

6.5 # 3, 5, 7, 9, 11, 17, 19, 21

3.) Find a least-squares solution of $A\vec{x} = \vec{b}$ by (a) constructing the normal equations for \vec{x} and (b) solving for \vec{x} .

$$A = \begin{bmatrix} 1 & -2 \\ -1 & 2 \\ 0 & 3 \\ 2 & 5 \end{bmatrix}, \quad \vec{b} = \begin{bmatrix} 3 \\ 1 \\ -4 \\ 2 \end{bmatrix} \quad A^T A = \begin{bmatrix} 1 & -1 & 0 & 2 \\ -2 & 2 & 3 & 5 \end{bmatrix} \begin{bmatrix} 1 & -2 \\ -1 & 2 \\ 0 & 3 \\ 2 & 5 \end{bmatrix} = \begin{bmatrix} 6 & 6 \\ 6 & 42 \end{bmatrix}$$

$$A^T \vec{b} = \begin{bmatrix} 1 & -1 & 0 & 2 \\ -2 & 2 & 3 & 5 \end{bmatrix} \begin{bmatrix} 3 \\ 1 \\ -4 \\ 2 \end{bmatrix} = \begin{bmatrix} 6 \\ -6 \end{bmatrix} \quad \text{a) The normal equations are the system given by } A^T A \hat{x} = A^T \vec{b}$$

$$\begin{bmatrix} 6 & 6 \\ 6 & 42 \end{bmatrix} \vec{x} = \begin{bmatrix} 6 \\ -6 \end{bmatrix}$$

$$\text{b) Solving this for } \hat{x}, \quad \left[\begin{array}{cc|c} 6 & 6 & 6 \\ 6 & 42 & -6 \end{array} \right] \sim \left[\begin{array}{cc|c} 1 & 0 & 4/3 \\ 0 & 1 & -1/3 \end{array} \right] \quad \boxed{\hat{x} = \begin{bmatrix} 4/3 \\ -1/3 \end{bmatrix}}$$

5.) Describe all least-squares solutions of $A\vec{x} = \vec{b}$.

$$A = \begin{bmatrix} 1 & 1 & 0 \\ 1 & 1 & 0 \\ 1 & 0 & 1 \\ 1 & 0 & 1 \end{bmatrix}, \quad \vec{b} = \begin{bmatrix} 1 \\ 3 \\ 8 \\ 2 \end{bmatrix} \quad A^T A = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 & 0 \\ 1 & 1 & 0 \\ 1 & 0 & 1 \\ 1 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 4 & 2 & 2 \\ 2 & 2 & 0 \\ 2 & 0 & 2 \end{bmatrix}$$

$$A^T \vec{b} = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 3 \\ 8 \\ 2 \end{bmatrix} = \begin{bmatrix} 14 \\ 4 \\ 10 \end{bmatrix}$$

$$\left[\begin{array}{ccc|c} 4 & 2 & 2 & 14 \\ 2 & 2 & 0 & 4 \\ 2 & 0 & 2 & 10 \end{array} \right] \sim \left[\begin{array}{ccc|c} 1 & 0 & 1 & 5 \\ 0 & 1 & -1 & -3 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

$$\hat{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 5 \\ -3 \\ 0 \end{bmatrix} + x_3 \begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix}$$

$$\begin{aligned} x_1 + x_3 &= 5 \\ x_2 - x_3 &= -3 \end{aligned}$$

$$\boxed{\hat{x} = \begin{bmatrix} 5 \\ -3 \\ 0 \end{bmatrix} + x_3 \begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix}}$$

7.) Compute the least-squares error associated w/ the least-squares solution found in Exercise 3.

The least-squares error is $\|A\hat{x} - \vec{b}\|$.

$$A\hat{x} - \vec{b} = \begin{bmatrix} 1 & -2 \\ -1 & 2 \\ 0 & 3 \\ 2 & 5 \end{bmatrix} \begin{bmatrix} 4/3 \\ -1/3 \end{bmatrix} - \begin{bmatrix} 3 \\ 1 \\ -4 \\ 2 \end{bmatrix} = \begin{bmatrix} 2 \\ -2 \\ -1 \\ 1 \end{bmatrix} - \begin{bmatrix} 3 \\ 1 \\ -4 \\ 2 \end{bmatrix} = \begin{bmatrix} -1 \\ -3 \\ 3 \\ -1 \end{bmatrix} \quad \|A\hat{x} - \vec{b}\| = \sqrt{20}$$

9.) Find (a) the orthogonal projection of \vec{b} onto $\text{col} A$ and (b) a least-squares solution of $A\vec{x} = \vec{b}$

$$A = \begin{bmatrix} 1 & 5 \\ 3 & 1 \\ -2 & 4 \end{bmatrix}, \vec{b} = \begin{bmatrix} 4 \\ -2 \\ -3 \end{bmatrix}$$

$\vec{a}_1 \cdot \vec{a}_2 = 5 + 3 - 8 = 0$ Since the columns of A are orthogonal, $\hat{\vec{b}} = \frac{\vec{b} \cdot \vec{a}_1}{\vec{a}_1 \cdot \vec{a}_1} \vec{a}_1 + \frac{\vec{b} \cdot \vec{a}_2}{\vec{a}_2 \cdot \vec{a}_2} \vec{a}_2$

$$(a) \hat{\vec{b}} = \frac{4-6+6}{1+9+4} \begin{bmatrix} 1 \\ 3 \\ -2 \end{bmatrix} + \frac{20-2-12}{25+1+16} \begin{bmatrix} 5 \\ 1 \\ 4 \end{bmatrix} = \frac{2}{7} \begin{bmatrix} 1 \\ 3 \\ -2 \end{bmatrix} + \frac{1}{7} \begin{bmatrix} 5 \\ 1 \\ 4 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$$

$$(b) \hat{\vec{x}} = \begin{bmatrix} 2/7 \\ 1/7 \end{bmatrix}$$

$$11.) A = \begin{bmatrix} 4 & 0 & 1 \\ 1 & -5 & 1 \\ 6 & 1 & 0 \\ 1 & -1 & -5 \end{bmatrix}, \vec{b} = \begin{bmatrix} 9 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\vec{a}_1 \cdot \vec{a}_2 = -5 + 6 - 1 = 0$$

$$\vec{a}_1 \cdot \vec{a}_3 = 4 + 1 - 5 = 0$$

$$\vec{a}_2 \cdot \vec{a}_3 = -5 + 5 = 0$$

$$(a) \hat{\vec{b}} = \frac{36}{54} \begin{bmatrix} 4 \\ 1 \\ 6 \\ 1 \end{bmatrix} + 0 \begin{bmatrix} 0 \\ -5 \\ 1 \\ -1 \end{bmatrix} + \frac{9}{27} \begin{bmatrix} 1 \\ 1 \\ 0 \\ -5 \end{bmatrix} = \frac{2}{3} \begin{bmatrix} 4 \\ 1 \\ 6 \\ 1 \end{bmatrix} + \frac{1}{3} \begin{bmatrix} 1 \\ 1 \\ 0 \\ -5 \end{bmatrix} = \begin{bmatrix} 3 \\ 1 \\ 4 \\ -1 \end{bmatrix}$$

$$(b) \hat{\vec{x}} = \begin{bmatrix} 2/3 \\ 0 \\ 1/3 \end{bmatrix}$$

6.5 continued

17.) True/False. A is an $m \times n$ matrix and $\vec{b} \in \mathbb{R}^m$.

- a.) The general least-squares problem is to find an \vec{x} that makes $A\vec{x}$ as close as possible to \vec{b} .
- b.) A least-squares solution of $A\vec{x} = \vec{b}$ is a vector \hat{x} that satisfies $A\hat{x} = \hat{b}$ where \hat{b} is the orthogonal projection of \vec{b} onto $\text{Col } A$.
- c.) A least-squares solution of $A\vec{x} = \vec{b}$ is a vector \hat{x} such that $\|\vec{b} - A\hat{x}\| \leq \|\vec{b} - A\vec{x}\|$ for all \vec{x} in \mathbb{R}^n .
- d.) Any solution of $A^T A \vec{x} = A^T \vec{b}$ is a least-squares solution of $A\vec{x} = \vec{b}$.
- e.) If the columns of A are linearly independent, then the equation $A\vec{x} = \vec{b}$ has exactly one least-squares solution.

a.) True b.) True c.) False d.) True e.) True

19.) Let A be an $m \times n$ matrix. Use the steps below to show that a vector \vec{x} in \mathbb{R}^n satisfies $A\vec{x} = \vec{0}$ if and only if $A^T A \vec{x} = \vec{0}$. This will show that $\text{Nul } A = \text{Nul } A^T A$.

a.) Show that if $A\vec{x} = \vec{0}$, then $A^T A \vec{x} = \vec{0}$.

b.) Suppose $A^T A \vec{x} = \vec{0}$. Explain why $\vec{x}^T A^T A \vec{x} = 0$ and use this to show that $A\vec{x} = \vec{0}$.

a.) If $A\vec{x} = \vec{0}$, then $A^T A \vec{x} = A^T \vec{0} = \vec{0}$. In other words if \vec{x} is in $\text{Nul } A$, then \vec{x} is in $\text{Nul}(A^T A)$. Thus $\text{Nul } A$ is contained in $\text{Nul}(A^T A)$.

b.) If $A^T A \vec{x} = \vec{0}$, then $\vec{x}^T A^T A \vec{x} = \vec{x}^T \vec{0} = 0$. Since $\vec{x}^T A^T = (A\vec{x})^T$ we have shown $(A\vec{x})^T (A\vec{x}) = 0$ or in other words $\|A\vec{x}\|^2 = 0$. This proves $A\vec{x} = \vec{0}$ therefore $\text{Nul}(A^T A)$ is contained in $\text{Nul } A$.

By combining (a) and (b) we have shown $\text{Nul } A = \text{Nul}(A^T A)$

21.) Let A be an $m \times n$ matrix whose columns are linearly independent.
(Careful, A may not be square.)

a.) Use Exercise 19 to show that $A^T A$ is invertible.

b.) Explain why A must have at least as many rows as columns.

c.) Determine the rank of A .

a.) If the columns of A are linearly independent, then $A\vec{x} = \vec{0}$ has only the trivial solution, so $\text{Nul } A = \{\vec{0}\}$. By #19 $\text{Nul } A = \text{Nul}(A^T A) = \{\vec{0}\}$. Since $\text{Nul}(A^T A) = \{\vec{0}\}$, $A^T A$ is invertible.

b.) Since the n linearly independent columns of A belong to \mathbb{R}^m , m cannot be less than n .

c.) Since the columns of A are linearly independent, these columns form a basis for $\text{Col } A$, so $\text{rank } A = n$.