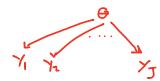
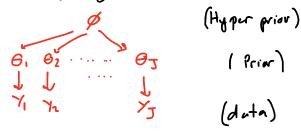
We've been considering the settings where

$$\begin{array}{ccccc} \lambda^{1} & \lambda^{2} & & \lambda^{2} \\ \uparrow & \uparrow & & \ddots & & \uparrow \\ \vdots & \vdots & \ddots & \ddots & & \lambda^{2} \end{array}$$



Is there an inbetween? Hierarchy



Two main advantagons

1. Berrowing of strongth Oily depends on full data set

2. More flexibility in modeling uncertainty - inharited from &

This representation makes it simpler to sample from posterior.

(iii) [For post pred.]
$$\tilde{Y} \sim \mathbb{P}(Y|\theta=\theta^s)$$

$$V_{ij} \setminus \Theta_{i} \stackrel{\text{ind}}{\sim} N(\Theta_{i}, \sigma^{2})$$
 known

Frequentist:
$$\hat{\theta}_{j}^{(i)} = \overline{Y}_{j}$$
 $\hat{\theta}_{j}^{(2)} = \frac{1}{5} \sum_{j=1}^{m} \overline{Y}_{,j} = \frac{\overline{Y}_{,j}}{\overline{Z}_{,j}^{(2)}} = \frac{\overline{Y}_{,j}}{\overline{Z}_{,j}^{(2)}}$

Common approach is to them test

However we could want weighted means

$$\hat{\Theta}_{j} = \lambda_{j} \hat{\Theta}_{j}^{(i)} + (1 - \lambda_{j}) \hat{\Theta}_{j}^{(2)}$$

Consider the hierachial model

$$\varphi = (\mu, \tau^2)$$

$$\varphi = (\mu,$$

From this the full posterior is then

$$\begin{split} \mathbb{P}(\theta, \phi | \gamma) & \propto \mathbb{P}(\gamma | \theta) \, \mathbb{P}(\theta | \mu, \tau) \, \mathbb{P}(\mu, \tau^2) \\ & \propto \prod_{j=1}^{J} \, \mathbb{N}(\overline{\gamma_{\cdot j}} | \theta_{j, \sigma_{j}^2}) \, \mathbb{N}(\theta_{j} | \mu, \tau^2) \, \mathbb{P}(\mu | \tau^2) \, \mathbb{P}(\tau^2) \end{split}$$

For partial conjugacy letisset MlT2~ N/Mo, T/ki)

Still need to understand

(3) P(22/y)

Rmk: Useful fact: XIB~N(B,02) B~N(B., Z2)

(i)
$$\times \sim N(\theta_0, \sigma^2 + \tau^2)$$

(i)
$$\Theta \mid \times \sim N \left(\frac{\chi/\sigma^2 + \theta_0/\tau^2}{1/\sigma^2 + 1/\tau^2}, \frac{1}{\gamma/\sigma^2 + 1/\tau^2} \right)$$

(1)
$$P(\theta_j \mid M, \tau^2, \gamma) \propto N(\overline{\gamma_{ij}} \mid \theta_j, \sigma_j^2) N(\theta_j \mid M, \tau^2)$$

$$\sqrt{\frac{\sqrt{\frac{y_{.j}}{o_{j}^{2} + \frac{m}{\tau^{2}}}}{\frac{y_{o_{j}^{2} + \frac{m}{\tau^{2}}}{1 + \frac{m}{\tau^{2}}}} } } \frac{1}{\sqrt{\frac{y_{o_{j}^{2} + \frac{m}{\tau^{2}}}{1 + \frac{m}{\tau^{2}}}}}$$

$$\equiv N \left(\hat{\Theta}_{j}, v_{j} \right)$$

$$\frac{1}{1-1} \int N(\bar{x}_{j} | \theta_{j}, \sigma^{2}) P(\theta_{j} | \mu, z^{2}) d\theta_{j} P(\mu | z^{2}) d\theta_{j} P(\mu | z^{2})$$

$$\frac{1}{1-1} \int N(\bar{x}_{j} | \theta_{j}, \sigma^{2}) P(\theta_{j} | \mu, z^{2}) d\theta_{j} P(\mu | z^{2})$$

note

$$M \mid \overline{Y}_{1}, \tau^{2} \sim N \left(\frac{\overline{Y}_{1} / \sigma_{j}^{2} + \tau^{2} + \frac{N_{0} / \tau^{2} / k_{0})}{\frac{1}{\sigma_{j}^{2} + \tau^{2}} + \frac{k_{0}}{\tau^{2}}} \right) \frac{1}{\sigma_{j}^{2} + \tau^{2} + \frac{k_{0}}{\tau^{2}}} \right)$$

Iteratively updating

$$\mathcal{N} \mid \tau^{2}, \mathcal{V} \sim \mathcal{N} \left(\hat{\mathcal{N}} = \frac{\sum_{j} \left(\overline{\mathcal{I}_{j}} / \sigma_{j}^{2} + \tau^{2} \right) + \frac{\mathcal{N}_{0} k_{0}}{\tau^{2}}}{\sum_{j} \frac{1}{\sigma_{j}^{2} + \tau^{2}} + \frac{k_{0}}{\tau^{2}}} \right) \hat{\mathcal{V}} = \frac{1}{\sum_{j} \frac{1}{\sigma_{j}^{2} + \tau^{2}} + \frac{k_{0}}{\tau^{2}}} \right)$$

(s)
$$P(\tau^2|y) = \int P(\mu, \tau^2|y) d\mu$$

-> Need numerical methods has.