

Note: when iterating between (α, β)
to find Gamma MLE, we
store $\Theta = \begin{pmatrix} \alpha \\ \beta \end{pmatrix}$

- Newton update is

$$\Theta^{(t+1)} = [\ell''(\Theta)]^{-1} \ell'(\Theta^{(t)})$$

- Advantage because we can
just compute at same time
you can get information $I(\theta)$

- Also gain the covariance matrix
 α, β

Expectation Maximization

• We've seen that we can use
a maximum likelihood criterion to
estimate Θ

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sometimes part of our data is latent - we don't know what z is and we have to estimate θ by using the information in it

Eg: Missing data in linear regression

Ideally we would like

$$L(\theta; x) = P(x; \theta) = \int P(x, z; \theta) dz$$

and then use MLE estimation as we did before

$$P(x, z; \theta) = L(\theta; \underbrace{x}_{\text{obs. data}}, \underbrace{z}_{\text{Missing}})$$

Complete data likelihood.

- But this is usually hard
- Alternatively we can use the

iterative procedure EM

E-Step: $Q(\theta; \theta^{(t)}) = \mathbb{E}_{z|x; \theta = \theta^{(t)}} [\ell(\theta; x, z)]$

M-Step: $\theta^{(t+1)} = \arg \max_{\theta} Q(\theta; \theta^{(t)})$

Ex: $x, z \sim \text{iid } \text{Exp}(\lambda)$ z missing

$$\ell(\theta; x, z) = \log f(x, z; \theta)$$

$$= \log f(x; \theta) f(z; \theta)$$

$$= \log f(x; \theta) + \log f(z; \theta)$$

$$= \ell(\theta; x) + \ell(\theta; z)$$

$$= 2 \log(\lambda) - \lambda x - \lambda z$$

$$\boxed{\mathbb{E}} \quad Q(\lambda, \lambda^{(t)}) = \mathbb{E}_{z|x, \lambda^{(t)}} (\ell(\lambda; x, z))$$

$$= 2 \log(\lambda) - \lambda x - \lambda \mathbb{E}_{z|x, \lambda^{(t)}}(z)$$

$$= 2 \log(\lambda) - \lambda x - \frac{\lambda}{\lambda^{(t)}}$$

$$\boxed{M} \quad Q'(\lambda^{(t+1)}, \lambda^{(t)}) = \frac{2}{\lambda^{(t+1)}} - x - \frac{1}{\lambda^{(t)}} = 0$$

$$\lambda^{(t+1)} = \frac{2}{x + \frac{1}{\lambda^{(t)}}}$$

Fixed Point Analysis

$$(\lambda^{(t)} \rightarrow \hat{\lambda}) \quad \frac{2}{\hat{\lambda}} - x - \frac{1}{\hat{\lambda}} = 0$$

$$\hat{\lambda} = \frac{1}{x} = \hat{\lambda}_{MLE}$$

Ex: $X_1, \dots, X_n, Z_1, \dots, Z_m \sim \text{iid Exp}(\lambda)$

but we only observe X_i $Y_i = \{Z_i > T\}$

$$\ell(\lambda; x, y, z) = \sum_{i=1}^n (\log(\lambda) - \lambda x_i)$$

$$+ \sum_{j=1}^m (\log \lambda - \lambda z_j)$$

$$\boxed{\text{E}} \quad Q(\lambda, \lambda^{(t)}) = \mathbb{E}_{z|x, y, \lambda^{(t)}} (\log(\lambda; x, y, z))$$

$$= n \log \lambda - n \lambda \bar{x} + m \log \lambda$$

$$- \lambda \sum_{i=1}^m \mathbb{E}_{z|x, y, \lambda^{(t)}} (z_j)$$

$$\mathbb{E}_{z|y, \lambda^{(t)}} (z_j) = \mathbb{E}_{\lambda^{(t)}} (z_j \mid z_j \geq T)$$

$$= T + \frac{1}{\lambda^{(t)}}$$

\implies

$$= (n+m) \log(\lambda) - \lambda n \bar{x} - \lambda m \left(T + \frac{1}{\lambda^{(t)}} \right)$$

$$\boxed{\text{M}} \quad Q'(\lambda^{(t+1)}, \lambda^{(t)}) = C$$

$$\frac{n+m}{\lambda} - n \bar{x} - m \left(T + \frac{1}{\lambda} \right) = n$$

$\lambda^{(t+1)}$ $\lambda^{(t)}$

$$\lambda^{(t+1)} = \frac{n+m}{n\bar{x} + m(1 + \frac{1}{\lambda^{(t)}})}$$

Again with fixed point analysis

$$\hat{\lambda} = \frac{m+n}{n\bar{x} + m(T + \frac{1}{\hat{\lambda}})} \Rightarrow \hat{\lambda} = \frac{n}{n\bar{x} + mT}$$