

function ANGELIC-SEARCH(*problem, hierarchy, initialPlan*) **returns** a solution or fail

frontier \leftarrow a FIFO queue with *initialPlan* as the only element

while true **do**

if IS-EMPTY?(*frontier*) **then return** fail

plan \leftarrow POP(*frontier*) // chooses the shallowest node in frontier

if REACH⁺(*problem*.INITIAL, *plan*) intersects *problem*.GOAL **then**

if *plan* is primitive **then return** *plan* // REACH⁺ is exact for primitive plans

guaranteed \leftarrow REACH⁻(*problem*.INITIAL, *plan*) \cap *problem*.GOAL

if *guaranteed* $\neq \{\}$ and MAKING-PROGRESS(*plan, initialPlan*) **then**

finalState \leftarrow any element of *guaranteed*

return DECOMPOSE(*hierarchy, problem*.INITIAL, *plan, finalState*)

hla \leftarrow some HLA in *plan*

prefix, suffix \leftarrow the action subsequences before and after *hla* in *plan*

outcome \leftarrow RESULT(*problem*.INITIAL, *prefix*)

for each *sequence* in REFINEMENTS(*hla, outcome, hierarchy*) **do**

 add APPEND(*prefix, sequence, suffix*) to *frontier*

function DECOMPOSE(*hierarchy, s₀, plan, s_f*) **returns** a solution

solution \leftarrow an empty plan

while *plan* is not empty **do**

action \leftarrow REMOVE-LAST(*plan*)

s_i \leftarrow a state in REACH⁻(*s₀, plan*) such that *s_f* \in REACH⁻(*s_i, action*)

problem \leftarrow a problem with INITIAL = *s_i* and GOAL = *s_f*

solution \leftarrow APPEND(ANGELIC-SEARCH(*problem, hierarchy, action*), *solution*)

s_f \leftarrow *s_i*

return *solution*