PhD Interview

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Overview

- Background
 - Education background
 - Awards
- 2 Research Experience
 - Estimate High-fidelity 3D Human Body Models from a Single Image using Deep Learning
 - RIS-aided Dual-Functional Radar and Communications Beamforming Design
- 3 Proposal
 - On Dual-Functional Radar and Communications Design with Reconfigurable Intelligent Surface

Education background

Education

Beijing University of Posts and Telecommunications¹ 2016

2016 - 2020

BEng Telecommunications Engineering with Management

Queen Mary University of London¹

2016 - 2020

 $BEng\ Telecommunications\ Engineering\ with\ Management,\ First\ Class\ Honours$

Imperial College London

2020 - 2021

MSc Communications and Signal Processing

^{1.} A joint programme of BUPT and QMUL

Awards

Main Awards

- Outstanding Final Project Paper of BUPT (Top 2%)
- Outstanding Graduate of BUPT (Top 5%)
- Outstanding Graduate of Beijing (Top 2%)
- First Prize of BUPT Innovation and Entrepreneurship Project (Top 3%)
- College Prize of QMUL (Top 3%)

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What

An end-to-end framework that can estimate 3D mesh of the human body from a single RGB image.



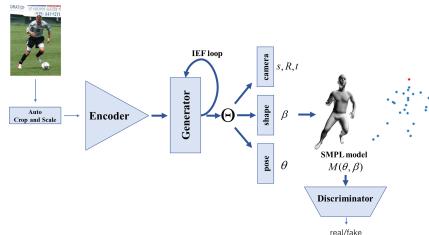
Why

- Many existing methods only estimate 3D joints or skeletons (pose), but ignore the 3D shape;
- Many existing methods have multiple stages leading to a loss of information;
- The lack of in-the-wile images with ground truth 3D annotations.

How

- Apply a skinned multi-person linear (SMPL) model [1] to catch up both 3D pose and shape;
- Develop an end-to-end network;
- Train the network with a Generative Adversarial Network (GAN) [2];
- Train the network in an iterative error feedback manner (IEF) [3].

Framework

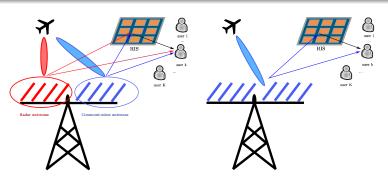


Conclusion

- With GAN, the overall network can be trained without the in-the-wild images with ground truth 3D annotations, but can still perform well on in-the-wild image.
- The training of this network only needs the in-the-wild images with ground truth 2D annotations. Thus, it is easier to improve in the future.
- As the network is end-to-end, the 3D model can be generated fast or even in real time.

What

An integrated radar and communication system that can simultaneously track a target and serve multiple communication users. A reconfigurable intelligent surface is deployed to improve the system performance.

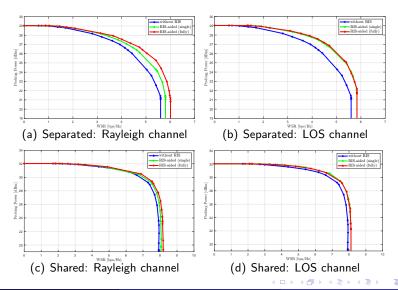


Why

- To solve the spectrum congestion problem of radar and communication system;
- To investigate the benefit of RIS in DFRC system;
- Weighted Sum Rate (WSR) maximization has not been studied in RIS-aided DFRC system [4, 5, 6].

How

- Jointly design the active and passive beamforming to maximize the WSR and probing power;
- Apply a novel group or fully connected RIS model [7];
- Simulate the system in both Rayleigh and Rician fading channels.



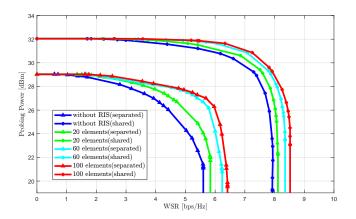


Figure: Effect of the number of reflecting elements

Conclusion

- RIS is capable of enlarge the achievable region of WSR and probing power.
- The fully connected RIS is more powerful than the single connected in Rayleigh channel, but not in LOS channel.
- More gain can be obtained by increasing the reflecting elements.

Limitation

- RIS is only used to improve the communication channel.
- The algorithm for the fully connected RIS converges slow. More efficient algorithm need to be found.

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Motivations

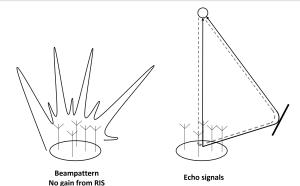
- To investigate the benefits of RIS is different system models.
- To explore the optimization of conventional radar metrics.
- To design more efficient algorithms for RIS-aided DFRC system (try deep learning?).

Literatures

- Maximize the detection probability under users' SINR constraints in RIS-aided RCC system [4]
- Maximize the SINR of radar echo signal under users' SINR constraints in RIS-aided DFRC system [5]
- Minimize the multi-user interference while approximate desired beampattern in RIS-aided DFRC system [6]

No-RIS DFRC vs RIS-aided DFRC

 In No-RIS DFRC, radar metric is usually approximating a desired beampattern [8, 9, 10]. But we can achieve more if the echo signals are considered in RIS-aided DFRC.



Conventional radar metrics

- ullet Detection: detection probability P_D and false-alarm probability P_{FA}
- Estimation: mean square error

Example

According to [4], when the generalized likelihood ratio test under the Neyman-Pearson criterion is applied, the detection probability is given as

$$P_D = 1 - \mathfrak{F}_{\chi_2^2(\rho)} \Big(\mathfrak{F}_{\chi_2^2}^{-1} (1 - P_{FA}) \Big) \tag{1}$$

If the radar signal is orthogonal, i.e., $\mathbf{R_r} = P_R \mathbf{I}_{N_t}$, and the echo signal is $\mathbf{y} = \beta \mathbf{Cr} + \mathbf{z}$, the parameter ρ is

$$\rho = |\beta|^2 P_R \operatorname{Tr} \left(\mathbf{CC}^H \mathbf{R}_{\mathbf{z}}^{-1} \right) \ge \operatorname{SINR}_{\text{echo}} \tag{2}$$

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Potential benefits of deep learning

- Deep learning may catch up more information than conventional optimization method.
- Deep learning algorithm may have lower complexity.

A simple idea

Deep reinforcement learning: we can set the detection probability and WSR as reward, and the model will learn what is the optimal beamforming (actions) in different environments (states).

References I

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- [2] Mehdi Mirza and Simon Osindero. "Conditional generative adversarial nets". In: arXiv preprint arXiv:1411.1784 (2014).
- [3] Joao Carreira et al. "Human pose estimation with iterative error feedback". In: *Proceedings of the IEEE conference on computer vision and pattern recognition*. 2016, pp. 4733–4742.
- [4] Xinyi Wang et al. "RIS-assisted spectrum sharing between MIMO radar and MU-MISO communication systems". In: *IEEE Wireless Communications Letters* 10.3 (2020), pp. 594–598.

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- [6] Xinyi Wang et al. "Joint Waveform Design and Passive Beamforming" for RIS-Assisted Dual-functional Radar-Communication System". In: IEEE Transactions on Vehicular Technology (2021).
- [7] Shanpu Shen, Bruno Clerckx, and Ross Murch. "Modeling and Architecture Design of Intelligent Reflecting Surfaces using Scattering Parameter Network Analysis". In: arXiv preprint arXiv:2011.11362 (2020).
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Thank you