## Outlier Detection

Need to estimate 
$$\hat{e}_i = \frac{Y_i - x_i T \hat{b}}{\hat{\sigma}} \rightarrow N(0.1)$$
if good
estimates

Should be rave to see |êi | >2 so detect outliars with the rule

$$\left|\frac{y_{i-x_{i}}T\hat{\beta}}{\hat{\sigma}}\right| > K_{\alpha} \quad \text{for} \quad K_{\alpha} = -\mathbb{E}(\alpha/2)$$

In the Bayesian paradigm BIY, 07 - N(\$, Ip)

Let's assume for simplicity P(P,02) & 1

$$\beta | \sigma^2, \forall \sim N \left( \hat{\beta}_{MLE}, \sigma^2 \left( \vec{X}^{\dagger} \vec{X} \right)^{-1} \right)$$

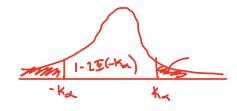
$$o^{2} | Y - I_{NV} - \chi^{2} (n-p), \frac{RSS(\hat{\rho}_{MLS})}{n-p} = I_{NV} - \chi^{2} (n-p), \hat{\sigma}_{MLE}^{2}$$

With this, it makes senere to discuss

With this we can calculate P( X -xiT) = Ka (Y) will do this numerically.

We will need a multiple test correction.

Let p(ka) = prob of being an outdir the we want



Finally, we can use this for model checking.

$$Y-X\beta \mid \sigma^2, Y - N(Y-X\beta, \sigma^2 \underbrace{\chi(x^Tx)^{-1}\chi^T})$$

H may be rank deficent; 
$$X = QR$$
,  $\hat{\beta} = (x^Tx)^{-1} x^Ty$ 

$$= (R^T G^T GR)^{-1} R^T G^T Y$$

$$= R^{-1} R^{-1} R^T G^T Y$$

$$\Rightarrow R \hat{\beta} = Q^T Y \qquad \text{numerically}$$

$$\text{stable}$$
to find  $\hat{\beta}$ 

$$Q^{T}(Y-YP)|O^{T},Y \sim N(Q^{T}_{Y}-G^{T}OR\beta,O^{2}G^{T}OG^{T}G)$$

$$= N(O,O^{2}I_{P})$$

Suggests use of a QQ-Plot on standadized residuals