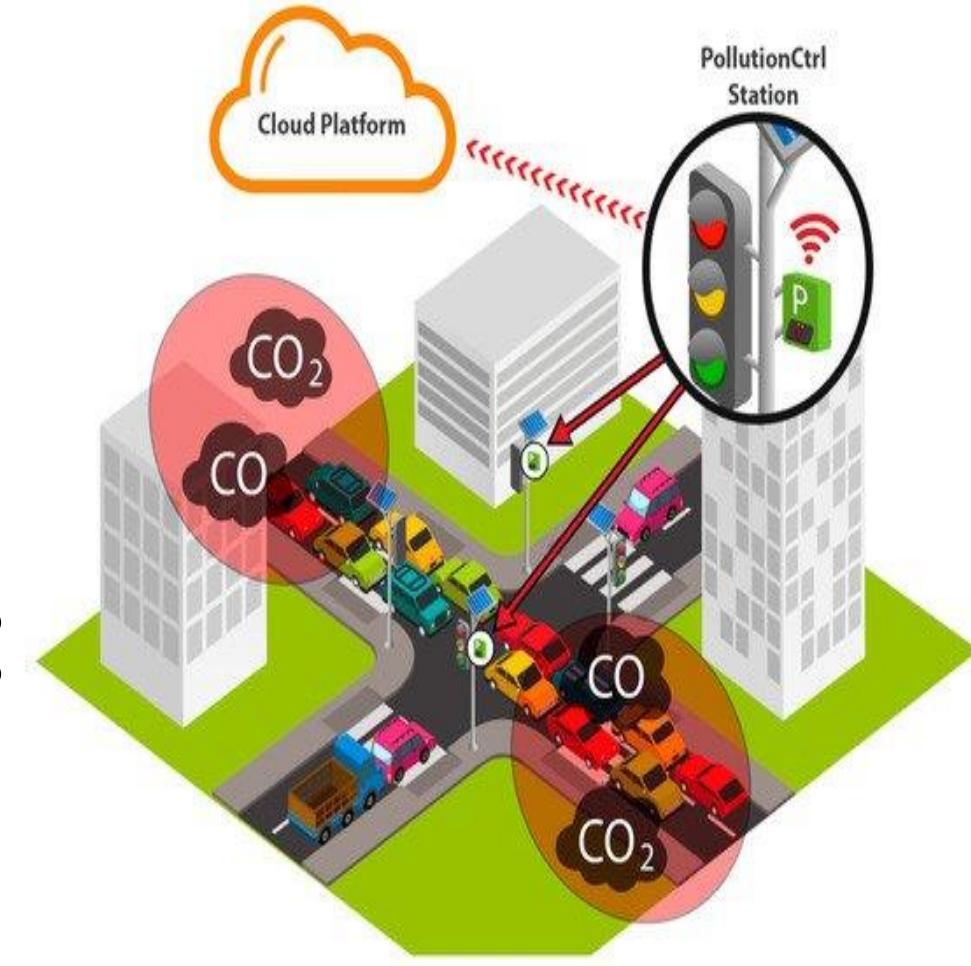
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161



# Project5:

IoT-based car Gas Detection System( air quality )





# Project 5: IoT-based car Gas Detection System

- Indoor air pollution has been consistently ranked by the US Environmental Protection Agency (EPA) and its Science Advisory Board to be among the top five environmental public health risks.
- Average person spends an estimated 90% of their time indoors so that poor indoor air quality (IAQ) poses a substantial risk to public health. Poor air quality may cause increased short-term health problems such as fatigue and nausea as well as chronic respiratory diseases, heart disease, and lung cancer.

Air Quality Index (AQI) Values	Levels of Health Concern	Colors
When the AQI is in this range:	...air quality conditions are:	..as symbolized by this color:
0-50	Good	Green
51-100	Moderate	Yellow
101-150	Unhealthy for Sensitive Groups	Orange
151 to 200	Unhealthy	Red
201 to 300	Very Unhealthy	Purple
301 to 500	Hazardous	Maroon



# Project 5:Component



MQ-3

The basic principle of the alcohol sensor MQ-3 can be briefly described as a device that converts the detected alcohol concentration into useful electrical signals. According to the strength of these electrical signals, information related to the presence of the gas to be measured in the environment can be obtained



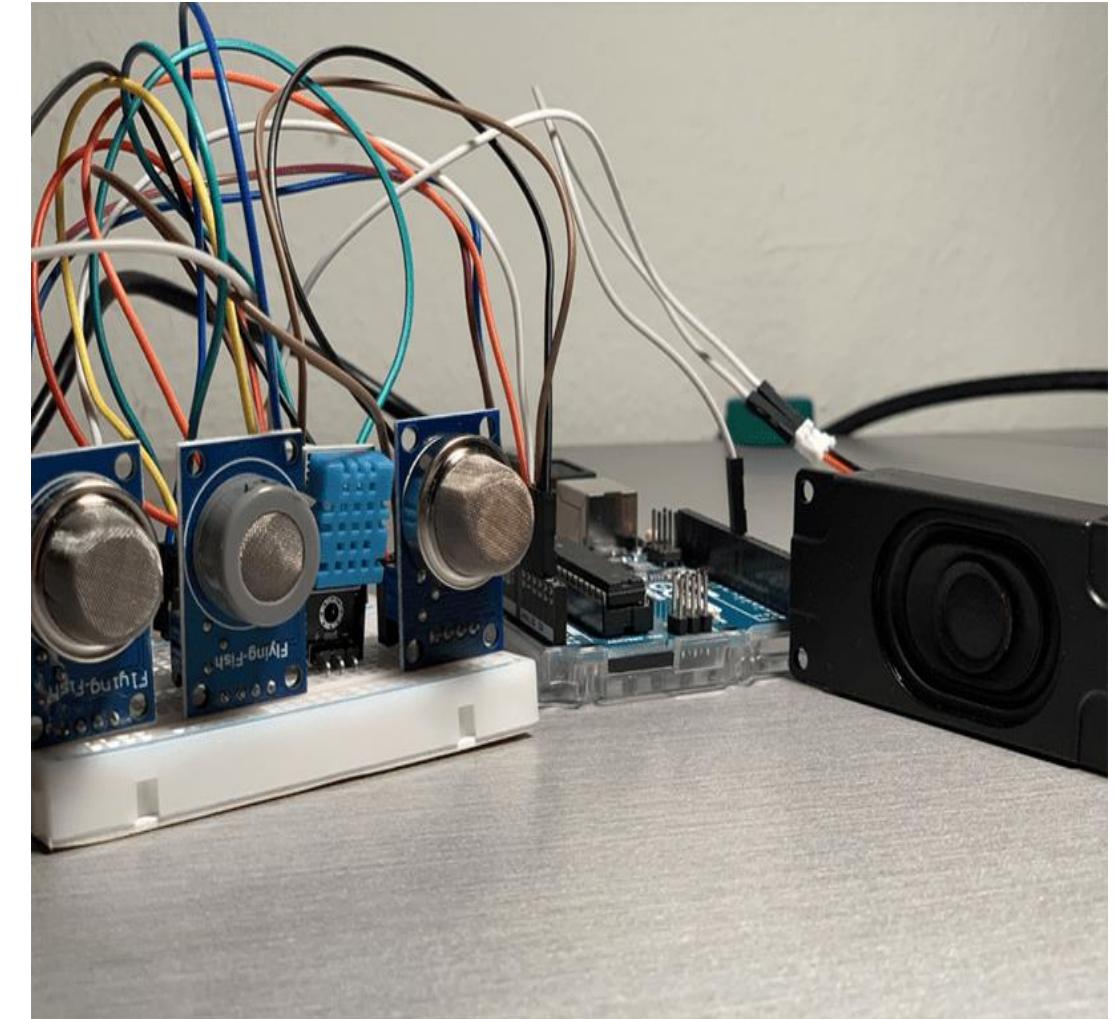
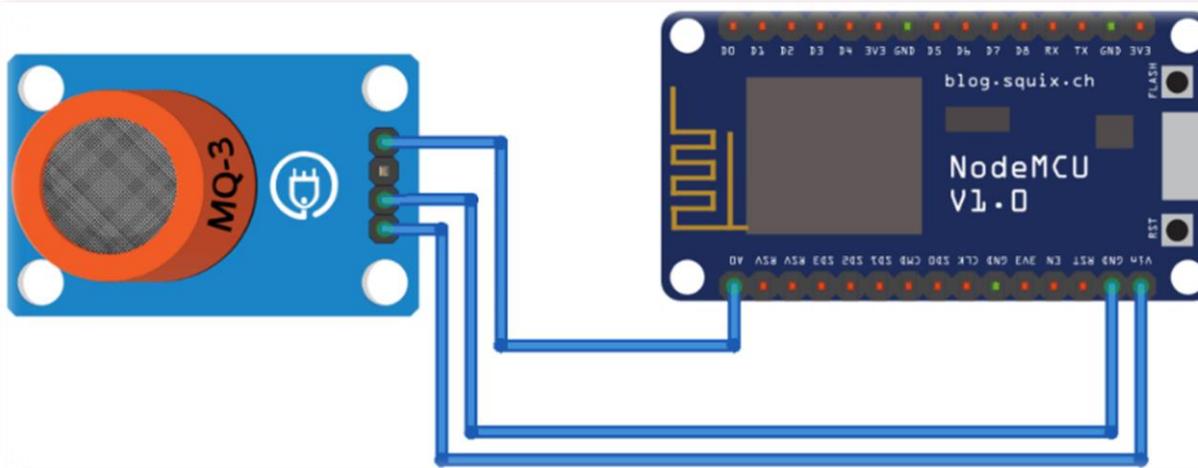
ESP8266

It is a utility system on chip (SoC), which is built in with TCP/IP protocol, since this arbitrary microcontroller can be connected to any Wi-Fi network. It has the power to supervise any other device and can easily be connected to a Wi-Fi network with other systems. It has a huge amount of on-chip variation which is good for the smallest external circuit. The module is an extremely cost effective board.



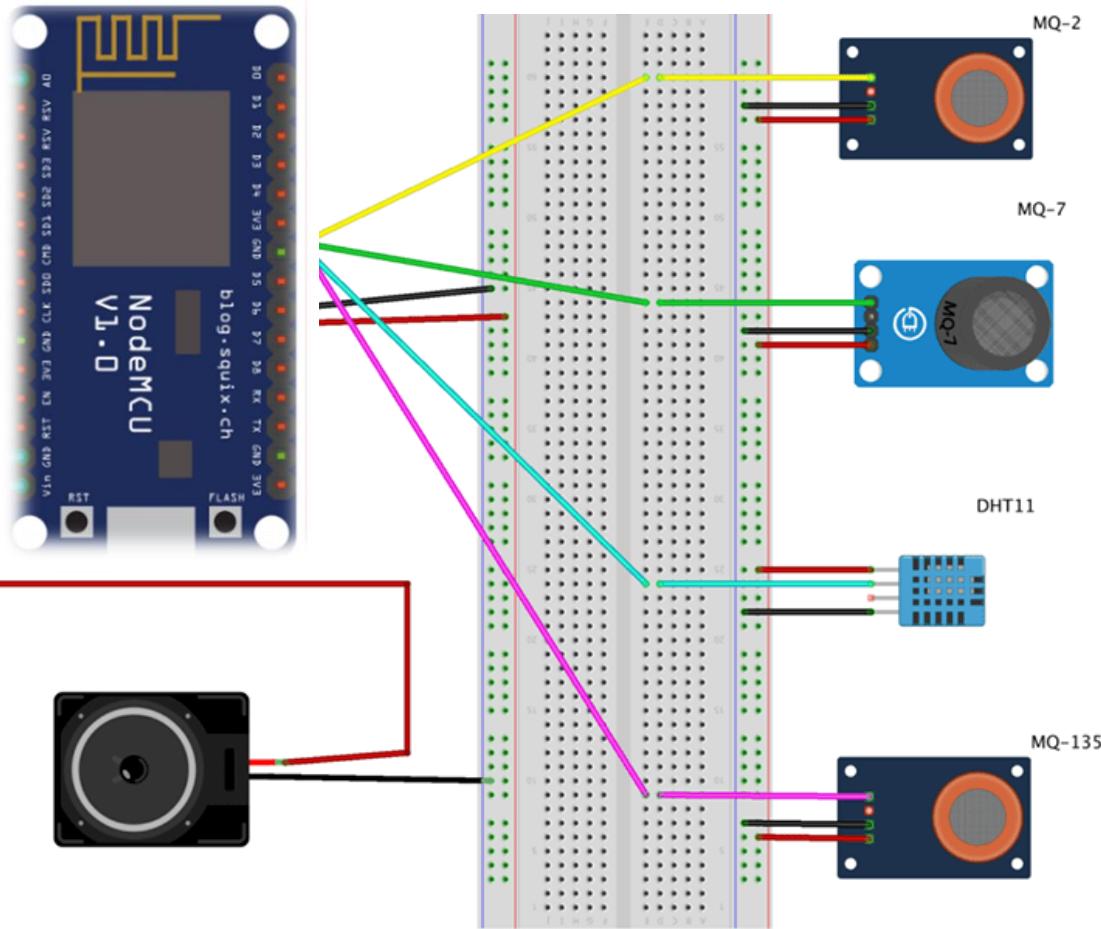
# Project 5:Component

---

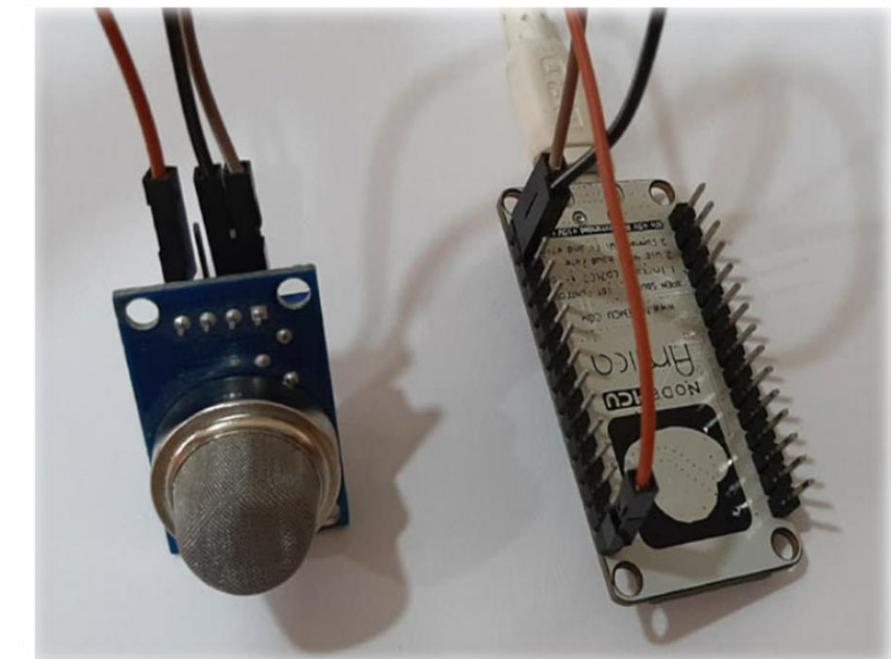
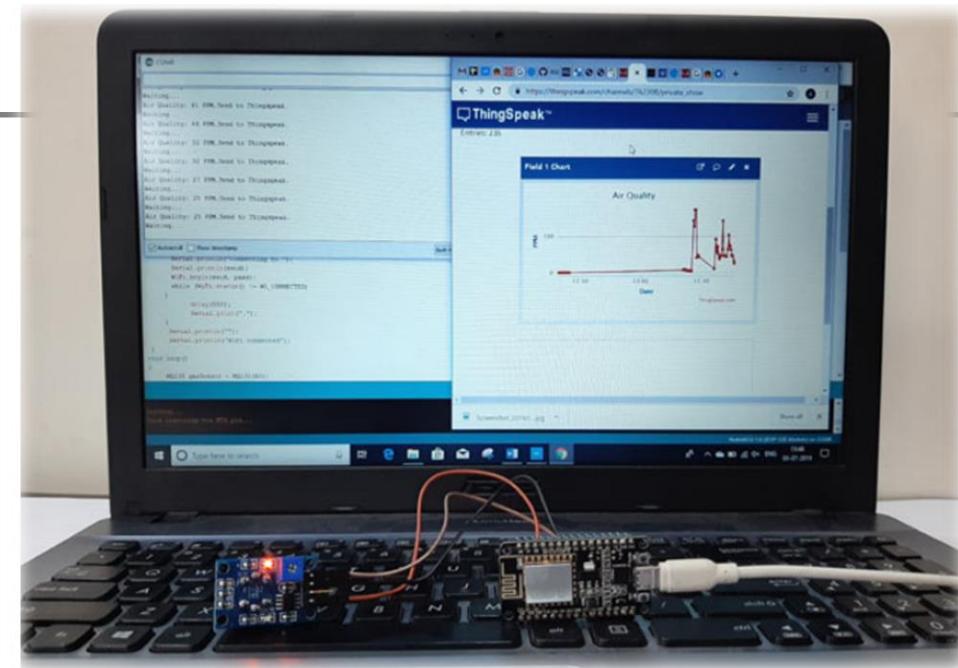


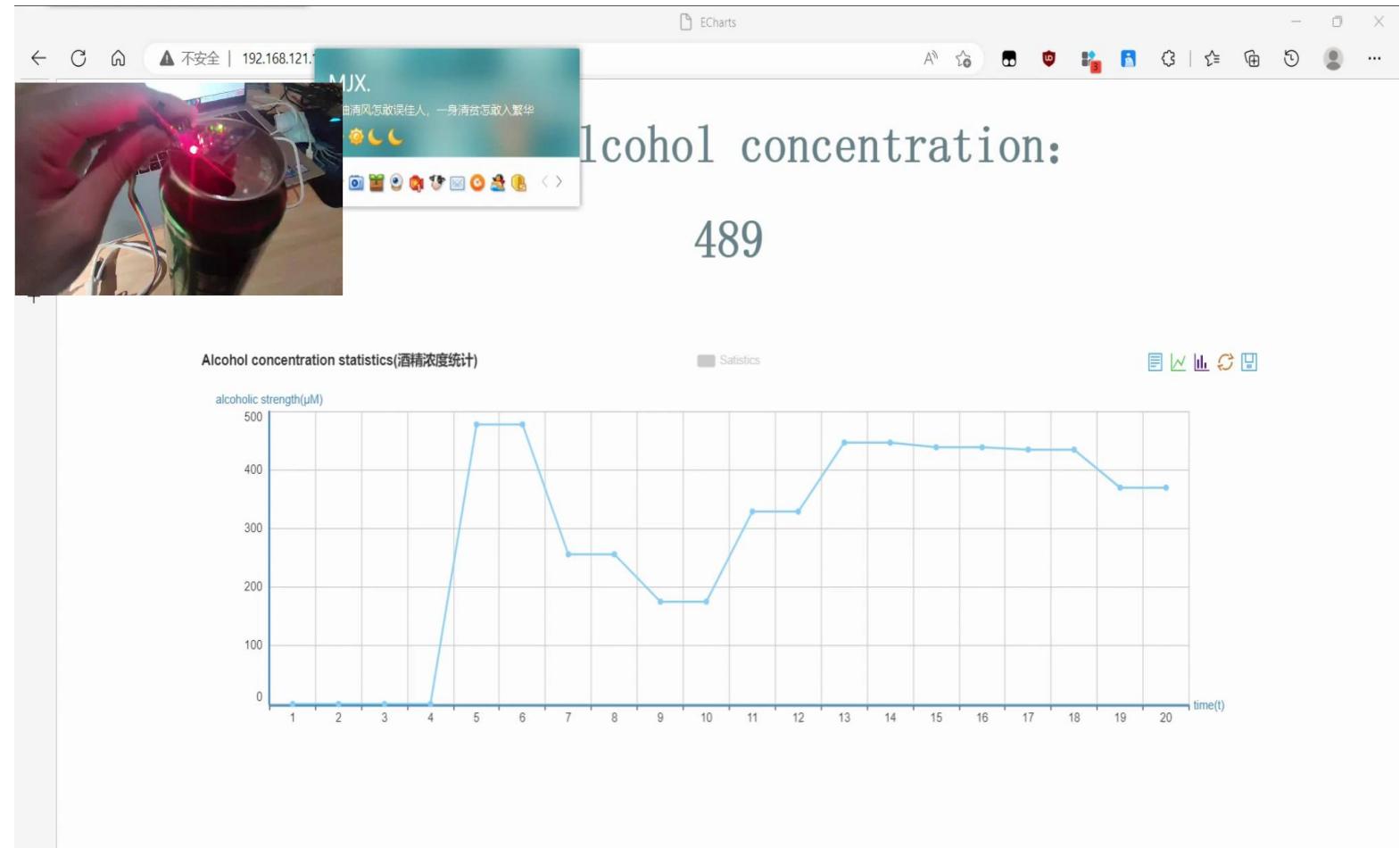
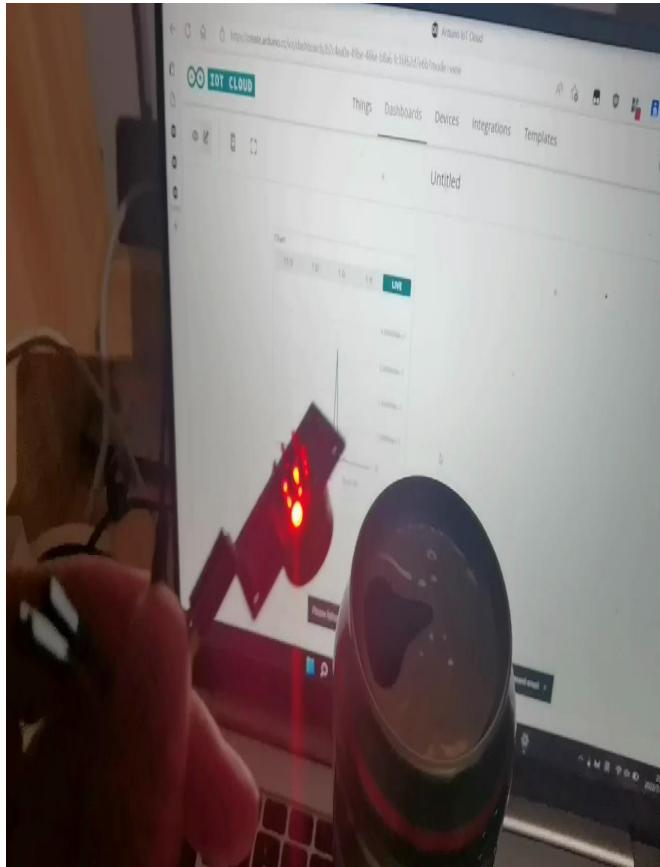


## Project 5:Component



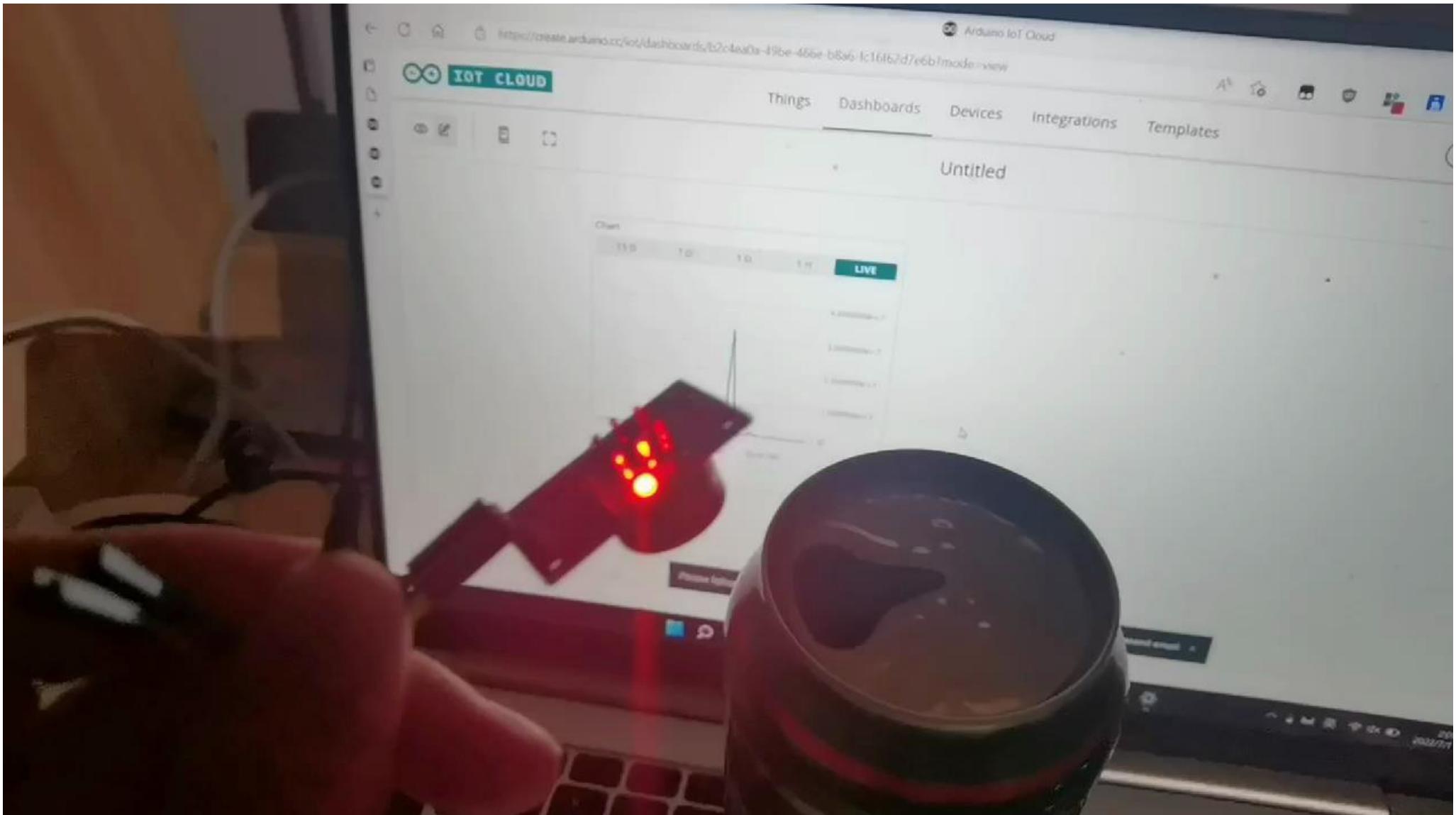
fritzinc







# Project 4: Demo Arduino IOT Cloud





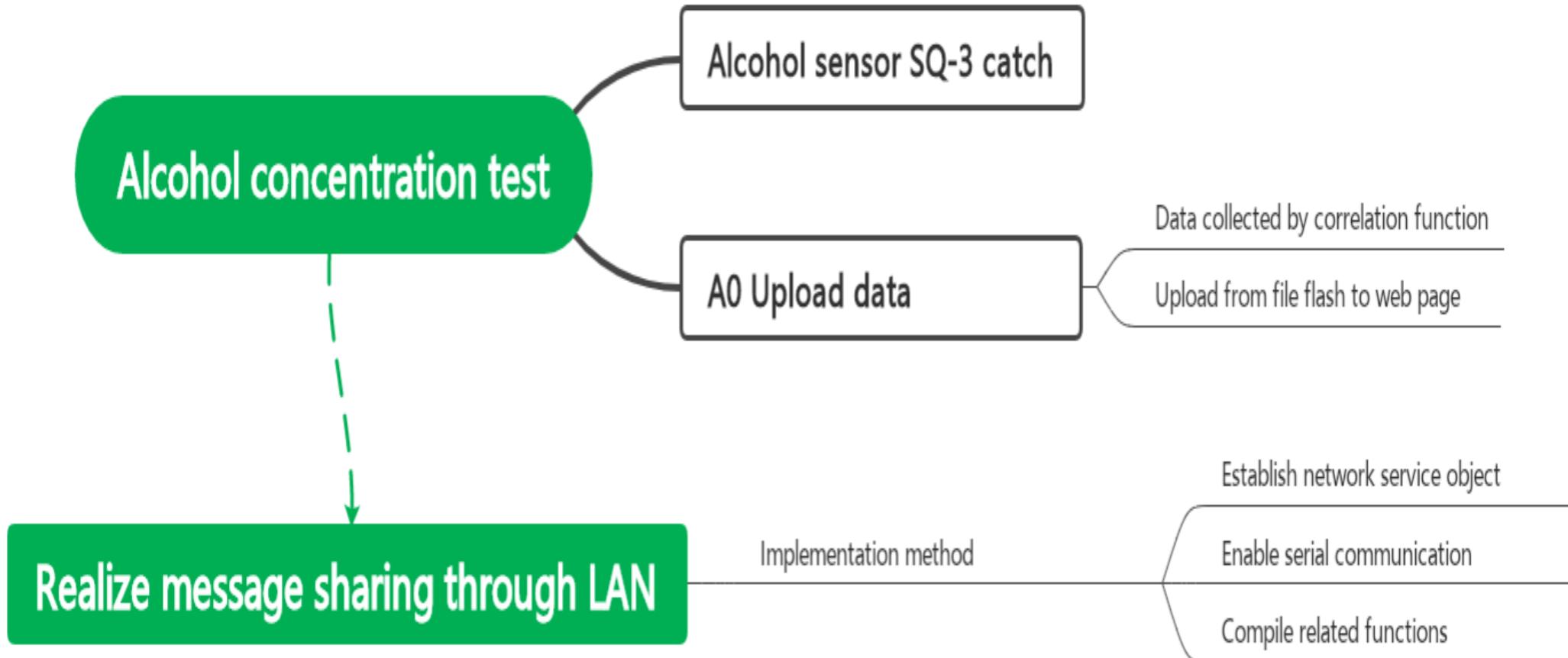
## Project 4:

QUESTIONS  
**ANSWERS**



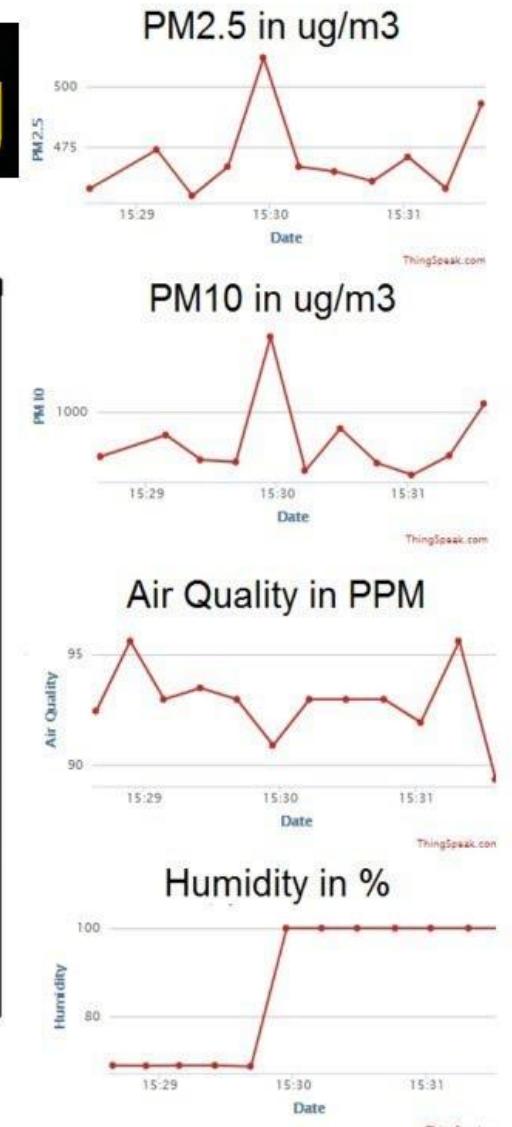
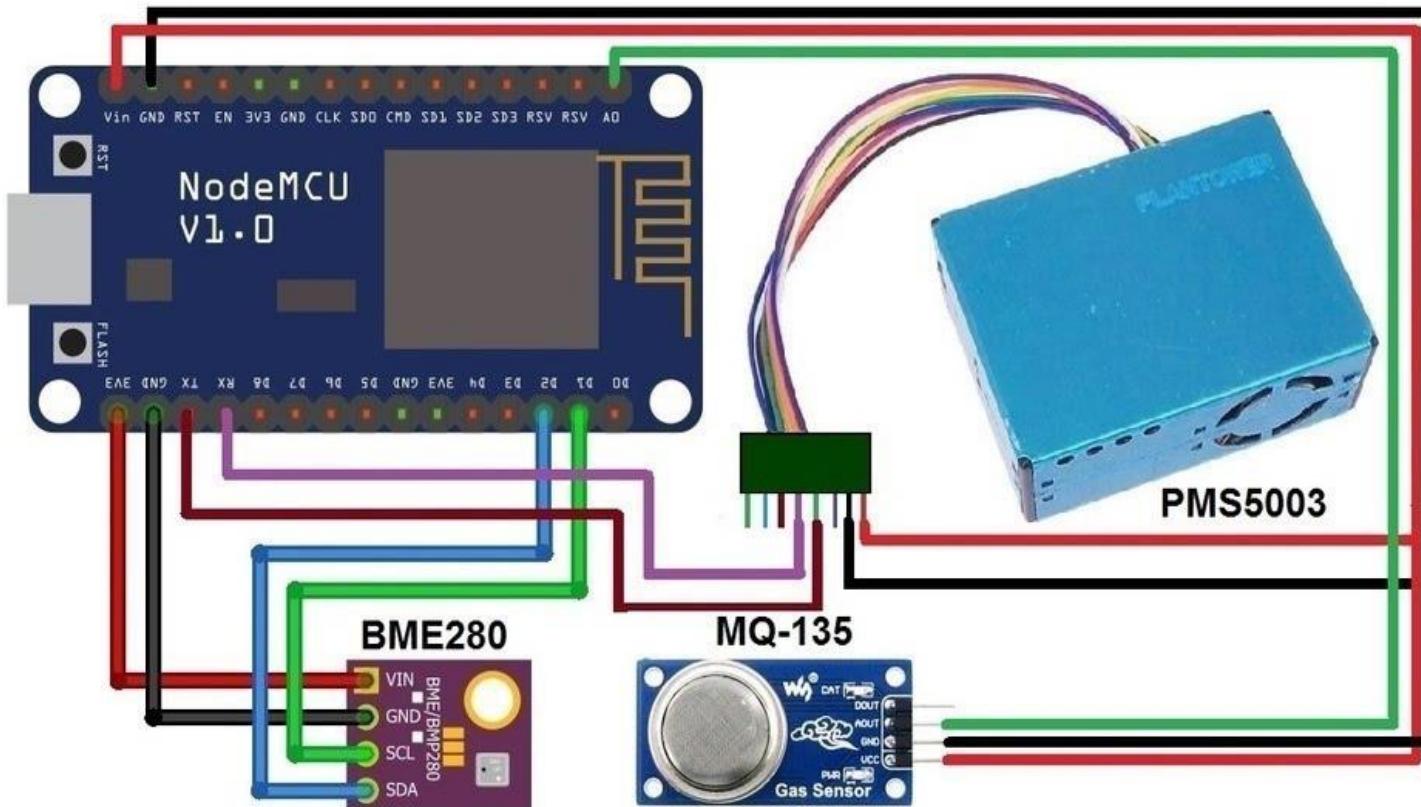


# Brain Map





# IoT Based Air Pollution Monitoring

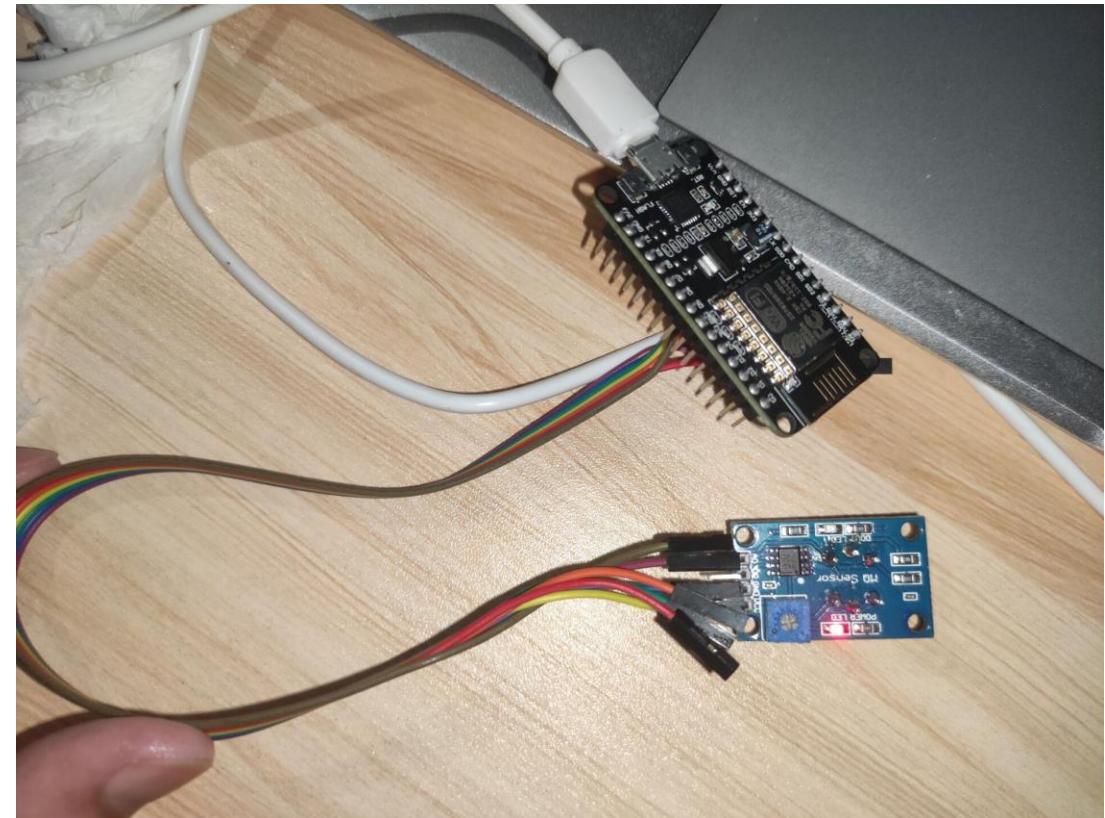


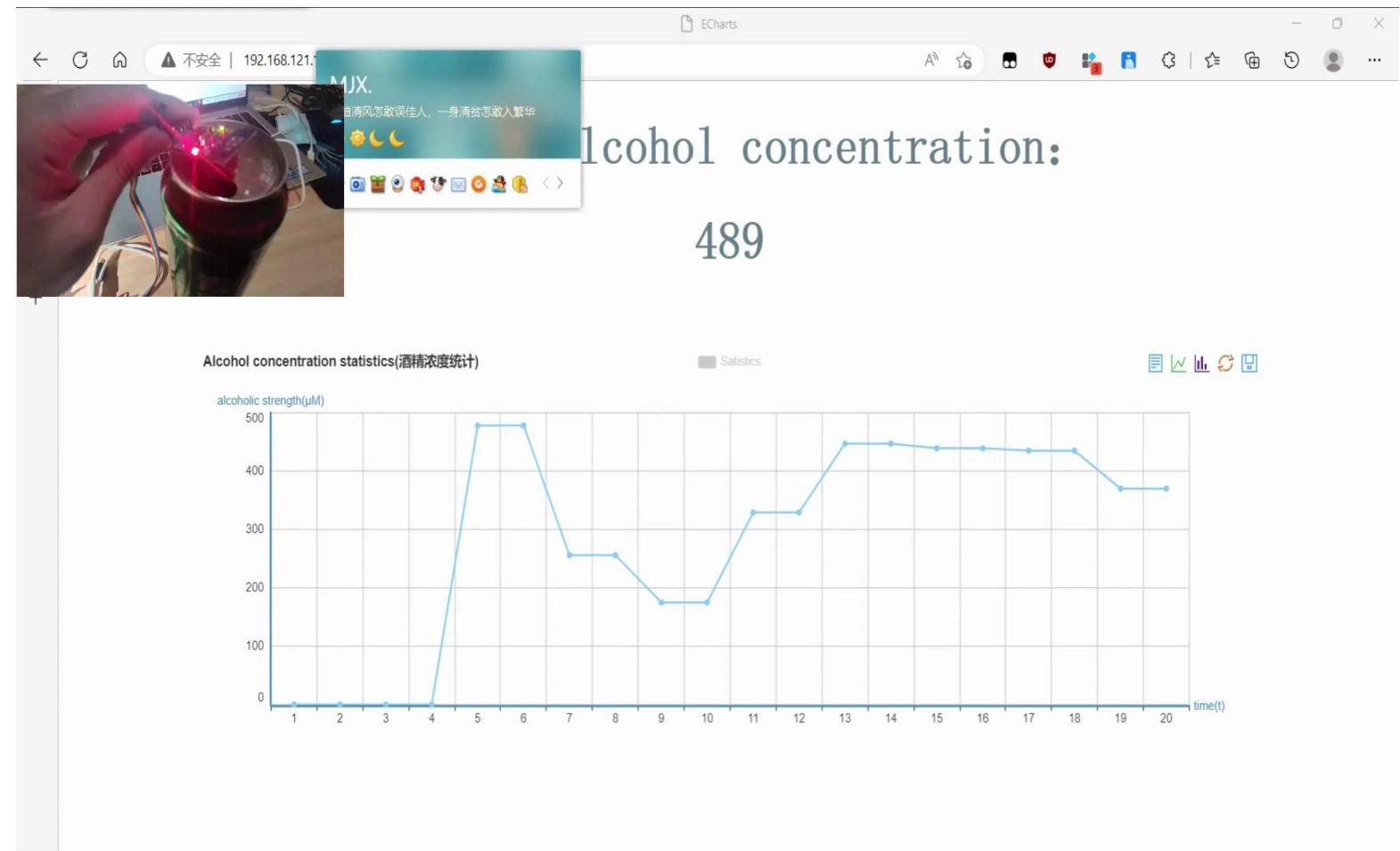
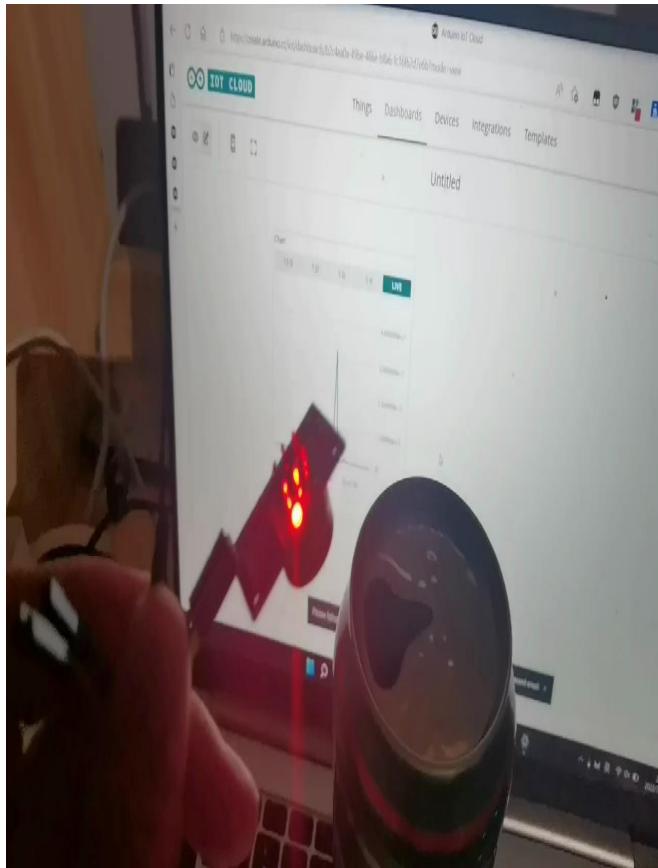


# Hardware connection diagram of the project

---

- The Vcc pin of MQ-3 sensor relates to Vin pin of NodeMCU, and GND pin relates to NodeMCU's GND pin. While the A0 pin relates to A0 pin of NodeMCU as shown in the circuit diagram above. The complete set-up will be powered by the micro-usb port of Node-MCU through a USB cable.







# Project5:

## Code Section



# WiFi build

```
ESP8266WiFiMulti wifiMulti;          // Create an esp8266wifimulti object whose name is 'wifiMulti'  
  
ESP8266WebServer esp8266_server(80); // Create a web server object that is used to respond to HTTP requests. Listening port (80)  
  
MQ135 gasSensor = MQ135(A0);  
  
void setup(void) {  
  
    Serial.begin(9600);           // Start serial communication  
  
    wifiMulti.addAP("2451070895的Redmi K30 Pro", "11111111"); //Enter a series of WiFi IDs and passwords you need to connect here  
  
    Serial.println("Connecting ..."); // Then try to connect using the password stored here.  
}  

```



# WiFi build

```
void setup(void) {  
    Serial.begin(9600);  
    // Start serial communication  
  
    wifiMulti.addAP("2451070895的Redmi K30 Pro", "1111111111"); // Enter a series of WiFi IDs and passwords you need to connect here  
    Serial.println("Connecting ..."); // Then try to connect using the password stored here.  
    int i = 0;  
    while (wifiMulti.run() != WL_CONNECTED) {  
        // WiFi multi Run () is the key. Via WiFi multi  
        // Run(), nodemcu will be in the current Search the WiFi stored by the addap function in the environment.  
        delay(1000); Serial.print(i++); Serial.print(' '); // If multiple stored WiFi is found, nodemcu will connect the WiFi signal with the strongest signal.  
    } // Once WiFi is successfully connected, WiFi multi Run() will return "wl_connected". This is also the  
    // condition for the while loop to judge whether to jump out of the loop.  
    if(SPIFFS.begin()){  
        //Boot flash file system  
        Serial.println("SPIFFS Started.");  
    } else {  
        Serial.println("SPIFFS Failed to Start.");  
    }
```



# Web page processing

```
void handleData()
{
    esp8266_server.send(200,"textain",(String)air_quality);
}

void handleUserRequest() {          //Get user request resource
    String reqResource = esp8266_server.uri();
    Serial.print("reqResource: ");
    Serial.println(reqResource);      //Handle user requested resources through
                                    //the handlefileread function
    bool fileReadOK = handleFileRead(reqResource);

                                    //If the resource accessed by the user cannot be found in
SPIFs, reply 404 (not found)
    if (!fileReadOK){
        esp8266_server.send(404, "textain", "404 Not Found");
    }
}
```



# Web page making

```
<!DOCTYPE html>
<head>
    <meta charset="utf-8">
    <title>ECharts</title>
</head>
<body>
    <h1>Current alcohol concentration: </h1><h1 id="x">x</h1>
    <br><br>
    <!-- 为ECharts准备一个具备大小（宽高）的Dom -->
    <div id="main" style="width:80%;height:400px;margin: 0 auto;background: #cccccc"></div>
</body>

<style>
    h1 {
        position: relative;
        text-align: center;
        color: #68838B;
        font-size: 50px;
        font-family: "Cormorant Garamond", serif;
    }
</style>
<!-- ECharts单文件引入 -->
<script src="http://echarts.baidu.com/build/dist/echarts.js"></script>
<script type="text/javascript">
    var arrX=[], arrY=[];
    var x=0;
    var i = 1;
    var sh = setInterval(function () {
        if(i>20){
            clearInterval(sh);
            myChart.setOption(option);
        }
    }, 1000);
    </script>
```

```
arrX.push(i)
    var j = parseInt(getAirQ())
    arrY.push(j)
    i = i + 1
    //Path configuration
    require.config({
        paths: {
            echarts: 'http://echarts.baidu.com/build/dist'
        }
    });
    creatCheart();
}, 1000);
function creatCheart(){
    // use
    require(
        [
            'echarts',
            'echarts/chart/bar', //Use the histogram to load the bar module, and      load it on demand
            'echarts/chart/line'
        ],
        function (ec) {
            //Initialize the ecarts chart based on the prepared DOM
            var myChart = ec.init(document.getElementById('main'));

            var option = { //Description of specific details
                title: {
                    text: 'Alcohol concentration statistics(酒精浓度统计)',
                    textStyle: { //主标题文本样式{"fontSize": 18,"fontWeight": "bolder","color": "#333" }
                        fontSize: 14,
                        fontStyle: 'normal',
                        fontWeight: 'bold',
                    },
                },
            };
        }
    );
}
```



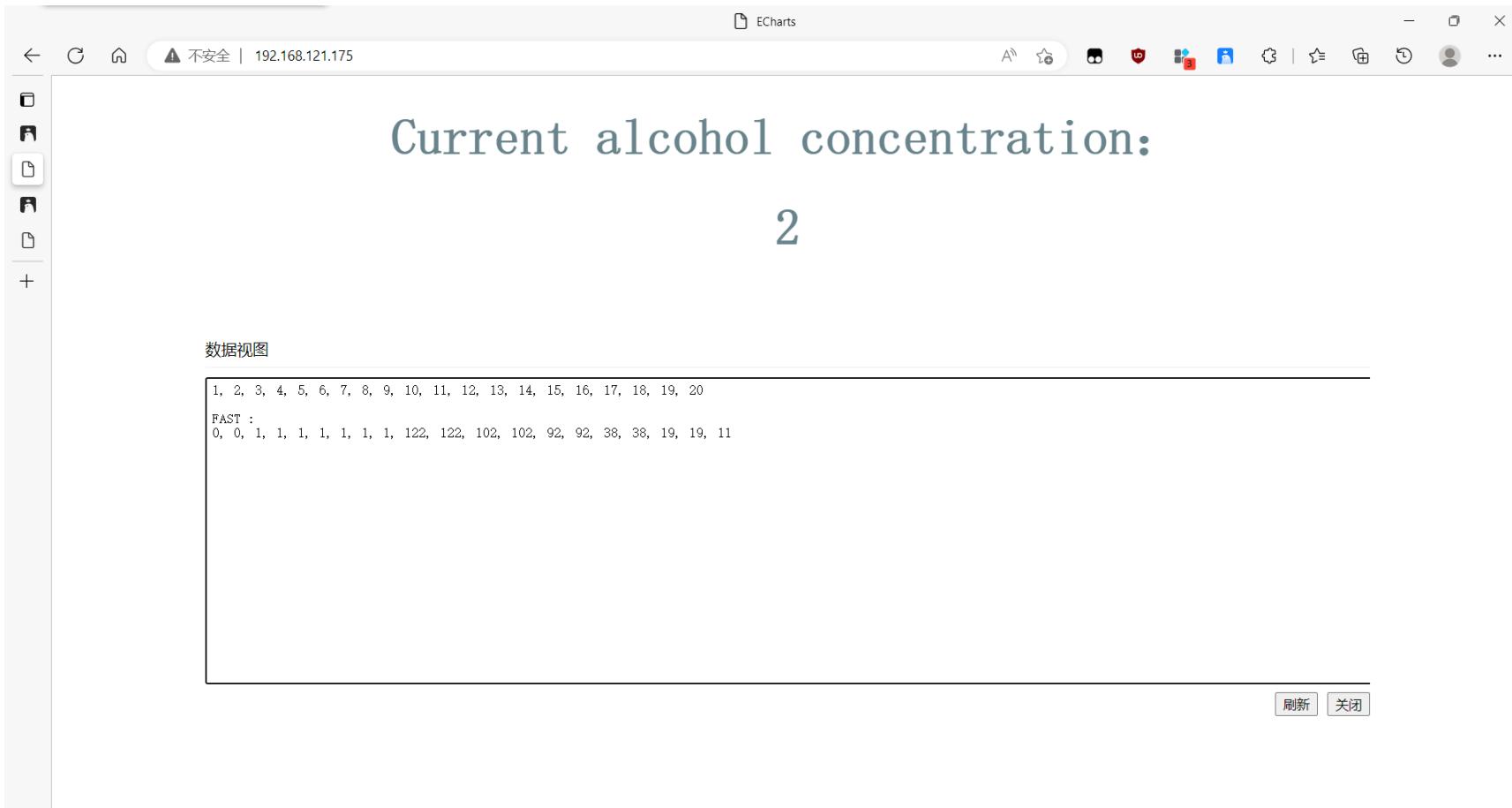
# Web page making

```
tooltip: {  
    trigger: 'axis'  
},  
legend: {  
    data: ['Statistics']  
},  
toolbox: { // you can select specific data, histogram, line chart, restore, and save the image  
    show: true,  
    feature: {  
        dataView: {  
            show: true,  
            readOnly: false  
        },  
        magicType: {  
            show: true,  
            type: ['line', 'bar'] //Line chart and histogram are optional  
        },  
        restore: {  
            show: true //Restore default  
        },  
        saveAsImage: {  
            show: true //Functions stored as pictures  
        }  
    }, calculable: true,  
    //Name:'time'on the horizontal axis  
xAxis: [{  
    type: 'category',  
    data: arrX,  
    name: 'time(t)',  
    position: 'left'  
}],  
//name: "alcoholic strength( μ M) "On the ordinate
```

```
yAxis: [{  
    type: 'value',  
    name: 'alcoholic strength(μM)',  
    position: 'left'  
}],  
series: [{  
    name: 'FAST',  
    type: 'line',// bar  
    data: arrY,  
    color: '#CC0066'  
}]  
};  
  
//Load data for the echorts object  
myChart.setOption(option);  
});  
}  
function getAirQ() {  
var xhttp = new XMLHttpRequest();  
xhttp.onreadystatechange = function () {  
    if (this.readyState == 4 && this.status == 200) {  
        document.getElementById("x").innerHTML =  
            this.responseText;  
        x = this.responseText  
    }  
};  
xhttp.open("GET", "data", true);  
xhttp.send();  
return x;  
}  
</script>
```



# We get three types of data result graphs



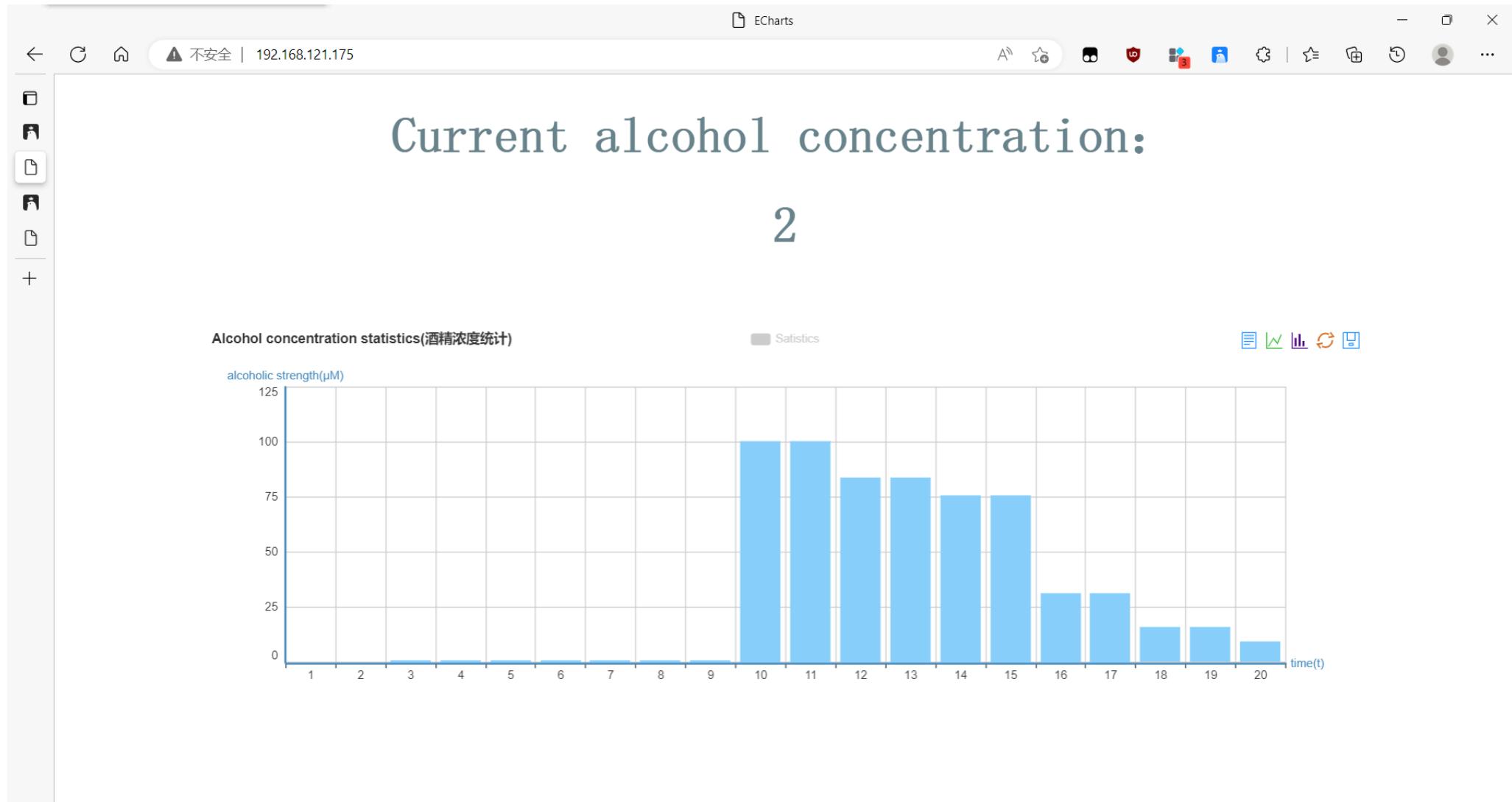


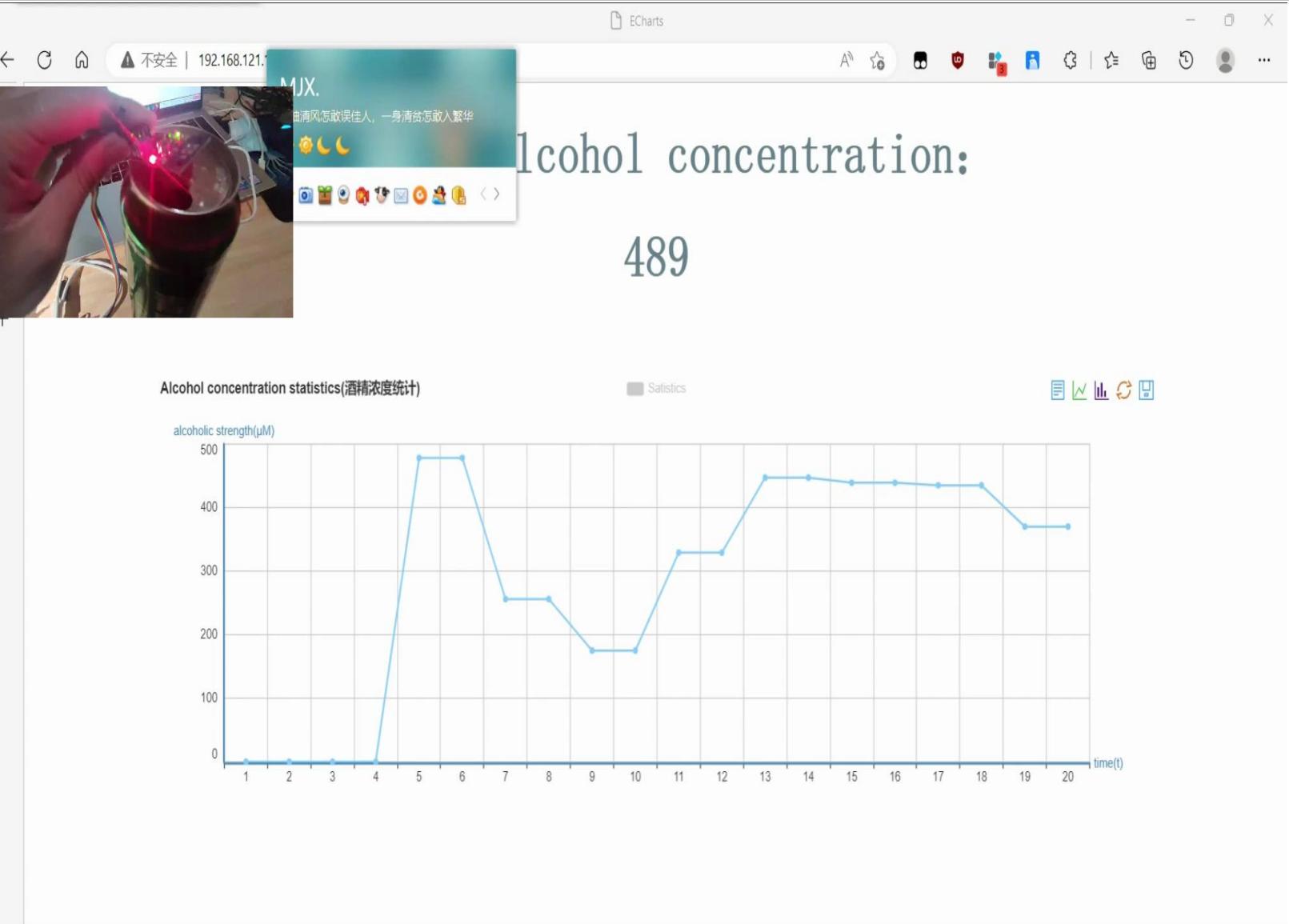
# We get three types of data result graphs





# We get three types of data result graphs







# Arduino IOT

## STEP 1 : Create Things

Things Dashboards Devices Integrations Templates

### Things

Search and filter Things

Name ↓	Device	Variables	Last Modified
<input type="checkbox"/> Untitled	Shirleen NodeMCU 1.0 (ESP-12E Mod...)	AirQuality	30 Jun 2022 15:49:14

**CREATE**

## Create Associated Device

Things Dashboards Devices Integrations Templates

### Devices

Search and filter Devices

Name ↓	Status	Linked Thing
<input type="checkbox"/> Shirleen NodeMCU 1.0 (ESP-12E Module)	Offline	Untitled

## Add variable

Things Dashboards Devices Integrations Templates

Untitled

Setup Sketch

### Variables

Name ↓	Last Value	Last Update
<input type="checkbox"/> AirQuality float sensorValue;	-	-

**ADD**

## STEP 2: Establish a dashboard association with a variable

### Widget Settings

Name  
AirQuality

Hide widget frame

### Linked Variable

AirQuality  
from Untitled

Change     Detach

Show Thing name on widget

### Data points interpolation

- Spline  
 Line



# Arduino IOT

## STEP 3: Modify the code

The screenshot shows the Arduino IDE interface with the following details:

- Editor Tab:** NEW SKETCH
- Sketchbook:** Untitled\_jun30c
- Code Content:** The code is for connecting an Arduino to the IoT Cloud. It includes includes for "thingProperties.h" and "MQTTSN.h", initializes serial communication at 9600 bps, connects to the cloud using "ArduinoCloud.begin(ArduinoIoTPreferredConnection)", and sets debug message levels. The code ends with a standard void loop().
- Message Bar:** A yellow bar at the top says "To upload a sketch via USB port, make sure the Agent is installed and running on this computer." with a "LEARN MORE" button.
- File Menu:** UPGRADE PLAN

```
#include "thingProperties.h"
#include "MQTTSN.h"

void setup() {
    // Initialize serial and wait for port to open:
    Serial.begin(9600);
    // This delay gives the chance to wait for a Serial Monitor without blocking if none is found
    delay(1500);
}

// Defined in thingProperties.h
initProperties();

// Connect to Arduino IoT Cloud
ArduinoCloud.begin(ArduinoIoTPreferredConnection);

/*
The following function allows you to obtain more information
related to the state of network and IoT Cloud connection and errors
the higher number the more granular information you'll get.
The default is 0 (only errors).
Maximum is 4
*/
setDebugMessageLevel(2);
ArduinoCloud.printDebugInfo();
}

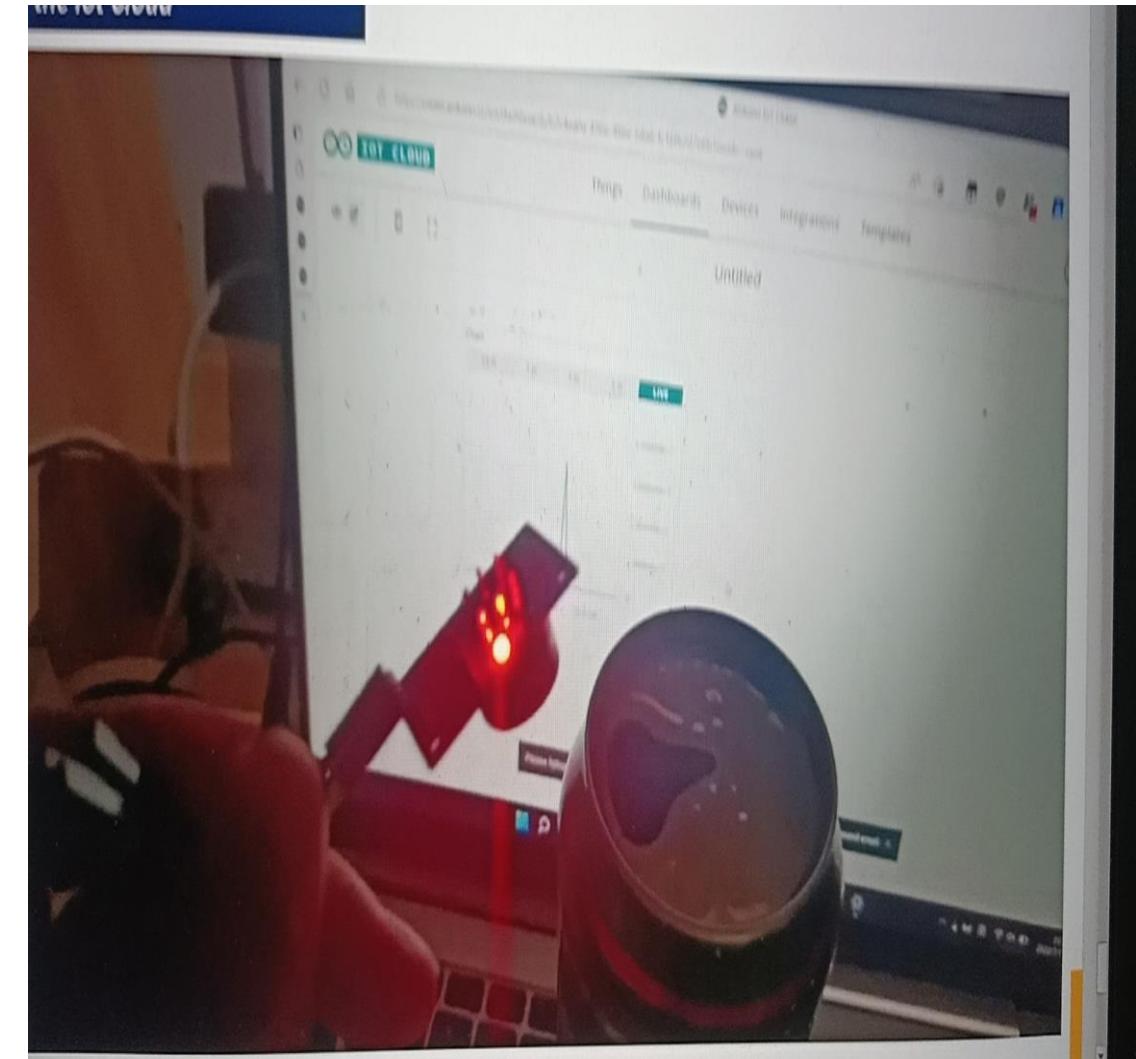
ArduinoCloud.begin(ArduinoIoTPreferredConnection);

/*
The following function allows you to obtain more information
related to the state of network and IoT Cloud connection and errors
the higher number the more granular information you'll get.
The default is 0 (only errors).
Maximum is 4
*/
setDebugMessageLevel(2);
ArduinoCloud.printDebugInfo();

void loop()
```

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## STEP 4: Start running





# SECOND:The codes we use in the IOT Clou

```
/*
Sketch generated by the Arduino IoT Cloud Thing "Untitled 2"
https://create.arduino.cc/cloud/things/a2621a1a-51c2-479b-
b440-8140d252da94

Arduino IoT Cloud Variables description

The following variables are automatically generated and
updated when changes are made to the Thing

int haha;

Variables which are marked as READ/WRITE in the Cloud
Thing will also have functions
which are called when their values are changed from the
Dashboard.

These functions are generated with the Thing and added at the
end of this sketch.
*/
```

```
#include "thingProperties.h"
#include "MQ135.h"

void setup() {
    // Initialize serial and wait for port to open:
    Serial.begin(9600);
    // This delay gives the chance to wait for a Serial Monitor without blocking if none is found
    delay(1500);

    // Defined in thingProperties.h
    initProperties();

    // Connect to Arduino IoT Cloud
    ArduinoCloud.begin(ArduinoIoTPreferredConnection);

    /*
    The following function allows you to obtain more information
    related to the state of network and IoT Cloud connection and errors
    the higher number the more granular information you'll get.
    The default is 0 (only errors).
    Maximum is 4
    */
    setDebugMessageLevel(2);
    ArduinoCloud.printDebugInfo();
}
```



## SECOND The codes we use in the IOT Cloud

```
ArduinoCloud.begin(ArduinoIoTPreferredConnection);
/*
    The following function allows you to obtain more
information
    related to the state of network and IoT Cloud
connection and errors
    the higher number the more granular information
you'll get.
    The default is 0 (only errors).
    Maximum is 4
*/
setDebugMessageLevel(2);
ArduinoCloud.printDebugInfo();
}
```

```
void loop() {
    ArduinoCloud.update();

    onHahahaChange();

}
```

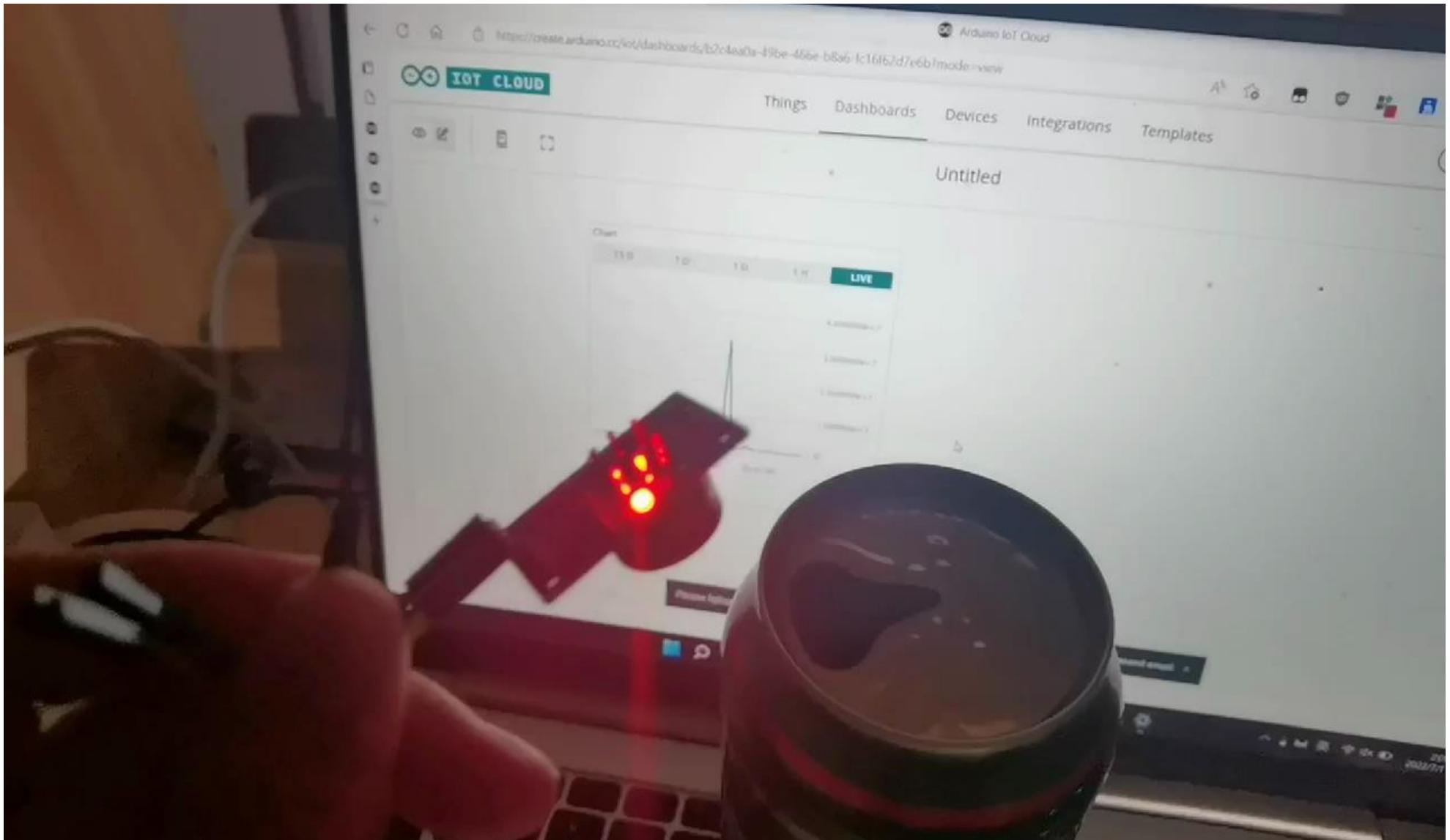
Since Hahaha is READ\_WRITE variable, onHahahaChange() is executed every time a new value is received from IoT Cloud.

```
/*
void onHahahaChange() {
    MQ135 gasSensor = MQ135(A0);
    hahaha = gasSensor.getPPM();
    delay(1000);
    Serial.println(hahaha);
}
```



# Next up is a video running in the iot Cloud

---





“Good scientists  
are perpetual  
adolescents.  
They never grow  
up.”

PETER DOHERTY  
Nobel Prize in Physiology or  
Medicine 1996