

4.1 Orthogonality

4.1. Key Ideas

- Subspaces V and W are orthogonal if every \mathbf{v} in V is orthogonal to every \mathbf{w} in W .

Question 4.1.1. How do we know when two vectors are *orthogonal* to each other?

- if in \mathbb{R}^2

$$\begin{bmatrix} a \\ b \end{bmatrix} \text{ is perp to } \begin{bmatrix} -b \\ a \end{bmatrix}$$

$$\uparrow$$

$$y = \frac{b}{a}x$$

$$y = -\frac{a}{b}x$$

$$by = -ax$$

- otherwise if $\mathbf{u} \cdot \mathbf{v} = 0$ then vectors perpendicular

$$\mathbf{u} \cdot \mathbf{v} = \|\mathbf{u}\| \|\mathbf{v}\| \cos \theta$$

Definition 4.1.2. Two vectors in \mathbf{u} and \mathbf{v} in \mathbb{R}^n are orthogonal if $\mathbf{u} \cdot \mathbf{v} = 0$.

Definition 4.1.3. A vector \mathbf{u} in \mathbb{R}^n is orthogonal to a subspace V of \mathbb{R}^n if and only if it's orthogonal to every vector in V .

In English...

to check if \vec{u} is orthogonal to V
 $\vec{u} \cdot \vec{v} = 0$ for all \vec{v} in V
 really only need to check for all \vec{v} in a spanning set for V .

Example 4.1.4. Show that $\begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix}$ is orthogonal to the column space of A .

$$A = \begin{bmatrix} 1 & 4 \\ 2 & 5 \\ 3 & 6 \end{bmatrix}$$

$$\text{Col } A = \text{Span} \left\{ \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}, \begin{bmatrix} 4 \\ 5 \\ 6 \end{bmatrix} \right\}$$

just check

$$\begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} = 1 - 4 + 3 = 0 \checkmark$$

$$\begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix} \cdot \begin{bmatrix} 4 \\ 5 \\ 6 \end{bmatrix} = 4 - 10 + 6 = 0 \checkmark$$

$$\Rightarrow \begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix} \text{ is orthogonal to Col } A$$

Definition 4.1.5. Two subspaces V and W of \mathbb{R}^n are orthogonal if and only if every vector in V is orthogonal to every vector in W .

In English...

given $V = \text{Span}\{v_1, \dots, v_p\}$
 $W = \text{Span}\{w_1, \dots, w_j\}$
 need to check each pair of v_i, w_k

Example 4.1.6. Find all of the vectors that are orthogonal to the column space of

$$A = \begin{bmatrix} 1 & 5 \\ 2 & 6 \\ 3 & 7 \\ 4 & 8 \end{bmatrix}$$

if \vec{x} is orthogonal to $\text{Col}(A)$

then $\begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \end{bmatrix} \cdot \vec{x} = 0 \quad \begin{bmatrix} 5 \\ 6 \\ 7 \\ 8 \end{bmatrix} \cdot \vec{x} = 0$

$$\Leftrightarrow \begin{aligned} 1 \cdot x_1 + 2x_2 + 3x_3 + 4x_4 &= 0 \\ 5x_1 + 6x_2 + 7x_3 + 8x_4 &= 0 \end{aligned}$$

$$\left[\begin{array}{cccc|c} 1 & 2 & 3 & 4 & 0 \\ 5 & 6 & 7 & 8 & 0 \end{array} \right] \quad \begin{bmatrix} 1 & 2 & 3 & 4 \\ 5 & 6 & 7 & 8 \end{bmatrix} \vec{x} = \vec{0}$$

$$\sim \left[\begin{array}{cccc|c} 1 & 0 & -1 & -2 & 0 \\ 0 & 1 & 2 & 3 & 0 \end{array} \right]$$

$$\sim \begin{cases} x_1 = x_3 + 2x_4 \\ x_2 = -2x_3 - 3x_4 \end{cases}$$

$$\vec{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} x_3 + 2x_4 \\ -2x_3 - 3x_4 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} 1 \\ -2 \\ 1 \\ 0 \end{bmatrix} x_3 + \begin{bmatrix} 2 \\ -3 \\ 0 \\ 1 \end{bmatrix} x_4$$

$$\text{soln set} = \text{Span} \left\{ \begin{bmatrix} 1 \\ -2 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 2 \\ -3 \\ 0 \\ 1 \end{bmatrix} \right\}$$

all orth to $\text{Col } A$

Definition 4.1.7. If A is an $m \times n$ matrix, the transpose of A is the $n \times m$ matrix, denoted A^T , whose columns are formed from the corresponding rows of A .

take columns make them rows

Example 4.1.8. Let $A = \begin{bmatrix} a & b & d \end{bmatrix}$, $B = \begin{bmatrix} 8 & 4 \\ 5 & 5 \\ 6 & 2 \end{bmatrix}$, and $C = \begin{bmatrix} 5 & -2 & 1 & 3 \\ 3 & 1 & 2 & -6 \end{bmatrix}$.

Find A^T , B^T , and C^T .

e.g. $\begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \end{bmatrix}^T = \begin{bmatrix} 1 & 2 & 3 & 4 \end{bmatrix}$

$$A^T = \begin{bmatrix} a & b & d \end{bmatrix}^T = \begin{bmatrix} a \\ b \\ d \end{bmatrix}$$

$$B^T = \begin{bmatrix} 8 & 4 \\ 5 & 5 \\ 6 & 2 \end{bmatrix}^T = \begin{bmatrix} 8 & 5 & 6 \\ 4 & 5 & 2 \end{bmatrix}$$

$$C^T = \begin{bmatrix} 5 & -2 & 1 & 3 \\ 3 & 1 & 2 & -6 \end{bmatrix}^T = \begin{bmatrix} 5 & 3 \\ -2 & 1 \\ 1 & 2 \\ 3 & -6 \end{bmatrix}$$

in the last example, we found vectors
orth to $\text{Col } A$
by solving $A^T \vec{x} = \vec{0}$
i.e. finding $\text{Nul}(A^T)$
 $\text{Col } A$ is always orth to $\text{Nul}(A^T)$

Observation 4.1.9. Using this notation, sometimes it's convenient to write the dot product as matrix multiplication

$$\mathbf{u} \cdot \mathbf{v} = \mathbf{u}^T \mathbf{v}$$

$$\begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} = 1 \cdot 1 + 2 \cdot 2 + 3 \cdot 3$$

$$\begin{bmatrix} 1 \\ 2 \\ 5 \end{bmatrix} \cdot \begin{bmatrix} 5 \\ 1 \\ 7 \end{bmatrix} = 5 + 2 + 35 = 42$$

$$\begin{bmatrix} 1 \\ 2 \\ 5 \end{bmatrix}^T = [1 \ 2 \ 5]$$

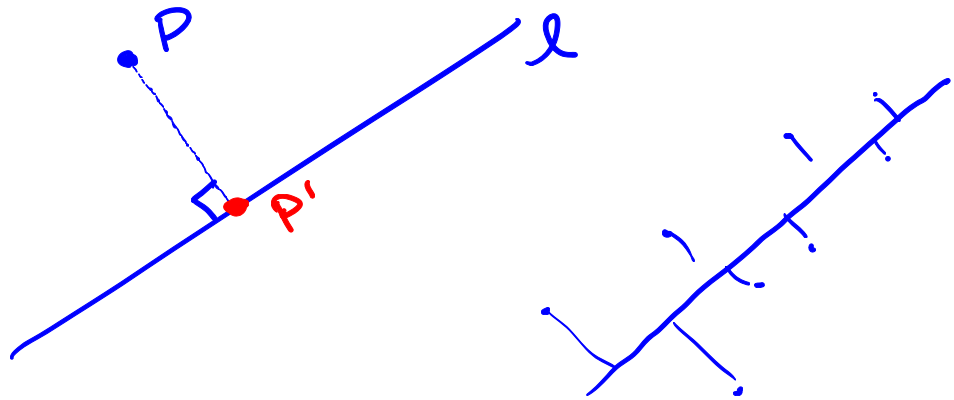
$$\begin{bmatrix} 1 \\ 2 \\ 5 \end{bmatrix}^T \begin{bmatrix} 5 \\ 1 \\ 7 \end{bmatrix} = [1 \ 2 \ 5] \begin{bmatrix} 5 \\ 1 \\ 7 \end{bmatrix} = [1 \cdot 5 + 2 \cdot 1 + 5 \cdot 7] \\ = [42] \\ = 42$$

4.2 Projections

4.2. Key Ideas

- projection of a point onto a line
- projection of a point onto a space

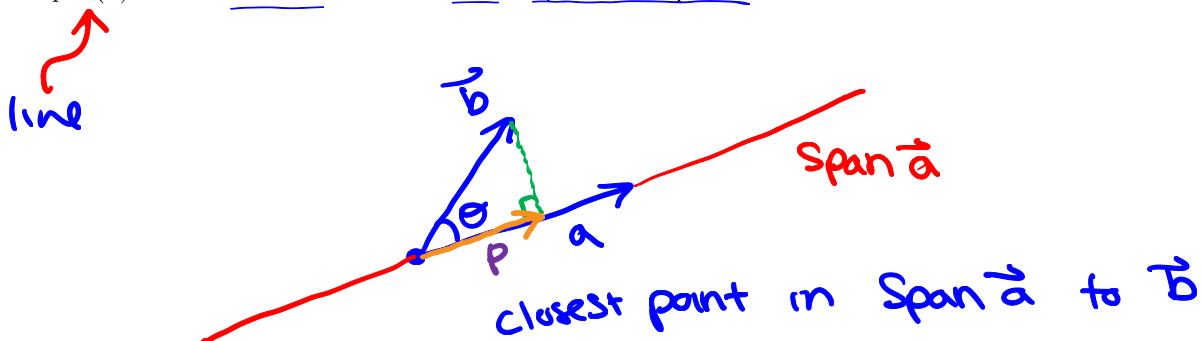
Question 4.2.1. Given a point P and a line ℓ , how can we find the closest point on ℓ to P ?



recall

$$u \cdot v = \|u\| \|v\| \cos \Theta$$

Question 4.2.2. Given two vectors \mathbf{b} and \mathbf{a} in \mathbb{R}^n , suppose we're interested in the closest point in $\text{Span}(\mathbf{a})$ to \mathbf{b} . How is this like our line and point example above?



trig \Rightarrow

$$\cos \Theta = \frac{\|\mathbf{p}\|}{\|\mathbf{b}\|} \Leftrightarrow \|\mathbf{p}\| = \|\mathbf{b}\| \cos \Theta$$

$$\Leftrightarrow \|\mathbf{a}\| \|\mathbf{p}\| = \|\mathbf{a}\| \|\mathbf{b}\| \cos \Theta$$

$$\|\mathbf{a}\| \|\mathbf{p}\| = \mathbf{a} \cdot \mathbf{b}$$

$$\Leftrightarrow \|\mathbf{p}\| = \frac{\mathbf{a} \cdot \mathbf{b}}{\|\mathbf{a}\|}$$

know $\|\vec{p}\|$ want to know \vec{p}

want vector of length $\|\vec{p}\|$ in direction of \vec{a}

$$\vec{p} = \|\vec{p}\| \frac{\vec{a}}{\|\vec{a}\|} = \frac{\vec{a} \cdot \vec{b}}{\|\vec{a}\|} \frac{\vec{a}}{\|\vec{a}\|} = \left(\frac{\vec{a} \cdot \vec{b}}{\vec{a} \cdot \vec{a}} \right) \vec{a}$$

scalar
↓

$$\left(\sqrt{a_1^2 + a_2^2 + \dots} \right)^2 = a_1^2 + a_2^2 + \dots$$

$\vec{e} = \vec{b} - \vec{p}$ error $\|\vec{e}\| = \text{distance from } \vec{b} \text{ to } \text{Span}(\vec{a})$

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MATH 118 Condensed Lecture Notes

Definition 4.2.3. The orthogonal projection of \vec{b} onto the span of \vec{a} is

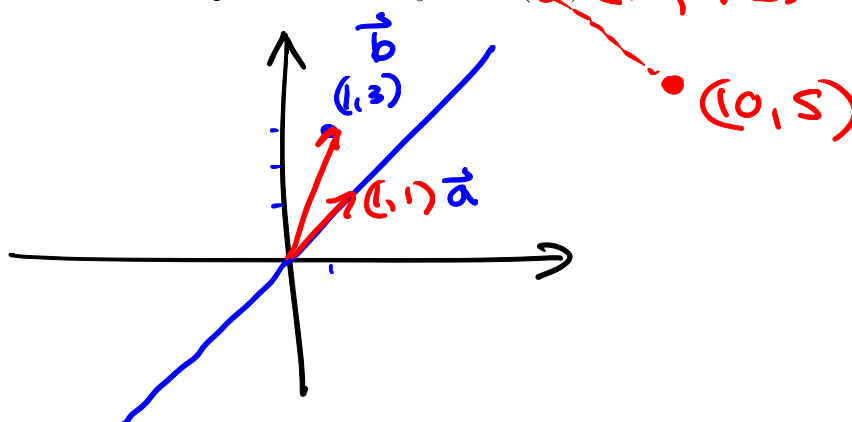
$$\vec{p} = \text{proj}_{\vec{a}} \vec{b} = \frac{\vec{a} \cdot \vec{b}}{\vec{a} \cdot \vec{a}} \vec{a} = \frac{\vec{a}^T \vec{b}}{\vec{a}^T \vec{a}} \vec{a} = \frac{\vec{a} \vec{a}^T}{\vec{a}^T \vec{a}} \vec{b}.$$

rearrange
called projection
matrix

The error is the vector $\vec{e} = \vec{b} - \vec{p}$. It's the vector that's perpendicular to \vec{a} and has length equal to the distance from \vec{b} to \vec{p} .

The matrix $P = \frac{\vec{a} \vec{a}^T}{\vec{a}^T \vec{a}}$ is called the **projection matrix**.

Example 4.2.4. Find the closest point on the line $y = x$ to $(1, 3)$.



closest point to \vec{b} on $\text{Span}(\vec{a})$ is \vec{p} (projection)

$$\vec{p} = \frac{\vec{a} \cdot \vec{b}}{\vec{a} \cdot \vec{a}} \vec{a} = \frac{[1] \cdot [3]}{[1] \cdot [1]} [1] = \frac{4}{2} [1] = [2]$$

$$\|\vec{e}\| = \|\vec{p} - \vec{b}\| = \left\| \begin{bmatrix} 2 \\ 2 \end{bmatrix} - \begin{bmatrix} 1 \\ 3 \end{bmatrix} \right\| = \left\| \begin{bmatrix} 1 \\ -1 \end{bmatrix} \right\| = \sqrt{1^2 + 1^2} = \sqrt{2}$$

distance from $(1, 3)$ to $y = x$

Projection mtrx
 $\vec{a} = [1]$

$$\vec{b} = \begin{bmatrix} 1 \\ 3 \end{bmatrix}$$

$$P = \frac{\vec{a} \vec{a}^T}{\vec{a}^T \vec{a}} = \frac{[1] [1, 1]}{[1, 1] [1]} = \frac{\begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}}{2} = \begin{bmatrix} 1/2 & 1/2 \\ 1/2 & 1/2 \end{bmatrix}$$

e.g. $P \vec{b} = \begin{bmatrix} 1/2 & 1/2 \\ 1/2 & 1/2 \end{bmatrix} \begin{bmatrix} 1 \\ 3 \end{bmatrix} = \begin{bmatrix} 2 \\ 2 \end{bmatrix}$

another ex $\begin{bmatrix} 1/2 & 1/2 \\ 1/2 & 1/2 \end{bmatrix} \begin{bmatrix} 10 \\ 5 \end{bmatrix} = \begin{bmatrix} 7.5 \\ 7.5 \end{bmatrix}$

Example 4.2.5. Find the projection matrix P onto the line through $\mathbf{a} = (1, 2, 2)$, and use this to find the point on the line closest to $(1, 1, 1)$.

$$P = \frac{\mathbf{a}\mathbf{a}^T}{\mathbf{a}^T\mathbf{a}} = \frac{\begin{bmatrix} 1 \\ 2 \\ 2 \end{bmatrix} \begin{bmatrix} 1 & 2 & 2 \end{bmatrix}}{\begin{bmatrix} 1 & 2 & 2 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \\ 2 \end{bmatrix}} = \frac{\begin{bmatrix} 1 & 2 & 2 \\ 2 & 4 & 4 \\ 2 & 4 & 4 \end{bmatrix}}{9}$$

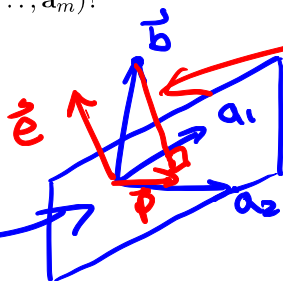
$$P = \begin{bmatrix} 1/9 & 2/9 & 2/9 \\ 2/9 & 4/9 & 4/9 \\ 2/9 & 4/9 & 4/9 \end{bmatrix}$$

$$P\mathbf{b} = \begin{bmatrix} 1/9 & 2/9 & 2/9 \\ 2/9 & 4/9 & 4/9 \\ 2/9 & 4/9 & 4/9 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 5/9 \\ 10/9 \\ 10/9 \end{bmatrix} \leftarrow \begin{array}{l} \text{closest point} \\ \text{on} \\ \text{Span}(\begin{bmatrix} 1 \\ 2 \\ 2 \end{bmatrix}) \\ \text{to } \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \end{array}$$

how far away from line

$$\|\vec{e}\| = \|\mathbf{p} - \mathbf{b}\| = \left\| \begin{bmatrix} 5/9 \\ 10/9 \\ 10/9 \end{bmatrix} - \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \right\| = \left\| \begin{bmatrix} -4/9 \\ 1/9 \\ 1/9 \end{bmatrix} \right\| = \frac{\sqrt{2}}{3} ?$$

Question 4.2.6. Given a collection of vectors $\mathbf{a}_1, \dots, \mathbf{a}_m$, and \mathbf{b} in \mathbb{R}^n , how could we find the closest point to \mathbf{b} in $\text{Span}(\mathbf{a}_1, \dots, \mathbf{a}_m)$?



Still want something perp

$$\vec{e} = \vec{p} - \vec{b} \Rightarrow \text{perpendicular}$$

WTF \hat{x} such that

$$\boxed{\vec{p} = A\hat{x}} = \vec{a}_1 \hat{x}_1 + \vec{a}_2 \hat{x}_2 + \dots + \vec{a}_n \hat{x}_n$$

\vec{p} in $\text{Col}(A)$ projecting onto column space of $A = [\vec{a}_1 \ \vec{a}_2 \ \dots \ \vec{a}_n]$

$\vec{e} = \vec{b} - \vec{p}$ is orthogonal to $\text{Col}(A)$

$$\text{so } \vec{a}_i \cdot \vec{e} = \vec{a}_i^T \vec{e} = 0 \text{ for all } \vec{a}_i$$

$$\vec{a}_1^T \vec{e} = \vec{a}_1^T (\vec{b} - \vec{p}) = \vec{a}_1^T (\vec{b} - A\vec{x}) = 0$$

$$\vec{a}_2^T (\vec{b} - A\vec{x}) = 0$$

$$\vec{a}_3^T (\vec{b} - A\vec{x}) = 0$$

\vdots

$$\vec{a}_n^T (\vec{b} - A\vec{x}) = 0$$

i.e. we have n -equations can rewrite as

$$\begin{bmatrix} -\vec{a}_1^T \\ -\vec{a}_2^T \\ -\vec{a}_3^T \\ \vdots \\ -\vec{a}_n^T \end{bmatrix} (\vec{b} - A\vec{x}) = \vec{0}$$

$$A^T (\vec{b} - A\vec{x}) = \vec{0}$$

$$\boxed{A^T A \vec{x} = A^T \vec{b}}$$

if $\vec{p} = A\hat{x}$ is closest point in $\text{Col}(A)$ to \vec{b} , then \hat{x} is a soln to $A^T A \hat{x} = A^T \vec{b}$

Definition 4.2.7. The combination $\mathbf{p} = \hat{x}_1 \mathbf{a}_1 + \cdots + \hat{x}_m \mathbf{a}_m = A\hat{\mathbf{x}}$ closest to \mathbf{b} comes from

$$A^T A \hat{\mathbf{x}} = A^T \mathbf{b}.$$

The **projection** of \mathbf{b} onto the subspace spanned by the \mathbf{a}_i is

$$\mathbf{p} = A\hat{\mathbf{x}} = A(A^T A)^{-1} A^T \mathbf{b}.$$

Again, $P = A(A^T A)^{-1} A^T$ is called the **projection matrix**. The **error** is the vector $\mathbf{e} = \mathbf{b} - \mathbf{p}$. Its length is equal to the distance from \mathbf{b} to \mathbf{p} .

Example 4.2.8. Find the closest point to $\mathbf{b} = \begin{bmatrix} 6 \\ 0 \\ 0 \end{bmatrix}$ in the plane spanned by $\mathbf{a}_1 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$ and $\mathbf{a}_2 = \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix}$.

$$A = \begin{bmatrix} 1 & 0 \\ 1 & 1 \\ 1 & 2 \end{bmatrix}$$

① Find A^T , $A^T A$, and $A^T \mathbf{b}$

② solve $A^T A \hat{\mathbf{x}} = A^T \mathbf{b}$

③ \vec{p} will be product $A \hat{\mathbf{x}}$

① $A^T = \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 2 \end{bmatrix}$

$$A^T A = \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 2 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 1 & 1 \\ 1 & 2 \end{bmatrix} = \begin{bmatrix} 3 & 3 \\ 3 & 5 \end{bmatrix}$$

$$A^T \mathbf{b} = \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 2 \end{bmatrix} \begin{bmatrix} 6 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 6 \\ 0 \end{bmatrix}$$

② Solve $A^T A \hat{\mathbf{x}} = A^T \mathbf{b}$

$$\begin{bmatrix} 3 & 3 \\ 3 & 5 \end{bmatrix} \hat{\mathbf{x}} = \begin{bmatrix} 6 \\ 0 \end{bmatrix} \sim \left[\begin{array}{cc|c} 3 & 3 & 6 \\ 3 & 5 & 0 \end{array} \right] \sim \left[\begin{array}{cc|c} 1 & 0 & 5 \\ 0 & 1 & -3 \end{array} \right]$$

so $\hat{\mathbf{x}} = \begin{bmatrix} 5 \\ -3 \end{bmatrix}$

③ Find $\vec{p} = A \hat{\mathbf{x}}$

$$\vec{p} = A \hat{\mathbf{x}} = \begin{bmatrix} 1 & 0 \\ 1 & 1 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} 5 \\ -3 \end{bmatrix} = \begin{bmatrix} 5 \\ 2 \\ -1 \end{bmatrix}$$