Chapter3Heuristic Search Techniques

(Cont....)

- ☐ It is an algorithm which helps us reach a global optimum of a multi-dimensional function despite the presence of several hills and valleys
- ☐ It is evolutionary in the sense that unlike traditional optimization techniques like random walk or hill climbing it will not get stuck at a local maximum
- Imagine you are standing in a place and you need to reach the highest point. you can look around you and if you see a place with a higher height than the ground you are standing, you move to that place, keep repeating this and you eventually reach a point where you cannot see a higher point. This technique is called hill climbing

- □ Problem: You might not be standing at the highest point, and you might not be able to see a higher point from where you are standing. you might have been able to observe a higher point if you where standing at some other point
- ☐ Simulated annealing takes the risk of occasionally moving to a lower point so that the chances of missing out on seeing a higher point are reduced
- ☐ Initially it is willing to take risks of jumping to lower points, however as time passes, it is less willing to jump to lower point and eventually terminates
- ☐ This idea lower the chances of getting caught at local maxima, plateau or ridge

☐ Change in terminology:

heuristic function → objective function

Goal: Minimize objective function value

☐ Process of valley descending rather than hill climbing

Annealing

☐ Physical substances such as metals are melted (raised to high temperature-energy levels) and then gradually cooled until some solid state is reached

Goal: produce minimal energy state

Physical substances usually move from higher energy configurations to lower ones, so the valley descending occurs naturally

☐ But, there is some probability that a transition to a higher energy state will occur

$$\mathbf{P} = \mathbf{e}^{-(-\delta \mathbf{E} / kt)}$$

Where,

δE: Change in energy level

T: Temperature

k: Boltzmann's constant

☐ Probability that an uphill move will be made, decreases as the temp decreases

T: 10,000	99.99990%
1000	99.9905%
100	99.99000%
10	90.04%
5	81.87%
3	71.89%
2	60.65%
1	36.78%

☐ Moves are more likely during the beginning of the process when the temperature is high and they become less likely at the end, as the temperature becomes less

Downhill moves → anytime

Upward moves→ **during initial time**

- ☐ Annealing Schedule:
 - Rate at which the system is cooled
- ☐ Metal heated to a sufficiently high temperature and all we want to do is cool the metal down
- ☐ Cooling can be done by two approaches
 - Hastily approach
 - Gradual approach
- ☐ These properties of physical annealing can be used to define an analogous process of simulated annealing

- ☐ In analogous process.....
- \Box δE is the change in the value of objective function
- □ k describes the correspondence between the units of temperature & unit of energy E & T are artificial, we drop 'k'

$$\mathbf{p'} = \mathbf{e}^{-(-\delta \mathbf{E}/kt)}$$

□ Need to choose a schedule of value T

- **☐** How Simulated Annealing is different than Hill Climbing?
 - The annealing schedule must be maintained
 - Move to worst/bad/poor states may be accepted
 - Maintains state 'best state found so far'

Relationship between Physical Annealing and Simulated Annealing

Thermodynamic	Combinatorial
Simulation	Optimisation
System States	Feasible Solutions
Energy	Cost
Change of State	Neighbouring Solutions
T	
Temperature	Control Parameter
Frozen State	Heuristic Solution

Algorithm:

- 1. Evaluate the initial state: If it is also a goal state, return it and quit. otherwise continue with initial state as current state
- 2. Initialize BEST-SO-FAR to the current state
- 3. Initialize 'T' according to annealing schedule
- 4. Loop until a solution is found or until there are no new operators left to be applied in the current state
 - a) Select an operator that has not yet been applied to the current state and apply it to produce a new state
 - b) Evaluate the new state

 $\delta E = (Value of current) - (Value of new state)$

- If the new state is goal state, return it & quit
- else if it is better than current state, make it the current state also set BEST-SO-FAR to this new state
- If it is not better than current state, then make it the current state with probability p'
- c) Revise T as necessary according to annealing schedule
- 5. Return BEST-SO-FAR as the answer

Application of Simulated Annealing

- ☐ To solve problems in which the number of moves from a given state is very large [More permutations/combinations]
 - Job scheduling
 - Time table management
 - **■** TSP, etc...