

# Artificial Intelligence

## Bayesian Networks

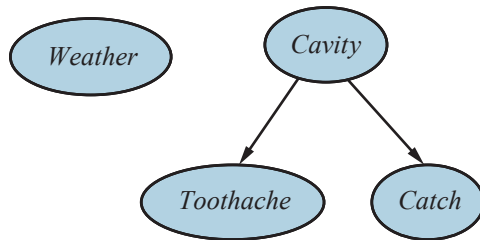
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# Representation of Uncertain Knowledge

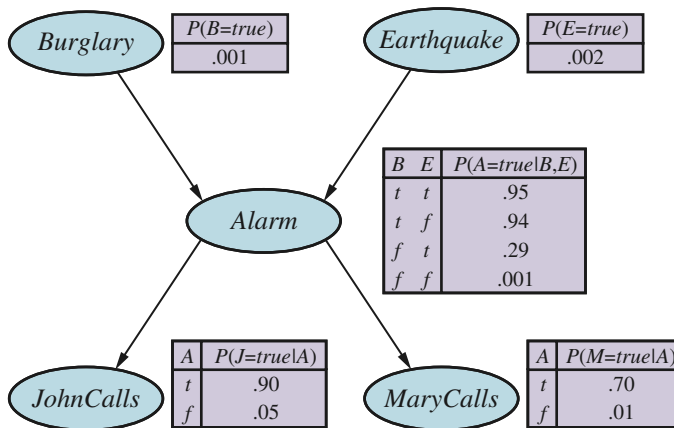
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# Bayesian Network Topology



# Conditional Probability Tables

The *syntax* of a Bayes net consists of a directed acyclic graph (DAG) with some local probability information attached to each node.



# Semantics of Bayesian Networks

The *semantics* defines how the syntax – a DAG with local probabilities – corresponds to a joint distribution over the variables of the network.

A Bayes net contains:

- ▶  $n$  variables,  $X_1, \dots, X_n$ , and
- ▶ (implicit) joint distributions  $Pr(X_1 = x_1 \wedge \dots \wedge X_n = x_n)$ , or  $Pr(x_1, \dots, x_n)$ .

Each entry in the joint distribution is defined by:

$$Pr(x_1, \dots, x_n) = \prod_{i=1}^n \theta(x_i | \text{parents}(X_i))$$

where  $\text{parents}(X_i)$  denotes the values of  $\text{Parents}(X_i)$  that appear in  $x_1, \text{dots}, x_n$ . So each entry in the joint distribution is the rproduct of appropriate elements of the local CPTs in the Bayes net.

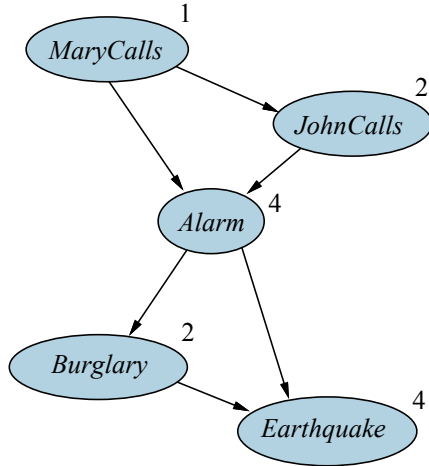
# Constructing Bayesian Networks

First, meet conditions:

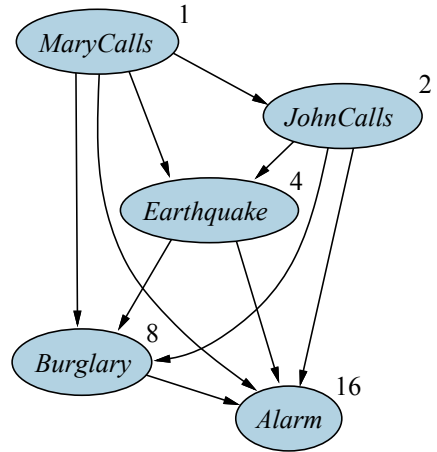
TODO: conditions

1. Nodes: First determine the set of variables that are required to model the domain. Now order them,  $\{X_1, \dots, X_n\}$ . Any order will work, but the resulting network will be more compact if the variables are ordered such that causes precede effects.
2. Links: For  $i = 1$  to  $n$  do:
  - ▶ Choose a minimal set of parents for  $X_i$  from  $X_1, \dots, X_{i-1}$ , such that Equation (13.3) is satisfied.
  - ▶ For each parent insert a link from the parent to  $X_i$ .
  - ▶ CPTs: Write down the conditional probability table,  $P(X_i | \text{Parents}(X_i))$ .

# Effects of Node Ordering

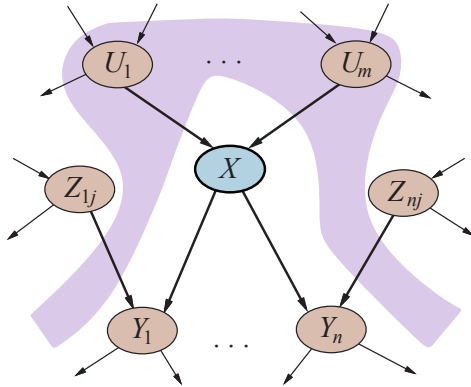


(a)

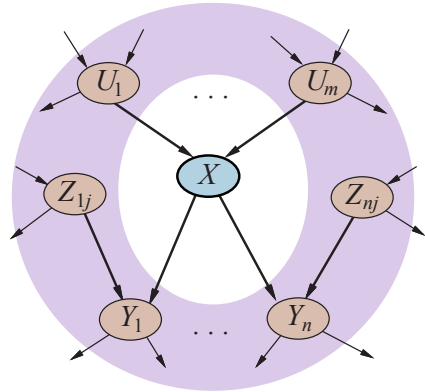


(b)

# Conditional Independence Relations



(a)



(b)

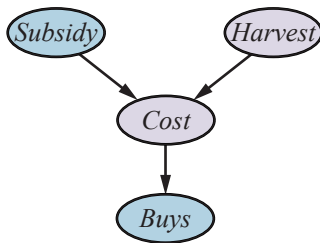


## CPTs Under Noisy-or Model

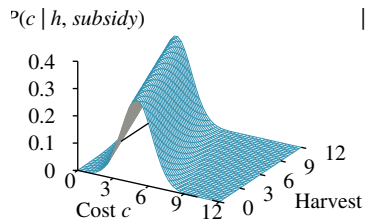
<i>Cold</i>	<i>Flu</i>	<i>Malaria</i>	$P(\text{fever} \cdot)$	$P(\neg\text{fever} \cdot)$
<i>f</i>	<i>f</i>	<i>f</i>	0.0	1.0
<i>f</i>	<i>f</i>	<i>t</i>	0.9	<b>0.1</b>
<i>f</i>	<i>t</i>	<i>f</i>	0.8	<b>0.2</b>
<i>f</i>	<i>t</i>	<i>t</i>	0.98	$0.02 = 0.2 \times 0.1$
<i>t</i>	<i>f</i>	<i>f</i>	0.4	<b>0.6</b>
<i>t</i>	<i>f</i>	<i>t</i>	0.94	$0.06 = 0.6 \times 0.1$
<i>t</i>	<i>t</i>	<i>f</i>	0.88	$0.12 = 0.6 \times 0.2$
<i>t</i>	<i>t</i>	<i>t</i>	0.988	$0.012 = 0.6 \times 0.2 \times 0.1$

# Hybrid Bayesian Networks

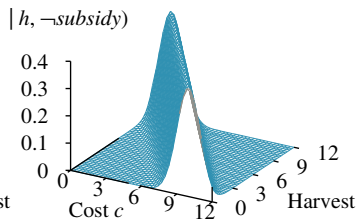
Bayesian Networks with Discrete and Continuous Variables



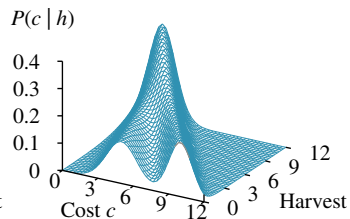
# Linear-Gaussian Conditional Distributions



(a)

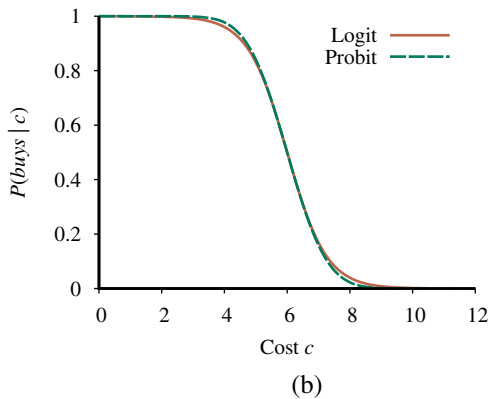
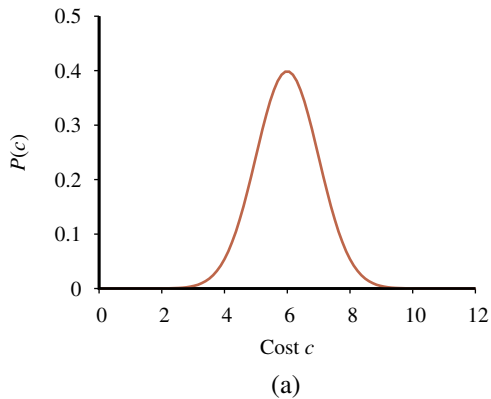


(b)



(c)

## Soft Thresholding for Continuous Parents



# Case Study: Car Insurance

