

RIS-Assisted Joint Radar and Communications Beamforming Design

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Communication and Radar Spectrum Sharing

- **Motivation**¹

- Radar systems utilize numerous spectrum bands below 10 GHz, leading to severe spectrum congestion with future wireless communications systems.

- **Communication and Radar Spectrum Sharing (CRSS)**²

- Coexistence of existing radar and communications.
- Co-design for dual-functional radar and communications (DFRC)
 - ① Radar-centric (information embedding)
 - ② Communication-centric (joint beamforming design)

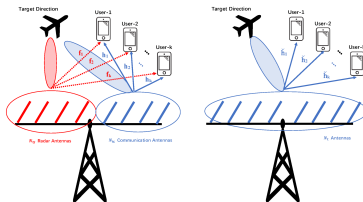


Figure: Schematic diagram for separated and shared multi-antenna joint RadCom³

¹F. Liu et al. "Joint Radar and Communication Design: Applications, State-of-the-Art, and the Road Ahead". In: *IEEE Transactions on Communications* 68.6 (2020), pp. 3834–3862. doi: 10.1109/TCOMM.2020.2973976.

²F. Liu and C. Masouros. "A Tutorial on Joint Radar and Communication Transmission for Vehicular Networks—Part I: Background and Fundamentals". In: *IEEE Communications Letters* 25.2 (2021), pp. 322–326. doi: 10.1109/LCOMM.2020.3025310.

³C. Xu, B. Clerckx, and J. Zhang. "Multi-Antenna Joint Radar and Communications: Precoder Optimization and Weighted Sum-Rate vs Probing Power Tradeoff". In: *IEEE Access* 8 (2020), pp. 173974–173982. doi: 10.1109/ACCESS.2020.3025156.

Trade-off between Radar and Communication

$$\begin{aligned} \max_{\mathbf{P}, \mathbf{R}_x} \quad & \rho \sum_{k=1}^K \mu_k R_k(\mathbf{P}, \mathbf{R}_x) + \\ & \mathbf{a}_1^H(\varphi_m) \mathbf{R}_x \mathbf{a}_1(\varphi_m) + \mathbf{a}_2^H(\varphi_m) \mathbf{P} \mathbf{P}^H \mathbf{a}_2(\varphi_m) \\ \text{s.t.} \quad & \text{diag}(\mathbf{R}_x) = \frac{P_r \mathbf{1}_{M_r \times 1}}{M_r} \\ & \text{Tr}(\mathbf{P} \mathbf{P}^H) \leq P_c \\ & \mathbf{R}_x \succeq 0 \end{aligned}$$

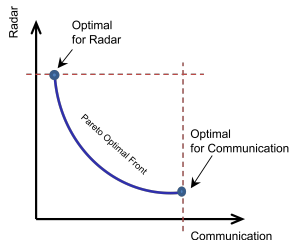


Figure: Pareto Optimal Front

- What if the channel is totally controllable?
 - Precoder (beamforming) is only for Radar
 - Control the channel to meet the Communication requirement
- Reconfigurable Intelligent Surface (RIS)⁴
 - Composed of many small and low-cost reflecting elements
 - Achieve the desired propagation characteristics

⁴Y. Liu et al. "Reconfigurable intelligent surfaces: Principles and opportunities". In: *arXiv preprint arXiv:2007.03435* (2020)

RIS-Assisted Joint RadCom Beamforming Design

• System Model

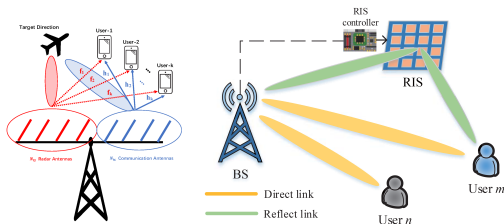
- M_r antennas for the radar, M_c antennas for the communication
- N reflecting elements at RIS
- K users with single antenna; 1 target
- Observation at user k

$$y_k = \mathbf{h}_k^H \Theta^H \mathbf{H}_c \sum_{j=1}^K \mathbf{p}_j s_j + \mathbf{h}_k^H \Theta^H \mathbf{H}_r \mathbf{r} + n_k$$

- SINR and Achievable Rate at user k

$$\gamma_k(\mathbf{P}, \mathbf{R}_x, \Theta) = \frac{|\mathbf{h}_k^H \Theta^H \mathbf{H}_c \mathbf{p}_k|^2}{\sum_{j=1, j \neq k}^K |\mathbf{h}_k^H \Theta^H \mathbf{H}_c \mathbf{p}_j|^2 + \mathbf{f}_k^H \mathbf{R}_x \mathbf{f}_k + 1}$$

$$R_k(\mathbf{P}, \mathbf{R}_x, \Theta) = \log_2(1 + \gamma_k(\mathbf{P}, \mathbf{R}_x, \Theta))$$

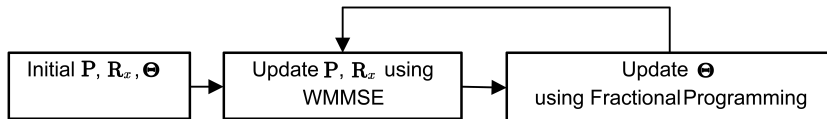


RIS-Assisted Joint RadCom Beamforming Design

- Optimization Problem

$$\begin{aligned}
 & \max_{\mathbf{P}, \mathbf{R}_x, \Theta} \rho \sum_{k=1}^K \mu_k R_k(\mathbf{P}, \mathbf{R}_x, \Theta) + \mathbf{a}_1^H(\varphi_m) \mathbf{R}_x \mathbf{a}_1(\varphi_m) + \mathbf{a}_2^H(\varphi_m) \mathbf{P} \mathbf{P}^H \mathbf{a}_2(\varphi_m) \\
 & \text{s.t.} \quad \text{diag}(\mathbf{R}_x) = \frac{P_r \mathbf{1}^{M_r \times 1}}{M_r} \\
 & \quad \text{Tr}(\mathbf{P} \mathbf{P}^H) \leq P_c \\
 & \quad \mathbf{R}_x \succeq 0 \\
 & \quad |\theta_n| \leq 1, n = 1, \dots, N
 \end{aligned}$$

- Block Coordinate Descent, WMMSE⁵⁶, Fractional Programming⁷



⁵S. S. Christensen et al. "Weighted Sum-Rate Maximization Using Weighted MMSE for MIMO-BC Beamforming Design". In: *2009 IEEE International Conference on Communications*. 2009, pp. 1–6. DOI: 10.1109/ICC.2009.5199574.

⁶C. Xu, B. Clerckx, and J. Zhang. "Multi-Antenna Joint Radar and Communications: Precoder Optimization and Weighted Sum-Rate vs Probing Power Tradeoff". In: *IEEE Access* 8 (2020), pp. 173974–173982. DOI: 10.1109/ACCESS.2020.3025156.

⁷K. Shen and W. Yu. "Fractional Programming for Communication Systems—Part I: Power Control and Beamforming". In: *IEEE Transactions on Signal Processing* 66.10 (2018), pp. 2616–2630. DOI: 10.1109/TSP.2018.2812733.

RIS-Assisted Joint RadCom Beamforming Design

- Update \mathbf{P} , \mathbf{R}_x using WMMSE \rightarrow Semi-definite Programming

$$\begin{aligned} \min_{\mathbf{P}, \mathbf{R}_x} \quad & \rho \sum_{k=1}^K \mu_k \xi_k(\mathbf{P}, \mathbf{R}_x) - \mathbf{a}_1^H(\varphi_m) \mathbf{R}_x \mathbf{a}_1(\varphi_m) + \sum_{k=1}^K \mathbf{p}_k^H \mathbf{Z}(\varphi_m) \mathbf{p}_k \\ \text{s.t.} \quad & \text{diag}(\mathbf{R}_x) = \frac{P_r \mathbf{1}^{M_r \times 1}}{M_r} \\ & \text{Tr}(\mathbf{P} \mathbf{P}^H) \leq P_c \\ & \mathbf{R}_x \succeq 0 \end{aligned}$$

- Update Θ using Fractional Programming \rightarrow Quadratic Programming

$$\begin{aligned} \max_{\mathbf{y}, \boldsymbol{\theta}} \quad & \sum_{k=1}^K \left(2\Re \left\{ y_k^* \sqrt{\tilde{\alpha}_k} \mathbf{a}_{k,k}^H \boldsymbol{\theta} \right\} - |y_k|^2 \left(\sum_{j=1}^K |\mathbf{a}_{j,k}^H \boldsymbol{\theta}|^2 + \boldsymbol{\theta}^H \mathbf{B}_k \boldsymbol{\theta} + 1 \right) \right) \\ \text{s.t.} \quad & |\theta_n| \leq 1, n = 1, \dots, N \\ & y_k \in \mathbb{C} \end{aligned}$$

RIS-Assisted Joint RadCom Beamforming Design

Algorithm WMMSE-FP Algorithm

Input: $t \leftarrow 0$, $\mathbf{P}^{[t]}$, $\Theta^{[t]}$

1: WSR^[t] is calculated from $\mathbf{P}^{[t]}$ and $\Theta^{[t]}$

2: **repeat**

3: $\omega^* = \omega^{\text{MMSE}}(\mathbf{P}^{[t]}, \Theta^{[t]})$

4: $\mathbf{g}^* = \mathbf{g}^{\text{MMSE}}(\mathbf{P}^{[t]}, \Theta^{[t]})$

5: update $\mathbf{P}^{[t+1]}$, $\mathbf{R}_x^{[t+1]}$ by solving the SDP with updated ω^* and \mathbf{g}^* .

6: $\alpha^* = \gamma(\mathbf{P}^{[t+1]}, \mathbf{R}_x^{[t+1]}, \Theta^{[t]})$

7:
$$y_k^* = \frac{\sqrt{\tilde{a}_k \mathbf{a}_{j,k}^H \boldsymbol{\theta}_k}}{\sum_{j=1}^K |\mathbf{a}_{j,k}^H \boldsymbol{\theta}_k|^2 + \boldsymbol{\theta}_k^H \mathbf{B}_k \boldsymbol{\theta}_k + 1}}, k = 1, \dots, K$$

8: update $\Theta^{[t+1]}$ by solving the QP with updated α^* and y_k^* .

9: $t++$

10: **until** $|\text{WSR}^{[t]} - \text{WSR}^{[t+1]}| \leq \epsilon$

Challenges

- If the discrete phase shift of RIS is considered, the constraint set is non-convex
 - Discrete set
- If the shared deployment is considered, the constraint set is also non-convex
 - Quadratic equality constraint

Thanks