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HW03 Code

You will complete the following notebook, as described in the PDF for Homework 03 (included in the download with the starter code). You will submit:

- 1. This notebook file, along with your COLLABORATORS.txt file and the two tree images (PDFs generated using graphviz within the code), to the Gradescope link for code.
- 2. A PDF of this notebook and all of its output, once it is completed, to the Gradescope link for the PDF.

Please report any questions to the <u>class Piazza page (https://piazza.com/tufts/spring2020/comp135)</u>.

Import required libraries.

```
In [213]: import os
    import numpy as np
    import pandas as pd

import sklearn.linear_model
    import sklearn.tree
    import sklearn.metrics

from matplotlib import pyplot as plt
    import seaborn as sns
%matplotlib inline
    plt.style.use('seaborn') # pretty matplotlib plots

import graphviz
```

Part One: Cancer-Risk Screening

1.1: Compute true/false positives/negatives.

Complete the following code.

```
In [214]:
          def calc TP TN FP FN(ytrue N, yhat N):
               ''' Compute counts of four possible outcomes of a binary classifie
          r for evaluation.
              Args
              ytrue N : 1D array of floats
                  Each entry represents the binary value (0 or 1) of 'true' labe
          1 of one example
                  One entry per example in current dataset
              yhat N : 1D array of floats
                  Each entry represents a predicted binary value (either 0 or 1)
                  One entry per example in current dataset.
                  Needs to be same size as ytrue N.
              Returns
               _____
               TP: float
                  Number of true positives
               TN: float
                  Number of true negatives
              FP: float
                  Number of false positives
              FN: float
                  Number of false negatives
               . . .
              TP = 0.0
              TN = 0.0
              FP = 0.0
              FN = 0.0
              for i in range(len(ytrue N)):
                  real = ytrue_N[i]
                  predict = yhat N[i]
                  if real == 1 and predict == 1:
                      TP += 1
                  if real == 0 and predict == 0:
                      TN += 1
                  if real == 1 and predict == 0:
                      FN += 1
                   if real == 0 and predict == 1:
                      FP += 1
              return TP, TN, FP, FN
```

```
In [215]: all0 = np.zeros(10)
    all1 = np.ones(10)
    calc_TP_TN_FP_FN(all0, all1)

Out[215]: (0.0, 0.0, 10.0, 0.0)

In [216]: calc_TP_TN_FP_FN(all1, all0)

Out[216]: (0.0, 0.0, 0.0, 10.0)

In [217]: calc_TP_TN_FP_FN(all1, all1)

Out[217]: (10.0, 0.0, 0.0, 0.0)

In [218]: calc_TP_TN_FP_FN(all0, all0)

Out[218]: (0.0, 10.0, 0.0, 0.0)
```

Supplied functions for later use

Do not edit the following functions. They are already complete, and will be used in your later code.

```
In [219]:
          def calc perf metrics for threshold(ytrue N, yprobal N, thresh):
              ''' Compute performance metrics for a given probabilistic classifi
          er and threshold
              tp, tn, fp, fn = calc_TP_TN_FP_FN(ytrue_N, yprobal_N >= thresh)
              ## Compute ACC, TPR, TNR, etc.
              acc = (tp + tn) / float(tp + tn + fp + fn + 1e-10)
              tpr = tp / float(tp + fn + 1e-10)
              tnr = tn / float(fp + tn + 1e-10)
              ppv = tp / float(tp + fp + 1e-10)
              npv = tn / float(tn + fn + 1e-10)
              return acc, tpr, tnr, ppv, npv
          def print perf metrics for threshold(ytrue N, yprobal N, thresh):
              ''' Pretty print perf. metrics for a given probabilistic classifie
          r and threshold
              acc, tpr, tnr, ppv, npv = calc perf metrics for threshold(ytrue N,
          yprobal N, thresh)
              ## Pretty print the results
              print("%.3f ACC" % acc)
              print("%.3f TPR" % tpr)
              print("%.3f TNR" % tnr)
              print("%.3f PPV" % ppv)
              print("%.3f NPV" % npv)
```

```
In [220]:
          def calc confusion matrix for threshold(ytrue N, yprobal N, thresh):
               ''' Compute the confusion matrix for a given probabilistic classif
          ier and threshold
              Args
              ytrue N : 1D array of floats
                  Each entry represents the binary value (0 or 1) of 'true' labe
          1 of one example
                  One entry per example in current dataset
              yprobal N : 1D array of floats
                  Each entry represents a probability (between 0 and 1) that cor
          rect label is positive (1)
                  One entry per example in current dataset
                  Needs to be same size as ytrue N
              thresh : float
                  Scalar threshold for converting probabilities into hard decisi
          ons
                  Calls an example "positive" if yprobal >= thresh
              Returns
              _____
              cm df : Pandas DataFrame
                  Can be printed like print(cm df) to easily display results
              cm = sklearn.metrics.confusion matrix(ytrue N, yprobal N >= thresh
          )
              cm df = pd.DataFrame(data=cm, columns=[0, 1], index=[0, 1])
              cm df.columns.name = 'Predicted'
              cm df.index.name = 'True'
              return cm df
In [221]:
          def compute perf metrics across thresholds(ytrue N, yprobal N, thresh
          grid=None):
               ''' Compute common binary classifier performance metrics across ma
          ny thresholds
              If no array of thresholds is provided, will use all 'unique' value
              in the yprobal N array to define all possible thresholds with diff
          erent performance.
              Args
              ytrue N : 1D array of floats
                  Each entry represents the binary value (0 or 1) of 'true' labe
          1 of one example
                  One entry per example in current dataset
              yprobal N : 1D array of floats
```

```
Each entry represents a probability (between 0 and 1) that cor
rect label is positive (1)
        One entry per example in current dataset
    Returns
    _____
    thresh grid : 1D array of floats
        One entry for each possible threshold
    perf dict : dict, with key, value pairs:
        * 'acc' : 1D array of accuracy values (one per threshold)
        * 'ppv' : 1D array of positive predictive values (one per thre
shold)
        * 'npv' : 1D array of negative predictive values (one per thre
shold)
        * 'tpr' : 1D array of true positive rates (one per threshold)
        * 'tnr': 1D array of true negative rates (one per threshold)
    if thresh grid is None:
        bin edges = np.linspace(0, 1.001, 21)
        thresh grid = np.sort(np.hstack([bin edges, np.unique(yprobal
N)]))
    tpr grid = np.zeros like(thresh grid)
    tnr grid = np.zeros like(thresh grid)
    ppv grid = np.zeros like(thresh grid)
    npv grid = np.zeros like(thresh grid)
    acc grid = np.zeros like(thresh grid)
    for tt, thresh in enumerate(thresh grid):
        # Apply specific threshold to convert probas into hard binary
values (0 or 1)
        # Then count number of true positives, true negatives, etc.
        # Then compute metrics like accuracy and true positive rate
        acc, tpr, tnr, ppv, npv = calc perf metrics for threshold(ytru
e N, yprobal N, thresh)
        acc grid[tt] = acc
        tpr grid[tt] = tpr
        tnr grid[tt] = tnr
        ppv grid[tt] = ppv
        npv grid[tt] = npv
    return thresh grid, dict(
        acc=acc grid,
        tpr=tpr grid,
        tnr=tnr grid,
        ppv=ppv_grid,
        npv=npv grid)
def make plot perf vs threshold(ytrue N, yprobal N, bin edges=np.linsp
ace(0, 1, 21)):
    ''' Make pretty plot of binary classifier performance as threshold
increases
```

```
Produces a plot with 3 rows:
    * top row: hist of predicted probabilities for negative examples (
shaded red)
    * middle row: hist of predicted probabilities for positive example
s (shaded blue)
    * bottom row: line plots of metrics that require hard decisions (A
CC, TPR, TNR, etc.)
    fig, axes = plt.subplots(nrows=3, ncols=1, figsize=(12, 8))
    sns.distplot(
        yprobal N[ytrue N == 0],
        color='r', bins=bin edges, kde=False, rug=True, ax=axes[0]);
    sns.distplot(
        yprobal N[ytrue N == 1],
        color='b', bins=bin edges, kde=False, rug=True, ax=axes[1]);
    thresh grid, perf grid = compute perf metrics across thresholds(yt
rue N, yprobal N)
    axes[2].plot(thresh grid, perf grid['acc'], 'k-', label='accuracy'
    axes[2].plot(thresh grid, perf grid['tpr'], 'b-', label='TPR (reca
11/sensitivity)')
    axes[2].plot(thresh grid, perf grid['tnr'], 'g-', label='TNR (spec
ificity)')
    axes[2].plot(thresh grid, perf grid['ppv'], 'c-', label='PPV (prec
ision)')
    axes[2].plot(thresh grid, perf grid['npv'], 'm-', label='NPV')
    axes[2].legend()
    axes[2].set ylim([0, 1])
```

Load the dataset.

The following should **not** be modified. After it runs, the various arrays it creates will contain the 2- or 3-feature input datasets.

```
In [222]: # Load 3 feature version of x arrays
x_tr_M3 = np.loadtxt('./data_cancer/x_train.csv', delimiter=',', skipr
ows=1)
x_va_N3 = np.loadtxt('./data_cancer/x_valid.csv', delimiter=',', skipr
ows=1)
x_te_N3 = np.loadtxt('./data_cancer/x_test.csv', delimiter=',', skipro
ws=1)

# 2 feature version of x arrays
x_tr_M2 = x_tr_M3[:, :2].copy()
x_va_N2 = x_va_N3[:, :2].copy()
x_te_N2 = x_te_N3[:, :2].copy()
```

```
In [223]: y_tr_M = np.loadtxt('./data_cancer/y_train.csv', delimiter=',', skipro
    ws=1)
    y_va_N = np.loadtxt('./data_cancer/y_valid.csv', delimiter=',', skipro
    ws=1)
    y_te_N = np.loadtxt('./data_cancer/y_test.csv', delimiter=',', skiprow
    s=1)
```

1.2: Compute the fraction of patients with cancer.

Complete the following code. Your solution needs to *compute* these values from the training, validation, and testing sets (i.e., don't simply hand-count and print the values).

```
In [224]: def computeFrac(data):
    return sum(data)/len(data)

train_frac = computeFrac(y_tr_M)
valid_frac = computeFrac(y_va_N)
test_frac = computeFrac(y_te_N)
```

```
In [225]: print("Fraction with cancer in TRAIN: %.3f" % train_frac) #TODO: modif
y what is printed here.
print("Fraction with cancer in VALID: %.3f" % valid_frac)
print("Fraction with cancer in TEST: %.3f" % test_frac)
```

```
Fraction with cancer in TRAIN: 0.141 Fraction with cancer in VALID: 0.139 Fraction with cancer in TEST: 0.139
```

1.3: The predict-0-always baseline

(a) Compute the accuracy of the always-0 classifier.

Complete the code to compute and print the accuracy of the always-0 classifier on validation and test outputs.

```
In [226]: def computeAccuracy(data=None,baseline=None):
    TP, TN, FP, FN = calc_TP_TN_FP_FN(data,baseline)
    return float((TP + TN)/(TP+TN+FP+FN))

In [227]: valid_all_zero = np.zeros(len(y_va_N))
    valid_accuracy = computeAccuracy(y_va_N,valid_all_zero)
    test_all_zero = np.zeros(len(y_te_N))
    test_accuracy = computeAccuracy(y_te_N,test_all_zero)

In [228]: print("Always-0: accuracy on VALID: %.3f" % valid_accuracy) # TODO editivalues!
    print("Always-0: accuracy on TEST: %.3f" % test_accuracy)

Always-0: accuracy on VALID: 0.861
    Always-0: accuracy on TEST: 0.861
```

(b) Print a confusion matrix for the always-0 classifier.

Add code below to generate a confusion matrix for the always-0 classifier on the validation set.

(c) Reflect on the accuracy of the always-0 classifier.

Answer: The always-0 classifier has a relatively acceptable accuracy at 86% compared to some problem like flipping coin with only 50% accuracy. But we can only treat always-0 classifier as a baseline. In reality, when we do a investigation on cancer, it is possibly that most people don't have a cancer. So compared to the it's original low cancer occurance rate, 86% accuracy is not that reliable. What's more important is, we need to focus on the group that carry cancer instead of who doesn't, and for this always-0 classifier, we can get nothing useful about the predicted true cases, so we can not calculate the Positive Predictive Value via True Positive Value and False Positive Value. And in this case, Positive Predictive Value is all we care about. So the always-0 classifier can be only treated as a baseline instead of a reliable classifier.

(d) Analyze the various costs of using the always-0 classifier.

Answer: The weakness of this classifier is that it pays more attention on the people who doesn't have cancer but ignore all the patients who have cancer. In reality, hospitals care more on the people who has cancer. From another aspects, we need False Negative as small as possible and False Positive weighs not that much. This means that we will focus more on people who diagnosed with cancer even it is not accurate, but we don't want those who have cancer but not detected because a person's life is invaluable. But this classifier only focus on the average accuracy and in reality this classifier is worse than a always-1 classifier even always-1 classifier only got 14% accuracy but it will not ignore any single life.

1.4: Logistic Regression

(a) Create a set of LogisticRegression models.

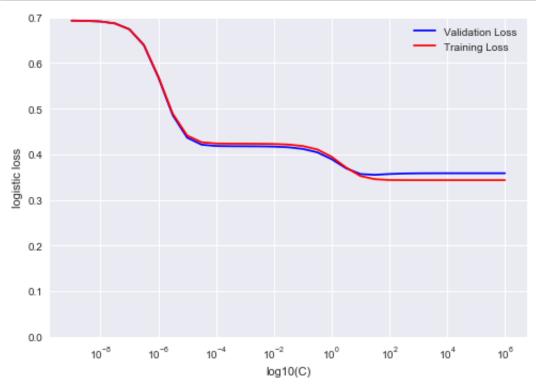
Each model will use a different control parameter, c, and each will be fit to 2-feature data. Probabilistic predictions will be made on both training set and validation set inputs, and logistic-loss for each will be recorded.

```
In [230]: from sklearn.linear_model import LogisticRegression
          tr loss list 2 = list()
          va loss list 2 = list()
          # TODO fit, predict proba, and evaluate logistic loss
          # Record the best model here
          def loss detection(C,x_tr,y_tr,x_va,y_va):
              LRM = LogisticRegression(C=C, solver='liblinear').fit(x_tr, y_tr)
              pred tr = LRM.predict proba(x tr)
              pred va = LRM.predict proba(x va)
              return sklearn.metrics.log_loss(y_tr,pred_tr),sklearn.metrics.log_
          loss(y va,pred va)
In [231]: C \text{ grid} = \text{np.logspace}(-9, 6, 31)
          for C in C grid:
              tr loss,va loss = loss detection(C,x_tr_M2,y_tr_M,x_va_N2,y_va_N)
              tr loss list 2.append(tr loss)
              va loss list 2.append(va loss)
```

Plot logistic loss (y-axis) vs. C (x-axis) on the training set and validation set.

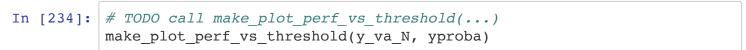
The best values for C and the loss should be printed.

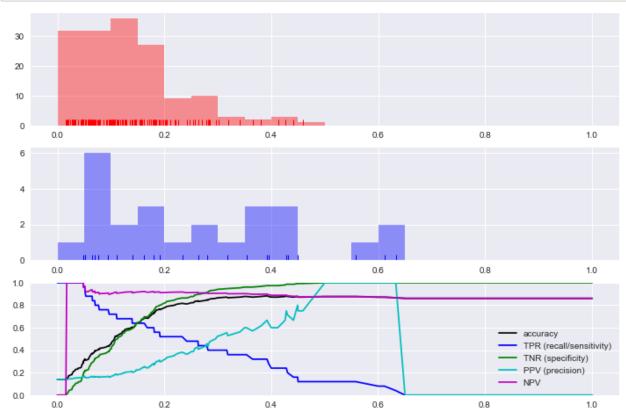
```
In [232]:
          # TODO make plot
          plt.xscale('log')
          plt.xlabel('log10(C)')
          plt.ylabel('logistic loss')
          plt.plot(C_grid, va_loss_list_2, color='blue', label = "Validation Loss"
          plt.plot(C grid,tr loss list 2, color='red',label = "Training Loss")
          plt.ylim([0.0, 0.7]);
          # TODO add legend
          # plt.legend(...);
          plt.legend()
          plt.show()
          print("Best C-value for LR with 2-feature data: %.3f" % C grid[np.argm
          in(va loss list 2)]) # TODO
          print("Validation set log-loss at best C-value: %.4f" % min(va loss li
          st 2))
```



Best C-value for LR with 2-feature data: 31.623 Validation set log-loss at best C-value: 0.3549

(b) Plot the performance of the predictions made by the best classifier from step (a) on the validation set.





(c) Model fitting with 3-feature data

Repeat the model generation from **1.4 (a)**, using the full 3-feature data.

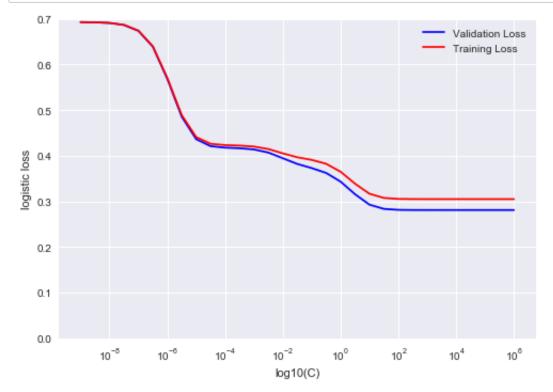
```
In [235]: # TODO like 1.4 (a), but with 3 features
    tr_loss_list_3 = list()
    va_loss_list_3 = list()
    C_grid = np.logspace(-9, 6, 31)
    for C in C_grid:
        tr_loss,va_loss = loss_detection(C,x_tr_M3,y_tr_M,x_va_N3,y_va_N)
        tr_loss_list_3.append(tr_loss)
        va_loss_list_3.append(va_loss)
```

Plot logistic loss (y-axis) vs. C (x-axis) for the 3-feature classifiers on the training set and validation set.

Again, the best values for C and the loss should be printed.

```
In [236]: # TODO make plot
   plt.xscale('log')
   plt.xlabel('log10(C)')
   plt.ylabel('logistic loss')
   plt.plot(C_grid,va_loss_list_3, color='blue',label = "Validation Loss")
   plt.plot(C_grid,tr_loss_list_3, color='red',label = "Training Loss")
   plt.ylim([0.0, 0.7]);

# TODO add legend
   # plt.legend(...);
   plt.legend()
   plt.show()
   print("Best C-value for LR with 2-feature data: %.3f" % C_grid[np.argm in(va_loss_list_3)]) # TODO
   print("Validation set log-loss at best C-value: %.4f" % min(va_loss_list_3))
```



Best C-value for LR with 2-feature data: 1000000.000 Validation set log-loss at best C-value: 0.2810

Plot the performance of the predictions made by the best 3-valued classifier on the validation set.

```
In [237]:
            # TODO call make plot perf vs threshold(...)
            best C 3 = C grid[np.argmin(va_loss_list_3)]
            LRM = LogisticRegression(C=best C 3,solver='liblinear').fit(x tr M3, y
            yproba = LRM.predict proba(x va N3)[:,1]
            make_plot_perf_vs_threshold(y_va_N, yproba)
             40
             20
              0
                  0.0
                                 0.2
                                               0.4
                                                              0.6
                                                                            0.8
                                                                                           1.0
              4
              3
              2
              1
              0
                  0.0
                                 0.2
                                               0.4
                                                              0.6
                                                                            0.8
                                                                                           1.0
             1.0
             0.8
                                                                                  TPR (recall/sensitivity)
             0.6
```

1.5: ROC Curves

0.4

0.0

These curves allow us to compare model performance in terms of trade-offs between false positive and true positive results.

0.4

(a) Plot ROC curves on the validation set.

There should be two curves in the plot, one for each of the best two classifiers from prior steps.

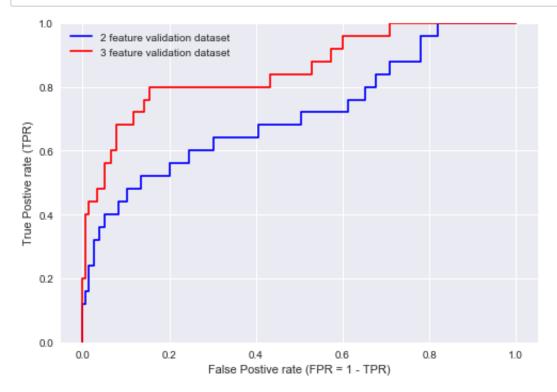
0.2

TNR (specificity)

PPV (precision)

```
In [239]: # TODO something like: fpr, tpr, thr = sklearn.metrics.roc_curve(...)

plt.ylim([0, 1]);
plt.plot(fpr_va_2,tpr_va_2, color='blue',label = "2 feature validation dataset")
plt.plot(fpr_va_3,tpr_va_3, color='red',label = "3 feature validation dataset")
plt.xlabel("False Postive rate (FPR = 1 - TPR)");
plt.ylabel("True Postive rate (TPR)");
plt.legend()
plt.show()
```

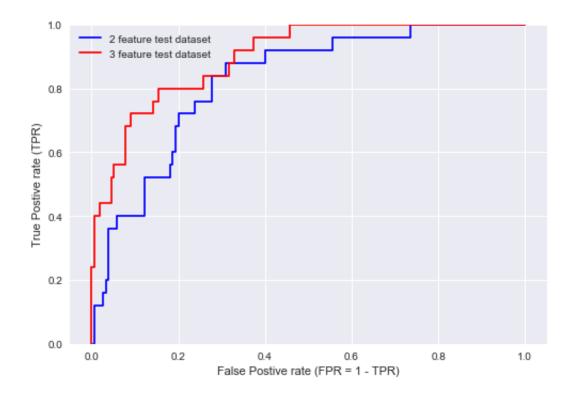


(b) Plot ROC curves on the test set.

There should be two curves in the plot, one for each of the best two classifiers from prior steps.

```
In [241]: # TODO something like: fpr, tpr, thr = sklearn.metrics.roc_curve(...)

plt.ylim([0, 1]);
plt.plot(fpr_te_2,tpr_te_2, color='blue',label = "2 feature test datas et")
plt.plot(fpr_te_3,tpr_te_3, color='red',label = "3 feature test datase t")
plt.xlabel("False Postive rate (FPR = 1 - TPR)");
plt.ylabel("True Postive rate (TPR)");
plt.legend()
plt.show()
```



(c) Analyze the results shown in both the above plots, to compare classifier performance.

Answer: For most situation 3 features classifier performs better than 2 features classifier in both testing dataset and validation dataset. The performance of a classifier in AUC depends on the area of its line intersects with line y = 0 and line x = 1, as we can see from two plots, red line's area stands for 3 features has a bigger area than blue line's area. So 3 features classifier performs better than 2 features classifier.

1.6: Selecting a decision threshold

(a) Using default 0.5 threshold.

Generate a confusion matrix for the best 3-feature logistic model on the test set, using threshold 0.5.

```
In [258]:
          best thr = 0.5
          LRM = LogisticRegression(C=best_C_3,solver='liblinear').fit(x_tr_M3, y
          ypred te 3 = LRM.predict(x te N3)
          print("ON THE VALIDATION SET:")
          print("Chosen best thr = %.4f" % best thr)
          print("")
          print("ON THE TEST SET:")
          print(calc confusion matrix for threshold(y te N,ypred te 3,best thr))
          # TODO: print(calc confusion matrix for threshold(...))
          print("")
          print_perf_metrics_for_threshold(y_te_N, ypred_te_3, best_thr)
          # TODO: print(print perf metrics for threshold(...))
          ON THE VALIDATION SET:
          Chosen best thr = 0.5000
          ON THE TEST SET:
          Predicted
                       0
                            1
          True
          0
                     152
                            3
          1
                       15
                           10
          0.900 ACC
          0.400 TPR
          0.981 TNR
          0.769 PPV
          0.910 NPV
```

(b) Pick a threshold to maximize TPR, while ensuring PPV >= 0.98.

After finding the best threshold on the validation set, plot its confusion matrix and print its various performance metrics, for the test set.

```
In [259]: LRM = LogisticRegression(C=best C 3, solver='liblinear').fit(x tr M3, y
          _tr_M)
          yproba_va_3 = LRM.predict_proba(x_va_N3)[:,1]
          thresh_grid, perf_grid = compute_perf_metrics_across_thresholds(y_va_N
          , yproba_va_3, thresh_grid=None)
          yproba te 3 = LRM.predict proba(x te N3)[:,1]
          def bestSatisfiedTPR(perf grid,ppv):
              tmp = perf grid['tpr'].copy()
              if (max(perf_grid['ppv']) < ppv):</pre>
                  print ("no threshold satisfied!")
                  return
              while True:
                  index = np.argmax(tmp)
                  if perf grid['ppv'][index] >= ppv:
                       return index
                  else:
                       tmp[index] = 0
          best thr index = bestSatisfiedTPR(perf grid, 0.98)
          best thr = thresh grid[best thr index]
```

```
In [260]: # TODO thresh grid, perf grid = compute perf metrics across thresholds
          (...)
          # TODO Find threshold that makes TPR as large as possible, while satis
          fying PPV >= 0.98
          print("ON THE VALIDATION SET:")
          print("Chosen best thr = %.4f" % best thr)
          print("")
          print("ON THE TEST SET:")
          print(calc confusion matrix for threshold(y te N,yproba te 3,best thr)
          # TODO: print(calc confusion matrix for threshold(...))
          print("")
          print_perf_metrics_for_threshold(y_te_N, yproba te 3, best thr)
          # TODO: print(print perf metrics for threshold(...))
          ON THE VALIDATION SET:
          Chosen best thr = 0.6290
          ON THE TEST SET:
          Predicted
                      0 1
          True
          0
                     155
                         0
          1
                      20 5
          0.889 ACC
          0.200 TPR
          1.000 TNR
          1.000 PPV
          0.886 NPV
```

(c) Pick a threshold to maximize PPV, while ensuring TPR >= 0.98.

After finding the best threshold on the validation set, plot its confusion matrix and print its various performance metrics, for the test set.

```
In [261]: LRM = LogisticRegression(C=best C 3, solver='liblinear').fit(x tr M3, y
          _tr_M)
          yproba_va_3 = LRM.predict_proba(x_va_N3)[:,1]
          thresh_grid, perf_grid = compute_perf_metrics_across_thresholds(y_va_N
          , yproba_va 3)
          yproba te 3 = LRM.predict proba(x te N3)[:,1]
          def bestSatisfiedPPV(perf grid,tpr):
              if (max(perf grid['tpr']) < tpr):</pre>
                  print ("no threshold satisfied!")
                  return
              tmp = perf_grid['ppv'].copy()
              while True:
                  index = np.argmax(tmp)
                  if perf grid['tpr'][index] >= tpr:
                       return index
                  else:
                      tmp[index] = 0
          best thr index = bestSatisfiedPPV(perf grid, 0.98)
          best thr = thresh grid[best thr index]
```

```
In [262]: # TODO thresh grid, perf grid = compute perf metrics across thresholds
          (...)
          # TODO Find threshold that makes PPV as large as possible, while satis
          fying TPR >= 0.98
          print("ON THE VALIDATION SET:")
          print("Chosen best thr = %.4f" % best_thr) # TODO
          print("")
          print("ON THE TEST SET:")
          # TODO: print(calc confusion matrix for threshold(...))
          print(calc confusion matrix for threshold(y te N,yproba te 3,best thr)
          )
          print("")
          # TODO: print(print perf metrics for threshold(...))
          print perf metrics for threshold(y te N, yproba te 3, best thr)
          ON THE VALIDATION SET:
          Chosen best thr = 0.0300
          ON THE TEST SET:
          Predicted 0 1
          True
                     57 98
          0
          1
                      0 25
          0.456 ACC
          1.000 TPR
          0.368 TNR
          0.203 PPV
          1.000 NPV
```

(d) Compare the confusion matrices from (a)–(c) to analyze the different thresholds.

Answer: From previous discussion, we conclude that we will pay more attention on reducint the False Negative Value since we cannot ignore those who have cancer. Among the TPR,TNR,PPV,NPV, we will focus more on TPR. Since TPR = TP/(TP + FP), with greater TPR, we can guarantee less amount of False Negative Values. So let's analyze three different model with different thresholds.\ Thresholds = 0.5: This model has a relatively good accuracy as 90%, but the TPR with 40% is too small, which means among all the people have cancer in real life, most of them are not detected. So if the hospital pays more attention on the diagnosis's correctness of cancer, then this model is not suitable for use in real life.\ Thresholds = 0.629: Compared to the first model, this model has a similar accuracy but with less TPR, since the first model is no longer useful in real life, this model is much worse. The high PPV stands for the accuracy of those detected as cancer are correctly labeled. This is important as well in real life, but as an exchange, this model ignored the one who have cancer but not detected, which is not reliable. \ Thresholds = 0.03 This model has a perfect TPR as we required, which means that we won't ignore any single person who has a cancer, which is great. But the problem is the accuracy is not ideal. The 45.6% accuracy may seems not very reliable in detecting cancer, an always-0 classifier has 86.1% accuracy. But the advantage of this model is that it will not neglect any patients who could have cancer. And compared to a always-1 classifier with 13.9% accuracy, this one works better.

(e) How many biopsies can be avoided using the best threshold for the classifier?

Answer: Suppose we choose thresholds = 0.03 as our best thresholds, and we can guarantee that all the patients have cancer in real life won't be ignored, than we can avoid biopsies on all the patients with prediction value of False, which is 57. If we choose thresholds = 0.5 or 0.629, we can avoid 167 or 175 biopsies, but some patients with cancer can also be ignored as well.

Part Two: Decision Trees

You should start by computing the two heuristic values for the toy data described in the assignment handout. You should then load the two versions of the abalone data, compute the two heuristic values on features (for the simplified data), and then build decision trees for each set of data.

2.1 Compute both heuristics for toy data.

(a) Compute the counting-based heuristic, and order the features by it.

```
In [247]: # TODO
          attr_A = np.array([[1,1],[0,0,0,0,1,1]])
          attr_B = np.array([[1,1,1,0],[1,0,0,0]])
          def countingBased(feature, attr, labels=2):
              totalVal = 0.0
              mojority = 0.0
              for l in attr:
                   d = dict() #dictionary is used to store the number of labels i
          n each attribute, decide the majority
                   for i in range(labels):
                       d[i] = 0
                   if labels == 2:
                       mojority += max(sum(1), len(1) - sum(1))
                  else:
                       for label in 1:
                           d[label] += 1
                      mojority += max(d[_] for _ in d)
                   totalVal += len(1)
              print(feature + ": "+ str(int(mojority)) +"/" + str(int(totalVal))
          )
          countingBased("A", attr A)
          countingBased("B", attr_B)
```

A: 6/8 B: 6/8

(b) Compute the information-theoretic heuristic, and order the features by it.

```
In [248]:
          # TODO
          def calEntropy(num):
              if num == 0:
                   return 0
              return (-1) * num * np.log2(num)
          def infoTheory(feature, attr, labels=2):
              totalNumberOfVal = 0
              total trueVal = 0
              reminder = 0
              d total = \{\}
              for l in attr:
                   totalNumberOfVal += len(1)
                   for value in 1:
                       if value in d total:
                           d total[value] += 1
                       else:
                           d total[value] = 1
              TotalAverage = 0.0
               for key in d_total.keys():
                   labelPossibility = d total[key] / totalNumberOfVal
                   TotalAverage += calEntropy(labelPossibility)
               for 1 in attr:
                   posibility = len(l) / totalNumberOfVal
                   sub label = {}
                   for value in 1:
                       if value in sub label:
                           sub label[value] += 1
                       else:
                           sub label[value] = 1
                   for key in sub label.keys():
                       sub label posibility = sub label[key] / len(1)
                       reminder += posibility * calEntropy(sub label posibility)
               gain = TotalAverage - reminder
              print (feature + ": " + str(gain))
          infoTheory("A", attr A)
          infoTheory("B", attr_B)
```

A: 0.31127812445913283 B: 0.18872187554086706

(c) Discussion of results.

Typically the counting-based heuristic is based on the mojority from each branch, in this method we will treat each leaf equally. As for feature A, when we apply with counting-based heurisitic, we can see that the left branch weighs can convey more information than right branch. But when computing the results, the useful information brought by left branch get balanced by the right branch.\ Information-theoretic heuristic, however, can help us detect the really useful branch that conveys more information. After the computation of feature A and B, we can see that A weighs more than B, which makes more sense since the left branch of A can help excluding some data while B cannot do in either its branch. \ In real life, counting-based heuristic is easier to implemented but not as accurate as information-theoretic heuristic. Basically information-theoretic heuristic stands for the entropy of the information, which exaclty satisfied our requirment for finding the most "useful" information in building a decision tree.

2.2 Compute both heuristics for simplified abalone data.

(a) Compute the counting-based heuristic, and order the features by it.

```
In [249]: #TODO
    small_tr_x = np.loadtxt('./data_abalone/small_binary_x_train.csv', del
    imiter=',', skiprows=1)
    small_te_x = np.loadtxt('./data_abalone/small_binary_x_test.csv', deli
    miter=',', skiprows=1)
    small_tr_y = np.loadtxt('./data_abalone/3class_y_train.csv', delimiter
    =',', skiprows=1)
    small_te_y = np.loadtxt('./data_abalone/3class_y_test.csv', delimiter=
    ',', skiprows=1)
```

```
In [250]:
          import csv
          small reader = csv.reader(open('./data abalone/small binary x train.cs
          v','rt'))
          small headers = next(small reader)
          all_reader = csv.reader(open('./data_abalone/x_train.csv','rt'))
          all headers = next(all reader)
          for i in range(len(small headers)):
              attr = []
              trueList = []
              falseList = []
              for index, value in enumerate(small tr x[:,i].transpose()):
                  if value == 0:
                      falseList.append(small tr y[index])
                  else:
                      trueList.append(small tr y[index])
              attr.append(trueList)
              attr.append(falseList)
              feature = small headers[i]
              countingBased(feature, attr,3)
```

is_male: 1864/3176 length_mm: 2230/3176 diam_mm: 2266/3176 height mm: 2316/3176

(b) Compute the information-theoretic heuristic, and order the features by it.

```
In [251]: # TODO
for i in range(len(headers)):
    attr = []
    trueList = []
    falseList = []
    for index, value in enumerate(small_tr_x[:,i].transpose()):
        if value == 0:
            falseList.append(small_tr_y[index])
        else:
            trueList.append(small_tr_y[index])
        attr.append(trueList)
        attr.append(falseList)
        feature = headers[i]
        infoTheory(feature,attr,3)
```

is_male: 0.02451648227175207 length_mm: 0.13543816377043694 diam_mm: 0.1500706886802703 height mm: 0.17302867291002488

2.3 Generate decision trees for full- and restricted-feature data

(a) Print accuracy values and generate tree images.

```
all tr x = np.loadtxt('./data abalone/x train.csv', delimiter=',', ski
In [252]:
          prows=1)
          all te x = np.loadtxt('./data abalone/x test.csv', delimiter=',', skip
          rows=1)
          all tr y = np.loadtxt('./data abalone/y train.csv', delimiter=',', ski
          prows=1)
          all te y = np.loadtxt('./data abalone/y test.csv', delimiter=',', skip
          rows=1)
          # TODO
In [253]:
          DTM Small = sklearn.tree.DecisionTreeClassifier(criterion = 'entropy')
          DTM_Small = DTM_Small.fit(small tr x,small tr y)
          score te small = DTM Small.score(small te x,small te y)
          score tr small = DTM Small.score(small tr x,small tr y)
          print ("Accuracy in testing data set is: %.4f"%score te small)
          print ("Accuracy in training data set is: %.4f"%score tr small)
          #sklearn.tree.plot tree(DTM Small)
          dot data = sklearn.tree.export graphviz(DTM Small,out file=None, featur
```

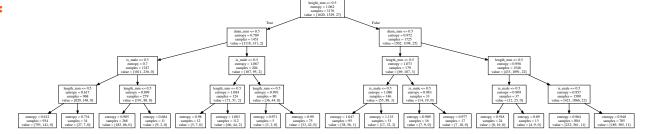
Accuracy in testing data set is: 0.7220 Accuracy in training data set is: 0.7327

graph = graphviz.Source(dot_data)
graph.render("simplified dataset")

e names = small headers)

graph

Out[253]:



```
In [254]:
          # TODO
          DTM All = sklearn.tree.DecisionTreeClassifier(criterion = 'entropy')
          DTM All.fit(all tr x,all tr y)
          score te all = DTM All.score(all te x,all te y)
          score tr all = DTM All.score(all tr x,all tr y)
          print ("Accuracy in testing data set is: %.4f"%score te all)
          print ("Accuracy in training data set is: %.4f"%score tr all)
          dot data = sklearn.tree.export graphviz(DTM_All,out_file=None,feature_
          names = all headers)
          graph = graphviz.Source(dot data)
          graph.render("full dataset")
          Accuracy in testing data set is: 0.1900
          Accuracy in training data set is: 1.0000
Out[254]: 'full dataset.pdf'
In [255]:
          graph
Out[255]:
```

(b) Discuss the results seen for the two trees:

Answer: As we can see from two decision trees, the former one with 4 features composed of simplified binary numbers is much smaller than the one with 8 features and all of float numbers. By giving more features with detailed data helps raise the accuracy of training dataset. But we can see that the testing accuracy is declined. This is called the overfitting problem, if we fill the model with all the features via all detailed data, then this will lead to an overfitting problem like we met before in linear regression model. \ So the first tree performs better than the second overfitting tree, and the cause of the overfitting is that there eixsts too much detailed features which leads to the number of leaves and depths of the tree much bigger than expected. When we have so much branches and leaves, the overffiting problem occurs, but we can avoid this by pruning some branches just like the first tree does.