4.4 # 2,3,5,7,10,11,13,15,17,21,23,32

$$\mathcal{B} = \left\{ \begin{bmatrix} 3 \end{bmatrix}, \begin{bmatrix} -4 \end{bmatrix} \right\}, \begin{bmatrix} \cancel{\lambda} \end{bmatrix} \mathcal{B} = \begin{bmatrix} -2 \\ 6 \end{bmatrix} \qquad \overrightarrow{X} = -2 \begin{bmatrix} 2 \\ 4 \end{bmatrix} + 5 \begin{bmatrix} -4 \\ 4 \end{bmatrix} = \begin{bmatrix} -26 \\ 6 \end{bmatrix}$$

3.)
$$\mathcal{B} = \left\{ \begin{bmatrix} 1 \\ -3 \end{bmatrix}, \begin{bmatrix} 5 \\ -2 \end{bmatrix}, \begin{bmatrix} 4 \\ -3 \end{bmatrix} \right\}, \begin{bmatrix} 1 \\ -3 \end{bmatrix}, \begin{bmatrix} 1 \\ -3 \end{bmatrix} = \begin{bmatrix} 1 \\ -2 \end{bmatrix} = \begin{bmatrix} 1 \\ -2 \end{bmatrix} + 0 \begin{bmatrix} 5 \\ 0 \\ -2 \end{bmatrix} + 0 \begin{bmatrix} 5 \\ 0 \\ -2 \end{bmatrix} = \begin{bmatrix} -7 \\ 4 \\ 3 \end{bmatrix}$$

5.) Find the coordinate vector [X] of
$$\vec{x}$$
 relative to the given basis $\mathcal{B} = \{\vec{b}_1, ..., \vec{b}_n\}$

$$\vec{b}_1 = [-1], \vec{b}_2 = [-1] \quad \begin{bmatrix} 1 & 3 & |-1| \\ -2 & -5 & |-1| \\ 2R_1 + R_2 & |-1| \end{bmatrix} \xrightarrow{-3R_2 + R_1} \begin{bmatrix} 1 & 0 & |-2| \\ 0 & 1 & |-1| \end{bmatrix}$$

$$B = \begin{cases} \begin{bmatrix} 3 \\ 6 \end{bmatrix}, \begin{bmatrix} 2 \\ -4 \end{bmatrix}, \begin{bmatrix} -2 \\ 3 \end{bmatrix} \end{cases} \quad P_B = \begin{bmatrix} \overline{b}, \overline{b}_2 \overline{b}_3 \end{bmatrix} = \begin{bmatrix} 3 & 2 & 1 \\ 0 & 2 & -2 \\ 6 & -4 & 3 \end{bmatrix}$$

Use an inverse matrix to find
$$\mathbb{I} \times \mathbb{I}_{\mathcal{B}}$$
 for $\hat{\mathbf{x}} = \begin{bmatrix} 3 \end{bmatrix}$ and $\hat{\mathcal{B}} = \underbrace{\begin{bmatrix} 1 & 2 \end{bmatrix}} \begin{bmatrix} 2 & 1 \end{bmatrix} \begin{bmatrix} 2$

13.) The set $\mathcal{B} = \{1+t^2, t+t^2, 1+2t+t^2\}$ is a basis for \mathbb{F}_a . Find the coordinate vector of $\vec{p}(t) = 1+4t+7t^2$ relative to \mathcal{B} .

$$C_1(1+t^2) + C_2(t+t^2) + C_3(1+2t+t^2) = 1+4t+7t^2$$
 $C_1+C_3+(c_2+2c_3)t+(c_1+c_2+c_3)t^2 = 1+4t+7t^2$
 $C_1+C_3+(c_2+2c_3)t+(c_1+c_2+c_3)t^2 = 1+4t+7t^2$
 $C_1+C_2+C_3=7$

$$\begin{bmatrix} 1 & 0 & 0 & | & 2 \\ 0 & 1 & 0 & | & 6 \\ 0 & 0 & 1 & | & -1 \end{bmatrix}$$

$$\begin{bmatrix} 2 & 3 & 3 \\ 0 & 0 & | & -1 \end{bmatrix}$$

- 15.) True/False. B is a basis for a vector space V.
 - a) If \vec{x} is in \vec{V} and if \vec{B} contains \vec{n} vectors, then the \vec{B} coordinate vector of \vec{x} is in \vec{R}^n .
 - bi) If PB is the change-of-coordinates matrix, then $[\hat{x}]_{B} = P_{B}\hat{x}$ for \hat{x} in \hat{V}_{e}
 - c) The vector spaces \$P3 and \$R3 are isomorphic.
 - ai) True bi) False ei) False
- 17.) The vectors $\vec{V}_1 = [-3]$, $\vec{V}_2 = [-8]$, $\vec{V}_3 = [-7]$ span \mathbb{R}^2 but do not form a basis. Find two different ways to express [1] as a linear combination of $\vec{V}_1, \vec{V}_2, \vec{V}_3$.

of $\sqrt{1}, \sqrt{2}, \sqrt{3}$. $\begin{bmatrix} 1 & 2 & -3 \\ -3 & -8 \end{bmatrix}$ $\begin{bmatrix} 1 & 2 & -3 \\ 3R_1 + R_2 \end{bmatrix}$ $\begin{bmatrix} 1 & 2 & -3 \\ 0 & 2 & -2 \end{bmatrix}$ $\begin{bmatrix} 1 & 2 & -3 \\ 4 & 2 & -2 \end{bmatrix}$ $\begin{bmatrix} 1 & 2 & -3 \\ 2 & 3 & -2 \end{bmatrix}$ $\begin{bmatrix} 1 & 2 & -3$

one answer:
$$\vec{X} = \begin{bmatrix} 5 \\ -2 \\ 0 \end{bmatrix}$$
 or $\vec{X} = \begin{bmatrix} 10 \\ -3 \\ 1 \end{bmatrix}$

4,4 continued

21.) Let $\mathcal{B} = \{ \begin{bmatrix} -4 \end{bmatrix}, \begin{bmatrix} -2 \end{bmatrix} \}$. Since the coordinate mapping determined by \mathcal{B} is a linear transformation from \mathbb{R}^2 into \mathbb{R}^2 , this mapping must be implemented by some 2×2 matrix A. Find it. (Hint: Multiplication by A should transform a vector \overline{x} into $\overline{LXJ}_{\mathcal{B}}$.) Since $\overline{P_{\mathcal{B}}} = \overline{LXJ}_{\mathcal{B}}$, $\overline{P_{\mathcal{B}}}$ is the matrix we are looking for. $\overline{P_{\mathcal{B}}} = \overline{LYJ}_{\mathcal{A}} = \overline{LXJ}_{\mathcal{B}}$, $\overline{P_{\mathcal{B}}}$ is the matrix we are looking for.

23.) Vis a vector space, $\mathcal{B} = \{\vec{b}_1, \dots, \vec{b}_n\}$ is a basis and $\vec{x} \mapsto [\vec{x}]_{\mathcal{B}}$ is the coordinate mapping. Show that the coordinate mapping is one-to-one. (Hint: Suppose $[\vec{u}]_{\mathcal{B}} = [\vec{w}]_{\mathcal{B}}$ for some $\vec{u}, \vec{w} \in V$ and show that $\vec{u} = \vec{w}$.)

[$\vec{u}]_{\mathcal{B}} = [\vec{w}]_{\mathcal{B}} = [\vec{c}_1]$ So $\vec{u} = \vec{c}_1\vec{b}_1 + \dots + \vec{c}_n\vec{b}_n$ and $\vec{w} = \vec{c}_1\vec{b}_1 + \dots + \vec{c}_n\vec{b}_n$ therefore $\vec{u} = \vec{w}$. Thus the coordinate mapping is one-to-one.

32.) Let $\vec{p}(t) = 1 + t^2$, $\vec{p}_a(t) = t + 3t^2$, $\vec{p}_a(t) = 1 + t - 3t^2$ a.) Use coordinate vectors to show that these polynomials form a basis for \mathbb{R}^2 . b.) Consider the basis $\mathcal{B} = \{\vec{p}_1, \vec{p}_2, \vec{p}_3\}$ for \mathbb{R}^2 . Find $\vec{q} \in \mathbb{R}^2$ sit. $[\vec{q}]_{\mathcal{B}} = [\vec{q}]_{\mathcal{B}}$.

a) [101] \[\left[101] This is row equivalent to I3, so its invertible, \\ \left[011] \sigma \left[011] \sigma \text{ forms are linearly independent and \\ \left[1-3-3] \left[00-1] \text{ span } \mathbb{R}^3. \text{ Since } \mathbb{R}^3 \text{ is isomorphic to } \mathbb{R}^3, \\ \left[\frac{1}{3} \right], \left[\frac{1}{3} \right], \left[\frac{1}{3} \right] \left[\frac{1}{63} \right] \text{ forms a basis for } \mathbb{R}^2.

bi) $\bar{q} = -1 \begin{bmatrix} i \\ 0 \end{bmatrix} + \begin{bmatrix} i \\ -3 \end{bmatrix} + 2 \begin{bmatrix} 1 \\ -3 \end{bmatrix} = \begin{bmatrix} 1 \\ 3 \end{bmatrix} = \begin{bmatrix} 1 \\ -10 \end{bmatrix}$ $\bar{q}(t) = 1 + 3t - 10t^2$

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