

Artificial Intelligence

Bayesian Networks

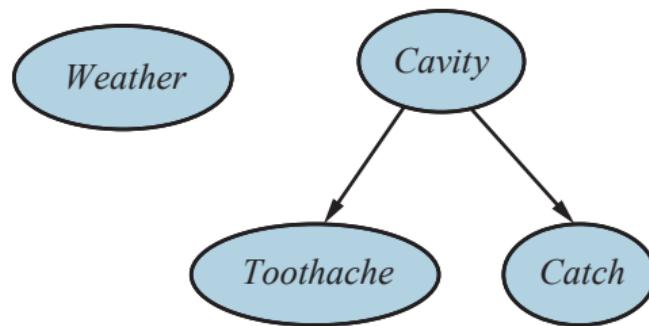
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Representation of Uncertain Knowledge

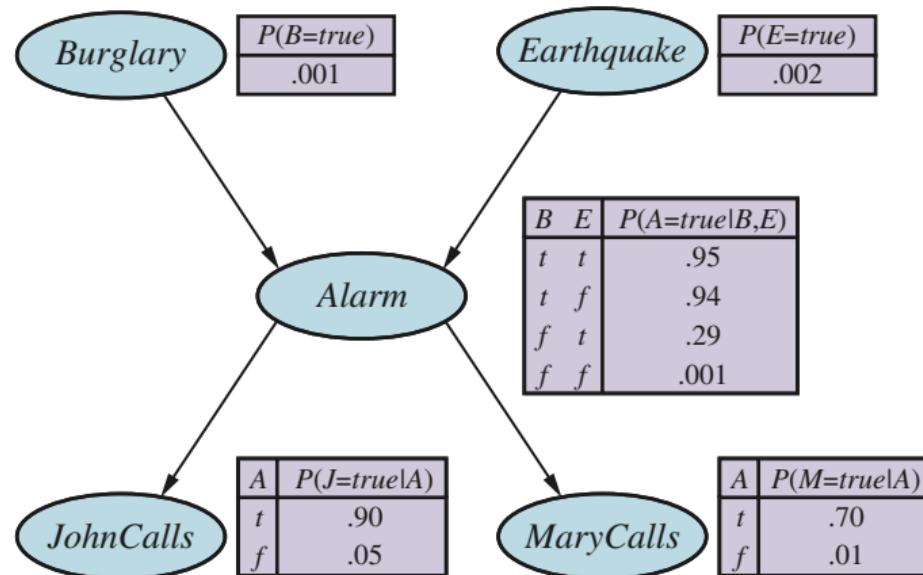
AIMA

Bayesian Network Topology



Conditional Probability Tables

The *syntax* of a Bayes net consists of a directed acyclic graph (DAG) with some local probability information attached to each node.



Semantics of Bayesian Networks

The *semantics* defines how the syntax – a DAG with local probabilities – corresponds to a joint distribution over the variables of the network.

A Bayes net contains:

- ▶ n variables, X_1, \dots, X_n , and
- ▶ (implicit) joint distributions $Pr(X_1 = x_1 \wedge \dots \wedge X_n = x_n)$, or $Pr(x_1, \dots, x_n)$.

Each entry in the joint distribution is defined by:

$$Pr(x_1, \dots, x_n) = \prod_{i=1}^n \theta(x_i | parents(X_i))$$

where $parents(X_i)$ denotes the values of $Parents(X_i)$ that appear in x_1, \dots, x_n . So each entry in the joint distribution is the product of appropriate elements of the local CPTs in the Bayes net.

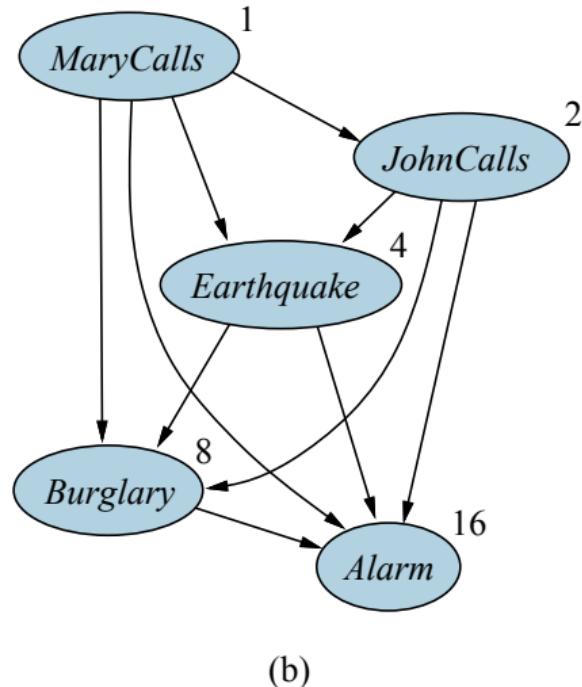
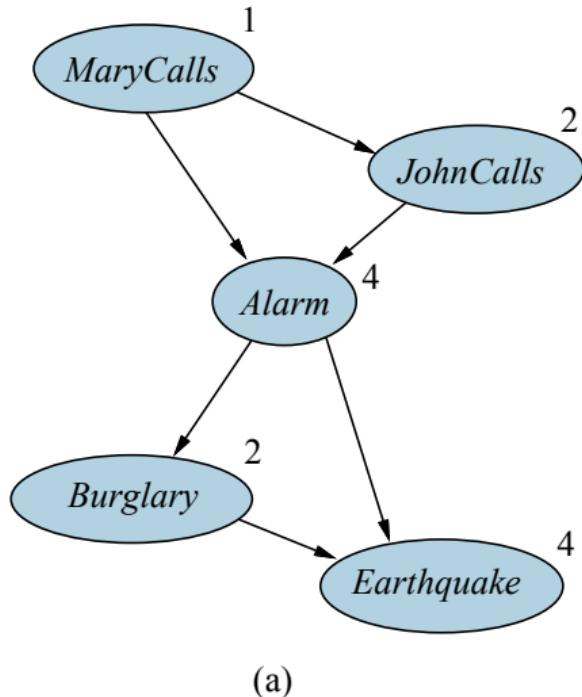
Constructing Bayesian Networks

First, meet conditions:

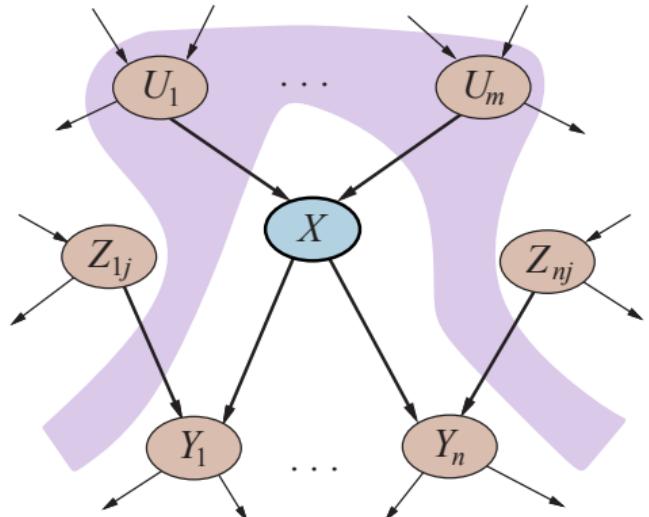
TODO: conditions

1. Nodes: First determine the set of variables that are required to model the domain. Now order them, $\{X_1, \dots, X_n\}$. Any order will work, but the resulting network will be more compact if the variables are ordered such that causes precede effects.
2. Links: For $i = 1$ to n do:
 - ▶ Choose a minimal set of parents for X_i from X_1, \dots, X_{i-1} , such that Equation (13.3) is satisfied.
 - ▶ For each parent insert a link from the parent to X_i .
 - ▶ CPTs: Write down the conditional probability table, $P(X_i | Parents(X_i))$.

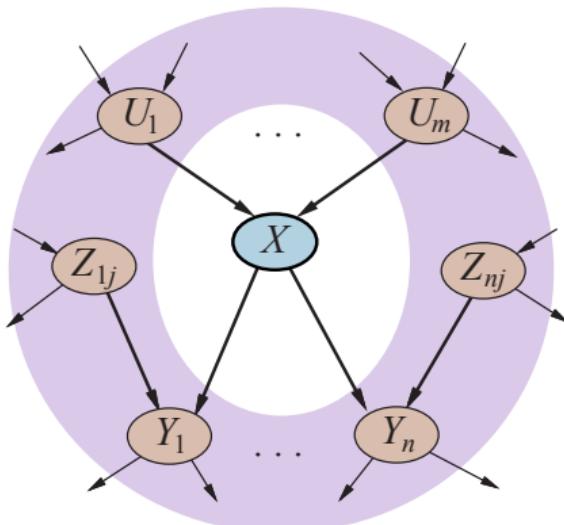
Effects of Node Ordering



Conditional Independence Relations



(a)



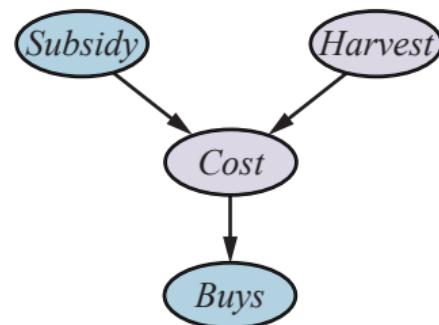
(b)

CPTs Under Noisy-or Model

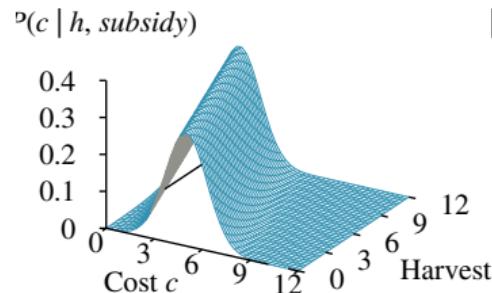
<i>Cold</i>	<i>Flu</i>	<i>Malaria</i>	$P(\text{fever} \cdot)$	$P(\neg\text{fever} \cdot)$
<i>f</i>	<i>f</i>	<i>f</i>	0.0	1.0
<i>f</i>	<i>f</i>	<i>t</i>	0.9	0.1
<i>f</i>	<i>t</i>	<i>f</i>	0.8	0.2
<i>f</i>	<i>t</i>	<i>t</i>	0.98	$0.02 = 0.2 \times 0.1$
<i>t</i>	<i>f</i>	<i>f</i>	0.4	0.6
<i>t</i>	<i>f</i>	<i>t</i>	0.94	$0.06 = 0.6 \times 0.1$
<i>t</i>	<i>t</i>	<i>f</i>	0.88	$0.12 = 0.6 \times 0.2$
<i>t</i>	<i>t</i>	<i>t</i>	0.988	$0.012 = 0.6 \times 0.2 \times 0.1$

Bybrid Bayesian Networks

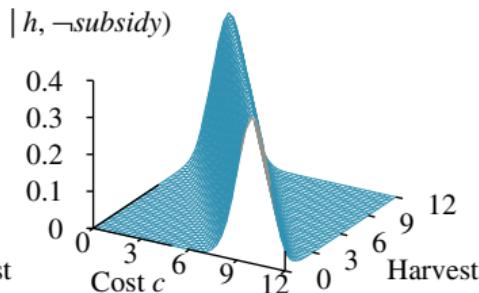
Bayesian Networks with Discrete and Continuous Variables



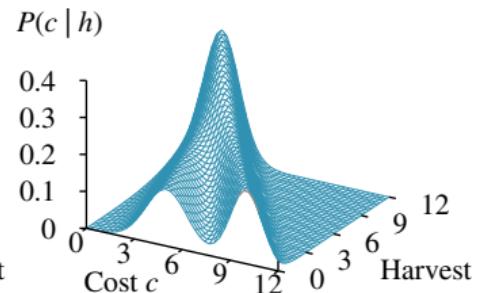
Linear-Gaussian Conditional Distributions



(a)

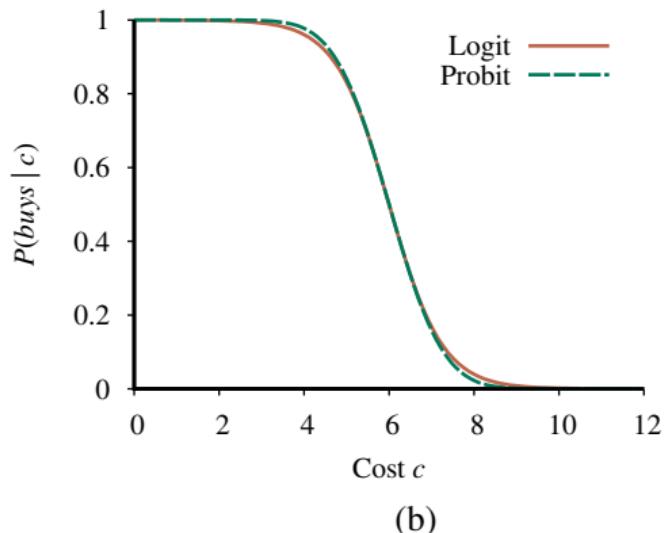
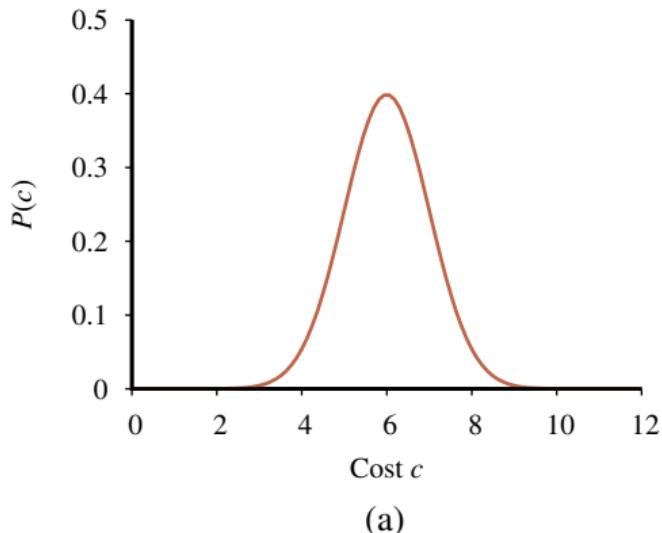


(b)



(c)

Soft Thresholding for Continuous Parents



Case Study: Car Insurance

