

# Interactive Program Design in C++

## A Taxonomy for Practitioners

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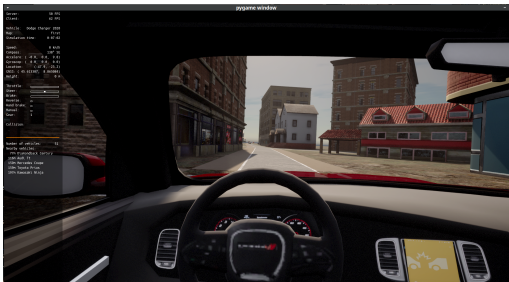
# Who Am I?

- ▶ Compiler researcher of Politecnico di Milano

## Research topic

How do you develop, test, refactor, maintain and reuse **hundreds** of **interactive** programs with as little overhead as possible?

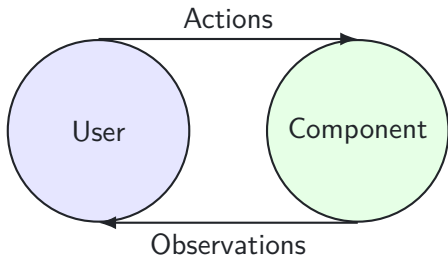
## Ex: Driving simulator developed with Vodafone Automotive



- ▶ We want to calibrate car **accident prediction** algorithms
- ▶ Corporate will **not** let us use real humans
- ▶ Simulations must be efficient because of machine learning.
- ▶ How do we maintain a **ever increasing** library of simulated scenarios?

# Defining interactive components

A **interactive component** is a program component which behaviour depends on some input, and the input depends on the component behaviour.



# Examples of interactive components

- ▶ A website with a multipage form
- ▶ A chess simulation to train AI agents
- ▶ The TCP protocol
- ▶ A load balancing algorithm that spawns and tears down servers depending on the state of the network

## Often but not always

- ▶ Often **interactive components** are part of larger systems
- ▶ Often **interactive components** are a small part of a programmer's job

Techniques to design, implement and maintain interactive components are not commonly known

- ▶ Often **interactive components** are mandated by business requirements and/or third party specification documents
- ▶ Often **interactive components** start simple and then grow in complexity as features are added.

Changes in requirements sometimes push, without programmers noticing, the system in a entirely new category of complexity that forces to rewrite the whole component.

## Running example

The user rolls to dices and sums them. If the result is less than 7 the user is allowed to reroll. Otherwise the user can add a number between 0 and 5 to the result.

```
1 void runningExample() {  
2     int result = rollTwoDice();  
3     if (result < 7 && userWantsToReroll()) {  
4         result = rollTwoDice();  
5         return;  
6     }  
7  
8     result += userDecidedQuantity();  
9 }
```

**userWantsToReroll** and **userDecidedQuantity** are user actions.  
**rollTwoDice** is a random event, independent from user actions.

**Interactive components original sin:**  
**thread blocking**



# No main loop

Functions either block the current thread or they do not.

```
1 void runningExample() {  
2     int result = rollTwoDice();  
3     if (result < 7 && userWantsToReroll()) { // waits for user input  
4         result = rollTwoDice();  
5         return;  
6     }  
7  
8     result += userDecidedQuantity(); // waits for user input  
9 }
```

Blocking is often unacceptable. Spawning a thread is sometimes too costly.

## Examples:

```
1 void graphical_engine_main_loop(Engine& engine) { // interactive
2     while (not engine.is_done()){
3         engine.render_and_display_frame(); // not interactive
4         engine.query_inputs();             // not interactive
5         engine.simulation_step();          // interactive
6     }}
```

```
1 void machine_learning_chess_engine(NeuralNetwork& nn, Game& game) {
2     while (not game.is_done()){
3         Move move = nn.select_action(game.observe()); // not interactive
4         game.apply_move(move);                        // interactive
5     }}
```

The engine owns the main loop, the application logic cannot have it.

# Class rewriting

```
void runningExample() {  
  
    int result = rollTwoDice();  
    if (result < 7 &&  
        userWantsToReroll()) {  
  
        result = rollTwoDice();  
        return;  
    }  
  
    result += userDecidedQuantity();  
}
```

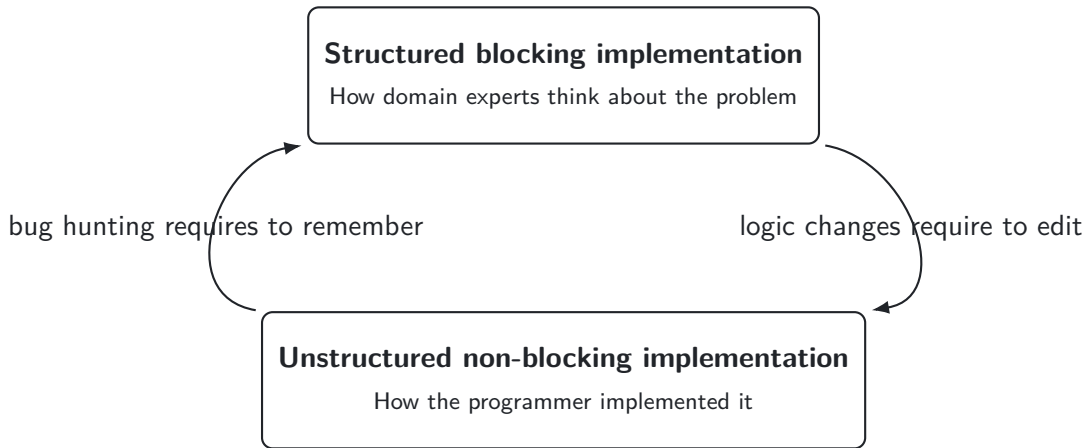
```
struct RunningExample {  
    int next = 0; int result;  
    void start() { assert(next == 0);  
        result = rollTwoDice();  
        next = result < 7 ? 1 : 2;  
    }  
    void userRerolls(bool it_does) {  
        assert(next == 1);  
        if (it_does)  
            result = rollTwoDice();  
        next = it_does ? -1 : 2;  
    }  
    void userDecidesQuantity(int q) {  
        assert(next == 2);  
        result += q;  
        next = -1;  
    }  
}
```

# Manual state management $\equiv$ Unstructured control flow

Exploiting a new variable to keep track of the point we are at in the program is equivalent to unstructured programming.

Class implementation	Unstructured C	Assembly
next next = 2 next = cond ? 1 : 2 next = -1	goto label2 switch (cond) {...} return	program counter jmp label2 cbr cond label1 label2 ret

# Class rewrites are inherently complex to manage



# Class rewriting, general methods

## Questions?

- ▶ Can any blocking function be rewritten as a class?  
yes
- ▶ Is there a general algorithm to convert a function into a class?  
yes: Control flow flattening in compilers, state machine synthesis in hardware design
- ▶ Can GCC, CLANG or MSVC do it for me?  
If coroutines are enough, yes

## Coroutines digression

```
Task runningExample(Input<bool>&
    reroll, Input<int>& quantity) {
    int result = rollTwoDice();
    if (result < 7) {
        bool do_reroll = co_await reroll
            ;
        if (do_reroll) {
            result = rollTwoDice();
            co_return result;
        }
    }
    result += co_await quantity;
    co_return result;}
```

```
int main() {
    Input<bool> reroll;
    Input<int> quantity;
    Task t = runningExample(reroll,
        quantity);
    t.start();
    reroll.supply(false);
    quantity.supply(3);
    if (t.done()) {
        print("done")
    }
}
```

CPP coroutines are not copiable or serializable. Copiable/serializable strongly typechecked zero-overhead coroutines are very challenging to implement.

## Original sin, conclusion

- ▶ Some use cases require the main loop. (web servers, graphical engines...)
- ▶ The interactive component cannot have it too.

### Solutions:

- ▶ Spawn a thread. **costly simple**
- ▶ Coroutines. **one malloc / free per coroutine creation, but manually optimizable complex at the start, easy afterward not copiable/serializable**
- ▶ Rewrite as a class. **1 extra integer cost in most situations Easy at the start, complex to maintain**



## Acceptable implementations

	No calls	Non Recursive	Recursive	Turing complete
Non serializable	threads - coroutines			
Serializable				

# Systems grow in complexity

- ▶ Domain experts often promise to never copy the state of interactive components, and then want to copy it. (Example: "In the car simulator, I want to copy the behaviour of a car, modify it, and after a while restore it to the previous behaviour")
- ▶ Often you want to isolate user actions in their own functions.

**If your solution cannot handle serialization and/or calls, you will have to rewrite the system.**

# Turing complete?

Interactive systems where a user can provide an arbitrary program as input:

- ▶ The python interpreter
- ▶ A moddable videogame

**Solution:** interpreter / just in time compiler

	No calls	Non Recursive	Recursive	Turing complete
Non serializable	threads - coroutines			interpreter - jit
Serializable				interpreter - jit

# Serializable interactive components that scales

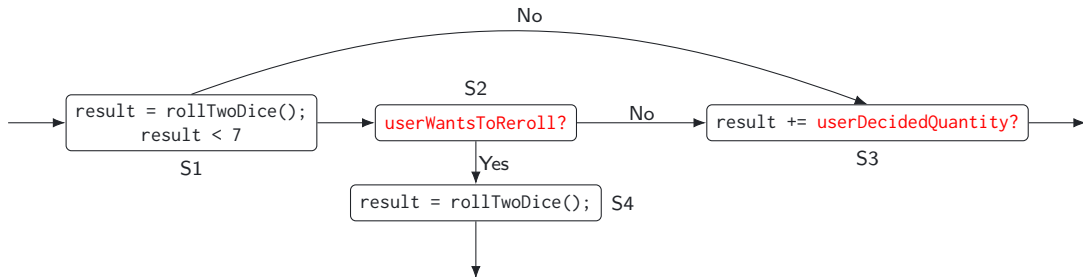
We need a way to implement those systems:

- ▶ Minimizing the distance between the mental model of the domain experts and of the implementation
- ▶ With as little overhead as possible
- ▶ With theoretical guarantees that expanding the implementation will not break the design.

State machines with extra tricks meet our requirements.

## Serializable, no-calls interactive component

No calls interactive components are interactive components where all user actions appear in a single function.



Common, but often you want to isolate sections into subfunctions to reuse them, even when you could just write everything in a single one.

## A possible implementation of a state machine library

```
STATE_MACHINE(resume) {  
  
    STATE(S1)  
    NEXT(S2)  
    ....  
    DECISION(S2):  
    ...  
}
```

```
void resume(Args args) {  
    switch(state) {  
labelS1: case S1: // S1 == 0  
        goto labelS2;  
        ....  
labelS2: state=S2; return; case S2:  
        ...  
    }  
}
```

**labelS2: state=S2;** allows us remember where we are.

**return;** stops the execution.

**case S2:** resumes the execution from the current line.

# Conversion to CPP

```
class RunningExample {
    STATE_MACHINE(resume, {
        STATE(S1):
            result = rollTwoDice();
        NEXT(result < 7, S2, S4)
        DECISION(S2):
        NEXT(userWantsToReroll, S3, S4)
        STATE(S3):
            result = rollTwoDice();
        NEXT(END)
        DECISION(S4):
            result += userDecidedQuantity;
        NEXT(END)
    });
};
```

```
enum State {
    S1, S2, S3, S4, END
};
int result; States state;
void start() {
    assert(state == S1);
    resume();
}
ACT(S2, do_reroll,
    bool, userWantsToReroll)

ACT(S4, decide_quantity,
    int, userDecidedQuantity)
};
```

```

void resume() {
    switch (state) {
        case S1:
            result = rollTwoDice();
            if (result < 7)
                goto labelS2;
            else
                goto labelS3;
labelS2: state=S2; return; case S2:
            if (userWantsToReroll)
                goto labelS4;
            else
                goto labelS3;
labelS3:
            result = rollTwoDice();
            goto labelEND;
labelS4: state=S4; return; case S4:
            result += userDecidedQuantity;
            goto labelEND;
labelEND: state = END; case END:
                return;
    }}

```

```

enum State {S1, S2, S3, END};
int result; States state;
void start() {
    assert(state == S1);
    resume();
}
bool userWantsToReroll;
void do_reroll(bool
    userWantsToReroll) {
    assert(state == S2);
    this->userWantsToReroll =
        userWantsToReroll;
    resume();
}
int userDecidedQuantity;
void decide_quantity(int
    userDecidedQuantity) {
    assert(state == S4);
    this->userDecidedQuantity =
        userDecidedQuantity;
    resume();
}
};

```

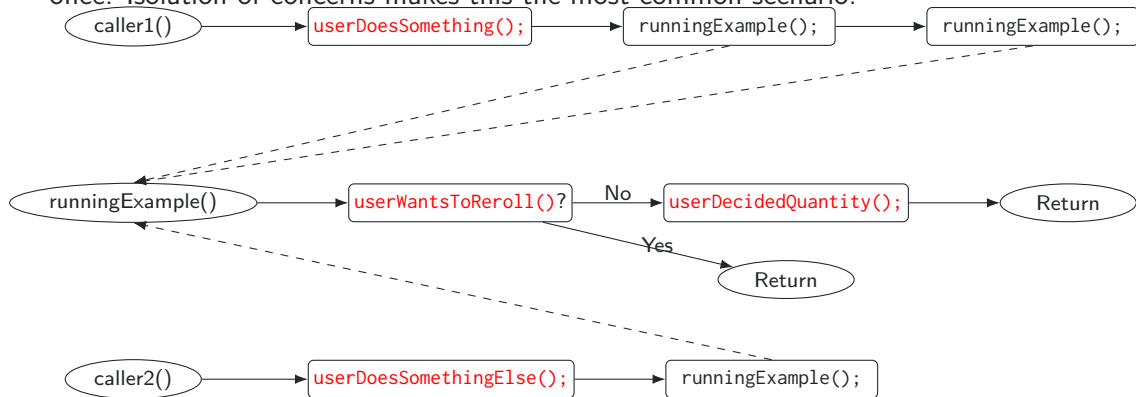


# Acceptable implementations

	No calls	Non Recursive	Recursive	Turing complete
<b>Non serializable</b>	threads - coroutines - rewrites			interpreter
<b>Serializable</b>	STM			interpreter

# Non-recursive non-blocking interactive functions

Actions may be located in multiple functions, but no functions is ever active more than once. Isolation of concerns makes this the most common scenario.



## Solution, introduce CALL/RETURN macros

```
CALL(runningExample, C1)
```

```
ret_addresses.push_back(C1);  
goto runningExample;  
case C1:
```

```
RETURN()
```

```
while (true) {  
    switch(state) {  
        ...  
        state = ret_addresses.back();  
        ret_addresses.pop_back();  
        continue;  
        ...  
    }  
}
```

Extra memory footprint  $< 1$  integer per function + 1.

## Acceptable implementations

	No calls	Non Recursive	Recursive	Turing complete
Non serializable	threads - coroutines			interpreter
Serializable	STM	STM+CALL/RET		interpreter

# Recursive interactive systems

User actions are located in functions that can call directly or indirectly themselves. Rare: code editor command stacks, videogames.

```
CALL(runningExample, C1)
```

```
stack_frames.emplace_back(  
    RunningExample());  
stack_frames.back().start();  
state = C1;  
return;
```

Requires dynamic memory (unless recursion is bounded), cost is proportional to the longest recursion chain.

Is your interactive component Turing-complete? — Yes — Interpreter / JIT

No

Any reason now or in the future to  
copy/serialize state *or*  
do you need the best performance?

No

Coroutines / Threads

Yes

Does it recursively call  
functions with user  
actions inside?

Yes

State machine  
+ non-recursive calls

State machine  
+ recursive calls

# Conclusions

- ▶ Non blocking interactive systems force you into unstructured control flow
- ▶ The compiler knows what to do, but will not do it when you need serializable/copiable objects.
- ▶ State machines of various complexity are the best tool you have to keep track of the complexity, while having guaranteed bounds on their cost.

# Thanks!

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Slides: [example.com](https://example.com)

Repo: [github.com/yourname/yourtalk](https://github.com/yourname/yourtalk)