<http://www.societyofrobots.com/member_tutorials/node/71>

* Link is to a post relating the pros and cons of infrared sensors to ultrasonic sensors. Infrared is not as accurate, can’t be used outside, and not on certain colors, but is monetarily cheaper. Ultrasonic is more accurate, has a further range, and can be used in any light, but is more expensive and soft surfaces can give faulty readings.
  + Since color tracking is an essential part of RoboCat and since we already have an ultrasonic device, using an ultrasonic device is the path we decided to use

<http://www.tautvidas.com/blog/2012/08/distance-sensing-with-ultrasonic-sensor-and-arduino/>

* Link is to working code that implements an ultrasonic device as a distance tracker using Arduino. This could be useful as we implement our own version to map the environment.

<http://playground.arduino.cc/Code/NewPing>

* Link is to an ultrasonic device library used to set up the device for distance measurement. This library could be very useful when setting up our device.