

Profile HMM for multiple sequences

# Pair HMM

HMM for pairwise sequence alignment,  
which incorporates affine gap scores.

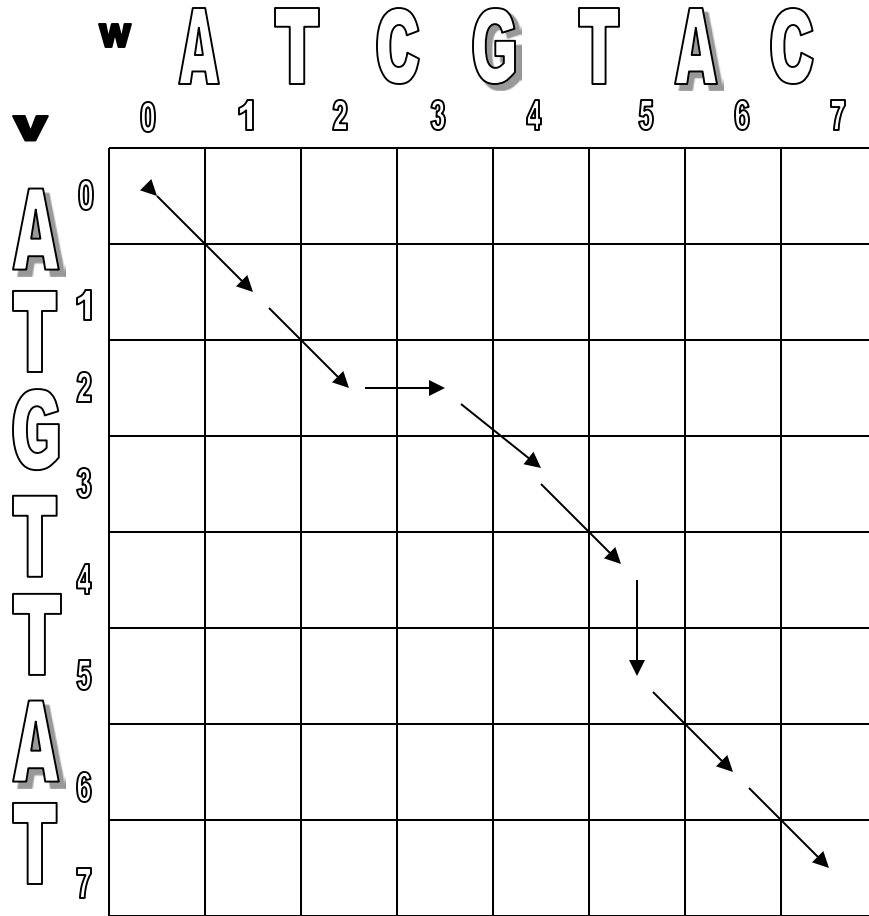
## “Hidden” States

- Match (M)
- Insertion in  $x$  (X)
- insertion in  $y$  (Y)

## Observation Symbols

- Match (M):  $\{(a,b) \mid a,b \text{ in } \Sigma \}$ .
- Insertion in  $x$  (X):  $\{(a,-) \mid a \text{ in } \Sigma \}$ .
- Insertion in  $y$  (Y):  $\{(-,a) \mid a \text{ in } \Sigma \}$ .

# Alignment: a path $\rightarrow$ a hidden state sequence

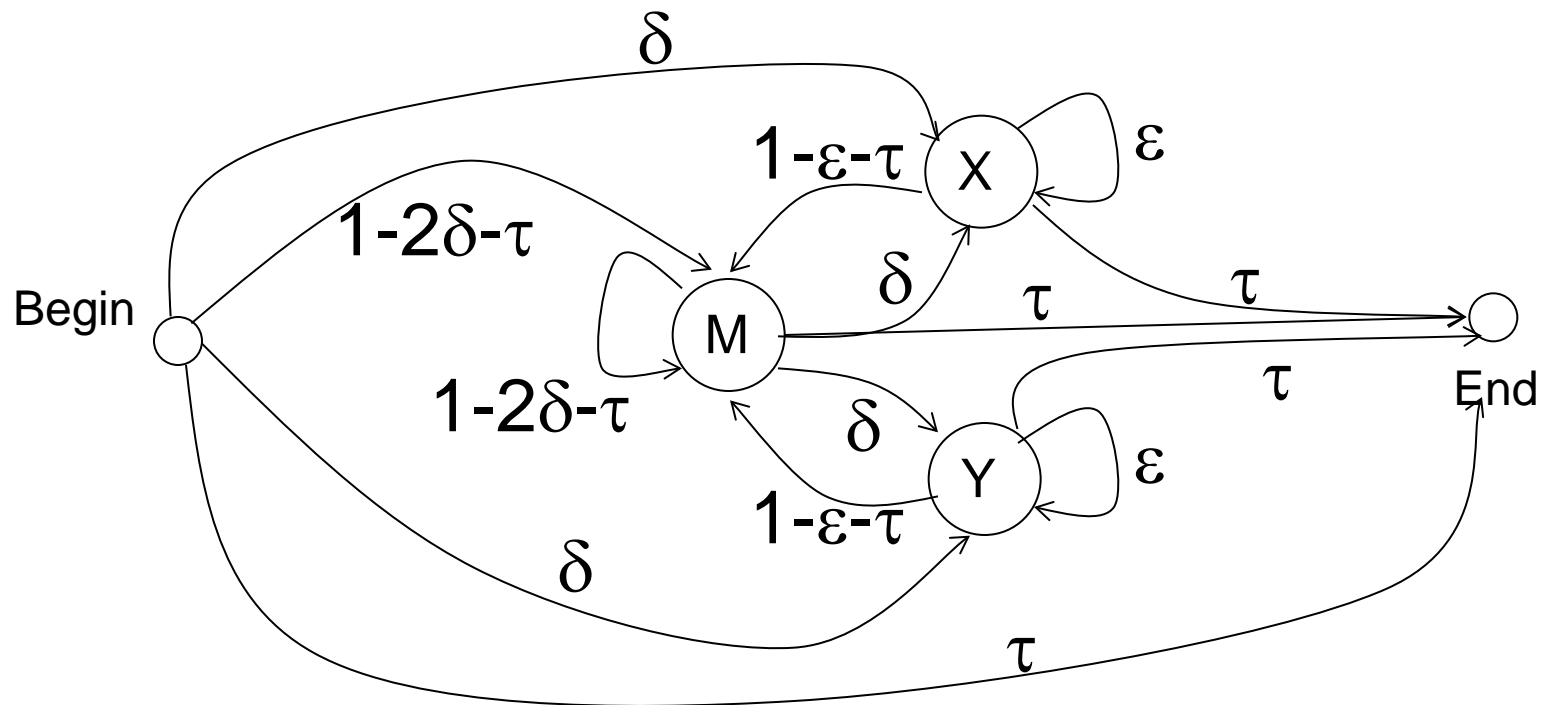


A T - G T T A T

A T C G T - A C

M M Y M M X M M

# Pair HMMs



# Multiple sequence alignment (Globin family)

```

Helix          AAAAAAAAAAAAAAAAAA  BBBBBBBBBBBBBBBBBBCCCCCCCCCCCC
HBA_HUMAN      -----VLSPADKTNVKAAWGKVGA--HAGEYGAEALERMFLSFPTTKTYFPHF
HBB_HUMAN      -----VHLTPEEKSAVTALWGKV---NVDEVGGEALGRLLVVYPWTQRFFESF
MYG_PHYCA      -----VLSEGEWQLVLHVWAKVEA--DVAGHGQDILIRLFKSHPETLEKFDRF
GLB3_CHITP     -----LSADQISTVQASFDKVKG-----DPVGILYAVFKADPSIMAKFTQF
GLB5_PETMA     PIVDTGSVAPLSAAEKTIRSAWAPVYS--TYETSGVDILVKFFTSTPAAQEFFPKF
LGB2_LUPLU     -----GALTESQAALVKSSWEEFN--NIPKHTHRFFILVLEIAPAAKDLFS-F
GLB1_GLYDI     -----GLSAAQRQVIAATWKDIAGADNGAGVGKDCLIKFLSAHPQMAAVFG-F
Consensus      Ls.... v a W kv . . g . L.. f . P . F F

```

```

Helix          DDDDDDDDEEEEEEEEEEEEEEEEEEEEEEE FFFFFFFF
HBA_HUMAN      -DLS-----HGSAQVKGHGKKVADALTNAVAHV--D--DMPNALSALSDLHAHKL-
HBB_HUMAN      GDLSTPDVAVMGNPKVKAHGKKVLGAFSDGLAHL--D--NLKGTATLSELHCDKL-
MYG_PHYCA      KHLKTEAEMKASEDLKKHGVTVLTAIGAILKK---K-GHHEAELKPLAQSHATKH-
GLB3_CHITP     AG-KDLESIKGTAPFETHANRIVGFFSKIIGEL--P---NIEADVNTFVASHKPRG-
GLB5_PETMA     KGLTTADQLKKSADVRWHAERIINAVNDAVASM--DDEKMSMKLRDLGKHAASF-
LGB2_LUPLU     LK-GTSEVPQNNPELQAHAGKVFCLVYEAAIQLOVTVGVVTDATLKNLGSVHVSFG-
GLB1_GLYDI     SG----AS---DPGVAALGAKVLAQIGVAVSHL--GDEGKMVAQMKAVGVRHKGYN
Consensus      . t . . . v..Hg kv. a a...l d . a l. l H .

```

```

Helix          FFGGGGGGGGGGGGGGGGGGGGGG HHHHHHHHHHHHHHHHHHHHHHHHHHHHH
HBA_HUMAN      -RVDPVNFKLLSHCLLVTLAAHLPAEFTPAVHASLDKFLASVSTVLTSKYR-----
HBB_HUMAN      -HVDPENFRLLGNVLVCVLAHHFGKEFTPPVQAAYQKVVAGVANALAHKYH-----
MYG_PHYCA      -KIPIKYLEFISEAIIHVLHSRHPGDFGADAQGAMNKALELFRKDIAAKYKELGYQG
GLB3_CHITP     --VTHDQLNNFRAGFVSVMKAHT--DFA-GAEAAWGATLDTFFGMIFSKM-----
GLB5_PETMA     -QVDPQYFKVLAAVIADTVAAG-----DAGFEKLMSMICILLRSAY-----
LGB2_LUPLU     --VADAHFPVVKAILKTIKEVVGAKWSEELNSAWTIAYDELAIVIKKEMNDAA---
GLB1_GLYDI     KHIKAQYFEPLGASLLSAMEHRIGGKMNAAKDAWAAAYADISGALISGLQS-----
Consensus      v. f l . . . . . f . aa. k. . l sky

```

# Profile model (PSSM)

- A natural probabilistic model for a conserved region would be to specify independent probabilities  $e_i(a)$  of observing nucleotide (amino acid)  $a$  in position  $i$
- The probability of a new sequence  $x$  according to this model is

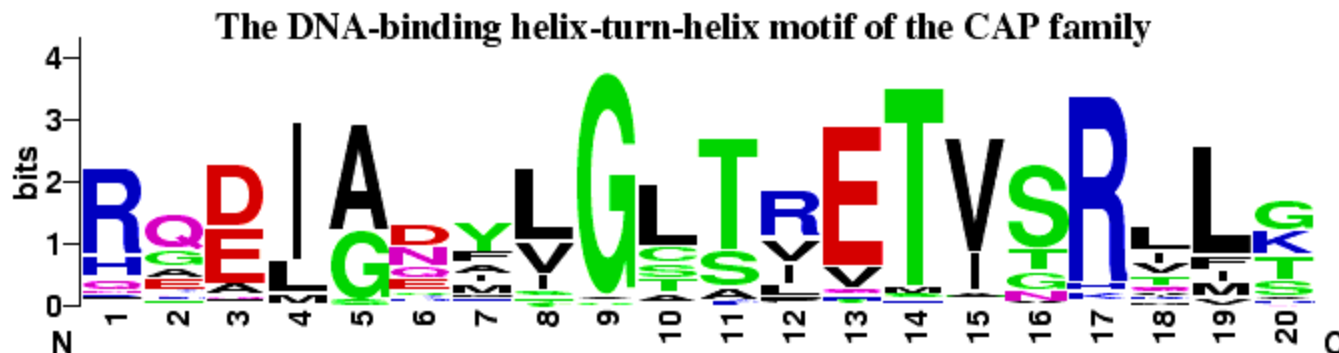
$$P(x \mid M) = \prod_{i=1}^L e_i(x_i)$$

# Profile / PSSM

- DNA / proteins Segments of the same length L;
- Often represented as Positional frequency matrix;

```

LTMTRGDIGNYLGLTVETISRLLGRFQKSGML
LTMTRGDIGNYLGLTIETISRLLGRFQKSGMI
LTMTRGDIGNYLGLTVETISRLLGRFQKSEIL
LTMTRGDIGNYLGLTVETISRLLGRLQKMGIL
LAMSrneIGNYLGLAVETVSRVFSRFQQNELI
LAMSrneIGNYLGLAVETVSRVFTRFQQNGLI
LPMSrneIGNYLGLAVETVSRVFTRFQQNGLL
VRMSreeIGNYLGLTLETVSRLFSRFGREGLI
LRMSreeIGSYLGLKLETVSRTLskFHQEGLI
LPMCRRDIGDYLGLTLETVSRALSQLHTQGIL
LPMSRRDIADYLGLTVETVSRAVSQlHTDGVl
LPMSRQDIADYLGLTIETVSRTFTKLERHGAI
    
```



# Searching profiles: inference

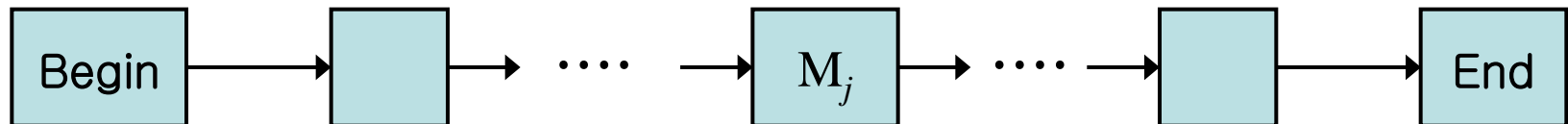
- Give a sequence  $S$  of length  $L$ , compute the likelihood ratio of being generated from this profile vs. from background model:
  - $R(S|P) = \prod_{i=1}^L \frac{e_i(x_i)}{b_s}$
  - Searching motifs in a sequence: sliding window approach



# Match states for profile HMMs

- Match states
  - Emission probabilities

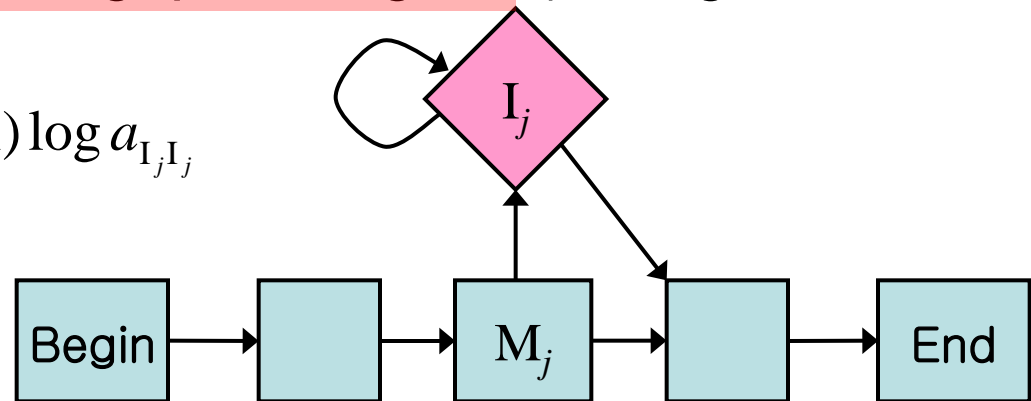
$$e_{M_i}(a)$$



# Components of profile HMMs

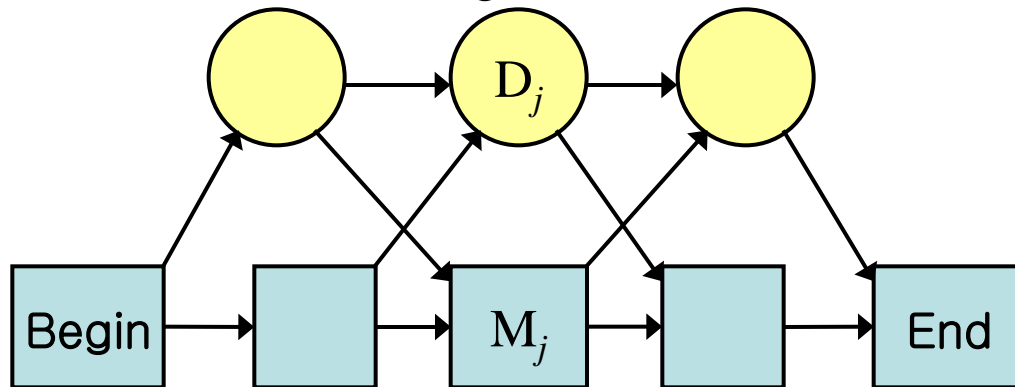
- Insert states  $e_{I_i}(a)$ 
  - Emission prob.
    - Usually back ground distribution  $q_a$ .
  - Transition prob.
    - $M_i$  to  $I_i$ ,  $I_i$  to itself,  $I_i$  to  $M_{i+1}$
  - Log-odds score for a gap of length  $k$  (no log-odds from emission)

$$\log a_{M_j I_j} + \log a_{I_j M_{j+1}} + (k-1) \log a_{I_j I_j}$$

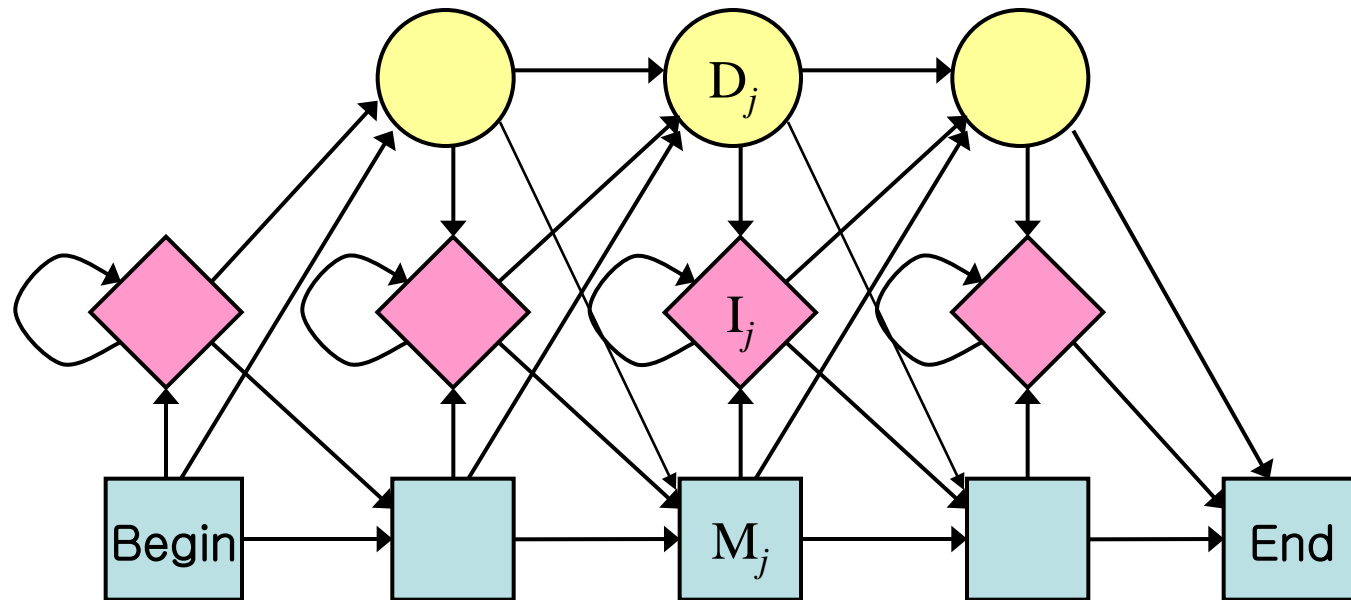


# Components of profile HMMs

- Delete states
  - No emission prob.
  - Cost of a deletion
    - $M \rightarrow D$ ,  $D \rightarrow D$ ,  $D \rightarrow M$
    - Each  $D \rightarrow D$  might be different



# Full structure of profile HMMs



# Deriving HMMs from multiple alignments

- Key idea behind profile HMMs
  - Model representing the consensus for the alignment of sequence from **the same family**
  - Not the sequence of any particular member

```
HBA_HUMAN   . . . VGA--HAGEY . . .
HBB_HUMAN   . . . V----NVDEV . . .
MYG_PHYCA   . . . VEA--DVAGH . . .
GLB3_CHITP   . . . VKG-----D . . .
GLB5_PETMA   . . . VYS--TYETS . . .
LGB2_LUPLU   . . . FNA--NIPKH . . .
GLB1_GLYDI   . . . IAGADNGAGV . . .
              * * *   * * * * *
```

# Deriving HMMs from multiple alignments

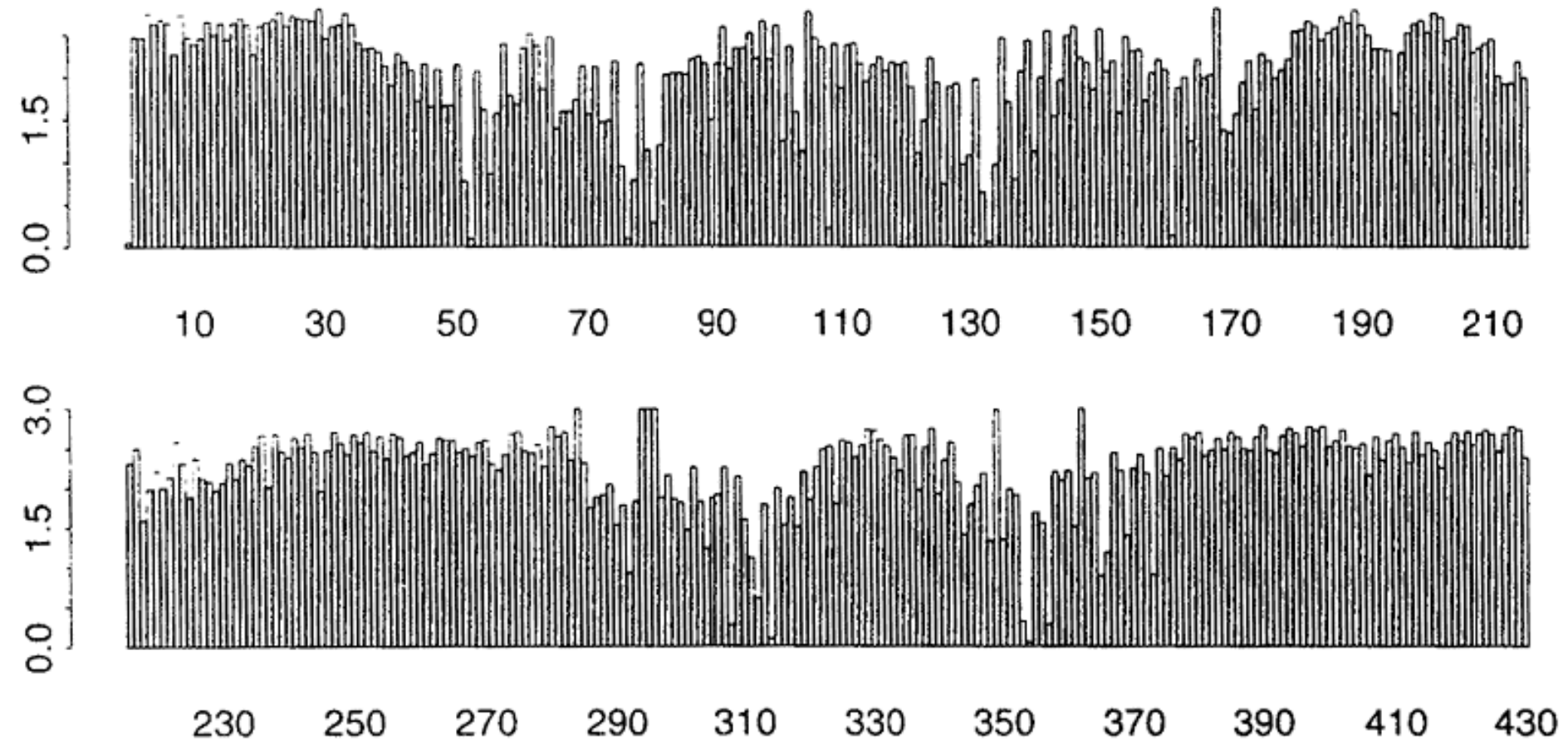
- Basic profile HMM parameterization
  - Aim: making the higher probability for sequences from the family
- Parameters
  - the probabilities values : trivial if many of independent alignment sequences are given.

$$a_{kl} = \frac{A_{kl}}{\sum_{l'} A_{kl'}} \quad e_k(a) = \frac{E_k(a)}{\sum_{a'} E_k(a')}$$

- length of the model: heuristics or systematic way

# Sequence conservation: entropy profile of the emission probability distributions

Main State Entropy Values



# Searching with profile HMMs

- Main usage of profile HMMs
  - Detecting potential sequences in a family
  - Matching a sequence to the profile HMMs
    - Viterbi algorithm or forward algorithm
  - Comparing the resulting probability with random model

$$P(x | R) = \prod_i q_{x_i}$$



# Searching with profile HMMs

- Viterbi algorithm (optimal log-odd alignment)

$$V_j^M(i) = \log \frac{e_{M_j}(x_i)}{q_{x_i}} + \max \begin{cases} V_{j-1}^M(i-1) + \log a_{M_{j-1}M_j}, \\ V_{j-1}^I(i-1) + \log a_{I_{j-1}M_j}, \\ V_{j-1}^D(i-1) + \log a_{D_{j-1}M_j}; \end{cases}$$

$$V_j^I(i) = \log \frac{e_{I_j}(x_i)}{q_{x_i}} + \max \begin{cases} V_j^M(i-1) + \log a_{M_jI_j}, \\ V_j^I(i-1) + \log a_{I_jI_j}, \\ V_j^D(i-1) + \log a_{D_jI_j}; \end{cases}$$

$$V_j^D(i) = \max \begin{cases} V_{j-1}^M(i) + \log a_{M_{j-1}D_j}, \\ V_{j-1}^I(i) + \log a_{I_{j-1}D_j}, \\ V_{j-1}^D(i) + \log a_{D_{j-1}D_j}; \end{cases}$$

# Searching with profile HMMs

- Forward algorithm: summing over all potent alignments

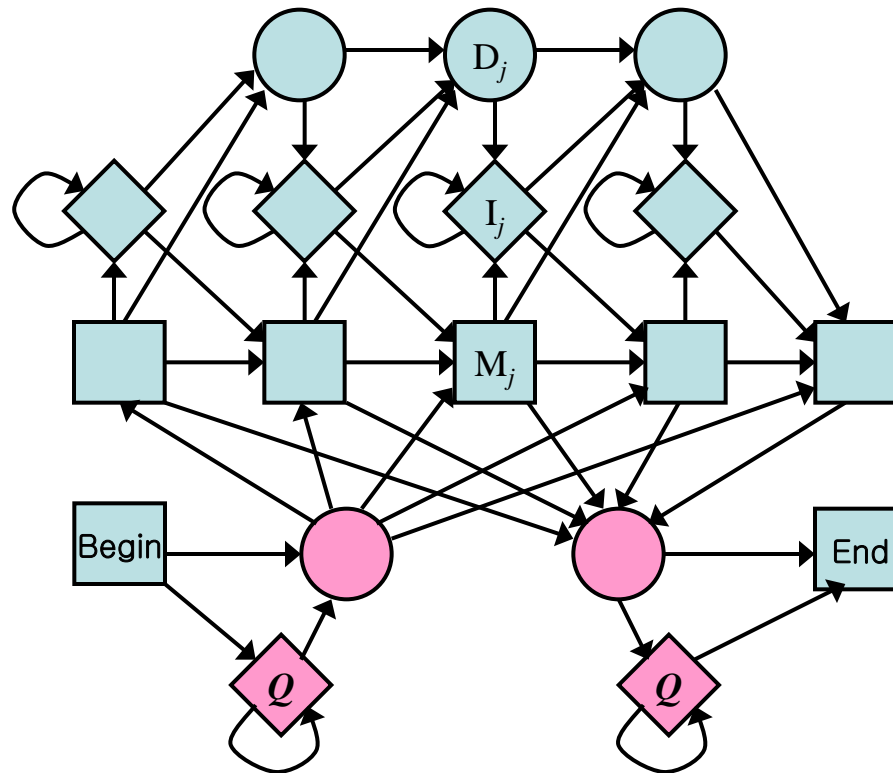
$$F_j^M(i) = \log \frac{e_{M_j}(x_i)}{q_{x_i}} + \log[a_{M_{j-1}M_j} \exp(F_{j-1}^M(i-1)) \\ + a_{I_{j-1}M_j} \exp(F_{j-1}^I(i-1)) + a_{D_{j-1}M_j} \exp(F_{j-1}^D(i-1))];$$

$$F_j^I(i) = \log \frac{e_{I_j}(x_i)}{q_{x_i}} + \log[a_{M_jI_j} \exp(F_j^M(i-1)) \\ + a_{I_jI_j} \exp(F_j^I(i-1)) + a_{D_jI_j} \exp(F_j^D(i-1))];$$

$$F_j^D(i) = \log[a_{M_{j-1}D_j} \exp(F_{j-1}^M(i)) + a_{I_{j-1}D_j} \exp(F_{j-1}^I(i)) \\ + a_{D_{j-1}D_j} \exp(F_{j-1}^D(i))];$$

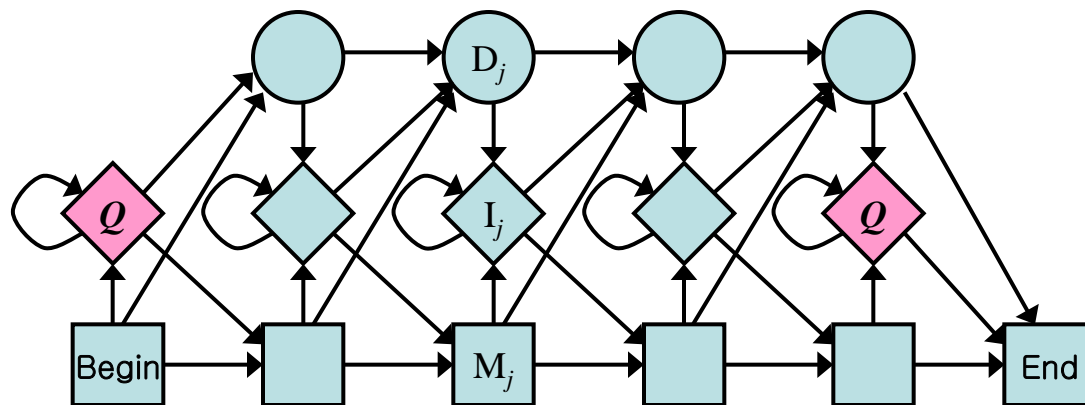
# Variants for non-global alignments

- Local alignments (flanking model)
  - Emission prob. in flanking states use background values  $q_a$ .
  - Looping prob. close to 1, e.g.  $(1 - \eta)$  for some small  $\eta$ .



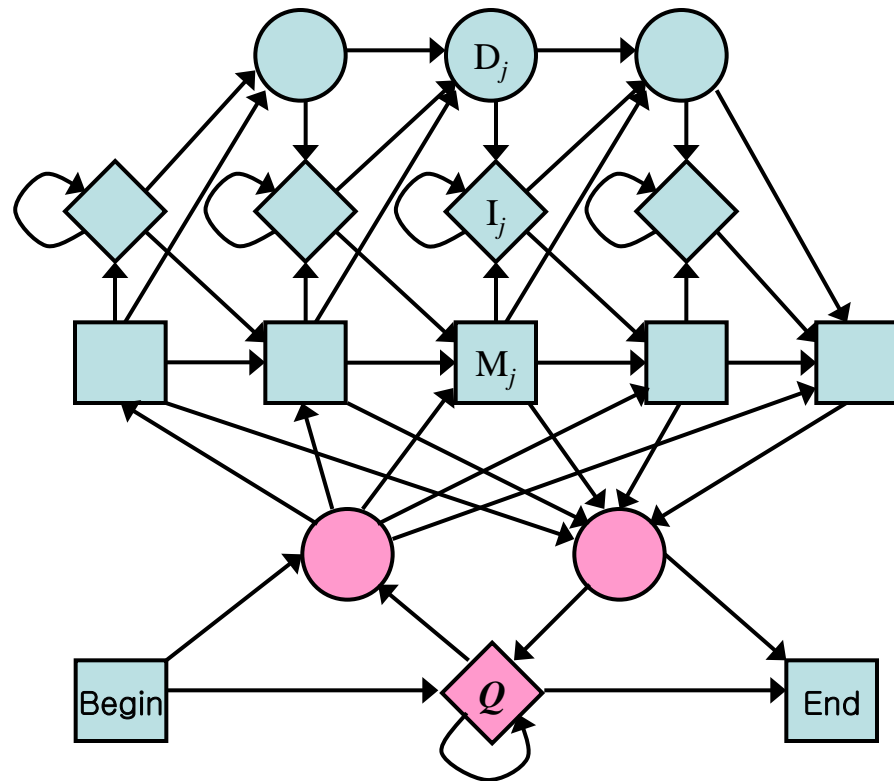
# Variants for non-global alignments

- Overlap alignments
  - Only transitions to the first model state are allowed.
  - When expecting to find either present as a whole or absent
  - Transition to first delete state allows missing first residue



# Variants for non-global alignments

- Repeat alignments
  - Transition from right flanking state back to random model
  - Can find multiple matching segments in query string



# Estimation of prob.

- Maximum likelihood (ML) estimation
  - given observed freq.  $c_{ja}$  of residue  $a$  in position  $j$ .

$$e_{M_j}(a) = \frac{c_{ja}}{\sum_{a'} c_{ja'}}$$

- Simple pseudocounts
  - $q_a$ : background distribution
  - $A$ : weight factor

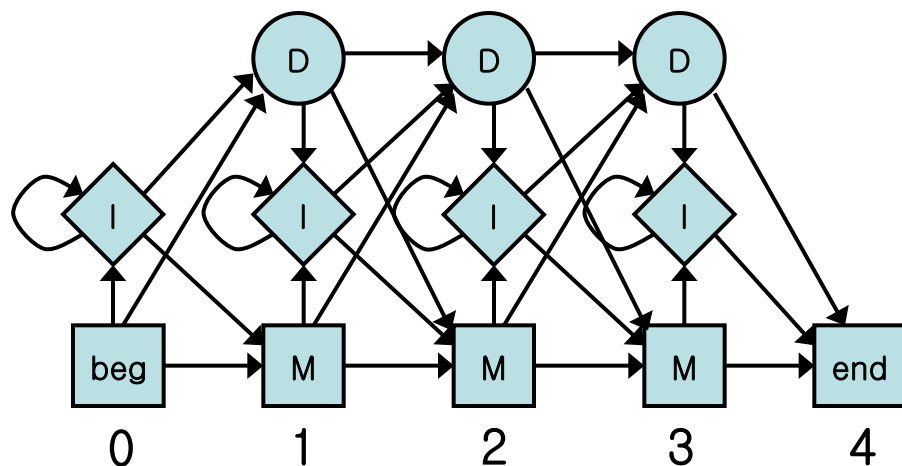
$$e_{M_j}(a) = \frac{c_{ja} + Aq_a}{A + \sum_{a'} c_{ja'}}$$

# Optimal model construction: mark columns

(a) Multiple alignment:

	x	x	.	.	.	x
bat	A	G	-	-	-	C
rat	A	-	A	G	-	C
cat	A	G	-	A	A	-
gnat	-	-	A	A	A	C
goat	A	G	-	-	-	C
	1	2	.	.	.	3

(b) Profile-HMM architecture:



(c) Observed emission/transition counts

		0	1	2	3
match emissions	A	-	4	0	0
	C	-	0	0	4
	G	-	0	3	0
	T	-	0	0	0
insert emissions	A	0	0	6	0
	C	0	0	0	0
	G	0	0	1	0
	T	0	0	0	0
state transitions	M-M	4	3	2	4
	M-D	1	1	0	0
	M-I	0	0	1	0
	I-M	0	0	2	0
	I-D	0	0	1	0
	I-I	0	0	4	0
	D-M	-	0	0	1
	D-D	-	1	0	0
	D-I	-	0	2	0

# Optimal model construction

- MAP (match-insert assignment)
  - Recursive calculation of a number  $S_j$ 
    - $S_j$ : log prob. of the optimal model for alignment up to and including column  $j$ , assuming  $j$  is marked.
    - $S_j$  is calculated from  $S_i$  and summed log prob. between  $i$  and  $j$ .
    - $T_{ij}$ : summed log prob. of all the state transitions between marked  $i$  and  $j$ .

$$T_{ij} = \sum_{x,y \in M,D,I} c_{xy} \log a_{xy}$$

- $c_{xy}$  are obtained from partial state paths implied by marking  $i$  and  $j$ .



# Optimal model construction

- Algorithm: MAP model construction

- Initialization:

- $S_0 = 0, M_{L+1} = 0.$

- Recurrence: for  $j = 1, \dots, L+1$ :

$$S_j = \max_{0 \leq i < j} S_i + T_{ij} + M_j + I_{i+1, j-1} + \lambda;$$

$$\sigma_j = \arg \max_{0 \leq i < j} S_i + T_{ij} + M_j + I_{i+1, j-1} + \lambda;$$

- Traceback: from  $j = \sigma_{L+1}$ , while  $\sigma_j > 0$ :

- Mark column  $j$  as a match column

- $j = \sigma_j.$

# Weighting training sequences

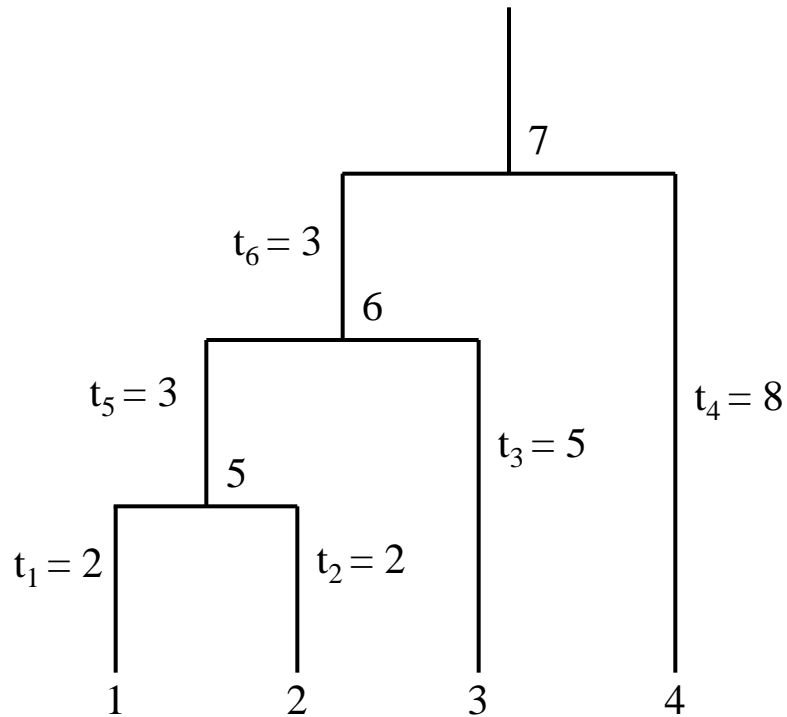
- Input sequences are random?
- “Assumption: all examples are independent samples” might be incorrect
- Solutions
  - Weight sequences based on similarity

# Weighting training sequences

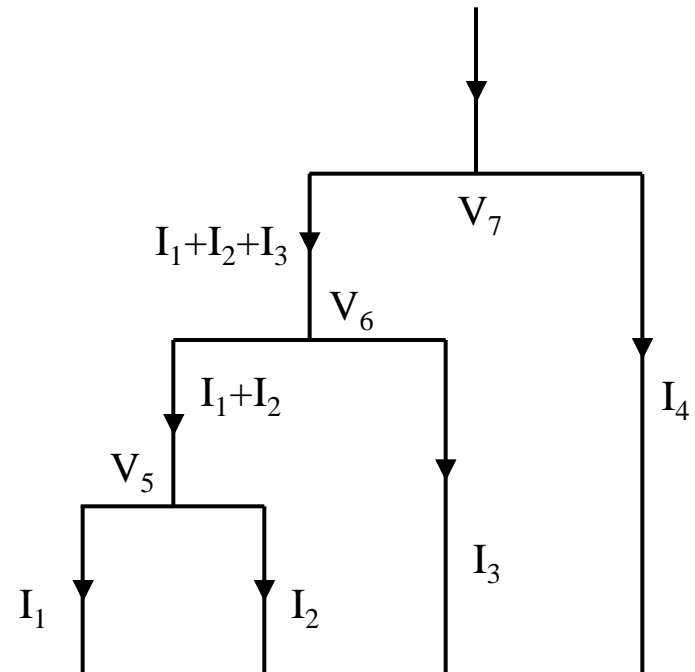
- Simple weighting schemes derived from a tree
  - Phylogenetic tree is given.
  - [Thompson, Higgins & Gibson 1994b]
  - [Gerstein, Sonnhammer & Chothia 1994]

$$\Delta w_i = t_n \frac{w_i}{\sum_{\text{leaves } k \text{ below } n} w_k}$$

# Weighting training sequences



$$w_1:w_2:w_3:w_4 = 35:35:50:64$$



$$I_1:I_2:I_3:I_4 = 20:20:32:47$$

# Multiple alignment by training profile HMM

- Sequence profiles could be represented as probabilistic models like profile HMMs.
  - Profile HMMs could simply be used in place of standard profiles in progressive or iterative alignment methods.
  - ML methods for building (training) profile HMM (described previously) are based on multiple sequence alignment.
  - Profile HMMs can also be trained from initially unaligned sequences using the Baum-Welch (EM) algorithm

# Multiple alignment by profile HMM training- Multiple alignment with a known profile HMM

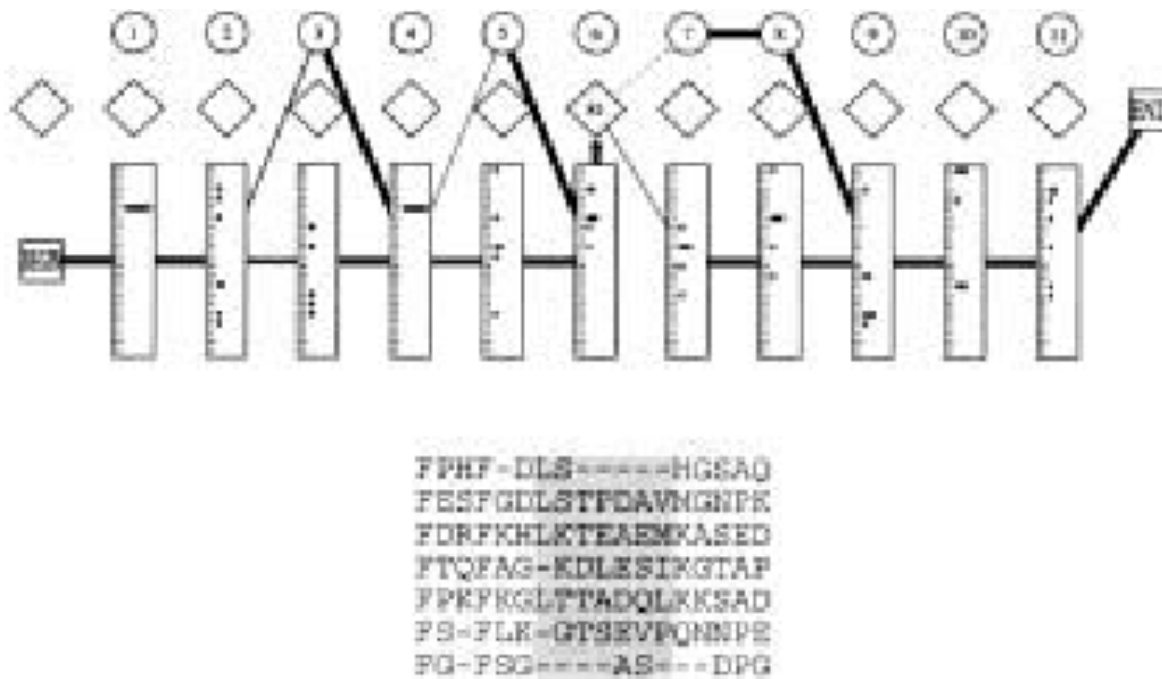
- Before we estimate a model and a multiple alignment simultaneously, we consider as simpler problem: derive a multiple alignment from a known profile HMM model.
  - This can be applied to align a large member of sequences from the same family based on the HMM model built from the (seed) multiple alignment of a small representative set of sequences in the family.

# Multiple alignment with a known profile HMM

- Align a sequence to a profile  
HMM → Viterbi algorithm
- Construction a multiple alignment just requires calculating a Viterbi alignment for each individual sequence.
  - Residues aligned to the same match state in the profile HMM should be aligned in the same columns.

# Multiple alignment with a known profile HMM

- Given a preliminary alignment, HMM can align additional sequences.





# Multiple alignment with a known profile HMM

- | Position | 1 | 2 | 3 | 4 | 5 | 6 | insert  | 7 | 8 | 9 | 10 | 11 |
|----------|---|---|---|---|---|---|---------|---|---|---|----|----|
|          | F | P | H | F | – | D | LS      | H | G | S | A  | Q  |
|          | F | E | S | F | G | D | LSTPDAV | M | G | N | P  | K  |
|          | F | D | R | F | K | H | LKTEAEM | K | A | S | E  | D  |
|          | F | T | Q | F | A | G | KDLESI  | K | G | T | A  | P  |
|          | F | P | K | F | K | G | LTTADQL | K | K | S | A  | D  |
|          | F | S | – | F | L | K | GTSEVP  | Q | N | N | P  | E  |
|          | F | G | – | F | S | G | AS      | – | – | D | P  | G  |

# Multiple alignment with a known profile HMM

- Important difference with other MSA programs
  - Viterbi path through HMM identifies inserts
  - Profile HMM does not align inserts
  - Other multiple alignment algorithms align the whole sequences.

```
FPHF-Dls.....HGSAQ
FESFGDlstpdavMGNPK
FDRFKHlkteaemKASED
FTQFAGkdlesi.KGTAP
FPKFKGlttadqlKKSAD
FS-FLKgtsevp.QNNPE
FG-FSGas.....--DPG
```

```
FS-FLKngvdptaa1--NPK
FPHF-Dls.....HGSAQ
FESFGDlstpdav..MGNPK
FDRFKHlkteaem..KASED
FTQFAGkdlesi...KGTAP
FPKFKGlttadql..KKSAD
FS-FLKgtsevp...QNNPE
FG-FSGas.....--DPG
```

# Profile HMM training from unaligned sequences

- Harder problem
  - estimating both a model and a multiple alignment from initially unaligned sequences.
  - Initialization: Choose the length of the profile HMM and initialize parameters.
  - Training: estimate the model using the Baum-Welch algorithm (iteratively).
  - Multiple Alignment: Align all sequences to the final model using the Viterbi algorithm and build a multiple alignment as described in the previous section.

# Profile HMM training from unaligned sequences

- Initial Model
  - The only decision that must be made in choosing an initial structure for Baum-Welch estimation is the length of the model  $M$ .
  - A commonly used rule is to set  $M$  be the average length of the training sequence.
  - We need some randomness in initial parameters to avoid local maxima.

# Multiple alignment by profile HMM training

- Avoiding Local maxima
  - Baum-Welch algorithm is guaranteed to find a LOCAL maxima.
    - Models are usually quite long and there are many opportunities to get stuck in a wrong solution.
  - Solution
    - Start many times from different initial models.
    - Use some form of stochastic search algorithm, e.g. simulated annealing.

# Multiple alignment by profile HMM - similar to Gibbs sampling

- The 'Gibbs sampler' algorithm described by Lawrence et al.[1993] has substantial similarities.
  - The problem was to simultaneously find the motif positions and to estimate the parameters for a consensus statistical model of them.
  - The statistical model used is essentially a profile HMM with no insert or delete states.

# Multiple alignment by profile HMM training-Model surgery

- We can modify the model after (or during) training a model by manually checking the alignment produced from the model.
  - Some of the match states are redundant
  - Some insert states absorb too many sequences
- Model surgery
  - If a match state is used by less than  $\frac{1}{2}$  of training sequences, delete its module (match-insert-delete states)
  - If more than  $\frac{1}{2}$  of training sequences use a certain insert state, expand it into  $n$  new modules, where  $n$  is the average length of insertions
  - ad hoc, but works well

# Phylo-HMMs: model multiple alignments of syntenic sequences

- A phylo-HMM is a probabilistic machine that generates a multiple alignment, column by column, such that each column is defined by a phylogenetic model
- Unlike single-sequence HMMs, the emission probabilities of phylo-HMMs are complex distributions defined by phylogenetic models



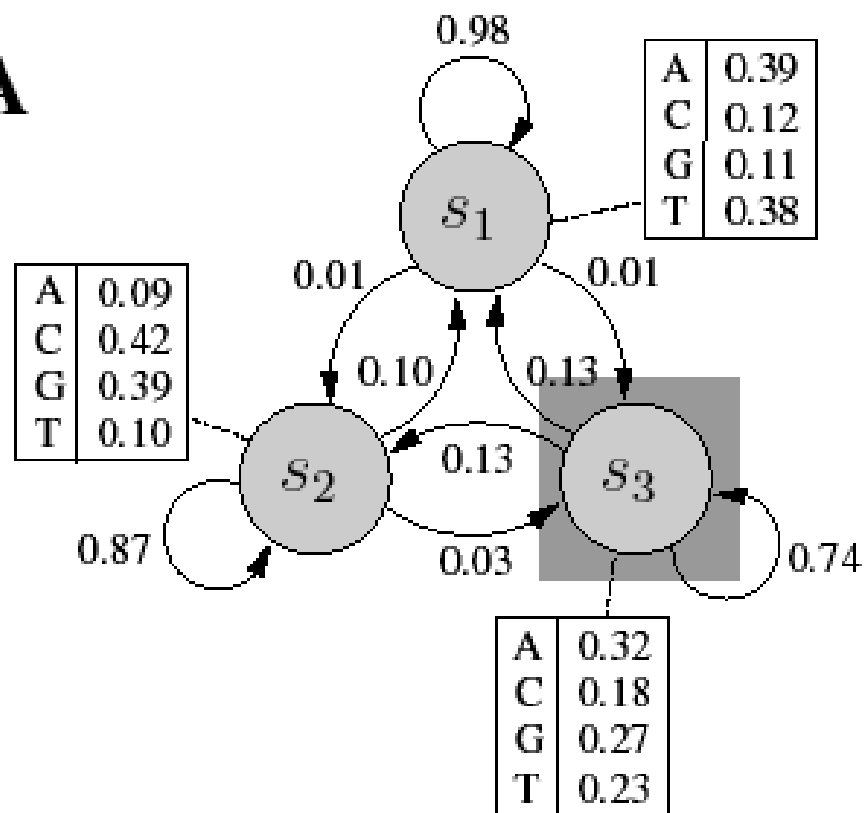
# Applications of Phylo-HMMs

- Improving phylogenetic modeling that allow for variation among sites in the rate of substitution (Felsenstein & Churchill, 1996; Yang, 1995)
- Protein secondary structure prediction (Goldman et al., 1996; Thorne et al., 1996)
- Detection of recombination from DNA multiple alignments (Husmeier & Wright, 2001)
- Recently, comparative genomics (Siepel, et. al. Haussler, 2005)

# Phylo-HMMs: combining phylogeny and HMMs

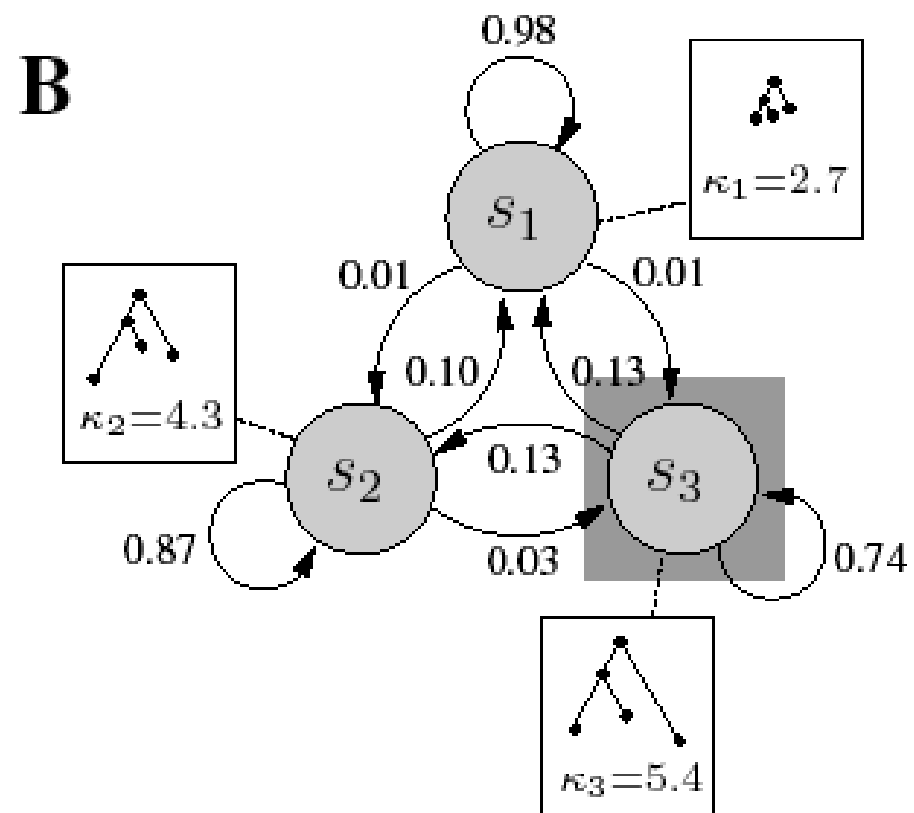
- Molecular evolution can be viewed as a combination of two Markov processes
  - One that operates in the dimension of **space** (along a genome)
  - One that operates in the dimension of **time** (along the branches of a phylogenetic tree)
- Phylo-HMMs model this combination

# Single-sequence HMM



$X = \text{TAACGGCAGA} \dots$

# Phylo-HMM



$X = \begin{matrix} \text{TAACGGCAGA} \dots \\ \text{TTAGGCAAGG} \dots \\ \text{AAGGCGCCGA} \dots \end{matrix} \dots$

# Phylogenetic models

- Stochastic process of substitution that operates independently at each site in a genome
- A character is first drawn at random from the background distribution and assigned to the root of the tree; character substitutions then occur randomly along the tree branches, from root to leaves
- The characters at the leaves define an alignment column

# Phylogenetic Models

- The different phylogenetic models associated with the states of a phylo-HMM may reflect different overall rates of substitution (e.g. in conserved and non-conserved regions), different patterns of substitution or background distributions, or even different tree topologies (as with recombination)

# Phylo-HMMs: Formal Definition

- A phylo-HMM is a 4-tuple  $\theta = (S, \psi, A, b)$ :
  - $S = \{s_1, \dots, s_M\}$  : set of hidden states
  - $\psi = \{\psi_1, \dots, \psi_M\}$  : set of associated phylogenetic models
  - $A = \{a_{j,k}\} \quad (1 \leq j, k \leq M)$  : transition probabilities
  - $b = (b_1, \dots, b_M)$  : initial probabilities

# The Phylogenetic Model

- $\psi_j = (Q_j, \pi_j, \tau_j, \beta_j) :$ 
  - $Q_j$  : substitution rate matrix
  - $\pi_j$  : background frequencies
  - $\tau_j$  : binary tree
  - $\beta_j$  : branch lengths

# The Phylogenetic Model

- The model is defined with respect to an alphabet  $\Sigma$  whose size is denoted  $d$
- The substitution rate matrix has dimension  $d \times d$
- The background frequencies vector has dimension  $d$
- The tree has  $n$  leaves, corresponding to  $n$  extant taxa
- The branch lengths are associated with the tree



# Probability of the Data

- Let  $X$  be an alignment consisting of  $L$  columns and  $n$  rows, with the  $i^{\text{th}}$  column denoted  $X_i$
- The probability that column  $X_i$  is emitted by state  $s_j$  is simply the probability of  $X_i$  under the corresponding phylogenetic model,  $P(X_i | \psi_j)$
- This is the likelihood of the column given the tree, which can be computed efficiently using Felsenstein's "pruning" algorithm (which we will describe in later lectures)

# Substitution Probabilities

- Felsenstein's algorithm requires the conditional probabilities of substitution for all bases  $a, b \in \Sigma$  and branch lengths  $t \in \beta_j$
- The probability of substitution of a base  $b$  for a base  $a$  along a branch of length  $t$ , denoted  $P(b \mid a, t, \psi_j)$  is based on a continuous-time Markov model of substitution, defined by the rate matrix  $Q_j$

# Substitution Probabilities

- In particular, for any given non-negative value  $t$ , the conditional probabilities  $P(b \mid a, t, \psi_j)$  for all  $a, b \in \Sigma$  are given the  $d \times d$  matrix  $P_j(t) = \exp(Q_j t)$ , where

$$\exp(Q_j t) = \sum_{k=0}^{\infty} \frac{(Q_j t)^k}{k!}$$

# Example: HKY model

$$Q_j = \begin{pmatrix} - & \pi_{C,j} & \kappa_j \pi_{G,j} & \pi_{T,j} \\ \pi_{A,j} & - & \pi_{G,j} & \kappa_j \pi_{T,j} \\ \kappa_j \pi_{A,j} & \pi_{C,j} & - & \pi_{T,j} \\ \pi_{A,j} & \kappa_j \pi_{C,j} & \pi_{G,j} & - \end{pmatrix}$$

$$\pi_j = (\pi_{A,j}, \pi_{C,j}, \pi_{G,j}, \pi_{T,j})$$

$\kappa_j$  represents the transition/transversion rate ratio for  $\psi_j$

'-'s indicate quantities required to normalize each row.

# State sequences in Phylo-HMMs

- A state sequence through the phylo-HMM is a sequence  $\phi = (\phi_1, \dots, \phi_L)$  such that  $\phi_i \in S \ \forall 1 \leq i \leq L$
- The joint probability of a path and alignment is

$$P(\phi, X \mid \theta) = \beta_{\phi_1} P(X_1 \mid \psi_{\phi_1}) \prod_{i=2}^L a_{\phi_{i-1}\phi_i} P(X_i \mid \psi_{\phi_i})$$

# Phylo-HMMs

- The likelihood is given by the sum over all paths (forward algorithm)

$$P(X \mid \theta) = \sum_{\phi} P(\phi, X \mid \theta)$$

- The maximum-likelihood path is (Viterbi's)

$$\hat{\phi} = \arg \max_{\phi} P(\phi, X \mid \theta)$$

# Computing the Probabilities

- The likelihood can be computed efficiently using the **forward** algorithm
- The maximum-likelihood path can be computed efficiently using the **Viterbi** algorithm
- The **forward** and **backward** algorithms can be combined to compute the posterior probability

$$P(\phi_i = j \mid X, \theta)$$

# Higher-order Markov Models for Emissions

- It is common with gene-finding HMMs to condition the emission probability of each observation on the observations that immediately precede it in the sequence
- For example, in a 3-rd-codon-position state, the emission of a base  $x_i = \text{"A"}$  might have a fairly high probability if the previous two bases are  $x_{i-2} = \text{"G"}$  and  $x_{i-1} = \text{"A"}$  (GAA=Glu), but should have zero probability if the previous two bases are  $x_{i-2} = \text{"T"}$  and  $x_{i-1} = \text{"A"}$  (TAA=stop)



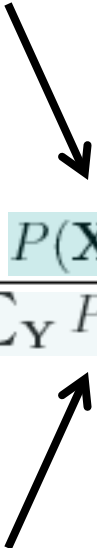
# Higher-order Markov Models for Emission

- Considering the  $N$  observations preceding each  $x_i$  corresponds to using an  $N^{\text{th}}$  order Markov model for emissions
- An  $N^{\text{th}}$  order model for emissions is typically parameterized in terms of  $(N+1)$ -tuples of observations, and conditional probabilities are computed as

$$P(x_i | x_{i-N}, \dots, x_{i-1}) = \frac{P(x_{i-N}, \dots, x_{i-1}, x_i)}{\sum_y P(x_{i-N}, \dots, x_{i-1}, y)}$$

# N<sup>th</sup> Order Phylo-HMMs

Probability of the  $N$ -tuple



The diagram consists of two arrows. One arrow points from the text 'Probability of the N-tuple' down to the numerator of the equation. The other arrow points from the text 'Sum over all possible alignment columns Y' up to the denominator of the equation.

$$P(\mathbf{X}_i | \mathbf{X}_{i-N+1}, \dots, \mathbf{X}_{i-1}) = \frac{P(\mathbf{X}_{i-N+1}, \dots, \mathbf{X}_{i-1}, \mathbf{X}_i)}{\sum_{\mathbf{Y}} P(\mathbf{X}_{i-N+1}, \dots, \mathbf{X}_{i-1}, \mathbf{Y})}$$

Sum over all possible alignment columns  $\mathbf{Y}$   
(can be calculated efficiently by a slight modification  
of Felsenstein's “pruning” algorithm)